

# A physical model for efficient ranking in networks

Daniel Larremore  
BioFrontiers Institute & Dept. of Computer Science

Apr 9, 2018  
Duke - DNAC



University of Colorado **Boulder**

[daniel.larremore@colorado.edu](mailto:daniel.larremore@colorado.edu)  
[@danlarremore](https://twitter.com/danlarremore)

# Rankings and linear hierarchies



# Rankings and linear hierarchies



# The idea of rankings—pervasive!

Assumptions:

1. Competitors have some intrinsic quality (or vector of qualities).
2. Interactions can (stochastically) reveal differences in qualities.
3. Competitions are pair-wise. (Lee Sedol vs. AlphaGo; Astros vs. Dodgers)

# The idea of rankings—pervasive!

Assumptions:

1. Competitors have some intrinsic quality (or vector of qualities).
2. Interactions can (stochastically) reveal differences in qualities.
3. Competitions are pair-wise. (Lee Sedol vs. AlphaGo; Astros vs. Dodgers)

In other words: outcomes are generated by a stochastic process, which is some function of the positions of the competitors.

# The idea of rankings—pervasive!

Assumptions:

1. Competitors have some intrinsic quality (or vector of qualities).
2. Interactions can (stochastically) reveal differences in qualities.
3. Competitions are pair-wise. (Lee Sedol vs. AlphaGo; Astros vs. Dodgers)

In other words: outcomes are generated by a stochastic process, which is some function of the positions of the competitors.



# Systems of dominance

social



mental



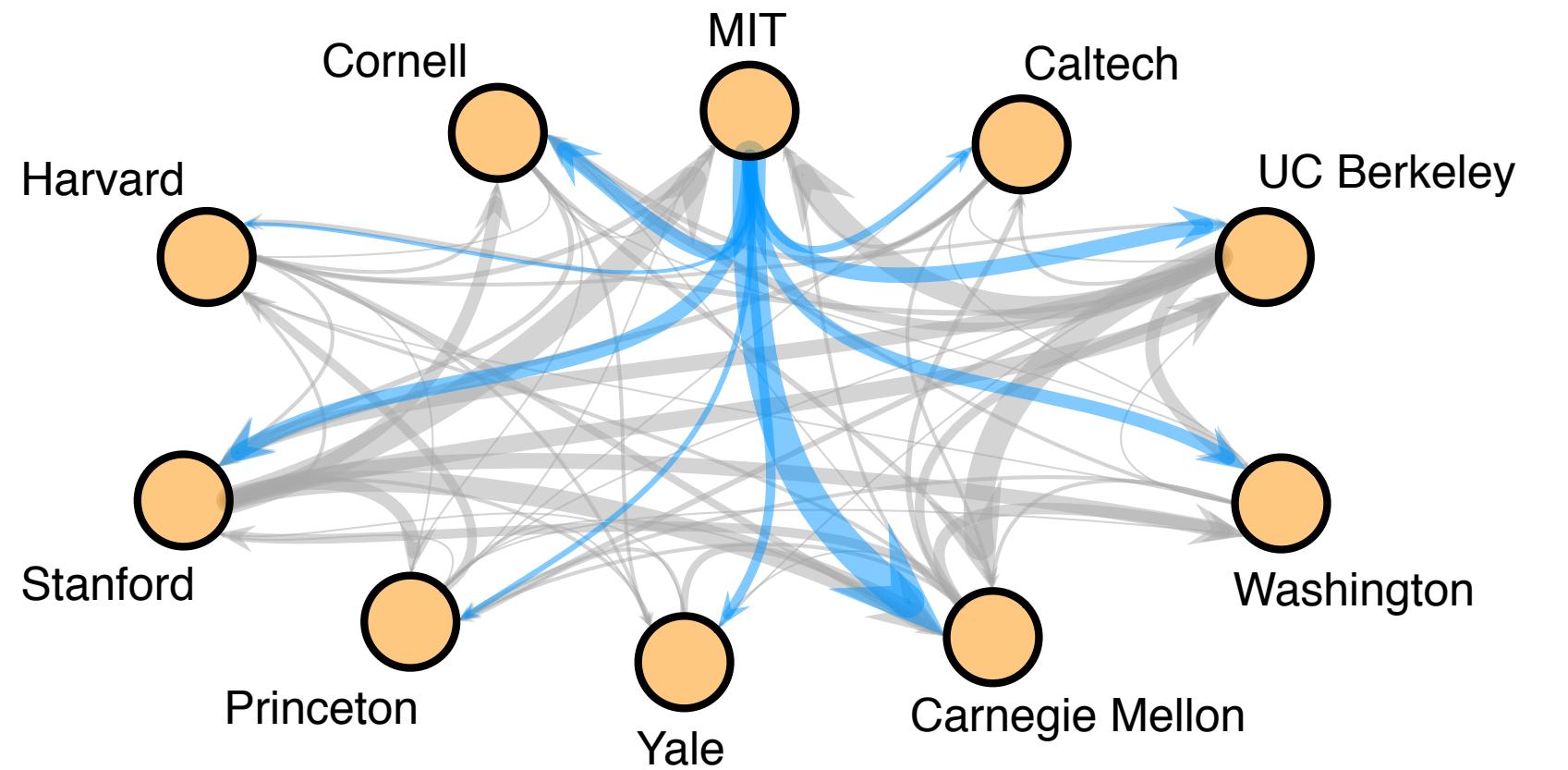
physical

A screenshot of the [hockeyfights.com](http://hockeyfights.com) website. The main heading is "Sam Bennett vs Ryan Johansen". Below it, the date is Feb 21, 2017, 2pd 06:27, and the season is 2016-2017 Regular Season. A video player shows two hockey players in action. To the left, there's a "Your vote" section with a note about signing in to vote and a link to sign up. Below that is a "Results" section showing a poll where Sam Bennett has 92.9% of the votes, Ryan Johansen has 5.4%, and Draw has 1.8%. The results are based on 56 votes with an average rating of 5.6. At the bottom, there are fields for User Name, Password, and Log in, along with a "Remember Me?" checkbox.

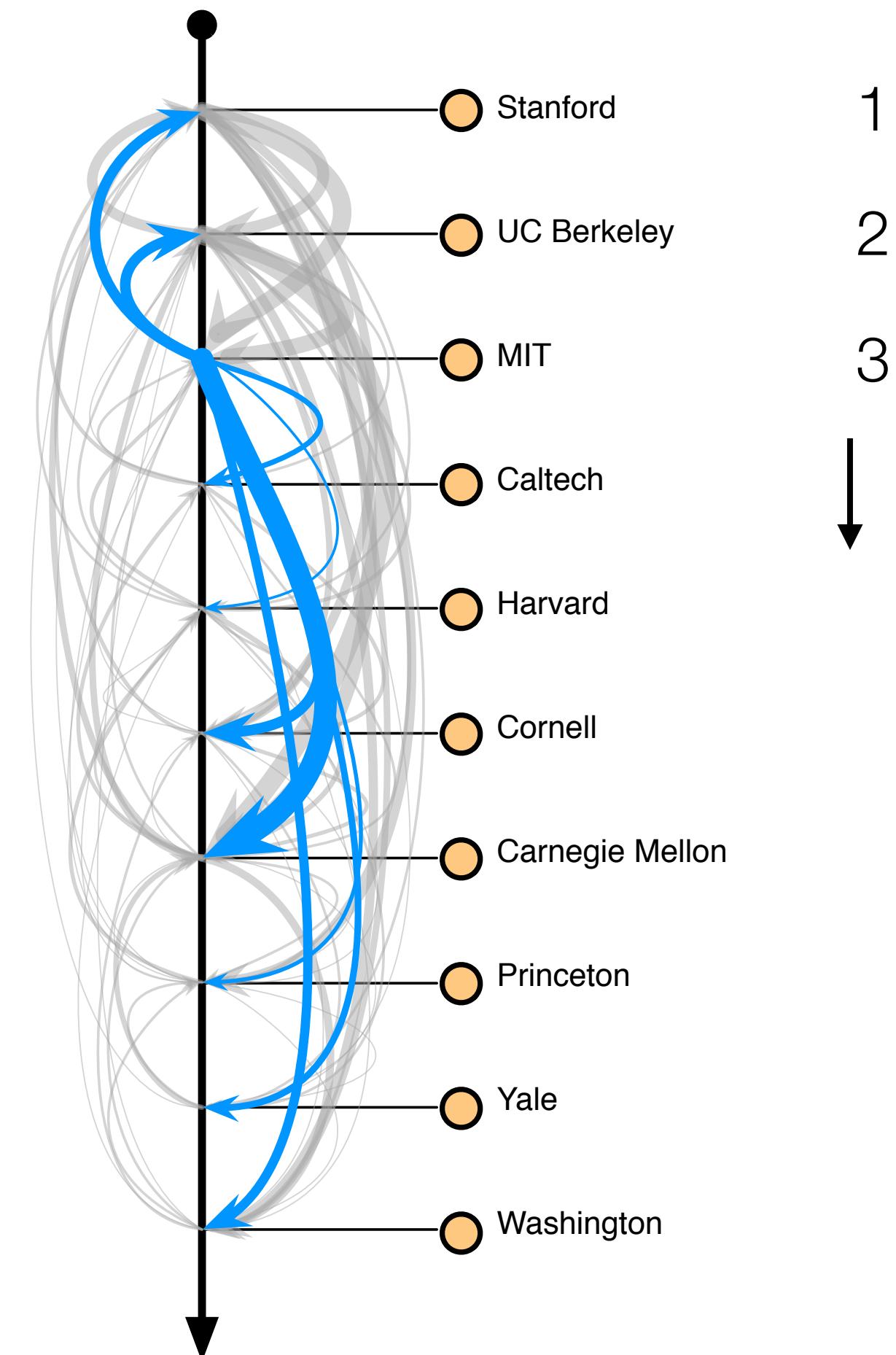
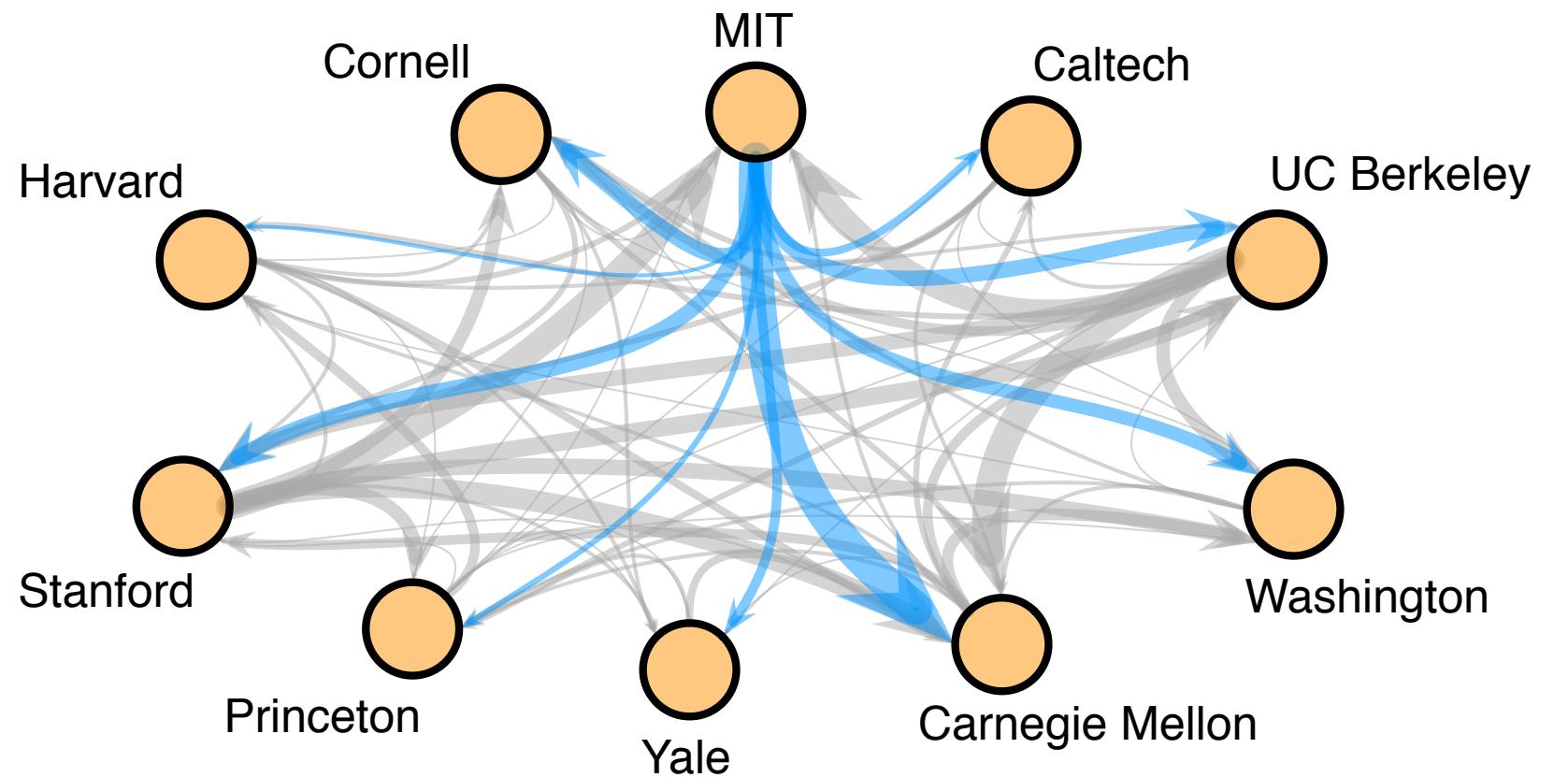
financial



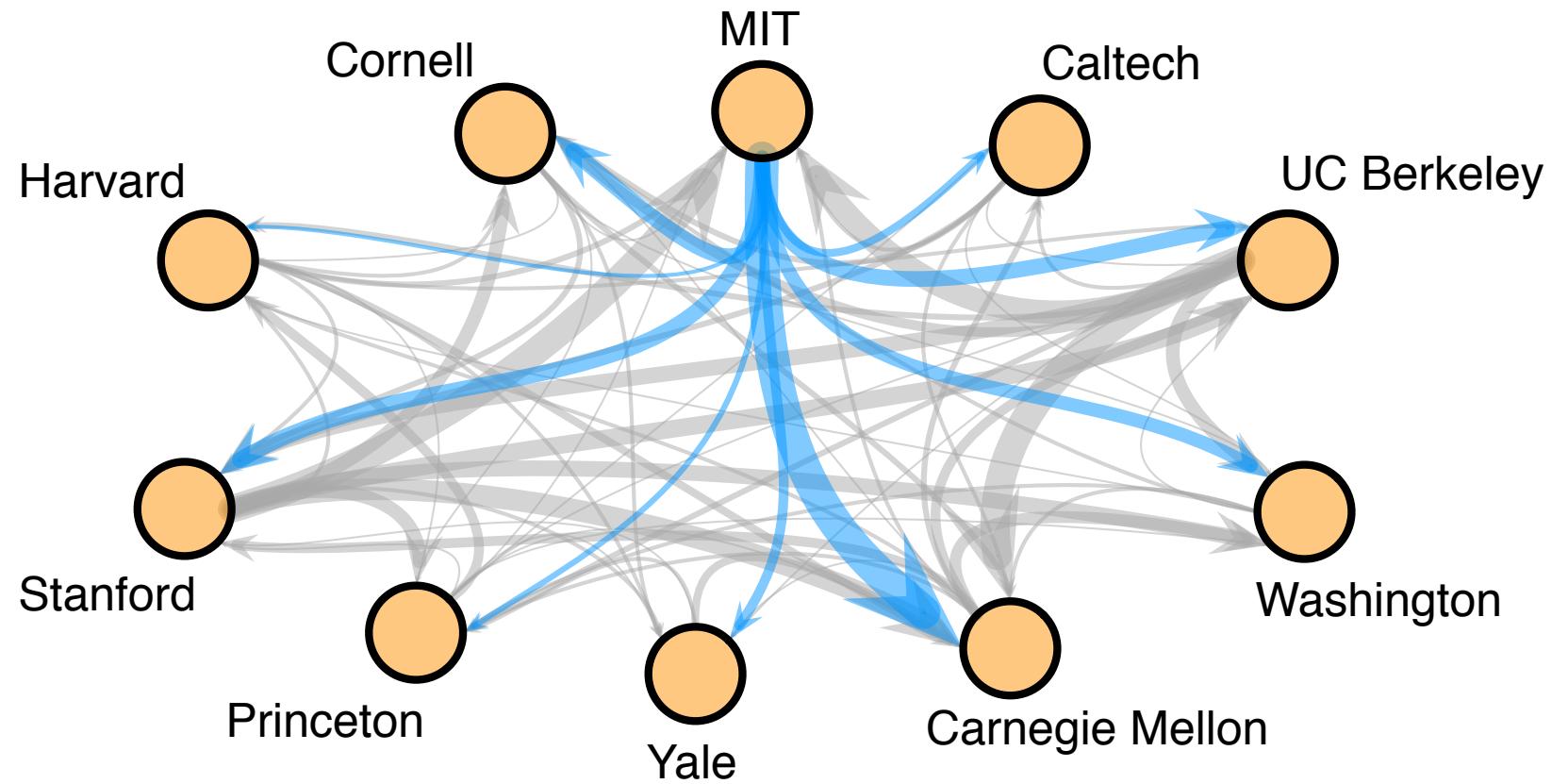
# Systems of endorsement



# Systems of endorsement

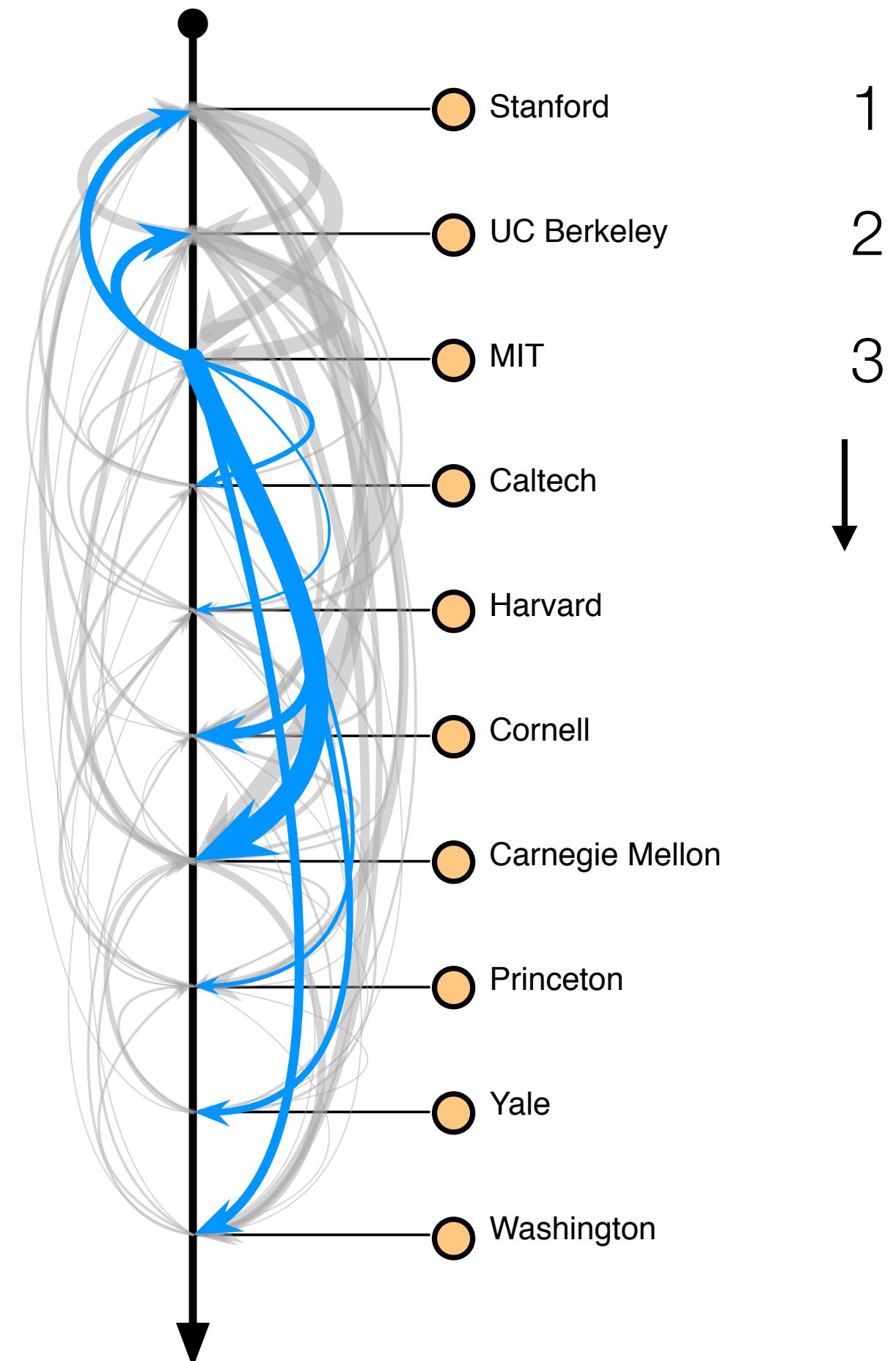


# Systems of endorsement

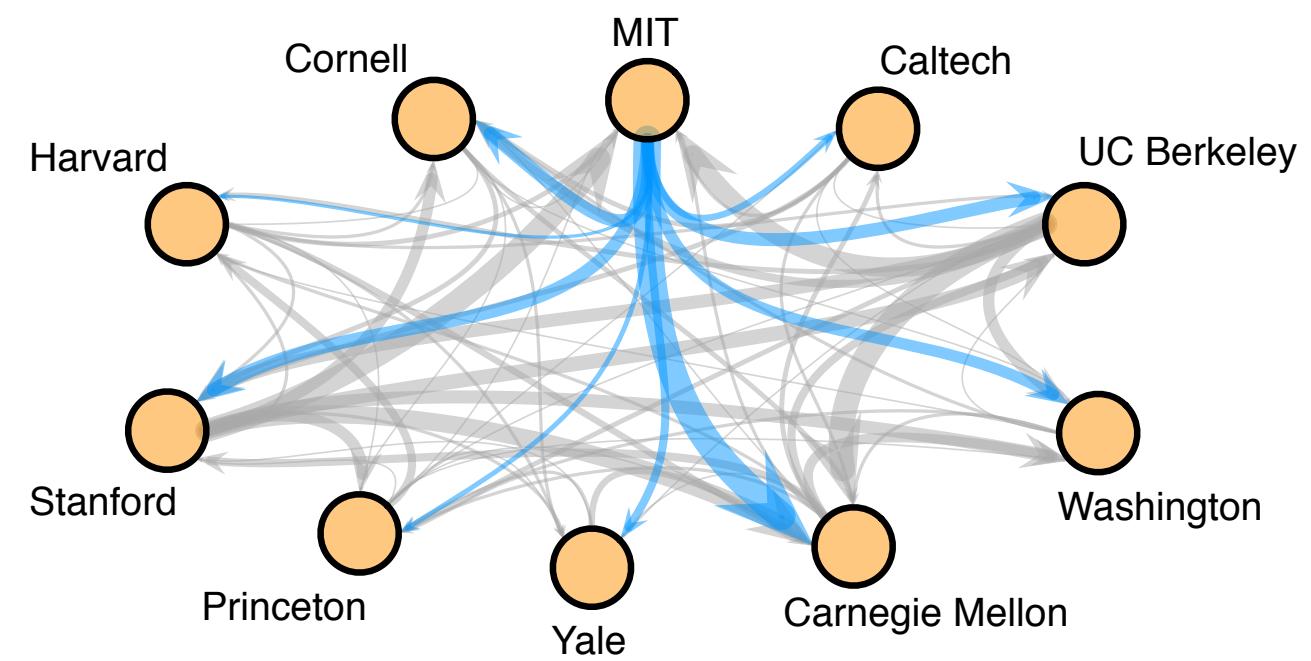


Assumptions:

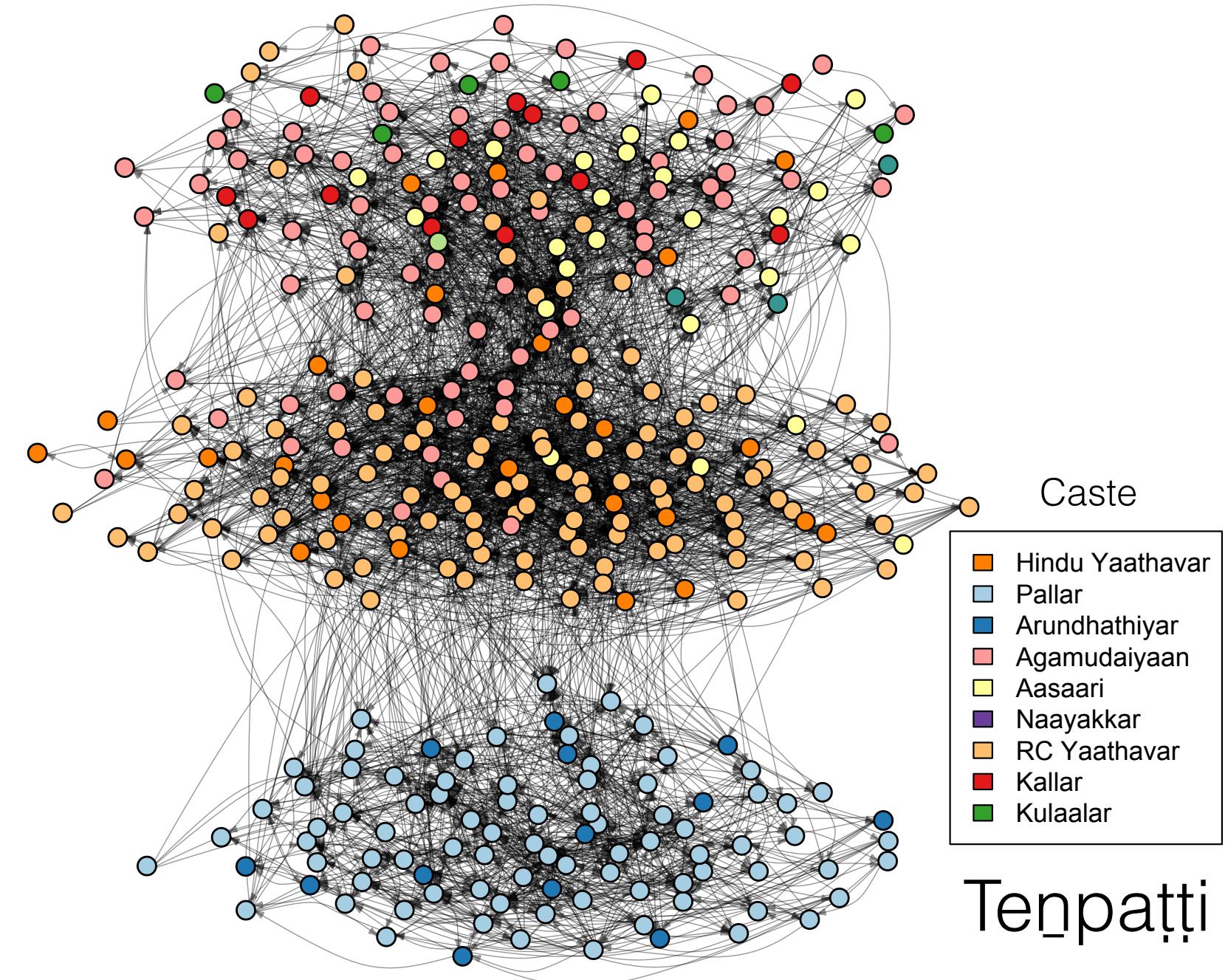
1. Endorsers have some intrinsic quality.
2. Interactions can reveal differences in qualities.
3. Endorsements are pair-wise.



