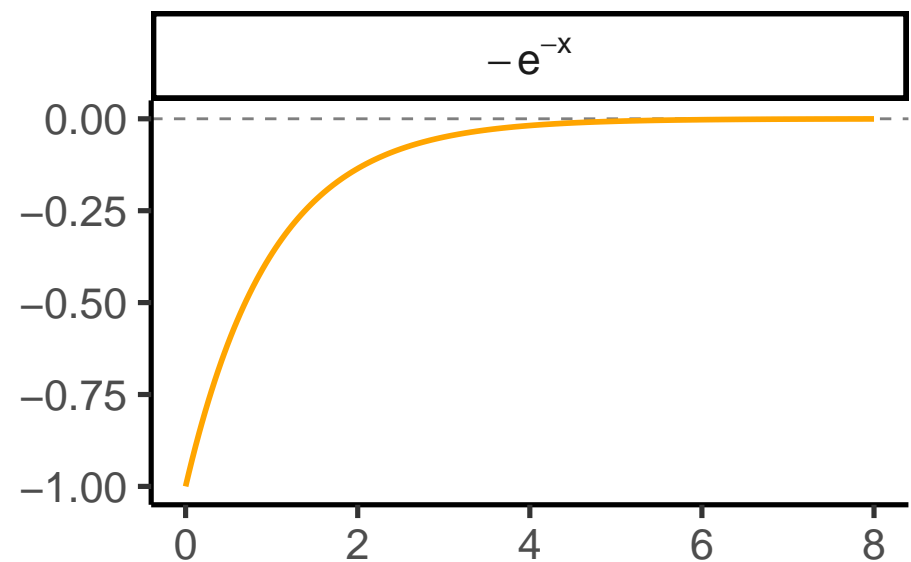
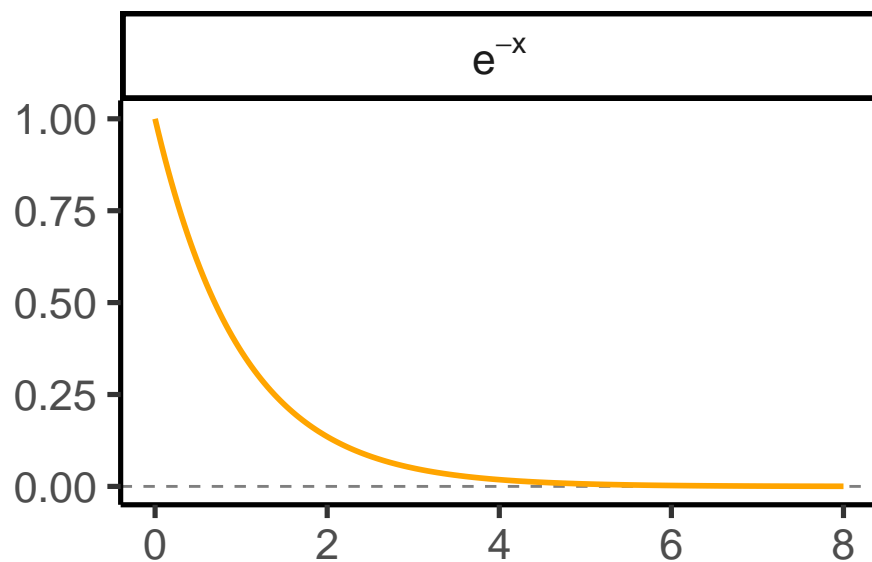
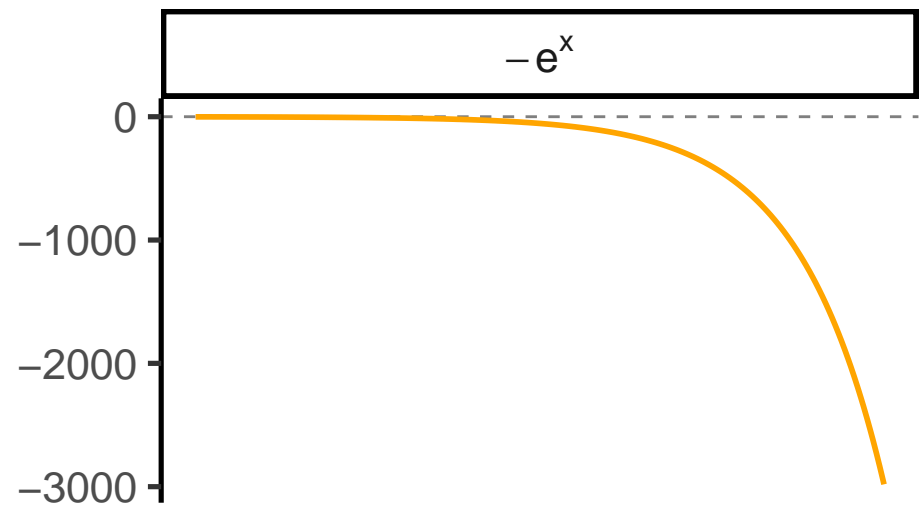
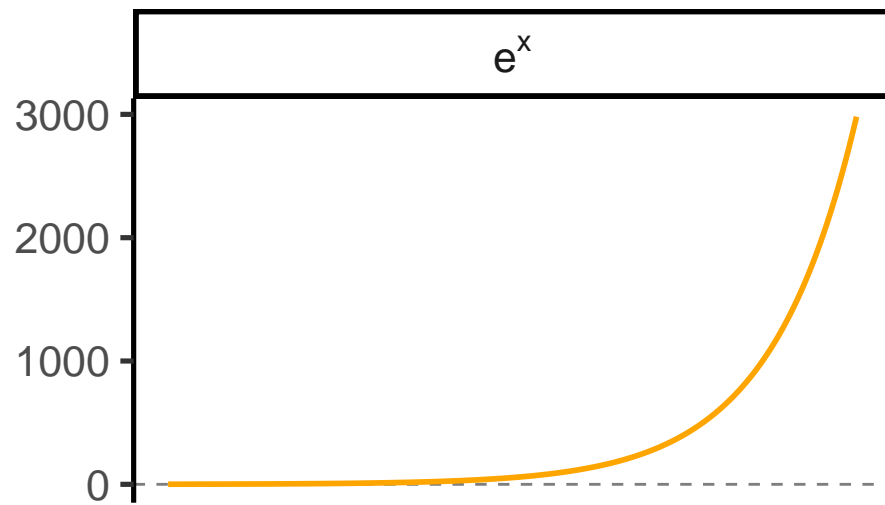


# Exponential Function Dynamics

Output



Input