

Introduction to Data Mining

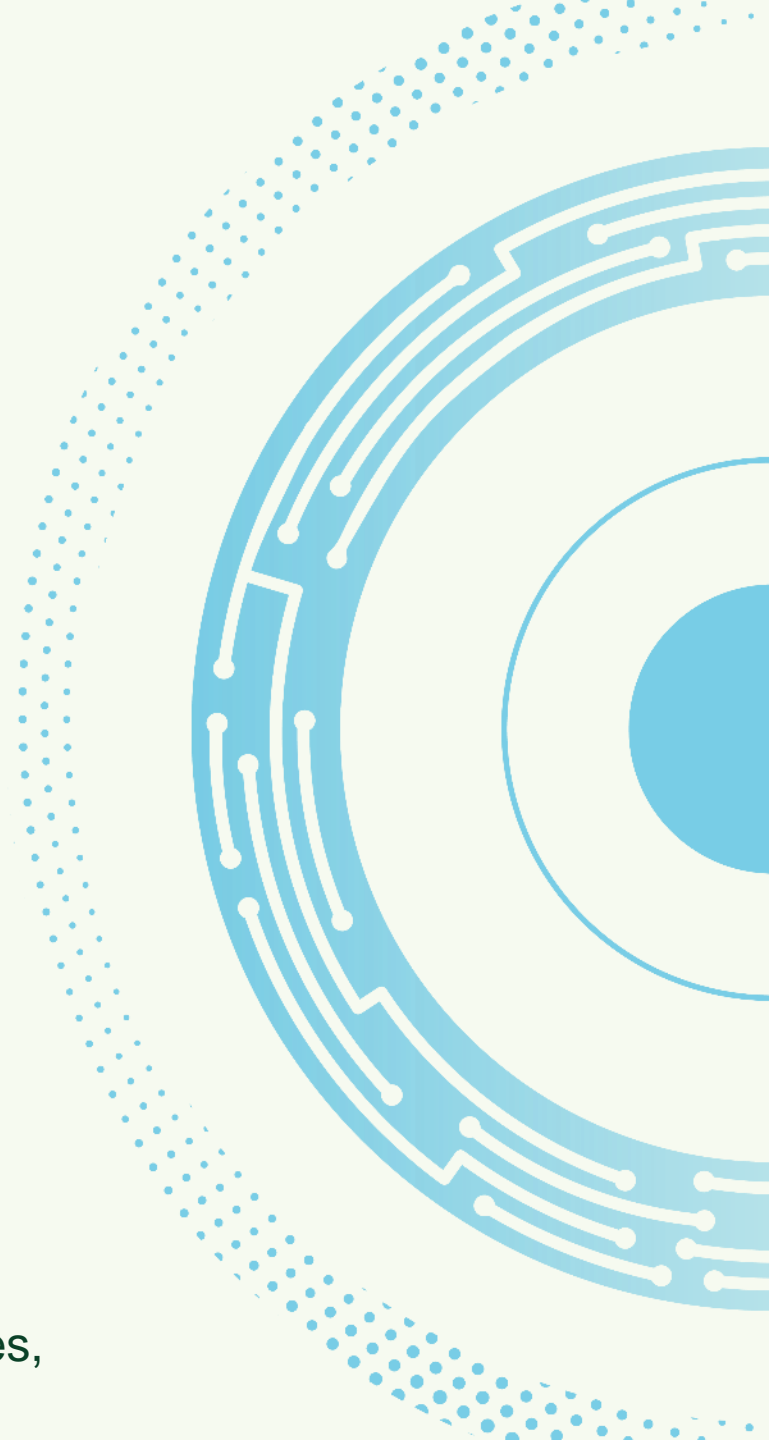
What is data mining?

Probability – reminder !

