

11.1

Suppose the $m \times n$ matrix A has the form

$$A = \begin{bmatrix} A_1 \\ A_2 \end{bmatrix}$$

where A_1 is a nonsingular matrix of dimension $n \times n$ and A_2 is an arbitrary matrix of dimension $(m-n) \times n$. Prove that $\|A^+\|_2 \leq \|A_1^{-1}\|_2$.

Proof: By definition, $A^+ = (A^*A)^{-1}A^*$. The matrix A has SVD $A = U\Sigma V^*$. Thus we may write

$$A^+ = [(U\Sigma V^*)^*(U\Sigma V^*)]^{-1}A^*$$

$$= [V\Sigma\Sigma V^*]^{-1}(V\Sigma U^*)$$

$$= V^{-*}\Sigma^{-1}\Sigma^{-1}V^{-1}V\Sigma U^* \leftarrow \text{since } V \text{ \& } \Sigma \text{ are invertible, and the product } V\Sigma\Sigma^+ \text{ is invertible.}$$

$$= V^{-*}\Sigma^{-1}U^*$$

$$= V\Sigma^{-1}U^{-1}$$

$$= (U\Sigma V^*)^{-1}$$

$$\leq A_1^{-1}$$

\leftarrow since V \& U are unitary

Thus, we have $\|A^+\|_2 \leq \|A_1^{-1}\|_2$. Since A is $m \times n$ with A_1 full rank, $(U\Sigma V^*)^{-1}$ not only construct A_1^{-1} , otherwise it would not be invertible.

11.2

In [121...

```
import sys
sys.path.insert(0, "/home/masvgp/dev/byu_num_lin_alg_2022/src/")

import numpy as np
import scipy as sp
import matplotlib.pyplot as plt
from factorizations.householder import house, formQ
```

In [122...

```
def lsqr(A, b):  
    """Solve the least squares problem given a linear system  $Ax = b$  with  $A$   $m \times n$ ,  $m$   
  
    Args:  
        A (arr): An  $m \times n$  matrix  $A$  with  $m > n$   
        b (arr): A vector of length  $m$   
    Returns:  
        x (arr): The optimal solution vector  $x$   
    """  
    # Get dim(A)  
    m = A.shape[0]  
    n = A.shape[1]  
  
    # Check if A has  $m > n$   
    if m <= n:  
        raise ValueError("A is not of appropriate dimensions. Should be  $m \times n$ ,  $m >$   
    # Check that A and b have same number of rows.  
    if len(b) != len(A):  
        raise ValueError("Number of rows of A must match number of rows of b.")  
  
    # Cast A as type np.float64  
    A = A.astype(np.float64)  
  
    # Compute the full QR factorization of A  
    R, W = house(A)  
    Q = formQ(W)  
  
    # Get the reduced QR factorization of A from the full factorization  
    # And ditch the 0 rows of R  
    R_hat = R[:n, :n]  
    Q_hat = Q[:m, :n]  
  
    # Compute  $Q^*b$   
    Q_hat_star_b = np.array(np.asmatrix(Q_hat).H) @ b  
  
    # Solve upper-triangular  $R\_hat x = Q\_hat\_star\_b$  for  $x$ . In this case, I will use  
    # To solve the system  
    # x_result = gauss_seidel(R_hat, Q_hat_star_b, x_start=np.zeros(len(Q_hat_star_  
    x_hat = np.linalg.solve(R_hat, Q_hat_star_b)  
  
    # Compute ssd  
    ssr = np.linalg.norm(A @ x_hat - b)  
  
    return (A @ x_hat), x_hat, ssr
```

11.2 (a)

