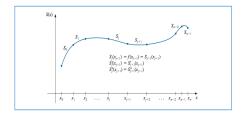
Review of Splines: Given n+1 distinct points

$$(x_0, f(x_0)), (x_1, f(x_1)), \cdots, (x_n, f(x_n)),$$

► Find cubic spline interpolant $S(x) \in C^2[x_0, x_n]$,

$$S(x) = S_j(x) \stackrel{\text{def}}{=} a_j + b_j(x - x_j) + c_j(x - x_j)^2 + d_j(x - x_j)^3,$$

for $x \in [x_j, x_{j+1}], \ 0 \le j \le n-1.$



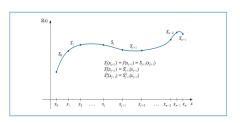
Review of Splines: Given n + 1 distinct points

$$(x_0, f(x_0)), (x_1, f(x_1)), \cdots, (x_n, f(x_n)),$$

► Find cubic spline interpolant $S(x) \in C^2[x_0, x_n]$,

$$S(x) = S_j(x) \stackrel{\text{def}}{=} a_j + b_j(x - x_j) + c_j(x - x_j)^2 + d_j(x - x_j)^3,$$

for $x \in [x_j, x_{j+1}], 0 \le j \le n-1$.



- ► Fake spine: $S_n(x) \stackrel{def}{=} a_n + b_n(x x_n) + c_n(x x_n)^2$, for $x > x_n$
 - Natural Splines: $S_0''(x_0) = S_{n-1}''(x_n) = 0$.

Recall n+1 variables in c with n-1 equations:

Recall
$$H+1$$
 variables in C with $H-1$ equations

where for $j = 0, 1, \dots n-1$

$$h_{j-1} c_{j-1} + 2(h_{j-1} + h_j) c_j + h_j c_{j+1} = 3\left(\frac{a_{j+1} - a_j}{h_i} - \frac{a_j - a_{j-1}}{h_{i-1}}\right), j = 1, \dots, n-1$$



 $b_j = -\frac{h_j}{3}(2c_j+c_{j+1}) + \frac{a_{j+1}-a_j}{h_i}. (\widehat{\ell}_0)$

 $b_{i+1} = b_i + h_i(c_i + c_{i+1}).$ $(\widehat{\ell}_1)$

- Clamped Splines: $S'_0(x_0) = f'(x_0), S'_{n-1}(x_n) = f'(x_n)$

Recall n + 1 variables in c with n - 1 equations:

$$a_{j+1} - a_{j}$$

 $h_{j-1} c_{j-1} + 2(h_{j-1} + h_j) c_j + h_j c_{j+1} = 3\left(\frac{a_{j+1} - a_j}{h_i} - \frac{a_j - a_{j-1}}{h_{i-1}}\right), j = 1, \dots, n-1$

where for $j = 0, 1, \dots, n-1$

$$(c_{i-1} + 2(h_{i-1} + h_i))c_{i+1} + h_ic_{i+1} = 3(\frac{a_{j+1} - a_{j+1}}{a_{j+1}})c_{i+1}$$

 $b_j = -\frac{h_j}{3}(2c_j+c_{j+1}) + \frac{a_{j+1}-a_j}{h_i}.(\widehat{\ell}_0)$

Equation for c_0, c_1 : $f'(x_0) = S'_0(x_0) = b_0 \stackrel{\widehat{(\ell_0)}}{=} - \frac{h_0}{3} (2c_0 + c_1) + \frac{a_1 - a_0}{b_1}$.

 $b_{i+1} = b_i + h_i(c_i + c_{i+1}).$ $(\widehat{\ell}_1)$

 $2h_0c_0 + h_0c_1 = 3\left(\frac{a_1-a_0}{h_0} - f'(x_0)\right).$

quations:
$$O_{n-1}(x_n) = V(x_n)$$

$$S'(x_0), \ S'_{n-1}(x_n) = f'(x_n)$$
 uations:

Clamped Splines:
$$S'_0(x_0) = f'(x_0)$$
, $S'_{n-1}(x_n) = f'(x_n)$
Recall $n+1$ variables in c with $n-1$ equations:

Recall n + 1 variables in c with n - 1 equations:

or: $h_{n-1}c_{n-1} + 2h_{n-1}c_n = 3\left(f'(x_n) - \frac{a_n - a_{n-1}}{h_{n-1}}\right)$

$$h_{j-1} c_{j-1} + 2(h_{j-1} + h_j) c_j + h_j c_{j+1} = 3\left(\frac{a_{j+1} - a_j}{h_i} - \frac{a_j - a_{j-1}}{h_{i-1}}\right), j = 1, \dots, n-1$$

where for $j = 0, 1, \dots, n-1$

$$(-h_j) c_j + h_j c_{j+1} = 3 \left(\frac{a_{j+1} - a_j}{h_i} \right)$$

$$(+h_j) c_j + h_j c_{j+1} = 3 \left(\frac{a_{j+1} - a_{j+1}}{h_i} \right)$$

 $b_{i+1} = b_i + h_i(c_i + c_{i+1}).$

$$(+h_j) c_j + h_j c_{j+1} = 3 \left(\frac{a_{j+1} - a_j}{h_i} \right)$$

Clamped Splines: $S'_0(x_0) = f'(x_0), S'_{n-1}(x_n) = f'(x_n)$

$$=3\left(\frac{a_{j+1}-a_{j}}{a_{j+1}}\right)$$

 $b_j = -\frac{h_j}{3}(2c_j+c_{j+1}) + \frac{a_{j+1}-a_j}{h_i}.(\widehat{\ell}_0)$

Equation for c_0, c_1 : $f'(x_0) = S'_0(x_0) = b_0 = \frac{(\widehat{\ell_0})}{3} - \frac{h_0}{3} (2c_0 + c_1) + \frac{a_1 - a_0}{h_0}$.

 $2h_0c_0+h_0c_1 = 3\left(\frac{a_1-a_0}{h_0}-f'(x_0)\right).$

For c_{n-1}, c_n : $f'(x_n) = S'_{n-1}(x_n) = b_n \frac{(\hat{\ell}_1)}{n} b_{n-1} + h_{n-1}(c_{n-1} + c_n)$

 $\frac{\widehat{(c_0)}}{3} - \frac{h_{n-1}}{3} (2c_{n-1} + c_n) + \frac{a_n - a_{n-1}}{h_{n-1}} + h_{n-1} (c_{n-1} + c_n)$

Clamped Splines: equations in matrix form

► Equations for $\{c_j\}_{j=0}^n$,

$$\begin{pmatrix} 2h_0 & h_0 \\ h_0 & 2(h_0 + h_1) \\ & \ddots & \ddots & \ddots \\ & & h_{n-2} & 2(h_{n-2} + h_{n-1}) & h_{n-1} \\ & & h_{n-1} & 2h_{n-1} \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \\ \vdots \\ c_{n-1} \\ c_n \end{pmatrix} = 3 \begin{pmatrix} \frac{a_1 - a_0}{h_0} - f'(x_0) \\ \frac{a_2 - a_1}{h_1} - \frac{a_1 - a_0}{h_0} \\ \vdots \\ \frac{a_n - a_{n-1}}{h_{n-1}} - \frac{a_{n-1} - a_{n-2}}{h_{n-2}} \\ f'(x_n) - \frac{a_n - a_{n-1}}{h_n} \end{pmatrix}.$$

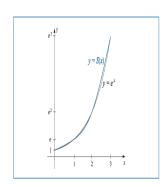
▶ Equations for $\{d_j\}_{j=0}^{n-1}, \{b_j\}_{j=0}^{n-1},$

$$d_j = \frac{c_{j+1} - c_j}{3h_i}$$
, and $b_j = -\frac{h_j}{3}(2c_j + c_{j+1}) + \frac{a_{j+1} - a_j}{h_i}$.

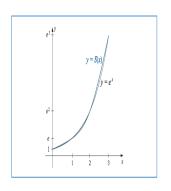
Clamped Splines

```
function Splines = ClampedSplines(x,f,df)
% This code implements the clamped splines
% Written by Ming Gu for Math 128A, Fall 2008
% Updated by Ming Gu for Math 128A, Spring 2015
윰
n = length(x):
h = diff(x(:));
rhs = 3 * diff([df(1);diff(f(:))./h;df(2)]);
A = diag(h,1)+diag(h,-1)+2*diag([[0;h]+[h;0]]);
% compute the c coefficients. This is a simple
% but very slow way to do it.
용
          = A \setminus rhs;
C
          = (diff(c)./h)/3;
d
          = diff(f(:))./h-(h/3).*(2*c(1:n-1)+c(2:n));
b
Splines.a = f(:);
Splines.b = b;
Splines.c = c;
Splines.d = d:
```

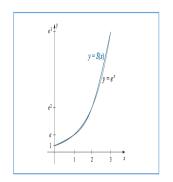
Natural Splines, $f(x) = e^x$, $x_0 = 0, x_1 = 1, x_2 = 2, x_3 = 3$



Natural Splines,
$$f(x) = e^x$$
, $x_0 = 0, x_1 = 1, x_2 = 2, x_3 = 3$

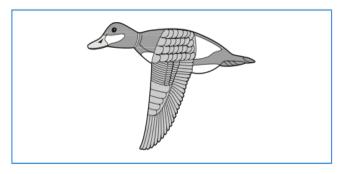


Clamped Splines, $f(x) = e^x$, $x_0 = 0, x_1 = 1, x_2 = 2$, $x_3 = 3, f'(0) = 1, f'(3) = e^3$