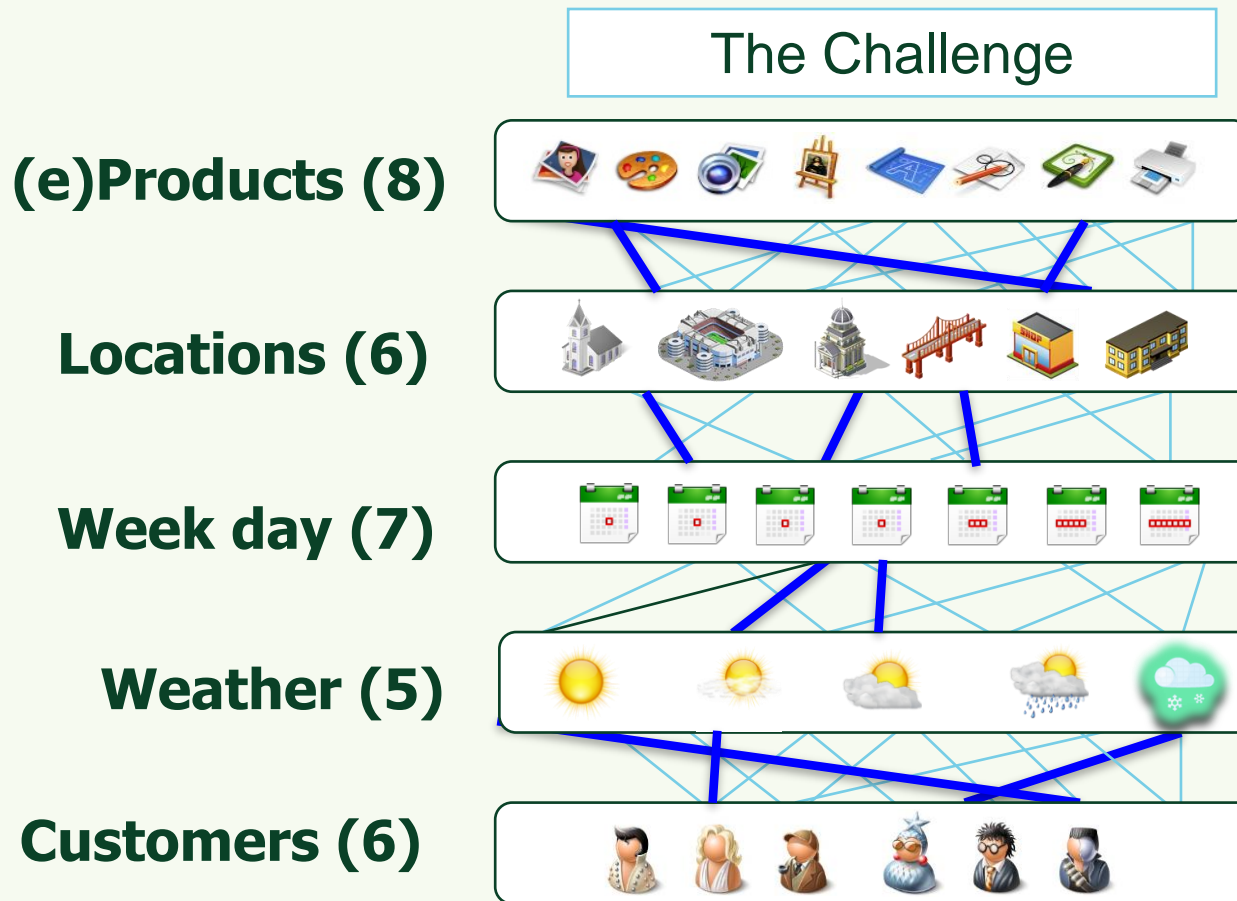


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Based on Data Mining – Concept and Techniques,
Jiawei Han, Micheline Kamber & Jian Pei



