

When does vapor pressure deficit drive or reduce evapotranspiration?

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Key Points:

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Abstract

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1 Introduction

Changes to vapor pressure deficit (VPD) alter the atmospheric demand for water from the land surface. Traditionally, atmospheric scientists and hydrometeorologists generally think that an increase in atmospheric demand induces an increase in evapotranspiration (ET) (citations?). This possible misconception developed in part due to the proliferation of studies examining potential ET (PET) rather than estimates of ET itself (citations?). In contrast, plant physiologists know that stomata have evolved to optimally regulate the exchange of water and carbon, and tend to close in response to increased atmospheric dryness [???]. Therefore, an increase (decrease) in VPD may not correspond to an increase (decrease) in ET because stomatal closure (opening) can cancel the effects of shifts to atmospheric demand.

Quantifying the plant response to a perturbation to atmospheric VPD increases our understanding of land surface response to shifts in atmospheric conditions. If plant response reduces ET in response to atmospheric drying then soil moisture will be conserved. An increase in ET in response to atmospheric drying will reduce soil moisture, but contribute increased moistening to the atmosphere. Clearly, the sign and magnitude of land-surface responses drive the co-evolution of the atmosphere and land-surface at many timescales, from diurnal to interdecadal.

We hypothesize that for most plant types a common response to increase in VPD will actually be a decrease in ET. The exception would be plants such as crops that are evolved (or bred) to prioritize gross primary production (GPP) over water conservation. However, for all other plant types, our hypothesis calls into question the validity of PET-based drought metrics developed by hydrometeorologists and used extensively in operations [e.g. PDSI, P-PET, ??]. These metrics ignore the role of plants as gatekeepers for surface water loss to the atmosphere and have limited physical meaning for drought of vegetated land types. Additionally, plants evolved in arid climates should prioritize water conservation and we would expect a very negative ET response to increase in VPD. Therefore, vegetated locations most likely to experience droughts should show the strongest deviation between reality and a PET-based approximation.

← This section needs to be fleshed out, and I definitely need to add more citations

← more citations needed, including recent PET climate studies like Jack Scheff

In order to quantify plant response to perturbations to atmospheric demand for water, we apply a Penman-Monteith framework to eddy-covariance observations spanning various biomes and climates. Section 2 describes the data used, Section 3 derives the framework, Section 4 presents results, and Section 5 discusses conclusions. The goal of this paper is to use reasonable approximations as a tool to increase intuition for plant response to atmospheric drying. This intuition will aid interpretation of observations and full complexity climate models.

2 Data

We use data from FLUXNET2015, including all sites with more than four years of data. Each site's plant functional type (PFT) was classified using the International Geosphere-Biosphere Programme vegetation classification scheme (?). Because g_1 coefficients [?] and $uWUE$ were only both available for five plant functional types (PFTs - see Table 3), only 56 of the 77 sites were used. Figure 1 presents each site and its plant functional type.

The purpose of this study is examine ecosystem response to atmospheric drying during the growing season. To accomplish this, we filter and quality control the data using a similiar procedure as ?:

- Only measured or highest ("good") quality gapfilled data, according to qualtiy control flags, are used.
- To isolate the growing season, we only use days in which the average GPP exceeds 10% of the observed 95th percentile of GPP for a given site.
- We remove days with rain and the day following to avoid issues with rain interveption and sensor satruation and high relative humidity (Medlyn et. al. 2017).

Additionally, we restrict data to the daytime which is identified when downwelling short-wave radation is greater than 50 W m^{-2} and sensible heat flux is greater than 5 W m^{-2} . To further reduce the chance of sensor saturation at high relative humidity, we remove all time steps for which VPD is less than .01 kPa. Timesteps with negative observed GPP or ET are also removed. After these quality control proceeedures, 332556 upscaled hourly observations remain.

← map needs to be improved - it's a placeholder for now

3 Methods

The Penman-Monteith equation (hereafter PM) estimates ET as a function of atmospheric and land-surface variables:

$$ET = \frac{\Delta R + g_a \rho_a c_p VPD}{\Delta + \gamma(1 + \frac{g_a}{g_s})}, \quad (1)$$

where variable definitions are given in Table 1. ? developed a model for g_s by combining optimal photosynthesis theory with empirical approaches. The result for leaf-scale stomatal resistance was:

$$g_{l-s} = g_0 + 1.6 \left(1 + \frac{g_1}{\sqrt{VPD}} \right) \frac{A}{c_s} \quad (2)$$

This can be adapted to an ecosystem-scale stomatal resistance by multiplying by leaf area index (LAI) and converting units to m s^{-1} :

$$g_s = \text{LAI} \frac{RT}{P} \left(g_0 + 1.6 \left(1 + \frac{g_1}{\sqrt{VPD}} \right) \frac{A}{c_s} \right) \quad (3)$$

While Equation 3 can be used in PM, it will make analytical work with the function intractable because A , net CO_2 assimilation, is closely functionally related to ET itself. To remove dependence of ET on A we can use the semi-empirical results of ?. ? showed that:

$$uWUE = \frac{GPP \cdot \sqrt{VPD}}{ET} \quad (4)$$

is relatively constant across time and space (within plant functional type). If, following ?, we approximate g_0 as 0, we can use $uWUE$ to remove A from g_s in a way that makes PM analytically tractable:

$$g_s = \frac{RT}{P} 1.6 \left(1 + \frac{g_1}{\sqrt{VPD}} \right) \frac{uWUE ET}{c_s \sqrt{VPD}} \quad (5)$$

