

# Data Structures

Gabriel Istrate

April 9, 2024

- Binary Search Trees. Operations. Randomization.
- AVL trees.
- Splay trees
- Red-black trees

- A **binary search tree** implements of a dynamic set
  - ▶ over a **totally ordered domain**

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  - ▶ iteration: **Tree-Successor**( $x$ ) and **Tree-Predecessor**( $x$ ) find the successor and predecessor, respectively, of an element  $x$

# Binary Search Trees (2)

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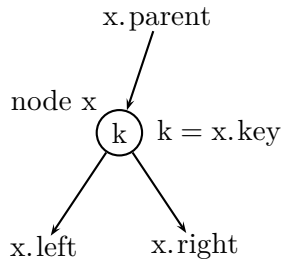
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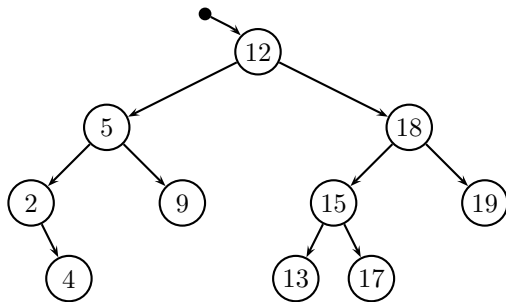
Node x

- ▶ x.parent is the parent of node x
- ▶ x.key is the key stored in node x
- ▶ x.left is the left child of node x
- ▶ x.right is the right child of node x

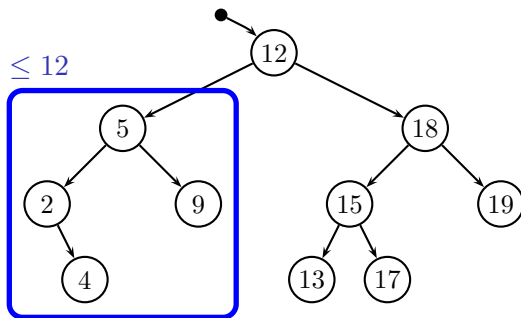


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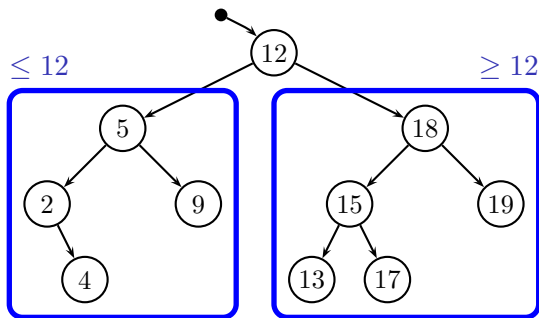
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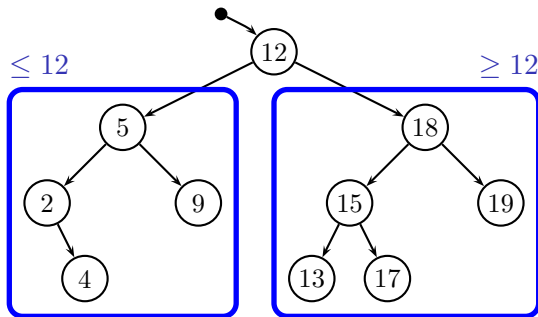


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- Binary-search-tree property

- ▶ for all nodes  $x$ ,  $y$ , and  $z$
- ▶  $y \in \text{left-subtree}(x) \Rightarrow y.\text{key} \leq x.\text{key}$
- ▶  $z \in \text{right-subtree}(x) \Rightarrow z.\text{key} \geq x.\text{key}$





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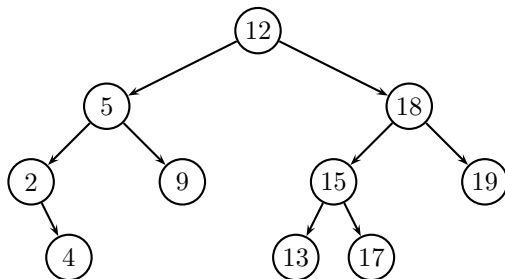


