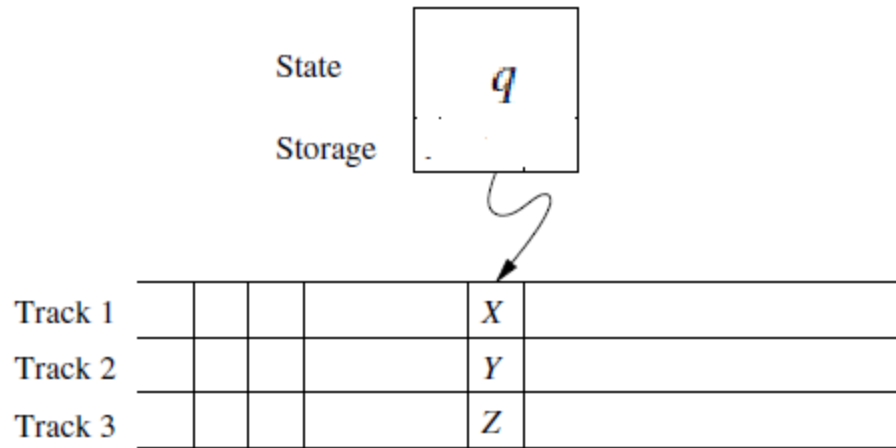


Variants of TM

Multi-track, multi-tape, NTM

<https://www.andrew.cmu.edu/user/ko/pdfs/lecture-14.pdf>

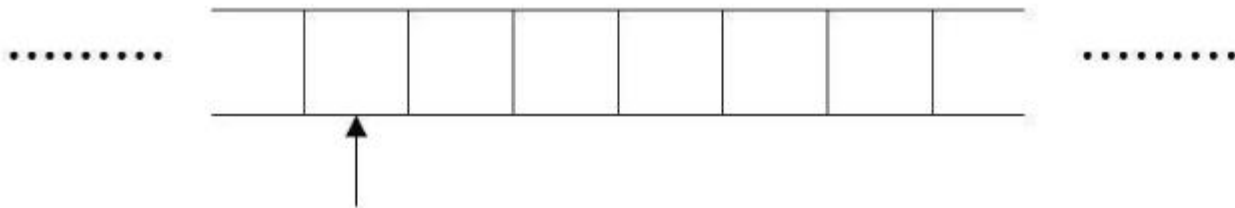
Multi-track



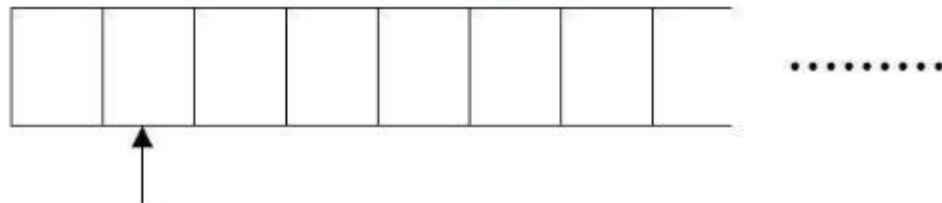
- In this example, the tape symbol is the triplet (X, Y, Z) and we can see the tape as a single-track one.