Note that $uWUE$ is fit on the ecosystem scale in ? so GPP in 4 is really $A \cdot \text{LAI}$. This leads to the cancelation of LAI in addition to $uWUE$ in Equation 3. Plugging Equation 5 into Equation 1 and rearranging gives:

$$ET = \frac{\Delta R + \frac{g_a P}{T} \left(\frac{c_p VPD}{R_{air}} - \frac{\gamma c_s \sqrt{VPD}}{R^* 1.6 uWUE (1 + \frac{g_1}{\sqrt{VPD}})} \right)}{\Delta + \gamma} \quad (6)$$

Given FLUXNET data described in Section 2, every term in Equation 6 is known. However, our sampling of sites and our focus on the growing season may introduce some deviations of $uWUE$ from those observed in ?. Also, we wish to include some measure of uncertainty in our analysis to guide if our many assumptions and simplifications are reasonable. To account for both mean deviations of $uWUE$ and uncertainty, we will introduce an uncertainty parameter σ modifying $uWUE$:

$$ET = \frac{\Delta R + \frac{g_a P}{T} \left(\frac{c_p VPD}{R_{air}} - \frac{\gamma c_s \sqrt{VPD}}{R * 1.6 \sigma uWUE (1 + \frac{g_1}{\sqrt{VPD}})} \right)}{\Delta + \gamma} \quad (7)$$

Now, from each FLUXNET observation we can calculate single value of σ :

$$\sigma = - \frac{g_a \gamma c_s \sqrt{VPD} L_v P}{(ET(\Delta + \gamma) - \Delta R - g_a \rho_a c_p VPD) 1.6 R T uWUE (1 + \frac{g_1}{\sqrt{VPD}})} \quad (8)$$

The variability of σ across sites and time will provides some measure of uncertainty in our model, assumptions, as well as the fluxnet observations themselves. To correct for differences in sampling between ? and our data, we set $uWUE$ such that $\bar{\sigma} = 1$. The variability of σ then propogates through any uncertainty to our derivative of Equation 8:

$$\frac{\partial ET}{\partial VPD} = \frac{2 g_a P}{T(\Delta + \gamma)} \left(\frac{c_p}{R_{air}} - \frac{\gamma c_s}{1.6 R * \sigma uWUE} \left(\frac{2g_1 + \sqrt{VPD}}{2(g_1 + \sqrt{VPD})^2} \right) \right) \quad (9)$$

With Equation 9 we have provided an analytical framework for ecosystem reponse to atmospheric demand perturbations. There are a few subtelties to taking the derivative in Equation 9: $\Delta (\frac{de_s}{dT})$ and VPD are functionally related, so while taking the derivative we evaluate $\frac{\partial ET}{\partial VPD} = \frac{\partial ET}{\partial e_s} \frac{\partial e_s}{\partial VPD} \Big|_{RH \text{ fixed}} + \frac{\partial ET}{\partial RH} \frac{\partial RH}{\partial VPD} \Big|_{e_s \text{ fixed}}$. RH and e_s are assumed to be approximately orthogonal.

The VPD dependence in Equation 9 is a little opaque. However, mean VPD is 1062 Pa, so \sqrt{VPD} is 32.6 Pa^{1/2}, which is much less than g_1 (with the exception of ENF; Table 3). So a series expansion in the limit $\frac{\sqrt{VPD}}{g_1} \rightarrow 0$ gives an approximation which makes the functional form more clear:

$$\frac{\partial ET}{\partial VPD} \approx \frac{g_a P}{T(\Delta + \gamma)} \left(\frac{c_p}{R_{air}} - \frac{\gamma c_s}{1.6 R * \sigma uWUE} \left(\frac{1}{g_1} - \frac{3\sqrt{VPD}}{2g_1^2} + \frac{2\sqrt{VPD}^2}{g_1^3} - \frac{5\sqrt{VPD}^3}{2g_1^4} + O\left(\left(\frac{\sqrt{VPD}}{g_1}\right)^4\right) \right) \right) \quad (10)$$

← Should I take the derivative this way? I think it's more mathematically correct, but it makes the explanation more complicated and only changes the solution by a factor of two. Should I even include the series expansion?

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Table 1. Definition of symbols and variables, with citation for calculation if applicable.

Variable	Description	Units	Citation
e_s	saturation vapor pressure	Pa	-
T	temperature	K	-
Δ	$\frac{\partial e_s}{\partial T}$	Pa K ⁻¹	-
R	net radiation at land surface minus ground heat flux	W m ⁻²	-
g_a	aerodynamic conductance	m s ⁻¹	?, ?, ?
ρ_a	air density	kg m ⁻³	-
c_p	specific heat capacity of air at constant pressure	J K ⁻¹ kg ⁻¹	-
VPD	vapor pressure deficit	Pa	-
γ	psychrometric constant	Pa K ⁻¹	-
g_s	stomatal conductance	m s ⁻¹	?
g_{l-s}	leaf-scale stomatal conductance	mol m ⁻² s ⁻¹	?
R^*	universal gas constant	J mol ⁻¹ K ⁻¹	-
LAI	leaf area index	-	-
σ	uncertainty parameter	-	-
c_s	CO ₂ concentration	μ mol CO ₂ mol ⁻¹ air	-

^aFootnote text here.

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One final comment on our derivation which will not be discussed further but is relevant for future analysis: if we approximate c_s at a global mean CO₂ concentration, then the RHS of Equation 6 is fully defined using commonly available weather station data and the constants published in ???. This then begs the question, why use PET for drought metrics in vegetated areas? It appears a much more physically realistic estimate of ET can be had with the same information required to calculate PET.

