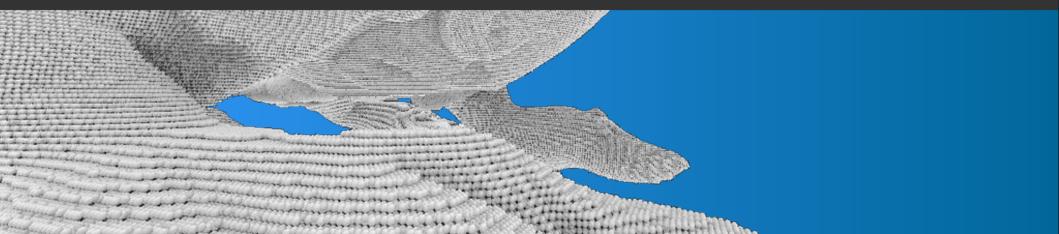


# OpenCL for realtime graphics

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### Why OpenCL?

- Because OpenCL does it all
  - Single source for all graphics APIs (D3D9, D3D10, D3D11, OpenGL 2.x 4.x)
  - Mobile support
  - Web support
- Clean interop API
- Easy debugging (printf on CPU!)

#### Interop API

- Acquire resource, map/unmap
- Automatic synchronization
- Minimal code required
  - Full production implementation: 900 LoC
  - Includes error checking & comments
  - Supports OpenCL 1.1 & 1.2, OpenGL, Direct3D11 KHR/NV



- 1. Divide screen into tiles and determine which lights affects which tiles
- 2. Only apply the visible light sources on pixels
  - Custom shader with multiple lights
  - Reduced bandwidth & setup cost

How can we do this best in DX11?

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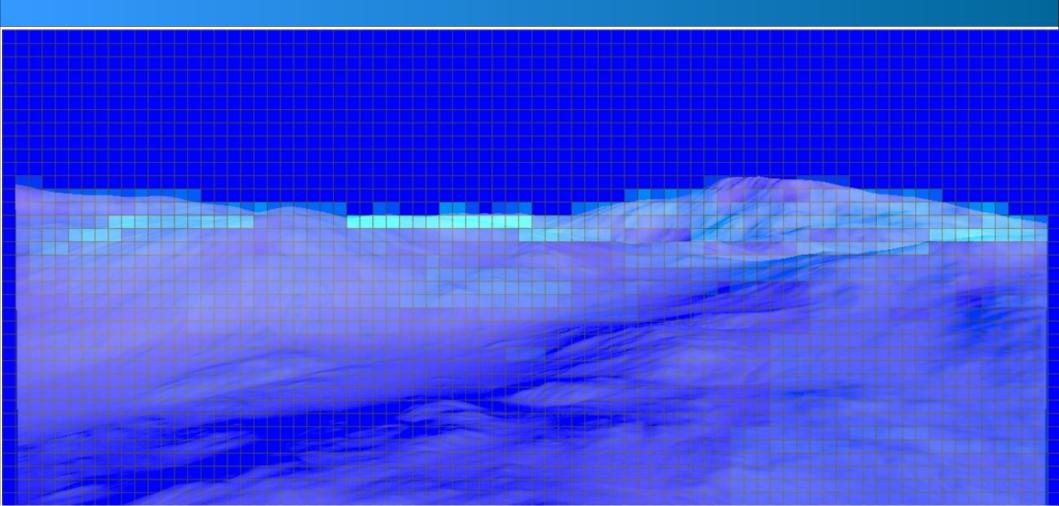
How can we do this best in



