ch 4

September 9, 2022

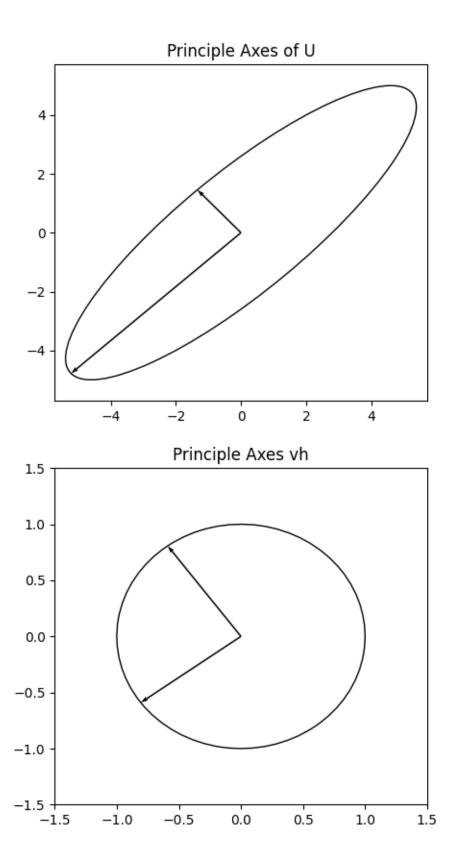
```
[80]: import numpy as np
       import matplotlib.pyplot as plt
       from matplotlib.patches import Ellipse
  [ ]: def plot_origin(matrix):
           return(np.zeros(len(matrix)))
[256]: def angle(p_vec, x = None):
           """Computes the angle that the principle axis in an ellipse makes relative\sqcup
        \Rightarrowto another vector x (x=(1, 0)* is default), i.e., the rotation angle of the
        \hookrightarrow ellipse.
           Args:
               p\_vec (arr): a numpy vector giving the direction of the principle axis\sqcup
        \hookrightarrow of the ellipse
           n n n
           # # If the vector is in Q3, reflect to Q1
           if ((p_{vec}[0] < 0)) and (p_{vec}[1] < 0):
               p_{vec} = -1 * p_{vec}
           # If the vector is in Q4, reflect to Q2
           if ((p_{vec}[0] > 0)) and (p_{vec}[1] < 0):
               p_{vec} = -1 * p_{vec}
           x = np.array([1, 0]) # Set default comparison vector as x-axis
           inner = p vec @ x # Compute inner product
           norms = np.linalg.norm(p_vec) * np.linalg.norm(x) # Compute norms
           cos = inner / norms # Compute cos of angle between x and p_vec
           return np.arccos(np.clip(cos, -1.0, 1.0))
[257]: # Test ellipse_angle function
       print(angle(np.array([1, -1])))
       print(angle(np.array([-1, -1])))
       print(angle(np.array([-1, 1])))
       print(angle(np.array([1, 1])))
       print(angle(np.array([0, 1])))
       print(angle(np.array([1, 0])))
```

```
print(angle(np.array([-1, 0])))
       print(angle(np.array([0, -1])))
      2.356194490192345
      0.7853981633974484
      2.356194490192345
      0.7853981633974484
      1.5707963267948966
      0.0
      3.141592653589793
      1.5707963267948966
[328]: def plot_svd(A):
           """Function takes a 2x2 matrix A, computes the SVD of A, and then plots the \Box
        \negvectors u_1, u_2, v_1, and v_2 along with the appropriate ellipse for the \sqcup
        ⇔underlying space.
           Arqs:
               A (arr): 2 x 2 array of floats
           # Check that the provided matrix is 2 x 2 or less and complain if it is not
           assert len(A) <= 2</pre>
           # Compute the SVD of the matrix A and store the results
           u, sig, vh = np.linalg.svd(A)
           # Compute U from u
           U = np.zeros((len(A), len(A)))
           U[:, 0] = sig[0] * u[:, 0]
           U[:, 1] = sig[1] * u[:, 1]
           # Define origin for U and vh vectors
           U_origin = np.zeros((len(U), len(U)))
           vh_origin = np.zeros((len(vh), len(vh)))
           # Define angles of principle axes for U and vh
           U angle = angle(U[:, 0])
           vh_angle = angle(vh[:, 0])
           # Define plot canvas
           fig, ax = plt.subplots(2, 1, figsize=(5, 10))
           # Set axis limits
           U_{lim} = max([np.abs(U[0, 0]), np.abs(U[1, 0])])
           vh_lim = 1
           ax[0].set_xlim(-U_lim - 0.5, U_lim + 0.5)
           ax[0].set_ylim(-U_lim - 0.5, U_lim + 0.5)
```