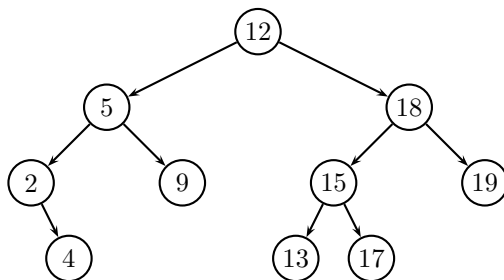
- Iterative binary search

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```
Iterative-Tree-Search(T, k)
1  x = T.root
2  while x ≠ nil ∧ k ≠ x.key
3      if k < x.key
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5      else x = x.right
6  return x
```







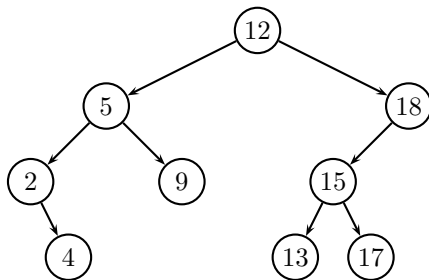
- Idea

- ▶ in order to insert  $x$ , we search for  $x$  (more precisely  $x.key$ )
- ▶ if we don't find it, we add it where the search stopped

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Tree-Insert(T, z) 1  y = nil
                  2  x = T.root
                  3  while x  $\neq$  nil
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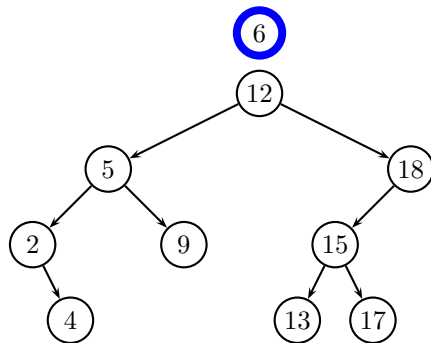
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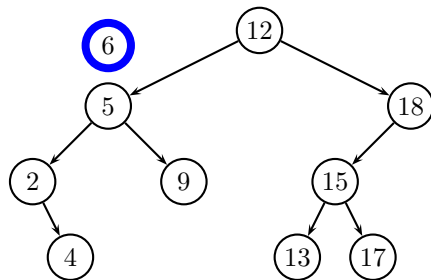
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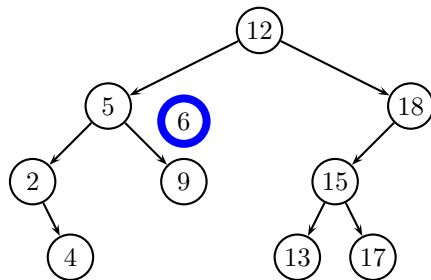
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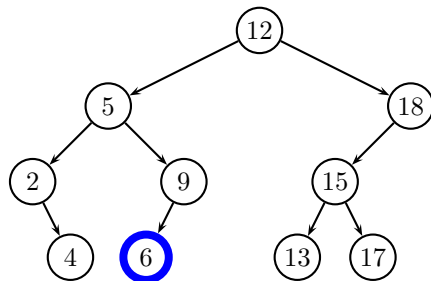
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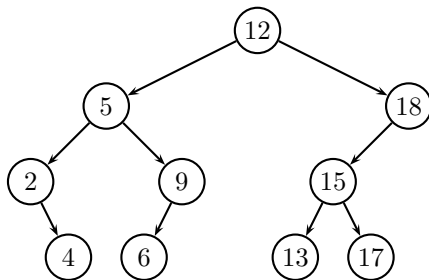
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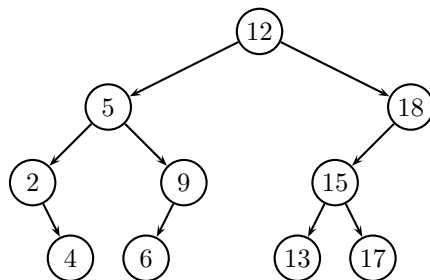
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- Idea: use randomization to turn all cases in the average case

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- Idea 2: we can obtain a random permutation of the input sequence by randomly alternating two insertion procedures
  - ▶ tail insertion: this is what Tree-Insert does
  - ▶ head insertion: for this we need a new procedure Tree-Root-Insert
    - ★ inserts  $n$  in  $T$  as if  $n$  was inserted as the first element



## Randomized Insertion (2)

```
Tree-Randomized-Insert1(T, z)
1  r = uniformly rand. val. from {1, ..., t.size + 1}
2  if r = 1
3      Tree-Root-Insert(T, z)
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  - ▶ this suggests a recursive application of this same procedure

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                               4  if r = 1 // Pr[r = 1] = 1/(t.size + 1)
                               5      z.size = t.size + 1
                               6      return Tree-Root-Insert(t, z)
                               7  if z.key < t.key
                               8      t.left = Tree-Randomized-Insert(t.left, z)
                               9  else t.right = Tree-Randomized-Insert(t.right, z)
                               10 t.size = t.size + 1
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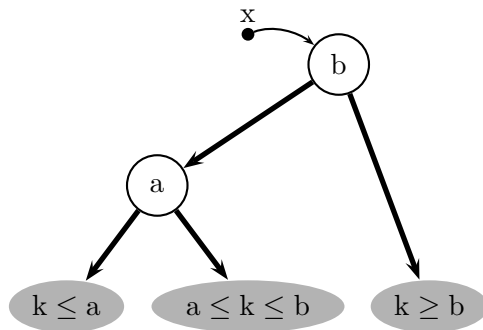
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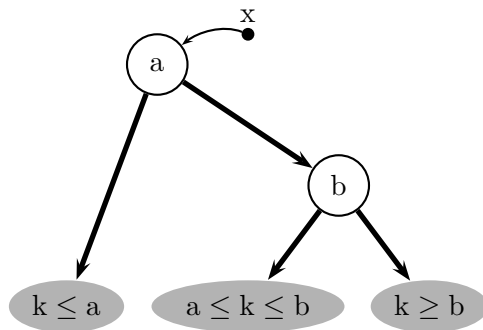
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- Looks like this one really simulates a random permutation...

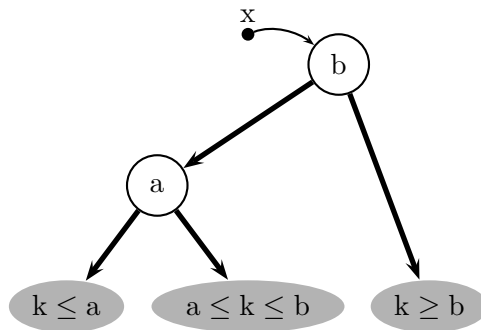




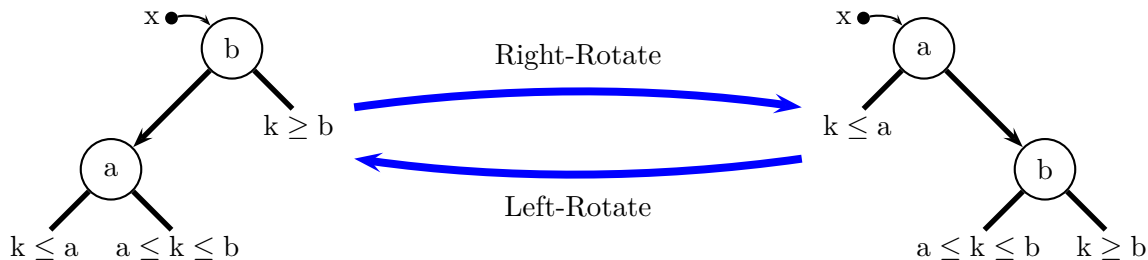




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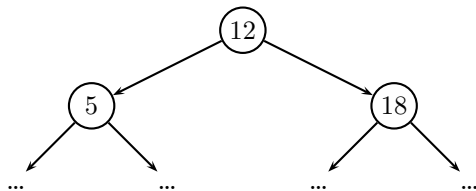


