

# Chemotactic encounters between bacteria and phytoplankton – the stakes are high for encounters with small phytoplankton.

Riccardo Foffi<sup>a</sup>, Douglas R. Brumley<sup>b</sup>, François Peaudecerf<sup>c</sup>, Roman Stocker<sup>a</sup>, and Jonasz Słomka<sup>a,1</sup>

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**Chemotaxis, the ability to navigate chemical gradients, enables motile bacteria to increase encounter rates with phytoplankton cells. However, it is unclear how the detection of noisy and spatially confined gradients around phytoplankton of different sizes depends on bacterial phenotypes, and how strongly the ensuing chemotactic behavior enhances encounters. Here, we compute an upper bound on the chemotactic index, a dimensionless number that measures the increase in encounter rate with a phytoplankton cell due to chemotaxis over random motility alone. We find that chemotaxis can strongly enhance the efficiency of searches for small phytoplankton, owing to the ballistic nature of encounters for those cells, but the chemotactic index, determined by the bacterial ability to resolve spatially confined gradients, is extremely sensitive to phytoplankton and bacterial phenotypes. In productive waters, chemotaxis can decrease the search times of bacteria for micron-sized picophytoplankton up to ten-fold, from days to a few hours; but an increase in swimming speed or a slight reduction in phytoplankton size or leakage rate may render gradients undetectable, easily erasing this benefit. For larger phytoplankton, above 10 micron in size, the decrease in search time is more moderate, from a month to a week, but, depending gently on gradient detection abilities, it is more robust to variations. Thus, engaging chemotaxis in interactions with small phytoplankton is a high-stakes game for bacteria: the potential payoff is large, but it changes abruptly with bacterial ability to sense gradients, a scenario that may promote a diversity of chemotactic strategies.**

encounter rates | chemotaxis | bacteria-phytoplankton interactions | microbial ecology

Chemotaxis, the ability of bacteria to navigate chemical gradients and reach proximity with phytoplankton cells, can be crucial for establishing symbiotic relationships and favoring metabolic exchanges which lie at the heart of oceanic carbon cycles (1–3). In the water column, phytoplankton cells generate complex chemical landscapes by leaking dissolved organic compounds which can be strong attractants for bacteria (4–6). The composition of marine phytoplankton communities, which can span two orders of magnitude in cell size, from  $\sim 0.5\ \mu\text{m}$  to hundreds of microns (7), exposes bacteria to gradients on a wide range of scales.

Bacterial chemotaxis operates by sensing temporal changes in the concentration of chemoattractant compounds and biasing bacterial motion towards regions where these chemoattractant concentrations are higher (8, 9). Based on a molecule counting process, chemotaxis is inherently subject to noise (10, 11), especially at the low attractant concentrations typical of oceanic environments (12). The limits that noise imposes on chemosensing are well characterized for wide concentration ramps (13), typical of laboratory assays and comparable to the gradients generated by large phytoplankton cells, and for intense but short-lived gaussian pulses, mimicking cell lysis events (14, 15). By contrast, our understanding of chemotaxis towards small cells, which may generate gradients tightly confined in space, is rather limited, despite the smallest phytoplankters being by far the most abundant (16, 17). Moreover, while it is qualitatively well understood that chemotaxis can favor bacteria-phytoplankton interactions, it is quantitatively unclear how much interaction rates can increase across the size spectrum.

Here we investigate, through the lens of encounter rates, how chemotaxis can increase interaction rates between bacteria and phytoplankton cells (18). Combining constraints on the detection of noisy and spatially confined gradients with the size-dependent nature of random encounters, we obtain an upper bound on the possible increase in encounter rates resulting from the use of chemotaxis, with respect to purely random searches. Our results, also supported by a minimal numerical model of an ideal sensor, show that chemotaxis towards large phytoplankton cells

## Significance Statement

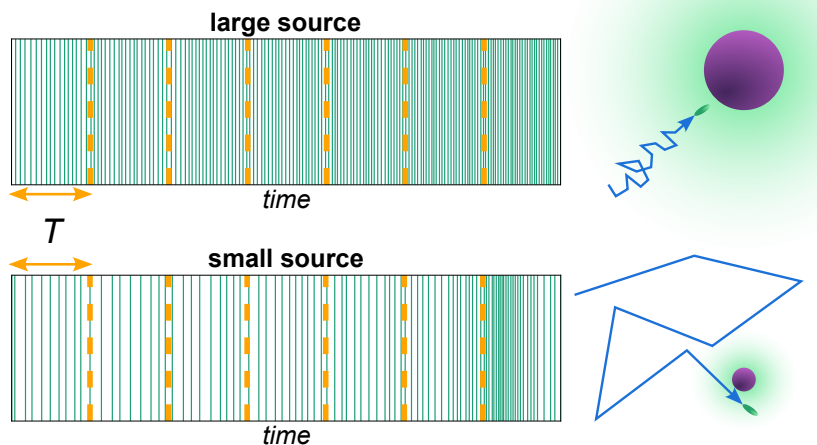
Microscale interactions between bacteria and phytoplankton control nutrient cycling in the ocean. Chemotaxis can aid bacteria in navigating chemical gradients exuded by the phytoplankton, favoring their encounter by reducing the search times. Chemotactic searches requires bacteria to accurately detect noisy gradients, with the type of noise depending on the size of the phytoplankton cell. Detection fails when gradients are too flat (large phytoplankton) or too spatially confined (small phytoplankton). We computed an upper bound on bacterial chemotactic advantage for different phytoplankton size classes and found that chemotaxis offers the largest reductions in search time for small phytoplankton. However, the advantage sensitively relies on the chemotactic strategy adopted by bacteria. Chemotactic encounters with small phytoplankton are thus a high-stakes game that may promote a diversity of size-dependent chemotactic strategies.

Author affiliations: <sup>a</sup>Institute of Environmental Engineering, Department of Civil, Environmental and Geomatic Engineering, ETH Zürich, 8093 Zürich, Switzerland; <sup>b</sup>School of Mathematics and Statistics, The University of Melbourne, Parkville, Victoria, Australia; <sup>c</sup>Univ Rennes, CNRS, IPR (Institut de Physique de Rennes) - UMR 6251, F-35000 Rennes, France

Please provide details of author contributions here.

Please declare any competing interests here.

