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% Mason Wheeler
% HW5 Code
% Exercise 1 (Component Skill 5.3) - Part a
% Load the salmon_data.mat file
load('salmon data.mat');
% first-degree polynomial that best fits the salmon data in the least-squares
sense
A1 = polyfit(year, salmon, 1);
% Display the coefficients of the first-degree polynomial
disp('Coefficients of the first-degree polynomial:');
disp(A1);
% Exercise 1 (Component Skill 5.3) - Part b
% Use the MATLAB built-in function 'polyfit' to find the coefficients of the
% third-degree polynomial that best fits the salmon data in the least-squares
sense
% Assign the row vector of coefficients to the variable A2
A2 = polyfit(year, salmon, 3);
% Display the coefficients of the third-degree polynomial
disp('Coefficients of the third-degree polynomial:');
disp(A2);
% Exercise 1 (Component Skill 5.3) - Part c
% Use the MATLAB built-in function 'polyfit' to find the coefficients of the
% fifth-degree polynomial that best fits the salmon data in the least-squares
sense
% Assign the row vector of coefficients to the variable A3
A3 = polyfit(year, salmon, 5);
% Display the coefficients of the fifth-degree polynomial
disp('Coefficients of the fifth-degree polynomial:');
disp(A3);
% Exercise 1 (Component Skill 5.3) - Part d
% True salmon count in 2021
true_salmon_2021 = 489523;
% Calculate the predicted salmon count in 2021 using the polynomials p1, p3,
and p5
p1_2021 = polyval(A1, 2021);
p3_2021 = polyval(A2, 2021);
p5_{2021} = polyval(A3, 2021);
% Calculate the relative errors (epsilon1, epsilon2, epsilon3)
epsilon1 = abs(p1_2021 - true_salmon_2021) / true_salmon_2021;
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epsilon2 = abs(p3_2021 - true_salmon_2021) / true_salmon_2021;
epsilon3 = abs(p5 2021 - true salmon 2021) / true salmon 2021;
% Assign the variable A4 to the 3x1 row vector [epsilon1, epsilon2, epsilon3]
A4 = [epsilon1; epsilon2; epsilon3];
% Display the relative errors
disp('Relative errors:');
disp(A4);
% Exercise 2 (Component Skill 5.3)
% Load CO2 data.mat file
load('CO2_data.mat');
% Part a
% Find the values of a, r, and b that minimize the least-squares error
initial_guess = [30; 0.03; 300];
A5 = fminsearch(@(params) lse(params, year, CO2), initial_guess);
% Part b
% Find the values of a, r, and b that minimize the L1 error
A6 = fminsearch(@(params) l1e(params, year, CO2), initial_guess);
% Plot the results
plot_results(year, CO2, A5, A6);
% Exercise 3 (Component Skill 5.3)
% Load spring data.mat file
load('spring_data.mat');
% Part a
% Estimate the value of the toy displacement at t = pi/2 seconds using cubic
spline interpolation
A7 = interp1(time, deltaz, pi/2, 'spline');
% Part b