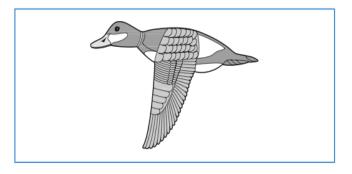
A duck in Splines: to approximate its top profile

► A duck in flight



A duck in Splines: to approximate its top profile

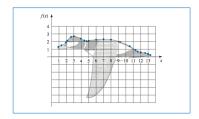
► A duck in flight

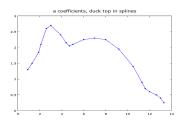


χ	0.9	1.3	1.9	2.1	2.6	3.0	3.9	4.4	4.7	5.0	6.0	7.0	8.0	9.2	10.5	11.3	11.6	12.0	12.6	13.0	13.3
f(x)	1.3	1.5	1.85	2.1	2.6	2.7	2.4	2.15	2.05	2.1	2.25	2.3	2.25	1.95	1.4	0.9	0.7	0.6	0.5	0.4	0.25

Duck top profile

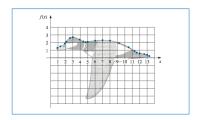
► Natural Splines, {a_k} coefficients

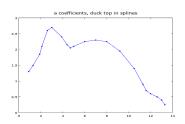




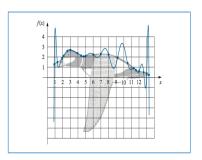
Duck top profile

Natural Splines, $\{a_k\}$ coefficients





▶ 20-degree polynomial interpolation



§3.6 Parametric Curve Approximation: x = x(t), y = y(t)

▶ Given n + 1 distinct points

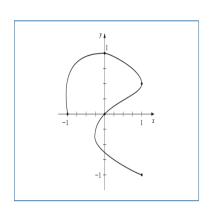
$$(x_0, y_0), (x_1, y_1), \cdots, (x_n, y_n),$$

where

$$x_j = x(t_j), \quad y_j = y(t_j), \quad j = 0, 1, \dots, n.$$

Example

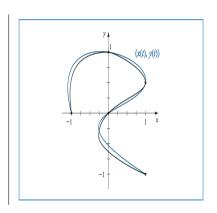
i	0	1	2	3	4
t_i	0	0.25	0.5	0.75	1
x_i	-1	0	1	0	1
y_i	0	1	0.5	0	-1



Parametric Curve with Polynomial Interpolation

• 4^{th} degree interpolation on both x = x(t) and y = y(t).

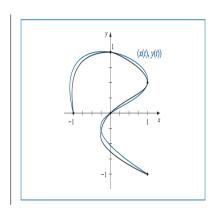
$$\begin{split} x(t) & = & \left(\left(\left(64t - \frac{352}{3} \right) t + 60 \right) t - \frac{14}{3} \right) t - 1, \\ y(t) & = & \left(\left(\left(-\frac{64}{3}t + 48 \right) t - \frac{116}{3} \right) t + 11 \right) t. \end{split}$$



Parametric Curve with Polynomial Interpolation

• 4th degree interpolation on both x = x(t) and y = y(t).

$$\begin{aligned} x(t) &=& \left(\left(\left(64t - \frac{352}{3} \right) t + 60 \right) t - \frac{14}{3} \right) t - 1, \\ y(t) &=& \left(\left(\left(-\frac{64}{3} t + 48 \right) t - \frac{116}{3} \right) t + 11 \right) t. \end{aligned}$$



Would like a better fit

Bezier Curves in Computer Graphics

- Design: Piece-wise cubic Hermite polynomials.
- Feature: Each cubic Hermite polynomial is completely determined by function/derivative at endpoints.
- Consequence:, Each portion of the curve can be changed while leaving most of the curve the same.



As duck flies, parametric curve can effectively evolve.

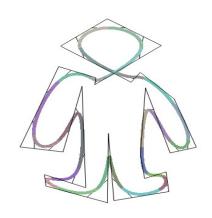
Bezier Curves in Computer Graphics

- Design: Piece-wise cubic Hermite polynomials.
- Feature: Each cubic Hermite polynomial is completely determined by function/derivative at endpoints.
- Consequence:, Each portion of the curve can be changed while leaving most of the curve the same.



As duck flies, parametric curve can effectively evolve.

► Bezier Curves with GUIDE POINTS



https://www.youtube.com/watch?v=TeXajQ62yZ8&ab_channel=corex

Parametric Curves: Piece-wise cubic Hermite polynomials

- **Given (I)**: n + 1 data points $(x(t_0), y(t_0)), \dots, (x(t_n), y(t_n)).$
- ▶ Given (II): n + 1 derivatives $\frac{dy}{dx} \Big|_{t=t_i}$, $0 \le i \le n$.
- **Find**: $2 \times n$ pieces of cubic Hermite polynomials:

$$x = x_i(t), \quad y = y_i(t), \quad \text{for} \quad i \in [t_i, t_{i+1}], \quad 0 \le i \le n,$$

such that

$$\begin{pmatrix} x_i(t_i) \\ y_i(t_i) \end{pmatrix} \quad = \quad \begin{pmatrix} x(t_j) \\ y(t_i) \end{pmatrix}, \; \begin{pmatrix} x_i(t_{i+1}) \\ y_i(t_{i+1}) \end{pmatrix} = \begin{pmatrix} x(t_{i+1}) \\ y(t_{i+1}) \end{pmatrix},$$

$$\frac{dy}{dx} \begin{vmatrix} t = t_i \end{vmatrix} = \quad \frac{y_i'(t_i)}{x_i'(t_i)}, \; \text{ and } \; \frac{dy}{dx} \begin{vmatrix} t = t_{i+1} \end{vmatrix} = \frac{y_i'(t_{i+1})}{x_i'(t_{i+1})}$$

Parametric Curves: Piece-wise cubic Hermite polynomials

- Given (I): n+1 data points $(x(t_0), y(t_0)), \dots, (x(t_n), y(t_n)).$
- Given (II): n+1 derivatives $\frac{dy}{dx}\Big|_{t=t_i}$, $0 \le i \le n$.
- ▶ Find: 2 × n pieces of cubic Hermite polynomials:

$$x = x_i(t), \quad y = y_i(t), \quad \text{for} \quad i \in [t_i, t_{i+1}], \quad 0 \le i \le n,$$

such that

$$\begin{pmatrix} x_i(t_i) \\ y_i(t_i) \end{pmatrix} = \begin{pmatrix} x(t_i) \\ y(t_i) \end{pmatrix}, \begin{pmatrix} x_i(t_{i+1}) \\ y_i(t_{i+1}) \end{pmatrix} = \begin{pmatrix} x(t_{i+1}) \\ y(t_{i+1}) \end{pmatrix},$$

$$\frac{dy}{dx} \begin{vmatrix} t_{t=t_i} \end{vmatrix} = \frac{y_i'(t_i)}{x_i'(t_i)}, \text{ and } \frac{dy}{dx} \begin{vmatrix} t_{t=t_{i+1}} \end{vmatrix} = \frac{y_i'(t_{i+1})}{x_i'(t_{i+1})}$$

- 8 parameters in x_i(t), y_i(t)
- only 6 given conditions for each i
- use guidepoints



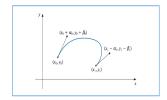
Cubic Bazier Curve

Guidepoints guide slopes (for $[t_i, t_{i+1}] = [0, 1]$)

Unique cubic Hermite polynomials x(t), y(t) with

$$\begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}, \begin{pmatrix} x(1) \\ y(1) \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix},$$

$$\begin{pmatrix} x'(0) \\ y'(0) \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \beta_0 \end{pmatrix}, \begin{pmatrix} x'(1) \\ y'(1) \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix}$$

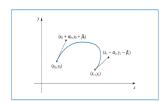


Guidepoints guide slopes (for $[t_i, t_{i+1}] = [0, 1]$)

Unique cubic Hermite polynomials x(t), y(t) with

$$\begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}, \begin{pmatrix} x(1) \\ y(1) \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix},$$

$$\begin{pmatrix} x'(0) \\ y'(0) \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \beta_0 \end{pmatrix}, \begin{pmatrix} x'(1) \\ y'(1) \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix}$$



Guidepoints

$$(x_0 + \alpha_0, y_0 + \beta_0)$$
 and $(x_1 - \alpha_1, y_1 - \beta_1)$

Guidepoints guide slopes

$$\frac{dy}{dx}\mid_{t=0} = \frac{\beta_0}{\alpha_0}, \quad \text{and} \quad \frac{dy}{dx}\mid_{t=1} = \frac{\beta_1}{\alpha_1}.$$

two degrees of freedom in guidepoints

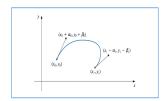
$$eta_0 = lpha_0 \left(rac{dy}{dx} \mid_{t=0}
ight), \quad ext{and} \quad eta_1 = lpha_1 \left(rac{dy}{dx} \mid_{t=1}
ight)$$

Guidepoints guide slopes (for $[t_i, t_{i+1}] = [0, 1]$)

Unique cubic Hermite polynomials x(t), y(t) with

$$\begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}, \begin{pmatrix} x(1) \\ y(1) \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix},$$

$$\begin{pmatrix} x'(0) \\ y'(0) \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \beta_0 \end{pmatrix}, \begin{pmatrix} x'(1) \\ y'(1) \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix}$$