<sup>1</sup>To whom correspondence should be addressed. E-mail: jslomka@ethz.ch



**Fig. 1. Detecting chemical gradients to increase encounter rates with phytoplankton through chemotaxis is a size-dependent challenge for bacteria.** To estimate the local concentration gradient, the bacterial chemosensory machinery integrates absorption sequences of chemoattractant molecules over a characteristic sensory timescale  $T$ . The phytoplankton size determines the lengthscale over which the gradients extend, leading to absorption sequences with well-distinguished features for small and large sources. The limiting factors for the detection of these sources are therefore of different nature: sensing noise for large sources arising from molecular fluctuations and dynamic noise for small sources resulting from bacterial motion and limited temporal resolution. The timeseries in these figures are generated from simulations of poissonian absorption events for a bacterium moving in a steady-state diffusive concentration field (Equation 1).

offers easily accessible but modest reductions in search times; search times for the small picophytoplankton can instead decrease drastically although the risk of failure is high. We hypothesize that such low-risk/low-gain performance for large targets and high-risk/high-gain for small targets may promote size-sensitive chemotactic strategies.

Phytoplankton cells of different sizes generate chemical gradients of varying steepness and spatial extent, posing fundamentally different gradient detection challenges for bacteria (Figure 1; see also discussion in SI). Bacteria experience concentration fields in the form of temporal sequences of molecular adsorption events, which are integrated over a sensory timescale  $T$  to form an estimate of the local concentration gradient (10). When moving in the chemoattractant field generated by a large phytoplankton cell, which may be characterized by wide spatial extent and a shallow gradient, a bacterium will experience a large baseline adsorption rate with only a gradual increase over subsequent sensory windows. Detection can fail if the gradient is too shallow, and the spatial increase in concentration is masked by fluctuations in the molecular adsorption events, a scenario which has been modeled in detail before (13). By contrast, in the case of a small phytoplankton cell, whose concentration fields are likely to be weaker and tightly localized in space, the signal will mostly be indistinguishable from the background, until, at very close distance from the phytoplankton, the bacterium will experience a sudden burst in adsorption events localized within a short time interval. Here the limiting factor is not the inherent noise arising from molecular fluctuations, but the dynamic noise resulting from bacterial motion, which limits the ability of the bacteria to properly resolve a signal appearing over timescales comparable or smaller to the sensory timescale  $T$ : the limited temporal resolution of the measurements may lead to aliasing effects (19), preventing an accurate reconstruction of the gradient. Spatially confined sources have received less attention after Jackson proposed that chemotaxis towards cells smaller than  $3 \sim 4 \mu\text{m}$  would not be possible (20); recently, however, it was shown that marine bacterium *Marinobacter adhaerens* can use chemotaxis to increase nutrient uptake from the picocyanobacterium *Synechococcus* (21), highlighting how chemotaxis might be relevant even at the smallest scales. To study how the phytoplankton size and the associated sensing limitations

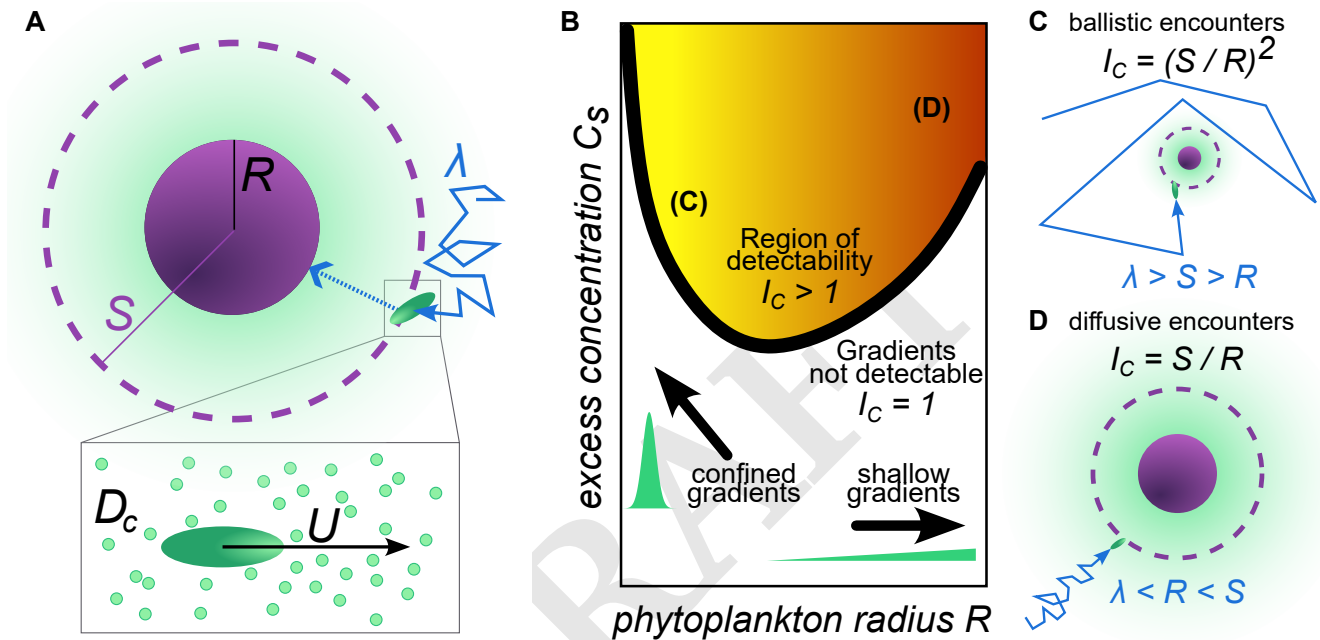
affect chemotaxis performance, we next outline how to compute an upper bound on the chemotactic index, a dimensionless number that measures the increase in encounter rate with a phytoplankton cell due to chemotaxis over random motility alone.