Motivation by examples



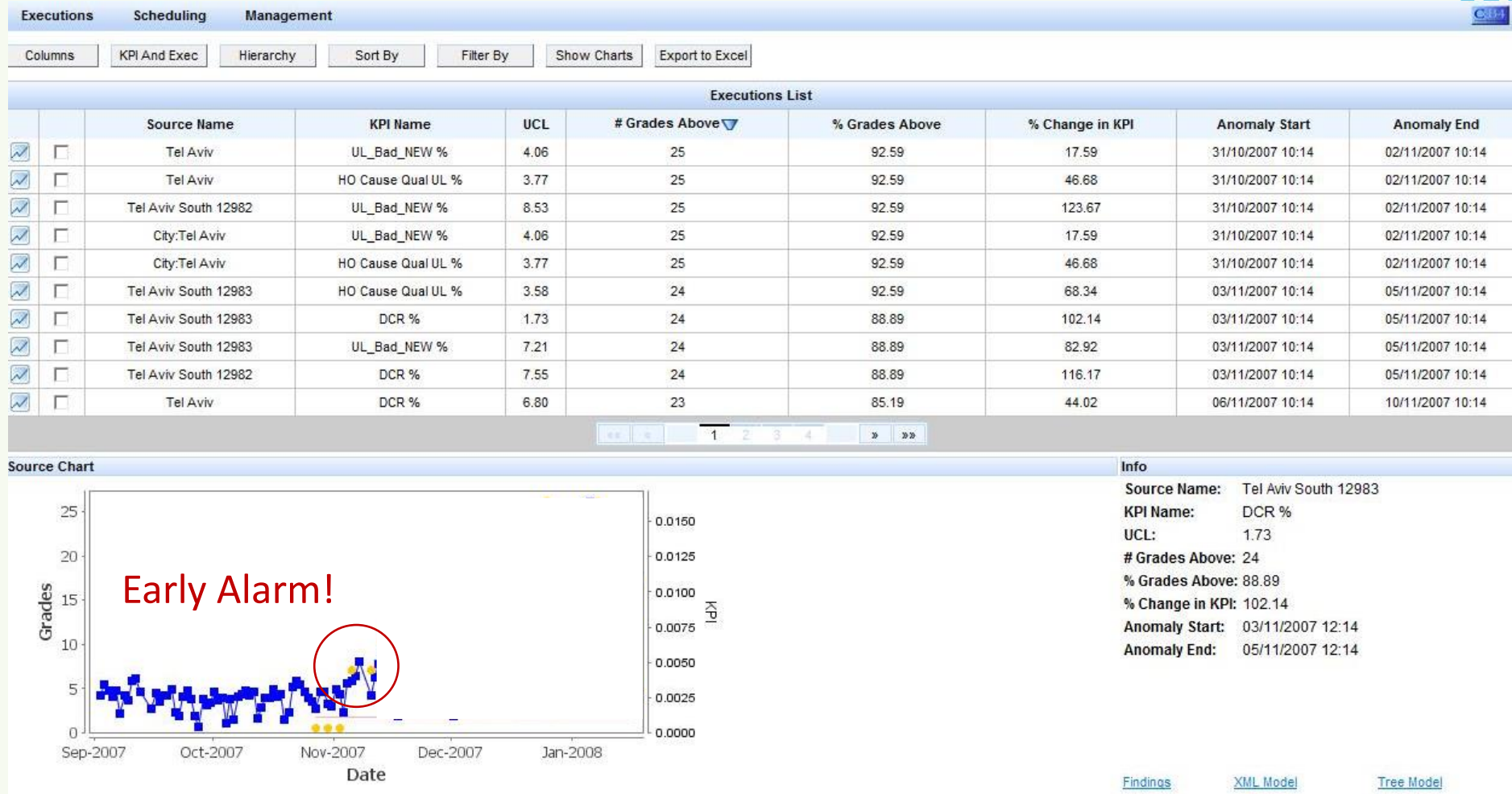
In this toy example:
4,294,967,296
potential patterns!!!

Sample pattern:
“**On rainy Tuesdays**
the customer will buy service A if he is located close to downtown”

The challenge: identifies the significant patterns and maps them into business opportunities.



Motivation by examples



Why data mining ?

The **Explosive Growth** of Data: from terabytes to petabytes

Data collection and **data availability**

Major sources of **abundant** data

We are drowning in **data**, but starving for **knowledge**!



What is data mining?