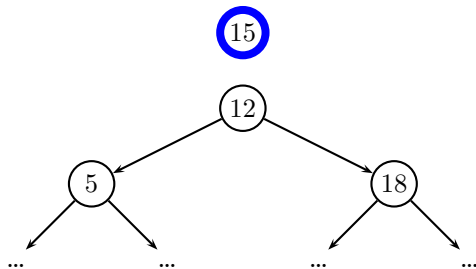
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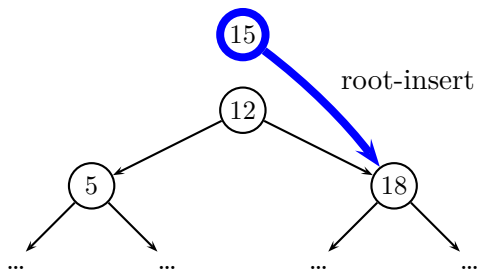
Right-Rotate(x)
1  l = x.left
2  x.left = l.right
3  l.right = x
4  return l
  
```

```

Left-Rotate(x)
1  r = x.right
2  x.right = r.left
3  r.left = x
4  return r
  
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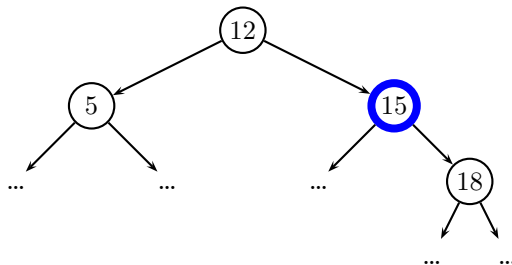




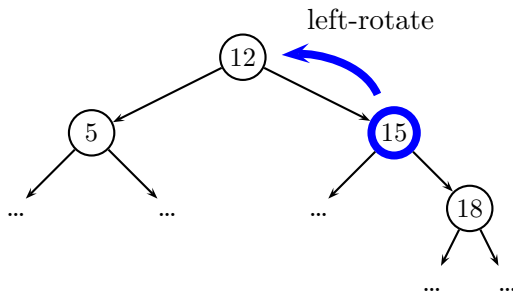


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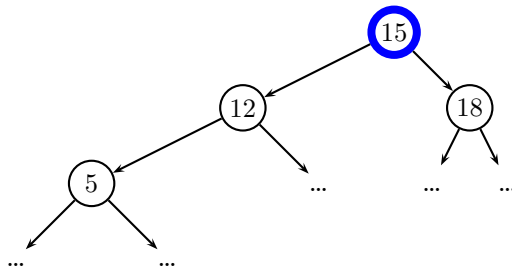




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## Root Insertion (2)

```
Tree-Root-Insert(x, z) 1 if x = nil
                        2     return z
                        3 if z.key < x.key
                        4     x.left = Tree-Root-Insert(x.left, z)
                        5     return Right-Rotate(x)
                        6 else x.right = Tree-Root-Insert(x.right, z)
                        7     return Left-Rotate(x)
```

- General strategies to deal with complexity in the worst case

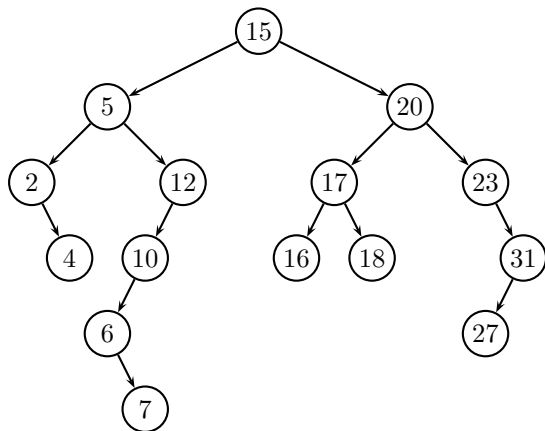
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    - ★ relatively expensive but “amortized” operations

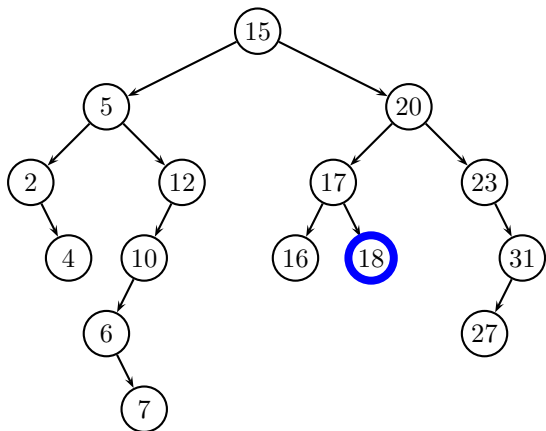
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  - ▶ amortized maintenance: e.g., balancing a BST or resizing a hash table
    - ★ relatively expensive but “amortized” operations
  - ▶ optimized data structures: a self-balanced data structure
    - ★ guaranteed  $O(\log n)$  complexity bounds