Suppose we want to estimate via least squares $y = f(x) = 1/x$ on the interval $[1, 2]$ using a linear combination of e^x , $\sin x$, and $\Gamma(x)$. Then we can form a design matrix containing samples of these functions as columns, that is, we may form the matrix $X = [e^x | \sin x | \Gamma(x)]$ such that x consists of linearly spaced points in the interval $[1, 2]$. Then we may define the $y = Xx$. We solve this using least squares to find the optimal estimate \hat{y} corresponding to the solution \hat{x} of the system of equations. With a sum of squared error close to 0, the fit appears to be very good.

```
In [123... x = np.linspace(1, 2, 20)
y = 1/x

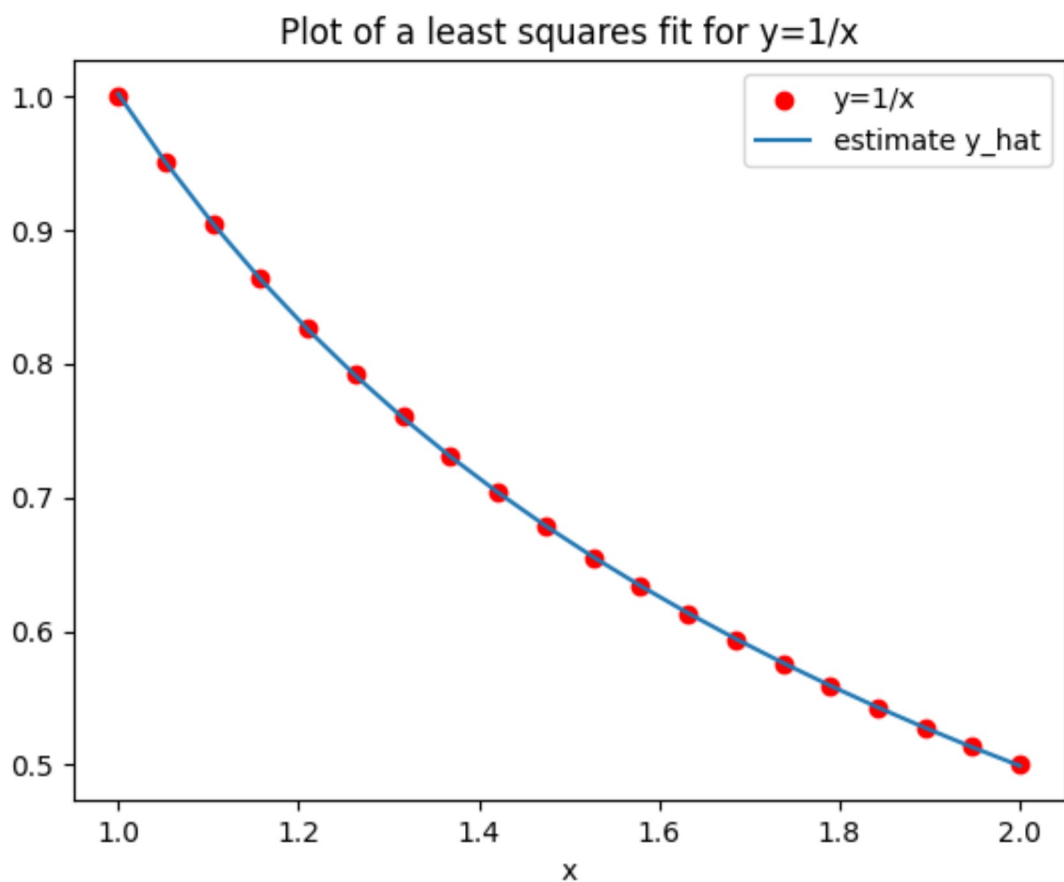
In [124... e = np.exp(x)
sin_x = np.sin(x)
gamma = sp.special.gamma(x)
X = np.array([e, sin_x, gamma]).T

In [125... y_hat, x_hat, ssr = lsqr(X, y)

In [126... print("y_hat: " + str(b_hat))
print("x_hat: " + str(x_hat))
print("Sum of squared errors: " + str(ssr))

y_hat: [0.66666763 1.83333377 3.16666903 3.99999986]
x_hat: [-0.10769069 0.01013855 1.28575148]
Sum of squared errors: 0.0027912911180240853

In [127... # Plot the results
plt.scatter(x, y, color='red', label='y=1/x')
plt.plot(x, y_hat, label='estimate y_hat')
plt.xlabel("x")
plt.legend()
plt.title("Plot of a least squares fit for y=1/x")
plt.show()
```



11.2 (b)