We compute an upper bound on the chemotactic index by considering a perfect chemotactic bacterium limited only by random encounters with a sensing horizon - a distance inside which the bacterium detects gradients and flawlessly navigates towards the phytoplankton (Figure 2). We represent a phytoplankton cell as a sphere of radius  $R$  which can exude chemoattractants to generate a steady-state diffusive concentration field (see SI for derivation and discussion of other concentration fields)

$$C(r) = C_0 + C_s \frac{R}{r} \quad [1]$$

where  $C_0$  is the background concentration of the compound far away from the phytoplankton cell,  $C_s$  is the excess concentration of the compound at the phytoplankton cell surface, and  $r$  is the radial distance from the center of the phytoplankton cell ( $r \geq R$ ). In the absence of chemoattractants, a bacterium performs a random walk with speed  $U$  and correlation length  $\lambda$ . When chemoattractant gradients are present, the bacterium can bias its motion in the direction of the positive gradient, increasing its chances of encountering a leaking phytoplankton cell. We find an upper bound to the encounter-enhancing effect of chemotaxis by considering the bacterium to be a “perfect chemotaxer”: there exists a “sensory horizon”,  $S$ , around the phytoplankton cell where the bacterium can reliably detect the gradient and exploit it to, eventually, yield an encounter with 100% probability; outside the sensory horizon no chemotactic behavior is manifested (Figure 2A). A real chemotaxer would exhibit a smooth, continuous response as a function of distance, and would never be able to outperform the perfect chemotaxer which always encounters the phytoplankton cell upon detecting the gradient; in this sense, the perfect chemotaxer imposes a limit on what any chemotactic bacterium could theoretically achieve. The problem of chemotactic encounters with the chemoattractant source is therefore reduced to the problem of identifying the sensory horizon.

The extent of the sensory horizon is defined by the bacterial ability to detect a signal (i.e., a positive gradient)



**Fig. 2. Chemotactic encounters are limited by the gradients' steepness and spatial extent, and ballistic or diffusive encounters with the sensing horizon.** (A) A phytoplankton cell of radius  $R$  produces a stationary diffusive field of a chemoattractant,  $C(r) = C_0 + C_s R/r$  (represented by the green halo). Far away from the cell, bacteria cannot sense the chemoattractant and thus swim in random walks, with correlation length  $\lambda$ . The "sensory distance"  $S$  is the distance from the phytoplankton cell at which a perfect chemotaxer would be able to detect the gradient and encounter its target with a 100% probability. (Inset) Chemosensing is a molecule-counting process based on encounters between the bacterium and individual chemoattractant molecules. Attractant molecules reach the bacterium via diffusion (diffusivity  $D_c$ ) while the bacterium swims at speed  $U$  through the chemoattractant field. (B) Schematic depiction of the performance landscape for chemotactic searches. The source size  $R$  and the chemoattractant concentration  $C_s$  determine whether gradients can be successfully detected or not. The thick black line defines the boundary of detection, separating the regions where gradient detection is or is not possible. Below the boundary ( $I_c = 1$ ), two conditions limit an organism's ability to perform chemotaxis: gradients are either too spatially confined or too shallow. In this region, chemotaxis provides no benefit over random motility. Above the boundary ( $I_c > 1$ ), gradients can be detected, and the increase in encounters compared to random motility, measured by the chemotactic index  $I_c$ , is determined by the relationship between bacterial correlation length  $\lambda$ , source size  $R$  and sensory radius  $S$ . The size dependence of random encounters identifies two subregions within the region of detectability (here qualitatively represented by the yellow-red shading), in which the chemotactic index displays two distinct behaviors. Small sources (C) lead to ballistic encounters for which the chemotactic index scales quadratically with the sensory radius  $S$ , whereas for large sources (D) the chemotactic index scales only linearly with  $S$  due to the diffusive nature of encounters.

at a given location, as determined by the signal-to-noise ratio. Chemotaxis operates through the adsorption of attractant molecules, which reach the bacterial cell surface with diffusivity  $D_c$  (Figure 2A inset) (10); the swimming speed,  $U$ , determines the temporal gradient experienced by the bacterium,  $U\nabla C$  (10, 14). In gradients with wide spatial extent, the inherent noise in the gradient measurements, arising from fluctuations in molecular adsorptions, was derived by Mora & Wingreen (13) as  $\sigma_0 = \sqrt{3C/(\pi a D_c T^3)}$ ; at any given location in space (assuming the bacterium is heading straight towards the phytoplankton cell) the signal-to-noise ratio (SNR) is then given by

$$\text{SNR} = \frac{|U\nabla C|}{\sqrt{3C/(\pi a D_c T^3)}}. \quad [2]$$

The SNR is related to the likelihood that a positive gradient can be resolved: when SNR is high, bacteria have a high probability to detect positive gradients; when it is low, gradients are masked by fluctuations. Equation 2 assumes that the concentration field does not vary significantly on times shorter than the sensory timescale  $T$ , ignoring the contribution of dynamic noise to gradient sensing. By introducing a non-linear (second-order) component to the concentration field, we derived a dynamic correction to  $\sigma_0$ , which, for the diffusive field in Equation 1, takes the form (SI)

$$\sigma_0^* = \sigma_0 \sqrt{1 + \frac{3}{20} \left( \frac{UT}{R + \Delta r} \right)^2} \quad [3]$$

where  $\Delta r$  is the distance from the surface of the source of radius  $R$ . Equation 3 shows that when the source is small compared to the distance traveled by the bacterium during the sensory interval, and the bacterium is close to the source (i.e., when  $UT > R + \Delta r$ ), the noise in the gradient estimate increases compared to the case of the linear ramp. The correction term highlights the importance of movement and size, reflecting the presence of a low-pass filter in the sensing process which prevents accurate measurement of high-frequency signals. Since a second-order expansion is not sufficient to fully represent the non-linearity of the diffusive concentration field over the entire parameter space, we capture the effect of the dynamic noise by phenomenologically augmenting the SNR with a low-pass filter  $f(x) = 1 - \exp(-x^{3/2})$ , which degrades the SNR for high-frequency signals ( $f(x \gg 1) = 0$ ), without affecting the lower frequency components ( $f(x \ll 1) = 1$ ). The results will be quantitatively, but not qualitatively, sensitive to the exact implementation of this low-pass filter. Further, following Brumley *et al.* (15), we introduce a chemotactic precision factor  $\Pi$  in front of the Mora-Wingreen noise  $\sigma = \Pi\sigma_0$ , which in marine bacterium *Vibrio anguillarum* was estimated as  $\Pi \approx 6$ . We then define the sensory horizon  $S$  as the farthest distance from the phytoplankton cell at which the SNR overcomes a threshold  $q$ ; mathematically,  $S$  is therefore the solution to the equation

$$\text{SNR} = \frac{|U\nabla C_{(S)}|f(UT/S)}{\Pi\sigma_{(S)}} = \frac{|U\nabla C_{(S)}|f(UT/S)}{6\sqrt{\frac{3C_{(S)}}{\pi a D_c T^3}}} = q \quad [4]$$

which can be solved numerically for any given set of parameters. A reasonable choice for the threshold is  $q = 1$ , which