Semi-infinite tape

Standard machine

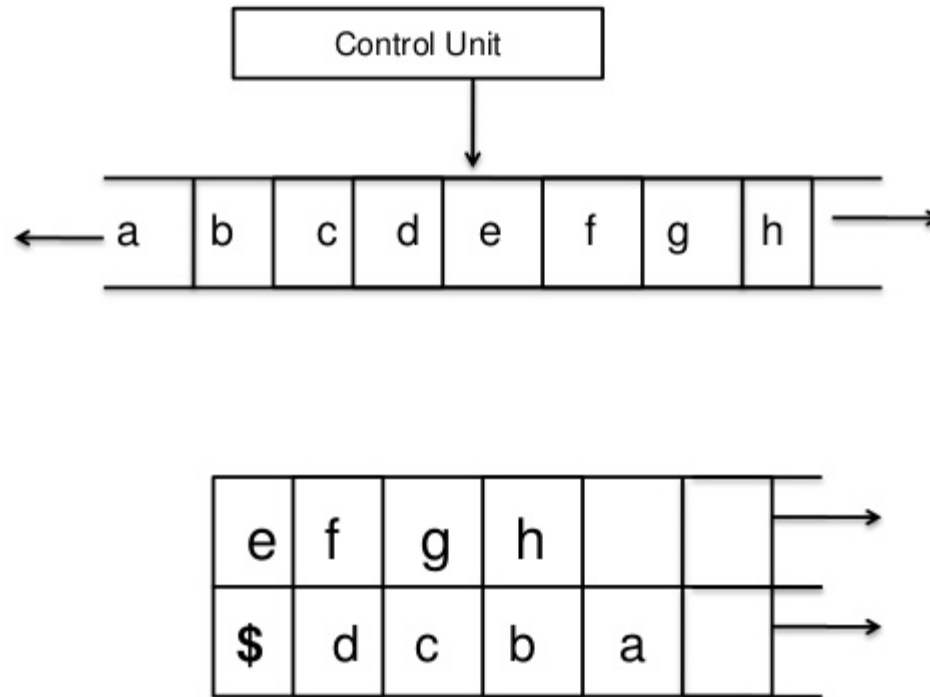


Semi-infinite tape machine



Simulation of two way infinite by semi-infinite tape

- Two way infinite tape simulated by semi -infinite tape



Multi-tape

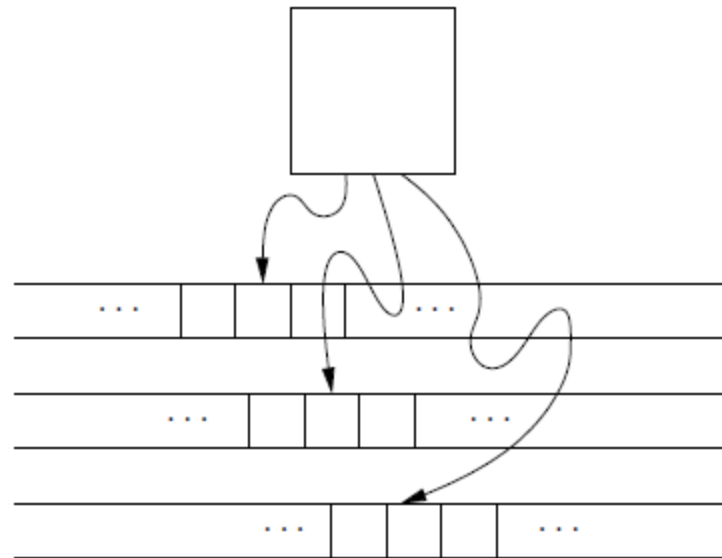


Figure 8.16: A multitape Turing machine

Simulation of multi-tape by one-tape

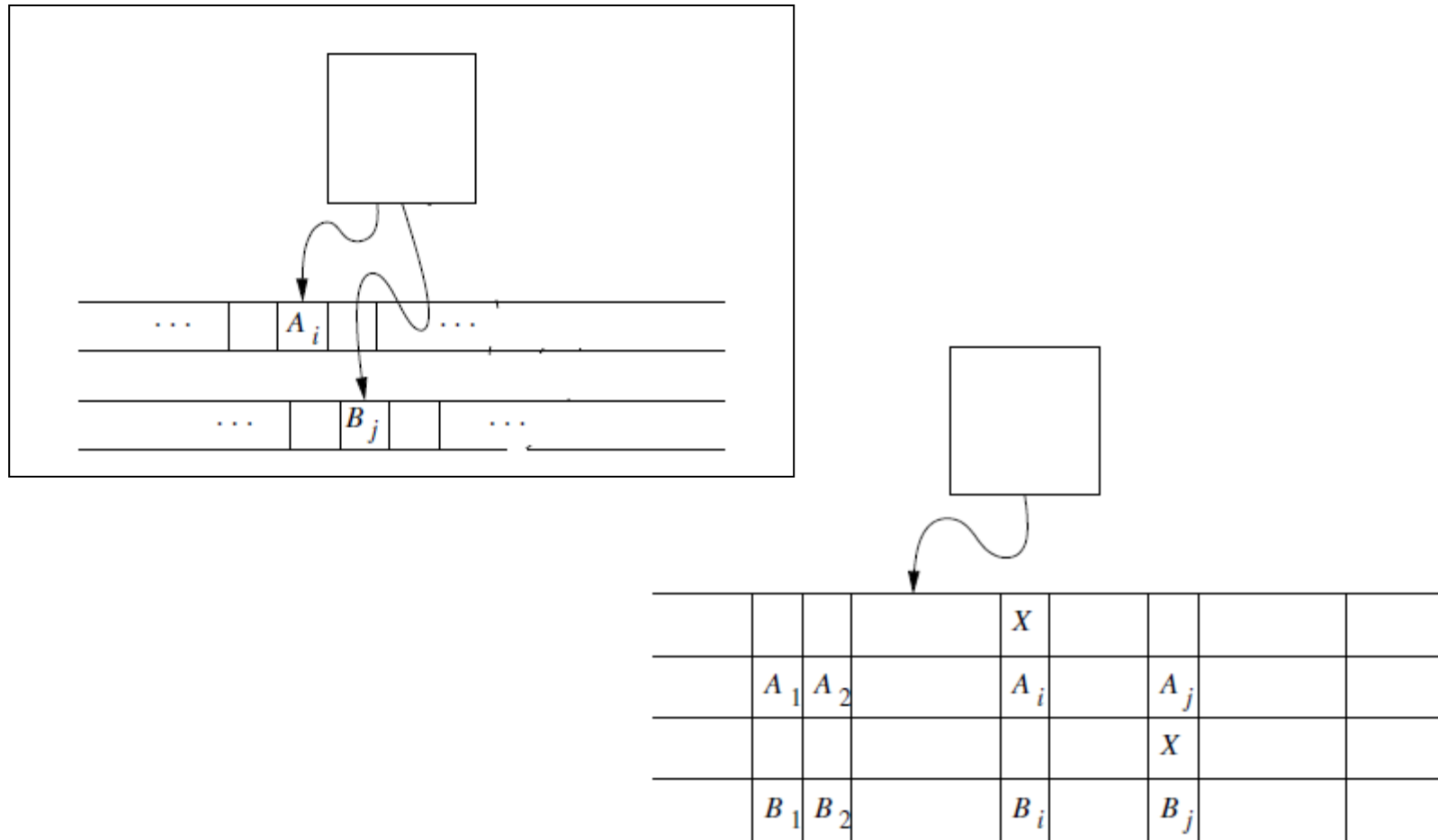


Figure 8.17: Simulation of a two-tape Turing machine by a one-tape Turing machine

NTM

NONDETERMINISTIC TM

- There is a choice in the next move.