Extraction of **interesting** knowledge from **huge** amount of data

non-trivial

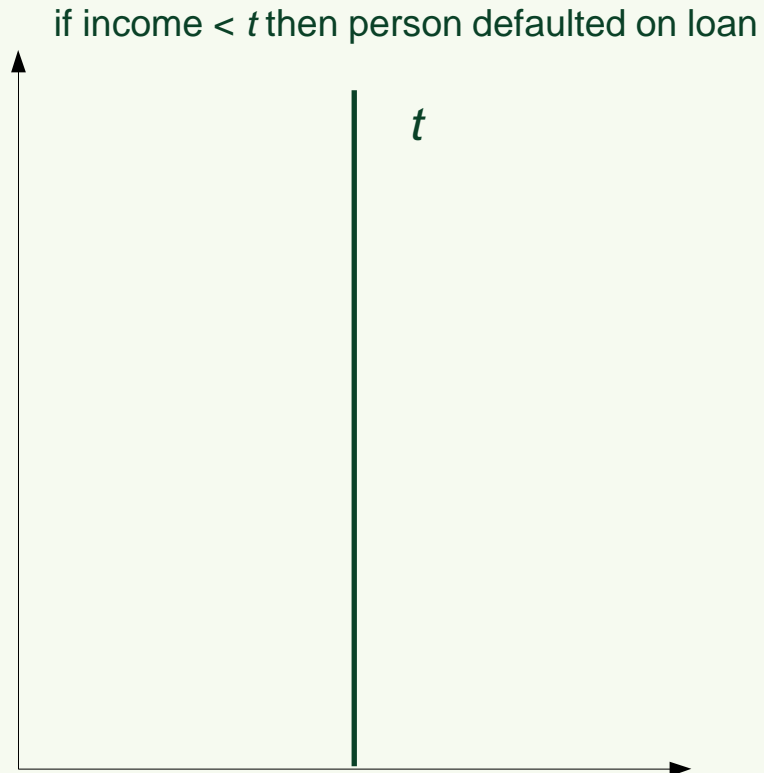
implicit

previously unknown

potentially useful



Example



X= bad situation

O= good situation

The graph represent historical data.

How to decide when to give a loan?

Definition of terms

- **Data** - is the set of facts (F)
In the example- collection of 23 cases, each containing three fields: debt income status
- **Pattern** - is an expression E describing facts in the subset E_F of F .
- **Process** – multi-step process to discover validity, useful and non-trivial but understandable results



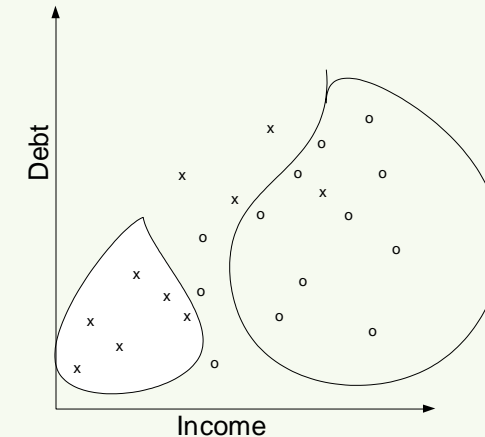
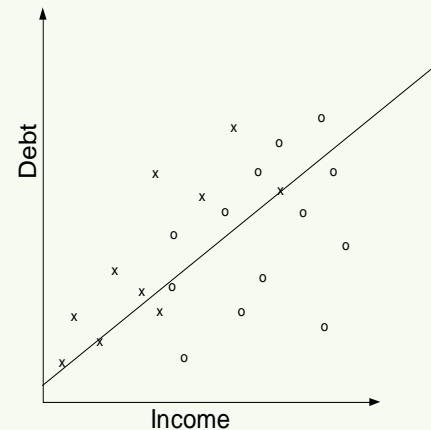
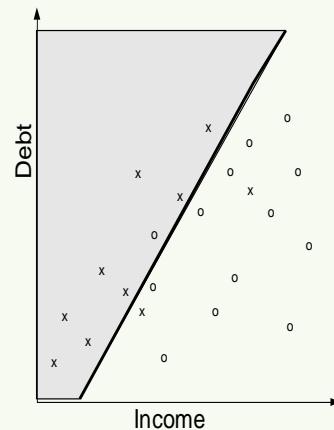
Example – definitions of terms

- **Validity** - The discovered patterns should be valid with some certainty, $C(E, F)$.
- **Potentially Useful** - The discovered patterns should do some useful actions that can be measured by some utility function $U(E, F)$.
- **Understandable** - The goal of KDD is to create patterns understandable in order to understand better the data. If this can be measured, it will be measured by $s=S(E, F)$.
- **Interestingness** - The overall measure of pattern value combining all the individual measures: $i = I(E, F, C, U, S)$
- **Knowledge** - A pattern $E \in L$ is called a knowledge if for some threshold $I(E, F, C, U, S) > v$.