Guidepoints

$$(x_0 + \alpha_0, y_0 + \beta_0)$$
 and $(x_1 - \alpha_1, y_1 - \beta_1)$

Guidepoints guide slopes

$$\frac{dy}{dx}\mid_{t=0} = \frac{\beta_0}{\alpha_0}, \quad \text{and} \quad \frac{dy}{dx}\mid_{t=1} = \frac{\beta_1}{\alpha_1}.$$

two degrees of freedom in guidepoints

$$eta_0 = lpha_0 \left(rac{dy}{dx} \mid_{t=0}
ight), \quad ext{and} \quad eta_1 = lpha_1 \left(rac{dy}{dx} \mid_{t=1}
ight)$$

choice of guidepoints changes curve shapes



```
function [bx,by] = Bezier(x,y,alphal,betal,alphar,betar)
n = length(x);
bx = zeros(n-1.4):
by = zeros(n-1,4);
bx=[x(1:n-1),alphal(1:n-1),x(2:n)-x(1:n-1)-alphal(1:n-1),
2*(x(2:n)-x(1:n-1))-(alphal(1:n-1)+alphar(2:n))];
by=[y(1:n-1),betal(1:n-1),y(2:n)-y(1:n-1)-betal(1:n-1),
```

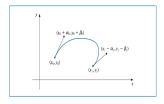
2*(y(2:n)-y(1:n-1))-(betal(1:n-1)+betar(2:n))];

Unique cubic Hermite polynomials x(t), y(t) with

$$\begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} x(1) \\ y(1) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix},$$

$$\begin{pmatrix} x'(0) \\ y'(0) \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \beta_0 \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \alpha_0 \end{pmatrix},$$

$$\begin{pmatrix} x'(1) \\ y'(1) \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ -\alpha_1 \end{pmatrix}$$

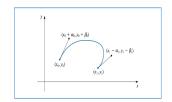


▶ Unique cubic Hermite polynomials x(t), y(t) with

$$\begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} x(1) \\ y(1) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix},$$

$$\begin{pmatrix} x'(0) \\ y'(0) \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \beta_0 \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \alpha_0 \end{pmatrix},$$

$$\begin{pmatrix} x'(1) \\ y'(1) \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ -\alpha_1 \end{pmatrix}$$



► Guidepoints guide slopes

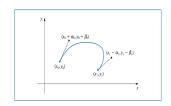
$$\frac{dy}{dx}\mid_{t=0}=\frac{\beta_0}{\alpha_0}=1, \quad \text{and} \quad \frac{dy}{dx}\mid_{t=1}=\frac{\beta_1}{\alpha_1}=-1.$$

Unique cubic Hermite polynomials x(t), y(t) with

$$\begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} x(1) \\ y(1) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix},$$

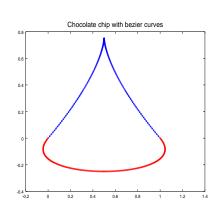
$$\begin{pmatrix} x'(0) \\ y'(0) \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \beta_0 \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \alpha_0 \end{pmatrix},$$

$$\begin{pmatrix} x'(1) \\ y'(1) \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ -\alpha_1 \end{pmatrix}$$



► Guidepoints guide slopes

$$\frac{dy}{dx}|_{t=0} = \frac{\beta_0}{\alpha_0} = 1$$
, and $\frac{dy}{dx}|_{t=1} = \frac{\beta_1}{\alpha_1} = -1$.

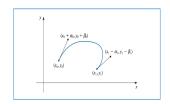


Unique cubic Hermite polynomials x(t), y(t) with

$$\begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} x(1) \\ y(1) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix},$$

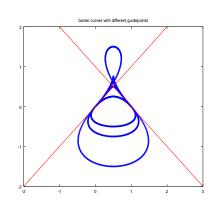
$$\begin{pmatrix} x'(0) \\ y'(0) \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \beta_0 \end{pmatrix} = \begin{pmatrix} \alpha_0 \\ \alpha_0 \end{pmatrix},$$

$$\begin{pmatrix} x'(1) \\ y'(1) \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix} = \begin{pmatrix} \alpha_1 \\ -\alpha_1 \end{pmatrix}$$



► Guidepoints guide slopes

$$\frac{dy}{dx}|_{t=0} = \frac{\beta_0}{\alpha_0} = 1$$
, and $\frac{dy}{dx}|_{t=1} = \frac{\beta_1}{\alpha_1} = -1$.



Parametric Curves: Summary of approaches

- ▶ **Given (I)**: n + 1 data points $(x(t_0), y(t_0)), \dots, (x(t_n), y(t_n))$.
- ▶ **Given (II)**: n+1 derivatives $\frac{dy}{dx}|_{t=t_i}$, $0 \le i \le n$.

Approaches

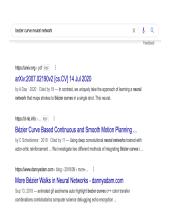
- Polynomial interpolations with n+1 data points $(x(t_0)), \dots, (x(t_n))$ and $(y(t_0)), \dots, (y(t_n))$, respectively. (likely to be unreliable)
- Splines approximations with n+1 data points $(x(t_0)), \dots, (x(t_n))$ and $(y(t_0)), \dots, (y(t_n))$, respectively. (more reliable and more computational cost)
- Bezier curves with Hermite polynomials (more reliable and less computational cost)

Neural Networks have changed the story

curve fitting



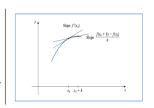
Bezier curve



Derivative of given function f(x) at x_0

$$f'(x_0) = \lim_{h \to 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

$$\approx \frac{f(x_0 + h) - f(x_0)}{h}, \quad |h| \text{ tiny}$$

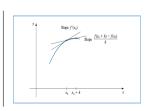


How good is this approximation?

Derivative of given function f(x) at x_0

$$f'(x_0) = \lim_{h \to 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

$$\approx \frac{f(x_0 + h) - f(x_0)}{h}, \quad |h| \text{ tiny}$$



How good is this approximation?

By Taylor expansion, there is a ξ between x_0 and $x_0 + h$,

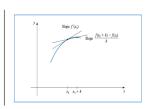
$$f(x_0 + h) = f(x_0) + h f'(x_0) + \frac{1}{2}h^2 f''(\xi),$$

therefore $f'(x_0) = \frac{f(x_0 + h) - f(x_0)}{h} - \frac{1}{2}h f''(\xi)$

Derivative of given function f(x) at x_0

$$f'(x_0) = \lim_{h \to 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

$$\approx \frac{f(x_0 + h) - f(x_0)}{h}, \quad |h| \text{ tiny}$$



How good is this approximation?

By Taylor expansion, there is a ξ between x_0 and $x_0 + h$,

$$f(x_0 + h) = f(x_0) + h f'(x_0) + \frac{1}{2}h^2 f''(\xi),$$
therefore $f'(x_0) = \frac{f(x_0 + h) - f(x_0)}{h} - \frac{1}{2}h f''(\xi)$

$$\approx \frac{f(x_0 + h) - f(x_0)}{h}.$$

Derivative of given function f(x) at x_0

$$f'(x_0) = \lim_{h \to 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

$$\approx \frac{f(x_0 + h) - f(x_0)}{h}, |h| \text{ tiny}$$

How good is this approximation?

By Taylor expansion, there is a ξ between x_0 and $x_0 + h$,

$$f(x_0 + h) = f(x_0) + h f'(x_0) + \frac{1}{2}h^2 f''(\xi),$$
therefore $f'(x_0) = \frac{f(x_0 + h) - f(x_0)}{h} - \frac{1}{2}h f''(\xi)$

$$\approx \frac{f(x_0 + h) - f(x_0)}{h}.$$

- forward-difference formula for h > 0,
- **backward-difference formula** for h < 0.

Numerical Differentiation, example

Example: Use the forward-difference formula to approximate the derivative of $f(x) = \ln(x)$ at $x_0 = 1.8$, using h = 0.1, 0.05, 0.01.

Because $f''(\xi) = -1/\xi^2$ for $\xi \in [x_0, x_0 + h] \subset [1.8, 1.9]$, it follows that the approximation error

$$\frac{1}{2}\left|h\ f''(\xi)\right| \leq \frac{1}{2}\left|\frac{h}{1.8^2}\right|.$$

Numerical Differentiation, example

Example: Use the forward-difference formula to approximate the derivative of $f(x) = \ln(x)$ at $x_0 = 1.8$, using h = 0.1, 0.05, 0.01.

Because $f''(\xi) = -1/\xi^2$ for $\xi \in [x_0, x_0 + h] \subset [1.8, 1.9]$, it follows that the approximation error

$$\frac{1}{2}\left|h\ f''(\xi)\right|\leq \frac{1}{2}\left|\frac{h}{1.8^2}\right|.$$

h	f(1.8+h)	$\frac{f(1.8+h) - f(1.8)}{h}$	$\frac{ h }{2(1.8)^2}$	
0.1	0.64185389	0.5406722	0.0154321	
0.05	0.61518564	0.5479795	0.0077160	
0.01	0.59332685	0.5540180	0.0015432	

Suppose that $\{x_0, x_1, \dots, x_n\}$ are n+1 distinct numbers,

$$f(x) = \left(\sum_{j=0}^{n} f(x_j) L_j(x)\right) + \frac{f^{(n+1)}(\xi(x))}{(n+1)!} \prod_{i=0}^{n} (x - x_i), \quad L_j(x) = \prod_{i \neq j} \frac{(x - x_i)}{(x_j - x_i)},$$

for some $\xi(x)$.