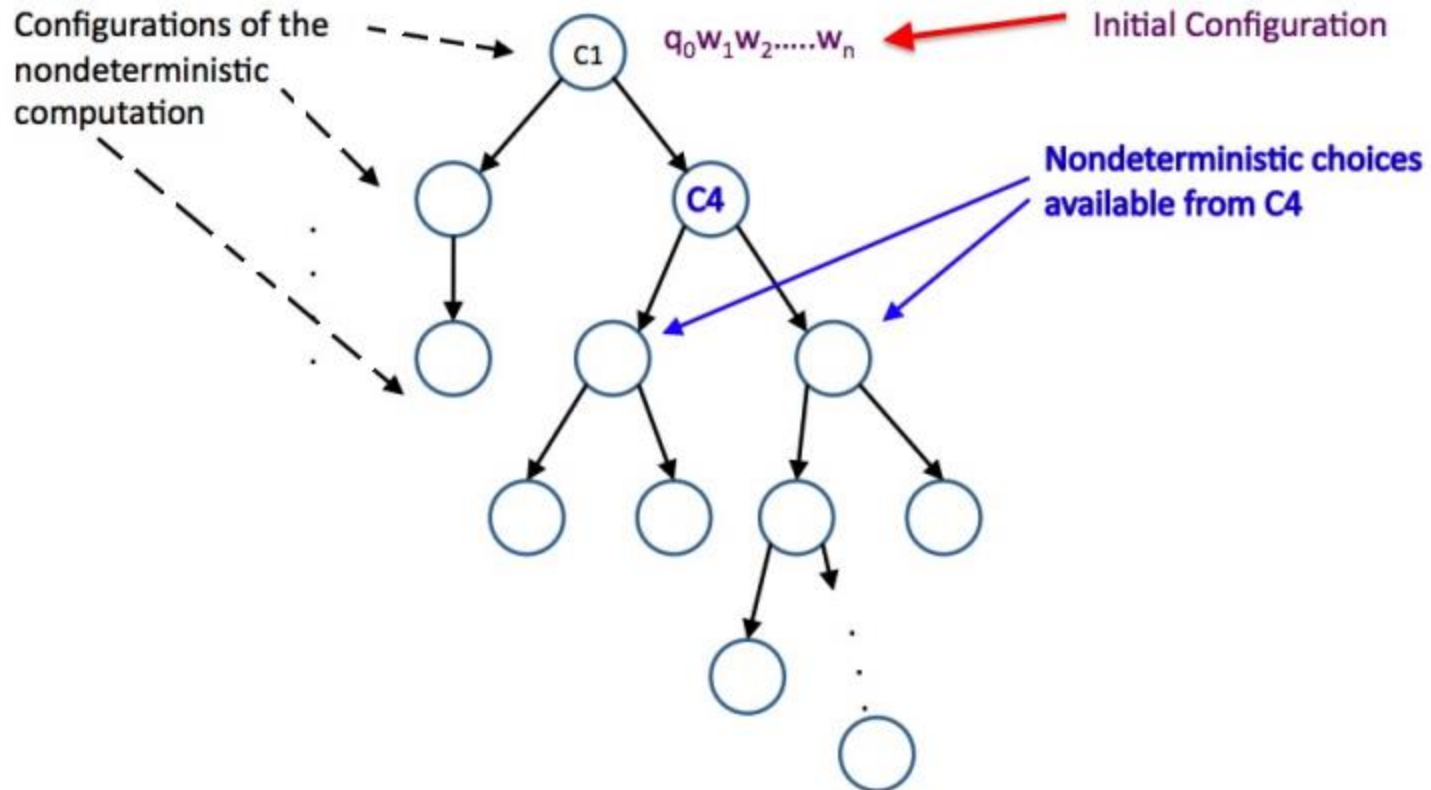
$$\delta(q, X) = \{(q_1, Y_1, D_1), (q_2, Y_2, D_2), \dots, (q_k, Y_k, D_k)\}$$

- Here, Y_i is a tape symbol, and D_i is one from $\{L, R\}$, the direction of movement of the head.

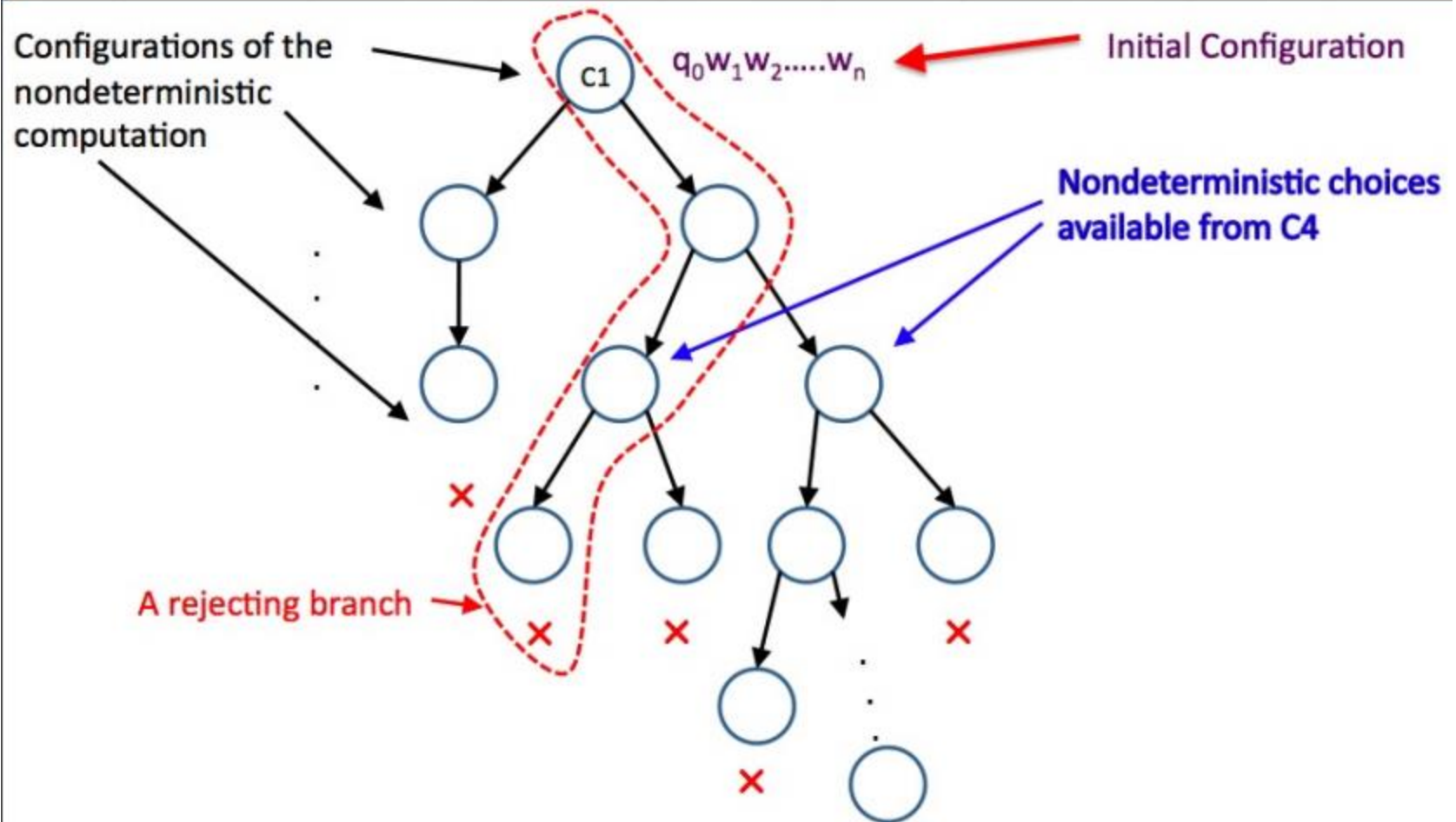
The transition function for a nondeterministic Turing machine has the form

