[Q1]

In data fitting, the task is to find a model, from a family of potential models, that best fits some observed data and prior information. Here the variables are the parameters in the model, and the constraints can represent prior information or required limits on the parameters (such as nonnegativity). The objective function might be a measure of misfit or prediction error between the observed data and the values predicted by the model, or a statistical measure of the unlikeliness or implausibility of the parameter values. The optimization problem is to find the model parameter values that are consistent with the prior information and give the smallest misfit or prediction error with the observed data.

In device sizing in electronic design, which is the task of choosing the width and length of each device in an electronic circuit. Here the variables represent the widths and lengths of the devices. The constraints represent a variety of engineering requirements, such as limits on the device sizes imposed by the manufacturing process, timing requirements that ensure that the circuit can operate reliably at a specified speed, and a limit on the total area of the circuit. A common objective in a device sizing problem is the total power consumed by the circuit. The optimization problem is to find the device sizes that satisfy the design requirements (on manufacturability, timing, and area) and are most power efficient.

[Q4]

The solution
$$x = [x_1, \dots, x_n]$$

$$D = \begin{bmatrix} \lambda_1 & \lambda_1 \\ \lambda_1 & \lambda_2 \end{bmatrix} \quad \text{where } \lambda_1 > 0$$

$$x^TDx = \sum_{i=1}^{n} \lambda_i X_i^2 \leq \max(\{X_i\}_{i=1}^n\}) \sum_{j=1}^{n} X_i^2 = \lambda_j \sum_{i=1}^{n} X_{i=1}^k \lambda_j (2)$$

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where $\lambda_j = \max(\{X_i\}_{i=1}^n\}) \quad \text{and } \lambda_j^2 > \{X_i\}_{i=1,i\neq j}^n$

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$$\sum_{j=1}^n \lambda_j X_j^2 \leq \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 \quad \text{when } \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \qquad \text{when } \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \qquad \text{when } \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \qquad \text{when } \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \qquad \text{when } \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \qquad \text{when } \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \qquad \text{when } \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \qquad \text{when } \sum_{j=1}^n \lambda_j^2 X_j^2 \leq \lambda_j^2 X_j^2 \qquad \text{when$$

[Q5]

This is a linear optimization problem.

[**Q**6]

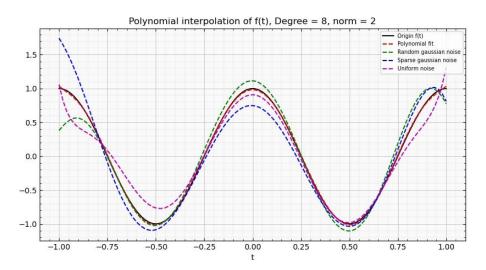
min
$$x^TT \times + \sum_{m=1}^{M} Um$$

 $x \in \mathbb{R}^N$, Um
Subject to $am \times \leq Um$
 $Zm \leq Um$

[**Q8**]

(a)

In the picture below, I draw the polynomial interpolation of f(t) under different situations, Where the black solid line indicates the origin f(t) and the red dashed line indicates polynomial fit without any noise, green dashed line indicates polynomial fit with random gaussian noise, blue dashed line indicates polynomial fit with sparse gaussian noise and purple dashed line indicates polynomial fit with uniform noise.



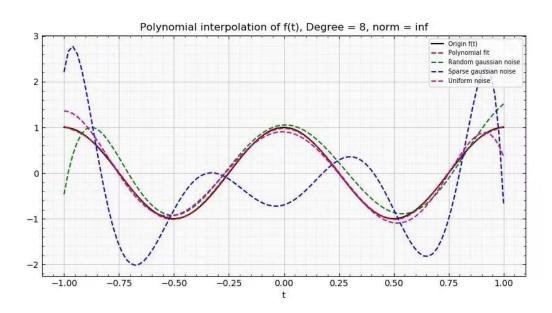
The corresponding norm residual is listed in the table below, clearly, random gaussian noise has least influences on fit.