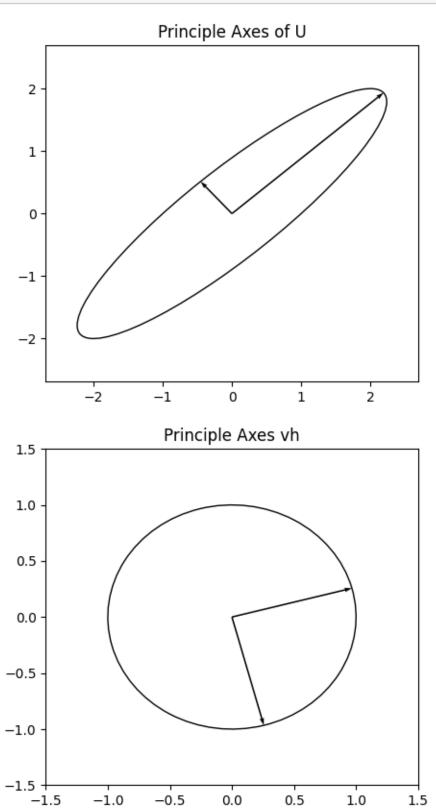
```
ax[1].set_xlim(-vh_lim - 0.5, vh_lim + 0.5)
  ax[1].set_ylim(-vh_lim - 0.5, vh_lim + 0.5)
  # Define plot Titles
  ax[0].set_title("Principle Axes of U")
  ax[1].set_title("Principle Axes vh")
  # Plot vectors
  ax[0].quiver(*U_origin, U[0, :], U[1, :], angles='xy', scale_units='xy',_u
⇒scale=1, width=.004)
  ax[1].quiver(*vh_origin, vh[0, :], vh[1, :], angles='xy', scale_units='xy',
⇒scale=1, width=.004)
  # Plot ellipses
  U_ellipse = Ellipse(
      (0, 0),
      width=2 * sig[0],
      height=2 * sig[1],
      angle=U_angle * (180/np.pi),
      zorder=0,
      fill=False
  )
  ax[0].add_patch(U_ellipse)
  vh_ellipse = Ellipse(
      (0, 0),
      width=2,
      height=2,
      angle=vh_angle * (180/np.pi),
      zorder=0,
      fill=False
  ax[1].add_patch(vh_ellipse)
  plt.show()
  #return U, vh
```

```
[326]: A = np.array([[5, 2], [3, 4]])

[329]: plot_svd(A)
```



[331]: A_37 = np.array([[1, 2], [0, 2]])
plot_svd(A_37)



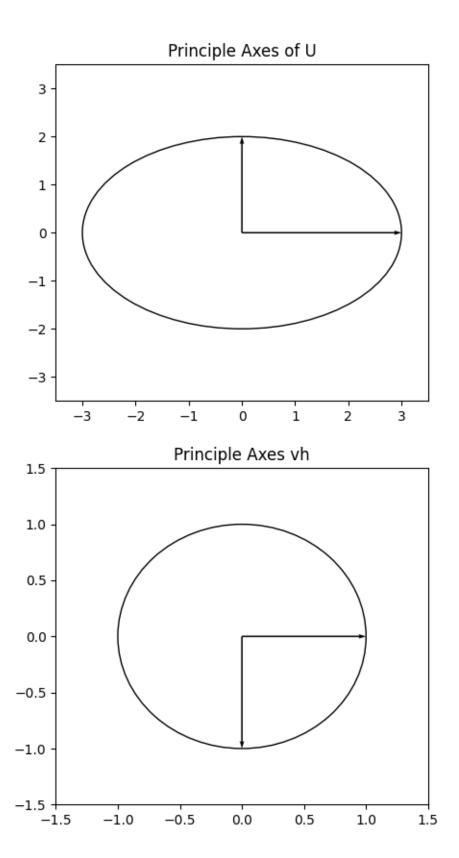
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[332]: A_41_a = np.array([[3, 0], [0, -2]])

