Joan Massich

Research fellow

massich massich jmassichBorn 15 March 1984



This is how I did it Anton. I never saved anything for the swim back. (Gattaca, 1997)

Experience

Dec. 2015 – Sep. 2016 Attaché temporaire dénseignement et de recherche (ATER), Le2i - Laboratorie Electronique, Informatique et Image UMR CNRS 6306 at IUT Dijon, Dijon

Dec. 2013 - Dec. 2015 Postdoctoral fellow, Le2i - Laboratorie Electronique, Informatique et Image UMR CNRS 6306 at IUT Le Creusot, Le Creusot

Oct. 2009 - Dec. 2013 Research assistant, ViCOROB - Computer Vision and Robotics group at University of Girona, Girona

June 2009 - Oct. 2009 Research assistant, Applied Vision Laboratory (AVL) at Texas Tech University (TTU), Lubbock

Dec. 2003 – June 2009 Research assistant, ViCOROB - Computer Vision and Robotics group at University of Girona, Girona

Education

Oct. 2009 - Dec. 2013 PhD in Computer Vision

Universitat de Girona, Girona, Catalonia.

Université de Bourgogne, Le Creusot, France. title: Deformable object segmentation in ultrasound images.

grade: Unanimity excellent with honors.

Sept. 2007 - June 2009 Erasmus Mundus Master Course on Computer Vision and Robotics (VIBOT)

Heriot-Watt University, Edinburgh, Scothland.

Universitat de Girona, Girona, Catalonia.

Université de Bourgogne, Le Creusot, France.

Autonomous Robots, Fundamentals on Robotics, Visual Perception, Real-time Image Processing, Scene Segmentation and Interpretation, Software Engineering, Image processing, Digital Signal Processing, Data Mining and Machine Learning, Medical Imaging, Shape Recognition Statistics, Infrared Imagery, Image Analysis.

grade: 8.1 over 10

Sept. 2005 - Sept. 2007 Computer Science Engineering,

Universitat de Girona, Girona, Catalonia

Software Engineering, Computer Networks, Compilers, Computer Architecture, Numeric Methods, Economy, Production Systems, Computer Vision, Statistics, User Interfaces, Security. grade: 7.7 over 10

Universitat de Girona, Girona, Catalonia

Algorithms, Computer Architecture, Electronics, Digital Circuits, Database Systems, Computer Vision, Robotics, Software Engineering, Computer Networks, Operating Systems, Discrete Structures, Probability and Statistics, Digital Logic, Control Systems, VLSI Design, Artificial Intelligence. grade: 6.9 over 10

PhD Thesis

title Deformable object segmentation in ultra-sound images.

supervisors Joan Martí and Prof. Fabrice Meriaudeau

description This thesis is devoted to automatic segmentation of breast lesions in ultrasound images, since this task is key for the development of robust Computer Aided Diagnosis (CAD) systems applied to this organ and image modality. The proposed segmentation strategy divides the images into meaningful regions called super-pixels and labels them using a minimization framework that takes into account training and regularization.

Languages

Catalan IRL 5 Mother tonge.

Spanish IRL 5

English IRL 4-5

French IRL 3-4

Publications

Medical Image Analysis

Alsaih, Khaled, Guillaume Lemaître, Joan Massich, Mojdeh Rastgoo, Désiré Sidibé, Tien Y Wong, Ecosse Lamoureux, Dan Milea, Carol Y Cheung, and Fabrice Mériaudeau, "Classification of SD-OCT volumes with multi pyramids, LBP and HOG descriptors: application to DME detections". In: 38th IEEE Engineering in Medicine and Biology Society (EMBC).

Lemaitre, Guillaume, Mojdeh Rastgoo, Joan Massich, Joan C. Vilanoma, Paul M. Walker, Jordi Freixenet, Anke Meyer-Baese, Robert Martí, and Fabrice Meriaudeau, "Normalization of T2W-MRI Prostate Images using Rician a priori". English. In: SPIE Medical Imaging 2016, pp. 978529–978529.

Massich, Joan, Mojdeh Rastgoo, Guillaume Lemaitre, Carol Cheung, Tien Y Wong, Desire Sidibe, and Fabrice Meriaudeau, "Classifying DME vs normal SD-OCT volumes: A review". English. In: 23rd International Conference on Pattern Recognition (ICPR).

Rastgoo, Mojdeh, Guillaume Lemaitre, Joan Massich, Oliver Morel, Frank Marzani, Rafael Garcia, and Fabrice Meriaudeau, "Tackling the Problem of Data Imbalancing for Melanoma Classification". English. In: 3rd International conference on BIOIMAGING.