$$\delta: Q \times \Gamma \longrightarrow \mathcal{P}(Q \times \Gamma \times \{L, R\}).$$

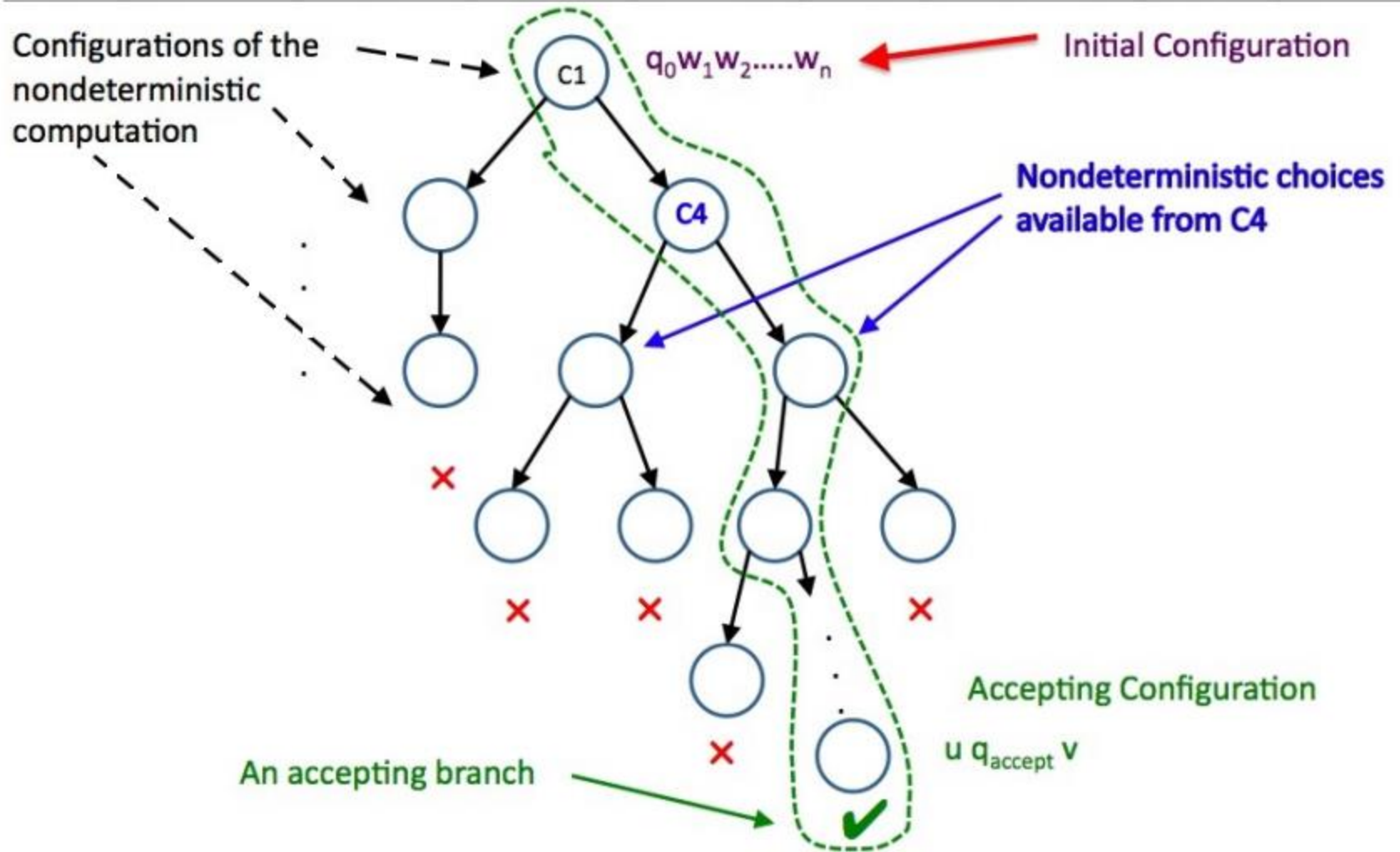
NONDETERMINISTIC COMPUTATION



NONDETERMINISTIC COMPUTATION

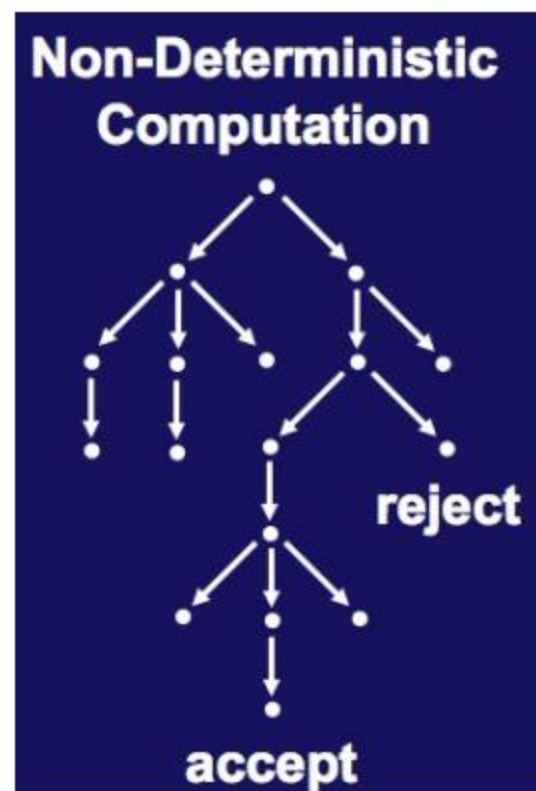
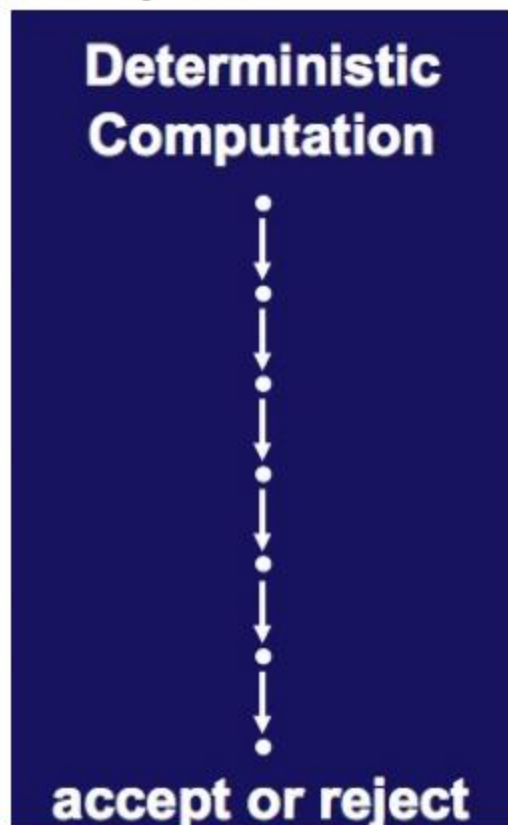


NONDETERMINISTIC COMPUTATION



NONDETERMINISTIC TURING MACHINES

- A computation of a Nondeterministic TM is a tree, where each branch of the tree is looks like a computation of an ordinary TM.



NONDETERMINISTIC TURING MACHINES

- If a single branch reaches the accepting state, the Nondeterministic TM accepts, even if other branches reach the rejecting state.
- What is the power of Nondeterministic TMs?
 - Is there a language that a Nondeterministic TM can accept but no deterministic TM can accept?

NONDETERMINISTIC TURING MACHINES

THEOREM

Every nondeterministic Turing machine has an equivalent deterministic Turing Machine.

