householder

September 21, 2022

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[]: import numpy as np
[]: def e(i, length):
          # Given a position and a length, return a vector with a 1.0 in the ith_{\sqcup}
       ⇔position and 0.0 else.
         e_i = np.zeros(length, dtype=np.float64)
         e_i[i] = 1.0
         return e_i
[]: def reflector(v):
          """Given a unit vector v, return the householder reflector I - 2 * np.
       \hookrightarrow outer(v, v)
         Args:
              v (arr): Vector
         Returns:
              reflector (arr): A len(v) x len(v) array representing a householder_{\sqcup}
       \hookrightarrow reflector
          11 11 11
         I = np.eye(len(v))
         outer = np.outer(v, v)
         return (I - 2 * outer)
[]: def formQ(W):
              """Form Q from the lower diagonal vk's formed in the householder_{\sqcup}
       \hookrightarrow algorithm.
              Args:
                   W (arr): An m x n matrix containing the vk in the kth column
              Returns:
                  arr: Returns an m x m orthonormal matrix Q such that QR = A
              m = W.shape[0]
              n = W.shape[1]
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[]: def house(A):
         """Compute the factor R of a QR factorization of an m x n matrix A with m_{\! \sqcup}
      ⇔>= .
         Args:
             A (arr): A numpy array of shape m \times n
         Returns:
             R (arr): The upper diagonal matrix R in a QR factorization
         m = A.shape[0] # Get row-dim of A
         n = A.shape[1] # Get col-dim of A
         W = np.zeros((m, n))
         \#Q = np.eye(m, m)
         \# V = np.zeros((m, n))
         # Cast A as type np.float64
         A = A.astype(np.float64)
         for k in range(n):
             # Get the first column of the (m-k+1, n-k+1) submatrix of A
             x = A[k:m, k]
             \# Compute e_1, sign function, and the norm of x
             e_1 = e(0, len(x))
             sign = np.sign(x[0])
             norm_x = np.linalg.norm(x)
             # Compute vk, the vector reflected across the Householder hyperplane
             vk = (sign * norm_x * e_1) + x
             vk = vk / np.linalg.norm(vk)
             # Store vk in W
             W[k:m, k] = vk
             # Apply the reflector to the k:m, k:n submatrix of A to put
             # zeros below the diagonal of the kth column of A
             A[k:m, k:n] = reflector(vk) @ A[k:m, k:n]
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return np.around(A, decimals=6), W
[]: A = np.array([[1, 2, 1], [4, 5, 6], [6, 9, 8]])
[]: R, W = house(A)
    print("R: \n" + str(R))
   R:
    [ -0.
                 1.00939 -0.672927]
    [ -0.
                  0.
                            0. ]]
[]: Q = formQ(W)
    print("Q: \n" + str(Q))
    Q:
    [[-0.137361 0.560772 0.816497]
     [-0.549442 -0.729004 0.408248]
     [-0.824163 0.392541 -0.408248]]
[]: np.linalg.qr(A)
[]: (array([[-0.13736056, 0.56077215, -0.81649658],
            [-0.54944226, -0.7290038, -0.40824829],
            [-0.82416338, 0.39254051, 0.40824829]]),
     array([[-7.28010989e+00, -1.04394029e+01, -1.00273212e+01],
            [ 0.00000000e+00, 1.00938988e+00, -6.72926585e-01],
            [ 0.0000000e+00, 0.0000000e+00, -6.16000306e-15]]))
[]: B = np.array([[2, 3, 4], [5, 6, 7], [8, 9, 10]])
    print(B)
    [[2 3 4]
     [5 6 7]
    [8 9 10]]
[]: R, W = house(B)
    print("R: \n" + str(R))
    R:
    [[ -9.643651 -11.199078 -12.754506]
    [ 0.
                 0.762001 1.524002]
    [ 0.
                 -0.
                           -0.
                                   ]]
[]: Q = formQ(W)
    print("Q: \n" + str(Q))
```

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Q:
    [[-0.20739
                0.889001 -0.408248]
     [-0.518476 0.254
                          0.816497]
     [-0.829561 -0.381
                         -0.408248]]
[]: np.linalg.qr(B)
[]: (array([[-0.20739034, 0.88900089, 0.40824829],
            [-0.51847585, 0.25400025, -0.81649658],
            [-0.82956136, -0.38100038, 0.40824829]])
     array([[-9.64365076e+00, -1.11990783e+01, -1.27545058e+01],
            [ 0.00000000e+00, 7.62000762e-01, 1.52400152e+00],
            [ 0.00000000e+00, 0.0000000e+00, 1.11022302e-15]]))
[]: C = np.array([[1, 2], [3, 4], [5, 6]])
    R, W = house(C)
    print("R: \n" + str(R))
    R:
    [[-5.91608 -7.437357]
     [-0.
                0.828079]
     [ 0.
               -0.
                        11
[]: Q = formQ(W)
    print("Q: \n" + str(Q))
    Q:
    [[-0.169031 0.897085 0.408248]
     [-0.507093 0.276026 -0.816497]
     [-0.845154 -0.345033 0.408248]]
[]: np.linalg.qr(C)
[]: (array([[-0.16903085, 0.89708523],
            [-0.50709255, 0.27602622],
            [-0.84515425, -0.34503278]]),
     array([[-5.91607978, -7.43735744],
            [ 0.
                       , 0.82807867]]))
[]:
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