Stefano Massaroli

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Education

2021–2022 Postdoc, University of Tokyo. Supervisor: Hajime Asama. 2019–2021 PhD in Engineering, University of Tokyo. Advisor: Hajime Asama Learning with Dynamical Systems: Implicit Models, Neural Differential Equations & Optimal Control Thesis committee: Atsushi Yamashita, Taiji Suzuki, Akio Yamamoto & Kiyoshi Kotani 2017–2019 ME in Robotics, University of Tokyo. Advisor: Hajime Asama. 2014–2017 BE in Automation, University of Bologna. Advisor: Claudio Melchiorri. (summa cum laude).	2022-	Postdoc, Mila. Supervisor: Yoshua Bengio.
Learning with Dynamical Systems: Implicit Models, Neural Differential Equations & Optimal Control Thesis committee: Atsushi Yamashita, Taiji Suzuki, Akio Yamamoto & Kiyoshi Kotani 2017–2019 ME in Robotics, University of Tokyo. Advisor: Hajime Asama.	2021 - 2022	Postdoc, University of Tokyo. Supervisor: Hajime Asama.
Thesis committee: Atsushi Yamashita, Taiji Suzuki, Akio Yamamoto & Kiyoshi Kotani 2017–2019 ME in Robotics, University of Tokyo. Advisor: Hajime Asama.	2019 – 2021	PhD in Engineering, University of Tokyo. Advisor: Hajime Asama
2017–2019 ME in Robotics, University of Tokyo. Advisor: Hajime Asama.		Learning with Dynamical Systems: Implicit Models, Neural Differential Equations & Optimal Control
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2014–2017 BE in Automation, University of Bologna. Advisor: Claudio Melchiorri. (summa cum laude).	2017 – 2019	ME in Robotics, University of Tokyo. Advisor: Hajime Asama.
	2014 – 2017	BE in Automation, University of Bologna. Advisor: Claudio Melchiorri. (summa cum laude).

Preprints

- 1. Zhou, L., Poli, M., Xu, W., Massaroli, M., & Ermon, S., 2022. Deep Latent State Space Models for Time-Series Generation. September 2022.
- 2. Hua, C., Berto, F., Poli, M., Massaroli, S., & Park, J., 2022. Graph Spline Networks for Efficient Continuous Simulation of Dynamical Systems. September 2022.
- 3. Poli, M.*, Massaroli, S.*, Federico Berto*, Park, J., Dao, T., Re, C., & Ermon, S., 2022. Transform Once: Efficient Operator Learning in Frequency Domain. To appear in Advances in Neural Information Processing Systems, 35th.
- 4. Poli, M.*, Xu, W.*, **Massaroli, S.***, Meng, C., Kim, K., & Ermon, S., 2022. *Self-Similarity Priors: Neural Collages as Differentiable Fractal Representations*. To appear in Advances in Neural Information Processing Systems, 35th.

Selected Publications

Full list of publications available on my website https://massaroli.site

- 1. Massaroli, S., Poli, M., Califano, F., Park, J., Yamashita, A., & Asama, H., 2022. Optimal Energy Shaping via Neural Approximators. SIAM Journal on Applied Dynamical Systems.
- 2. Berto, F., Massaroli, S., Poli, M., & Park, J., 2022. Neural Solvers for Fast and Accurate Numerical Optimal Control. In International Conference for Learning Representations 2022.
- 3. Massaroli, S.*, Poli*, M., Sonoda, S., Suzuki, T., Park, J., Yamashita, A., & Asama, H., 2021. Differentiable Multiple Shooting Layers. Advances in Neural Information Processing Systems, 34th.
- 4. Poli, M.*, Massaroli, S.*, Scimeca, L., Chun, S., Oh, S.J., Yamashita, A., Asama, H., Park, J., & Garg, A., 2021. Neural Hybrid Automata: Learning Dynamics with Multiple Modes and Stochastic Transitions. Advances in Neural Information Processing Systems, 34th.
- 5. Massaroli, S., Poli, M., Peluchetti, S., Park, J., Yamashita, A., & Asama, H., 2021. Learning Stochastic Optimal Policies via Gradient Descent. IEEE Control Systems Letters.
- 6. Massaroli, S.*, Poli, M.*, Park, J., Yamashita, A., & Asama, H., 2020. Dissecting Neural ODEs. Advances in Neural Information Processing Systems, 33th. (oral, $r_a \approx 1\%$).
- 7. Poli, M.*, **Massaroli, S.***, Yamashita, A., Asama, H., & Park, J., 2020. *Hypersolvers: Toward Fast Continuous-Depth Models*. Advances in Neural Information Processing Systems, 33th.

^{*} Denotes equal contribution. r_a denotes the acceptance rate.

Experience

University of Tokyo, Tokyo, Japan *Visiting Researcher*, Incoming

Reference: Hajime Asama asama@robot.t.u-tokyo.ac.jp

RIKEN AiP, Tokyo, Japan Visiting Researcher, Incoming

Reference: Taiji Suzuki taiji@mist.t.u-tokyo.ac.jp

Korean Advanced Institute of Science and Technology, Daejeon, South Korea

Visiting Researcher, 2020.1 -

Reference: Jinkyoo Park jinkyoo@kaist.ac.kr

University of Tokyo, Japan

Research Assistant, 2019.9 - 2022.4

Reference: Hajime Asama asama@robot.t.u-tokyo.ac.jp

Reviewing

NeurIPS 2021; 2022 ICLR 2022; 2023 ICML 2021 AISTAT 2021

IEEE Transactions on Neural Networks and Learning Systems

IEEE Transactions on Mechatronics

IEEE Transactions on Industrial Informatics

IEEE Control Systems Letters

IEEE Conference on Decision and Control

Other Activities:

Organizer of the 2021 and 2022 editions of the NeurIPS workshop *The Symbiosis of Deep Learning and Differential Equations* (DLDE 21–22).