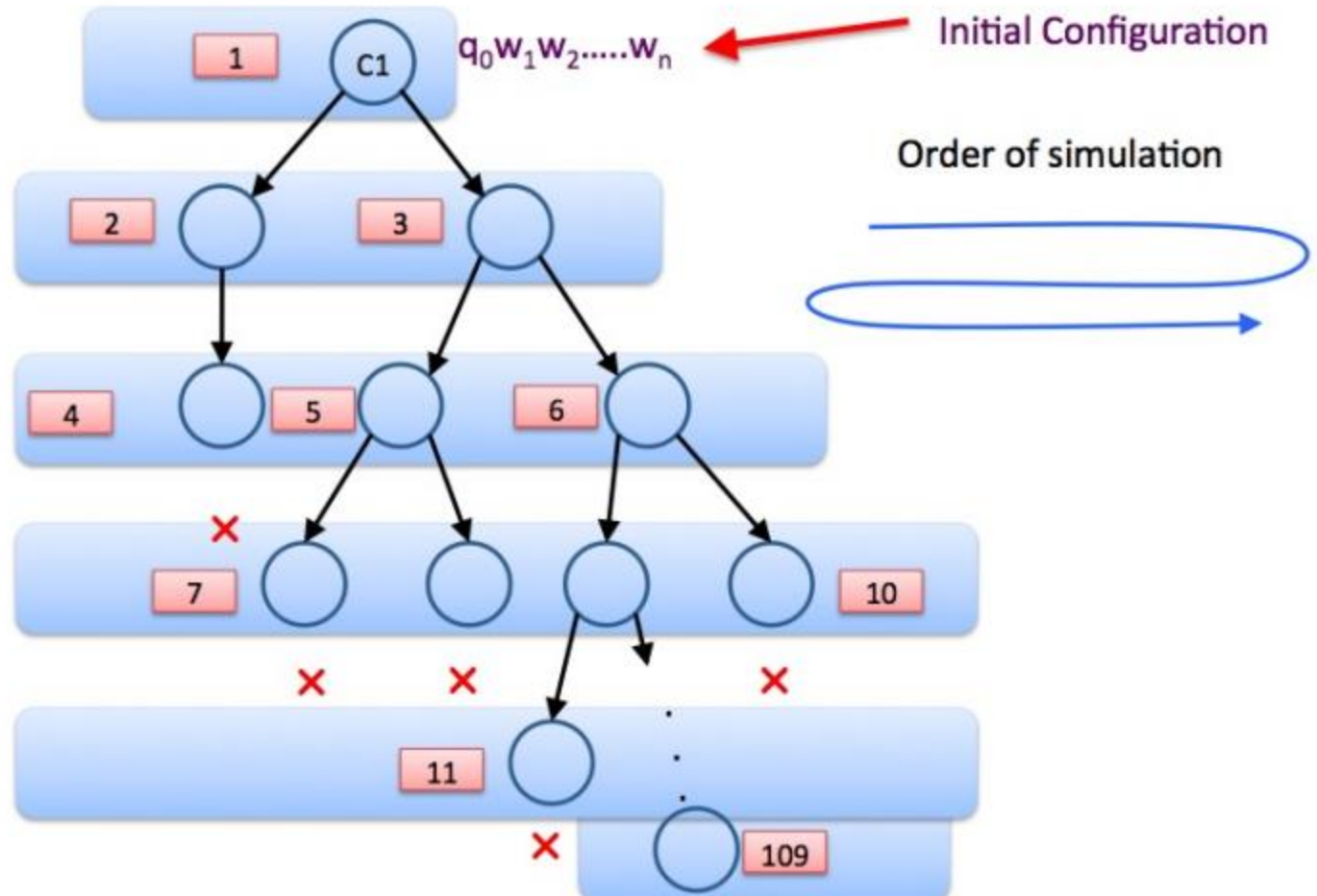
PROOF IDEA

- Timeshare a deterministic TM to different branches of the nondeterministic computation!
- Try out all branches of the nondeterministic computation until an accepting configuration is reached on one branch.
- Otherwise the TM goes on forever.

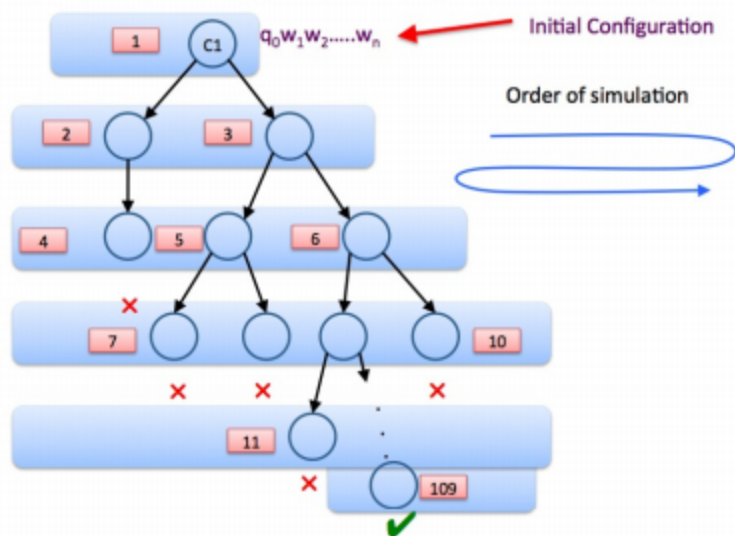
NONDETERMINISTIC TURING MACHINES

- Deterministic TM D simulates the Nondeterministic TM N .
- Some of branches of the N 's computations may be infinite, hence its computation tree has some infinite branches.
- If D starts its simulation by following an infinite branch, D may loop forever even though N 's computation may have a different branch on which it accepts.
