

### CONVOLUTIONAL NEURAL NETWORKS - I

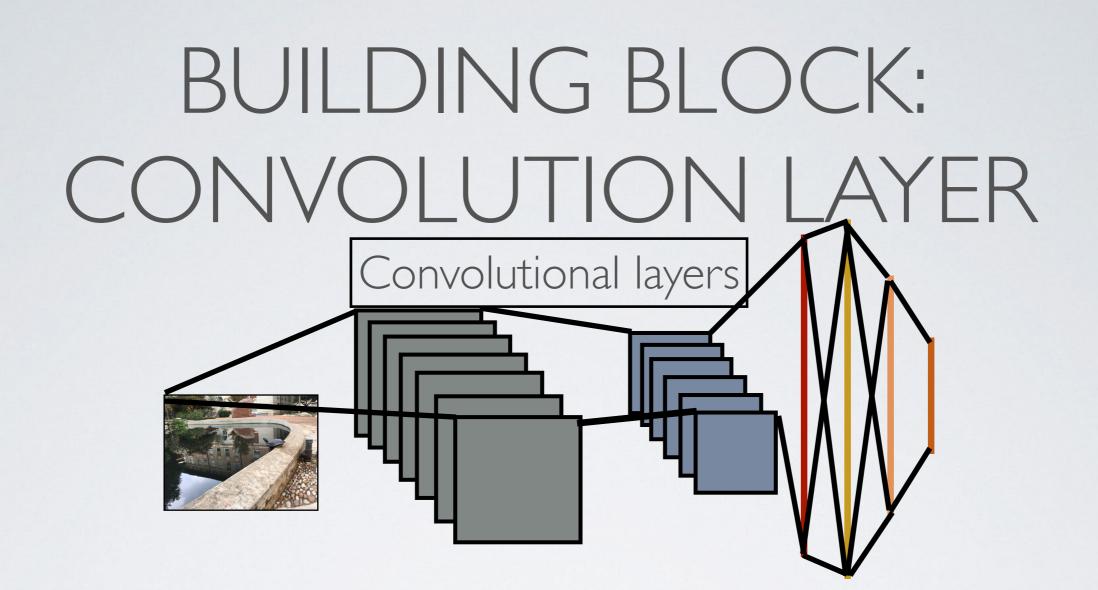
Sumohana S. Channappayya

### OUTLINE

- Motivation
- Building blocks
  - Convolutional layer/non-linearity layer
  - Pooling layer
  - Fully connected layer
- Training
  - Loss function
  - Gradient descent and learning rate
  - Data handling and stopping condition
- Generalisation

#### MOTIVATION

- Human Visual System (HVS)
- Dealing with 2D data
- Parameter reduction



- Linear component of the network
- Parameter sharing
- Local connectivity

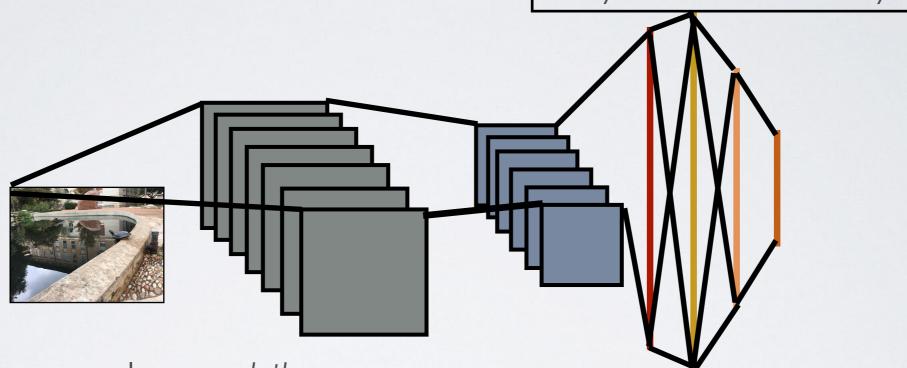
### BUILDING BLOCK: NON-LINEARITY LAYER

- Fundamental to NN
  - Allows for modelling complex input/output relations
  - Inspired by the neuron
  - Examples: sigmoid, tanh, ReLU etc.
  - Also called Activation Layer

# BUILDING BLOCK: POOLING LAYER

- Pooling of output
  - Dimensionality reduction
  - Control overfitting
  - Invariant to small translation
  - Examples: max, 12 norm, average etc.

# BUILDING BLOCK: FULLY CONNECTED LAYER Fully connected layers



- Essentially, a regular multilayer perceptron
- · Input is a vector formed by flattening pooling layer output
- · Output is vector whose size equals number of classes

#### TRAINING: LOSS FUNCTION

- Standard loss functions such as softmax or cross entropy
- Loss functions are non-convex leading to locally optimal solutions

# TRAINING: GRADIENT DESCENT BASED METHODS

- Several optimisation methods can be applied:
  - Gradient descent, Stochastic gradient descent
  - Momentum, Nesterov momentum
  - · AdaGrad, RMSProp, Adam
- Stopping condition based on training/validation error
- Choice of initialisation important
- · Backpropagation of forward loss used for gradient computation

# TRAINING: PARAMETERS AND DATA

- Similar rules as in neural network training:
  - Weights typically initialised randomly
  - Pre-trained weights also used commonly
  - Feed data in small batches (mini batches)
  - Epoch is one forward and backward pass of all training data points

#### GENERALISATION

- Any model's performance is measured on previously unseen inputs
- This is also known as generalisation
- Typically, the dataset is divided into training, validation and test set
- · Generalisation performance is reported on the test set

#### SUMMARY

- CNNs form the fundamental building blocks of modern machine learning models
- Allow for feature learning
- Extremely successful in solving several machine learning problems: image recognition, video analysis, natural language processing, drug discovery, visual system modelling etc.
- Reason for the deep learning revolution

#### REFERENCES

- https://www.deeplearningbook.org
- https://cs23 In.github.io/convolutional-networks/