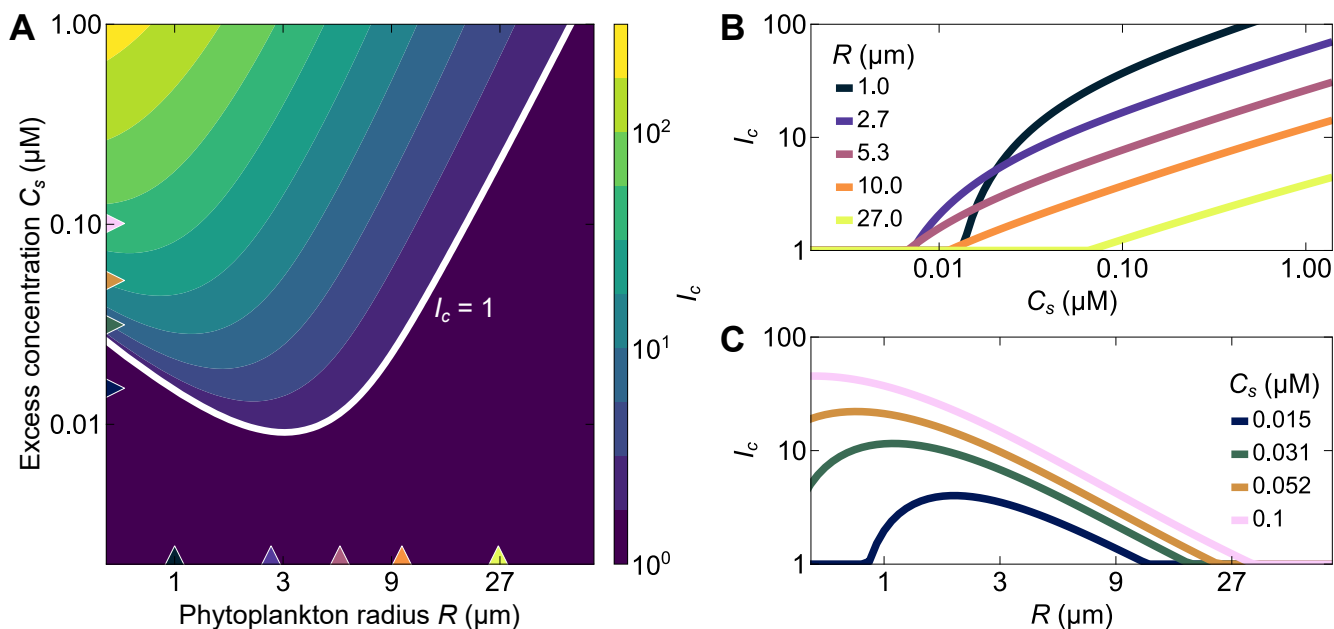
equates to defining  $S$  as the distance where bacteria can detect a positive gradient with a probability  $\approx 84\%$  (SI). For any given phytoplankton size and excess concentration, we can then determine whether a sensory horizon exists (i.e., if, for the given parameters, there is a distance  $S > R$  at which the SNR overcomes the threshold), and thus gradient detection is possible, or if gradients are not detectable (Figure 2B). Independently of the details of the signal processing mechanism and of the specific form of the concentration field, the two limiting factors of gradient steepness and spatial confinement, as described by the inherent and dynamic noise respectively, define a convex region where gradients can be detected.

When gradient detection is possible, the performance of chemotactic searches is limited by the ballistic or diffusive nature of encounters with the sensory horizon. In the perfect chemotaxis limit, reaching the sensory horizon  $S$  ensures that the bacterium will eventually reach the target phytoplankton: the problem of chemotactic encounters with the phytoplankton cell thus simplifies to the problem of random encounters with the sensory horizon. We quantify the maximum possible performance of a chemotactic search through a chemotactic index,  $I_c$ , defined as the ratio between the rate of random encounters with the sensory horizon,  $S$ , and the rate of random encounters with the phytoplankton cell of radius  $R$ . Successful chemosensing implies an increase in the apparent size of the phytoplankton cell,  $S > R$ , and is therefore characterized by  $I_c > 1$ . When a sensory horizon  $S > R$  does not exist, chemotaxis can provide no enhancement to encounter rates and therefore  $I_c = 1$  (we ignore possible scenarios where chemotaxis is detrimental to encounters leading to  $I_c < 1$ ).

The chemotactic index,  $I_c$ , within the region of detectability is determined (SI) by the relationship between the correlation length of the bacterial random walk,  $\lambda$ , the phytoplankton radius,  $R$ , and sensory horizon,  $S$ . The encounters with small phytoplankton cells ( $\lambda > S > R$ ) have a ballistic nature and display a quadratic scaling  $I_c = S^2/R^2$  (Figure 2C). For large phytoplankton cells ( $\lambda < R < S$ ) encounters are of diffusive nature and the chemotactic index scales only linearly  $I_c = S/R$  (Figure 2D). The different nature of detection limits and encounter mechanisms for small and large phytoplankton cells suggests an asymmetry in chemotactic performance as a function of size. The asymmetry should be particularly strong at the boundary of detection, where, for large cells, the sensing horizon is comparable with the cell size ( $S \sim R$ ) because gradients are sharpest close to the cell surface. Combined with the linear scaling ( $I_c = S/R$ ), we expect the  $I_c$  to vary smoothly across the detection boundary for large cells. By contrast, for small cells, the sensing horizon is not limited by gradient sharpness but by the temporal resolution of bacterial measurement, i.e., the sensing horizon is on the order of  $S \sim UT$ . Consequently, combined with the quadratic scaling ( $I_c = S^2/R^2$ ), we expect  $I_c$  to exhibit a sudden jump from  $I_c \sim (UT/R)^2$  to  $I_c = 1$  across the detection boundary for small cells as we verify next.

