Numerical Linear Algebra: Exam#1

Due on October 1, 2022 at $5:00\mathrm{PM}$

Instructor: Professor Blake Barker Section 1

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Let $A \in \mathbb{R}^{2 \times 2}$ be a matrix that satisfies

$$\sup_{\left\Vert x\right\Vert _{2}=1}\left\Vert Ax\right\Vert _{2}=3,\quad\inf_{\left\Vert x\right\Vert _{2}=1}\left\Vert Ax\right\Vert _{2}=2.$$

What are the singular values of A?

Solution:

Proof. By Theorem 4.1, A has an SVD. Let it be represented in the standard way, $A = U\Sigma V^*$. By Theorem 3.1, for any $A \in \mathbb{C}^{m \times n}$ and unitary $Q \in \mathbb{C}^{m \times m}$, $\|QA\|_2 = \|A\|_2$. Thus, $\|A\|_2 = \|U\Sigma V^*\|_2 = \|\Sigma\|_2$. Using these relationships we find that

$$\dagger \quad 3 = \sup_{\|x\|_2 = 1} \|Ax\|_2 = \sup_{\|x\|_2 = 1} \|\Sigma x\|_2 = \sup_{\|x\|_2 = 1} \sqrt{(\sigma_1 x_1)^2 + (\sigma_2 x_2)^2}.$$

By convention, singular values are arranged such that $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_n$. Hence the quantity $\sqrt{(\sigma_1 x_1)^2 + (\sigma_2 x_2)^2}$ is maximized for $x = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$. But this means, completing the equalities in \dagger , we have

$$\sup_{\|x\|_{2}=1} \sqrt{(\sigma_{1}x_{1})^{2} + (\sigma_{2}x_{2})^{2}} = \sqrt{(\sigma_{1} \cdot 1)^{2} + (\sigma_{2} \cdot 0)^{2}} = \sigma_{1},$$

and thus, $\sigma_1 = 3$.

By similar logic, we have that $\sqrt{(\sigma_1 x_1)^2 + (\sigma_2 x_2)^2}$ is minimized for $x = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, and thus,

$$2 = \inf_{\|x\|_2 = 1} \|Ax\|_2 = \inf_{\|x\|_2 = 1} \|\Sigma x\|_2 = \inf_{\|x\|_2 = 1} \sqrt{(\sigma_1 x_1)^2 + (\sigma_2 x_2)^2} = \sqrt{(\sigma_1 \cdot 0)^2 + (\sigma_2 \cdot 1)^2} = \sigma_2.$$

Thus, the singular values of A are $\sigma_1 = 3$ and $\sigma_2 = 2$.

Suppose $A \in \mathbb{C}^{m \times m}$ has an SVD $A = U\Sigma V^*$. Find an eigenvalue decomposition (5.1) of the $2m \times 2m$ hermitian matrix

$$\begin{bmatrix} 0 & A^* \\ A & 0 \end{bmatrix}.$$

Solution:

Proof. I can't seem to figure this one out... I've tried a few things. The thing that seemed the most promising was observing that if $B = \begin{bmatrix} 0 & A^* \\ A & 0 \end{bmatrix}$, then

$$B^*B=BB^*=BB=\begin{bmatrix} V\Sigma^2V^* & 0 \\ 0 & U\Sigma^2U^* \end{bmatrix}=\begin{bmatrix} V & 0 \\ 0 & U \end{bmatrix}\begin{bmatrix} \Sigma^2 & 0 \\ 0 & \Sigma^2 \end{bmatrix}\begin{bmatrix} V^* & 0 \\ 0 & U^* \end{bmatrix}=Q\Sigma^2Q^*$$

In a typical SVD $Q = \begin{bmatrix} V & 0 \\ 0 & U \end{bmatrix} = U_B$ would form the right singular vectors and $V_B = Q^*$ the left singular vectors. However, I cannot verify this, unless it is the case that V = U in the SVD of A. If V = U, then

$$B = U_B \Sigma V_B^* = Q \Sigma Q^*$$

is an SVD of B. This would also be an eigenvalue decomposition of B.

We have studied the QR and SVD decompositions. This problem develops a variant of the QR decomposition, the QL decomposition. An $m \times m$ matrix of the form

$$K_m = \left[egin{array}{cccc} & & & & 1 \ & & & 1 \ & & & \ddots & & \ & 1 & & & \ & 1 & & & \ & 1 & & & \ \end{array}
ight] = \left[k_{ij}
ight],$$

where $k_{i,m-i+1} = 1$, $1 \le i \le m$, and all other entries are zero is termed a reversal matrix and sometimes the reverse identity matrix.