- This is a very similar problem to processor scheduling in operating systems.
 - If you give the CPU to a (buggy) process in an infinite loop, other processes "starve".
- In order to avoid this unwanted situation, we want D to execute all of N 's computations concurrently.

SIMULATING NONDETERMINISTIC COMPUTATION



SIMULATING NONDETERMINISTIC COMPUTATION

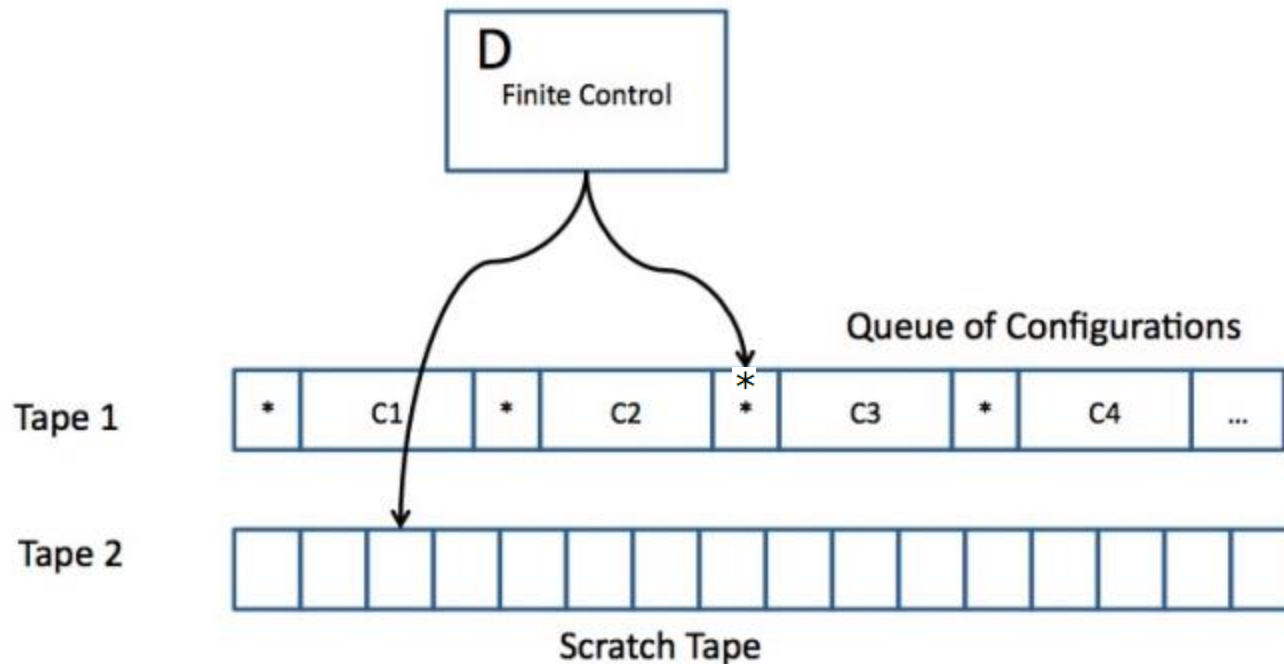


- During simulation, D processes the configurations of N in a **breadth-first fashion**.
- Thus D needs to maintain a **queue** of N 's configurations (Remember queues?)