Chemotaxis towards small phytoplankton cells can be risky but highly rewarding. Application of our model to a “typical” marine bacterium (radius  $a = 0.5 \mu\text{m}$ , swimming speed  $U = 50 \mu\text{m s}^{-1}$ , sensory timescale  $T = 100 \text{ ms}$ )



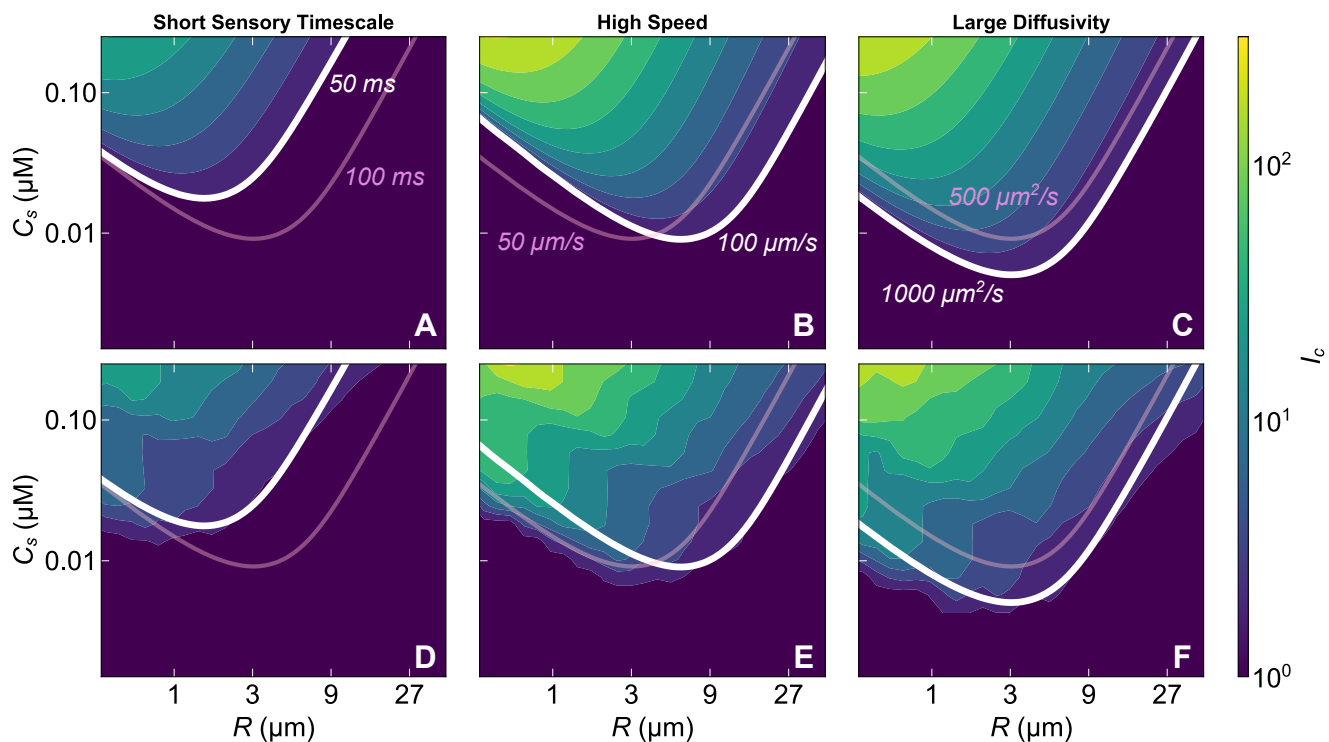


**Fig. 3. The stakes are high for encounters with small phytoplankton – the chemotactic index is largest for small phytoplankton, but it drops sharply when gradient detection fails.** (A) Performance ( $I_c$ ) landscape for a bacterium using chemotaxis to drive encounters with spherical targets of different radii ( $R$ ) and chemoattractant concentrations ( $C_s$ ) calculated using Equation 4. The thick white line defines the boundary of detection, separating the region where gradients are detectable and chemotaxis is beneficial to encounters ( $I_c > 1$ ) from the region where gradients are too shallow or too spatially confined to be detected ( $I_c = 1$ ). (B) Vertical transects from panel A for fixed values of the target radius  $R$  (corresponding to the upward-pointing triangles). In chemotaxis towards small targets, a slight variation in the chemoattractant concentration can make the difference between a highly successful search ( $I_c \sim 10$ ) or a failure ( $I_c = 1$ ), whereas for larger targets the dependency of  $I_c$  on the chemoattractant concentration is more gradual. (C) Horizontal transects from panel A for fixed values of the chemoattractant concentration  $C_s$  (corresponding to the right-pointing triangles). For weak sources, an increase in size  $R$  produces initially large enhancements in chemotactic performance, with diminishing returns upon further enlargement. As the source gets stronger, the increase in performance for chemotaxis towards small targets becomes disproportionately larger; larger sources also become detectable although offering modest performance improvements over random searches. A web app/notebook to interactively evaluate the  $I_c$  landscape for any set of parameters is freely available here: XXX.

chemotactic towards some sugar-like compound (diffusivity  $D_c = 500 \mu\text{m}^2/\text{s}$ ) yields a quantitative description of the chemotactic performance landscapes which shows clear differences between the small-radii and the large-radii region (Figure 3A). Here we assume the background concentration of the compound ( $C_0$  in Equation 1) to be fixed at 1 nM, a value on the low-end for dissolved free amino acids in ocean waters (12). The effect of changing background concentration is discussed in the SI. Contour lines of the  $I_c$  profile have a higher density close to the detection boundary in the region of small phytoplankton radii, suggesting that modest variations in the excess concentration  $C_s$  leaked by a small phytoplankter can have large impacts on the performance of bacterial chemotaxis. Indeed, the  $I_c$  has a much sharper dependency on  $C_s$  when the phytoplankton radius  $R$  is small, and especially so when crossing the detection boundary (Figure 3B): while a bacterium might not be able to sense ( $I_c = 1$ ) an attractant gradient from a 1  $\mu\text{m}$  phytoplankter leaking with  $C_s = 10$  nM, a few nM increase can quickly enhance the  $I_c$  to values of 10 and more; as  $C_s$  is further increased we get deeper into sensing territory, and the dependency of  $I_c$  on  $C_s$  quickly smooths out. For larger phytoplankton cells, there is no sharp increase: when the boundary of detection is crossed, the  $I_c$  only grows gradually with  $C_s$ . Simultaneously, for small values of the excess concentration  $C_s$ , an increase in phytoplankton radius  $R$  leads first to a sharp increase in chemotactic index and then a gradual decrease towards  $I_c = 1$  when  $R$  overcomes an optimal value (Figure 3C). As  $C_s$  is increased, phytoplankton cells with smaller sizes keep offering disproportionately larger

advantages to chemotactic performance compared to the larger cells whose detection requires larger and larger values of  $C_s$ .