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4 Results

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By construction, the variability in the σ term (Equation ??) contains all model and observational uncertainties. For an observation that perfectly matches our model and constant uWUE assumption σ will be one. Therefore, for our assumptions and framework to be reasonable σ should be $O(1)$. Figure 2 presents the histogram of calculated σ s with outliers

Table 2. Plant functional types, their abbreviation, Medlyn coefficient [from ?], and uWfUE [from ?].

Note that units are converted such that the quantities fit into Equations 1-8 with the variables in Table 1.

Abbreviation	PFT	g_1 (Pa ^{0.5})	uWUE (μ -mol [C] Pa ^{0.5} J ⁻¹ [ET])
CRO	cropland	183.1	3.80
CSH	closed shrub	148.6	2.18
DBF	deciduous broadleaf forest	140.7	3.12
ENF	evergreen needleleaf forest	74.3	3.30
GRA	grassland (C3)	166.0	2.68

^aFootnote text here.

(lowest and highest 5% percent). All remaining σ values are $O(1)$ which provides confidence in model framework.

An additional concern is that the σ term may in fact be some function of VPD , in which case the dependence would need to be accounted for when taking the derivative. Figure 3 plots the joint distribution of σ and VPD , and shows that σ is very weakly a function of VPD . Given this weak dependence, we argue that Equation 9 is a valid approximation for ET response to VPD .

Before calculating the sensitivity of ET to VPD , it is useful to consider the functional form of Equation 9. There are two main terms: a “scaling” term which modifies the magnitude but not the sign:

$$\frac{g_a P}{T(\Delta + \gamma)},$$

and a “sign” term which determines whether the derivative is positive or negative:

$$\frac{c_p}{R_{air}} - \frac{\gamma c_s}{1.6 R \text{ uWUE}} \left(\frac{2g_1 + \sqrt{VPD}}{2(g_1 + \sqrt{VPD})^2} \right).$$

All variables are positive, so the relative magnitude between the first term and the second term will determine whether ET increases or decreases with increasing VPD . If the second term is larger magnitude then plant response dominates, while if the first term is larger then

atmospheric demand dominates. Given that the sign term is crucial to answering our question “When does VPD drive or reduce ET?”, we will explore its functional form first.

4.1 Functional Form of the Sign Term

Term 2 minus Term 3’s role in determining the sign of the sensitivity of ET to VPD makes it crucial for answering our question “When does VPD drive or reduce ET?” Exploring these terms more, c_s and γ variability is relatively less than σ and VPD variability, so variability within PFT will be solely determined by σ and VPD . If we fix uncertainty σ at 1, then Term 2 minus Term 3 is just a function of VPD . We can further determine a VPD_{crit} where $\frac{\partial ET}{\partial VPD} = 0$:

$$VPD_{crit} = \frac{R_{air}}{4c_p} \left(\frac{\gamma c_s}{1.6 R \bar{\sigma} uWUE} + \sqrt{\frac{\gamma c_s}{1.6 R \bar{\sigma} uWUE} \left(\frac{\gamma c_s}{1.6 R \bar{\sigma} uWUE} + 8g_1 \frac{c_p}{R_{air}} \right)} - 4g_1 \frac{c_p}{R_{air}} \right) \quad (11)$$

Values of VPD_{crit} as a function of PFT are shown in Table 4. For any values of VPD less than VPD_{crit} , $\frac{\partial ET}{\partial VPD}$ will be negative, and for values of VPD greater than VPD_{crit} , $\frac{\partial ET}{\partial VPD}$ will be positive. Intuitively this makes sense; as VPD increases ecosystems will start to run out of strategies to hold back water, and atmospheric demand will increase. Any further increases in atmospheric demand will then result in an increase in VPD. The extent to which a given ecosystem has evolved to conserve water will determine at what VPD atmospheric demand takes over.

Figure 4 provides greater description for how the sign term varies with VPD , as a function of PFT. Equation 10 aids interpretation of Figure 4. Larger $uWUE$, and g_1 shift the leading-order constant term ($\frac{1}{g_1}$) towards smaller values, and the sign term towards overall positive values. $uWUE$ and g_1 are both water-use efficiency type constants. Higher values correspond to plants that are more willing to spend water on primary production and less evolved to conserve water. Figure 4 confirms our physical intuition: CROs are the least water conservative so have the smallest constant portion of Term 3, while CSH are the most water conservative and have the largest constant portion of Term 3. For the VPD-dependent terms in Equation 10, differences in g_1 between PFTs exert a greater influence than difference $uWUE$, as the power of g_1 increases. Increasing $uWUE$ and g_1 decreases the VPD-dependence, but g_1 has the bigger effect due to its increasing powers. ENF ($g_1 = 74.31$) has

← really need to think about this sentence more, there is more nuance and I actually thing g_1 and $uwue$ really partially cancel.

Table 3. Values of VPD_{crit} , where $\frac{\partial ET}{\partial VPD} = 0$, evaluated at PFT average values for R_{air} , σ , γ , and c_s . For reference, these values are also provided. For values of VPD less than VPD_{crit} , $\frac{\partial ET}{\partial VPD}$ will be negative, and for values of VPD greater than VPD_{crit} , $\frac{\partial ET}{\partial VPD}$ will be positive.

PFT	R_{air}	c_s (ppm)	γ	$\bar{\sigma}$	$\bar{\sigma} \cdot uWUE$	VPD_{crit} (Pa)
CRO	288.680920	372.567691	65.351523	0.684394	2.602873	133.165438
CSH	289.067152	381.593622	67.613172	0.997224	2.175278	4439.564212
DBF	288.624437	377.449849	63.421812	0.881061	2.746393	888.773243
ENF	288.183849	377.676463	61.559242	1.217892	4.015362	978.084845
GRA	288.425651	377.264645	61.598768	0.850869	2.281074	1141.630778

^aFootnote text here.

by far the largest VPD dependence of response, while CRO ($g_1 = 183.1$) has the smallest VPD dependence.

