Facial Emotion Recognition with Convolutional Neural Networks

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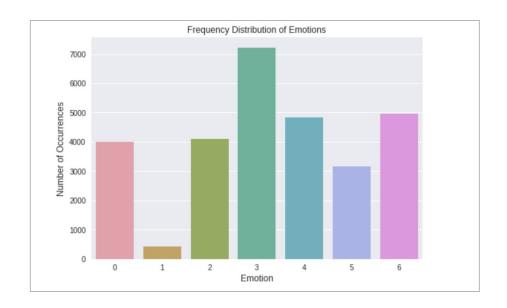
Background

- Automatic Facial Emotion Recognition (FER)
 - Human Computer Interaction
 - Virtual Reality
 - Augmented Reality
 - Driver Assistant Systems
 - Entertainment
- Find more efficient and smooth connections between humans and machines



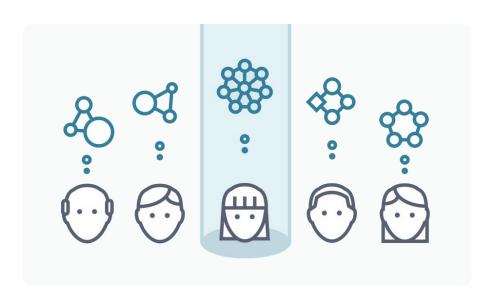
Dataset

- FER2013 Dataset
 - 35887 sample images
 - Seven labels
 - 1. Anger
 - 2. Disgust
 - 3. Fear
 - 4. Happy
 - 5. Sad
 - 6. Surprise
 - 7. Neutral



Past Results with FER2013

- Kaggle Competition
 - Challenges in Representation Learning: Facial Expression Recognition Challenge (2013)
 - Top accuracy ~ 0.71
- Github Paper
 - Used Sequential CNN and Xception inspired architectures
 - Accuracy ~ 0.66



Difficulties

- FER has many challenges
 - Non-uniform nature of human face
 - Limitations due to
 - Lighting
 - Face orientation
 - Shadows
- Nature of facial expressions
 - Subtle movements
- Need accurate and robust models
 - Deep learning can help achieve this



Implementations

- Visual Geometry Group (VGG)
- Residual Neural
 Network (ResNet)
- Self-created model



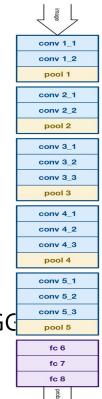
VGG (2014)

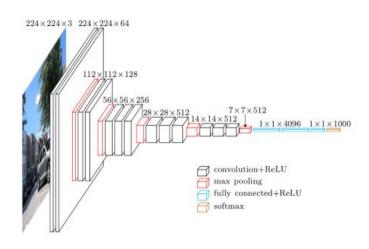
- Developed by Oxford University's Visual Geometry Group (VGG)
- Created model for ImageNet competition
 - Placed second for classification
- Wanted to see how ConvNet depth affects accuracy
- Best performing models
 - VGG16
 - VGG19



Architecture

- VGG Block
 - Convolution Layer
 - Nonlinearity
 - Maximum Pooling
- Kernel Size
 - 3x3 used in each Convolution
- Pooling Size
 - o 2x2 with stride of 2 in each Pool
- Different implementations of VGC





VGG Implementations

- Implemented VGG11 and VGG16
 - Tested batch sizes of 32, 64, and 128 for each
- Tested Dropout with VGG11
 - More Dropout
 - 50% dropout after every layer
 - Less Dropout
 - 50% dropout after every other layer



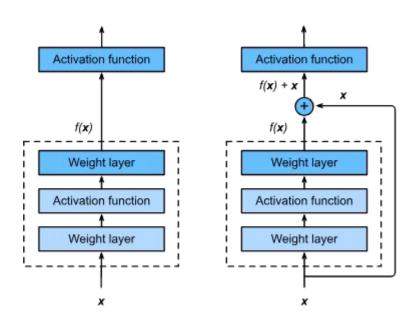
Resnet (2015)

- Developed by Microsoft Research
- Placed first in ImageNet 2015 competition for classification
 - Achieved error of .357
- Introduced deep residual learning framework
 - Eases training of deep networks
- Combats increasing depth problem



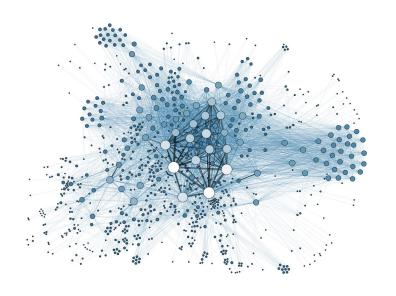
Architecture

- Idea: Allow information to easily propagate through the network
- Residual Blocks
 - Convolution Layer
 - Batch Normalization
 - Nonlinearity
 - Skip Connection
- Kernel Size
 - Uses VGG's 3x3 design