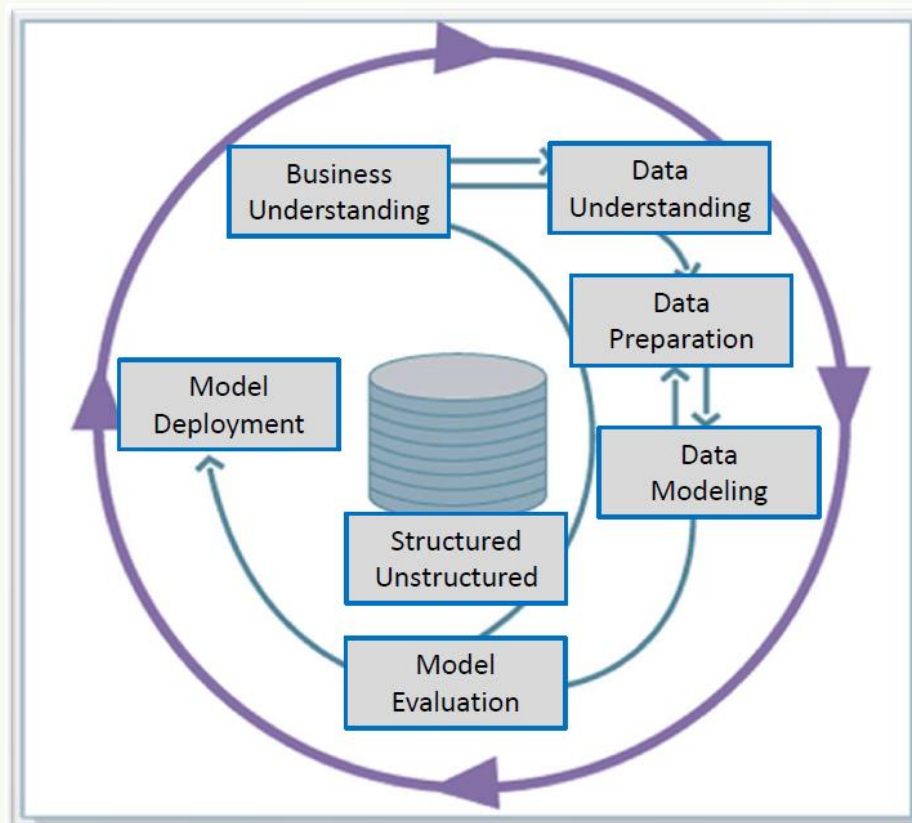
Data mining - tasks

- **Classification** - is the learning of a function that maps a data into one of several predefined classes.
- **Prediction** - is the learning of a function that maps data item into A prediction variable.
- **Clustering** - Identify a set of items with common characteristics
- **And more : reinforcement learning; associating; sequencing**



CRISP-DM

The Cross Industry Process for Data Mining –
(www.crispdm.org) (CRISP DM; Shearer, 2000)



Probability -reminder

- “Introduction to Probability Models”, Sheldon Ross
- “Introduction to Probability and Statistics for Engineers and Scientists”, Sheldon Ross
- “Introduction To Probability”, Dimitri P. Bertsekas, John N. Tsitsiklis



Probability – basics

- Random experiment E , outcome $\omega \in \Omega$, events F , sample space (Ω, F)
- Probability measure $P: F \rightarrow R$
- Axioms of probability, basic laws of probability
- Discrete sample space, discrete probability measure
- Continuous sample space, continuous probability measure
- Conditional probability, multiplicative rule, theorem of total probability, Bayes theorem
- Independence, pair-wise, mutual, conditional independence



Random variables

- $X: \Omega \rightarrow R$
- Example:
 - Experiment: Tossing of two coins
 - Random variable: sum of two outcomes
 - $\{X = 2\} \equiv \{\omega: \text{sum of scores} = 2\} = \{\{1,1\}\}$



Some discrete distributions

- Bernoulli: $X \sim Ber(p)$, $P_X(k) = p^k(1-p)^{1-k}; k = 0,1$
- Binomial: $X \sim Bin(n, p)$, $P_X(k) = P\{X = k\} = \binom{n}{k} p^k q^{n-k} \quad ; \quad k = 0,1,\dots,n$
- Poisson: $X \sim Poisson(\lambda)$, $P_X(k) = P\{X = k\} = e^{-\lambda} \frac{\lambda^k}{k!} \quad ; \quad k = 0,1,2,\dots$
- Geometric: $X \sim Geo(p)$, $P_X(k) = P\{X = k\} = p \cdot (1-p)^{k-1} \quad ; \quad k = 1,2,\dots$



Some density functions

Uniform: $x \sim U(a,b) \equiv f(x) = \frac{1}{b-a}$

Exponential: $x \sim \text{Exp}(\lambda) \equiv f(x) = \lambda e^{-\lambda x}$

Standard Normal: $x \sim N(0,1) \equiv f(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$

Gaussian: $x \sim N(\mu,\sigma) \equiv f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}$

Much more, Gamma, Beta et. al.