Suppose that $\{x_0, x_1, \dots, x_n\}$ are n+1 distinct numbers,

$$f(x) = \left(\sum_{j=0}^{n} f(x_j) L_j(x)\right) + \frac{f^{(n+1)}(\xi(x))}{(n+1)!} \prod_{i=0}^{n} (x-x_i), \quad L_j(x) = \prod_{i \neq j} \frac{(x-x_i)}{(x_j-x_i)},$$

for some $\xi(x)$. So

$$f'(x) = \left(\sum_{j=0}^{n} f(x_j) L'_j(x)\right) + \left(\frac{f^{(n+1)}(\xi(x))}{(n+1)!}\right) \frac{d}{dx} \left(\prod_{i=0}^{n} (x - x_i)\right) + \frac{d}{dx} \left(\frac{f^{(n+1)}(\xi(x))}{(n+1)!}\right) \left(\prod_{i=0}^{n} (x - x_i)\right).$$

Last term messy, but = 0 for $x = x_k, k = 0, 1, \dots, n$

$$f'(x_k) = \left(\sum_{j=0}^n f(x_j) L'_j(x_k)\right) + \left(\frac{f^{(n+1)}(\xi(x_k))}{(n+1)!}\right) \left(\prod_{i \neq k} (x_k - x_i)\right)$$

$$\approx \sum_{j=0}^n f(x_j) L'_j(x_k).$$

(n+1)-point formula, works (in theory) for any nodal choices.

2-point formulas (n = 1), j = 0, 1

$$L_0(x) = \frac{x - x_1}{x_0 - x_1}, \quad L'_0(x) = \frac{1}{x_0 - x_1},$$

$$L_1(x) = \frac{x - x_0}{x_1 - x_0}, \quad L'_1(x) = \frac{1}{x_1 - x_0} = -L'_0(x)$$

2-point formulas (n = 1), j = 0, 1

$$L_0(x) = \frac{x - x_1}{x_0 - x_1}, \quad L'_0(x) = \frac{1}{x_0 - x_1},$$

$$L_1(x) = \frac{x - x_0}{x_1 - x_0}, \quad L'_1(x) = \frac{1}{x_1 - x_0} = -L'_0(x)$$

So
$$f'(x_0) \approx f(x_0) L'_0(x_0) + f(x_1) L'_1(x_0) = \frac{f(x_1) - f(x_0)}{x_1 - x_0},$$

 $f'(x_1) \approx f(x_0) L'_0(x_1) + f(x_1) L'_1(x_1) = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$

$$f'(x_k) = \left(\sum_{j=0}^n f(x_j) L'_j(x_k)\right) + \left(\frac{f^{(n+1)}(\xi(x_k))}{(n+1)!}\right) \left(\prod_{i \neq k} (x_k - x_i)\right)$$

$$\approx \sum_{j=0}^n f(x_j) L'_j(x_k),$$

$$L'_j(x_k) = \begin{cases} \frac{1}{x_j - x_k} \prod_{i \neq j, k} \frac{(x_k - x_i)}{(x_j - x_i)}, & \text{for } k \neq j, \\ \sum_{i \neq i} \frac{1}{x_i - x_i} & \text{for } k = j. \end{cases}$$

(n+1)-point formula, works for any nodal choices.

3-point formulas (n = 2), equi-spaced nodes

Choose $x_1 = x_0 + h, x_2 = x_0 + 2h$, with $h \neq 0$.

$$f'(x_0) = \frac{1}{2h} (-3f(x_0) + 4f(x_1) - f(x_2)) + \frac{h^2}{3} f^{(3)} f(\xi_0)$$

$$= \frac{1}{2h} (-3f(x_0) + 4f(x_0 + h) - f(x_0 + 2h)) + \frac{h^2}{3} f^{(3)} f(\xi_0)$$

$$f'(x_0 + h) = \frac{1}{2h} (-f(x_0) + f(x_0 + 2h)) - \frac{h^2}{6} f^{(3)} f(\xi_1)$$

$$f'(x_0 + 2h) = \frac{1}{2h} (f(x_0) - 4f(x_0 + h) + 3f(x_0 + 2h)) + \frac{h^2}{3} f^{(3)} f(\xi_2)$$

Second order derivatives, equi-spaced points

$$f(x_0 + h) = f(x_0) + f'(x_0) h + \frac{1}{2} f''(x_0) h^2 + \frac{1}{6} f'''(x_0) h^3 + \frac{1}{24} f^{(4)}(\xi_+) h^4,$$

$$f(x_0 - h) = f(x_0) - f'(x_0) h + \frac{1}{2} f''(x_0) h^2 - \frac{1}{6} f'''(x_0) h^3 + \frac{1}{24} f^{(4)}(\xi_-) h^4.$$

Second order derivatives, equi-spaced points

$$f(x_0 + h) = f(x_0) + f'(x_0) h + \frac{1}{2} f''(x_0) h^2 + \frac{1}{6} f'''(x_0) h^3 + \frac{1}{24} f^{(4)}(\xi_+) h^4,$$

$$f(x_0 - h) = f(x_0) - f'(x_0) h + \frac{1}{2} f''(x_0) h^2 - \frac{1}{6} f'''(x_0) h^3 + \frac{1}{24} f^{(4)}(\xi_-) h^4.$$

Adding up, terms with difference signs cancel,

$$f(x_0 + h) + f(x_0 - h) = 2f(x_0) + f''(x_0) h^2 + \frac{h^4}{24} \left(f^{(4)}(\xi_+) + f^{(4)}(\xi_-) \right)$$
$$= 2f(x_0) + f''(x_0) h^2 + \frac{2h^4}{24} f^{(4)}(\xi).$$

Second order derivatives, equi-spaced points

$$f(x_0 + h) = f(x_0) + f'(x_0) h + \frac{1}{2} f''(x_0) h^2 + \frac{1}{6} f'''(x_0) h^3 + \frac{1}{24} f^{(4)}(\xi_+) h^4,$$

$$f(x_0 - h) = f(x_0) - f'(x_0) h + \frac{1}{2} f''(x_0) h^2 - \frac{1}{6} f'''(x_0) h^3 + \frac{1}{24} f^{(4)}(\xi_-) h^4.$$

Adding up, terms with difference signs cancel,
$$f(x_0+h)+f(x_0-h) = 2f(x_0)+f''(x_0)\,h^2+\frac{h^4}{24}\left(f^{(4)}(\xi_+)+f^{(4)}(\xi_-)\right)$$
$$= 2f(x_0)+f''(x_0)\,h^2+\frac{2h^4}{24}f^{(4)}(\xi).$$
 Therefore

Therefore
$$f''(x_0) = \frac{f(x_0 + h) + f(x_0 - h) - 2f(x_0)}{h^2} - \frac{h^2}{12}f^{(4)}(\xi).$$

Three-point midpoint formula

$$f'(x_0) = \frac{f(x_0+h)-f(x_0-h)}{2h} - \frac{h^2}{6}f^{(3)}(\xi).$$

- every computation incurs round-off error.
- division by 2h magnifies round-off error
- assume round-off error model

$$f(x_0 + h) = \widehat{f}(x_0 + h) + e(x_0 + h)$$

 $f(x_0 - h) = \widehat{f}(x_0 - h) + e(x_0 - h)$

$$\text{ for } |e(x_0+h)| \le \epsilon, \ |e(x_0-h)| \le \epsilon$$

no other round-off errors

Three-point midpoint formula

$$f'(x_0) = \frac{f(x_0 + h) - f(x_0 - h)}{2h} - \frac{h^2}{6}f^{(3)}(\xi).$$

- every computation incurs round-off error.
- division by 2h magnifies round-off error
- assume round-off error model

$$f(x_0 + h) = \widehat{f}(x_0 + h) + e(x_0 + h)$$

 $f(x_0 - h) = \widehat{f}(x_0 - h) + e(x_0 - h)$

for
$$|e(x_0 + h)| \le \epsilon$$
, $|e(x_0 - h)| \le \epsilon$

no other round-off errors

It follows

$$\begin{split} f'(x_0) &- \frac{\widehat{f}(x_0 + h) - \widehat{f}(x_0 - h)}{2h} \\ &= \frac{e(x_0 + h) - e(x_0 - h)}{2h} - \frac{h^2}{6} f^{(3)}(\xi) \\ \left| f'(x_0) - \frac{\widehat{f}(x_0 + h) - \widehat{f}(x_0 - h)}{2h} \right| \\ &\leq \left| \frac{e(x_0 + h) - e(x_0 - h)}{2h} \right| + \frac{h^2}{6} |f^{(3)}(\xi)| \end{split}$$

Three-point midpoint formula

$$f'(x_0) = \frac{f(x_0 + h) - f(x_0 - h)}{2h} - \frac{h^2}{6}f^{(3)}(\xi).$$

- every computation incurs round-off error.
- division by 2h magnifies round-off error
- assume round-off error model

$$f(x_0 + h) = \widehat{f}(x_0 + h) + e(x_0 + h)$$

 $f(x_0 - h) = \widehat{f}(x_0 - h) + e(x_0 - h)$

for $|e(x_0 + h)| < \epsilon$, $|e(x_0 - h)| < \epsilon$

no other round-off errors

It follows

$$f'(x_0) - \frac{\widehat{f}(x_0 + h) - \widehat{f}(x_0 - h)}{2h}$$

$$= \frac{e(x_0 + h) - e(x_0 - h)}{2h} - \frac{h^2}{6} f^{(3)}(\xi)$$

$$\left| f'(x_0) - \frac{\widehat{f}(x_0 + h) - \widehat{f}(x_0 - h)}{2h} \right|$$

$$\leq \left| \frac{e(x_0 + h) - e(x_0 - h)}{2h} \right| + \frac{h^2}{6} |f^{(3)}(\xi)|$$