Variations in chemotactic search strategies, defined by parameters such as swimming speed  $U$ , sensory timescale  $T$  or diffusivity of the sought-for compound  $D_c$ , determine the benefits of chemotaxis for a given phytoplankton radius and excess concentration, but do not affect the fundamental structure of the performance landscape (Figure 4). A reduction in sensory timescale from 100 to 50 ms significantly decreases bacterial ability to detect gradients from large phytoplankton cells and reduces the overall performance of chemotaxis (Figure 4A): a larger  $T$  reduces sensing noise ( $\propto T^{-3/2}$ ) but increases dynamic noise by reducing the frequency of measurements. An increase in swimming speed from 50 to 100  $\mu\text{m s}^{-1}$  improves the performance of chemotaxis within the region of detectability, but the region itself is shifted towards larger radii values, highlighting a tradeoff between degraded spatial resolution (lower frequency of measurements) and improved sensing accuracy by reducing bias in the signal (14)(Figure 4B). An increase in the diffusivity of the chemoattractant compound from 500 to 1000  $\mu\text{m}^2/\text{s}$  (values which are representative respectively of sugars (22), and DMSP (23) or amino acids (24)) enhances the signal-to-noise ratio without affecting spatial resolution (sensing noise  $\propto D_c^{-1/2}$ ), and it thus shifts the region of detectability towards lower  $C_s$  values (Figure 4C). Unaffected by the variation in these quantities, the high-stakes nature of chemotactic searches towards small phytoplankton cells is



**Fig. 4. Bacterial chemotactic strategy controls the chemotactic index but does not alter the high-stakes nature of encounters with small phytoplankton.** Performance landscapes of different chemotactic strategies obtained from theoretical (A–C) and computational (D–F) models. In all the panels, the pink curve is the detection boundary for a reference strategy with parameter values  $U = 50 \mu\text{m s}^{-1}$ ,  $T = 100 \text{ ms}$ ,  $D_c = 500 \mu\text{m}^2/\text{s}^2$  (same as in Figure 3A). (A) Reduction in sensory timescale  $T$  from 100 ms to 50 ms. (B) Increase in swimming speed from  $50 \mu\text{m s}^{-1}$  to  $100 \mu\text{m s}^{-1}$ . (C) Increase in chemoattractant diffusivity from  $500 \mu\text{m}^2/\text{s}$  to  $1000 \mu\text{m}^2/\text{s}$ . (D–F) Theoretically predicted features of bacterial chemotactic performance are reproduced by an ideal sensor based on the Kolmogorov-Smirnov test. In panels D to F, the white line is the detection boundary from the theoretical prediction of panels A to C, respectively. Despite small quantitative differences in the estimated  $I_c$  values, arising from the distinct signal processing mechanism and the finite spatial resolution of numerical simulations, the features of the performance landscape are clearly conserved.

therefore only a direct result of the sharp cutoff on spatial resolution arising from dynamic noise combined with the quadratic scaling of the  $I_c$  associated to ballistic encounters.

The generality of our theoretical analysis is supported by a minimal numerical model of an ideal sensor (Fig. 4D–F). This ideal sensor is defined as a sphere moving at constant speed  $U$  towards a phytoplankton cell leaking a chemoattractant field  $C(r)$ . As it moves, the sensor registers all the adsorption events of chemoattractant molecules, occurring as Poisson events with instantaneous rate  $4\pi D_c a C(r)$ , where  $r$  is the instantaneous position of the sensor. After an interval of length  $T$ , the registered events are processed and a new acquisition starts. For the signal processing, the sensor performs a one-sided Kolmogorov-Smirnov test (25) comparing the distribution of the waiting times recorded in the first and the second half of the acquisition window. If the cumulative distribution function in the second half is found to be larger than that in the first half, then the sensor has detected a gradient. Averaging the successful gradient detections over an ensemble ( $N = 1000$ ) of such ideal sensors provides an estimate of the sensory distance  $S$ , defined as the largest distance where at least a fraction  $f$  of the sensors has detected a gradient. The estimates of  $S$  can then be used to evaluate the chemotactic index  $I_c$ . Remarkably, we find that choosing a high consensus threshold  $f = 0.99$  provides close agreement with our theoretical calculations, both in terms of the shape of the detectability region and of the estimated  $I_c$  values. This fact highlights how the detection limits evaluated for bacterial chemosensing and the asymmetric nature of the chemotactic performance are not specific to bacteria, but can be used to describe a wide class of systems estimating gradients through temporal comparisons, independently of the particular signal processing mechanism and navigation parameters.

The physiological range of exudation rates for healthy phytoplankton cells lies across the boundary of chemotactic detection (Figure 5A), suggesting that chemotaxis might play a relevant role for encounters across the entire size spectrum. The physiology of marine phytoplankton enforces a specific coupling between size  $R$  and excess concentration  $C_s$ . Empirical carbon-size scaling laws predict that the carbon content of a cell scales with cell size as  $\sim R^{2.28}$  (26); the percent extracellular release (PER) then determines how much of this total content is leaked to the environment (SI). Average values of the PER are expected to be around 10%, but variations between values of PER  $\approx 2\%$  and 40% are typical and also strongly dependent on physiological and environmental conditions (27).