# Systems of endorsement



Latent position can be revealed by dominance or endorsement interactions.



# Win-Loss is not satisfactory: schedule matters

Beating the grandmaster counts for more than beating a novice.

# Win-Loss is not satisfactory: schedule matters

Beating the grandmaster counts for more than beating a novice.

Win and loss tallies don't take this "schedule difficulty" into account. Put differently, win-loss records leave information on the table.

# Win-Loss is not satisfactory: schedule matters

Beating the grandmaster counts for more than beating a novice.

Win and loss tallies don't take this "schedule difficulty" into account. Put differently, win-loss records leave information on the table.

Ranking methods: many competing ideas!

# Win-Loss is not satisfactory: schedule matters

Beating the grandmaster counts for more than beating a novice.

Win and loss tallies don't take this "schedule difficulty" into account. Put differently, win-loss records leave information on the table.

Ranking methods: many competing ideas!

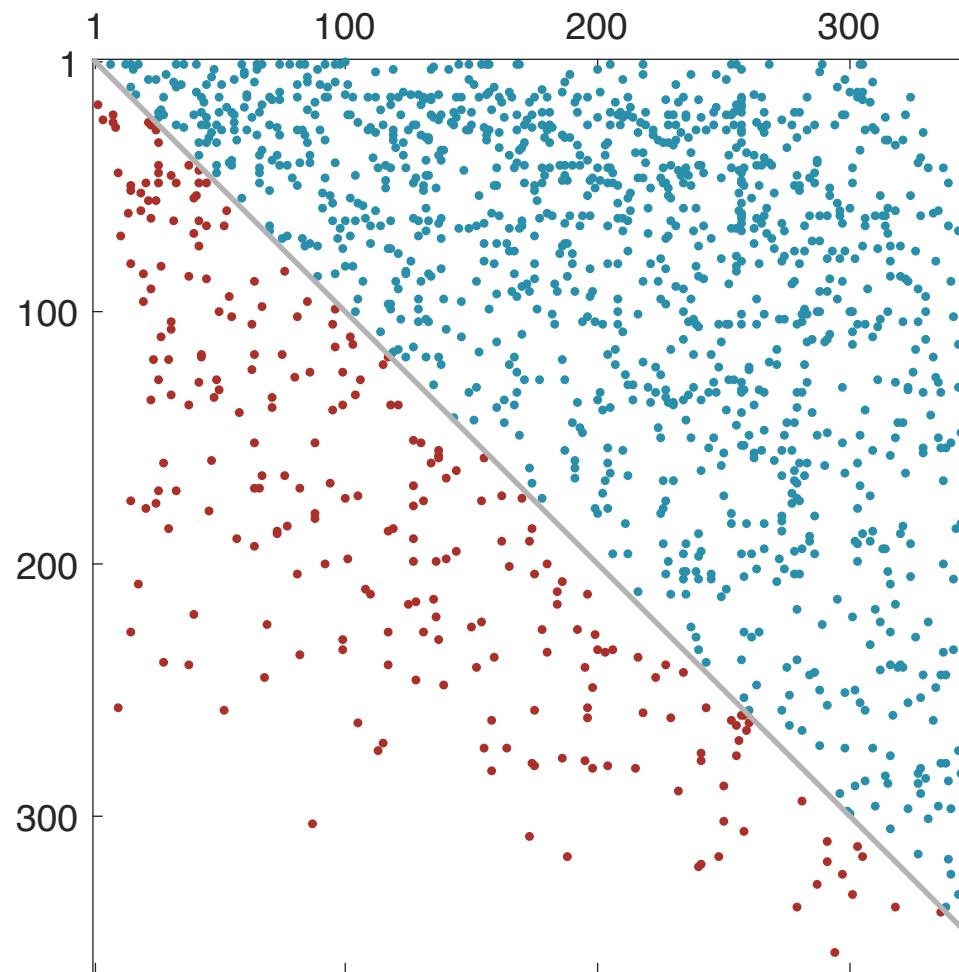
**Ordinal rankings** (order nodes; integer values)

**Embeddings** (place nodes; continuous values)

# Ranking methods: many competing ideas!

**Minimum Violations Rank** finds an order of nodes to minimize “upsets”:

- No ties (but see Agony methods), many minima, and provably NP hard.



minimum violation ranking: sort  $A$ .

# Ranking methods: many competing ideas!

**Minimum Violations Rank** finds an order of nodes to minimize “upsets”:

- No ties (but see Agony methods), many minima, and provably NP hard.

**PageRank** defines scalar rank recursively:

*important pages are those that are linked to by important pages.*

- Great at finding the top 3 but low interpretability of the PageRank scores.

## The PageRank Citation Ranking: Bringing Order to the Web

January 29, 1998

### Abstract

The importance of a Web page is an inherently subjective matter, which depends on the readers interests, knowledge and attitudes. But there is still much that can be said objectively about the relative importance of Web pages. This paper describes PageRank, a method for rating Web pages objectively and mechanically, effectively measuring the human interest and attention devoted to them.

We compare PageRank to an idealized random Web surfer. We show how to efficiently compute PageRank for large numbers of pages. And, we show how to apply PageRank to search and to user navigation.

# Ranking methods: many competing ideas!

**Minimum Violations Rank** finds an order of nodes to minimize “upsets”:

- No ties (but see Agony methods), many minima, and provably NP hard.

**PageRank** defines scalar rank recursively:

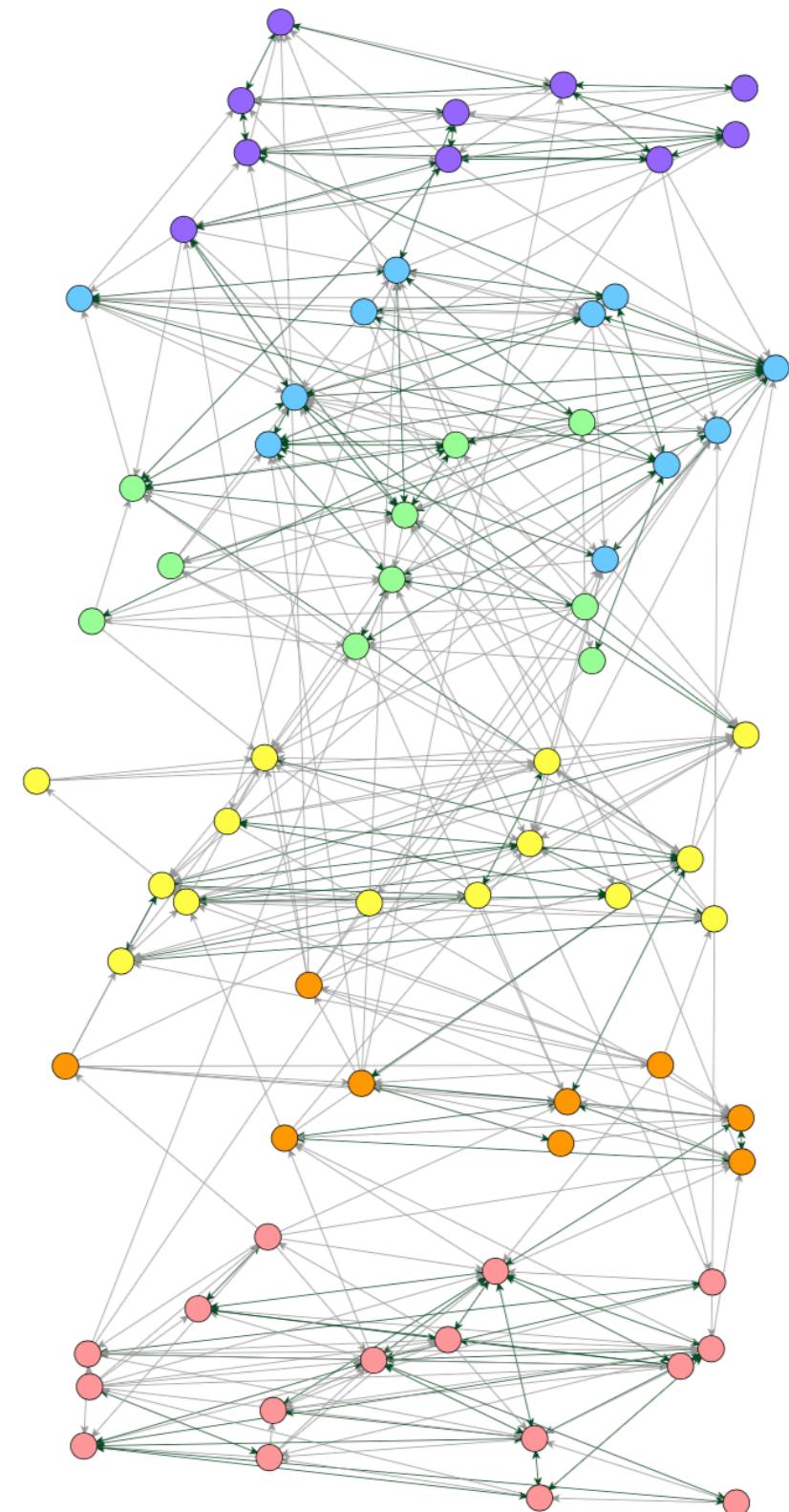
*important pages are those that are linked to by important pages.*

- Great at finding the top 3 but low interpretability of the PageRank scores.

**Ball & Newman** inferred ordinal rank via random graph + ranks model:

*infer parameters of people's attachment preferences & ranks.*

- Found that in AddHealth data, teens link to others of *nearby* social status.



# Ranking methods: many competing ideas!

**Minimum Violations Rank** finds an order of nodes to minimize “upsets”:

- No ties (but see Agony methods), many minima, and provably NP hard.

**PageRank** defines scalar rank recursively:

*important pages are those that are linked to by important pages.*

- Great at finding the top 3 but low interpretability of the PageRank scores.

**Ball & Newman** inferred ordinal rank via random graph + ranks model:

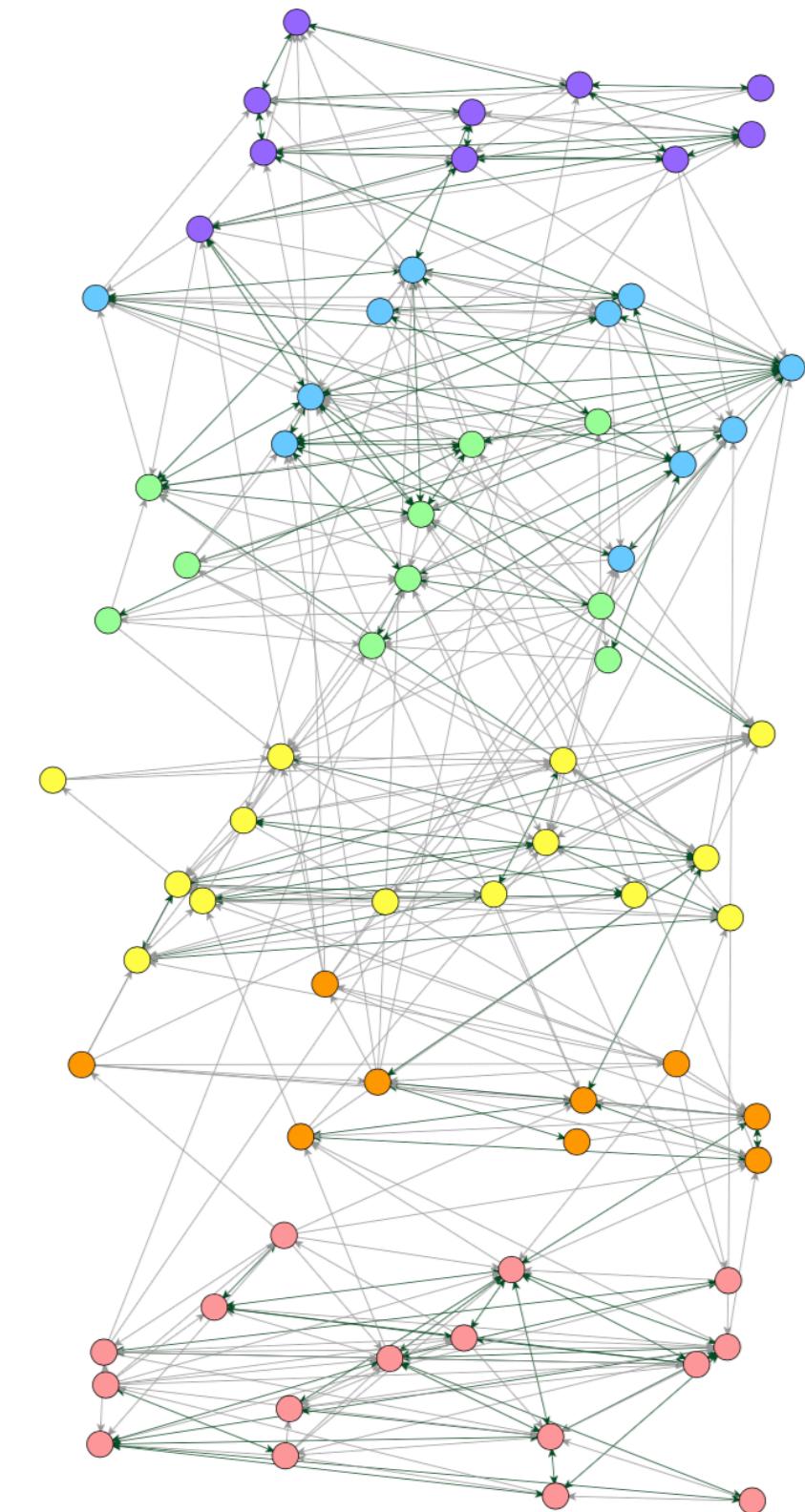
*infer parameters of people's attachment preferences & ranks.*

- Found that in AddHealth data, teens link to others of *nearby* social status.

**Niche Models** embed species in a latent space based on feeding preferences:

*most species feed from narrow range in a 1-dim. space (~body size).*

- Great for food webs. Inference models v slow for all but small networks.



# Ranking methods: many competing ideas!

## Minimum Violations Ranking

- No ties (but see Agarwal et al.)

## PageRank defines scalar importance

*important pages are those that link to them*

- Great at finding the most important pages

## Ball & Newman inferred parameters of species

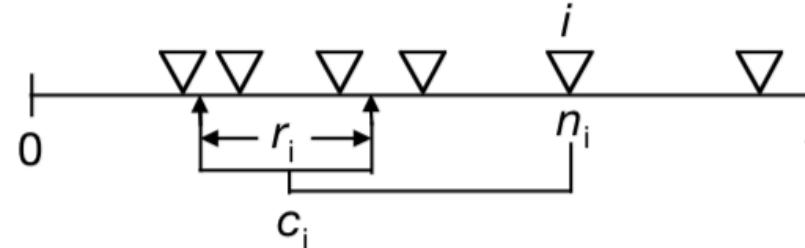
- Found that in Additive Models

## Niche Models

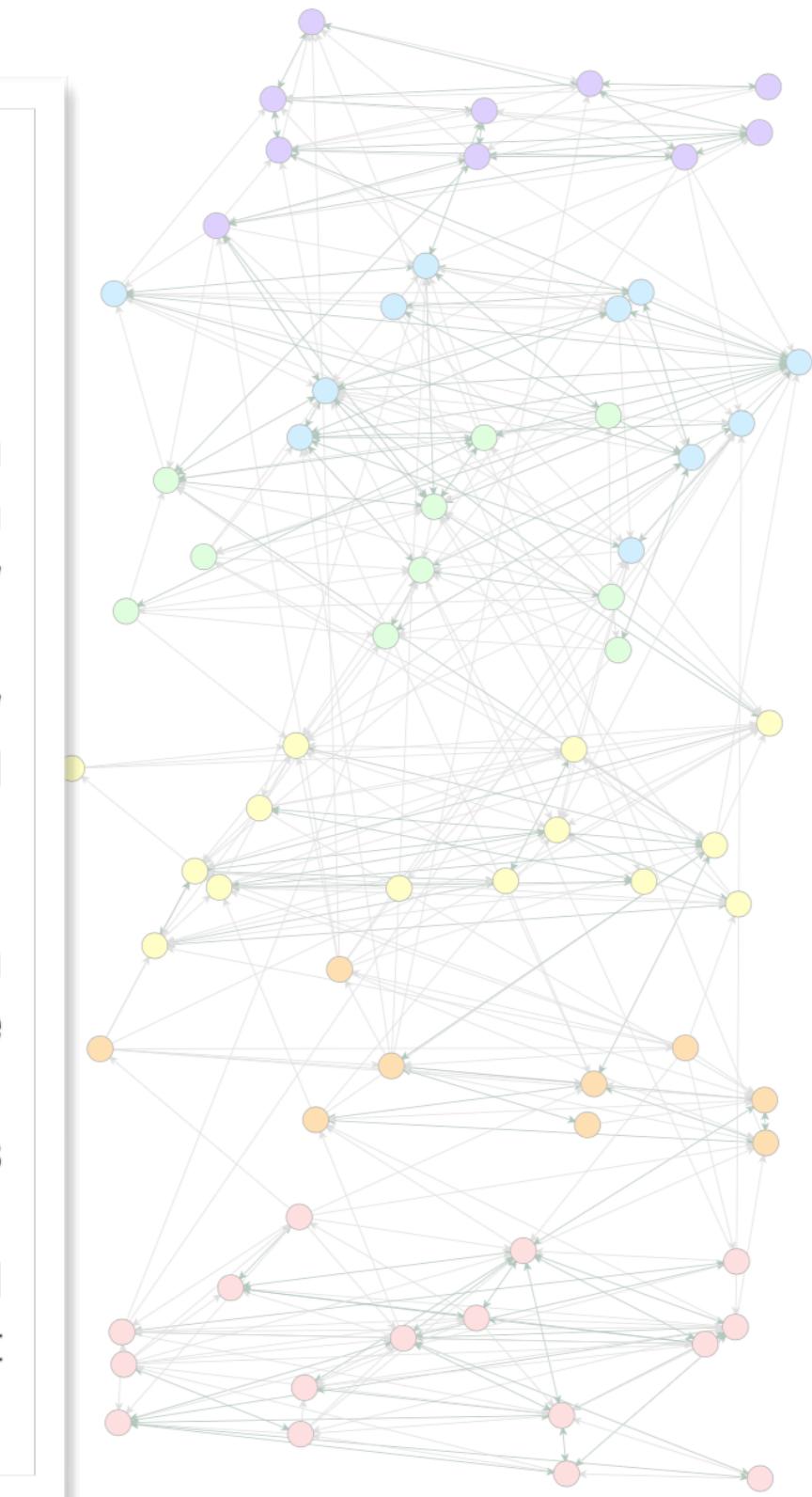
embed species in a space

*most species feed from a few niches*

- Great for food web analysis



**Figure 1** Diagram of the niche model. Each of  $\mathbf{S}$  species (for example,  $\mathbf{S}=6$ , each shown as an inverted triangle) is assigned a ‘niche value’ parameter ( $n_i$ ) drawn uniformly from the interval  $[0,1]$ . Species  $i$  consumes all species falling in a range ( $r_i$ ) that is placed by uniformly drawing the centre of the range ( $c_i$ ) from  $[r/2, n_i]$ . This permits looping and cannibalism by allowing up to half of  $r_i$  to include values  $\geq n_i$ . The size of  $r_i$  is assigned by using a beta function to randomly draw values from  $[0,1]$  whose expected value is  $2\mathbf{C}$  and then multiplying that value by  $n_i$  [expected  $E(n_i) = 0.5$ ] to obtain the desired  $\mathbf{C}$ . A beta distribution with  $\alpha = 1$  has the form  $f(x|1, \beta) = \beta(1-x)^{\beta-1}$ ,  $0 < x < 1$ , 0 otherwise, and  $E(X) = 1/(1+\beta)$ . In this case,  $x = 1-(1-y)^{1/\beta}$  is a random variable from the beta distribution if  $y$  is a uniform random variable and  $\beta$  is chosen to obtain the desired expected value. We chose this form because of its simplicity and ease of calculation. The fundamental generality of species  $i$  is measured by  $r_i$ . The number of species falling within  $r_i$  measures realized generality. Occasionally, model-generated webs contain completely disconnected species or trophically identical species. Such species are eliminated and replaced until the web is free of such species. The species with the smallest  $n_i$  has  $r_i = 0$  so that every web has at least one basal species.



# Ranking methods: many competing ideas!

**Minimum Violations Rank** finds an order of nodes to minimize “upsets”:

- No ties (but see Agony methods), many minima, and provably NP hard.

**PageRank** defines scalar rank recursively:

*important pages are those that are linked to by important pages.*

- Great at finding the top 3 but low interpretability of the PageRank scores.

**Ball & Newman** inferred ordinal rank via random graph + ranks model:

*infer parameters of people's attachment preferences & ranks.*

- Found that in AddHealth data, teens link to others of *nearby* social status.

**Niche Models** embed species in a latent space based on feeding preferences:

*most species feed from narrow range in a 1-dim. space (~body size).*

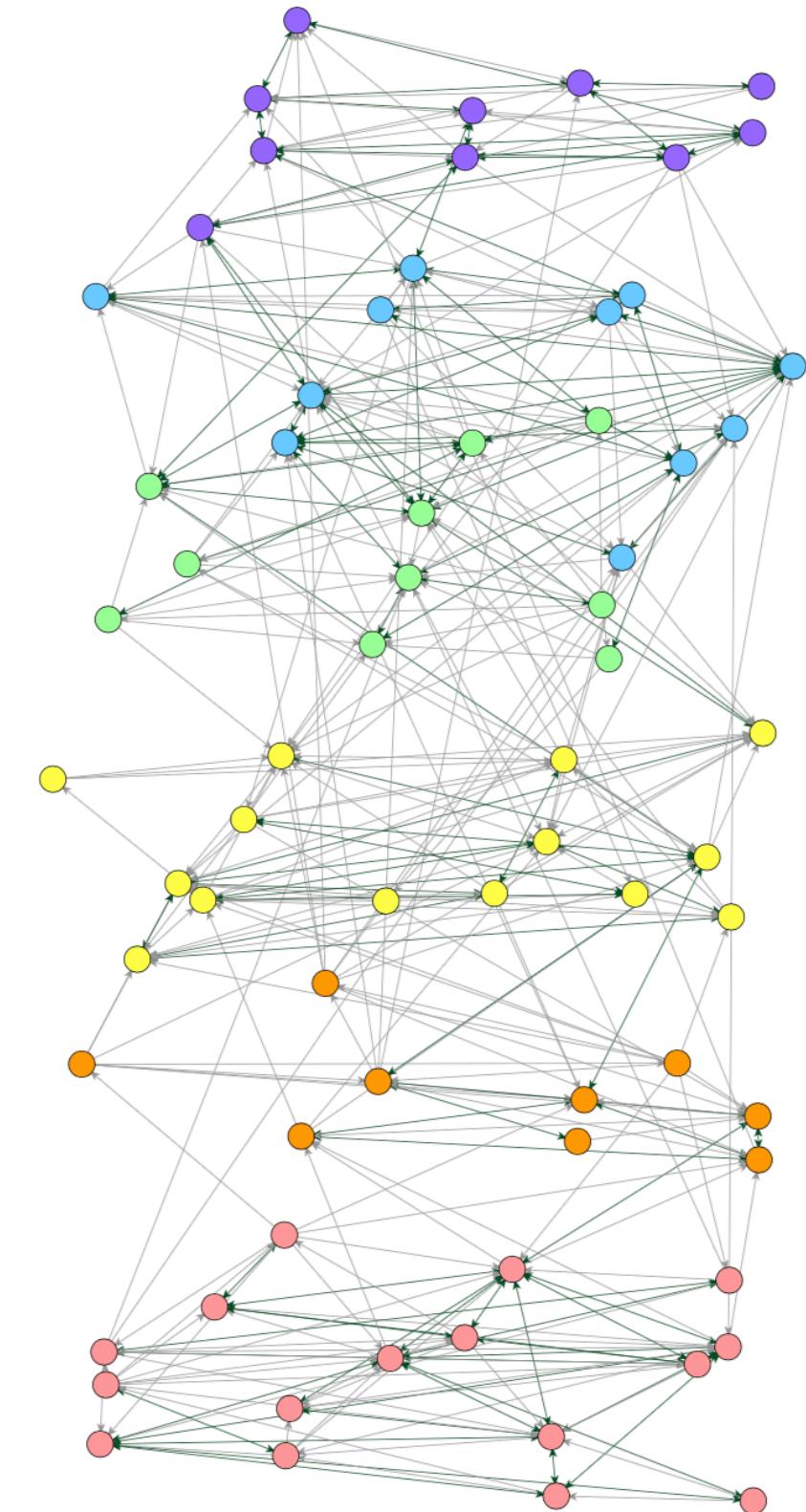
- Great for food webs. Inference models v slow for all but small networks.