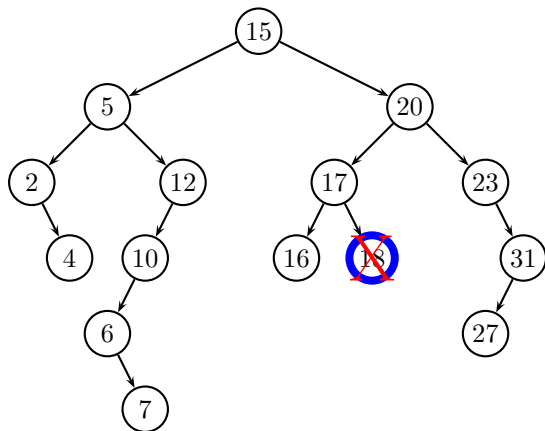




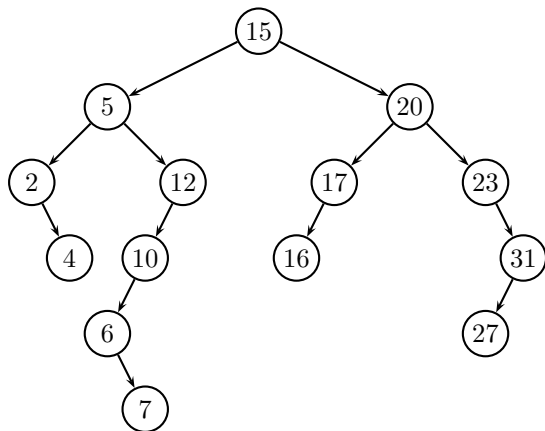


1. z has no children

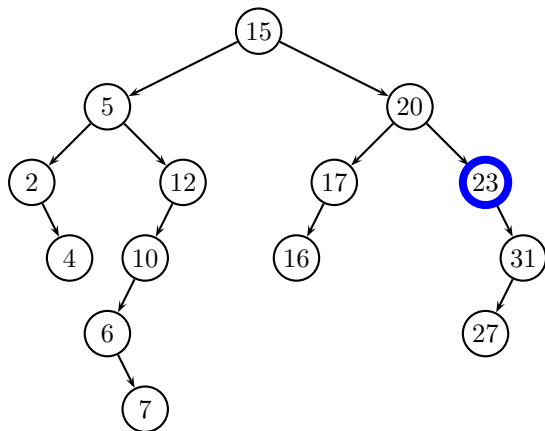




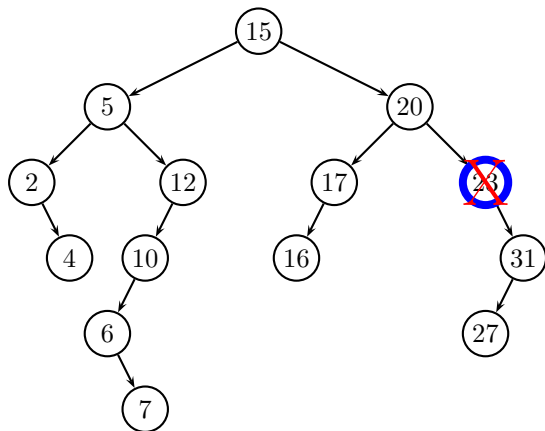
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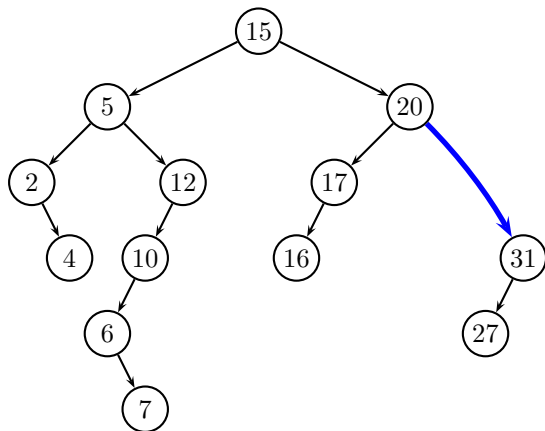
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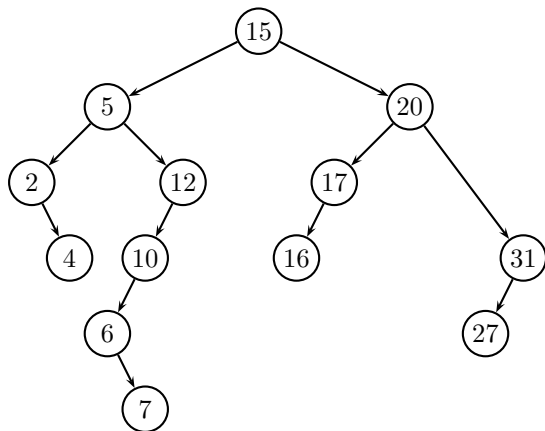


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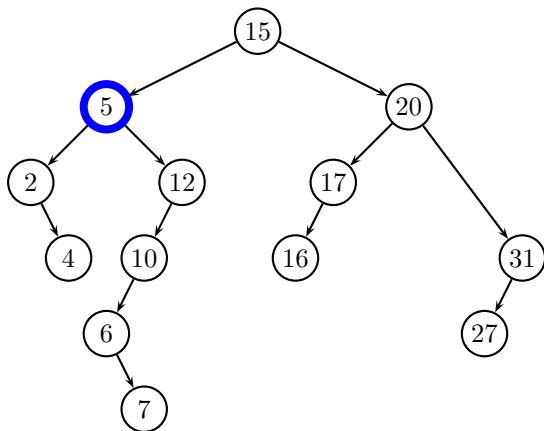


1. z has no children
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  - ▶ remove z
  - ▶ connect z.parent to z.right