Norm/Noise type	Random gaussian noise	Sparse gaussian noise	Uniform noise
2	1.48	1.88	1.59

And the optimal x value is listed below under different situations, note that all the results retain two decimal places

Noise	The optimal x value								
type									
Random	1.11	-0.15	-20.57	-0.10	61.47	1.85	-61.08	-1.40	19.65
gaussian									
noise									
Sparse	0.75	-0.22	-16.13	1.36	44.35	-0.96	-37.69	-0.64	10.00
gaussian									
noise									
Uniform	0.91	-0.03	-18.46	-1.46	62.02	3.30	-74.68	-1.67	31.4
noise									

(b) For norm infinity, I draw the plot below. Graphically, uniform noise makes the smallest influence on fit, random gaussian noise seems fit better than sparse gaussian noise and worse than uniform noise.



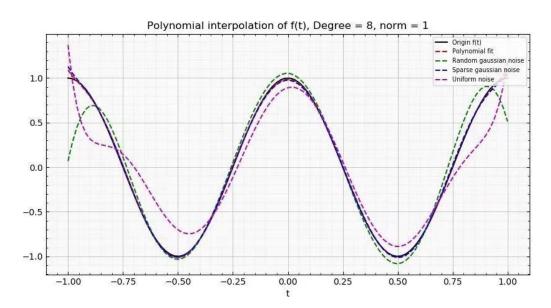
The corresponding norm residual is listed in the table below, clearly, uniform noise has least influences on the fit.

Norm/Noise type	Random gaussian noise	Sparse gaussian noise	Uniform noise
inf	1.47	1.80	0.64

Besides, the optimal x value is listed below under different situations, note that all the results retain two decimal places

icsuits ictui	esuits retain two decimal places								
Noise		The optimal x value							
type									
Random	1.05	0.23	-16.66	0.44	43.37	-6.05	-32.91	6.37	5.67
gaussian									
noise									
Sparse	-0.70	1.45	19.92	-11.56	-135.07	28.13	247.40	-19.46	-130.79
gaussian									
noise									
Uniform	0.90	-0.20	-16.3	-0.46	42.34	3.15	-32.59	-3.00	6.51
noise									

(c) For norm 1, similarly, I draw the plot below. Graphically, sparse gaussian noise seems to make the smallest influences on the fit, while random gaussian noise and uniform noise don't fit so well.



The corresponding norm residual is listed in the table below, clearly, sparse gaussian noise has least influences on the fit.

Norm/Noise type	Random gaussian noise	Sparse gaussian noise	Uniform noise
1	9.38	1.28	17.67

Quantatively, the optimal x value is listed below under different situations, note that all the results retain two decimal places.

Noise	The optimal x value								
type									
Random	1.05	-0.12	-19.88	0.35	58.67	-0.29	-55.64	0.28	16.1
gaussian									
noise									
Sparse	0.98	-0.00	-18.81	-0.04	56.82	0.22	-58.54	-0.22	20.64
gaussian									
noise									
Uniform	0.89	0.67	-18.48	-5.85	65.68	11.08	-84.51	-5.99	37.69
noise									

Here, I calculate the corresponding norm residual for different cases

Norm/Noise type	Random gaussian	Sparse gaussian	Uniform noise
	noise	noise	
1	9.38	1.28	17.67
2	1.48	1.88	1.59
inf	1.47	1.80	0.64

The norm 1 is best suited for the Sparse Gaussian noise case, the inf norm is best suited for the uniform noise and norm inf is best suited for Random gaussian noise.

[**Q9**]

After setting the optimization problem and use CVXPY package to model it, there are 1000 predicted x value. In the program, I only print values which are greater than $1e-5(1 \times 10^{-5})$, and only ten results are left. Note that all results are preserved two decimal places.