(a) Show that $K_m^2 = I$ (a very handy feature).

Proof. To avoid confusion in notation, for Part (a) we assume K is $m \times m$ and refer to the matrix K_m as K. Singular subscripts on K will refer to a columns of K, e.g., K_j is the j^{th} column of K. Double subscripts on K will refer to entries in K, i.e., K_{ij} is the ij-entry of K. With that out of the way, let $B = K^2$. Then by (1.6) from the text we have that the j^{th} column of B is

$$\star \quad b_j = \sum_{k=1}^m K_{kj} K_k,$$

that is, b_j is a linear combination of the columns of K whose coefficients are the j^{th} columns of K. But $K_{kj}=0$ unless k=m-j+1, in which case it equals 1. Thus, the formula \star selects the $(m-j+1)^{st}$ column of K_m for b_j . This selection effectively flips K_m across it's 'y-axis.' That is, $b_1=K_{m-1+1}=K_m, b_2=K_{m-2+1}=K_{m-2}, b_3=K_{m-3+1}=K_{m-2}, \ldots, b_m=K_{m-m+1}=K_1$. The result is that

$$K_m^2 = I$$
.

(b) If A is $m \times n$ matrix, $m \ge n$, what is the action of $K_m A$? What about AK_n ?

Solution: K_mA reflects A across it's 'x-axis.' This can be seen by considering the formula \star . The j^{th} column of K_mA is given by $\sum_{k=1}^m a_{kj}K_j$, where again, K_j refers to the j^{th} column of K_m . Since the K_j column only has a one in it's $(m-j+1)^{st}$ entry for $j=1,\ldots,m$, this selects $a_{(m-k+1)j}$, that is, $b_j=a_{(m-k+1)j}$ for $k=1,\ldots m$. As already stated, this is a reflection across A's 'x-axis.'

(c) If R is an upper triangular $n \times n$ matrix, what is the form of the product $K_n R K_n$?

Solution: As shown in Part (a), right multiplication by K_n results in a reflection of K_nR across it's 'y-axis.' Thus, in K_nRK_n , we have a reflection first across R's x-axis, then that result is reflected across it's y-axis.

(d) Let $AK_n = \hat{Q}\hat{R}$ be the reduced QR decomposition of AK_n , $m \ge n$. Show that $A = (\hat{Q}K_n)(K_n\hat{R}K_n)$, and from that deduce the decomposition

$$A = QL$$

where Q is an $m \times n$ matrix with orthogonal columns, and L is an $n \times n$ lower triangular matrix. This is a reduced QL decomposition.

Solution:

Proof. We are given $AK_n = \hat{Q}\hat{R}$. By Part (a), $K_n^2 = I$. Moreover, since $K_n^* = K_n$, K_n is unitary. Using these facts, we have

$$AK_n = \hat{Q}\hat{R}$$

$$AK_n^2 = \hat{Q}I\hat{R}K_n$$

$$A = \hat{Q}K_nK_n\hat{R}K_n$$

$$A = (\hat{Q}K_n)(K_n\hat{R}K_n)$$

By Part (c), $K_n \hat{R} K_n = L$ and by Part (a), $\hat{Q} K_n = Q$. Therefore,

$$A = (\hat{Q}K_n)(K_n\hat{R}K_n) = QL.$$

See attached code.

```
In []: # Import standard numeric and visualization libs
import numpy as np
import matplotlib.pyplot as plt

# Import my householder QR factorization implementation
# import sys
# sys.path.insert(0, "/home/masvgp/dev/byu_num_lin_alg_2022/src/")
# from factorizations.householder import house, formQ
```