Rastgoo, Mojdeh, Guillaume Lemaitre, Oliver Morel, Joan Massich, Frank Marzani, Rafael Garcia, and Desire Sidibe, "Classification of melanoma lesions using sparse coded features and random forests". English. In: SPIE Medical Imaging 2016.

2016

2016

2016

2016

2016



1	0	1	÷
4	U	Т	J

Massich, Joan, Fabrice Meriaudeau, Elsa Pérez, Robert Martí, Arnau Oliver, and Joan Martí, "Seed selection criteria for breast lesion segmentation in ultra-sound images". In: Proc. MICCAI 2011 Workshop on Breast Image Analysis. Ed. by Christine Tanner, Julia Schnabel, Nico Karssenmeijer, Mads Nielsen, Maryellen Giger, and Dawid Hawkes, pp. 57–64.

2010

Massich, Joan, Fabrice Meriaudeau, Elsa Pérez, Robert Martí, Arnau Oliver, and Joan Martí, "Lesion Segmentation in Breast Sonography". English. In: Lecture Notes in Computer Science vol. 6136. Ed. by Joan Martí, Arnau Oliver, Jordi Freixenet, and Robert Martí, pp. 39–45.

Other Publications in Computer Vision and Robotics

2016

Belkacemi, M, J Massich, G Lemaitre, C Stolz, V Daval, G Pot, O Aubreton, R Collet, and F Meriaudeau, "Wood fiber orientation assessment based on punctual laser beam excitation". English. In: 13rd Quantitative Infrared Thermography Conference (QIRT).

2015

Belkacemi, Mohamed, Christophe Stolz, Alex andre Mathieu, Guillaume Lemaitre, Joan Massich, and Olivier Aubreton, "Nondestructive testing based on scanning-from-heating approach: application to nonthrough defect detection and fiber orientation assessment". In: Journal of Electronic Imaging 24.6, pp. 061112–061112.

2015

Lemaitre, Guillaume, A. Bikfalvi, J. Llach, Joan Massich, and F. Julian, "Business Model Design for University Technology Valorisation". English. In: Proc. International Technology, Education and Development Conference (INTED).

2009

Falcao, Gabriel, Natalia Hurtos, Joan Massich, and David Fofi, Projector-camera calibration toolbox. *Comp. software. Le2i UMR CNRS 6306 - IUT Le Creusot, France* . URL: http://code.google.com/p/procamcalib

2008

Falcao, Gabriel, Natalia Hurtos, and Joan Massich, Plane-based calibration of a projector-camera system. Research rep. Le Creusot, France: Shape Recognition Statistics course (EMMc VIBOT).

2006

Hernàndez, Emili, Pere Ridao, Marc Carreras, David Ribas, Narcís Palomeras, Andrés El-fakdi, Francois Chung, Xavier Ribas, Guillermo García de Marina, Natalia Hurtós, Joan Massich, Antonio Almohaya, and Josep Vila, "ICTINEU AUV, un Robot per a Competir". Catalan. In: Artificial Intelligence Research and Development, Proceedings of the 9th International Conference of the ACIA, CCIA 2006. Ed. by Monique Polit, Thierry Talbert, Beatriz López, and Joaquím Meléndez.

2006

Ribas, David, Narcís Palomeras, Xavier Ribas, Guillermo García de Marina, Emili Hernández, Francois Chung, Natalia Hurtós, Joan Massich, Antonio Almohaya, Josep Vila, and Andrés El-fakdi, ICTINEU AUV Takes the Challenge. Research rep. Universitat de Girona Girona, Catalonia

Education

2014

Ligusova, Jana, Nina Bencheva, Jean-Marc Thiriet, Gert Jervan, and Massich Joan, "Reflections about the integration of global challenges into higher education future programs: application in the field of ICT security". In: Proceedings of ITHET 2014. 13th International Conference on Information Technology Based Higher Education and Training.

2012

Cufí, Xevi, Miquel Villanueva, Andrés ElFakdi, Joan Massich, and Rafael Garcia, "Team-based Building of a Remotely Operated Robot as a Method to Increase the Interest for Engineering among Secondary School Students". In: Proceedings of EDULEARN 2012. 4th International Conference on Education and New Learning Technologies.

2011

Villanueva, Miquel, Xevi Cufí, Andrés ElFakdi, Joan Massich, and Rafael Garcia, "Attracting talent to increase interest for engineering among secondary school students". In: Global Engineering Education Conference (EDUCON), 2011 IEEE, pp. 347–353.

Awards

Feb. 2016

Best student paper award for, Rastgoo et. al. "Classification of melanoma lesions using sparse coded features and random forests", Rome

Aug. 2006

Member of the ViCOROB-UDG team honored as the winner of the 2006 SAUC-E (Student Autonomous Underwater Challenge Europe) competition, London