The steep size-structure of marine phytoplankton communities favors encounters with small phytoplankton cells. The average search time required by an individual bacterium to encounter a phytoplankton cell can be obtained as

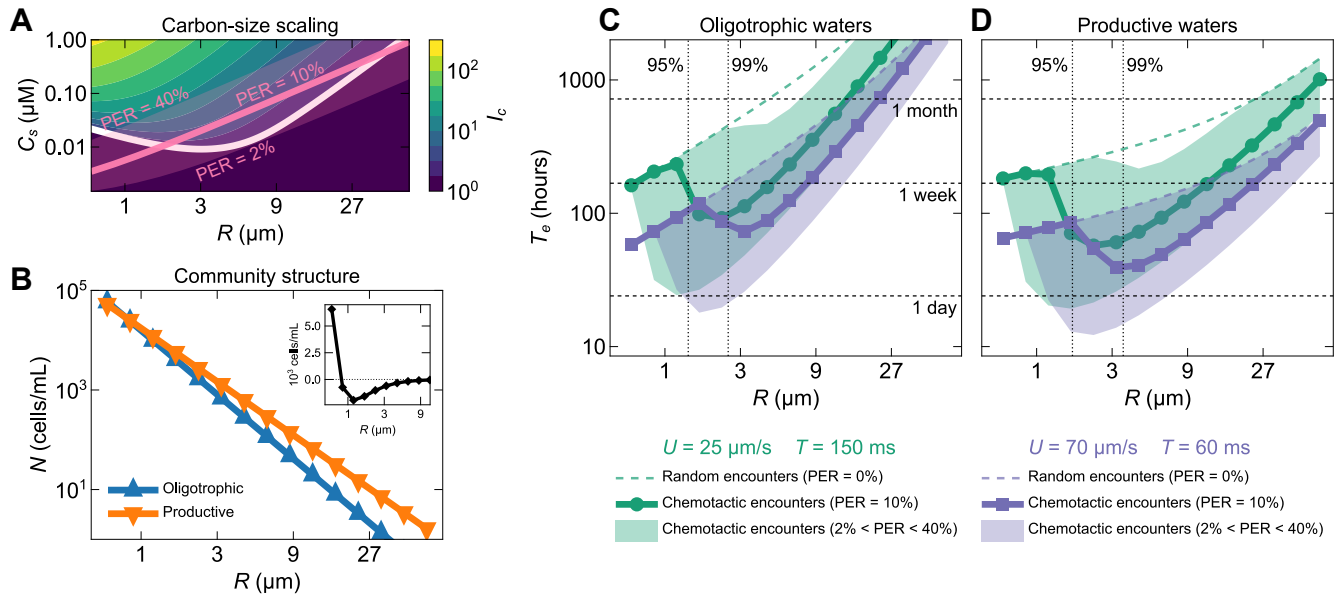
$$T_e = \frac{1}{I_c \Gamma N} \quad [5]$$

where  $N$  is the phytoplankton concentration, and  $\Gamma$  is the random encounter kernel, which represents the amount of volume swept, per unit time, by the motion of the bacterium relative to the phytoplankton cell (18, 28). Marine phytoplankton communities have characteristic size structures which usually follow a power-law size-abundance relationship of the form  $N(R) \propto R^{-3\alpha}$ , where the allometric exponent

$\alpha$  takes typical values  $\alpha \approx 0.9$  in oligotrophic waters and  $\alpha \approx 0.75$  in productive waters (17). Phytoplankton cells with smaller radii are therefore vastly more abundant than cells with larger radii, and particularly so in oligotrophic environments where large phytoplankters are extremely rare (Figure 5B). This steep size-structure allows bacterial search times for small phytoplankton cells to be much shorter than those for larger cells. The overabundance of small cells, combined with the asymmetric performance landscape of bacterial chemotaxis, further raises the stakes for chemotactic searches in the low end of the size spectrum.

Chemotaxis significantly reduces search times in the sub- $5\mu\text{m}$  range, but different chemotactic strategies can display substantial performance differences in the low end of the spectrum (Figure 5C–D). In the absence of chemotaxis, small phytoplankton cells require much shorter search times than large phytoplankton (Figure 5C–D, thin broken lines). In oligotrophic waters, a bacterium swimming randomly with speed  $25\mu\text{m s}^{-1}$  can encounter a phytoplankton of radius  $0.5 \sim 0.7\mu\text{m}$  roughly every week, while encountering a phytoplankton in the range  $24\text{--}33\mu\text{m}$  will require on average more than a month. In productive waters the search times for small cells are only slightly higher, whereas those for larger cells fall down below a month. Bacteria with a higher swimming speed of  $80\mu\text{m s}^{-1}$  reduce their random search times due to improved exploration efficiency, although that comes with a tradeoff in terms of chemotactic performance, as also shown in Figure 4B. The decreases in search times resulting from the use of chemotaxis, over the whole range of phytoplankton PER values, are shown as shaded bands in Figure 5C and D, with the thick marker-decorated line representing the typical value PER = 10%. Bacteria with lower speed but longer sensory timescales  $T$  can decrease their search times for the smallest phytoplankton almost by a factor 10, whereas the faster swimming bacteria with a shorter sensory timescale cannot benefit at all from chemotaxis at this extreme of the spectrum. While the major difference in the  $I_c$  between the two strategies is limited to the micron-size range, we stress that this region of the size-spectrum encloses the vast majority of the population. The 95th percentile of the populations (marked by the dotted vertical lines in the figures) is below the  $2\mu\text{m}$  radius, and, in both environments, more than half of the population is contained within the first size class. Therefore, losing the ability to increase encounters with the smallest cells in the spectrum can dramatically impact the dynamics and the fate of populations. We must also note that the boost in chemotactic performance towards small cells occurs only at high PER, while no gain can be obtained with intermediate PER values; for the larger ( $> 2\mu\text{m}$ ) radii, the reduction in search times is more robust and occurs also at lower PER values.

The chemotactic encounter problem can be seen as an evolutionary game with a strongly asymmetric fitness function. Interpreting  $I_c$  as a measure of the maximum possible fitness attainable by a bacterium, our results show that a perfect chemotaxer obtains large fitness benefits in the search for small phytoplankton cells, but relatively small ones when searching for large cells (Figure 3). We must keep in mind, however, that the encounter is only the initiating step of a possibly multi-stage interaction process and that fitness is determined by the ability to grow and reproduce. To obtain