Figure 4b shows the location of the minima of ET, as a function of σ and VPD . For any σ or VPD less (more) than these curves, sign term will be negative (positive). It is clear that the portion of VPD observations below/above these curves will be a strong function of σ . However, we can see some general trends. For CSH, $\frac{\partial ET}{\partial VPD}$ should be negative for the vast majority of observed σ and VPD. The fraction of positive $\frac{\partial ET}{\partial VPD}$ appears to be more even for ENF, GRA, and DBF, and we might expect a greater frequency of positive $\frac{\partial ET}{\partial VPD}$ for CRO.

4.2 Functional Form Scaling Term

While the above discussion of the sign of $\frac{\partial ET}{\partial VPD}$ is important to answer our research question, the magnitude of $\frac{\partial ET}{\partial VPD}$ will also impact statistics of $\frac{\partial ET}{\partial VPD}$ and the importance of VPD variability for overall ET variability. So we will more closely examine the scaling Term 1: $\frac{P}{T} \propto \rho$, so this should vary little relative to aerodynamic conductance and Δ . γ should also be relatively constant, so Term 1 should be primarily a function of aerodynamic conductance and temperature (through the function Δ). This makes sense, as aerodynamic conductance represents how efficiently response at the surface is communicated to the atmosphere. As it increases, any plant response will be communicated more strongly to the atmosphere (and vice-versa).

← could probably simplify and just say that g_1 controls VPD dependence.

Δ 's presence in the scaling term also matches physical intuition. Evaporative cooling will dampen the ability of the atmosphere to take more moisture, because e_s decreases with decreasing temperature. The decrease in e_s is proportional to Δ ($\delta e_s = \Delta \delta T$). So as Δ increases, you will get a larger damping of ET due to evaporative cooling. The functional form of Δ will be the same across PFT, but the temperature range may vary slightly. In contrast, aerodynamic conductance will vary strongly with PFT due to the importance of surface roughness. So most of the differences in scaling between PFT should be in the aerodynamic conductance term. One interesting side note is that the coefficient of variability for both aerodynamic conductance and the scaling term is relatively constant across PFT, suggesting that the influence of aerodynamic conductance on the relative (to the PFT mean) variability of the scaling term is approximately similar across PFT.

Figure 5A shows scaling term normalized by mean aerodynamic conductance (calculated for each plant functional type), and confirms that much of the relative variability of the scaling term is contained in the aerodynamic conductance variability. Generally, T has less of a role. Additionally, the impact of T on the relative variability increases with increasing aerodynamic conductance.

While the relative variability of scaling term is similar across PFT, the absolute value of scaling term varies strongly across PFT. Figure 5B shows scaling term evaluated with the mean aerodynamic conductance for each PFT, and at the range of observed temperatures for each PFT. As expected, for the tree PFTs (DBF, ENF) scaling term is much larger and the temperature dependence is much stronger. Systematic differences in observed temperatures also cause differences in the average magnitude of scaling term. For example, ENF experiences on average colder temperatures and is thus more likely to have a larger scaling term. Additionally, because the variability of aerodynamic conductance increases proportionally to the mean, the spread of scaling term due to aerodynamic conductance variability will be larger for the tree PFTs, although this is not shown for simplicity. To summarize, the variability of scaling term within each PFT will look like Figure 5A for each PFT, but the scale of the y-axis will increase or decrease according to mean aerodynamic conductance observed in Figure 5B.

4.3 Bulk statistics of $\frac{\partial ET}{\partial VPD}$

Table 3 confirms our expectations for PFT behavior of $\frac{\partial ET}{\partial VPD}$. For all PFTs except for CRO, average $\frac{\partial ET}{\partial VPD}$ is less than zero. However, $\frac{\partial ET}{\partial VPD}$ evaluated at the average of all variables (e.g. σ , T , c_s , VPD) is only negative for CSH and GRA. And, DBF in addition to CRO experiences $\frac{\partial ET}{\partial VPD} < 0$ less than half the time. These observations highlight the effect of the nonlinear function in Figure 4: $\frac{\partial ET}{\partial VPD}$ has a much steeper slope when the function is negative, and is thus more likely to be large magnitude.

The units of $\frac{\partial ET}{\partial VPD}$ make it difficult to interpret if VPD is even a meaningful contributor to ET's variability. To better understand VPD 's contribution, we multiply $\frac{\partial ET}{\partial VPD}$ with VPD 's standard deviation to define a (linearized) relative change in ET for variations in VPD . VPD 's contribution to ET's variability ranges between 30 - 40 W m⁻² for all PFTs except for CSH, which is about 100 W m⁻². Another meaningful comparison is to $\frac{\partial ET}{\partial R}$ · $std(R)$, as net radiation is generally the driver of ET (cite joe berry here). For all PFTs except for CSH VPD contributes between 30 - 40 % of R 's contribution to variability. For CSH the portion is much larger, about 88 %. VPD 's variability is certainly a primary contributor to ET 's variability.