▶ assume an upper bound: $|f^{(3)}(\xi)| \leq M$

$$\left|f'(x_0) - \frac{\widehat{f}(x_0 + h) - \widehat{f}(x_0 - h)}{2h}\right| \leq \frac{\epsilon}{h} + \frac{Mh^2}{6} \stackrel{def}{=} e(h).$$

Three-point midpoint formula

$$f'(x_0) = \frac{f(x_0 + h) - f(x_0 - h)}{2h} - \frac{h^2}{6}f^{(3)}(\xi).$$

- every computation incurs round-off error.
- division by 2h magnifies round-off error
- assume round-off error model

$$f(x_0 + h) = \widehat{f}(x_0 + h) + e(x_0 + h)$$

 $f(x_0 - h) = \widehat{f}(x_0 - h) + e(x_0 - h)$

for $|e(x_0 + h)| < \epsilon$, $|e(x_0 - h)| < \epsilon$

no other round-off errors

It follows

$$f'(x_0) - \frac{\widehat{f}(x_0 + h) - \widehat{f}(x_0 - h)}{2h}$$

$$= \frac{e(x_0 + h) - e(x_0 - h)}{2h} - \frac{h^2}{6} f^{(3)}(\xi)$$

$$\left| f'(x_0) - \frac{\widehat{f}(x_0 + h) - \widehat{f}(x_0 - h)}{2h} \right|$$

$$\leq \left| \frac{e(x_0 + h) - e(x_0 - h)}{2h} \right| + \frac{h^2}{6} |f^{(3)}(\xi)|$$

ightharpoonup assume an upper bound: $|f^{(3)}(\xi)| \leq M$

$$\left|f'(x_0) - \frac{\widehat{f}(x_0 + h) - \widehat{f}(x_0 - h)}{2h}\right| \leq \frac{\epsilon}{h} + \frac{Mh^2}{6} \stackrel{def}{=} e(h).$$

ightharpoonup e(h) too big as $h \longrightarrow 0^+$

Round-Off Error Instability: optimal h choice

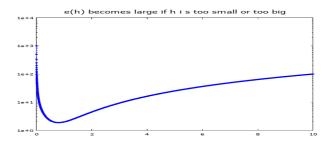
$$e(h) = \frac{\epsilon}{h} + \frac{M h^2}{6}$$

is smallest at

$$h_{\min} = \left(\frac{3\epsilon}{M}\right)^{\frac{1}{3}} = O\left(\epsilon^{\frac{1}{3}}\right),$$

with

$$e(h_{\min}) = \frac{1}{2} \left(9 M \epsilon^2\right)^{\frac{1}{3}} = O\left(\epsilon^{\frac{2}{3}}\right).$$



▶ **Given (I)**: A formula $N_1(h)$ that approximates an unknown constant M for any $h \neq 0$.

▶ **Given (I)**: A formula $N_1(h)$ that approximates an unknown constant M for any $h \neq 0$.

(Example:
$$f'(x_0) \approx \frac{f(x_0+h)-f(x_0)}{h}$$
)

Solution Given (I): A formula $N_1(h)$ that approximates an unknown constant M for any $h \neq 0$.

(Example:
$$f'(x_0) \approx \frac{f(x_0+h)-f(x_0)}{h}$$
)

▶ **Given (II)**: Truncation error satisfies power series for $h \neq 0$

$$M - N_1(h) = K_1 h + K_2 h^2 + K_3 h^3 + \dots = O(h),$$
 (1)

with (unknown) constants $K1, K_2, K_3, \cdots$.

▶ **Given (I)**: A formula $N_1(h)$ that approximates an unknown constant M for any $h \neq 0$.

(EXAMPLE:
$$f'(x_0) \approx \frac{f(x_0 + h) - f(x_0)}{h}$$
)

▶ **Given (II)**: Truncation error satisfies power series for $h \neq 0$

$$M - N_1(h) = K_1 h + K_2 h^2 + K_3 h^3 + \dots = O(h),$$
 (1)

with (unknown) constants $K1, K_2, K_3, \cdots$.

$$\left(f'(x_0) - \frac{f(x_0 + h) - f(x_0)}{h} = -\frac{1}{2} h f''(x_0) - \dots - \frac{1}{n!} h^{n-1} f^{(n)}(x_0) - \dots\right)$$

Goal: Generate higher order approximations

Key: Equation (1) works for any $h \neq 0$, including $\frac{h}{2}$.

Extrapolation, Step I

$$M - N_1(h) = K_1 h + K_2 h^2 + K_3 h^3 + \cdots,$$
(1)

$$M - N_1(\frac{h}{2}) = K_1(\frac{h}{2}) + K_2(\frac{h}{2})^2 + K_3(\frac{h}{2})^3 + \cdots.$$
(2)

 $(2)\times 2-(1)$:

$$M - N_2(h) = -\frac{K_2}{2}h^2 - \frac{3K_3}{4}h^3 - \dots - (1 - 2^{-(t-1)})K_th^t - \dots,$$

$$\stackrel{def}{=} \widehat{K}_2h^2 + \widehat{K}_3h^3 + \dots \widehat{K}_th^t + \dots = O(h^2), \qquad (3)$$

where
$$N_2(h) = N_1(\frac{h}{2}) + \left(N_1(\frac{h}{2}) - N_1(h)\right)$$
.

Equation (3) again power series, but now 2nd order.

Extrapolation, Step II

$$M - N_2(h) = \widehat{K}_2 h^2 + \widehat{K}_3 h^3 + \cdots \widehat{K}_t h^t + \cdots,$$

$$M - N_2(\frac{h}{2}) = \widehat{K}_2(\frac{h}{2})^2 + \widehat{K}_3(\frac{h}{2})^3 + \cdots.$$
(4)

$$\frac{(4)\times 2^2-(3)}{2^2-1}$$
:

$$M - N_3(h) = -\frac{\widehat{K}_3}{6}h^3 - \dots - \frac{1 - 2^{-(t-2)}}{3}\widehat{K}_t h^t - \dots, \quad (5)$$
where $N_3(h) \stackrel{def}{=} N_2(\frac{h}{2}) + \frac{N_2(\frac{h}{2}) - N_2(h)}{3}.$

Equation (5) is one more power series, but 3rd order.

Extrapolation, Step III

Assume

$$M - N_j(h) = \widehat{K}_j h^j + \widehat{K}_{j+1} h^{j+1} + \cdots \widehat{K}_t h^t + \cdots,$$

replace h by h/2:

$$M-N_j(\frac{h}{2})=\widehat{K}_j(\frac{h}{2})^j+\widehat{K}_{j+1}(\frac{h}{2})^{j+1}+\cdots\widehat{K}_t(\frac{h}{2})^t+\cdots.$$

 $\frac{\text{second equation } \times 2^{j} - \text{ first equation}}{2^{j} - 1}$:

$$M - N_{j+1}(h) = -\frac{K_{j+1}}{2(2^{j}-1)}h^{j+1} - \cdots = O(h^{j+1}),$$

where
$$N_{j+1}(h) \stackrel{def}{=} N_j(\frac{h}{2}) + \frac{N_j(\frac{h}{2}) - N_j(h)}{2^j - 1}$$
.

Richardson's Extrapolation Table

Richardson's Extrapolation: even power series

- ▶ **Given (I)**: A formula $N_1(h)$ that approximates an unknown constant M for any $h \neq 0$.
- ▶ **Given (II)**: Truncation error satisfies even power series

$$M - N_1(h) = K_1 h^2 + K_2 h^4 + K_3 h^6 + \dots = O(h^2),$$
 (1)

with (unknown) constants $K1, K_2, K_3, \cdots$.

Goal: Generate higher order approximations

Key: Equation (1) works for any h, including $\frac{h}{2}$.

Even power extrapolation, Step I

$$M - N_1(h) = K_1 h^2 + K_2 h^4 + K_3 h^6 + \cdots,$$
(1)

$$M - N_1(\frac{h}{2}) = K_1(\frac{h}{2})^2 + K_2(\frac{h}{2})^4 + K_3(\frac{h}{2})^6 + \cdots.$$
(2)

$$\frac{(2)\times 2^2-(1)}{2^2-1}$$
:

$$M - N_2(h) = -\frac{K_2}{4}h^4 - \frac{5K_3}{16}h^6 - \dots - \frac{1 - 2^{-2(t-1)}}{3}K_th^{2t} - \dots,$$

$$\stackrel{def}{=} \widehat{K}_2h^4 + \widehat{K}_3h^6 + \dots \widehat{K}_th^{2t} + \dots = O(h^4), \qquad (3)$$

where
$$N_2(h) = N_1(\frac{h}{2}) + \frac{N_1(\frac{h}{2}) - N_1(h)}{3}$$
.

Equation (3) again even power series, but now 4th order.