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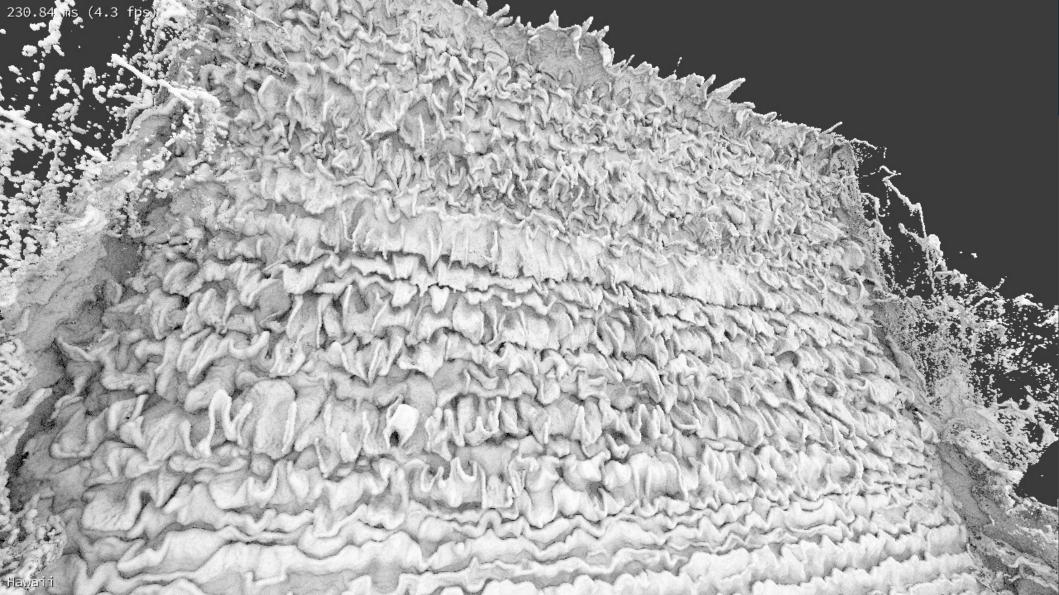






- Works!
- Performance roughly the same as DirectCompute
- Some limitations apply though ...

- No image read/write
  - Just map image twice & get the desired undefined behavior :)
  - Fixed in OpenCL 2.0
- No depth images
  - Fixed by extension (for OpenGL)
- No MSAA images
  - Fixed by extension (for OpenGL)

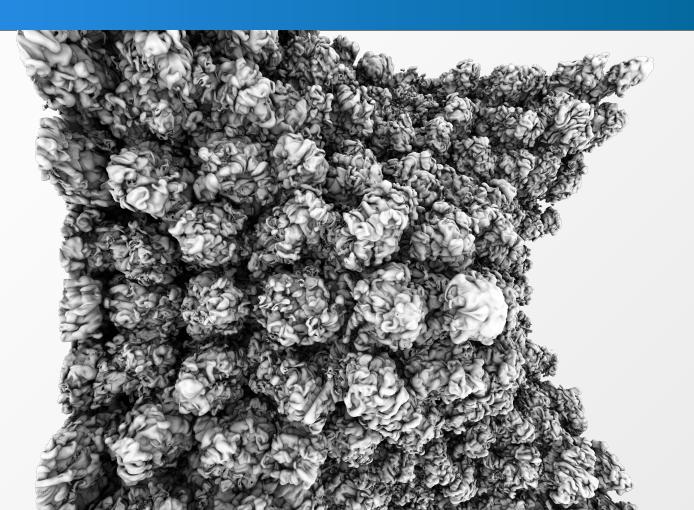


#### Real compute

- Voxel raytracing
  - 600 LoC of kernel code
  - Tree traversal
  - Per-thread stacks
- Run out of GPU memory?
  - Current GPUs max out at 16 GiB (AMD) or 12 GiB (NVIDIA)
  - CPUs max out at ... well ...