So far, idealized plots and statistics have illuminated the form of $\frac{\partial ET}{\partial VPD}$ and how it varies with PFT. Large mean $uWUE$ shifts CRO and DBF towards positive $\frac{\partial ET}{\partial VPD}$. However, the strongly nonlinear function of $\frac{\partial ET}{\partial VPD}$ at $\frac{\partial ET}{\partial VPD} < 0$ pushes $\frac{\partial ET}{\partial VPD}$ negative for DBF (it does not do this for CRO because of CRO's high g_1). ENF's low g_1 value increases the dependence of $\frac{\partial ET}{\partial VPD}$ on VPD , and makes the function more strongly nonlinear. This has the side effect of pushing $\frac{\partial ET}{\partial VPD}$ negative further than other PFTs for a given fraction $\frac{\partial ET}{\partial VPD} < 0$ and magnitude $\frac{\partial ET}{\partial VPD}(\overline{T}, \dots, \overline{VPD})$. GRA shows the opposite behavior; a relatively high g_1 makes the function more linear, decreasing the magnitude of $-\frac{\partial ET}{\partial VPD}$ for a given [large] fraction $\frac{\partial ET}{\partial VPD} < 0$ and negative $\frac{\partial ET}{\partial VPD}(\overline{T}, \dots, \overline{VPD})$. However, aerodynamic conductance and scaling term also probably have a role in this. Finally, the low $uWUE$ of CSH pushes it toward by far the lowest values $\frac{\partial ET}{\partial VPD}$ (Figure 4). Variability in VPD accounts for the largest about of ET variability for CSH. For the other PFTs, VPD contributes less to ET variability, but still represents about 15-20 % of R 's contributions to ET variability.

← depending on how we take the derivative, this could be 30-40%.

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Table 4. Statistics of $\frac{\partial ET}{\partial VPD}$ as a function of PFT.

PFT	$\overline{\frac{\partial ET}{\partial VPD}}$	$\frac{\partial ET}{\partial VPD}(\overline{env})$	$\frac{\partial ET}{\partial VPD}(\overline{env}) * \text{std}(VPD)$	$\frac{\frac{\partial ET}{\partial VPD}(\overline{env}) * \text{std}(VPD)}{\frac{\partial ET}{\partial R}(\overline{env}) * \text{std}(R)}$	fraction $\frac{\partial ET}{\partial VPD} < 0$.
CRO	0.000853	0.026241	37.05	0.41	0.473311
CSH	-0.108234	-0.091526	101.72	0.88	0.931660
DBF	-0.012727	0.013794	39.47	0.33	0.461674
ENF	-0.034087	0.000706	33.22	0.30	0.534425
GRA	-0.019637	-0.000921	33.60	0.35	0.631735

^aFootnote text here.

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4.4 Testing the theory - does the data match the model?

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So far we have developed a theory for $\frac{\partial ET}{\partial VPD}$'s behavior. In particular, we determined a critical threshold VPD_{crit} for $\frac{\partial ET}{\partial VPD}$. For $VPD < VPD_{crit}$, $\frac{\partial ET}{\partial VPD} < 0$, and for $VPD > VPD_{crit}$, $\frac{\partial ET}{\partial VPD} > 0$. This VPD_{crit} is only a function of PFT. However, many assumptions, including constant uWUE, were made in deriving VPD_{crit} . So, we need to test if our theory and VPD_{crit} hold up in the face of uncertainty.

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Figure 6 presents calculated $\frac{\partial ET}{\partial VPD}$ where, unless otherwise noted, all variables in Equation 9 are allowed to vary, including uncertainty. Each column is a different quantity related to $\frac{\partial ET}{\partial VPD}$, and each row is a different PFT.

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The full observations generally confirm expectations from Section 4. CRO has the most positive values of $\frac{\partial ET}{\partial VPD}$, $\frac{\partial ET}{\partial VPD}$ is almost always negative for CSH, and response depends more with the environmental conditions for the other PFTs (especially ENF). Through the columns of Figure 6 we can see the impact of σ and g_a on the variability of $\frac{\partial ET}{\partial VPD}$. g_a 's scaling (included in columns 1 and 3) alters the magnitude considerably. σ variability (included in columns 1 and 2) adds a lot of additional noise to the signal of $\frac{\partial ET}{\partial VPD}$, which is slightly undesirable given σ 's role in representing model and observational uncertainty. However, the general story with the noise appears to match the cleaner signal when σ is held constant and VPD_{crit} is clearly visible. One exception is possibly with GRA, for which uncertainty represented in σ is high and causes the full complexity plots (Columns 1 and 2) to not match well with σ held fixed (Columns 3 and 4).

For ENF and GRA VPD_{crit} does not appear to be only a function of σ (most observable in Column 4). It turns out that the site to site variability in γ causes VPD_{crit} to vary, which is not discussed in the previous section. The impact is observable in both ENF and GRA, but especially for ENF which has a larger $\frac{\partial^2 ET}{\partial^2 VPD}$ than the other PFTs.

In general the full complexity plots of $\frac{\partial ET}{\partial VPD}$ match our expectations, even with the large sensitivity to σ measures of uncertainty observed in Figure 4. Our σ -based method of uncertainty propagation blurs the idealized expectations the most for GRA, and also has a considerable effect for CRO. We therefore have the most confidence in our conclusion based on Equation 9 for PFTS CSH, DBF, and ENF, as the full complexity plots with uncertainty included closely match the story when σ is held fixed.

5 Conclusions

The idealized representation of ET used here is successful in developing intuition for how ET responds to changes in VPD . This intuition will aid the community in interpreting observations and output from sophisticated full complexity climate models.

The idealized framework leads to the following general conclusions:

- Aerodynamic resistance plays an important role of scaling $\frac{\partial ET}{\partial VPD}$. This is a leading order effect for observing higher magnitude responses in DBF and ENF.
- In general, CSH has the most negative (i.e. ET reduced) response to increases in VPD (atmospheric drying). So CSH plants will almost always try and conserve water, effectively reducing ET with dry atmospheric perturbation.
- Additionally for CSH, VPD variability contributes the most to ET variability.
- CRO has the most positive response (i.e. ET increased) in response to increases in VPD . This is consistent with CROs that may be evolved or bred to thrive in non-water-limited environments.
- The response is more a function of the environment for DBF, ENF, and GRA. Because as VPD increases the response is more likely to be positive, if RH is fixed then the response will be more likely to be positive at warmer T, or if T is fixed the response is more likely to be positive with decreasing RH.
- ENF has the strongest dependence on environmental conditions due to its small g_l .

← also need to flesh this section out

- Model and observational uncertainty is highest for GRA and CRO, so conclusions about those PFTs should be tempered.
- However, inclusion of uncertainty doesn't alter conclusions about DBF, ENF, and CSH.

The intuition developed using this framework can be used to understand how the land surface will respond and contribute to changes in the environment. Additionally, Equation 6 gives provides an estimate of ET that requires no additional information beyond that required to calculate PET. Given that for all PFTs, with the exception of CRO, we found a high frequency and magnitude of negative $\frac{\partial ET}{\partial VPD}$, PET is a physically unrealistic representation of ET for vegetated surfaces and PET-based drought metrics are not useful. We advocate for drought metrics using Equation 6 instead of PET.

Acknowledgments

This work used eddy covariance data acquired and shared by the FLUXNET community, including these networks: AmeriFlux, AfriFlux, AsiaFlux, CarboAfrica, CarboEuropeIP, CarboItaly, CarboMont, ChinaFlux, Fluxnet-Canada, GreenGrass, ICOS, KoFlux, LBA, NECC, OzFlux-TERN, TCOS-Siberia, and USCCC. The ERA-Interim reanalysis data are provided by ECMWF and processed by LSCE. The FLUXNET eddy covariance data processing and harmonization was carried out by the European Fluxes Database Cluster, AmeriFlux Management Project, and Fluxdata project of FLUXNET, with the support of CDIAC and ICOS Ecosystem Thematic Center, and the OzFlux, ChinaFlux and AsiaFlux offices.

References

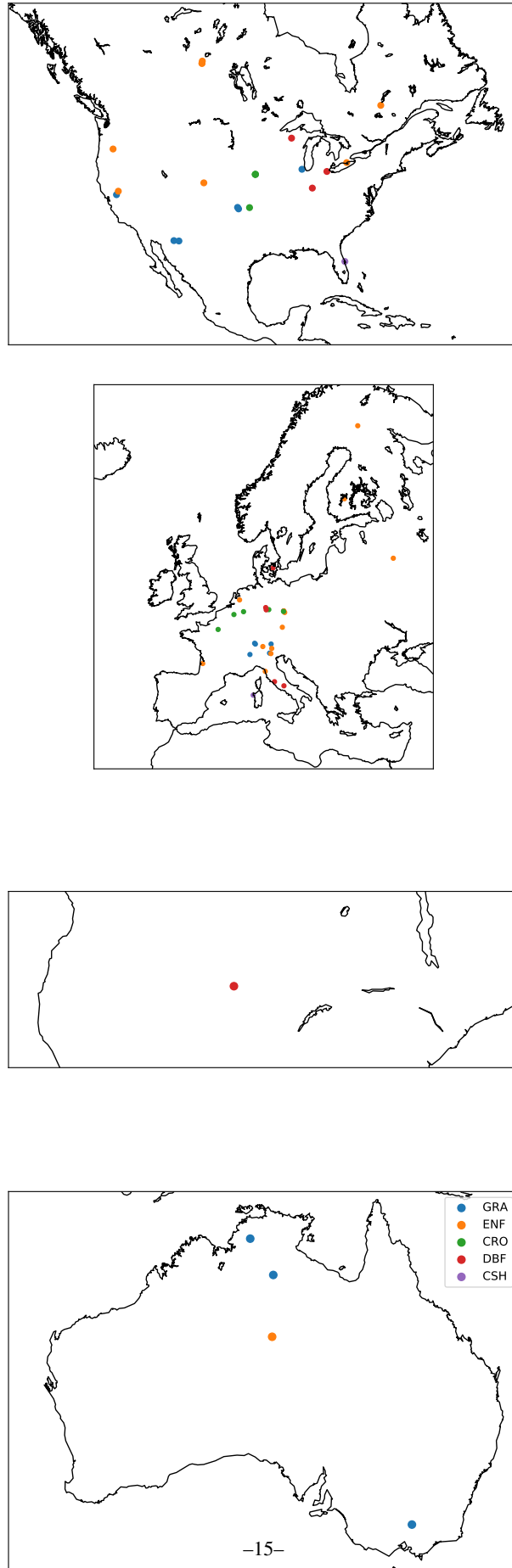


Figure 1. Plant functional type and location of sites used in analysis. ***This is just a placeholder for now and needs to be improved i.e. with lat lon, better placement of continents, etc.)***

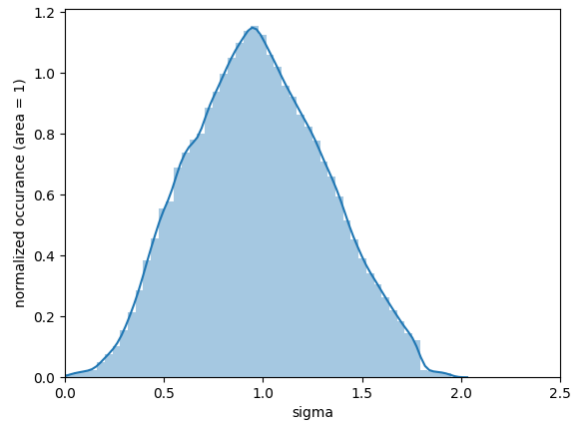


Figure 2. Histogram of σ values calculated for each site and time according to Equation ???. The lowest and highest 5% are removed as outliers, as well as any values below 0. The curve is normalized such that its area is 1.