- D gets the next configuration from the head of the queue.
- D creates copies of this configuration (as many as needed)
- On each copy, D simulates one of the nondeterministic moves of N .
- D places the resulting configurations to the **back** of the queue.

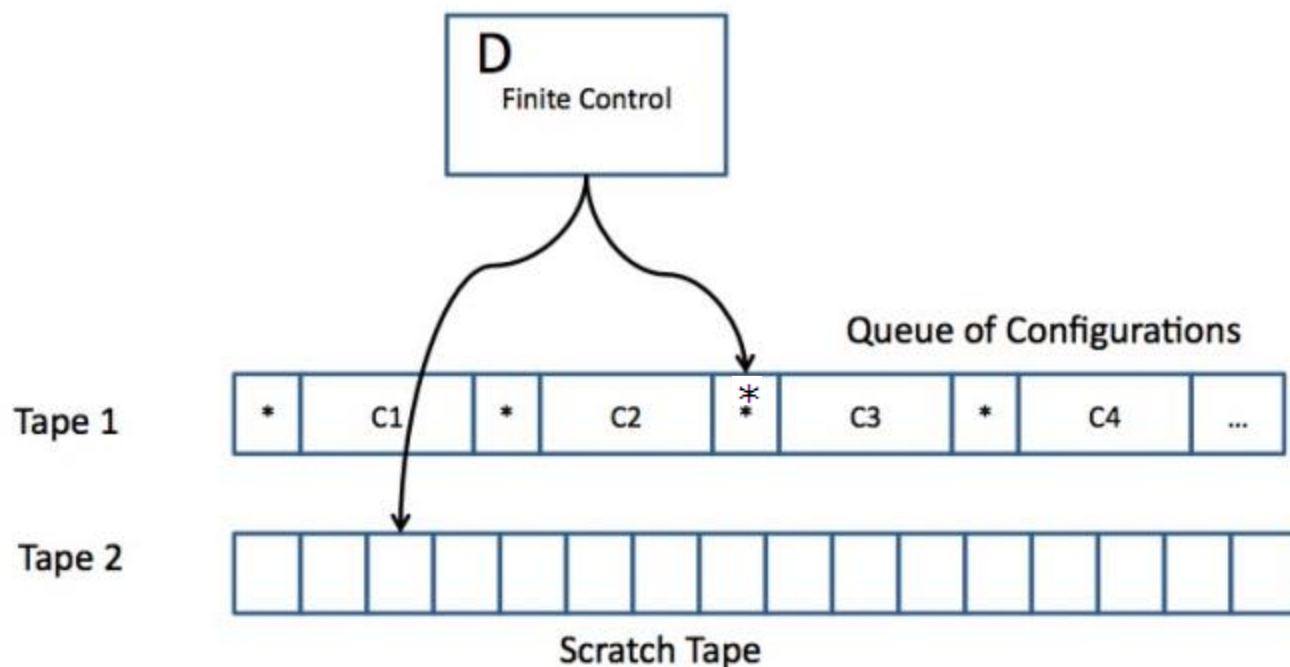
STRUCTURE OF THE SIMULATING DTM

- N is simulated with 2-tape DTM, D



STRUCTURE OF THE SIMULATING DTM

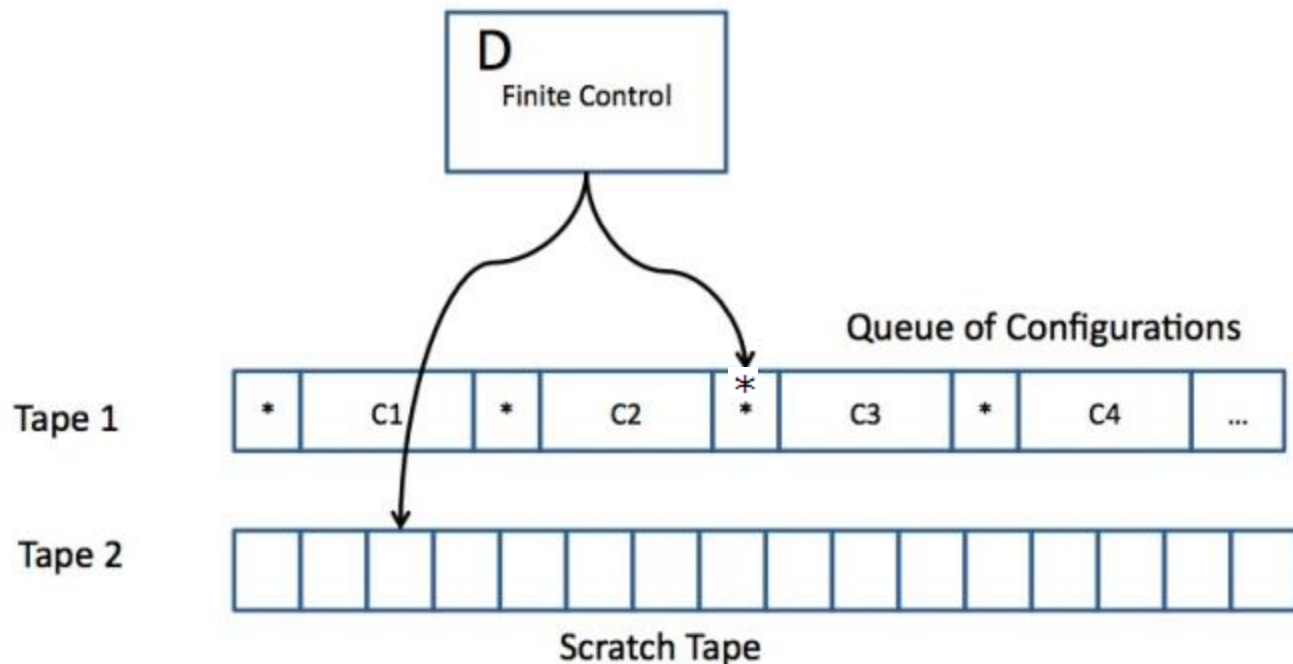
- N is simulated with 2-tape DTM, D



- Built into the finite control of D is the knowledge of what choices of moves N has for each state and input.