Moments

The r -th moment

$$m_r = \sum_i x_i^r \cdot p(x_i)$$

Mean (the first raw moment)

$$(\mu =) m_1 = E(x) = \sum_i x_i p(x_i) \left(= \int x p(x) dx \right)$$

$$a. E(aX + bY) = aE(X) + bE(y)$$

Variance (the second central moment)

$$Var[X] = E[(X - E[X])^2] = E(x^2) - \mu^2$$

$$a. Var(a) = 0$$

$$b. Var(ax) = a^2 Var(x)$$

$$c. Var(a + x) = Var(x)$$



Covariance

Covariance :

$$\text{Cov}(x, y) = E\{(x - \mu_x)(y - \mu_y)\} = E(x \cdot y) - \mu_x \mu_y$$

a. if x and y are independent then : $E(x \cdot y) = E(x)E(y) = \mu_x \mu_y \rightarrow \text{Cov}(x, y) = 0$

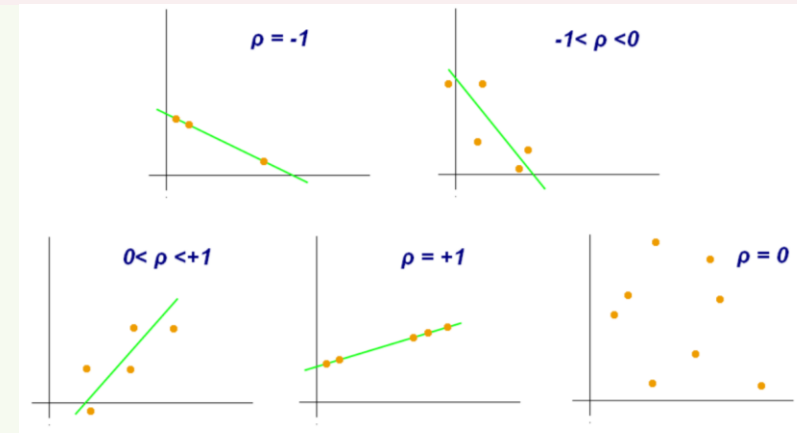
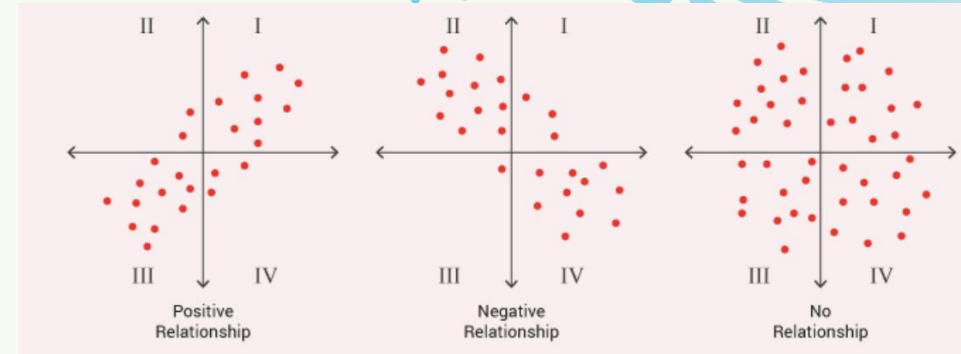
Correlation co-efficient

$$\rho(x, y) = \frac{\text{Cov}(x, y)}{\sigma_x \sigma_y}$$

a. if x and y are independent then : $\rho(x, y) = 0$

b. $|\rho(x, y)| \leq 1$

c. $|\rho(x, y)| = 1 \Leftrightarrow y = ax + b$



Central Limit Theorem

- N i.i.d. random variables X_i with mean μ , variance σ^2
- $S_N = \sum_i X_i$
- $Z_N = \frac{S_N - N\mu}{\sigma\sqrt{N}}$
- As N increases the distribution of Z_N approaches the standard normal distribution $f(Z_N) \sim \mathcal{N}(0,1)$