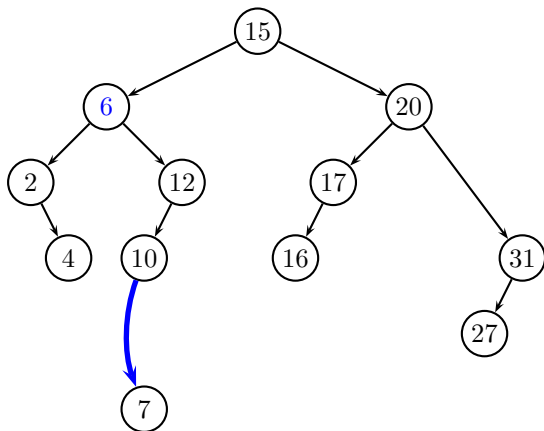


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                  14  if y ≠ z
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                  16      copy any other data from y into z
```

- Want: data structure to support INSERT, DELETE, SEARCH in  $O(\log n)$  time.
- Binary search trees: insert, delete, search.
- But complexity bound not met unless trees balanced.
- Can rebalance.

Next: three self-adjusting trees, finally meet the  $O(\log n)$  bound: AVL trees, splay trees, red-black-trees.

# Summary on Binary Search Trees

- Binary search trees

- ▶ embody the **divide-and-conquer** search strategy
- ▶ Search, Insert, Min, and Max are  $O(h)$ , where  $h$  is the **height of the tree**
- ▶ in general,  $h(n) = \Omega(\log n)$  and  $h(n) = O(n)$
- ▶ **randomization** can be used to make the worst-case scenario  $h(n) = n$  highly unlikely

# Summary on Binary Search Trees

- Binary search trees

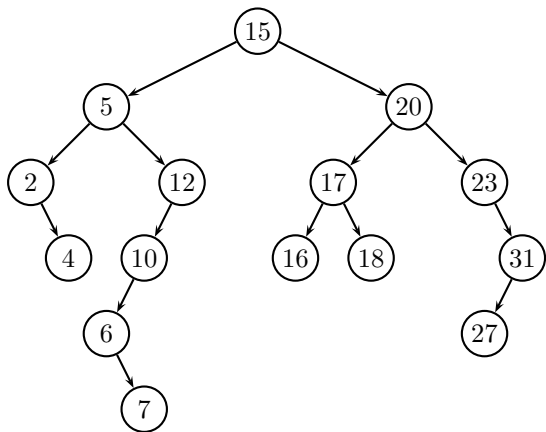
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- Problem

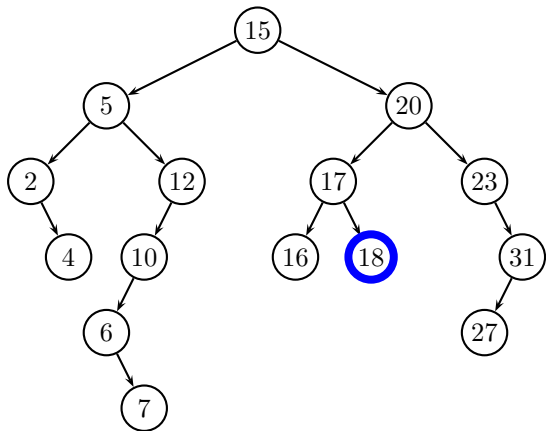
- ▶ worst-case scenario is unlikely but still possible
- ▶ simply bad cases are even more probable

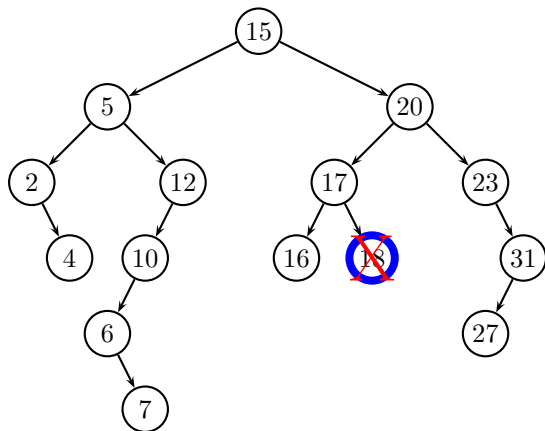




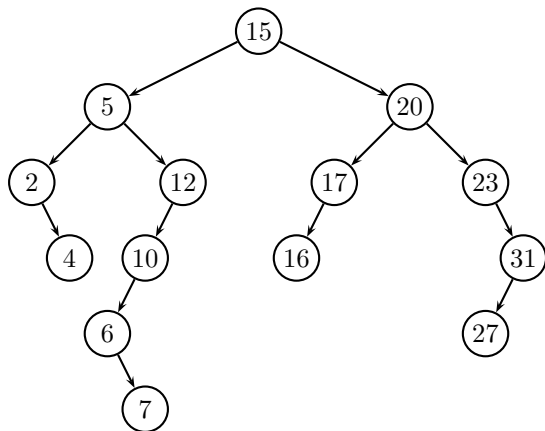


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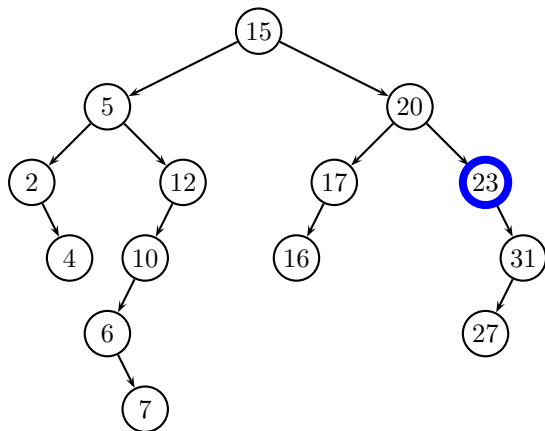




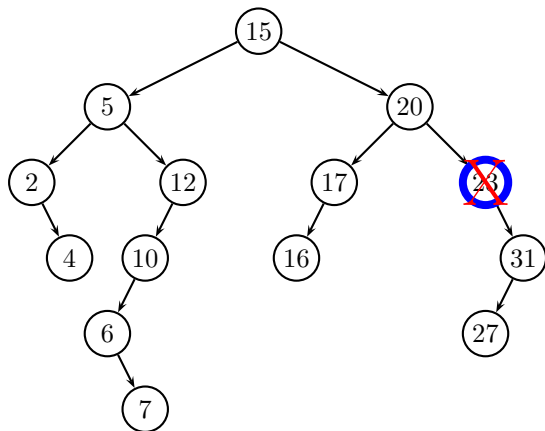
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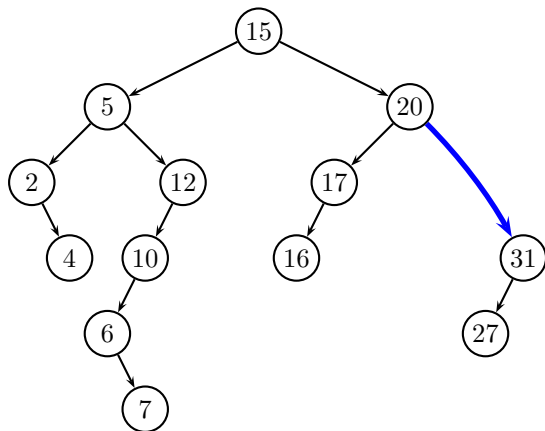
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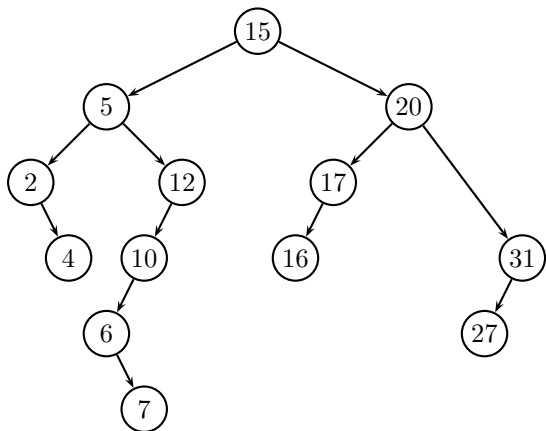


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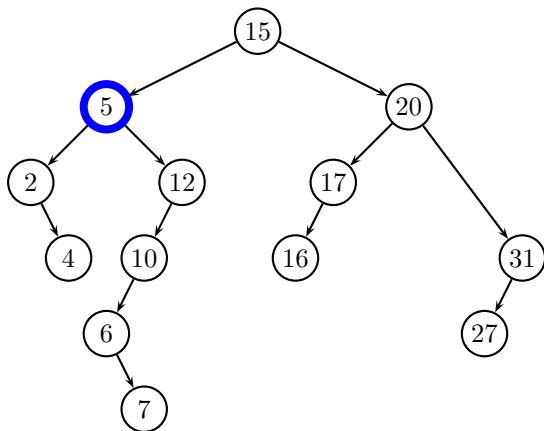


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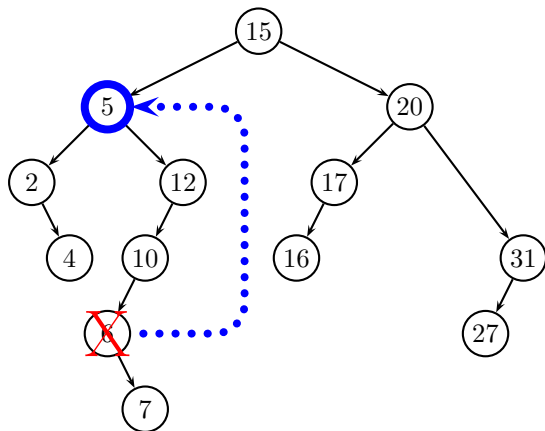




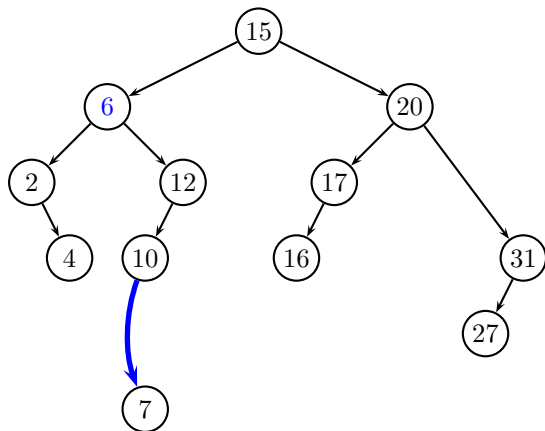
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- Why study all this stuff ?
- Linked list: **search linear**.
- **Balanced** binary trees: **search logarithmic**.