STRUCTURE OF THE SIMULATING DTM

- N is simulated with 2-tape DTM, D



- 1 D examines the state and the input symbol of the current configuration (right after the dotted separator)
- 2 If the state of the current configuration is the accept state of N , then D accepts the input and stops simulating N .

HOW D SIMULATES N

- Let m be the maximum number of choices N has for any of its states.
- Then, after n steps, N can reach at most $1 + m + m^2 + \dots + m^n$ configurations (which is at most nm^n)
- Thus D has to process at most this many configurations to simulate n steps of N .
- Thus the simulation can take **exponentially** more time than the nondeterministic TM.
- It is not known whether or not this exponential slowdown is necessary.

IMPLICATIONS

COROLLARY

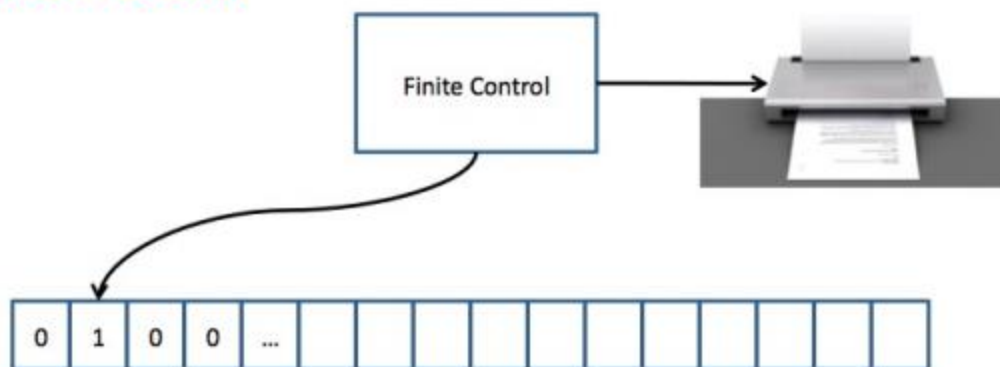
A language is Turing-recognizable if and only if some nondeterministic TM recognizes it.

COROLLARY

A language is decidable if and only if some nondeterministic TM decides it.

ENUMERATORS

- Remember we noted that some books used the term **recursively enumerable** for Turing-recognizable.
- This term arises from a variant of a TM called an **enumerator**.



- TM generates strings one by one.
- Everytime the TM wants to add a string to the list, it sends it to the printer.

ENUMERATORS

- The enumerator E starts with a blank input tape.
- If it does not halt, it may print an infinite list of strings.
- The strings can be enumerated in any order; repetitions are possible.
- The language of the enumerator is the collection of strings it eventually prints out.

ENUMERATORS

THEOREM

A language is Turing recognizable if and only if some enumerator enumerates it.

PROOF.

The If-part: If an enumerator E enumerates the language A then a TM M recognizes A .

$M =$ “On input w

- ① Run E . Everytime E outputs a string, compare it with w .
- ② If w ever appears in the output of E , *accept*.”

Clearly M accepts only those strings that appear on E 's list.



ENUMERATORS

THEOREM

A language is Turing recognizable if and only if some enumerator enumerates it.

PROOF.

The Only-If-part: If a TM M recognizes a language A , we can construct the following enumerator for A . Assume s_1, s_2, s_3, \dots is a list of possible strings in Σ^* .

E = "Ignore the input

- ① Repeat the following for $i = 1, 2, 3, \dots$
- ② Run M for i steps on each input $s_1, s_2, s_3, \dots, s_i$.
- ③ If any computations accept, print out corresponding s_j ."

If M accepts a particular string, it will appear on the list generated by E (in fact infinitely many times)

THE DEFINITION OF ALGORITHM - HISTORY

- in 1900, Hilbert posed the following problem:
“Given a polynomial of several variables with integer coefficients, does it have an integer root – an assignment of integers to variables, that make the polynomial evaluate to 0”
- For example, $6x^3yz^2 + 3xy^2 - x^3 - 10$ has a root at $x = 5, y = 3, z = 0$.
- Hilbert explicitly asked that an algorithm/procedure to be “devised”. He assumed it existed; somebody needed to find it!
- 70 years later it was shown that no algorithm exists.
- The intuitive notion of an algorithm may be adequate for giving algorithms for certain tasks, but was useless for showing no algorithm exists for a particular task.

THE DEFINITION OF ALGORITHM - HISTORY

- In early 20th century, there was no formal definition of an algorithm.
- In 1936, Alonzo Church and Alan Turing came up with formalisms to define algorithms. These were shown to be equivalent, leading to the

CHURCH-TURING THESIS

Intuitive notion of algorithms \equiv Turing Machine Algorithms

THE DEFINITION OF AN ALGORITHM

- Let $D = \{p \mid p \text{ is a polynomial with integral roots}\}$
- Hilbert's 10th problem in TM terminology is "Is D decidable?" (No!)
- However D is Turing-recognizable!
- Consider a simpler version
 $D_1 = \{p \mid p \text{ is a polynomial over } x \text{ with integral roots}\}$
- $M_1 =$ "The input is polynomial p over x .
 - 1 Evaluate p with x successively set to 0, 1, -1, 2, -2, 3, -3,
 - 2 If at any point, p evaluates to 0, *accept*."
- D_1 is actually decidable since only a finite number of x values need to be tested (math!)
- D is also recognizable: just try systematically all integer combinations for all variables.