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```
In [ ]: # My implementation of householder factorization and it's associated utility functi
        def e(i, length):
            """Generate a unit coordinate vector, i.e., Given an index i and a length, retu
            Args:
                i (int): Integer index in which 1.0 will be assigned
                length (int): Length of the desired output vector
            Returns:
                arr: Unit coordinate vector with 1.0 in the ith position
            e_i = np.zeros(length, dtype=np.float64)
            e_i[i] = 1.0
            return e i
        def reflector(v):
            """Given a unit vector v, return the householder reflector I - 2 * np.outer(v,
            Args:
                v (arr): Vector
            Returns:
                reflector (arr): A len(v) x len(v) array representing a householder reflect
            I = np.eye(len(v))
            outer = np.outer(v, v)
            return (I - 2 * outer)
        def house(A, reduced=False):
            """Compute the factor R of a QR factorization of an m 	imes n matrix A with m 	imes .
            Args:
                A (arr): A numpy array of shape m x n
            Returns:
                R (arr): The upper diagonal matrix R in a QR factorization
            m = A.shape[0] # Get row-dim of A
            n = A.shape[1] # Get col-dim of A
            W = np.zeros((m, n))
            \#Q = np.eye(m, m)
            \# V = np.zeros((m, n))
            # Cast A as type np.float64
            A = A.astype(np.float64)
            for k in range(n):
                # Get the first column of the (m-k+1, n-k+1) submatrix of A
                x = A[k:m, k]
                # Compute e_1, sign function, and the norm of x
                e_1 = e(0, len(x))
                sign = np.sign(x[0])
                norm_x = np.linalg.norm(x)
                # Compute vk, the vector reflected across the Householder hyperplane
```

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vk = (sign * norm_x * e_1) + x
        vk = vk / np.linalg.norm(vk)
        # Store vk in W
        W[k:m, k] = vk
        # Apply the reflector to the k:m, k:n submatrix of A to put
        # zeros below the diagonal of the kth column of A
        A[k:m, k:n] = reflector(vk) @ A[k:m, k:n]
    if reduced == True:
        # return np.around(A[:n, :n], decimals=8), W
        return A[:n, :n], W
    else:
        # Return full R
        return A, W
        # return np.around(A, decimals=8), W
def formQ(W, reduced=False):
    """Form Q from the lower diagonal vk's formed in the householder algorithm.
    Args:
        W (arr): An m x n matrix containing the vk in the kth column
    Returns:
        arr: Returns an m x m orthonormal matrix Q such that QR = A
    m = W.shape[0]
    n = W.shape[1]
    Q = np.eye(m, m)
    for k in range(n):
            Qk = np.eye(m, m)
            Qk[k:m, k:m] = reflector(W[k:m, k])
            Q = Q @ Qk
    if reduced == True:
        # Return reduced Q
        return Q[:m, :n]
        # return np.around(Q[:m, :n], decimals=8)
    else:
        # Return full Q
        return Q
        # return np.around(Q, decimals=6)
```

Use the result of Problem 3 to develop a Python function lq that takes as input a matrix A and returns Q and L where A=QL is a QL-decomposition, and test it with random matrices of sizes 10×7 and 75×50 . Organize your code in a single Python notebook and include it in the PDF you turn in. By test your code, I mean that you compute the QL decomposition, that you verify Q has orthonormal columns, you verify that L is lower triangular, and that you compute $\|A-QL\|_{2^t}$ where A is a random matrix for wich you

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```
In [ ]: def ql(A):
            """Compute the QL factorization of an m x n matrix A.
                A (arr): An m x n matrix
            Return:
                 Q (arr): a unitary matrix
                 L (arr): A lower triangular matrix
             # Get dims of A
            m = A.shape[0]
            n = A.shape[1]
            # Define the reversal matrix K n
            Kn = np.flip(np.eye(n), axis=0)
             # Compute reduced QR(AK_n) - \hat{Q} is m x n, \hat{R} is n x n.
             Rhat, W = house(A @ Kn, reduced=True)
             Qhat = formQ(W, reduced=True)
             # Compute Q = \hat{Q}K_n
             Q = Qhat @ Kn
             \# Compute L = K_n \setminus \{R\} K_n
             L = Kn @ Rhat @ Kn
             # return Q, L
             return Q, L
```

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Testing

- 1. Define matrices A and B of size 10×7 and 75×50 , respectively. Then do the following:
- 2. Compute QL(A) and QL(B)
- 3. Verify that Q has orthonormal columns
- 4. Verify that ${\cal L}$ is lower triangular
- 5. Compute $\parallel A-QL\parallel_2$ and $\parallel B-QL\parallel_2$, where A and B are the random matrices defined in (1).

Testing for the 10 imes 7 random matrix a