% Plot the data and cubic spline interpolation
plot_spline(time, deltaz);
% Create separate functions for least-squares error and L1 error
function error = lse(params, year, CO2)
    error = sum((CO2 - (params(1) * exp(params(2) * year) + params(3))).^2);
end
function error = lle(params, year, CO2)
    error = sum(abs(CO2 - (params(1) * exp(params(2) * year) + params(3))));
end
function plot_results(year, CO2, A5, A6)
```

```
% Plot CO2 data in black
    figure;
   plot(year, CO2, '.', 'MarkerSize', 10, 'Color', 'k', 'LineStyle', 'none');
   hold on;
    % Plot least-squares error exponential curve in red
   x = linspace(0, 63, 1000);
   y lse = A5(1) * exp(A5(2) * x) + A5(3);
   plot(x, y_lse, 'r', 'LineWidth', 2);
    % Plot L1 error exponential curve in blue
   y_11e = A6(1) * exp(A6(2) * x) + A6(3);
   plot(x, y_l1e, 'b--', 'LineWidth', 2);
    % Set axis limits
   xlim([0, 63]);
   ylim([300, 420]);
    % Add legend, labels, and title
   legend('CO2 data', 'LSE', 'L1E', 'Location', 'NorthWest');
   xlabel('Years since 1958', 'FontSize', 16);
   ylabel('CO_2 Concentration (ppm)', 'FontSize', 16);
   title('CO_2 Concentration vs. Time', 'FontSize', 20);
    % Hold off
   hold off;
end
function plot_spline(time, deltaz)
    % Create cubic spline interpolation with sample points t = 0:0.01:10
    t interp = 0:0.01:10;
    z_interp = interp1(time, deltaz, t_interp, 'spline');
    % Plot cubic spline interpolation in blue
    figure;
   plot(t_interp, z_interp, 'b', 'LineWidth', 2);
   hold on;
    % Superimpose the displacement data in black
   plot(time, deltaz, 'k.', 'MarkerSize', 15, 'LineStyle', 'none');
    % Set axis limits
   xlim([0, 10]);
   ylim([-1, 1]);
    % Add labels and title
   xlabel('Time (s)', 'FontSize', 16);
   ylabel('Vertical Displacement (cm)', 'FontSize', 16);
   title('Vertical Displacement vs. Time', 'FontSize', 20);
    % Hold off
   hold off;
end
```

Coefficients of the first-degree polynomial: 1.0e+06 *

0.0042 -7.8654

Warning: Polynomial is badly conditioned. Add points with distinct X values, reduce the degree of the polynomial, or try centering and scaling as described in HELP POLYFIT.

Coefficients of the third-degree polynomial:

1.0e+10 *

0.0000 -0.0000 0.0016 -1.0637

Warning: Polynomial is badly conditioned. Add points with distinct X values, reduce the degree of the polynomial, or try centering and scaling as described in HELP POLYFIT.

Coefficients of the fifth-degree polynomial:

1.0e+14 *

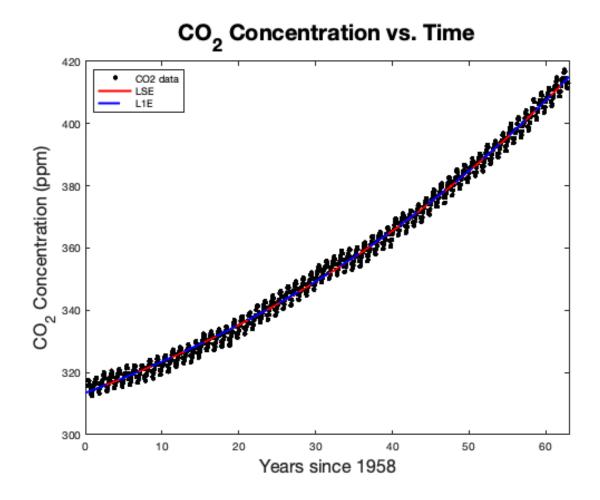
-0.0000 0.0000 -0.0000 0.0000 -0.0103 4.0754

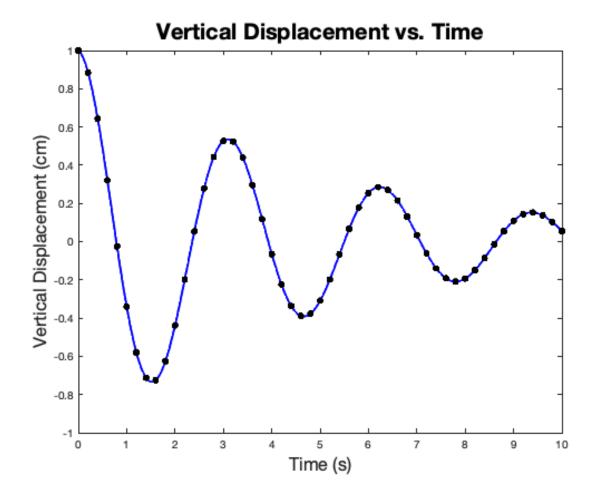
Relative errors:

0.2233

0.6722

0.1778





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