- **For frequent searches it pays**.
- Advantage: as long as trees “approximately balanced”.
- But: operations (inserts/deletes) can destroy balance.

## Self-balancing trees

If insertion/deletion unbalances the tree, **rebalance it**.

# Why three of them ?

- AVL trees: more strictly balanced than R-B trees. Better for **lookup intensive** programs.
- For an **insert intensive tasks**, use a Red-Black tree.
- Simplicity of implementation: splay trees > red-black trees > AVL trees.
- Splay trees: only  $O(\log n)$  amortized.
- Splay trees: suitable for cases where there are **large number of nodes but only few of them are accessed frequently**.
- Splay trees: more memory-efficient than AVL trees, because they do not need to store balance information in the nodes.
- AVL trees: more useful in multithreaded environments with lots of lookups, because lookups in an AVL tree can be done in parallel.
- Benchmarking: **AVL trees more than 20% faster than R-B trees** in "real-life" benchmarkis

# Why three of them ?

- treaps
- T-trees
- tango trees

... many other ! (But this is an introduction)



# You can invent your own trees ...

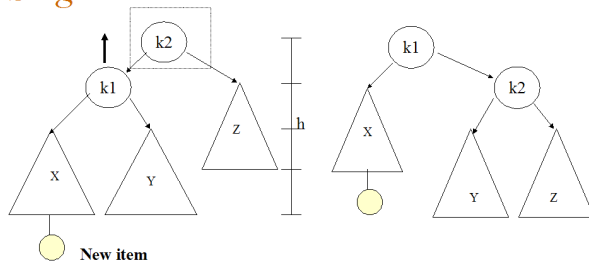
**Tango trees:** A type of binary search tree proposed by Erik D. Demaine, Dion Harmon, John Iacono, and Mihai Pătraşcu in 2004.

They work by partitioning a BST into a set of preferred paths, which are themselves stored in auxiliary trees (so the tango tree is represented as a tree of trees)

- **red-black trees:**
  - ① **Java:** `java.util.TreeMap` , `java.util.TreeSet` .
  - ② **C++ STL:** `map`, `multimap`, `multiset`.
  - ③ **Linux kernel:** completely fair scheduler, `linux/rbtree.h`
- Splay trees: typically used in the implementation of caches, memory allocators, routers, garbage collectors, data compression, etc.
- Implementations of AVL trees, RB-trees, splay trees: not standardized. STL provides only **minimal set of containers**.

- Balancedness condition #1: left and right subtrees of the root have the same height. *too weak.*