**Fig. 5. The high-stakes nature of phytoplankton-bacteria interactions may promote a diversity of chemotactic strategies.** (A) Characteristic values of size and released chemoattractant for phytoplankton cells are constrained by carbon-size scaling laws (pink areas). When overlaid on the performance landscape of a bacterium (same as in Figure 3A), the physiological range of exudation rates lies across the boundary of detection. The thick pink line corresponds to phytoplankton cells with a percent extracellular release (PER) of 10%, the shaded pink band represents variations in the percent extracellular release between 2% (lower limit) and 50% (upper limit). (B) Marine phytoplankton communities are dominated by small cells. The size structure follows a power-law distribution, where the abundance  $N$  decreases with increasing size  $R$  as  $N(R) \propto R^{-3\alpha}$ . The allometric exponent is larger in oligotrophic waters ( $\alpha \simeq 0.9$ ) than in more productive waters ( $\alpha \simeq 0.75$ ). Both communities are normalized to a total cell abundance of  $1 \times 10^5$  cells/mL. Inset: difference between cell abundance in oligotrophic and productive waters. (C-D) Comparison of search times between random motility and chemotaxis. Carbon-size scaling, phytoplankton community structure and chemotactic index jointly define the average search time ( $T_e$ ) (Equation 5) an individual bacterium requires to encounter a phytoplankton cell using chemotaxis. The thin broken lines represent the search times in the absence of chemotaxis ( $I_c = 1$ ). The thick lines with markers indicate search times for phytoplankton cells with percent extracellular release of 10% (corresponding to the thick pink line in panel A), and the shaded bands represent variations in percent extracellular release between 2% and 50% (matching the pink shaded band in panel A). The two curves correspond to distinct chemotactic strategies: in green with circle markers, a strategy with low speed and long sensory timescale; in violet with square markers, a strategy with high swimming speed and short sensory timescale. The vertical dotted lines mark the radii corresponding to the 95<sup>th</sup> and 99<sup>th</sup> percentiles of the phytoplankton community abundance. A web app/notebook to interactively evaluate the search times for any set of parameters and community structures is freely available here: XXX.



a more complete eco-evolutionary picture, one would need to simultaneously consider the search time and the growth return associated with phytoplankton cells of different sizes. In fact, chemotaxis is expected to not only reduce search times but also improve the growth returns, allowing bacteria to remain near local maxima of chemoattractants even without a direct encounter (29). Indeed, Raina *et al.* (21) have shown that *Marinobacter adhaerens* can use chemotaxis to increase nutrient uptake from *Synechococcus* cells, and also increase the encounter rates with their phycosphere. Generally, it can be expected that larger sources, while offering less drastic enhancements in search times, may provide larger growth returns, but any further consideration on the growth returns should also include estimates of the energy expenditure associated with motility and chemotaxis (30, 31), and the fact that foraging efficiency is typically positively correlated with predation risk (32, 33).

Our results show that the limits of the chemotactic sensing of small phytoplankton cells are sensitive to the details of the sensing mechanism. Almost 40 years ago, Jackson concluded that the gradients around small prokaryotic cells could not be sensed by a swimming bacterium (20). Modern experimental efforts, such as the aforementioned *Marinobacter adhaerens*–*Synechococcus* interaction (21), or the recent investigation of the chemotactic response of marine heterotrophic bacteria to the exudates of virus-infected *Synechococcus* extending to distances larger than 100  $\mu\text{m}$  (34), strongly suggest that the limit calculated by Jackson is not universal (35). Our results confirm that micron-sized targets are, in principle, detectable, and thus chemotaxis can significantly reduce the search time in that size range (Figure 5). However, the exact position of the detection boundary is very sensitive to a large variety of parameters, such as swimming speed, size, leakage rates, molecular diffusivity, sensory timescales and chemotactic sensitivity (Figure 4). Consequently, while chemotaxis may be more pervasive than previously thought (35), outstanding questions related to its operational limits or its benefit to cell growth may need to be answered individually for each specific system. This sensitivity, combined with the high-stakes nature of the search problem, may, in turn, drive a diversity of chemotactic strategies.

More work is needed to evaluate how close to the predicted idealized chemotactic performance bacteria can operate. Agent-based simulations of bacterial chemotaxis towards leaky phytoplankton cells could help establish the distance to the idealized limit as a function of chemotactic strategy. Our work indicates that optimal strategies may depend on the phytoplankton cell size — strategies that work well for large cells will likely underperform for small ones and vice versa (Figure 5). Moreover, experiments designed to assess how far from a phytoplankton cell chemoattractants can be detected could aid in providing a stronger connection between the mathematical notion of “sensory horizon” (Figure 2), and the empirically grounded concept of phycosphere (6, 36, 37), the biochemically-rich microenvironment which surrounds phytoplankton cells.

Our analysis is based on several simplifying assumptions. Phytoplankton exudates typically vary in composition and abundance as a function of the organism’s physiological state and life stage (4, 6, 27); different chemoattractants (which we only considered through their diffusivity) are known to

elicit wildly different chemotactic responses, especially when multiple chemical species are simultaneously present (38, 39), and each of them may affect bacterial metabolism and behavior in different ways (40, 41). Metabolic shifts can in turn result in dramatic variations of the chemotactic sensitivity (42, 43), thus affecting the interaction rates with the phytoplankton cells and introducing feedback loops between behavior, physiology, and environment. All these factors and many others (fluid flows (44–47), predation (32), fluctuations from the scale of minutes, to days, to seasonal cycles (48–50)) contribute to shape the microscale interaction landscape of the ocean.

In conclusion, using idealized models of phytoplankton leakage and bacterial chemotaxis, we calculated upper bounds on the enhancement in bacteria-phytoplankton encounters driven by chemotaxis over random motility, and studied how sensitive the enhancement is to the size of phytoplankton. We found that bacterial chemotaxis offers low-risk/low-gain performance for searches of large phytoplankton but high-risk/high-gain performance for small phytoplankton. These tradeoffs arise from chemotactic encounters being limited by fundamentally different mechanisms at the two ends of phytoplankton size spectrum. For large cells, the limitation stems from gradients’ steepness and the diffusive nature of bacterial motility and leads to a moderate reduction in chemotactic search times. By contrast, for small phytoplankton, the limit is set by the gradients’ spatial confinement and ballistic motility of bacteria, which, in principle, allows for nearly ten-fold reductions in search times provided that bacteria can detect the gradients. We found that searching for small phytoplankton is more efficient when bacteria swim slower but integrate the gradients over longer sensory timescales. Overall, our results suggest that the high-stakes nature of encounters with small phytoplankton is a fundamental feature of chemotactic searches that may drive a diversity of size-sensitive chemotactic strategies.

## Author Affiliations.

## Digital Figures.

## Supporting Information Appendix (SI).

## Materials and Methods

All the data shown in this work has been generated through custom Julia () code; all the processed data and the scripts used to generate it are freely available at [zenodo](#) and [github](#) respectively. Project codes and data were managed with DrWatson.jl (), explicit simulations of molecular absorption events made use of Distributions.jl (), and HypothesisTests.jl () was employed to perform the Kolmogorov-Smirnov tests. Figures were realized with Makie.jl () and Inkscape ().

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