Even extrapolation, Step II

$$M - N_2(h) = \widehat{K}_2 h^4 + \widehat{K}_3 h^6 + \cdots \widehat{K}_t h^{2t} + \cdots, \qquad (3)$$

$$M - N_2(\frac{h}{2}) = \widehat{K}_2(\frac{h}{2})^4 + \widehat{K}_3(\frac{h}{2})^6 + \cdots$$
 (4)

$$\frac{(4)\times 2^4-(3)}{2^4-1}:$$

$$M - N_3(h) = -\frac{\widehat{K}_3}{20}h^6 - \dots - \frac{1 - 2^{-2(t-2)}}{15}\widehat{K}_th^{2t} - \dots,$$
where $N_3(h) \stackrel{def}{=} N_2(\frac{h}{2}) + \frac{N_2(\frac{h}{2}) - N_2(h)}{15}.$

One more even power series, but now 6-th order.

Even extrapolation, Step III

Assume

$$M - N_j(h) = \widehat{K}_j h^{2j} + \widehat{K}_{j+1} h^{2(j+1)} + \cdots \widehat{K}_t h^{2t} + \cdots,$$

replace h by h/2:

$$M - N_j(\frac{h}{2}) = \widehat{K}_j(\frac{h}{2})^{2j} + \widehat{K}_{j+1}(\frac{h}{2})^{2(j+1)} + \cdots \widehat{K}_t(\frac{h}{2})^{2t} + \cdots$$

 $\frac{\text{second equation } \times 4^{j} - \text{ first equation}}{4^{j} - 1}$:

$$M - N_{j+1}(h) = -\frac{3\widehat{K}_{j+1}}{4(4^{j}-1)}h^{2(j+1)} - \cdots = O\left(h^{2(j+1)}\right),$$

where
$$N_{j+1}(h) \stackrel{\text{def}}{=} N_j(\frac{h}{2}) + \frac{N_j(\frac{h}{2}) - N_j(h)}{4^j - 1}$$
.

Richardson's Even Extrapolation Table

Even extrapolation, example

Consider Taylor expansion for a given function f(x) with h > 0:

$$f(x+h) = f(x) + f'(x) h + \frac{1}{2} f''(x) h^2 + \dots + \frac{1}{n!} f^{(n)}(x) h^n + \dots,$$

$$f(x-h) = f(x) - f'(x) h + \frac{1}{2} f''(x) h^2 + \dots + \frac{1}{n!} f^{(n)}(x) (-h)^n + \dots.$$

Take the difference:

$$\frac{f(x+h)-f(x-h)}{2h}=f'(x)+\cdots+\frac{1}{(2t+1)!}f^{(2t+1)}(x)h^{2t}+\cdots.$$

This is an even power series with 2nd order approximation

$$f'(x), \approx N_1(h) \stackrel{\text{def}}{=} \frac{f(x+h) - f(x-h)}{2h}.$$

Even extrapolation, example

Consider Taylor expansion for a given function f(x) with h > 0:

$$f(x+h) = f(x) + f'(x) h + \frac{1}{2} f''(x) h^2 + \dots + \frac{1}{n!} f^{(n)}(x) h^n + \dots,$$

$$f(x-h) = f(x) - f'(x) h + \frac{1}{2} f''(x) h^2 + \dots + \frac{1}{n!} f^{(n)}(x) (-h)^n + \dots.$$

Take the difference:

$$\frac{f(x+h)-f(x-h)}{2h}=f'(x)+\cdots+\frac{1}{(2t+1)!}f^{(2t+1)}(x)h^{2t}+\cdots$$

This is an even power series with 2nd order approximation

$$f'(x), \approx N_1(h) \stackrel{\text{def}}{=} \frac{f(x+h) - f(x-h)}{2h}.$$

4th order approximation

$$f'(x) \approx N_1(h) + \frac{N_1(h) - N_1(2h)}{3}$$

$$= \frac{f(x - 2h) - 8f(x - h) + 8f(x + h) - f(x + 2h)}{12h}$$

Even extrapolation, example

Approximate f'(2.0) with central difference $N_1(0.1)$ and extrapolation $N_2(0.1)$ for $f(x) = xe^x$.

Solution:
$$f'(x) = (1+x)e^x$$
, therefore $f'(2.0) = 3e^2 \approx 22.167$.

$$N_1(0.1) = \frac{f(2.1) - f(1.9)}{2 \times 0.1} \approx 22.229.$$

$$N_1(0.2) = \frac{f(2.2) - f(1.8)}{2 \times 0.2} \approx 22.414.$$

 $N_2(0.2) = N_1(h) + \frac{N_1(h) - N_1(2h)}{3} \approx 22.167.$

- covers material up to and include §4.2 (six questions total)
 - one question each from chapters 1 and 4
 - two questions each from chapters 2 and 3

- covers material up to and include §4.2 (six questions total)
 - one question each from chapters 1 and 4
 - two questions each from chapters 2 and 3
- ▶ DSP students will get DSP recommended extra time
- Sample exam has been provided.
 Solutions available over the weekend

- covers material up to and include §4.2 (six questions total)
 - one question each from chapters 1 and 4
 - two questions each from chapters 2 and 3
- DSP students will get DSP recommended extra time
- Sample exam has been provided.
 Solutions available over the weekend
- one page cheat sheet on one side only

- covers material up to and include §4.2 (six questions total)
 - one question each from chapters 1 and 4
 - two questions each from chapters 2 and 3
- DSP students will get DSP recommended extra time
- Sample exam has been provided. Solutions available over the weekend
- one page cheat sheet on one side only
- You can skip the exam, but this is NOT encouraged
 - Final worth 50 (as opposed to 30) points if you do skip.
 - If you submit the exam, it WILL count.



Sample exam problem

► How many multiplications and additions are required to determine a sum of the form

$$S \stackrel{\text{def}}{=} \sum_{i=1}^{n} \sum_{j=1}^{m} \alpha_{i} \beta_{j}$$
 (1)

▶ Modify the sum in part (1) to an equivalent form that reduces the number of computations.

► How many multiplications and additions are required to determine a sum of the form

$$S \stackrel{\text{def}}{=} \sum_{i=1}^{n} \sum_{j=1}^{m} \alpha_{i} \beta_{j} \tag{1}$$

▶ Modify the sum in part (1) to an equivalent form that reduces the number of computations.

SOLUTION:

- \blacktriangleright it takes m n multiplications and m n additions in (1).
- Rewrite

$$S \stackrel{\text{def}}{=} \left(\sum_{i=1}^{n} \alpha_i \right) \left(\sum_{j=1}^{m} \beta_j \right)$$

it takes 1 multiplication and m + n additions.

The following two methods are proposed to compute $7^{1/5}$. Discuss their orders of convergence, assuming $p_0 = 1$.

- 1. $p_{n+1} = p_n \frac{p_n^5 7}{5 p_n^4}$ 2. $p_{n+1} = p_n \frac{p_n^5 7}{100}$

The following two methods are proposed to compute $7^{1/5}$. Discuss their orders of convergence, assuming $p_0 = 1$.

- 1. $p_{n+1} = p_n \frac{p_n^5 7}{5 p_n^4}$
- 2. $p_{n+1} = p_n \frac{p_n^5 7}{100}$

SOLUTION:

- 1. Newton's method, quadratic convergence.
- 2. fixed point iteration, linear convergence.

A quadratic spline interpolating function S defined with the nodes $x_0 < x_1 < x_2$ is such that S is a quadratic polynomial on each of the intervals $[x_0, x_1]$ and $[x_1, x_2]$, respectively. Assume that $S(x) \in C^2[x_0, x_2]$. Show that S must be a quadratic polynomial on the entire interval $[x_0, x_2]$.

A quadratic spline interpolating function S defined with the nodes $x_0 < x_1 < x_2$ is such that S is a quadratic polynomial on each of the intervals $[x_0, x_1]$ and $[x_1, x_2]$, respectively. Assume that $S(x) \in C^2[x_0, x_2]$. Show that S must be a quadratic polynomial on the entire interval $[x_0, x_2]$.

SOLUTION: Parameterize S as

$$S(x) = \begin{cases} a_0 + b_0 (x - x_1) + c_0 (x - x_1)^2, & \text{if } x \in [x_0, x_1], \\ a_1 + b_1 (x - x_1) + c_1 (x - x_1)^2, & \text{if } x \in [x_1, x_2]. \end{cases}$$

The condition that $S(x) \in C^2[x_0, x_2]$ implies that

$$S(x)\Big|_{x=x_1^-} = S(x)\Big|_{x=x_1^+}, \ S(x)'\Big|_{x=x_1^-} = S(x)'\Big|_{x=x_1^+}, \ S(x)''\Big|_{x=x_1^-} = S(x)''\Big|_{x=x_1^+}$$

This leads to

$$a_0 = a_1, \quad b_0 = b_1, \quad c_0 = c_1$$

§4.3 Numerical Integration: general idea

▶ **Goal**: Numerical method /quadrature for approximating $\int_a^b f(x)dx$.