Conditional probability & Bayes

$$P(A | B) = \frac{P(A \cap B)}{P(B)}, \quad P(B) > 0$$

$$P(A \cap B) = P(A) \cdot P(B | A)$$

$$P(A \cap B) = P(B) \cdot P(A | B)$$

$$P(A | B) = \frac{P(A) \cdot P(B | A)}{P(B)}$$

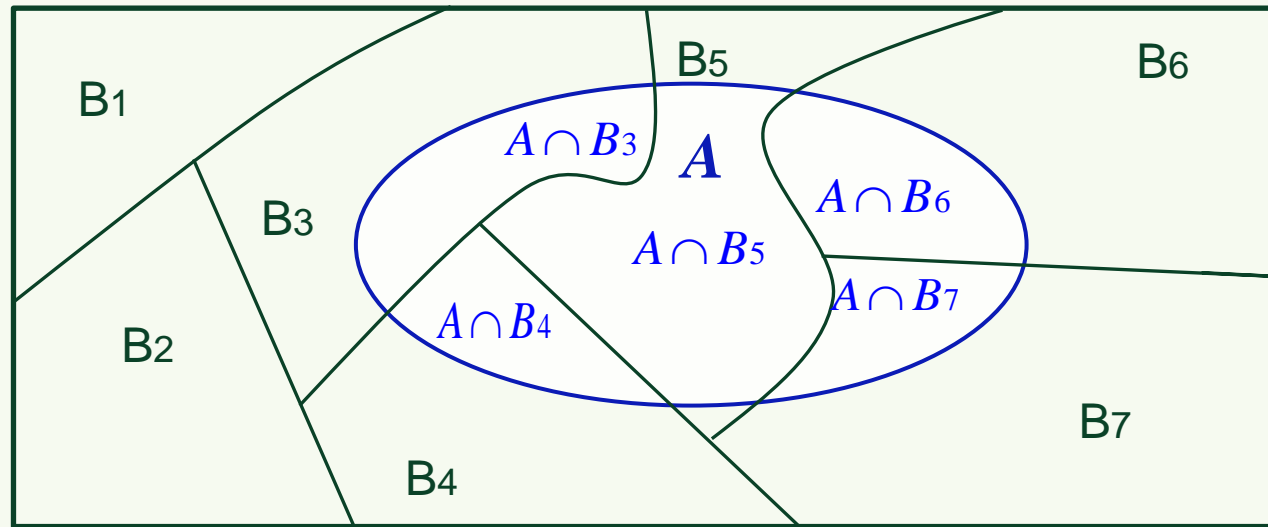
נוסחת הכפל:

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Total probability Theorem

$\{B_i\}$ divide Ω where $B_i \cap B_j = \phi$, $\forall i, j$



$$A = \bigcup (A \cap B_i)$$

$$\Rightarrow P\{A\} = \sum_I P\{A \cap B_i\}$$

$$\Rightarrow P\{A\} = \sum_I P\{A/B_i\} \cdot P\{B_i\}$$

\Rightarrow

$$P(B_j | A) = \frac{P(A | B_j)P(B_j)}{\sum_{i=1}^n P(A | B_i)P(B_i)}$$



Bayes' Theorem: Basics

- Total probability Theorem:
- Bayes' Theorem:
$$P(H | \mathbf{X}) = \frac{P(\mathbf{X} | H)P(H)}{P(\mathbf{X})} = P(\mathbf{X} | H) \times P(H) / P(\mathbf{X})$$
 - Let \mathbf{X} be a data sample (“evidence”): class label is unknown
 - Let H be a *hypothesis* that X belongs to class C
 - Classification is to determine $P(H|\mathbf{X})$, (i.e., *posteriori probability*): the probability that the hypothesis holds given the observed data sample \mathbf{X}
 - $P(H)$ (*prior probability*): the initial probability
 - E.g., \mathbf{X} will buy computer, regardless of age, income, ...
 - $P(\mathbf{X})$: probability that sample data is observed
 - $P(\mathbf{X}|H)$ (likelihood): the probability of observing the sample \mathbf{X} , given that the hypothesis holds
 - E.g., Given that \mathbf{X} will buy computer, the prob. that X is 31..40, medium income



Thank you!



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