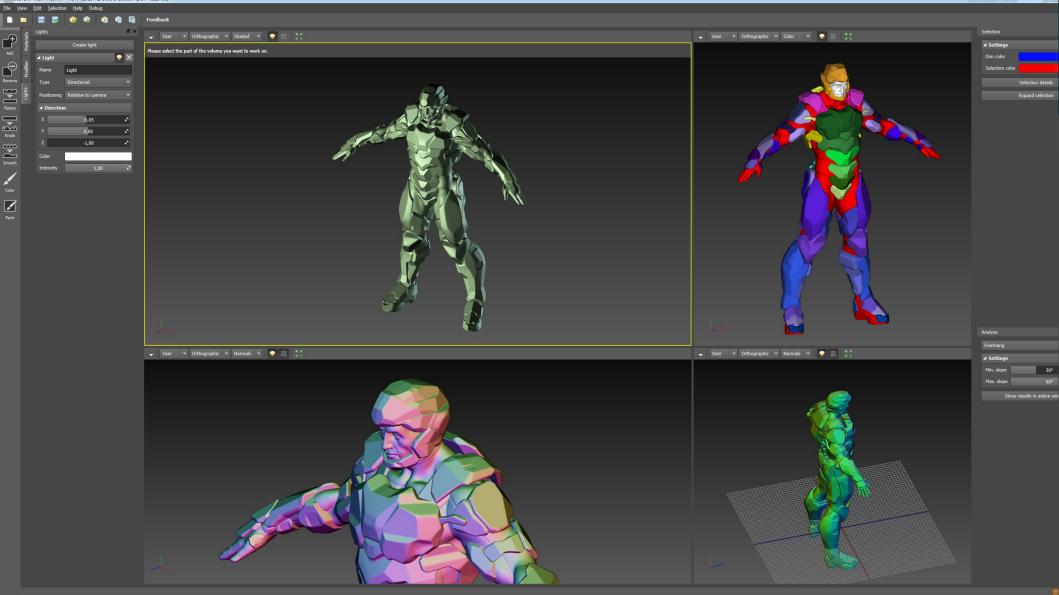
# Voxel raytracing

- Same code
- Really!
- Portable performance is not a myth!



#### Voxel raytracing

- GPU optimizations benefit CPU and vice versa
- No special casing
  - Avoid some "obviously" slow paths
  - AMD & NVIDIA\* get comparable performance/efficiency
  - CPU performance ~ 30% slower than extremely optimized ISPC code



#### Shipping products/VOTA

- Voxel editor
- All editing is done in OpenCL only
- Graphics interop running all the time
  - OpenCL prepares data for visualization
  - Minimal CPU intervention (to minimize buffer sizes)

#### VOTA, lessons learned

- All users have OpenCL installed
- AMD doesn't have a kernel cache (just do it on your own)
- Compiler quality is "good enough"
  - Still, we eagerly wait for SPIR
  - Initial startup takes quite some time due to compiling
- Query everything which is implementation specific

#### OpenCL/Graphics interop state

#### AMD

- Direct3D: Works
- OpenGL: Works mostly\* (Linux & Windows)

#### NVIDIA

- Direct3D: Through \_NV extension, \_KHR not supported.
- OpenGL: Works (Linux & Windows)

#### OpenCL/Graphics interop state

- AMD's implementation is much stricter (similar to OpenGL)
- Both have occasionaly issues with memory management
  - Need extension to force GPU memory defragment & query where buffer ended up
- For debugging/profiling, use CodeXL/KernelAnalyzer
  - NVIDIA stopped supporting OpenCL profiling some time ago

#### Reporting bugs

- AMD: Just report through normal channels. They got back to me quickly & and you get status updates (cool)
- NVIDIA, best report through CUDA bug report form. They don't say much about it, but they still fix OpenCL bugs.
- Intel: The forums seem to work fine.

#### OpenCL for graphics, the road ahead

- With OpenCL 2.0, OpenCL will far surpass
  DirectCompute/OpenGL compute shaders
  - GPU pipelining
  - Shared CPU/GPU memory data structures
  - AMD is aggressively working on it, first OpenCL 2.0 SDK should come this June
  - Intel most likely working on it as well

#### Conclusion

- You can ship an application built on OpenCL today
- For games, you'll likely want the MSAA/depth extensions
  - Vendors should do it instantly once requested
  - Can start writing the game today without problems
- In future, hard to avoid
  - OpenCL 2.0 allows GPU to traverse scene graph, prepare draw commands, then issue draw calls from CPU, with zero copy overhead

#### Thanks to ...

- The whole Volumerics team
  - @janjorrit, @mreitinger
- @repi
- AMD
  - @grahamsellers, @JCBaratault
- Codeplay & Khronos
  - @codeandrew, @neilt3d