§4.3 Numerical Integration: general idea

- ▶ **Goal**: Numerical method /quadrature for approximating $\int_a^b f(x)dx$.
- **Approach**: Replacing f(x) by a polynomial.
 - ▶ **Choose**: n + 1 points $a < x_0 < x_1 < \cdots < x_n < b$.
 - ► Interpolation:

$$f(x) = P(x) + \frac{f^{(n+1)}(\xi(x))}{(n+1)!} \prod_{i=0}^{n} (x - x_i), \quad P(x) = \sum_{i=0}^{n} f(x_i) L_j(x).$$

Approximate Integration:

$$\int_{a}^{b} f(x)dx = \left(\int_{a}^{b} P(x)dx\right) + \frac{1}{(n+1)!} \int_{a}^{b} f^{(n+1)}(\xi(x)) \prod_{j=0}^{n} (x - x_{j}) dx$$

$$= \left(\sum_{j=0}^{n} a_{j} f(x_{j})\right) + \frac{1}{(n+1)!} \int_{a}^{b} f^{(n+1)}(\xi(x)) \prod_{j=0}^{n} (x - x_{j}) dx$$

$$\approx \sum_{j=0}^{n} a_{j} f(x_{j}),$$

§4.3 Numerical Integration: general idea

- ▶ **Goal**: Numerical method /quadrature for approximating $\int_a^b f(x)dx$.
- **Approach**: Replacing f(x) by a polynomial.
 - Choose: n+1 points a ≤ x₀ < x₁ < · · · < x_n ≤ b.
 Interpolation:

$$f(x) = P(x) + \frac{f^{(n+1)}(\xi(x))}{(n+1)!} \prod_{i=0}^{n} (x - x_i), \quad P(x) = \sum_{i=0}^{n} f(x_i) L_i(x).$$

► Approximate Integration:

$$\int_{a}^{b} f(x)dx = \left(\int_{a}^{b} P(x)dx\right) + \frac{1}{(n+1)!} \int_{a}^{b} f^{(n+1)}(\xi(x)) \prod_{j=0}^{n} (x-x_{j}) dx$$

$$= \left(\sum_{j=0}^{n} a_{j} f(x_{j})\right) + \frac{1}{(n+1)!} \int_{a}^{b} f^{(n+1)}(\xi(x)) \prod_{j=0}^{n} (x - x_{j}) dx$$

$$\approx \sum_{j=0}^{n} a_{j} f(x_{j}), \text{ with } a_{j} = \int_{a}^{b} L_{j}(x) dx = \int_{a}^{b} \prod_{k \neq j} \frac{(x - x_{k})}{(x_{j} - x_{k})} dx.$$

The Trapezoidal Rule: n = 1, $x_0 = a$, $x_1 = b$, h = b - a.

Linear Interpolation:

$$P_1(x) = \frac{(x-x_1)}{(x_0-x_1)}f(x_0) + \frac{(x-x_0)}{(x_1-x_0)}f(x_1),$$

$$f(x) = P_1(x) + \frac{1}{2}f''(\xi(x))(x-x_0)(x-x_1).$$

The Trapezoidal Rule: n = 1, $x_0 = a$, $x_1 = b$, h = b - a.

► Linear Interpolation:

$$P_1(x) = \frac{(x-x_1)}{(x_0-x_1)}f(x_0) + \frac{(x-x_0)}{(x_1-x_0)}f(x_1),$$

$$f(x) = P_1(x) + \frac{1}{2}f''(\xi(x))(x-x_0)(x-x_1).$$

Quadrature:

$$\int_{a}^{b} P_{1}(x)dx = \int_{a}^{b} \left(\frac{(x-x_{1})}{(x_{0}-x_{1})} f(x_{0}) + \frac{(x-x_{0})}{(x_{1}-x_{0})} f(x_{1}) \right) dx$$

$$= \frac{1}{2} \left(\frac{(x-x_{1})^{2}}{(x_{0}-x_{1})} f(x_{0}) + \frac{(x-x_{0})^{2}}{(x_{1}-x_{0})} f(x_{1}) \right)_{x_{0}}^{x_{1}} = \frac{h}{2} \left(f(x_{0}) + f(x_{1}) \right).$$

The Trapezoidal Rule: n = 1, $x_0 = a$, $x_1 = b$, h = b - a. Linear Interpolation:

$$(x_0)$$

$$\frac{1}{2}f(x)$$

$$=\frac{1}{2}\left(\frac{(x-x_1)^2}{(x_0-x_1)}f(x_0)+\frac{(x-x_0)^2}{(x_1-x_0)}f(x_1)\right)_{x_0}^{x_1}=\frac{h}{2}\left(f(x_0)+f(x_1)\right).$$

error =
$$\int_{a}^{b} \frac{1}{2} f''(\xi(x))(x - x_{0})(x - x_{1}) dx$$
=
$$\frac{f''(\xi)}{2} \int_{a}^{b} (x - x_{0})(x - x_{1}) dx$$

$$P_1(x) = \frac{(x-x_1)}{(x_0-x_1)}f(x_0) + \frac{(x-x_0)}{(x_1-x_0)}f(x_1),$$

$$f(x) = P_1(x) + \frac{1}{2}f''(\xi(x))(x - x_0)(x - x_1).$$

$$f^b = \int_a^b \int_a^$$

$$f(x) dx = \int_{a}^{b} \left(\frac{x}{x} \right) dx$$

$$\int_{a}^{b} P_{1}(x)dx = \int_{a}^{b} \left(\frac{(x-x_{1})}{(x_{0}-x_{1})} f(x_{0}) + \frac{(x-x_{0})}{(x_{1}-x_{0})} f(x_{1}) \right) dx$$

 $= -\frac{f''(\xi)}{12}(b-a)^3$

Quadratic Interpolation:

$$P_2(x_j) = f(x_j), \quad j = 0, 1, 2.$$

$$P_{2}(x) = \frac{(x-x_{1})(x-x_{2})}{(x_{0}-x_{1})(x_{0}-x_{2})}f(x_{0}) + \frac{(x-x_{1})(x-x_{0})}{(x_{2}-x_{1})(x_{2}-x_{0})}f(x_{2}) + \frac{(x-x_{0})(x-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})}f(x_{1}).$$

Interpolation error:

$$f(x) = P_2(x) + \frac{1}{3!}f^{(4)}(\xi(x))(x - x_0)(x - x_1)(x - x_2).$$

► Simpson's Rule and error:

$$\int_{a}^{b} f(x) dx = \int_{a}^{b} P_{2}(x) dx + \int_{a}^{b} \left(\frac{1}{3!} f^{(4)}(\xi(x))(x - x_{0})(x - x_{1})(x - x_{2})\right) dx$$

Simpson's Rule: n = 2, $x_0 = a$, $x_1 = \frac{a+b}{2}$, $x_2 = b$, $h = \frac{b-a}{2}$. **Quadratic Interpolation:**

$$P_2(x_i) = f(x_i), \quad j = 0, 1, 2.$$

$$P_2(x) = \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)}f(x_0) + \frac{(x-x_1)(x-x_0)}{(x_2-x_1)(x_2-x_0)}f(x_2)$$

 $+\frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)}f(x_1).$

$$f(x) = P_2(x) + \frac{1}{3!}f^{(4)}(\xi(x))(x - x_0)(x - x_1)(x - x_2).$$

 $\int_{a}^{b} f(x) dx = \int_{a}^{b} P_{2}(x) dx + \int_{a}^{b} \left(\frac{1}{3!} f^{(4)}(\xi(x))(x - x_{0})(x - x_{1})(x - x_{2}) \right) dx$ $\approx \int_{-\infty}^{b} P_2(x) dx = \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2))$

Quadrature Rule

$$\int_{a}^{b} f(x) dx \approx \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2))$$

$$\int_{a}^{b} (f(x_{0}) dx \approx \frac{h}{3} (f(x_{0}) + 4f(x_{1}) + f(x_{2}))$$

Quadrature Error:
$$\frac{1}{3!} \int_{a}^{b} f^{(3)}(\xi(x))(x - x_0)(x - x_1)(x - x_2) dx$$

$$\frac{1}{3!} \int_{a}^{b} f^{(3)}(\xi(x))(x - x_0)(x - x_1)(x - x_2) dx$$

$$\frac{\text{maybe}}{6} \frac{f^{(3)}(\xi)}{6} \int_{a}^{b} (x - x_0)(x - x_1)(x - x_2) dx$$

$$\frac{???}{6} 0.$$

$$\int_{a}^{b} f(x) dx \approx \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2))$$

Quadrature Error:
$$\frac{1}{3!} \int_{a}^{b} f^{(3)}(\xi(x))(x - x_0)(x - x_1)(x - x_2) dx$$

$$= \frac{1}{3!} \int_{a}^{b} f^{(3)}(\xi(x))(x - x_0)(x - x_1)(x - x_2) dx$$

$$= \frac{\text{maybe}}{6} \int_{a}^{b} (x - x_0)(x - x_1)(x - x_2) dx$$

$$= \frac{???}{6} = 0.$$

Error estimate wrong. Need approach better than in book.