Resnet Implementation

- Implemented ResNet50, ResNet18, and ResNet10*
 - Tested batch sizes of 32, 64, and 128 for each
 - Tested Adam and RMSProp optimizers for each
- ResNet10 was an attempt to simplify the larger architectures
 - Used half the blocks of ResNet18



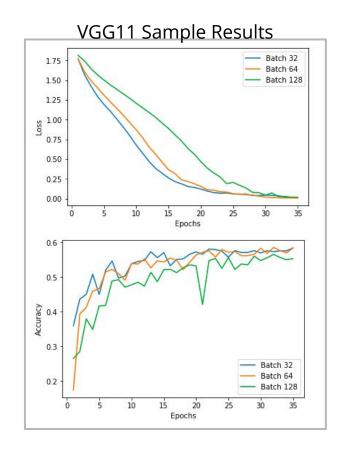
Our Model Architecture

- Followed the VGG Block architecture
 - Added Batch Normalization after each layer
 - Increase number of filters in each block
 - Number of filters: 3,5,7
- Added an attention component
 - Tells model what areas of the image are more important



VGG Results

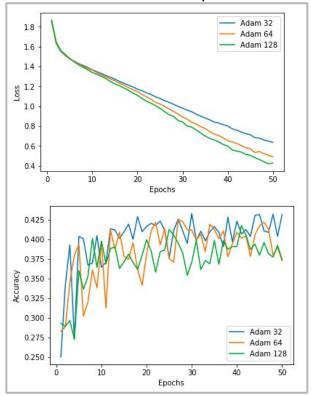
- VGG11
 - Batch size of 64 had best performance
 - Test accuracy of 58.9%
- VGG16
 - Batch size of 32 had the best performance
 - Test accuracy of 57.8%
- VGG11 with More Dropout
 - Test accuracy of 38%
- VGG11 with Less Dropout
 - Test accuracy of 58.7%



ResNet Results

- ResNet50 and ResNet18
 - Accuracies were low for both Adam and RMSProp optimizers
 - No accuracy above 25%
- Modified ResNet (10 Layers)
 - Best performance was with batch size
 32 and Adam optimizer
 - Accuracy of 43.2%

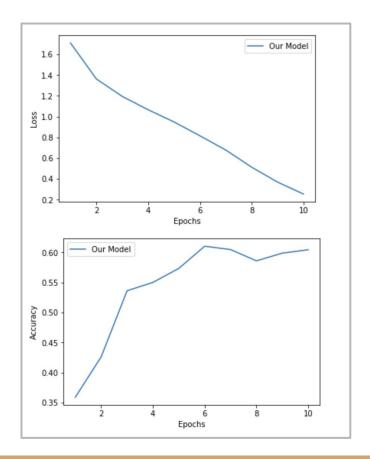
Modifed ResNet Sample Results



Our Model Results

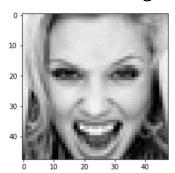
- Batch size of 64 with an Adam optimizer
 - Test Accuracy of 61.4%
- Best performance on Happy (3) and Surprise (5)

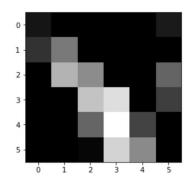
	precision	recall	f1-score	support
0	0.68	0.41	0.51	958
1	0.79	0.49	0.60	111
2	0.41	0.54	0.47	1024
3	0.84	0.81	0.82	1774
4	0.45	0.57	0.50	1247
5	0.83	0.65	0.73	831
6	0.58	0.58	0.58	1233

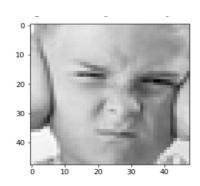


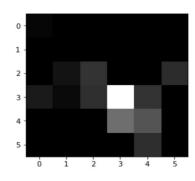
Attention Areas

Anger Attention

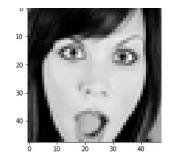


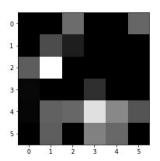




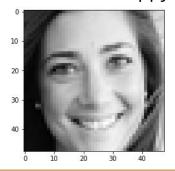


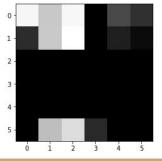
Surprise Attention





Happy Attention





Demo