All the results are shown in the picture,

```
/Users/gexueren/opt/anaconda3/python.app/Contents/MacOS/python /Users/gexueren/Desktop/6270/assignment/hw01/hw01_probo9.py
The optimal value is -2.554929424943638e-12
The optimal x is
[0.42, 0.47, 0.39, 0.97, 0.38, 0.11, 0.11, 0.76, 0.84, 0.39]
Predicted number of infected people
[[66], [83], [241], [347], [365], [500], [559], [620], [662], [968]]
True number of infected people
[66, 83, 241, 347, 365, 500, 559, 620, 662, 968]
The norm of the residual is 0.0
```

From this picture, we can see clearly the value of optimal x and their predicted indexes. Meanwhile, I print the true indexes of infected people. Compare the two results, we can clearly see that all the predictions are 100 percent correct.

(b)

Here is how I get the optimal k:

Firstly, I find the optimal x whose value is greater than 1e-5. Secondly, if the number of optimal values is not equal setting number of infected individuals which is 10 in this case, then the optimization fails.

Not only I decrease K from 10 to 0 and find the lower bound, but also increase K from 10 to 100 and find the upper bound.

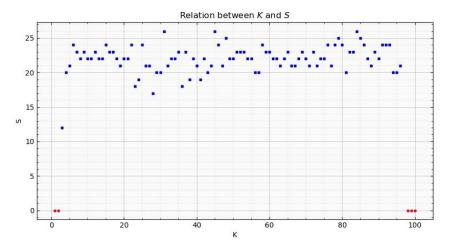
The final answer I got from the program is that **the lower bound of K is 3 and the upper bound of K is 97.**

Here is how I do it:

I set 2 for loops in the program, the outer loop sets the value of K (number of batches), and the inner loop sets the value of S (number of infected individuals). Note that the range of S is [10, 1000] and the range of K is [1, 100].

And for most K, it's able to find a maximum s which the optimization solution exists. And for some certain cases, there is no solution.

In order to show it graphically, I set the initial value of S is equal to 0, and replace it with the optimal solution if exists. To be more clear, the red dots in picture indicates that there's no optimal solution and the blue dots indicates the maximum S which the optimal solution exists.



Clearly, we can see that the model is robust because when K ranges from 4 to 96, the optimal S always around 23. When K is lower than 4 or higher than 97, there is no optimal solution for S.

Appendix (Code for Problem 8 and 9)

Problem 8

```
import numpy as np
from matplotlib import pyplot as plt
   print('Random gaussian noise: ', list(round(i, 2) for i in xhat 1))
```

```
noise2 = np.zeros(M)
noise2[Gamma] = np.random.randn(K)
plt.plot(tt, ff, color='k', label='Origin f(t)')
plt.plot(tt, fhat, 'k--', color='r', label='Polynomial fit')
plt.plot(tt, yhat_1, 'k--', color='g', label='Random gaussian noise')
plt.plot(tt, yhat_2, 'k--', color='b', label='Sparse gaussian noise')
plt.savefig('/Users/gexueren/Desktop/6270/assignment/hw01/2.jpg')
               x = cp.Variable(N)
              prob.solve()
```

Problem 9

```
Author: Xueren Ge
Time: 2021/1/24
Descrption:
This script models the spread of virus and how
to find the optimal Number of infected individuals
and optimal Number of splits of each sample
'''

import numpy as np
import cvxpy as cp
from matplotlib import pyplot as plt
import warnings
warnings.filterwarnings("ignore")

if __name__ == '__main__':
    ## PROBLEM 9
    # Construct the problem
    N = 1000 # Population size
    S = 10 # Number of infected individuals
```

```
ind0 = np.random.choice(N,S,0) # index subset
x0 = np.zeros(N)
prob.solve()
    ind0 = np.random.choice(N, S, 0) # index subset
    x0 = np.zeros(N)
```

```
if np.argwhere(x.value > 1e-5).shape[0] != len(ind0):
```

```
plt.grid(True, which='minor', linewidth=0.1)
```

plt.ylabel("S")
plt.savefig('D:\gexueren\prob09.jpg')