- Balancedness condition #2: left and right subtrees of every node have the same height. *too strong.*
- AVL (Adelson-Velskii and Landis) trees: binary search trees that verify the following *balancedness condition*: for every node  $v$  *the left and right subtrees of  $v$  have height differing by at most one.*
- When a tree violates rule #3 a repair is done.
- *The repair is done during insertions, as soon as rule #3 is violated.*
- The repair is accomplished via *"single"* and *"double"* rotations.

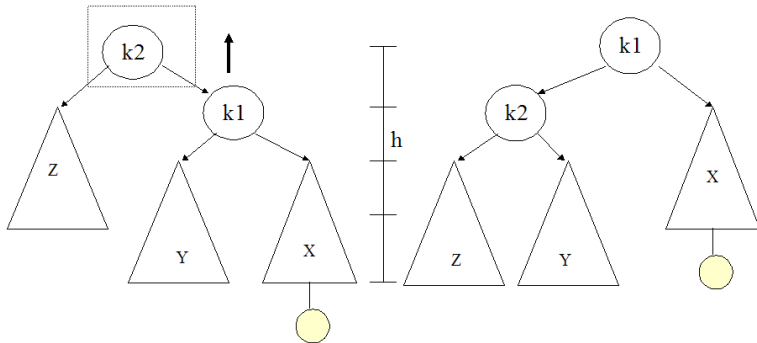
## Single Rotation



Suppose an item is added at the bottom of subtree  $X$ , thus causing an imbalance at  $k2$ . Then pull  $k1$  up. Note that after the rotation, the height of the tree is the same as it was before the insertion.

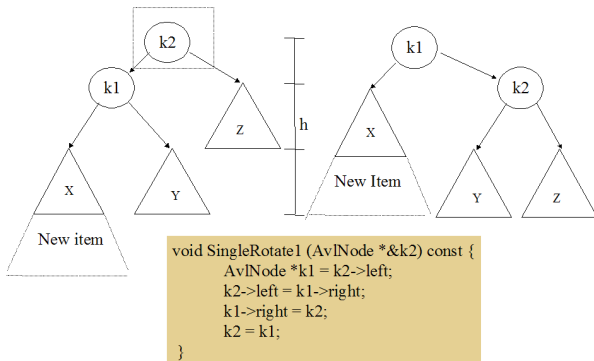
- **Balance factor of a node:** difference of heights between left and right subtrees.
- **AVL trees:** each node balance factor 0 or  $\pm 1$ .
- After single rotations, the new height of the entire subtree is exactly the same as the height of the original subtree prior to the insertion of the new data item that caused X to grow.
- Thus no further updating of heights on the path to the root is needed, and consequently no further rotations are needed.

## Single rotations: another example

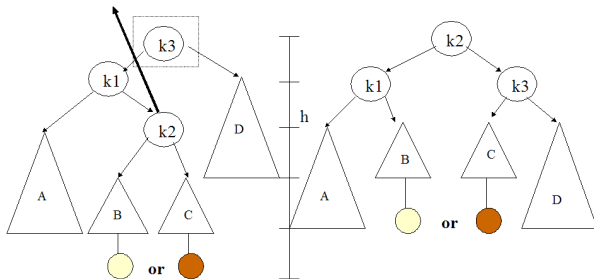


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# Single rotations: C++



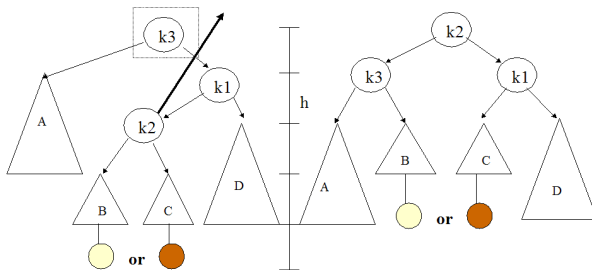
## Double Rotation



Suppose an item is added below  $k2$ . This causes an imbalance at  $k3$ . Then pull  $k2$  up. Note that after the rotation, the height of the tree is the same as it was before the insertion.

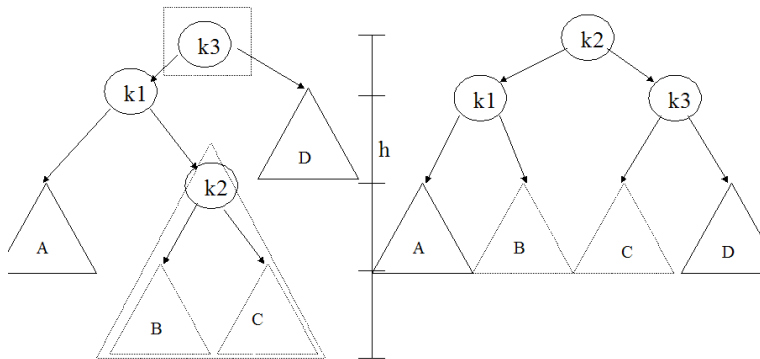


## *Another Double Rotation*



Suppose an item is added below k2. This causes an imbalance at k3. Then pull k2 up. Note that after the rotation, the height of the tree is the same as it was before the insertion.

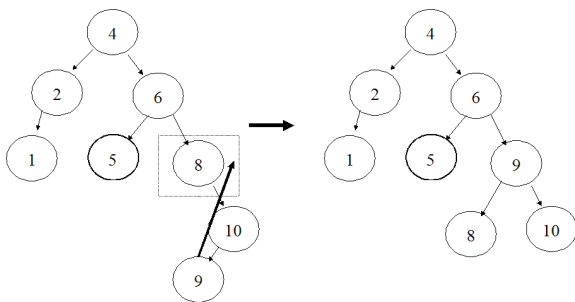
## Double rotations: C++