A_41_b = np.array([[2, 0], [0, 3]])

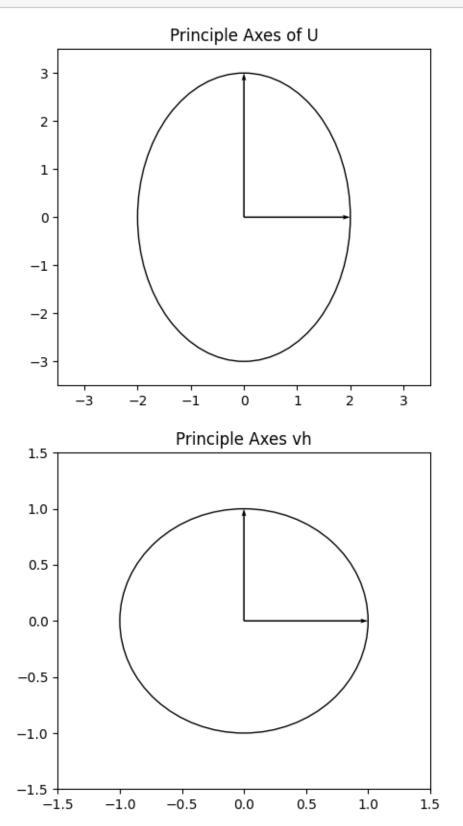
A_41_d = np.array([[1, 1], [0, 0]])

A_41_e = np.array([[1, 1], [1, 1]])
```

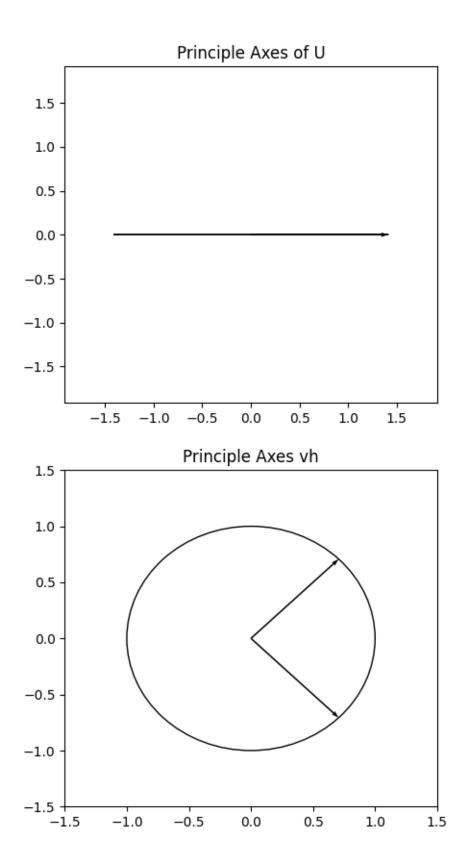
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[333]: plot_svd(A_41_a)
```



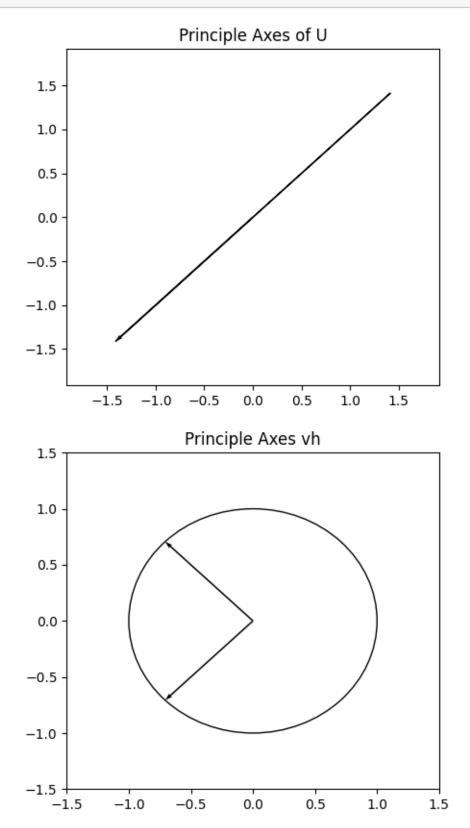
[334]: plot_svd(A_41_b)



[335]: plot_svd(A_41_d)



[336]: plot_svd(A_41_e)



[]:[