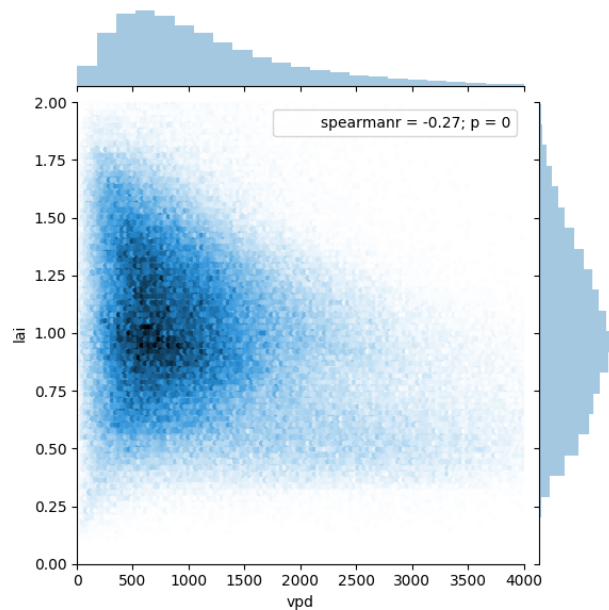


Figure 3. The joint distribution of VPD and σ . σ has only a weak dependence on VPD . ***This plot could probably benefit from a box plot of site specific correlations, because some sites do have stronger dependence than others. Note also Figs 3 and 2 can probably be combined because this figure shows σ 's histogram.***

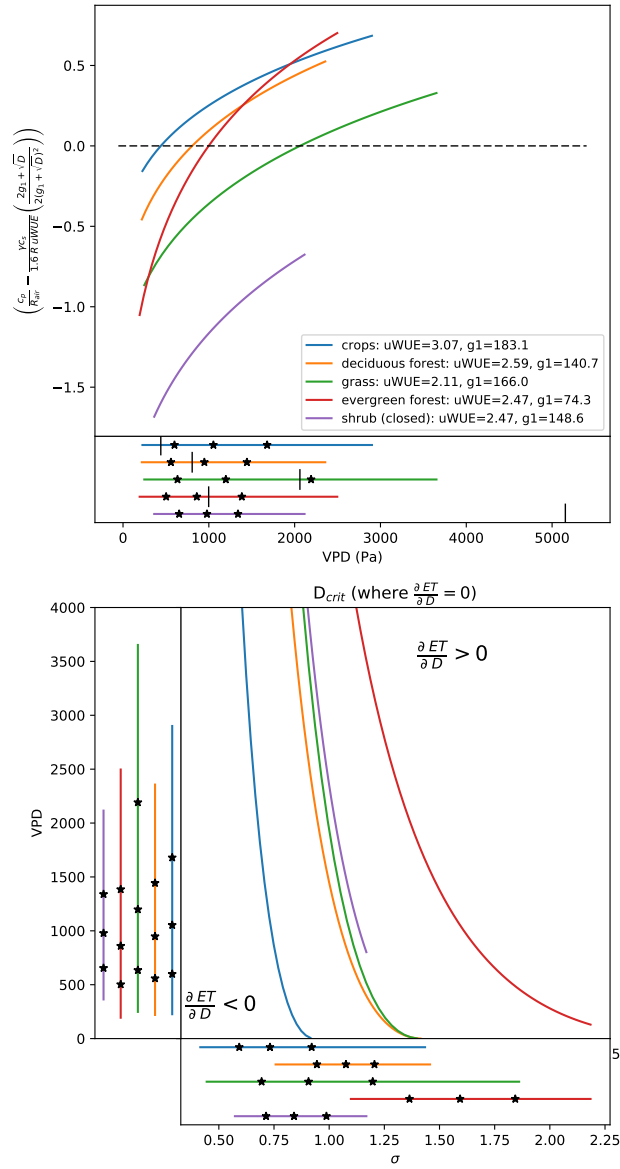


Figure 4. Sources of variability for sign term. Top: sign term as a function of VPD, with σ held fixed at PFT averages. The observed range of VPD for each PFT is also shown below the x-axis. Line extent corresponds to 5th and 95th percentiles, while stars denote the location of the 25th, 50th, and 75th percentiles.

Bottom: The location of the minima of ET, as a function of VPD and σ . Lines and stars denote the distribution of VPD and σ next to each axis, following the same percentiles as above.