Cubic Interpolation with double node in x_1 :

$$P_3(x_j) = f(x_j), \quad j = 0, 1, 2; \quad P'_3(x_1) = f'(x_1).$$

$$P_{3}(x) = \frac{(x-x_{1})^{2}(x-x_{2})}{(x_{0}-x_{1})^{2}(x_{0}-x_{2})}f(x_{0}) + \frac{(x-x_{1})^{2}(x-x_{0})}{(x_{2}-x_{1})^{2}(x_{2}-x_{0})}f(x_{2})$$

$$+ \frac{(x-x_{0})(x-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})}\left(1 - \frac{(x-x_{1})(2x_{1}-x_{0}-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})}\right)f(x_{1})$$

$$+ \frac{(x-x_{0})(x-x_{1})(x-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})}f'(x_{1}).$$

Cubic Interpolation with double node in x_1 :

$$P_3(x_j) = f(x_j), \quad j = 0, 1, 2; \quad P'_3(x_1) = f'(x_1).$$

$$P_{3}(x) = \frac{(x-x_{1})^{2}(x-x_{2})}{(x_{0}-x_{1})^{2}(x_{0}-x_{2})}f(x_{0}) + \frac{(x-x_{1})^{2}(x-x_{0})}{(x_{2}-x_{1})^{2}(x_{2}-x_{0})}f(x_{2})$$

$$+ \frac{(x-x_{0})(x-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})}\left(1 - \frac{(x-x_{1})(2x_{1}-x_{0}-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})}\right)f(x_{1})$$

$$+ \frac{(x-x_{0})(x-x_{1})(x-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})}f'(x_{1}).$$

Interpolation error:

$$f(x) = P_3(x) + \frac{1}{4!}f^{(4)}(\xi(x))(x - x_0)(x - x_1)^2(x - x_2)$$

Quadrature Rule

$$\int_{a}^{b} P_{3}(x) dx = f(x_{0}) \int_{a}^{b} \frac{(x - x_{1})^{2}(x - x_{2})}{(x_{0} - x_{1})^{2}(x_{0} - x_{2})} dx + f(x_{2}) \int_{a}^{b} \frac{(x - x_{1})^{2}(x - x_{0})}{(x_{2} - x_{1})^{2}(x_{2} - x_{0})} dx$$
$$+ f(x_{1}) \int_{a}^{b} \frac{(x - x_{0})(x - x_{2})}{(x_{1} - x_{0})(x_{1} - x_{2})} \left(1 - \frac{(x - x_{1})(2x_{1} - x_{0} - x_{2})}{(x_{1} - x_{0})(x_{1} - x_{2})}\right) dx$$

$$+f'(x_1)\int_a^b \frac{(x-x_0)(x-x_1)(x-x_2)}{(x_1-x_0)(x_1-x_2)} dx$$

Quadrature Rule

$$\int_{a}^{b} P_{3}(x)dx = f(x_{0}) \int_{a}^{b} \frac{(x-x_{1})^{2}(x-x_{2})}{(x_{0}-x_{1})^{2}(x_{0}-x_{2})} dx + f(x_{2}) \int_{a}^{b} \frac{(x-x_{1})^{2}(x-x_{0})}{(x_{2}-x_{1})^{2}(x_{2}-x_{0})} dx$$
$$+ f(x_{1}) \int_{a}^{b} \frac{(x-x_{0})(x-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})} \left(1 - \frac{(x-x_{1})(2x_{1}-x_{0}-x_{2})}{(x_{1}-x_{0})(x_{1}-x_{2})}\right) dx$$

$$+f'(x_1) \int_a^b \frac{(x-x_0)(x-x_1)(x-x_2)}{(x_1-x_0)(x_1-x_2)} dx$$
!! $h(f(x_1) + f(x_2) + f(x_3))$

 $\stackrel{!!!}{=} \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2)).$

Quadrature Rule

$$\int_{a}^{b} P_{3}(x) dx = f(x_{0}) \int_{a}^{b} \frac{(x - x_{1})^{2}(x - x_{2})}{(x_{0} - x_{1})^{2}(x_{0} - x_{2})} dx + f(x_{2}) \int_{a}^{b} \frac{(x - x_{1})^{2}(x - x_{0})}{(x_{2} - x_{1})^{2}(x_{2} - x_{0})} dx
+ f(x_{1}) \int_{a}^{b} \frac{(x - x_{0})(x - x_{2})}{(x_{1} - x_{0})(x_{1} - x_{2})} \left(1 - \frac{(x - x_{1})(2x_{1} - x_{0} - x_{2})}{(x_{1} - x_{0})(x_{1} - x_{2})}\right) dx
+ f'(x_{1}) \int_{a}^{b} \frac{(x - x_{0})(x - x_{1})(x - x_{2})}{(x_{1} - x_{0})(x_{1} - x_{2})} dx
= \frac{h}{3} (f(x_{0}) + 4f(x_{1}) + f(x_{2})).$$

Stroke of luck: $f'(x_1)$ does not end up in quadrature

$$\int_{a}^{b} P_{3}(x) dx = f(x_{0}) \int_{a}^{b} \frac{(x - x_{1})^{2}(x - x_{2})}{(x_{0} - x_{1})^{2}(x_{0} - x_{2})} dx + f(x_{2}) \int_{a}^{b} \frac{(x - x_{1})^{2}(x - x_{0})}{(x_{2} - x_{1})^{2}(x_{2} - x_{0})} dx$$

$$+f(x_1)\int_{a}^{b} \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} \left(1 - \frac{(x-x_1)(2x_1-x_0-x_2)}{(x_1-x_0)(x_1-x_2)}\right) dx$$

$$+f'(x_1)\int_{a}^{b} \frac{(x-x_0)(x-x_1)(x-x_2)}{(x_1-x_0)(x_1-x_2)} dx$$

$$\stackrel{!!!}{=} \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2)).$$

Stroke of luck:
$$f'(x_1)$$
 does not end up in quadrature

Quadrature Error
$$= \frac{1}{4!} \int_{a}^{b} f^{(4)}(\xi(x))(x - x_0)(x - x_1)^2(x - x_2) dx$$

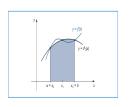
$$= \frac{f^{(4)}(\xi)}{4!} \int_{a}^{b} (x - x_0)(x - x_1)^2(x - x_2) dx = -\frac{f^{(4)}(\xi)}{90} h^5$$

$$\int_a^b f(x)dx = \frac{h}{3} \left(f(x_0) + 4f(x_1) + f(x_2) \right) - \frac{f^{(4)}(\xi)}{90} h^5.$$



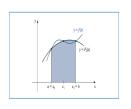
$$\int_a^b f(x)dx = \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2)) - \frac{f^{(4)}(\xi)}{90} h^5.$$

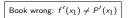


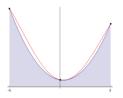


$$\int_a^b f(x)dx = \frac{h}{3} \left(f(x_0) + 4f(x_1) + f(x_2) \right) - \frac{f^{(4)}(\xi)}{90} h^5.$$









Correct plot: $f'(x_1) = P'(x_1)$

	(a)	(b)	(c)	(d)	(e)	(f)
f(x)	x^2	x^4	$(x+1)^{-1}$	$\sqrt{1+x^2}$	$\sin x$	e^{x}
Exact value	2.667	6.400	1.099	2.958	1.416	6.389
Trapezoidal	4.000	16.000	1.333	3.326	0.909	8.389
Simpson's	2.667	6.667	1.111	2.964	1.425	6.421

Example: approximate $\int_0^2 f(x)dx$: Simpson wins

	(a)	(b)	(c)	(d)	(e)	(f)
f(x)	x^2	x^4	$(x+1)^{-1}$	$\sqrt{1+x^2}$	$\sin x$	e^{x}
Exact value	2.667	6.400	1.099	2.958	1.416	6.389
Trapezoidal	4.000	16.000	1.333	3.326	0.909	8.389
Simpson's	2.667	6.667	1.111	2.964	1.425	6.421

▶ DEFINITION — **Degree of precision (DoP)**: integer n such that quadrature formula is <u>exact</u> for $f(x) = x^k$, for each $k = 0, 1, \dots, n$ but <u>inexact</u> for $f(x) = x^{n+1}$

	(a)	(b)	(c)	(d)	(e)	(f)
f(x)	x^2	x^4	$(x+1)^{-1}$	$\sqrt{1+x^2}$	$\sin x$	e^{x}
Exact value	2.667	6.400	1.099	2.958	1.416	6.389
Trapezoidal	4.000	16.000	1.333	3.326	0.909	8.389
Simpson's	2.667	6.667	1.111	2.964	1.425	6.421

- ▶ DEFINITION **Degree of precision (DoP)**: integer n such that quadrature formula is <u>exact</u> for $f(x) = x^k$, for each $k = 0, 1, \dots, n$ but inexact for $f(x) = x^{n+1}$
- ► **Theorem**: quadrature formula is exact for all polynomials of degree at most *n*.

	(a)	(b)	(c)	(d)	(e)	(f)
f(x)	x^2	x^4	$(x+1)^{-1}$	$\sqrt{1+x^2}$	$\sin x$	e^{x}
Exact value	2.667	6.400	1.099	2.958	1.416	6.389
Trapezoidal	4.000	16.000	1.333	3.326	0.909	8.389
Simpson's	2.667	6.667	1.111	2.964	1.425	6.421

- ▶ DEFINITION **Degree of precision (DoP)**: integer n such that quadrature formula is <u>exact</u> for $f(x) = x^k$, for each $k = 0, 1, \dots, n$ but inexact for $f(x) = x^{n+1}$
- ► **Theorem**: quadrature formula is exact for all polynomials of degree at most *n*.
- **Simplification**: only need to verify exactness on interval [0,1].

	(a)	(b)	(c)	(d)	(e)	(f)
f(x)	x^2	x^4	$(x+1)^{-1}$	$\sqrt{1+x^2}$	$\sin x$	e^{x}
Exact value	2.667	6.400	1.099	2.958	1.416	6.389
Trapezoidal	4.000	16.000	1.333	3.326	0.909	8.389
Simpson's	2.667	6.667	1.111	2.964	1.425	6.421

- ▶ DEFINITION **Degree of precision (DoP)**: integer n such that quadrature formula is <u>exact</u> for $f(x) = x^k$, for each $k = 0, 1, \dots, n$ but inexact for $f(x) = x^{n+1}$
- ► **Theorem**: quadrature formula is exact for all polynomials of degree at most *n*.
- Simplification: only need to verify exactness on interval [0,1].
 DoP = 1 for Trapezoidal Rule, DoP = 3 for Simpson.