**Discrete Choice Models** (BTL, Thurstone V) embed products in a 1D space.

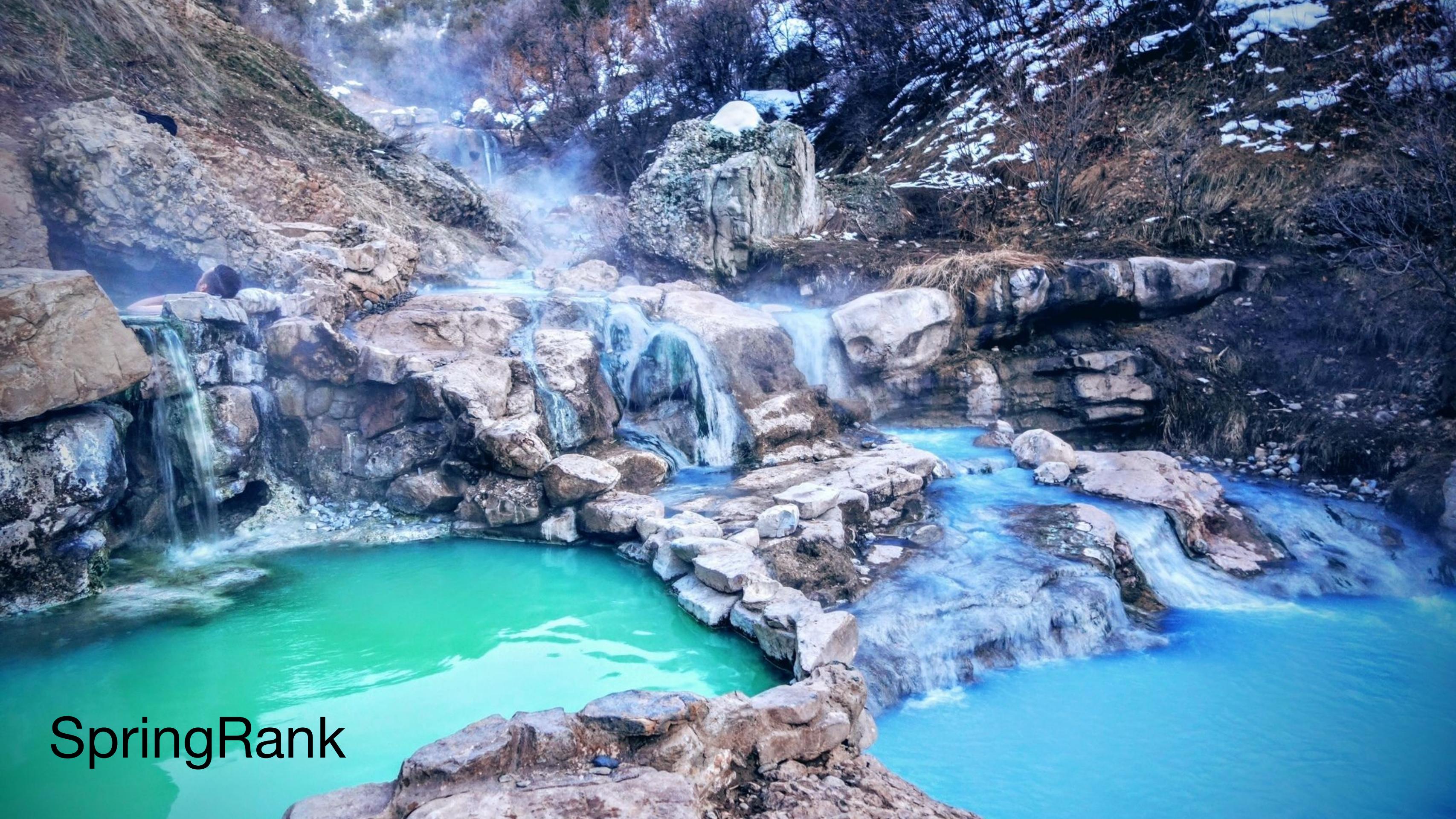
For BTL, outcome direction is simply:

$$P(i \rightarrow j) = \frac{\gamma_i}{\gamma_i + \gamma_j}$$

- Provably avoids non-transitive properties.
- Great when lots of data per interaction.



The rest of this talk:  
**SpringRank**—fast, interpretable, predictive.

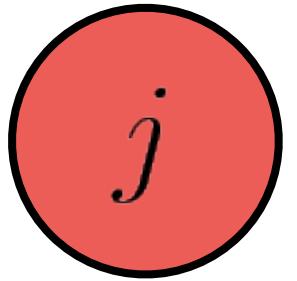
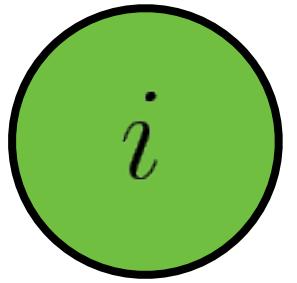


SpringRank

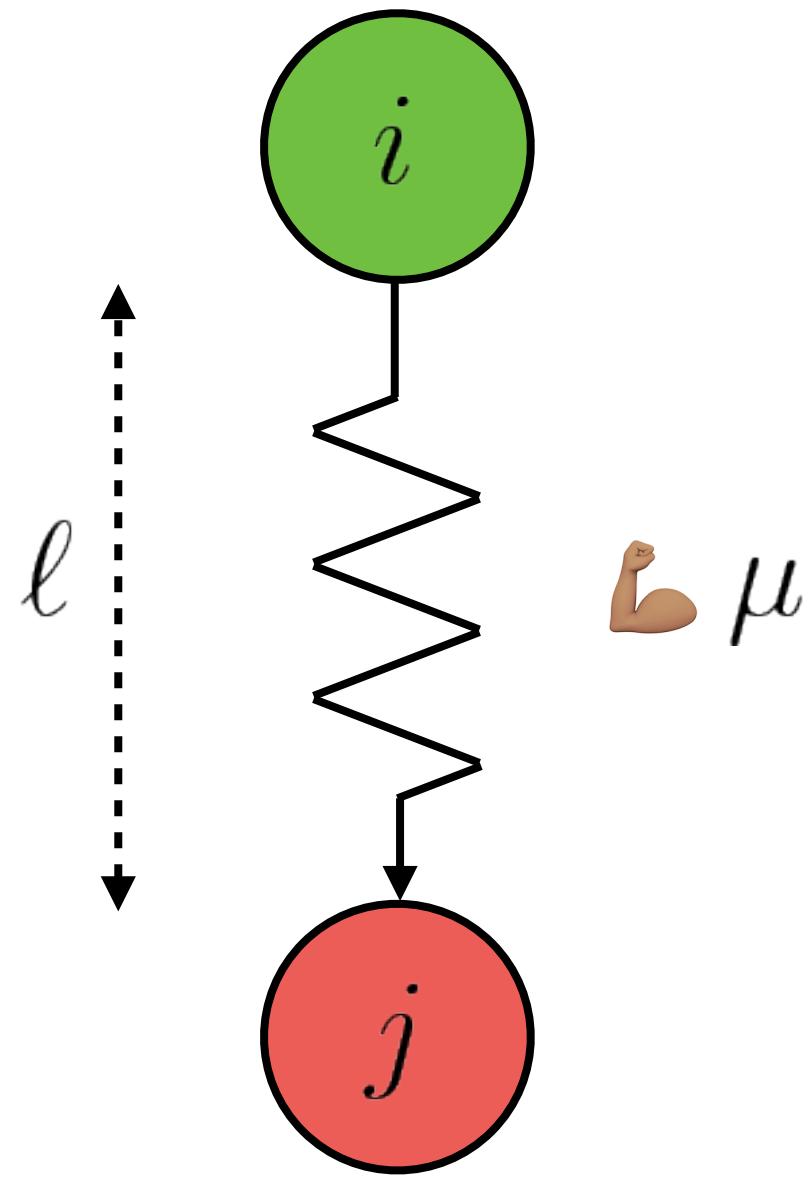


SpringRank

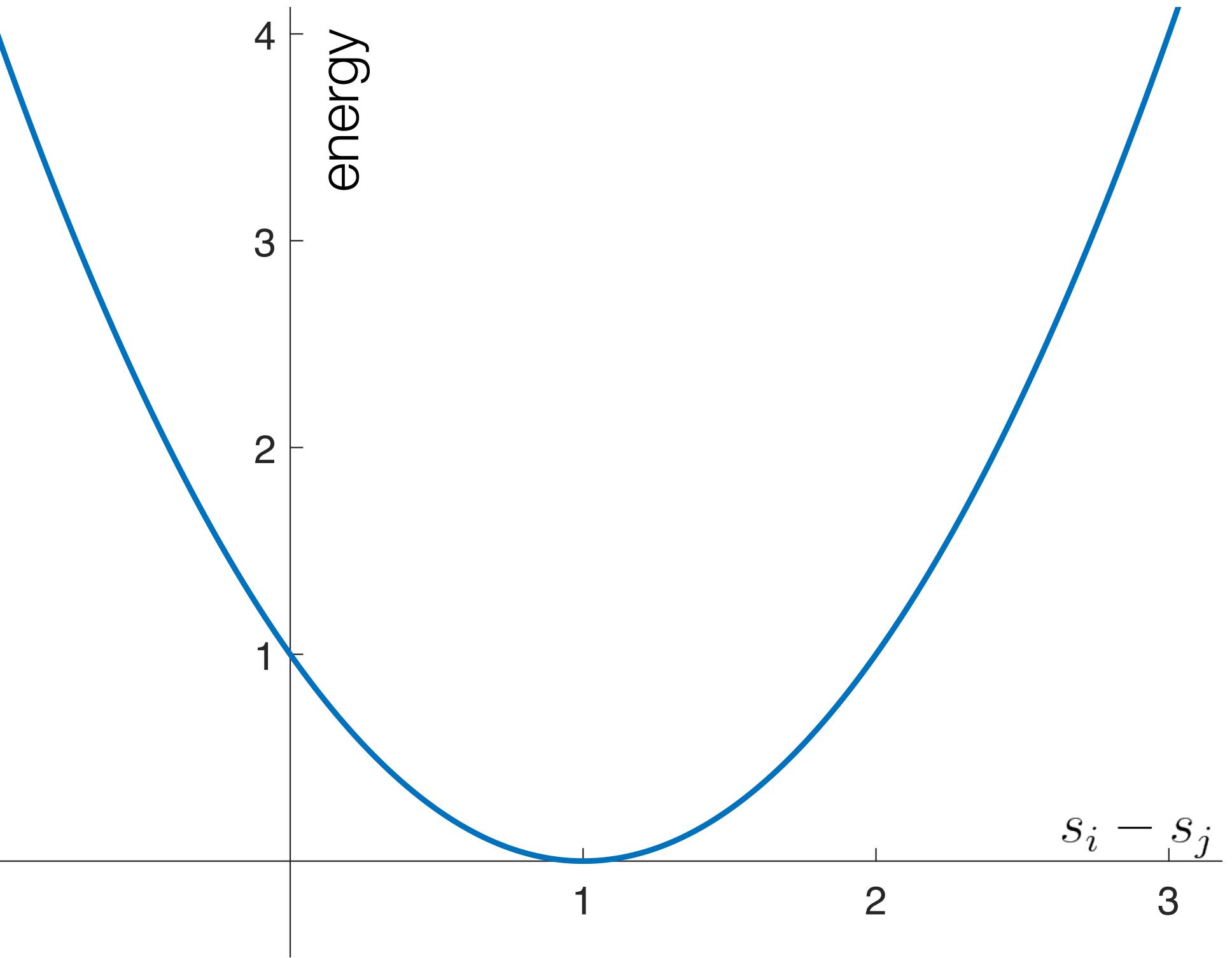
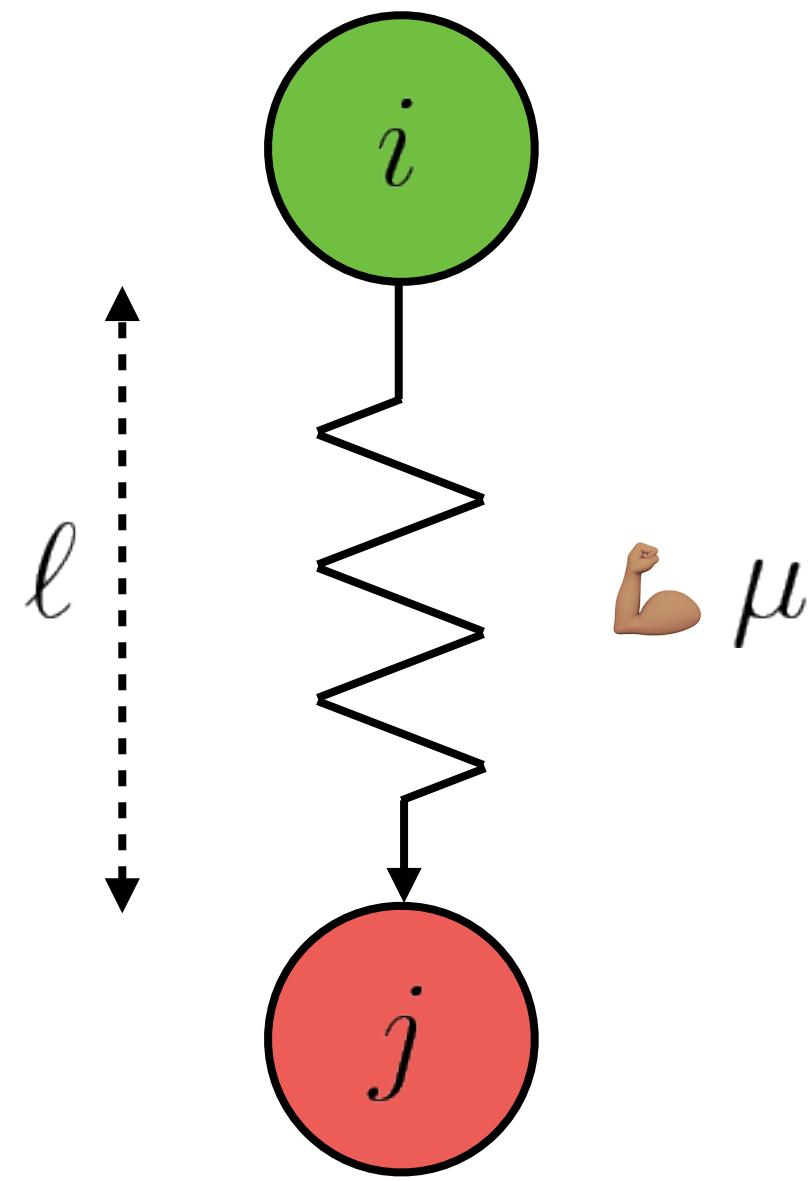
Each directed edge = directed spring



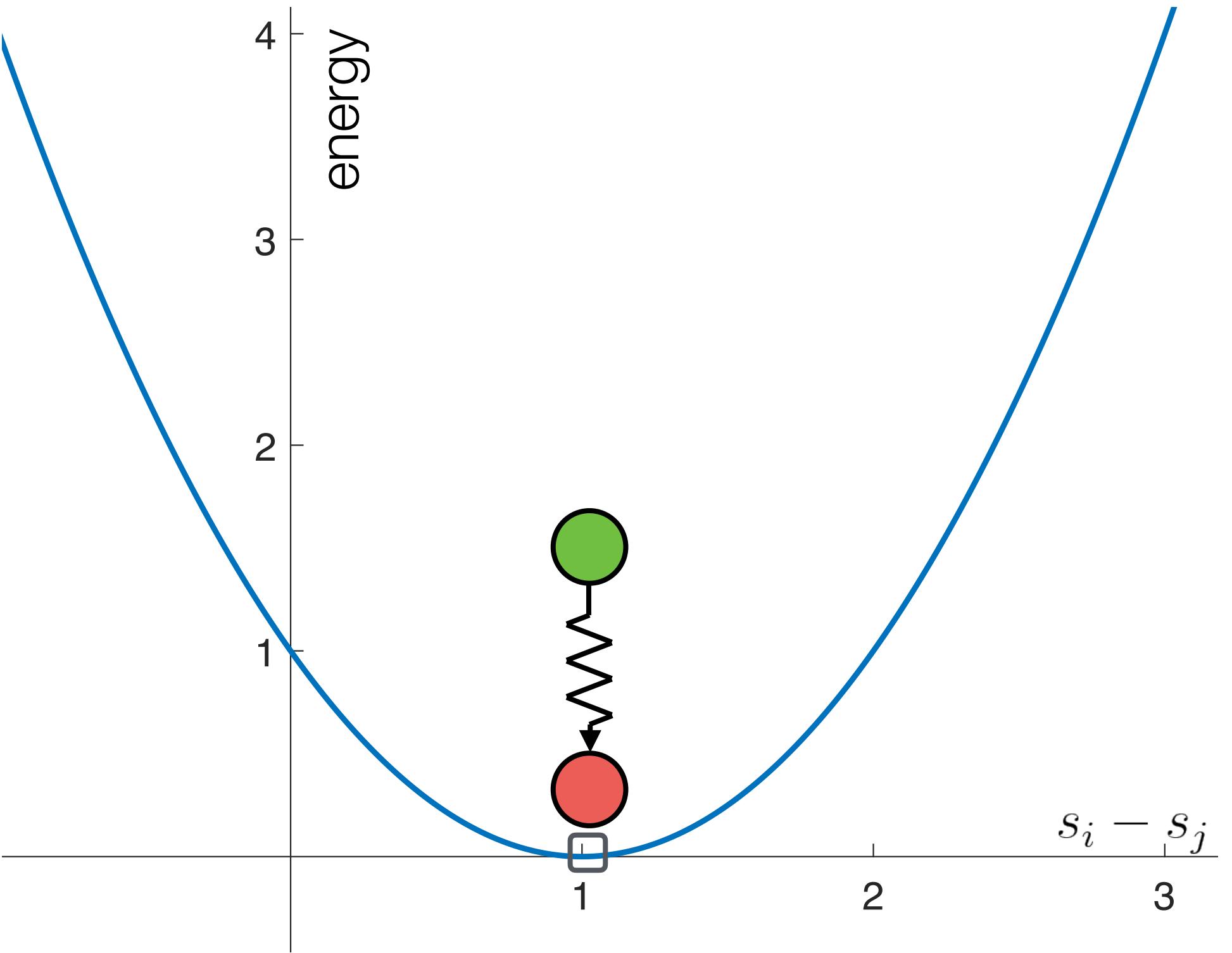
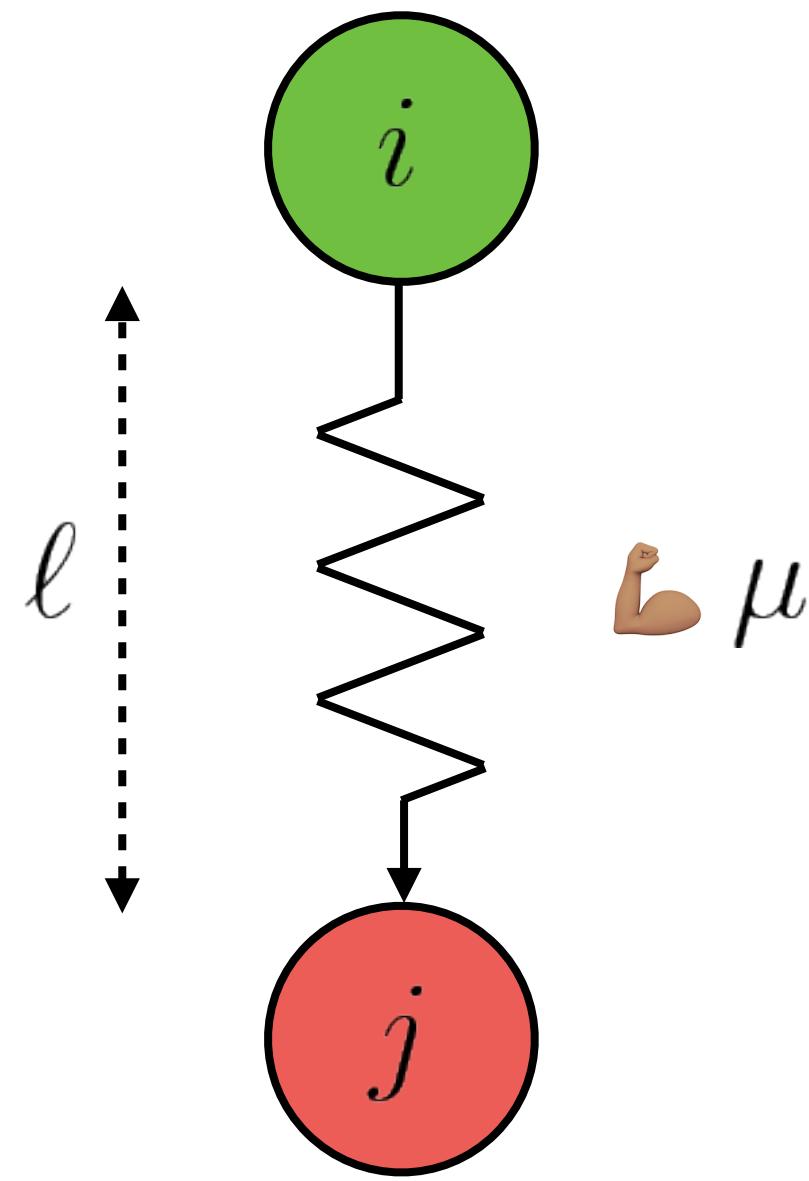
Each directed edge = directed spring