```
In []: # 1. Define random matrix of size 10 x 7
A = np.random.normal(loc=0.0, scale=1.0, size=(10, 7))
In []: # 2. Compute $QL(A)$
QA, LA = ql(A)
```

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```
In [ ]: # 3. Verify that $Q$ has orthonormal columns
        # Compute QA.T @ QA
        QATQA = QA \cdot T @ QA
        # Check the diagonals are 1.0
        print(f"The dimensions of $QA.T @ QA are: {QATQA.shape[0]} x {QATQA.shape[1]}")
        print(f"Check that the diagonal entries of QA.T @ QA sum to {QATQA.shape[0]} by che
        # Set diagonal entries to 0.0
        for i in range(QATQA.shape[0]):
            QATQA[i, i] = 0.0
        # Compute the max absolute value of the the array QATQA with diagonal set to 0.0.
        print("Check the max absolute value of the array after setting the diagonal entries
        The dimensions of QA.T @ QA are: 7 \times 7
        Check that the diagonal entries of QA.T @ QA sum to 7 by checking the sum of the di
        agonal entries.
        The sum is equal to 7: True
        Check the max absolute value of the array after setting the diagonal entries to 0.
        This effectively checks the max absolute value of the off-diagonal entries.
        The max absolute value of the resulting array is: 3.2963142379103426e-16
In [ ]: # 4. Verify that $L$ is lower triangular
        # Extract upper diagonal part of L
        LA_upper_diag = [LA[i, j] for i in range(LA.shape[0]) for j in range(LA.shape[1]) i
        # Extract the lower diagonal part of L
        LA_lower_diag = [LA[i, j] for i in range(LA.shape[0]) for j in range(LA.shape[1]) i
        print("The max absolute value of the upper diagonal entries of LA is: " + str(np.ma
        print("The max absolute value of the lower diagonal entries of LA is: \n" + str(np.
        The max absolute value of the upper diagonal entries of LA is: 4.2312988466972233e-
        The max absolute value of the lower diagonal entries of LA is:
        3.0734874283890266
In [ ]: # 5. Compute $\begin{Vmatrix} A - QL \end{Vmatrix}_2$, where $A$ is the random matr
        print("The L2-norm of A - QL is: " + str(np.linalg.norm(A - QA @ LA)))
        The L2-norm of A - QL is: 3.831465111543962e-15
        Testing for the 75 \times 50 random matrix B.
In [ ]: # 1. Define random matrix of size 75 x 50
        B = np.random.normal(loc=0.0, scale=1.0, size=(75, 50))
In [ ]: # Compute QL for the 75 x 50 matrix B
        QB, LB = q1(B)
```

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```
In [ ]: # 3. Verify that $Q$ has orthonormal columns
        # Compute QA.T @ QA
        QBTQB = QB.T @ QB
        # Check the diagonals are 1.0
        print(f"The dimensions of $QB.T @ QB are: {QBTQB.shape[0]} x {QBTQB.shape[1]}")
        print(f"Check that the diagonal entries of QB.T @ QB sum to {QBTQB.shape[0]} by che
        # Set diagonal entries to 0.0
        for i in range(QBTQB.shape[0]):
            QBTQB[i, i] = 0.0
        # Compute the max absolute value of the the array QATQA with diagonal set to 0.0.
        print("Check the max absolute value of the array after setting the diagonal entries
        The dimensions of $QB.T @ QB are: 50 x 50
        Check that the diagonal entries of QB.T @ QB sum to 50 by checking the sum of the d
        iagonal entries.
        The sum is equal to 50: True
        Check the max absolute value of the array after setting the diagonal entries to 0.
        This effectively checks the max absolute value of the off-diagonal entries.
        The max absolute value of the resulting array is: 8.721678135614107e-16
In [ ]: # 4. Verify that $L$ is lower triangular
        # Extract upper diagonal part of L
        LB_upper_diag = [LB[i, j] for i in range(LB.shape[0]) for j in range(LB.shape[1]) i
        # Extract the lower diagonal part of L
        LB_lower_diag = [LB[i, j] for i in range(LB.shape[0]) for j in range(LB.shape[1]) i
        print("The max absolute value of the upper diagonal entries of LB is: " + str(np.ma
        print("The max absolute value of the lower diagonal entries of LB is: \n" + str(np.
        The max absolute value of the upper diagonal entries of LB is: 2.9251450570491478e-
        15
        The max absolute value of the lower diagonal entries of LB is:
        9.757443792666914
In [ ]: # 5. Compute $\begin{Vmatrix} B - QL \end{Vmatrix}_2$ where $B$ is the random matri
        print("The L2-norm of B - QL is: " + str(np.linalg.norm(B - QB @ LB)))
        The L2-norm of B - QL is: 1.0843623836693697e-13
```

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