Viewpoint Selection for Visual Failure Detection

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- Visual differences in outcomes of robotics tasks may be fine-grained and observable from certain viewpoints only
- Table assembly task example
 Success: tip of the screw in the hole
 Failure: tip of the screw near the hole
- Static and active viewpoint selection with finegrained random forests and SVMs trained on deep CNN features
- Failures detected more accurately from active viewpoints over static viewpoints

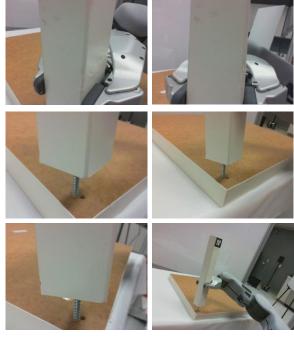


Fig: Views for a failed attempt of furniture assembly