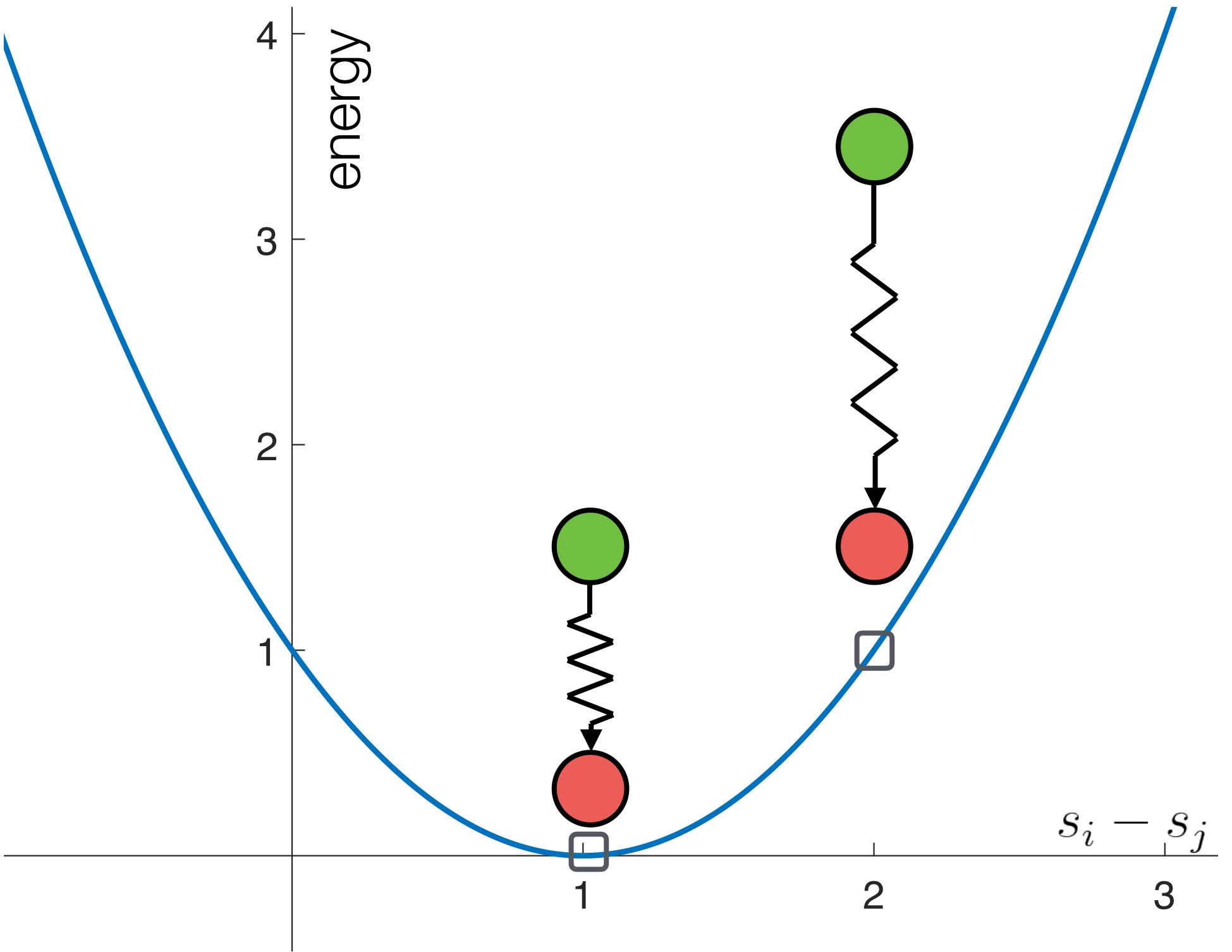
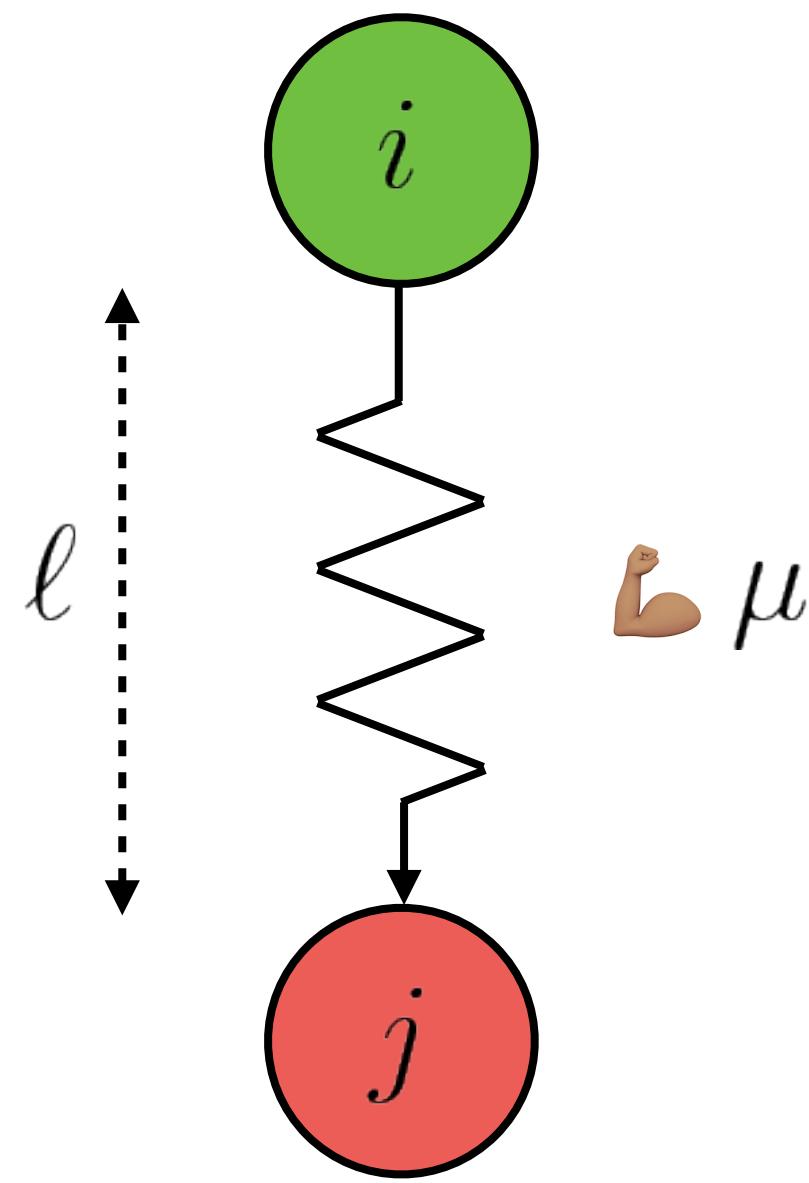
Each directed edge = directed spring



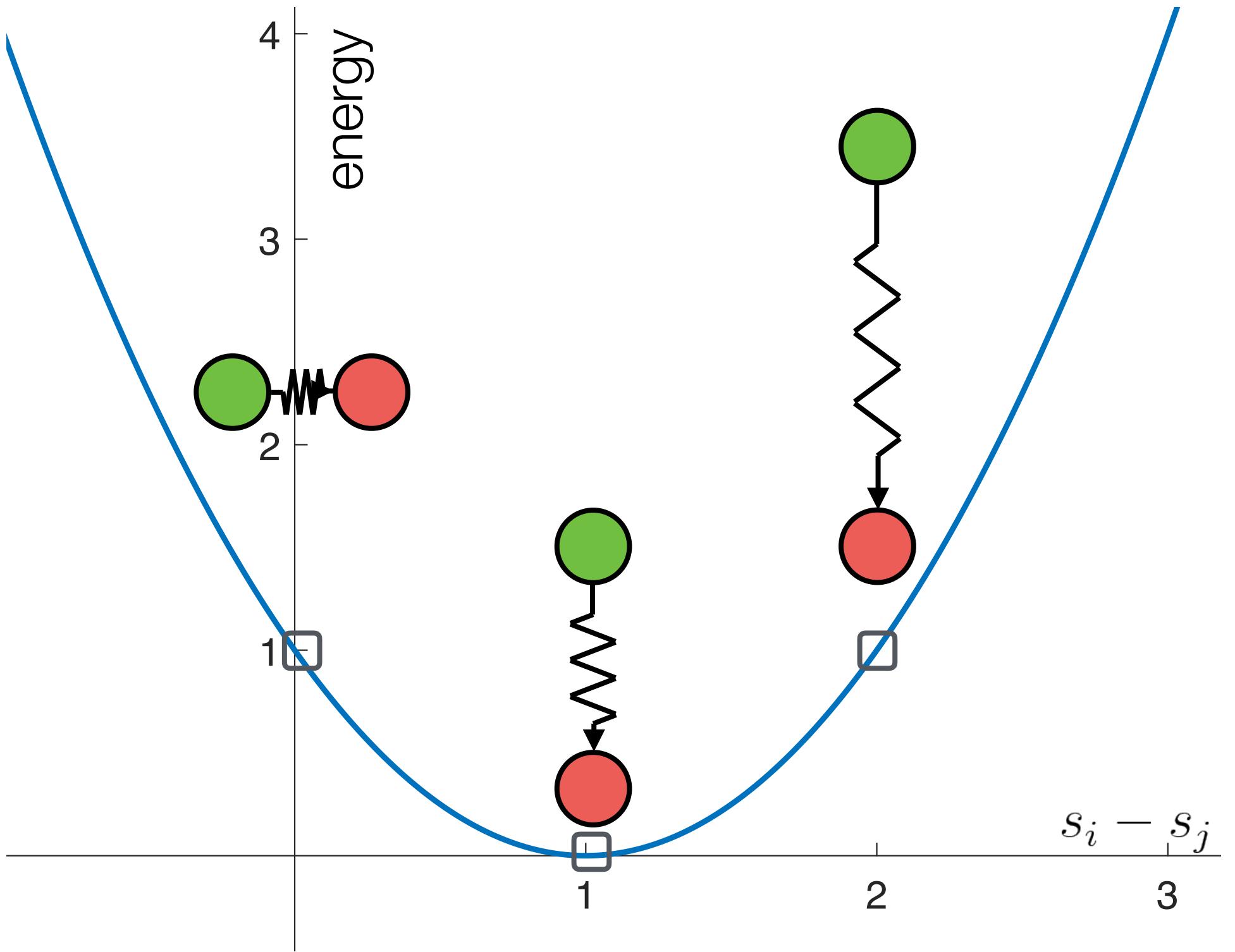
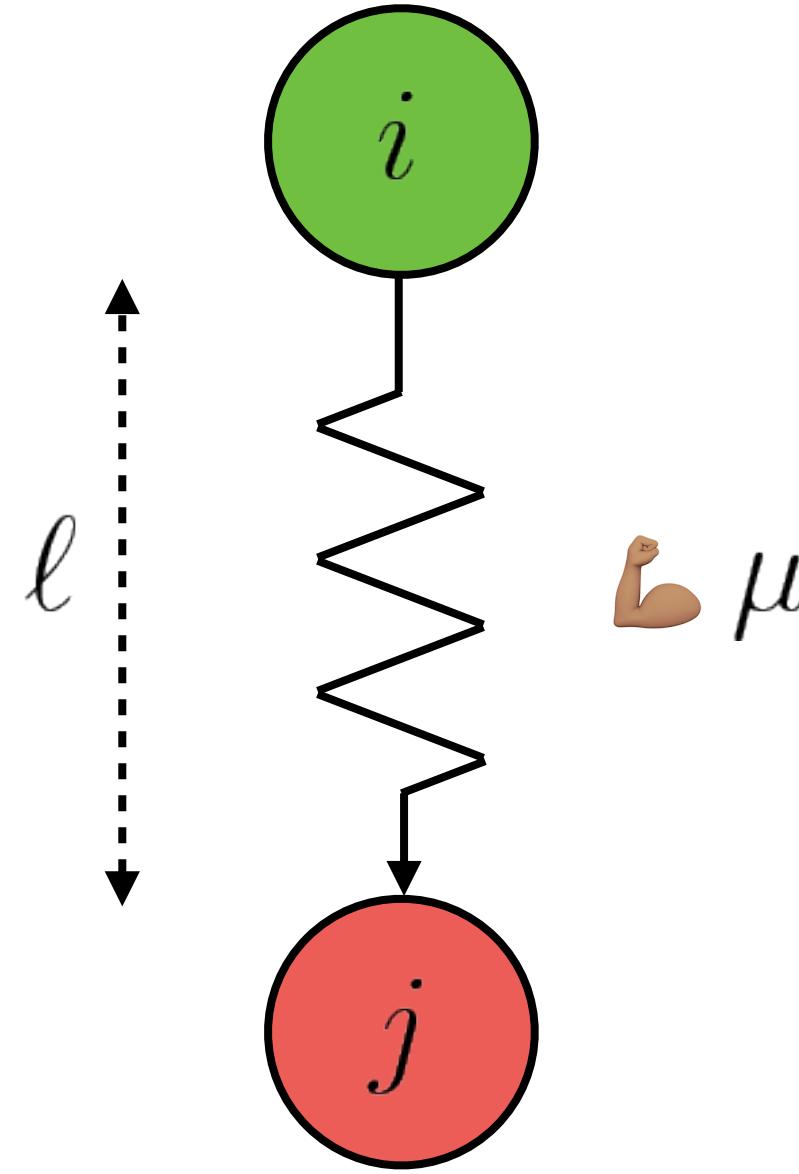
Each directed edge = directed spring



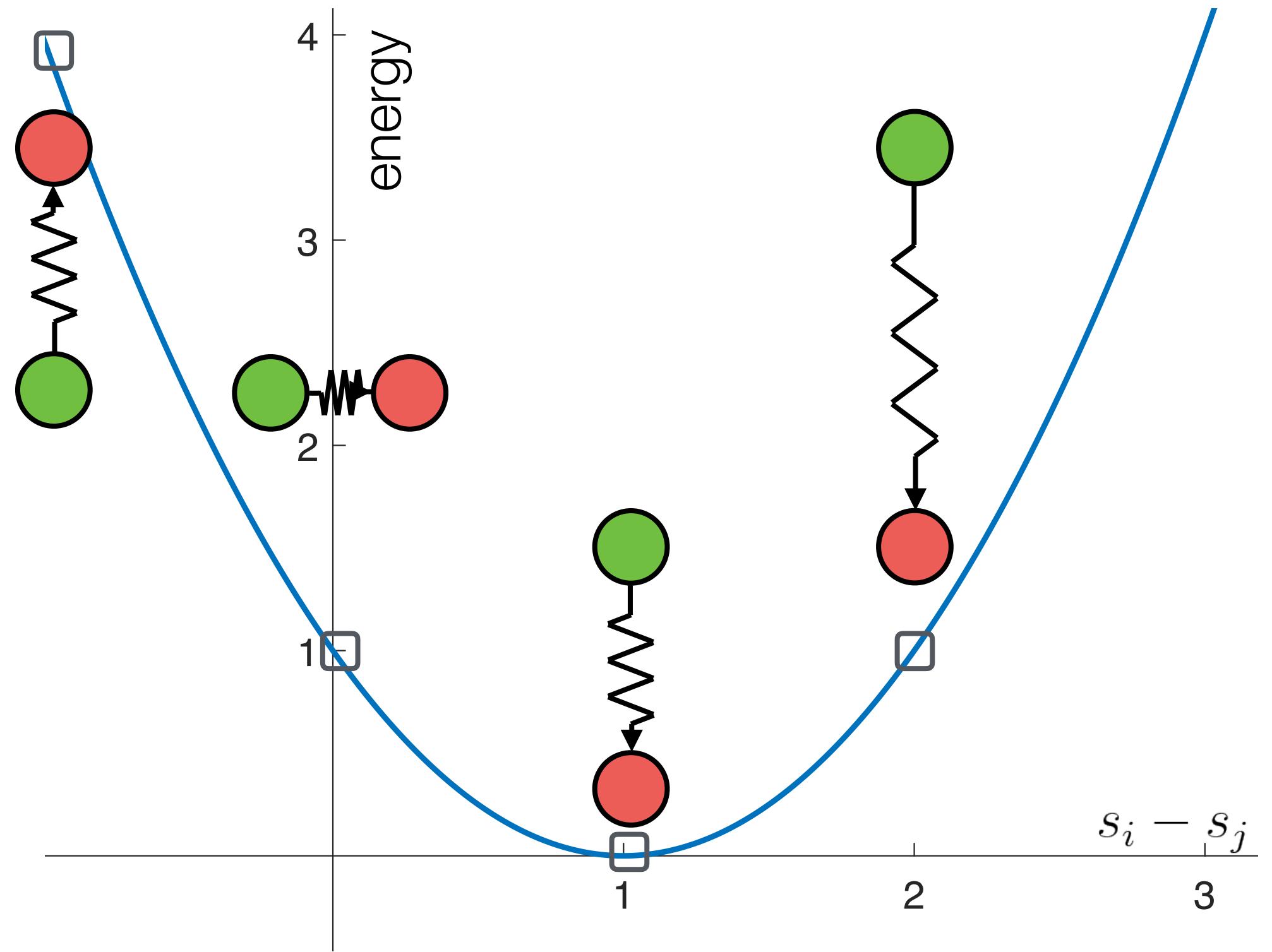
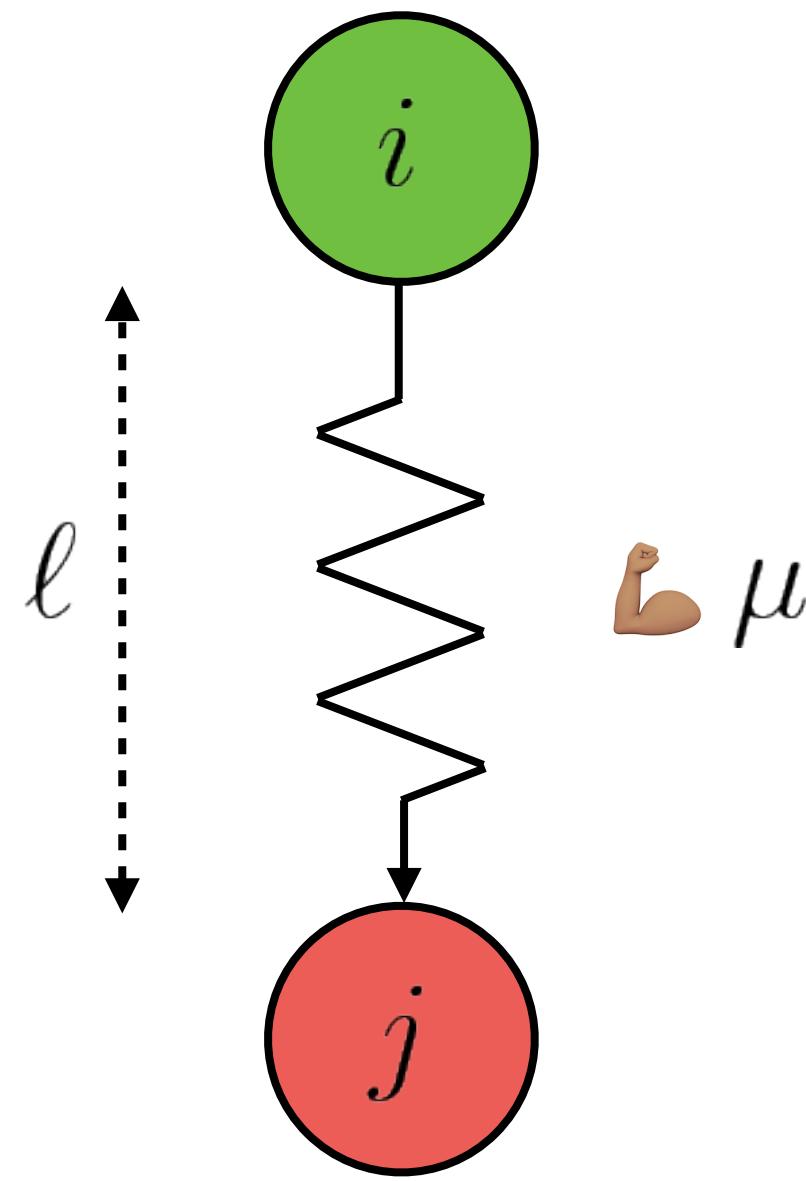
Each directed edge = directed spring



Each directed edge = directed spring



Each directed edge = directed spring



# Relax and let the springs decide the ranks

$$H(s) = \frac{1}{2} \sum_{i,j=1}^N \mu_{ij} A_{ij} (s_i - s_j - \ell)^2$$

SpringRank Hamiltonian: energy of the system, given the positions  $s$ .

Because the springs are linear, the potential is quadratic.

# Relax and let the springs decide the ranks

$$H(s) = \frac{1}{2} \sum_{i,j=1}^N \mu_{ij} A_{ij} (s_i - s_j - \ell)^2$$

SpringRank Hamiltonian: energy of the system, given the positions  $s$ .

Because the springs are linear, the potential is quadratic.

The SR Hamiltonian is *convex* in  $s$ .

$$\nabla H(s) = 0$$

The solution is unique...up to an additive constant. (Why?)

# Derivatives work out nicely

$$0 = \frac{\partial H}{\partial s_i} = \sum_j A_{ij} (s_i - s_j - \ell) - A_{ji} (s_j - s_i - \ell)$$

NB: the matrix on the left is also called the *Network Laplacian matrix*.

# Derivatives work out nicely

$$0 = \frac{\partial H}{\partial s_i} = \sum_j A_{ij} (s_i - s_j - \ell) - A_{ji} (s_j - s_i - \ell)$$

Rewrite as a linear algebra problem.

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

NB: the matrix on the left is also called the *Network Laplacian matrix*.

# Derivatives work out nicely

$$0 = \frac{\partial H}{\partial s_i} = \sum_j A_{ij} (s_i - s_j - \ell) - A_{ji} (s_j - s_i - \ell)$$

Rewrite as a linear algebra problem.

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

We know *a priori* that the matrix on the left is singular: translational invariance of  $H(s)$ .

NB: the matrix on the left is also called the *Network Laplacian matrix*.

# Derivatives work out nicely

$$0 = \frac{\partial H}{\partial s_i} = \sum_j A_{ij} (s_i - s_j - \ell) - A_{ji} (s_j - s_i - \ell)$$

Rewrite as a linear algebra problem.

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

We know *a priori* that the matrix on the left is singular: translational invariance of  $H(s)$ .

[if  $s$  is a solution, then  $s + k$  is a solution for any constant  $k$ ; eigenvalue 0, eigenvector  $\mathbf{1}$ ]

NB: the matrix on the left is also called the *Network Laplacian matrix*.

# Dealing with translational invariance

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

1. Invert this matrix on the  $n-1$  dimensional subspace orthogonal to  $\mathbf{1}$ . (pseudoinverse)

# Dealing with translational invariance

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

1. Invert this matrix on the  $n-1$  dimensional subspace orthogonal to  $\mathbf{1}$ . (pseudoinverse)
2. Fix a rank. Say  $s_1=0$ . Or  $\min(s)=0$ . Or  $\text{mean}(s)=0$ .

# Dealing with translational invariance

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

1. Invert this matrix on the  $n-1$  dimensional subspace orthogonal to  $\mathbf{1}$ . (pseudoinverse)
2. Fix a rank. Say  $s_1=0$ . Or  $\min(s)=0$ . Or  $\text{mean}(s)=0$ .
3. Impose some regularization to prevent wandering.  
You could call it an external field.  
Or an undirected spring attached to the origin.

$$H_{\text{reg}}(s) = H(s) + \frac{\alpha}{2} \sum_{i=1}^N s_i^2$$

# Dealing with translational invariance

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

1. Invert this matrix on the  $n-1$  dimensional subspace orthogonal to  $\mathbf{1}$ . (pseudoinverse)
2. Fix a rank. Say  $s_1=0$ . Or  $\min(s)=0$ . Or  $\text{mean}(s)=0$ .
3. Impose some regularization to prevent wandering.  
You could call it an external field.  
Or an undirected spring attached to the origin.

$$H_{\text{reg}}(s) = H(s) + \frac{\alpha}{2} \sum_{i=1}^N s_i^2$$

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T) + \alpha I] s^* = [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

now the eigenvector  $\mathbf{1}$  has eigenvalue  $\alpha$

# Dealing with translational invariance

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

1. Invert this matrix on the  $n-1$  dimensional subspace orthogonal to  $\mathbf{1}$ . (pseudoinverse)
2. Fix a rank. Say  $s_1=0$ . Or  $\min(s)=0$ . Or  $\text{mean}(s)=0$ .
3. Impose some regularization to prevent wandering.  
You could call it an external field.  
Or an undirected spring attached to the origin.

$$H_{\text{reg}}(s) = H(s) + \frac{\alpha}{2} \sum_{i=1}^N s_i^2$$

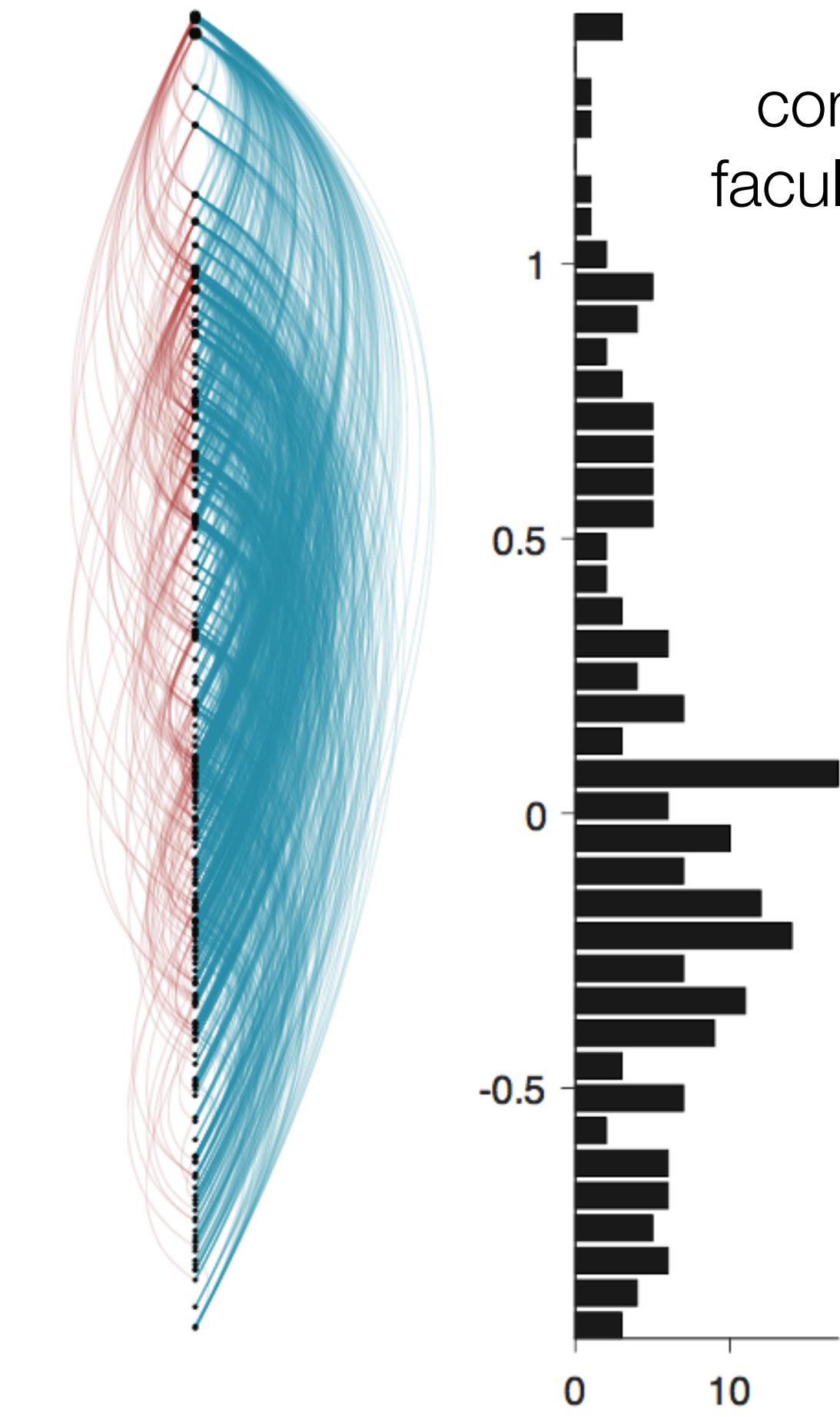
$$[D^{\text{out}} + D^{\text{in}} - (A + A^T) + \alpha I] s^* = [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

now the eigenvector  $\mathbf{1}$  has eigenvalue  $\alpha$

$$\alpha \rightarrow 0$$

$$[D^{\text{out}} + D^{\text{in}} - (A + A^T)] s^* = \ell [D^{\text{out}} - D^{\text{in}}] \mathbf{1}$$