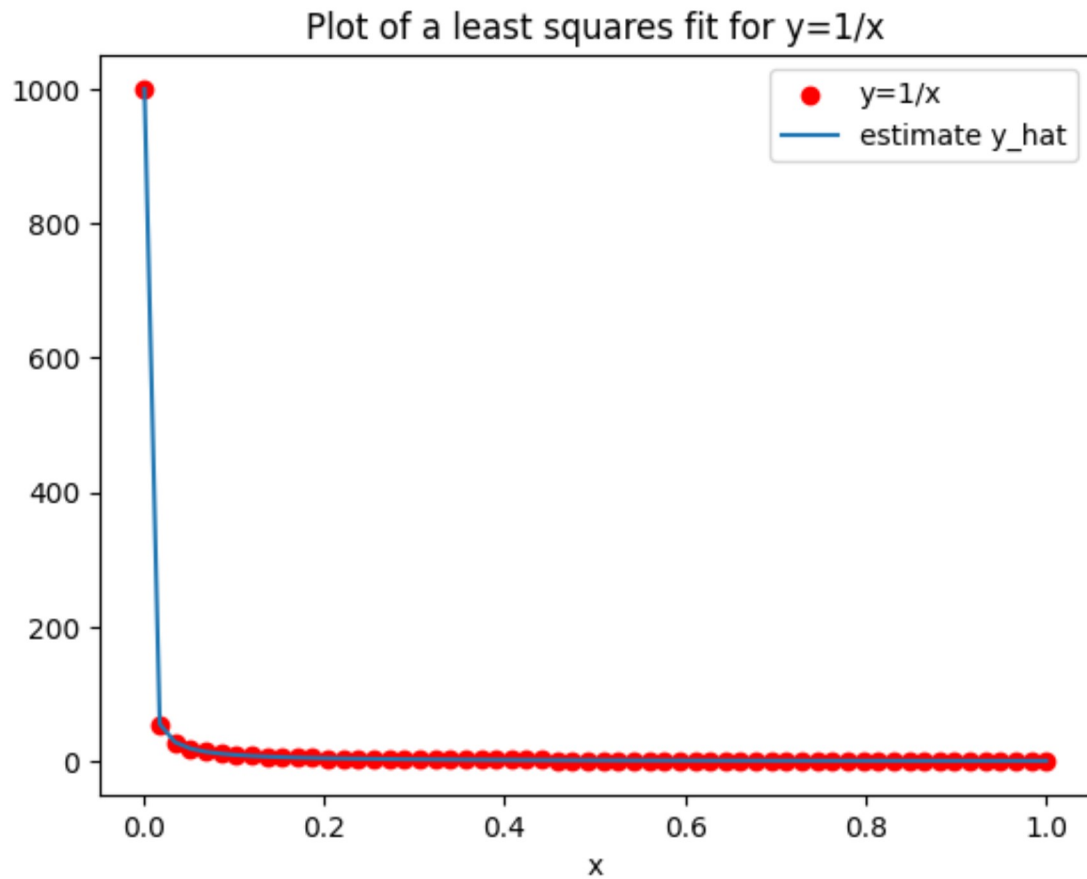
```
In [128... x = np.linspace(0.001, 1, 60)
y = 1/x
e = np.exp(x)
sin_x = np.sin(x)
gamma = sp.special.gamma(x)
X = np.array([e, sin_x, gamma]).T
```

```
In [129... y_hat, x_hat, ssr = lsqr(X, y)
```

```
In [130... print("y_hat: " + str(b_hat))
print("x_hat: " + str(x_hat))
print("Sum of squared errors: " + str(ssr))
```

```
y_hat: [0.66666763 1.83333377 3.16666903 3.99999986]
x_hat: [ 0.63101588 -1.838535  0.99994246]
Sum of squared errors: 0.4561267020208506
```

```
In [131... # Plot the results
plt.scatter(x, y, color='red', label='y=1/x')
plt.plot(x, y_hat, label='estimate y_hat')
plt.xlabel("x")
plt.legend()
plt.title("Plot of a least squares fit for y=1/x")
plt.show()
```



```
In [132... # Intial test of lsqr function
A = np.array([[1, 2, 1], [4, 5, 6], [6, 9, 8], [5, 4, 3]])
b = np.array([1, 2, 3, 4])
b_hat, x_hat, ssr = lsqr(A, b)
print("b_hat: " + str(b_hat))
print("x_hat: " + str(x_hat))
print("Sum of squared errors: " + str(ssr))

b_hat: [0.66666763 1.83333377 3.16666903 3.99999986]
x_hat: [ 1.01851794  0.01851945 -0.3888892 ]
Sum of squared errors: 0.4082482904720687
```

In []: