A quick overview of Graph Embedding Methods

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14 December 2020



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- Problem Formalization
- Factorization based Methods
- 4 Graph Convolutional Network
- 5 GCN applications : GCN for Text Classification
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Introduction

- ► Graph are naturally occurring in the variety of situations such as social media network, knowledge graph, users graph,...
- Analysing these graphs provides insights into how to make good use of the information hidden in graphs, and thus has received significant attention in the last few decades.
- Graph analytic tasks can be divided into four categories: Nodes clustering, link prediction, node retrieval/recommendation, visualisation
- Major problem : Most existing graph analytics methods suffer the high computation and space cost.
- ► How to fix this?



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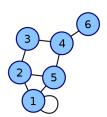


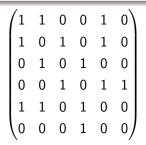
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Problem Formalization

Definition: Graph

A graph G=(V,E), where $v\in V$ is a node and $e\in E$ is an edge. The adjacency matrix A of graph G contains non-negative weights associated with each edge : $A_{i,j}=s_{ij}\geq 0$. If v_i and v_j are not connected to each other, then $s_{ii}=0$.



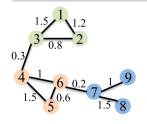


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Problem Formalization: First-order proximity

Definition: First-order proximity

The **first-order proximity** between node v_i and node v_j is the weight of the edge e_{ij} , ie, $s_{ij} = A_{i,j}$



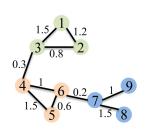
- Let $s_1 = [s_{11}^1, s_{12}^1, ... s_{1|V|}^1]$ denote the first-order proximity between v_1 and other nodes.
- In this case, $s_1^{(1)} = [0, 1.2, 1.5, 0, 0, 0, 0, 0, 0]$

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Problem Formalization : Second-order proximity

Definition: Second-order proximity

The **second-order proximity** $s_{ij}^{(2)}$ between node v_i and v_j is a similarity between v_i 's neighbourhood $s_i^{(1)}$ and v_j 's neighborhood $s_i^{(1)}$



- Let's take a look at $s_{12}^{(2)}$ which is the similarity between $s_1^{(1)}$ and $s_2^{(1)}$.
- We can choose the cosine similarity measure and another one.
- In this case, $s_1^{(1)} = [0, 1.2, 1.5, 0, 0, 0, 0, 0, 0],$ $s_2^{(1)} = [1.2, 0, 0.8, 0, 0, 0, 0, 0, 0]$
- So, $s_{12}^{(2)} = cosinus(s_1^{(1)}, s_2^{(1)}) = 0.43$

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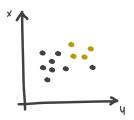
Problem Formalization

Definition: Graph Embedding

Given a graph G = (V, E), a graph embedding is a mapping $f : v_i \longrightarrow y_i \in \mathbb{R}^d$ such that $d \ll |V|$ and the function f preserves some proximity measure defined on graph G.

from a graph representation ...

to real vector representation



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Factorization-based methods

- Matrix factorization based methods, which are directly inspired by classic techniques for dimensional reduction, represent the connections between nodes in the form of a matrix and factorize this matrix to obtain the embeddings.
- ▶ A number of algorithms have emerged, from the simplest MDS (directly adopted the Euclidean distance between two features), passing through the Locally Linear Embedding algorithm up to Laplacian Eigenmaps (spectral techniques)...

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DL-based methods

- We can separate Deep learning based graph embedding into two types :
 - Using a random walk: The graph is represented as a set of random walk paths and we can apply deep learning methods to the sampled paths which preserve the properties of the graph.
 Some references: DeepWalk [PEROZZI, AL-RFOU et SKIENA 2014], node2vec [GROVER et LESKOVEC 2016], ...
 - Not using a random walk: The multi-layered learning architecture is a robust and effective solution to encode the graph into low dimensional space.
 - Focusing on one method in particular : Graph Convolution Network

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What is a Graph Convolutional Network?

- A Graph Convolutional Network is a multilayer neural network that operates directly on a graph and induces embedding vectors of nodes based on properties of their neighborhoods.
- Graph convolution network is equal to a CNN based on graphs.

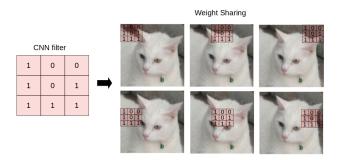


Figure – The same filter in CNNs is applied throughout the image

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GCN Formalization

- ▶ Goal : Learn a **function of features f** on a graph G = (V, E) which takes as input :
 - A feature matrix $X \in \mathbb{R}^{N \times D}$ (N :number of nodes, D :dimension of features)
 - A graph structure representative matrix, adjacency matrix A in $\mathbb{R}^{N\times N}$
 - and produces a **output feature matrix** $Z \in \mathbb{R}^{NxF}$ (F : number of output features per node)
- Each neural network layer can be written as a non-linear function

$$H^{(l+1)} = f(H^{(l)}, A)$$

with $H^{(0)} = X$ and $H^{(I)} = Z$, L is the number of layers.

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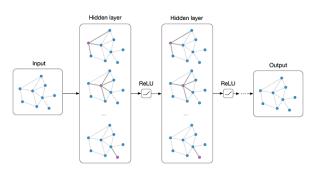


Figure - GCN with two layers



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GCN: Propagation rule

Example of very simple form of layer-wise propagation rule :

$$f(H^{(I)},A) = \sigma(AH^{(I)}W^{(I)})$$

where

- $W^{(I)}$ is a weight matrix for the layer I
- ullet σ is a non-linear activation function such as the ReLU
- ► Layer-wise propagation rule introduced by KIPF et WELLING 2016 :

$$f(H^{(I)}, A) = \sigma(\underbrace{\hat{D}^{-\frac{1}{2}}\hat{A}\hat{D}^{-\frac{1}{2}}}_{NSAM^{1}}H^{(I)}W^{(I)})$$

with $\hat{A} = A + I$ (I : Identity matrix) and \hat{D} is the diagonal node degree matrix of A.

^{1.} Normalized Symmetric Adjacency Matrix



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Summary

- Factorization based Methods
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- Graph Convolutional Networks for Text Classification
 - YAO, MAO et Luo 2019
- ► **Goal :** Transform text classification problem into a node classification problem
- ▶ The major difference is that these methods (Doc2vec LE et MIKOLOV 2014, ...) build text representation after learning words embeddings while we learn word and document embeddings simultaneously.

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 Building a wide and heterogeneous² text graph which contains word nodes and document nodes so that global word co-occurrence can be explicitly modeled and graph convolution can be easily adapt.

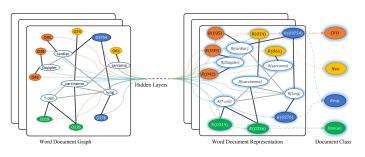


Figure – Text GCN with "O" nodes represent documents, other represent word. Black bold lines are doc-word edges and regular lines are words-words edges

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^{2.} All nodes in G don't belong to a single type and all edges don't belong to one single type

- Set feature matrix X = I as identity matrix (each word/doc represent as a one-hot vector)
- ► The weight of the edge between a document node and a word node is the TFIDF of the word in the document.
- ► The weight of the edge between a word node and a word node is the point-wise mutual information (PMI).

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• So, formally, our adjacency matrix is constructed as follows :

$$A_{ij} = \left\{ egin{array}{ll} PMI(i,j) & i,j ext{ are words, } PMI(i,j) > 0 \\ \mathsf{TF-IDF}_{ij} & i ext{ is document, } j ext{ is a word} \\ 1 & i = j \\ 0 & \mathsf{otherwise} \end{array}
ight.$$

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 After building the adjacency matrix A, we'll use the multi-layer GCN previously explained and only replaced the second layer of RELU in a Softmax because our goal is to classify the documents.

$$Z = softmax(\widehat{A} \underbrace{ReLU(\widehat{A}XW_0)W_1)}_{\text{first layer}})$$
 (1)

with W_0 and W_1 are the weight matrix for layer 0 et 1 and $\hat{A} = \hat{D}^{-\frac{1}{2}}(A+I)\hat{D}^{-\frac{1}{2}}$

minimize the cross-entropy error over all labeled documents :

$$\mathcal{L} = -\sum_{d \in \mathcal{Y}_{\mathcal{D}}} \sum_{f=1}^{F} Y_{df} \ln Z_{df}$$

where Y_D is the set of document indices that have labels and F is equals to the number of classes.