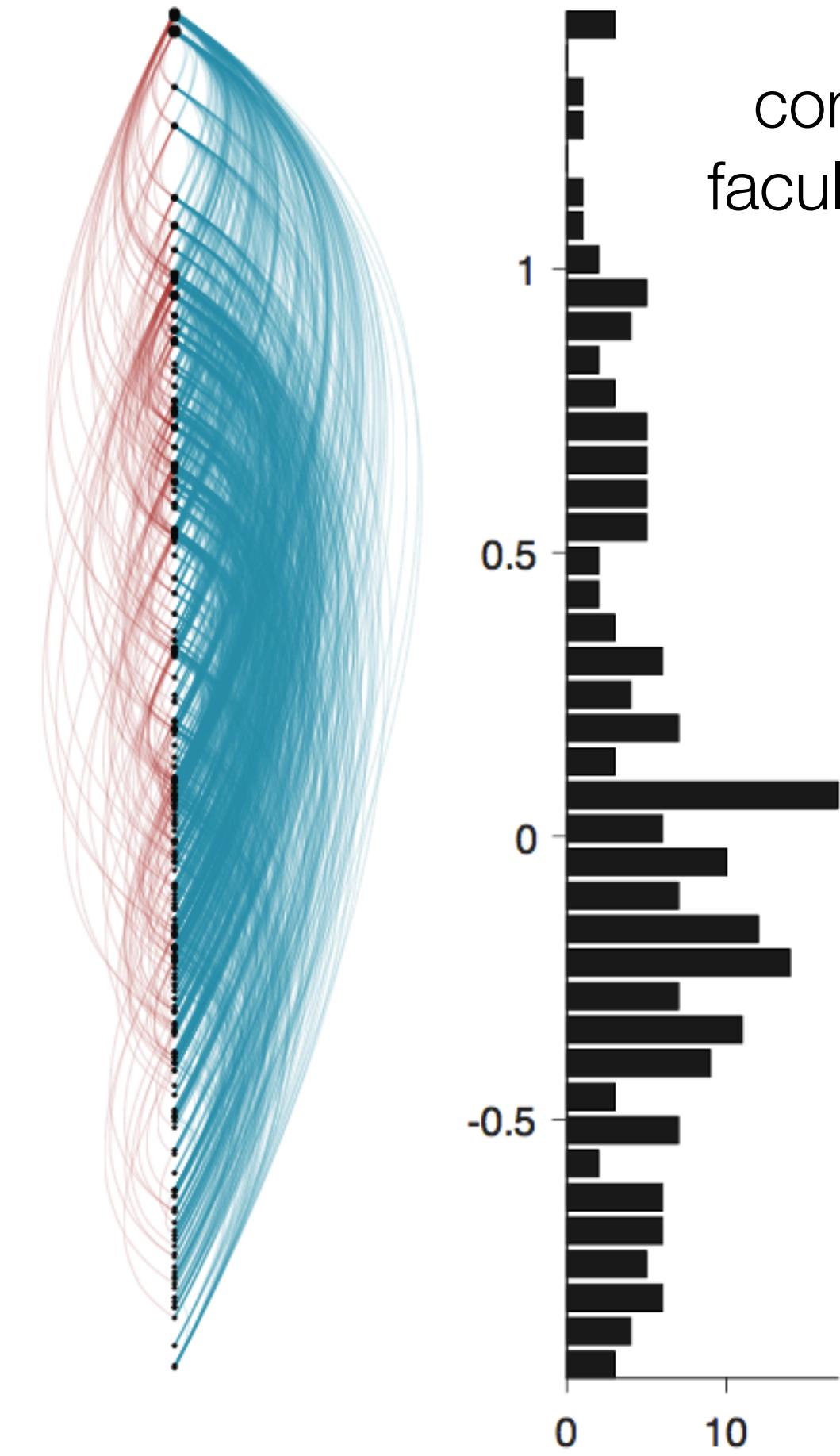
# It works!



computer science  
faculty hiring network

# It works!

Real networks tend to be sparse...  
our linear algebra problem is sparse...  
we can use sparse iterative solvers...  
**millions of edges in seconds.**

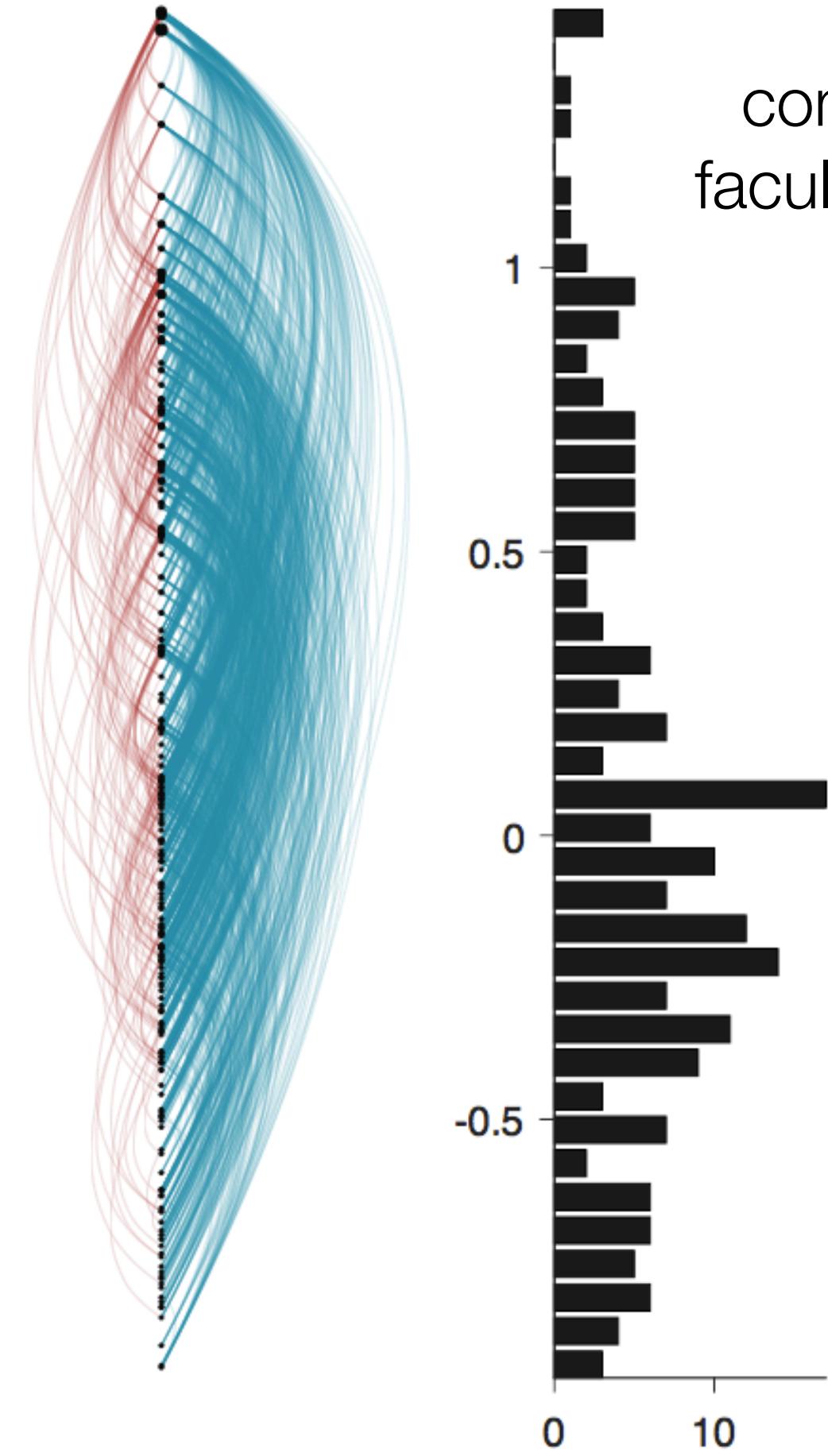


computer science  
faculty hiring network

# It works!

Real networks tend to be sparse...  
our linear algebra problem is sparse...  
we can use sparse iterative solvers...  
**millions of edges in seconds.**

[Even better: Spielman & Teng showed  
that the solution to these Laplacian systems  
can be found in  $O(\text{edges})$  time.]



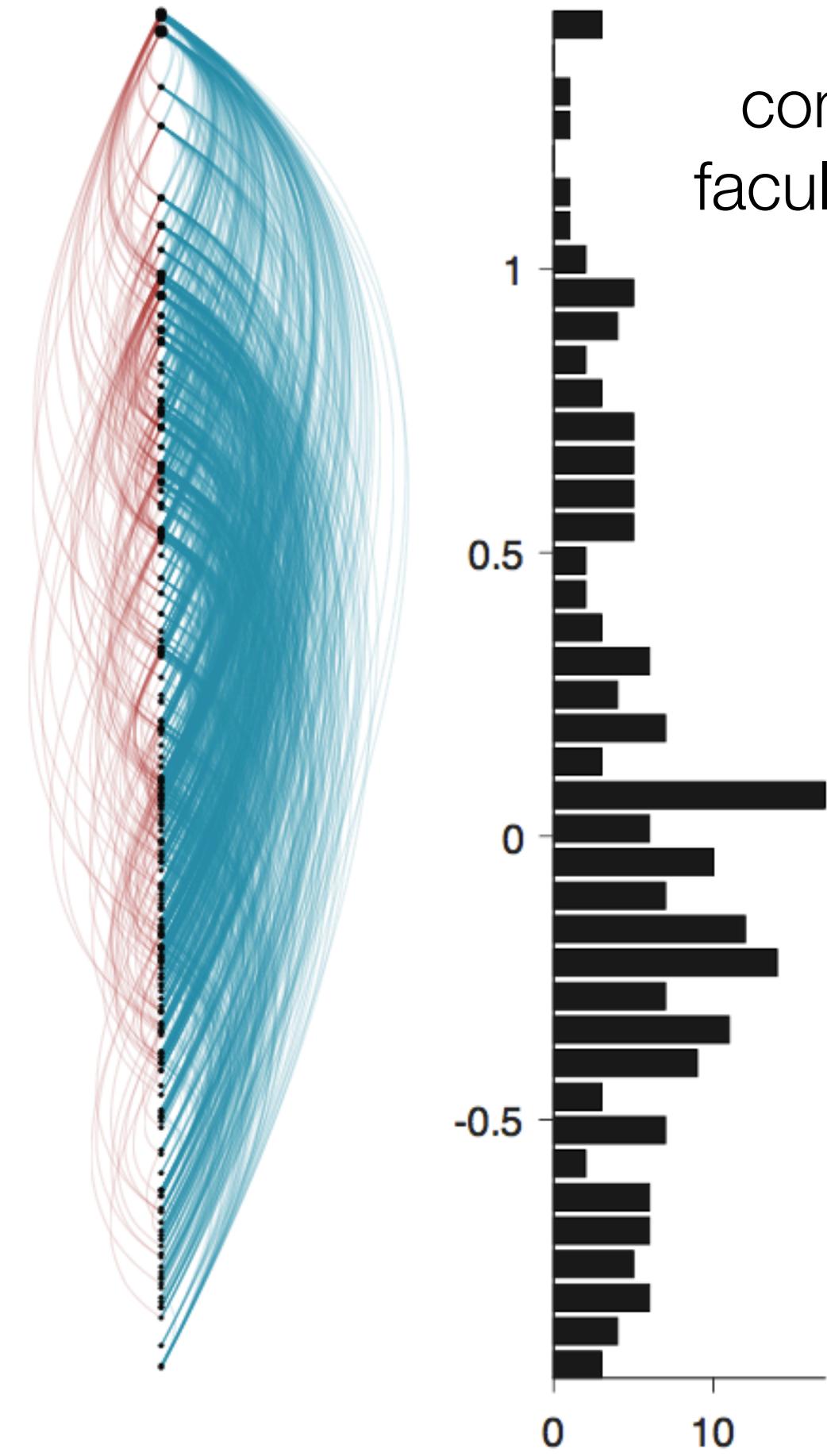
computer science  
faculty hiring network

# It works!

Real networks tend to be sparse...  
our linear algebra problem is sparse...  
we can use sparse iterative solvers...  
**millions of edges in seconds.**

[Even better: Spielman & Teng showed  
that the solution to these Laplacian systems  
can be found in  $O(\text{edges})$  time.]

Note that node positions can be clumpy.



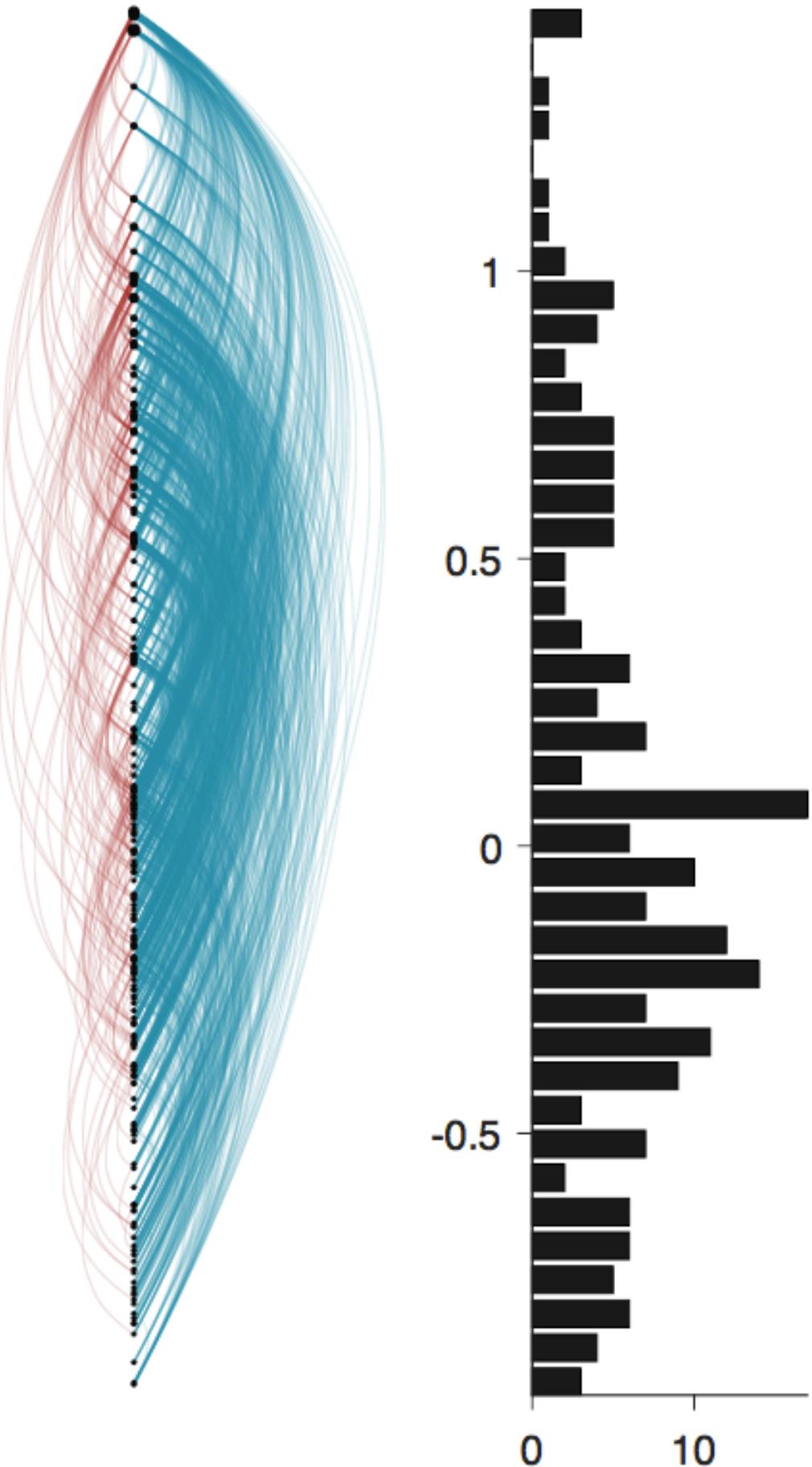
computer science  
faculty hiring network

# How certain are we?

$$P(s) \propto e^{-\beta H(s)}$$

Boltzmann distribution: probability around ranks s

$$P(s) \propto \exp -\frac{\beta}{2} \sum_{i,j=1}^N A_{ij} (s_i - s_j - \ell)^2$$



# How certain are we?

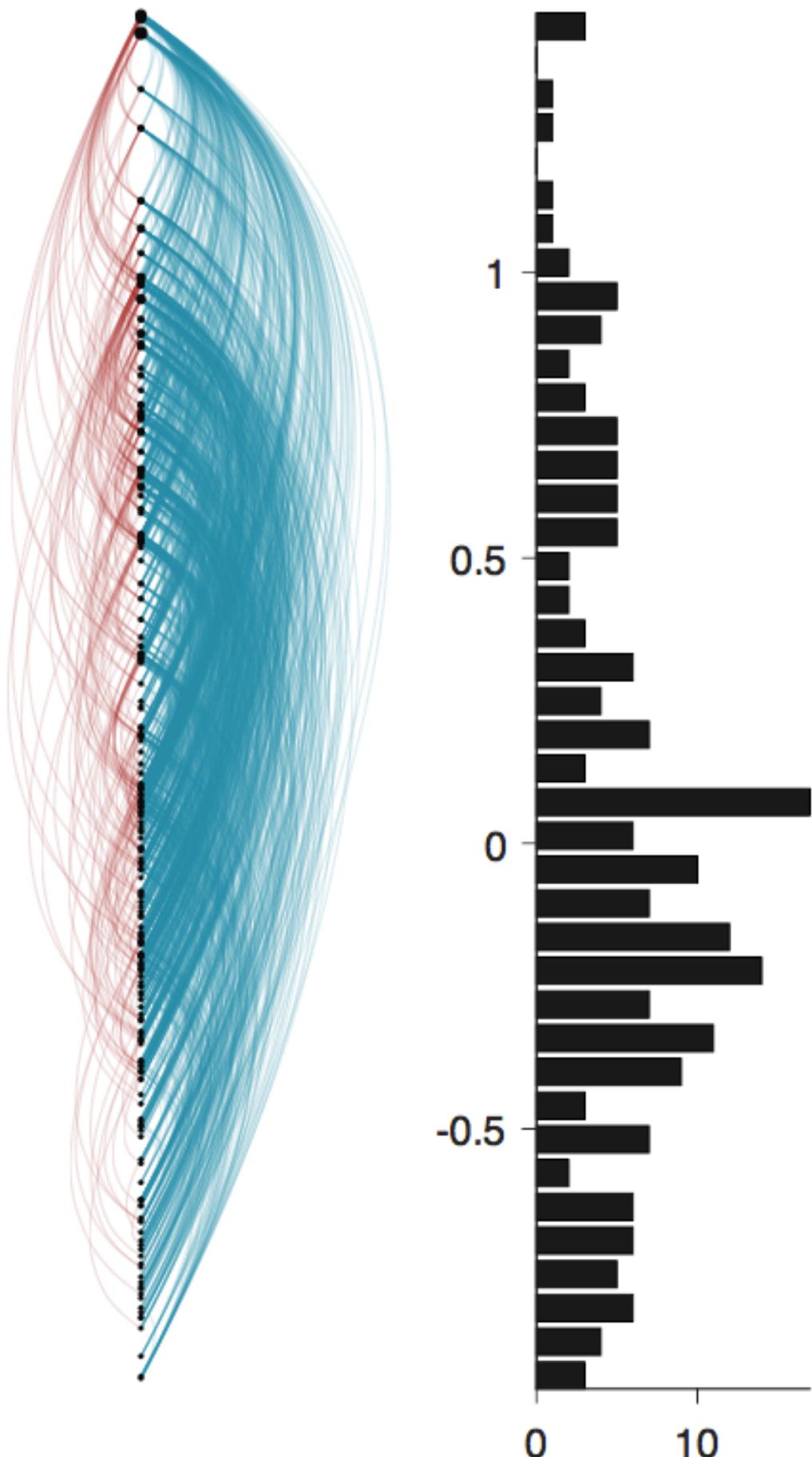
$$P(s) \propto e^{-\beta H(s)}$$

Boltzmann distribution: probability around ranks s

$$P(s) \propto \exp -\frac{\beta}{2} \sum_{i,j=1}^N A_{ij} (s_i - s_j - \ell)^2$$

consider:

$$\begin{aligned}\beta &\rightarrow 0 \\ \beta &\rightarrow \infty\end{aligned}$$



# How certain are we?

$$P(s) \propto e^{-\beta H(s)}$$

Boltzmann distribution: probability around ranks  $s$

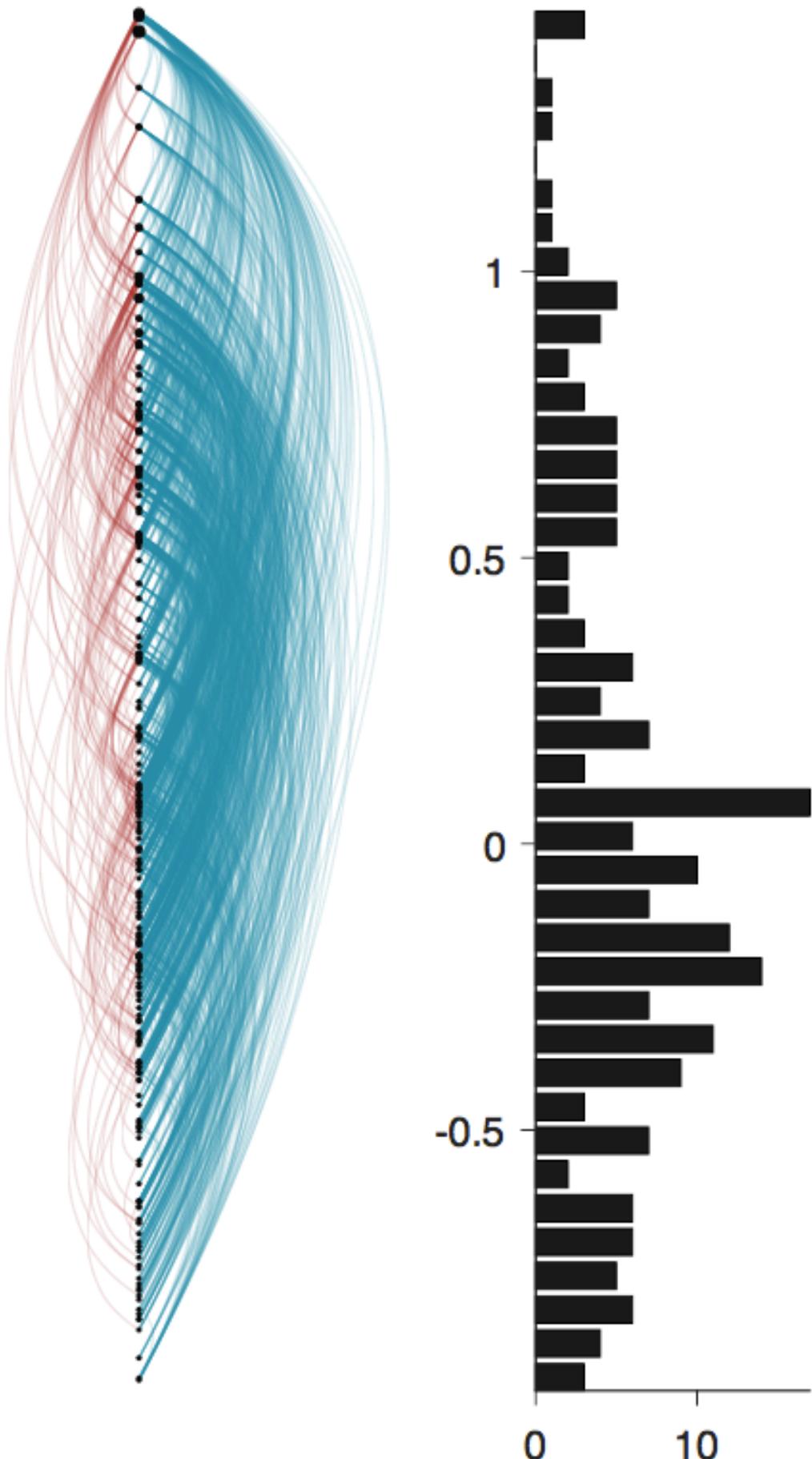
$$P(s) \propto \exp -\frac{\beta}{2} \sum_{i,j=1}^N A_{ij} (s_i - s_j - \ell)^2$$

$$P(s) \propto \exp \left( -\frac{1}{2} (s - \underline{s})^\top \Sigma^{-1} (s - \underline{s}) \right)$$

consider:

$$\beta \rightarrow 0$$

$$\beta \rightarrow \infty$$



# How certain are we?

$$P(s) \propto e^{-\beta H(s)}$$

Boltzmann distribution: probability around ranks s

$$P(s) \propto \exp -\frac{\beta}{2} \sum_{i,j=1}^N A_{ij} (s_i - s_j - \ell)^2$$

consider:

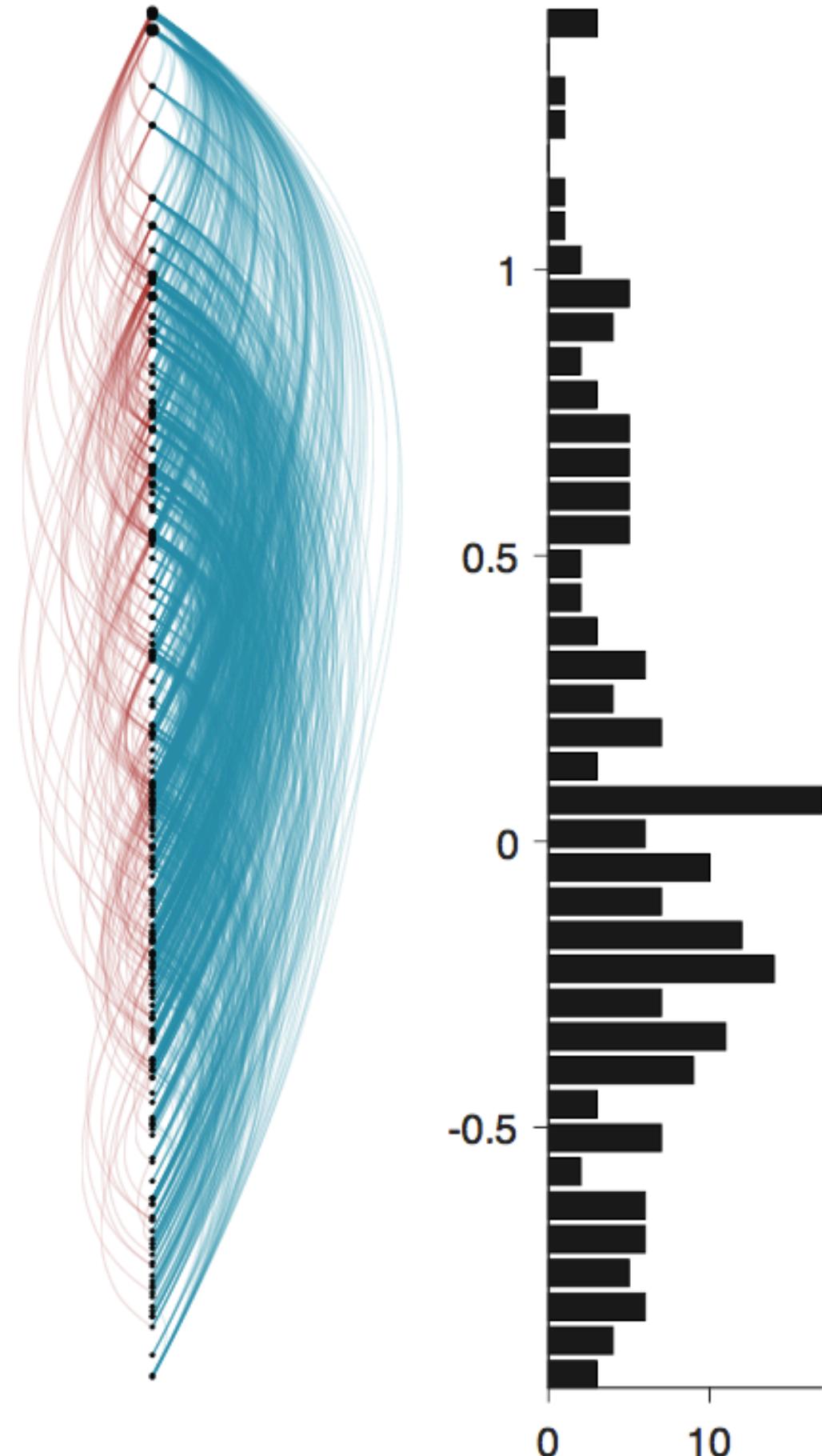
$$\beta \rightarrow 0$$

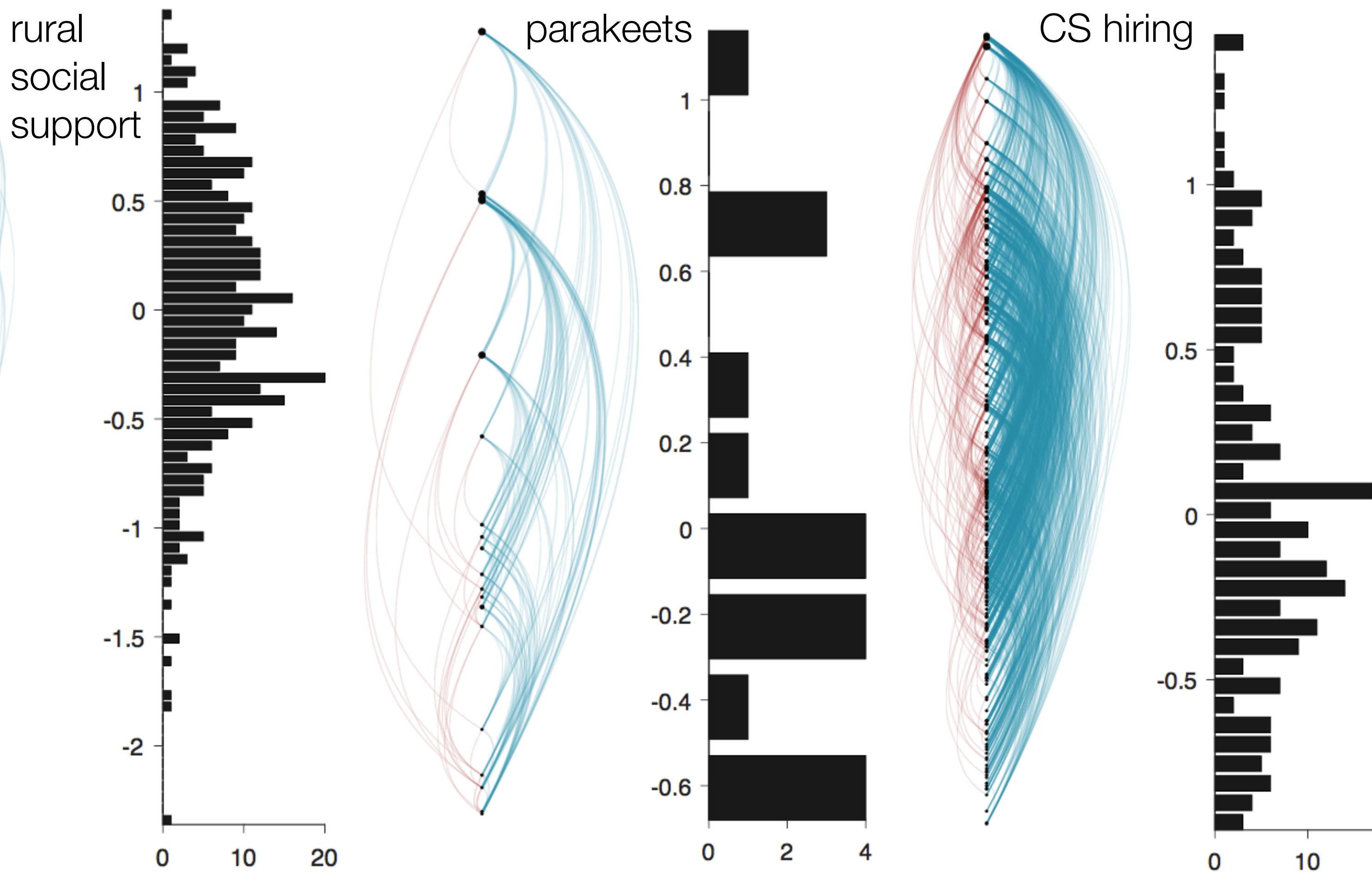
$$\beta \rightarrow \infty$$

$$P(s) \propto \exp \left( -\frac{1}{2} (s - \underline{s})^\top \Sigma^{-1} (s - \underline{s}) \right)$$

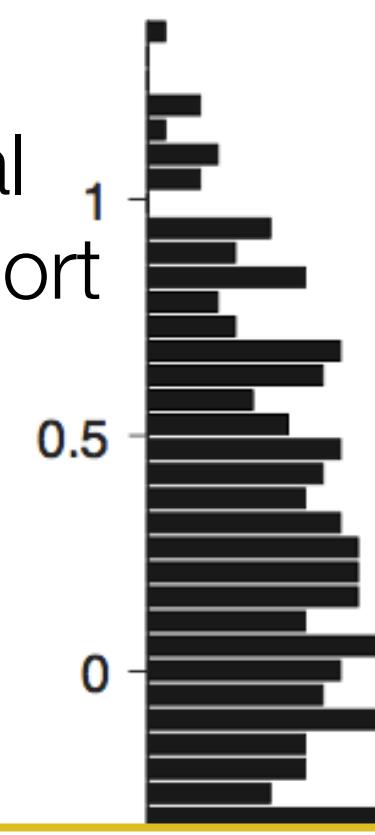
Comparison shows that mean rank is the SR solution,  
and ranks are distributed according to n-variate Gaussian!

$$\Sigma = \frac{1}{\beta} [D^{\text{out}} + D^{\text{in}} - (A + A^T + \alpha I)]^{-1} \quad \text{covariance matrix}$$

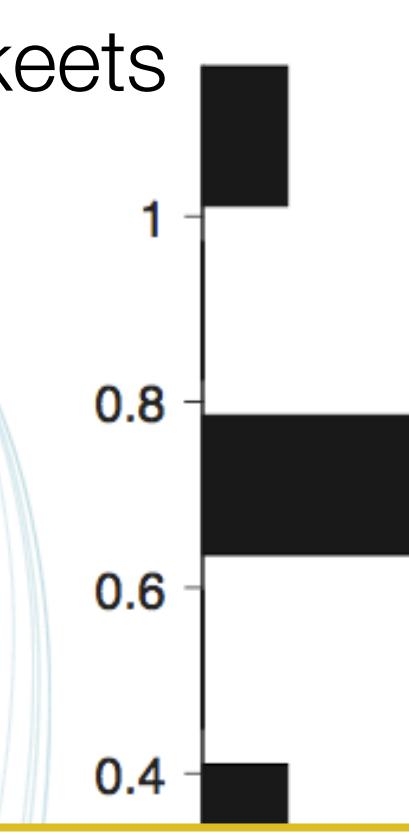




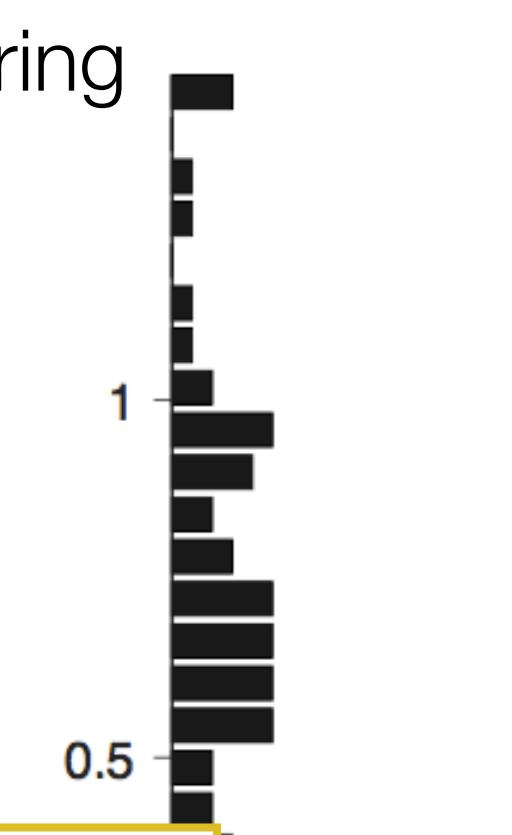
rural  
social  
support



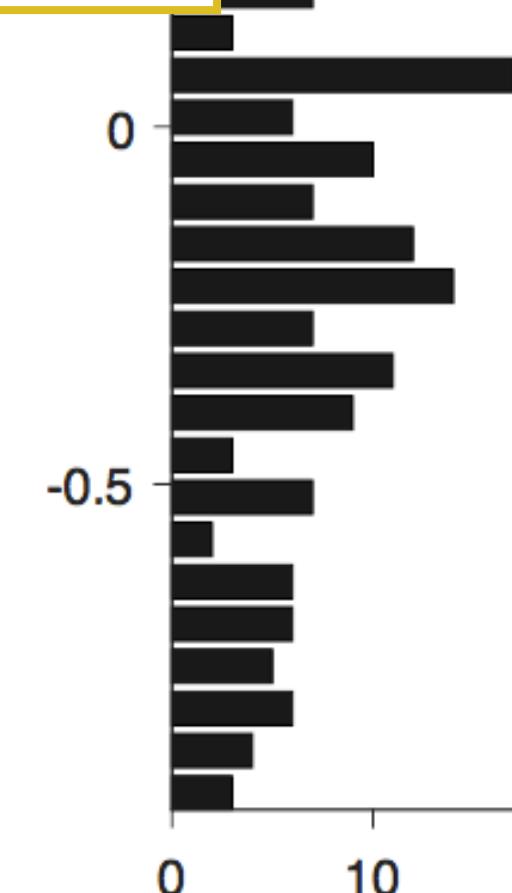
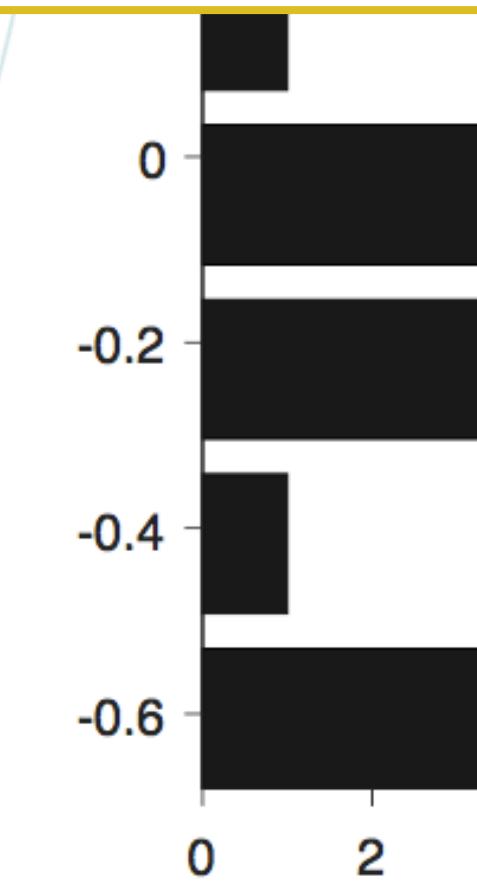
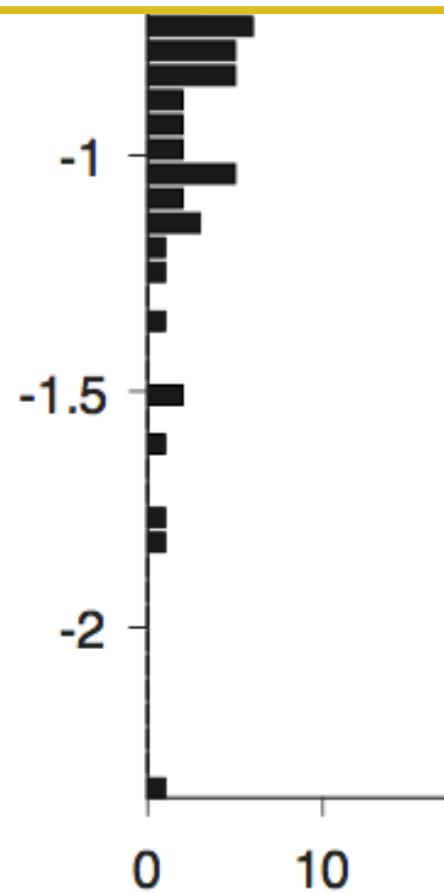
parakeets



CS hiring



risk: stopping at “ours is faster” + pretty pictures



# Generative models



# Generative models

Recall assumptions:

1. Competitors have some intrinsic quality (or vector of qualities).
2. Interactions can (stochastically) reveal differences in qualities.

# Generative models

Recall assumptions:

1. Competitors have some intrinsic quality (or vector of qualities).
2. Interactions can (stochastically) reveal differences in qualities.

This actually suggests a generative model:

*On the first day, the Research Team initialized an  $n$ -vector of qualities,  $s$ .*

# Generative models

Recall assumptions:

1. Competitors have some intrinsic quality (or vector of qualities).
2. Interactions can (stochastically) reveal differences in qualities.

This actually suggests a generative model:

*On the first day, the Research Team initialized an  $n$ -vector of qualities,  $s$ .*

*On the second day, a number of interactions occurred, whose outcomes were chosen by the Research Team in order to reflect the qualities,  $s$ .*

# Generative models

Recall assumptions:

1. Competitors have some intrinsic quality (or vector of qualities).
2. Interactions can (stochastically) reveal differences in qualities.

This actually suggests a generative model:

*On the first day, the Research Team initialized an  $n$ -vector of qualities,  $s$ .*

*On the second day, a number of interactions occurred, whose outcomes were chosen by the Research Team in order to reflect the qualities,  $s$ .*

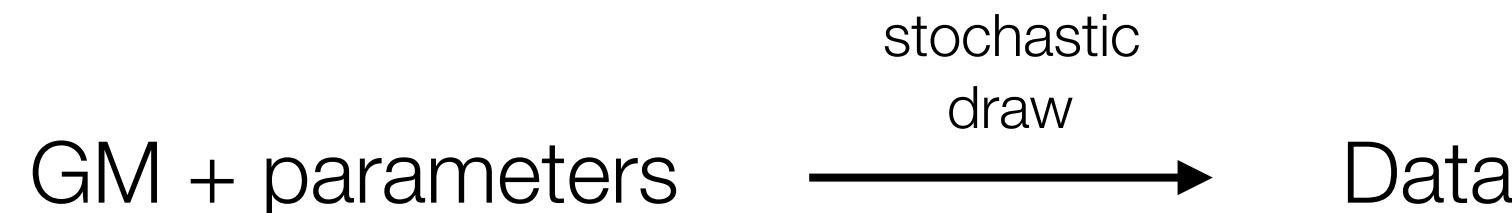
*On the third day, these interactions were written down as an adjacency matrix, and the Reviewers saw that it was good. 😊*

# Generative models

We like generative models because they open the door to inference:

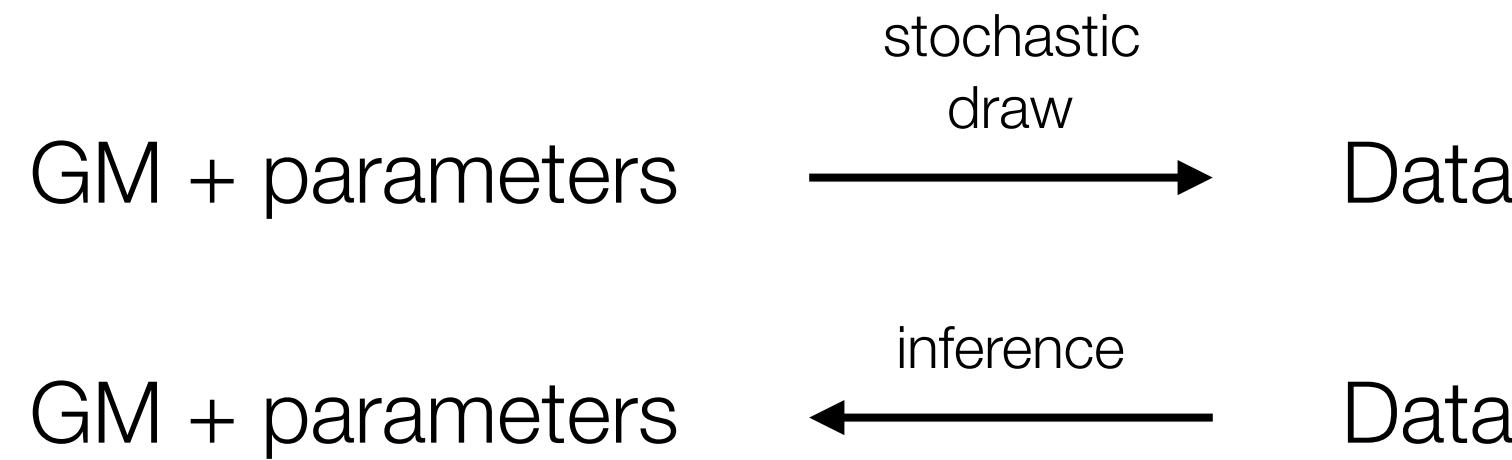
# Generative models

We like generative models because they open the door to inference:



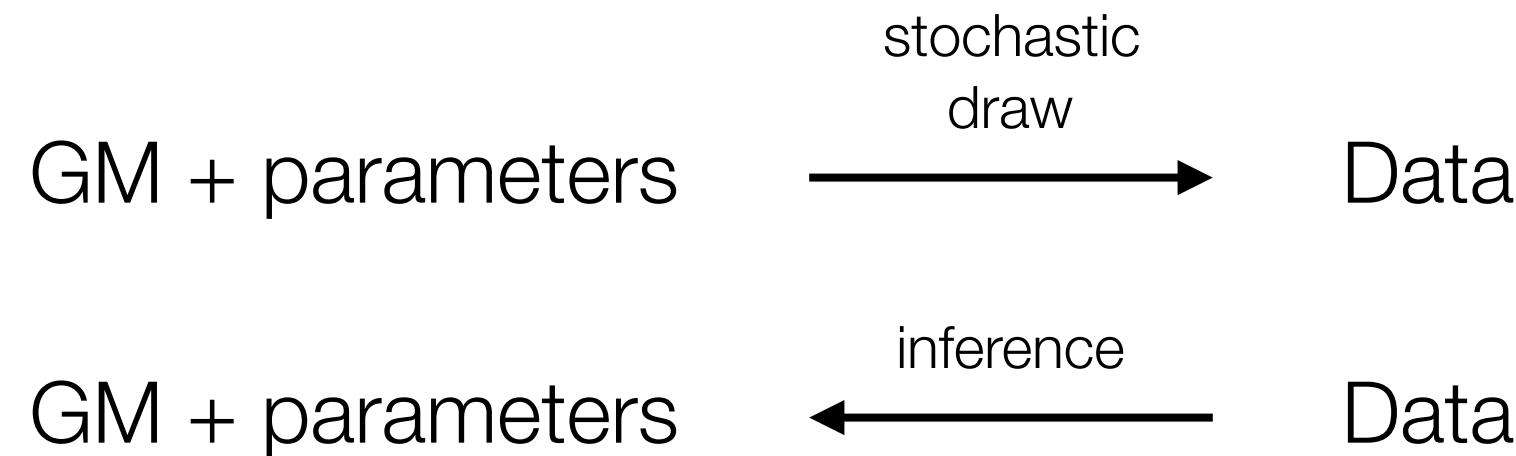
# Generative models

We like generative models because they open the door to inference:



# Generative models

We like generative models because they open the door to inference:



Let the expected number of edges from  $i$  to  $j$  be:

$$\text{E}[A_{ij}] = c \exp \left[ -\frac{1}{2} \beta (s_i - s_j - 1)^2 \right]$$

And let the actual number of edges be drawn from a Poisson distribution with that mean.

# Parameters...

$$\text{E}[M] = \sum_{i,j} [A_{ij}] = c \sum_{i,j} \exp \left[ -\frac{1}{2} \beta (s_i - s_j - 1)^2 \right]$$

Thus, the total number of edges is proportional to  $c$ , meaning  $c$  controls for sparsity.

$\beta$  specifies the disorder in the system; the extent to which edges respect the ranks  $s$ .

# Parameters...

$$\text{E}[M] = \sum_{i,j} [A_{ij}] = c \sum_{i,j} \exp\left[-\frac{1}{2}\beta(s_i - s_j - 1)^2\right]$$

Thus, the total number of edges is proportional to  $c$ , meaning  $c$  controls for sparsity.

$\beta$  specifies the disorder in the system; the extent to which edges respect the ranks  $s$ .

The likelihood of observing/generating data  $A$ , given the parameters is:

$$P(A | s, \beta, c) = \prod_{i,j} \frac{\left[ce^{-\frac{\beta}{2}(s_i - s_j - 1)^2}\right]^{A_{ij}}}{A_{ij}!} \exp\left[-ce^{-\frac{\beta}{2}(s_i - s_j - 1)^2}\right]$$

# Maximize the likelihood to find the ranks!

the usual tricks:

maximize the *log*; take derivatives & set to zero; chuck out additive constants.

$$\mathcal{L}(A \mid s, \beta) = -\beta H(s) - M \log \left[ \sum_{i,j} e^{-\frac{\beta}{2}(s_i - s_j - 1)^2} \right]$$

# Maximize the likelihood to find the ranks!

the usual tricks:

maximize the *log*; take derivatives & set to zero; chuck out additive constants.

$$\mathcal{L}(A \mid s, \beta) = -\beta H(s) - M \log \left[ \sum_{i,j} e^{-\frac{\beta}{2}(s_i - s_j - 1)^2} \right]$$

For low temperature ( $\beta$  large) or a sparse network (M small) ,  
the ML ranks are *equal to* the ranks minimizing the SR Hamiltonian!

# Maximize the likelihood to find the ranks!

the usual tricks:

maximize the *log*; take derivatives & set to zero; chuck out additive constants.

$$\mathcal{L}(A \mid s, \beta) = -\beta H(s) - M \log \left[ \sum_{i,j} e^{-\frac{\beta}{2}(s_i - s_j - 1)^2} \right]$$

For low temperature ( $\beta$  large) or a sparse network (M small) ,  
the ML ranks are *equal to* the ranks minimizing the SR Hamiltonian!