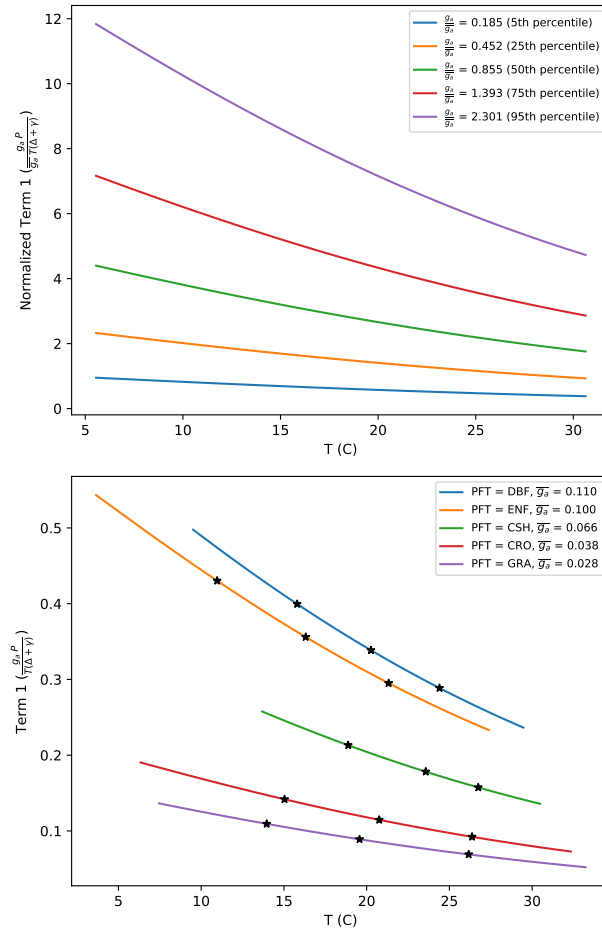


Figure 5. Primary sources of variability for scaling term. A) Variability within each PFT: scaling term normalized by mean g_a for each PFT. B) Variability between each PFT: scaling term evaluated at mean g_a for each PFT. Temperature range is 5-95th percentile for each PFT. Additionally, stars denote the location of the 25th, 50th, and 75th percentiles.

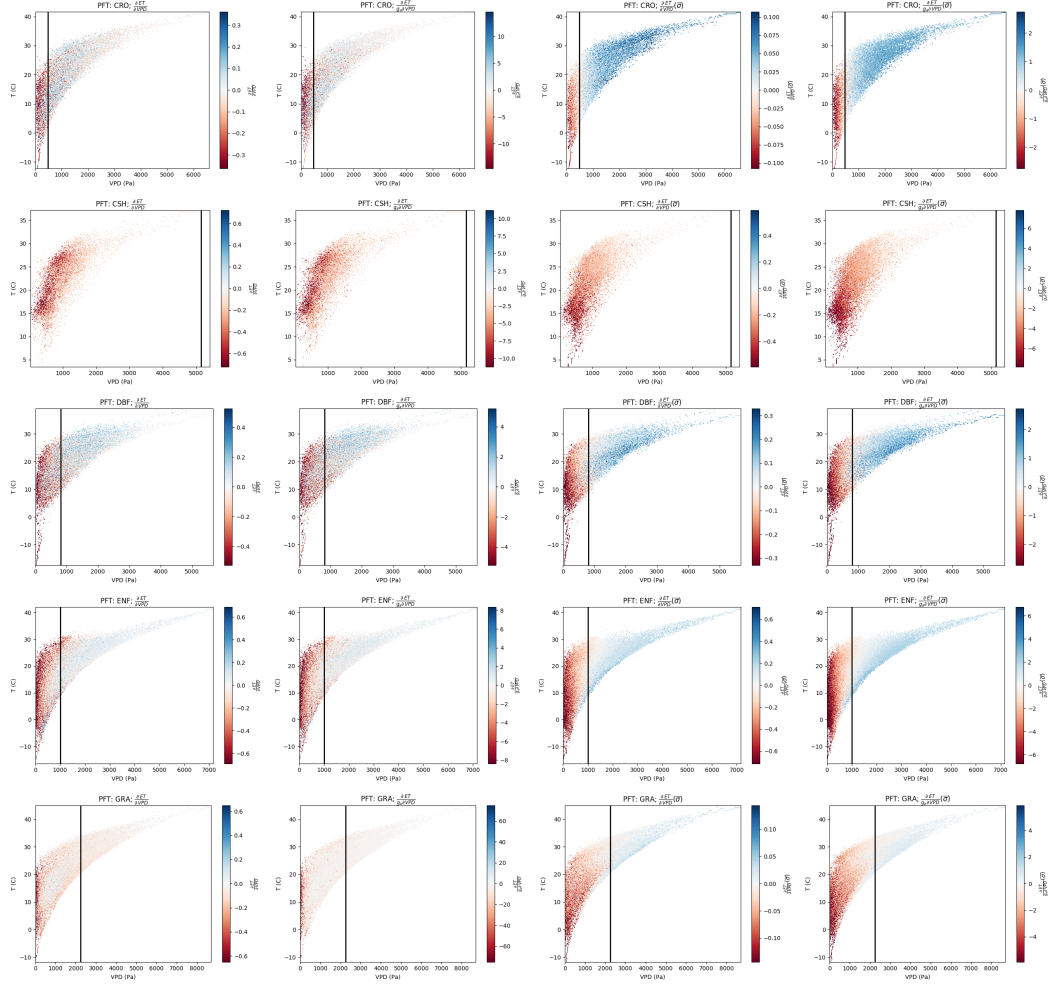


Figure 6. Scatter plots of $\frac{\partial ET}{\partial VPD}$. Each row is a different PFT, and each column is a different quantity related to $\frac{\partial ET}{\partial VPD}$, as labeled: Column 1 - $\frac{\partial ET}{\partial VPD}$; Column 2 - $\frac{\partial ET}{\partial VPD}$ normalized by g_a ; Column 3 - $\frac{\partial ET}{\partial VPD}$ with σ held fixed at PFT average; and Column 4 - $\frac{\partial ET}{\partial VPD}$ normalized by g_a and with σ held fixed. For reference, lines corresponding to RH = 20% and RH = 90 % are drawn. Please note differences in the colorbar scale. ***see alternate (or additional) plot below.***