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GCN for Text Classification: Results

Model	20NG ³	R8 ⁴
TF-IDF+LR	0.8319 ± 0.0000	0.9374 ± 0.0000
Bi-LSTM	0.7318 ± 0.0185	0.9631 ± 0.0033
fastText	0.7938 ± 0.0030	0.9613 ± 0.0021
Text GCN	0.8634 ± 0.0009	$\underline{0.9707 \pm 0.0010}$

Table – Accuracy measure on document classification task. They run all models 10 times and report mean \pm standard deviation

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^{3.} The 20 newsgroups dataset comprises around 18000 (11k train, 7.5k test) newsgroups posts on 20 topics.

^{4.} A dataset subset of Reuters 21578 comprises around 8k documents (5.5k train, 2.1k test) into 8 categories.

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Discussion and conclusion

- Only a very small part of all Graph Embeddding Techniques
- A comprehensive survey Graph Embedding: Problems, Techniques and Applications [CAI, ZHENG et CHANG 2018], the authors propose to categorize graph embedding work based on problem setting.

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References

Thank you for your attention!



For further...

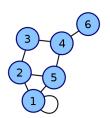
• Point-wise mutual information (PMI),

$$PMI(i,j) = \log \frac{p(i,j)}{p(i)p(j)}$$
$$p(i,j) = \frac{\#W(i,j)}{\#W}$$
$$p(i) = \frac{\#W(i)}{\#W}$$

where $\sharp W(i)$ is the number of sliding windows in a copus that contain word i, $\sharp W(i,j)$ is the number of sliding windows that contain both word i and j, and $\sharp W$ is the total number of sliding windows in the corpus.

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Adjacency matrix



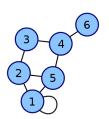
$$\begin{pmatrix} 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix}$$

• Given G = (V, E), the adjacency matrix A of G relating to this set of vertices is the $n \times n$ Boolean matrix A with :

$$a_i j = \begin{cases} 1 & \text{if } (v_i, v_j) \in E \\ 0 & \text{Otherwise} \end{cases}$$

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Degree matrix



$$\begin{pmatrix} 3 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

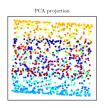
• Given G = (V, E), the degree matrix D for G is a $n \times n$ diagonal matrix defined as :

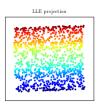
$$d_i j = \begin{cases} deg(v_i) & \text{if } i = j \\ 0 & \text{Otherwise} \end{cases}$$

LLE: Main idea

- Other dimensionality reduction methods fail to be successful on nonlinear space. (PCA, ...)
- LLE takes advantage of the local geometry and pieces it together to preserve the global geometry on a lower dimensional space.







Locally Linear Embedding

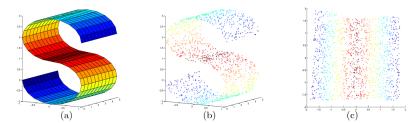


Figure – N-dimensional manifold to 2-dimensional space

► LLE basic idea is to take n-dimensional manifold and cast it into a lower dimensional space while preserving the manifold geometric features.

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Locally Linear Embedding

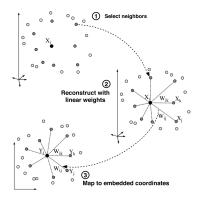


Figure - Caption

- Step 1 : Assign neighbors to each data point X_i using the K-nearest neighbors (K is the only parameters)
- Step 2:
 - Rows of the weight matrix must equal to $1: \sum_{i} A_{ij} = 1$
 - Minimize the cost function below, ie, find the best linear combination of A_{ii} which reconstructs X_i

$$\epsilon(W) = \sum_i |\hat{X}_i - \sum_j A_{ij} \hat{X}_j|^2$$

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Factorization-based methods

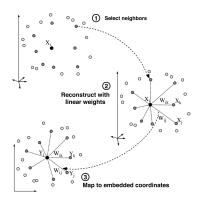


Figure - Caption

Step 3: Thanks to weights W_{ij} that we were previously defined in step 2, we obtain the embedding Y^{N×d} by minimizing the cost function below:

$$\psi(Y) = \sum_{i} |\hat{Y}_{i} - \sum_{j} W_{ij} \hat{Y}_{j}|^{2}$$

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Factorization-based methods

- The LLE method is simply a tiny part of all Factorization-based methods that they exist. Indeed, there are no less than 30 in the surveys (Laplacian Eigenmaps, GraRep, Hope, Rescal, ...)
- For the LLE method, several limations appear. Besides the temporal complexity which is of $\mathcal{O}(|E|d^2)$, it's a shallow model and preserves only the structure of the first-order proximity.
- Indeed, Due to the limited representation ability of shallow models, it's difficult for them to capture the highly non linear network structure.

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