In other words: solving SpringRank is asymptotically equivalent to inferring  $s$  using the GM.

# What about priors?

$$P(s) \propto \prod_{i=1}^N e^{-\frac{\alpha\beta}{2}s_i^2}$$

For example, we believe the ranks were drawn from a Gaussian.

# What about priors?

$$P(s) \propto \prod_{i=1}^N e^{-\frac{\alpha\beta}{2}s_i^2}$$

For example, we believe the ranks were drawn from a Gaussian.

Then the maximum a posteriori estimate, asymptotically, becomes the minimizer of

$$H_{\text{reg}}(s) = H(s) + \frac{\alpha}{2} \sum_{i=1}^N s_i^2$$

# What about priors?

$$P(s) \propto \prod_{i=1}^N e^{-\frac{\alpha\beta}{2}s_i^2}$$

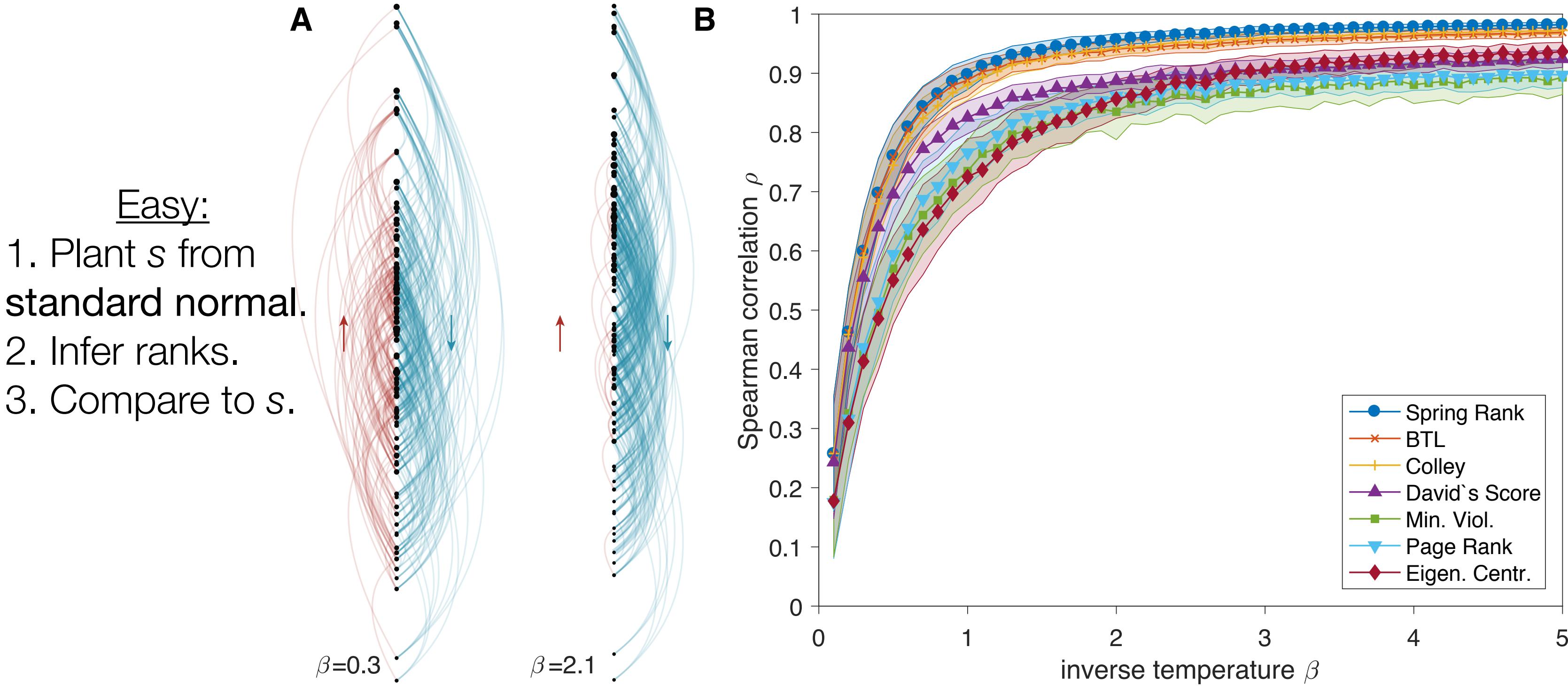
For example, we believe the ranks were drawn from a Gaussian.

Then the maximum a posteriori estimate, asymptotically, becomes the minimizer of

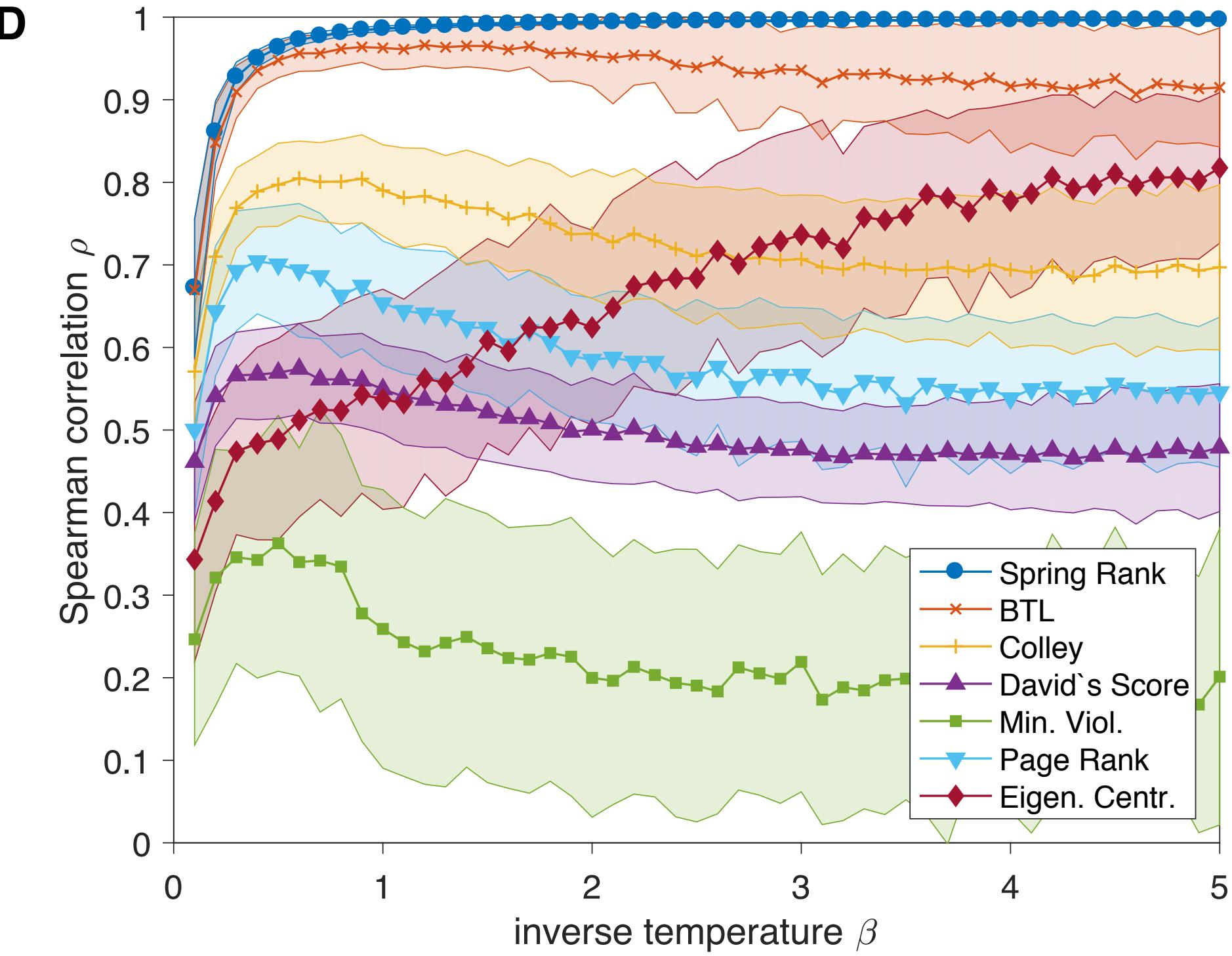
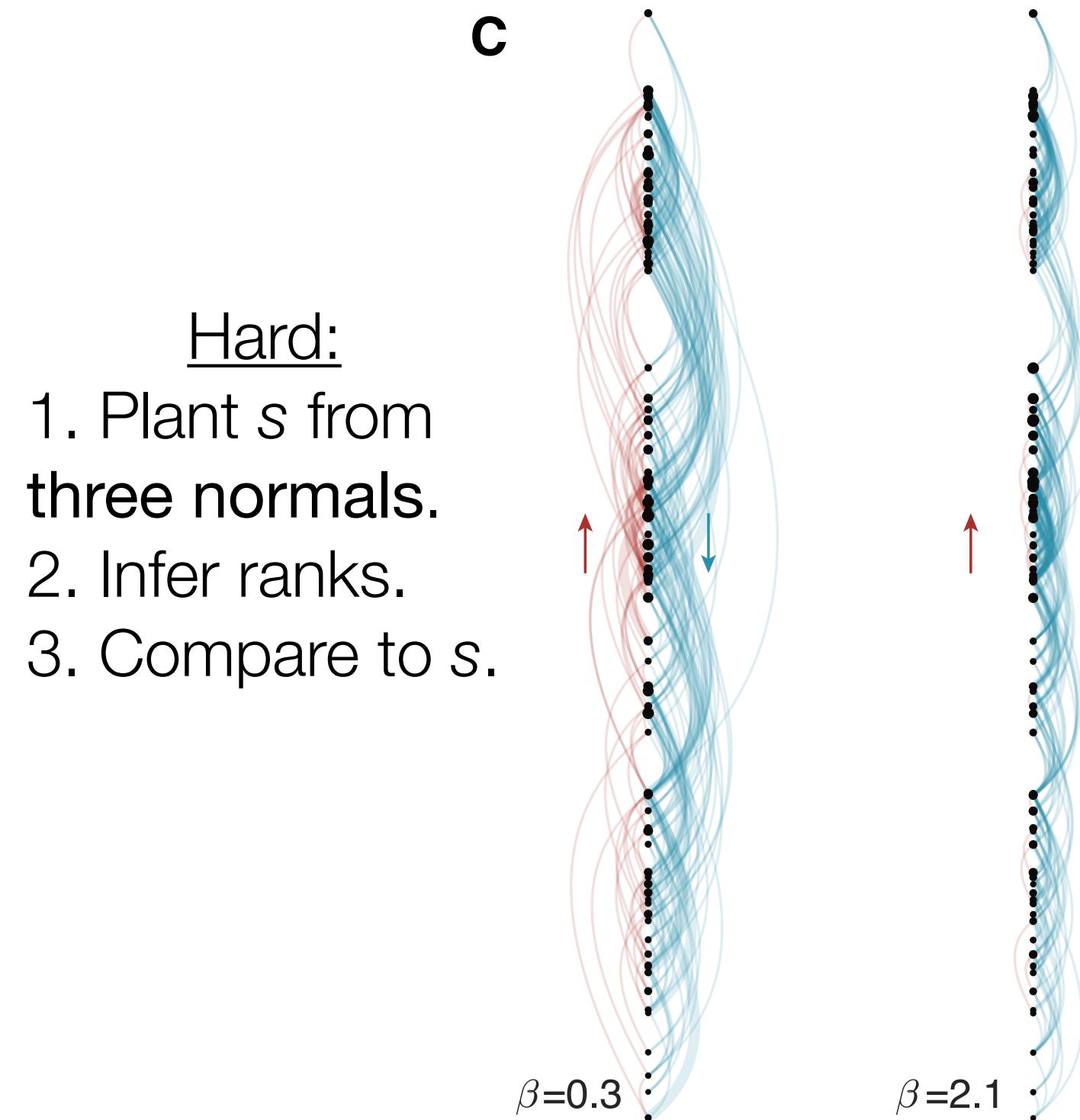
$$H_{\text{reg}}(s) = H(s) + \frac{\alpha}{2} \sum_{i=1}^N s_i^2$$

Put differently: a Gaussian prior over  $s$  corresponds to the regularization from before!

# Consistency: Test SpringRank using GM synthetic data



# Consistency: Test SpringRank using GM synthetic data





Edge prediction & cross validation

# Cross validation: train on 80%, predict 20%

In a linear hierarchy the key quantity to predict is *edge direction*, given *edge existence*.

If  $i$  and  $j$  were to face off, who would win?

# Cross validation: train on 80%, predict 20%

In a linear hierarchy the key quantity to predict is *edge direction*, given *edge existence*.

If  $i$  and  $j$  were to face off, who would win?

I'll give you *undirected*( $A$ ), and you predict *directed*( $A$ ).

# Cross validation: train on 80%, predict 20%

In a linear hierarchy the key quantity to predict is *edge direction*, given *edge existence*.

If  $i$  and  $j$  were to face off, who would win?

I'll give you  $\text{undirected}(A)$ , and you predict  $\text{directed}(A)$ .

**Setup:** learn  $s$  from 80% of  $A$ . Then predict edge directions for remaining 20% of  $A$ .

# Cross validation: train on 80%, predict 20%

In a linear hierarchy the key quantity to predict is *edge direction*, given *edge existence*.

If  $i$  and  $j$  were to face off, who would win?

I'll give you *undirected*( $A$ ), and you predict *directed*( $A$ ).

**Setup:** learn  $s$  from 80% of  $A$ . Then predict edge directions for remaining 20% of  $A$ .

SpringRank predicts edge direction based on the relative direction probabilities:

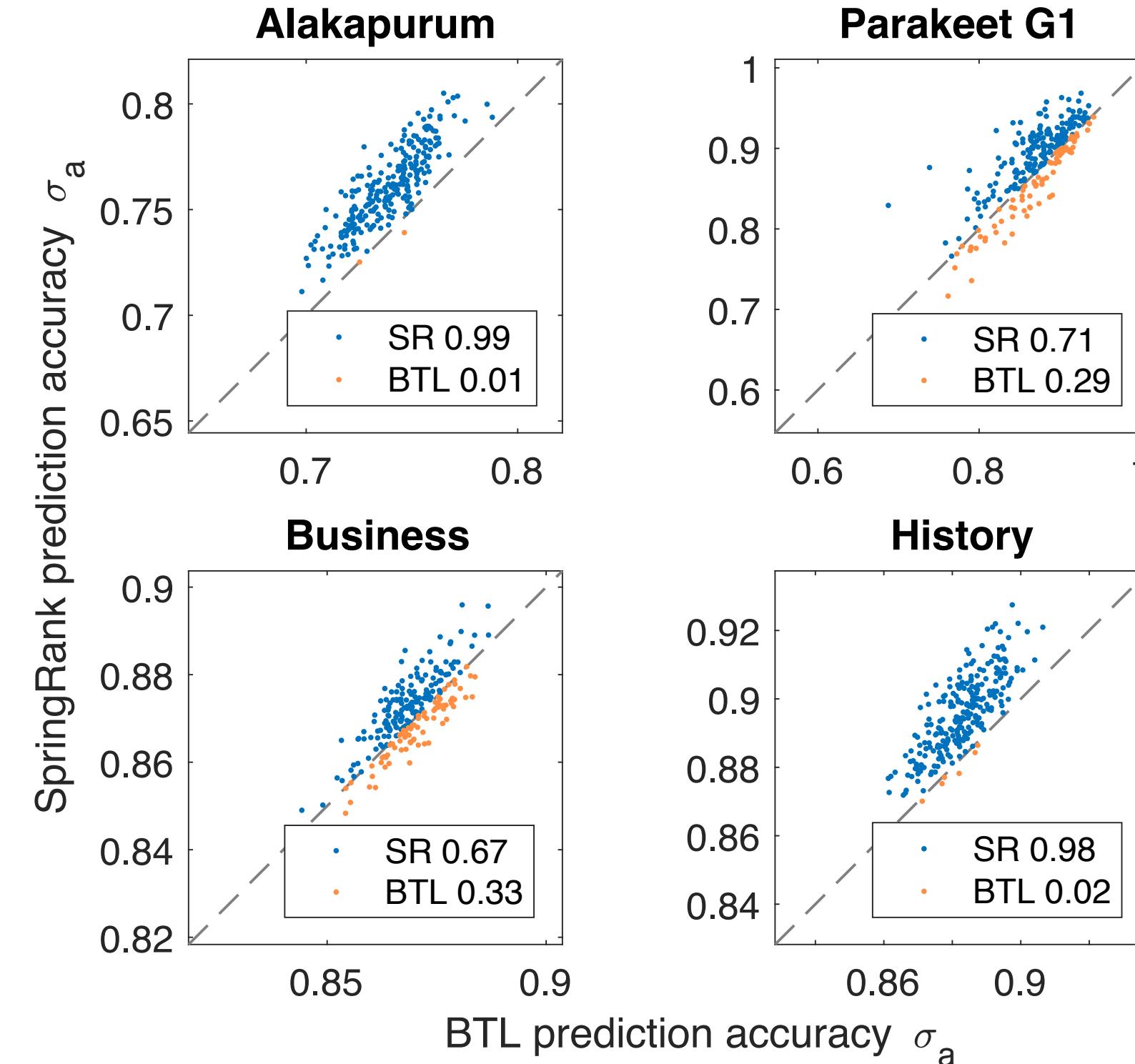
$$P_{ij}(\beta) = \frac{e^{-\beta H_{ij}}}{e^{-\beta H_{ij}} + e^{-\beta H_{ji}}} = \frac{1}{1 + e^{-2\beta(s_i - s_j)}}$$

# Cross validation results

Accuracy:

$$\sigma_a = 1 - \frac{1}{2M} \sum_{i,j} |A_{ij} - (A_{ij} + A_{ji}) P_{ij}|$$

Goal: maximize the number of correctly predicted edge directions

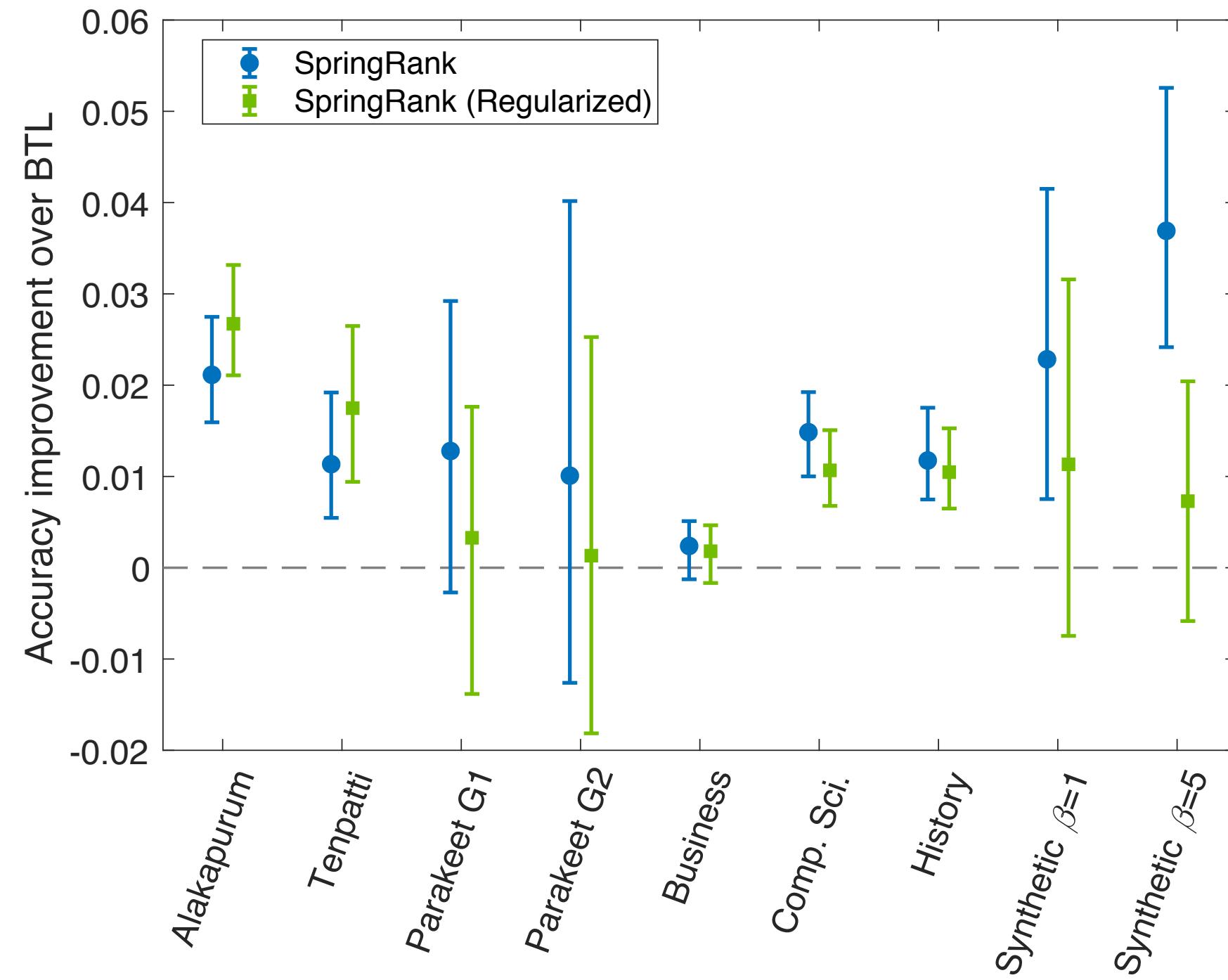


# Cross validation results

Accuracy:

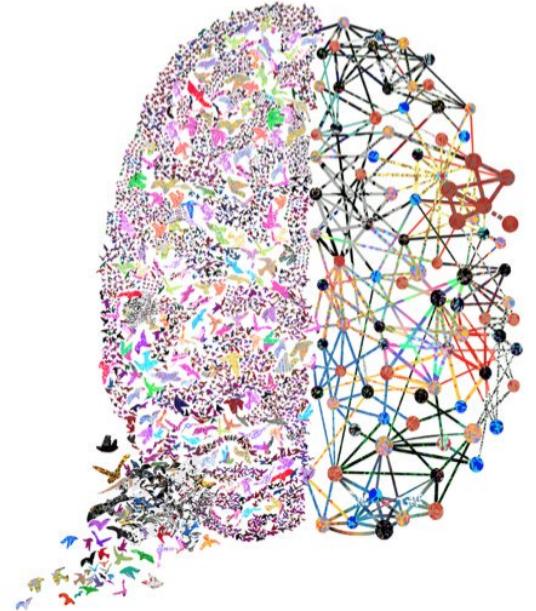
$$\sigma_a = 1 - \frac{1}{2M} \sum_{i,j} |A_{ij} - (A_{ij} + A_{ji}) P_{ij}|$$

Goal: maximize the number of correctly predicted edge directions.



# Conference on Complex Networks **COMPLENET '18**

Hosted by Northeastern University Network Science Institute



BOSTON, MA

APRIL 2018

Xindi Wang



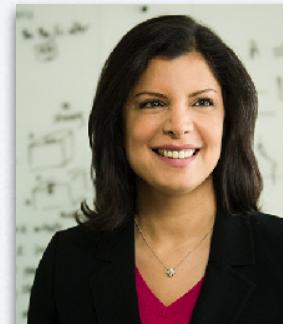
**LEARNING TO PLACE OBJECTS:  
A NETWORK-BASED APPROACH**

Xindi Wang

Onur Varol



Tina Eliassi-Rad



Albert-László Barabási

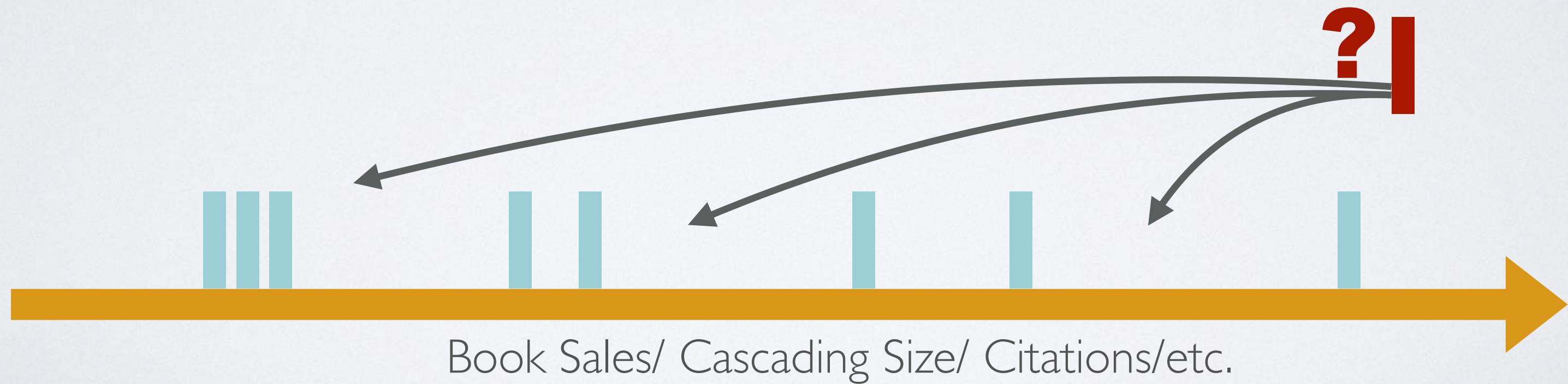


**Northeastern University  
Network Science Institute**

**netsi**

# PROBLEM DEFINITION

**Learning to place: Given a sequence of ordered items, where should we place a new item?**



# AUC

Method	AUC on Fiction	AUC on Biography
Pairwise +	KNN	0.759
	Cohen et al.	0.892
	WTG wave	<b>0.910</b>
	Voting	<b>0.915</b>
	FAS-PIVOT	<b>0.907</b>
	SpringRank	<b>0.908</b>

# AUC

Method	AUC on Fiction	AUC on Biography
Pairwise +	KNN	0.759
	Cohen et al.	0.892
	WTG wave	<b>0.910</b>
	Voting	<b>0.915</b>
	FAS-PIVOT	<b>0.907</b>
	SpringRank	 <b>0.908</b>

# But is there *really* a linear hierarchy?

If ranks are meaningful, then they are related to *outcomes*, i.e. the directions of edges.

Use the ground-state energy as a test statistic,  
under an edge-direction randomized null.

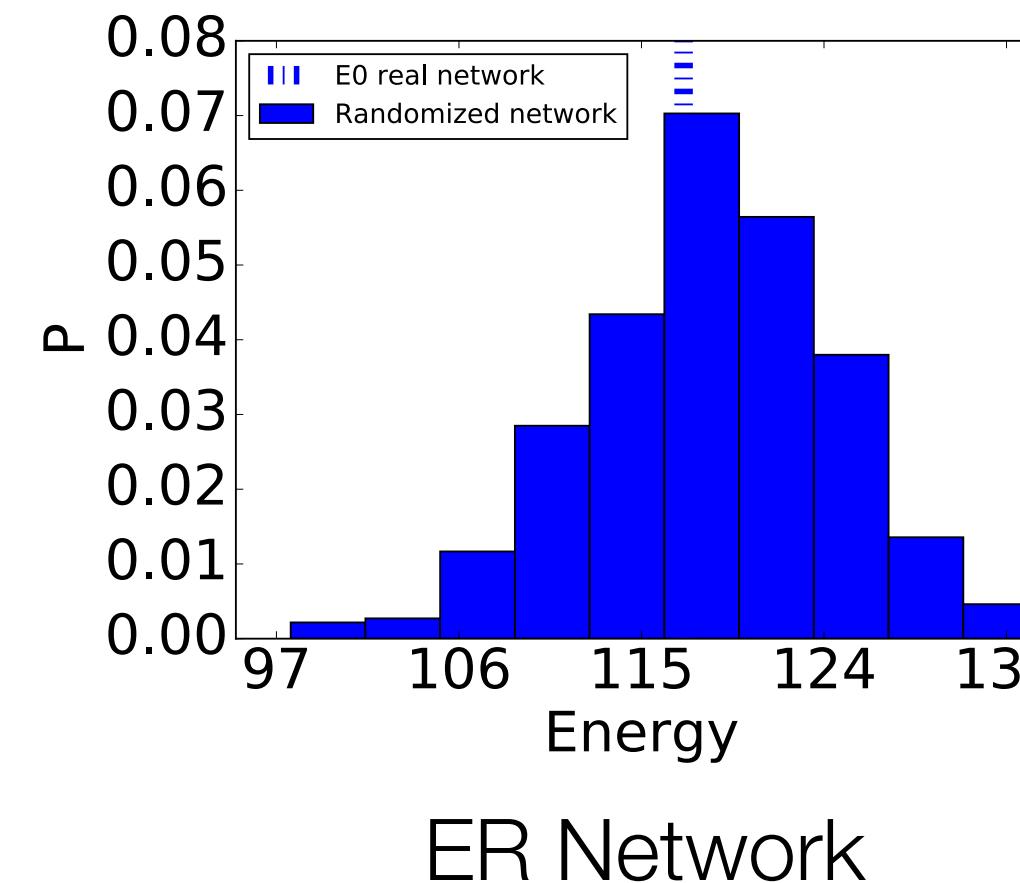
$$\frac{H(s^*)}{M} = \frac{1}{2M} \sum_i (d_i^{\text{in}} - d_i^{\text{out}}) s_i^* + \frac{1}{2}$$

# But is there *really* a linear hierarchy?

If ranks are meaningful, then they are related to *outcomes*, i.e. the directions of edges.

Use the ground-state energy as a test statistic,  
under an edge-direction randomized null.

$$\frac{H(s^*)}{M} = \frac{1}{2M} \sum_i (d_i^{\text{in}} - d_i^{\text{out}}) s_i^* + \frac{1}{2}$$

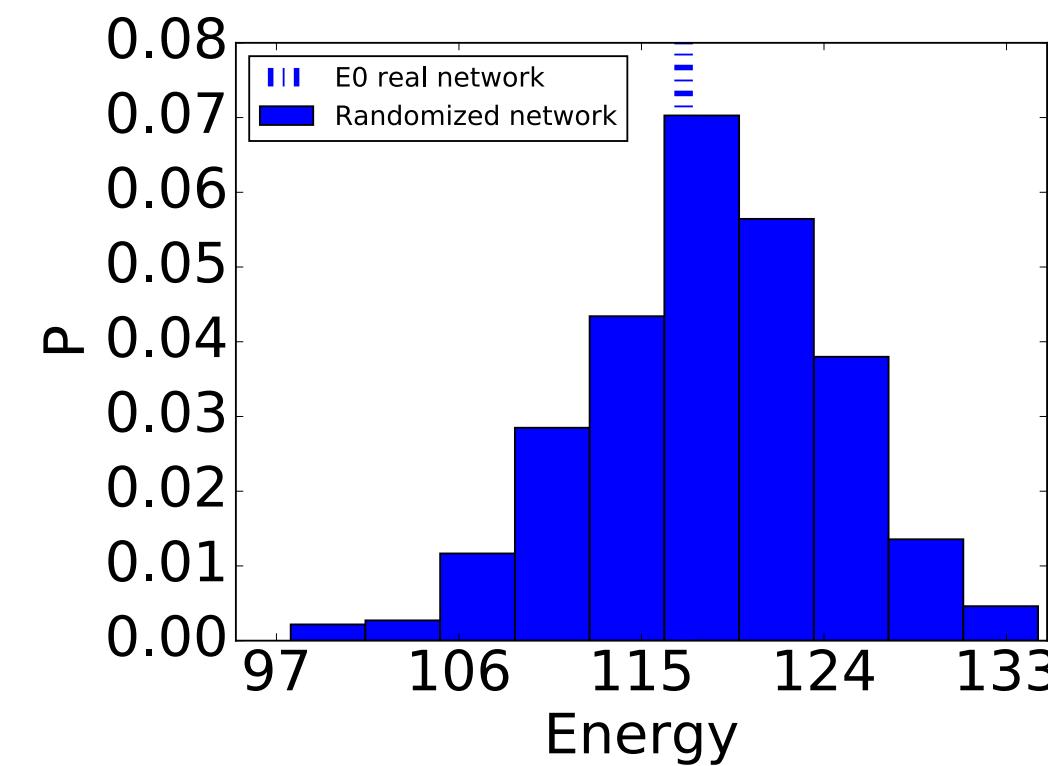


# But is there *really* a linear hierarchy?

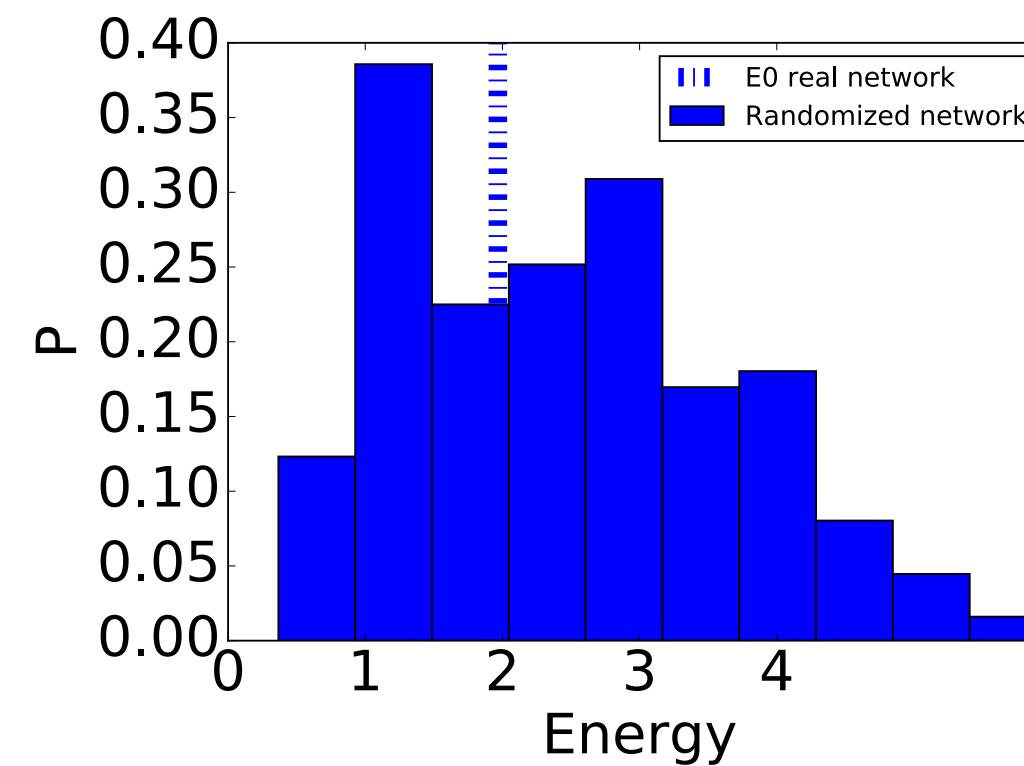
If ranks are meaningful, then they are related to *outcomes*, i.e. the directions of edges.

Use the ground-state energy as a test statistic,  
under an edge-direction randomized null.

$$\frac{H(s^*)}{M} = \frac{1}{2M} \sum_i (d_i^{\text{in}} - d_i^{\text{out}}) s_i^* + \frac{1}{2}$$



ER Network



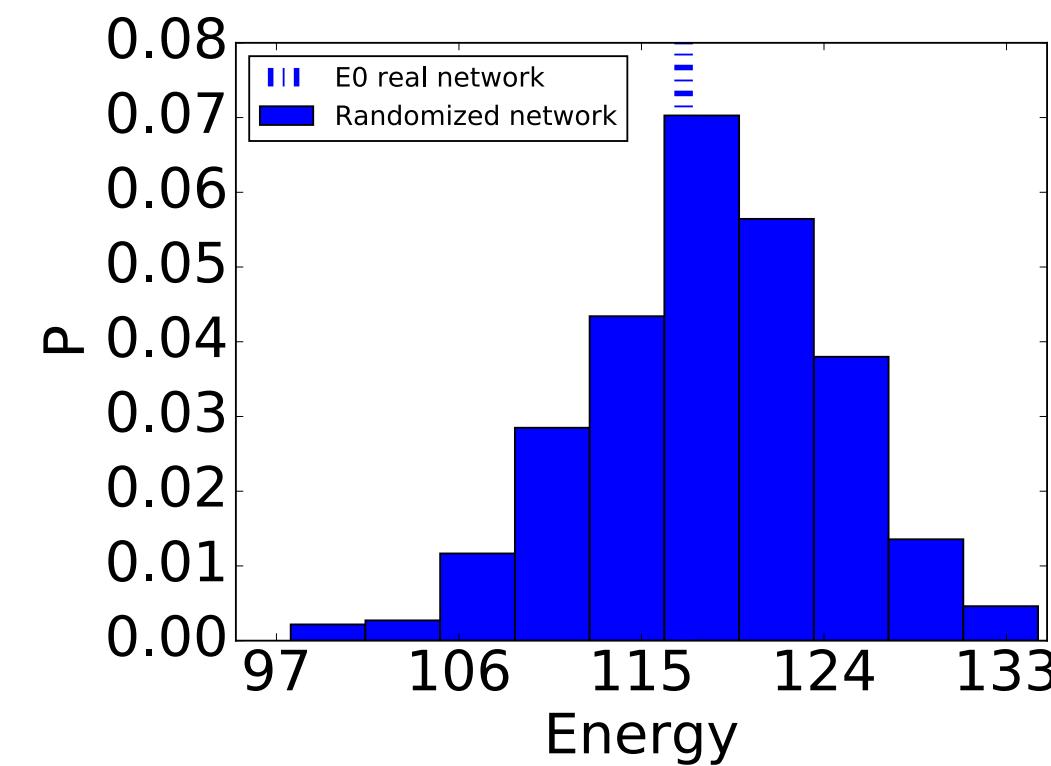
Asian Elephants

# But is there *really* a linear hierarchy?

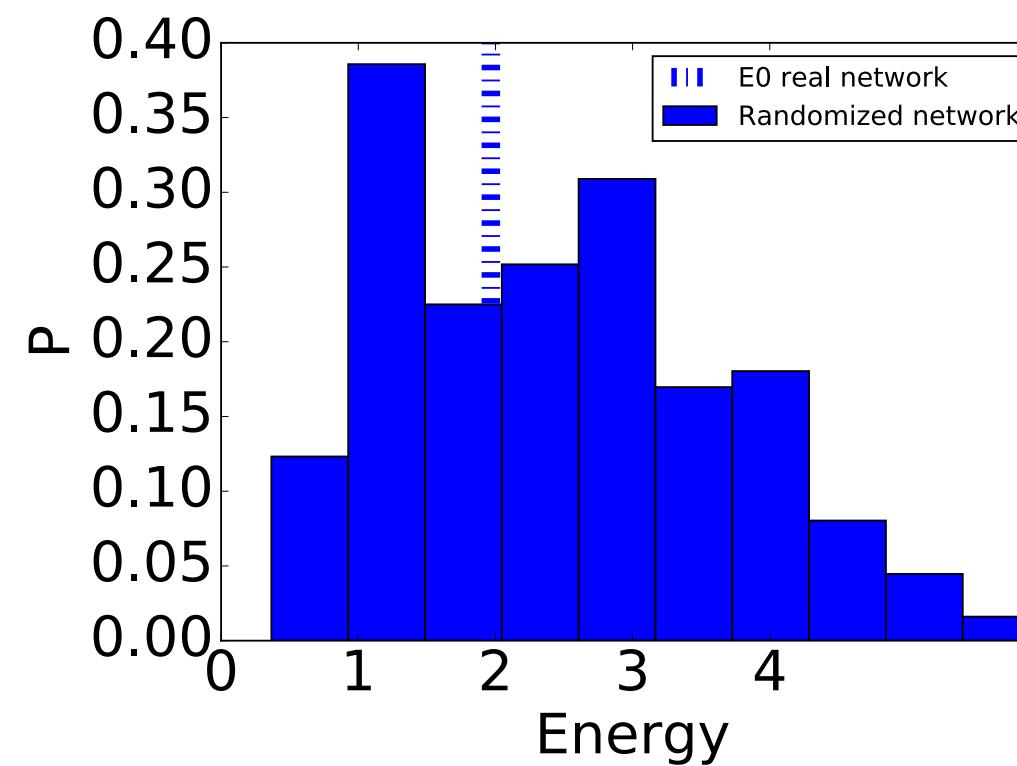
If ranks are meaningful, then they are related to *outcomes*, i.e. the directions of edges.

Use the ground-state energy as a test statistic,  
under an edge-direction randomized null.

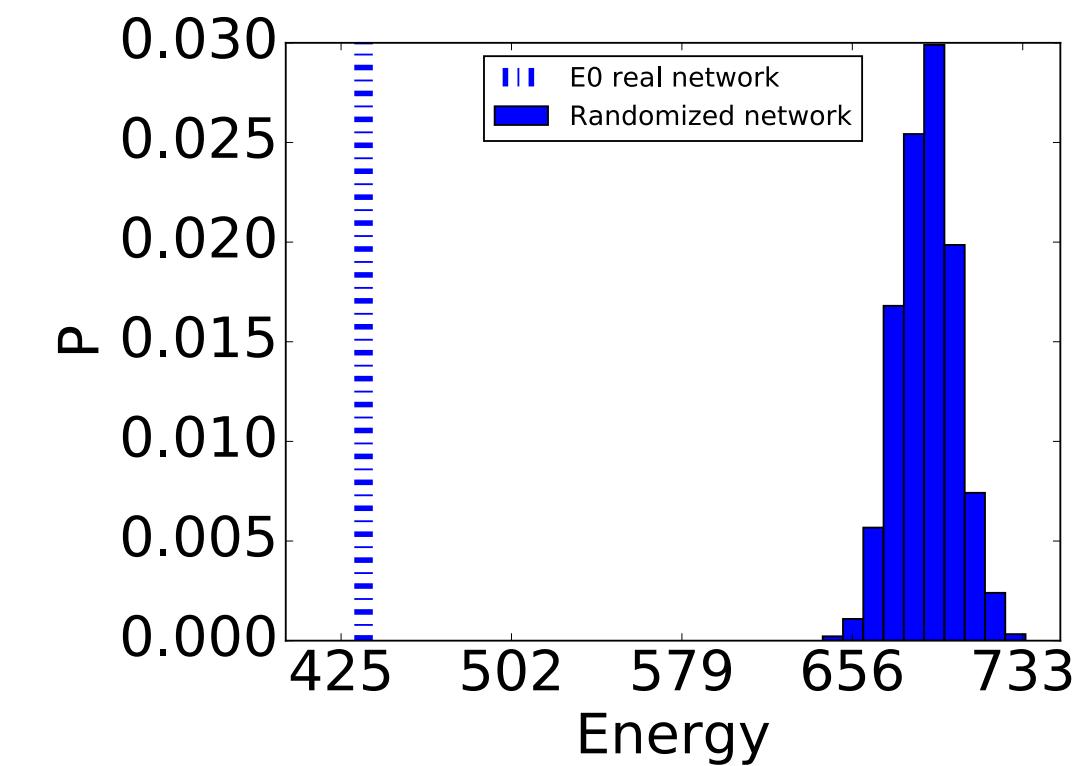
$$\frac{H(s^*)}{M} = \frac{1}{2M} \sum_i (d_i^{\text{in}} - d_i^{\text{out}}) s_i^* + \frac{1}{2}$$



ER Network



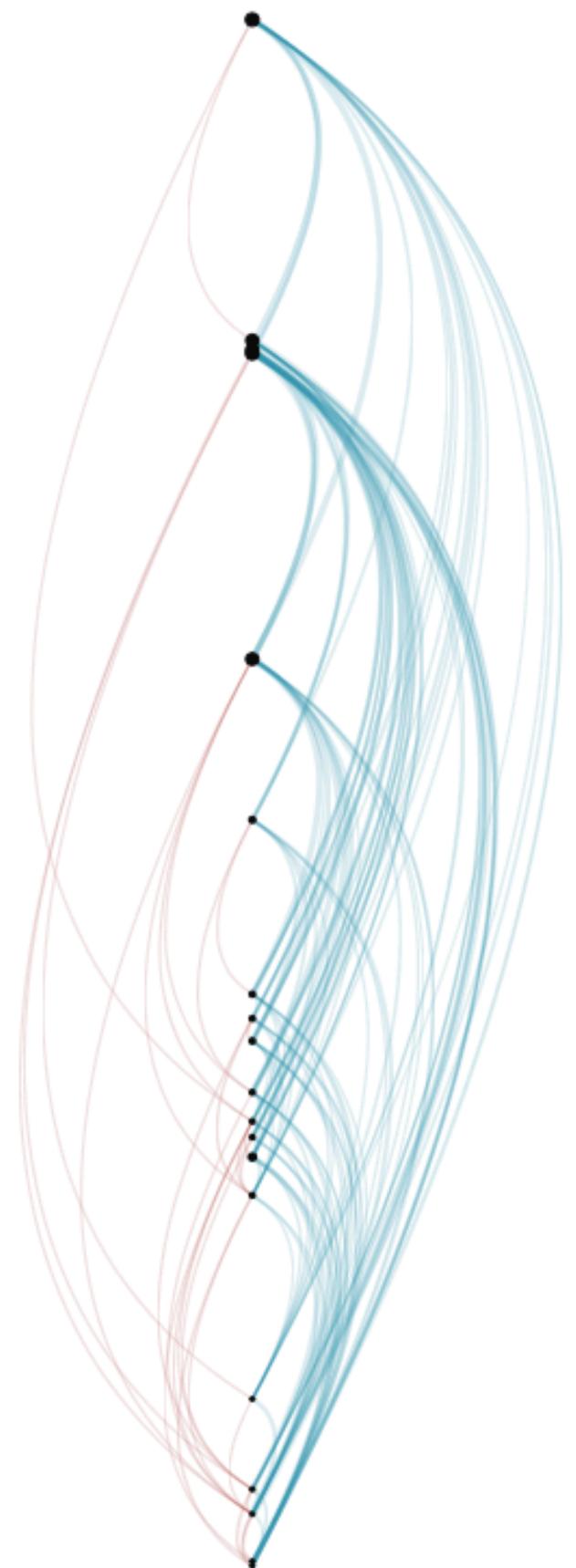
Asian Elephants



Social Support

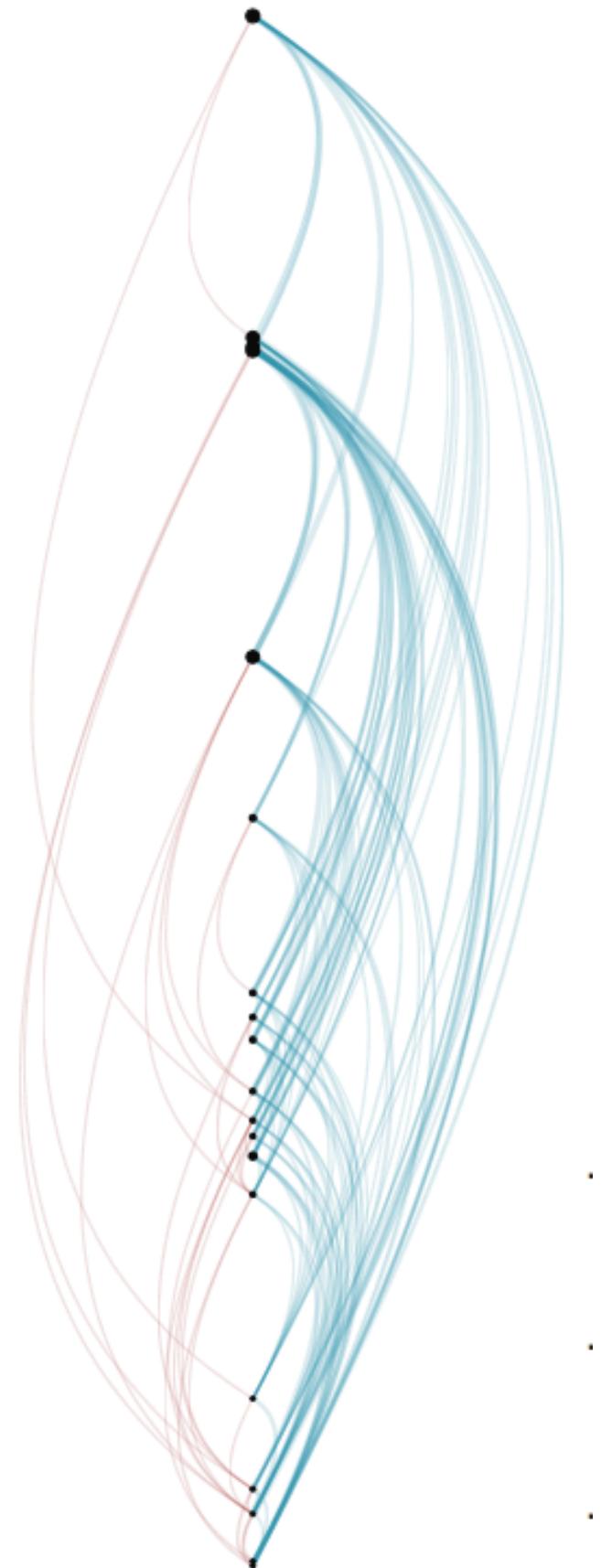
# Conclusions and extensions

1. SpringRank is a fast, scalable, *predictive* approach to ranking in directed networks. Works for Dominance or Endorsement.
2. It formalizes the idea that we can learn from not just the *direction* of edges, but the *existence* of edges as well.
3. There is a corresponding generative model whose ML solution is asymptotically equivalent. SpringRank approximates this ML solution.



# Conclusions and extensions

1. SpringRank is a fast, scalable, *predictive* approach to ranking in directed networks. Works for Dominance or Endorsement.
2. It formalizes the idea that we can learn from not just the *direction* of edges, but the *existence* of edges as well.
3. There is a corresponding generative model whose ML solution is asymptotically equivalent. SpringRank approximates this ML solution.
  - a. What if the hierarchy branches, like a Y?
  - b. What about other convex spring potential functions?
  - c. When might the spring constants depend on  $i$  or  $j$  ?





Caterina De Bacco

 COLUMBIA UNIVERSITY



Cris Moore



SANTA FE INSTITUTE

A physical model for efficient ranking in networks  
De Bacco\*, Larremore\*, and Moore. In Revision.  
{preprint, python, matlab, viz} → [danlarremore.com](http://danlarremore.com)



# Thank you

@danlarremore

daniel.larremore@colorado.edu

# Supplement: Non-transitive dice

- 3 (or more) dice {A,B,C}
- faces chosen so that they have the property:
  - A>B more than half the time.
  - B>C more than half the time.
  - C>A more than half the time (?!)

[https://en.wikipedia.org/wiki/Nontransitive\\_dice](https://en.wikipedia.org/wiki/Nontransitive_dice)

A great gift for your favorite nerd's desk!  
Go to the Makerspace and laserbeam your own?