```
void DoubleRotate1 (AvlNode *&k3) const {  
    SingleRotate1( k3->left );  
    SingleRotate1( k3 );  
}
```

# Using double rotations in practice

## *An Example*



Imbalance at node 8 solved with double rotation.

# Which rotations to use ?

- Recognizing which rotation you have to use is the hardest part.
  - ① Find the imbalanced node.
  - ② Go down two nodes towards the newly inserted node.
  - ③ If the path is straight, use single rotation.
  - ④ If the path zig-zags, use double rotation.

# Deleting a node

- Use `deleteByCopying()` to delete a node. This allows reducing the problem of deleting a node with two descendants to deleting a node with at most one descendant.
- After a node has been deleted, balance factors updated from the parent of the deleted node to the root.
- For each node whose balance becomes  $\pm 2$ , a single or double rotation has to be performed to restore balance of the tree.
- Deletion: at most  $O(\log n)$  rotations.
- Deletion might improve balance factor of its parent.
- It may also worsen the balance factor of its grandparent.

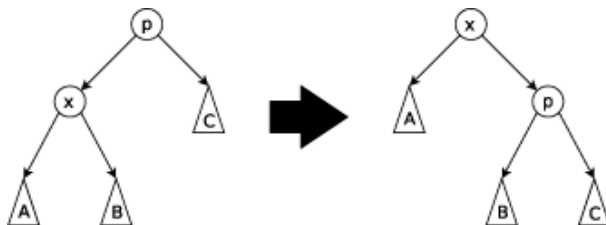
- As with the single rotations, double rotations restore the height of the subtree to what it was before the insertion.
- This guarantees that all rebalancing and height updating is complete.
- AVL trees maintain balance of binary search trees while they are being created via insertions of data.
- An alternative approach is to have trees that readjust themselves when data is accessed, making often accessed data items move to the top of the tree (splay trees).

- Invented by Sleator and Tarjan (1985).
- to splay  $\sim$  to spread out.
- Self-balancing binary trees, simpler to implement than AVL, red-black trees.
- Additional property: recently accessed elements quick to access.
- Insertion, lookup, removal:  $O(\log n)$  **amortized time**.
- That roughly means that the average price per operation in a long sequence of operations is  $O(\log n)$ .
- Fundamental operation: **splaying**. Rearranging the tree such that certain elements are brought to the top of the tree.

- When a node  $x$  is accessed, a **splaying operation** performed to bring it to the top.
- Composed of a sequence of **splaying steps**.
- Each splaying step brings  $x$  closer to the root.
- Steps depend on:
  - Whether  $z$  is left or right child of its parent  $p$ .
  - Whether  $p$  is root or not, and
  - Whether  $p$  is left or right child of its parent  $g$ .
- **Three types** of splaying steps.

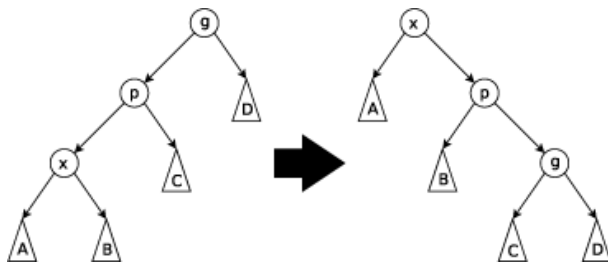


First case: p is the root



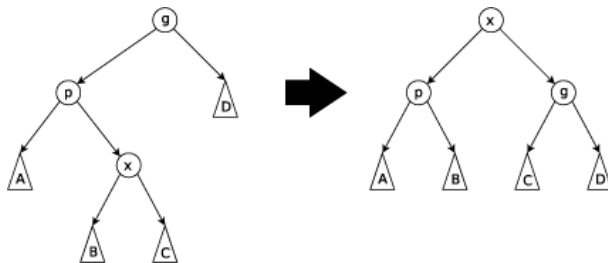
“zig”: basically rotation.

Second case: p not the root, x, p both left or both right children



“Zigzag”

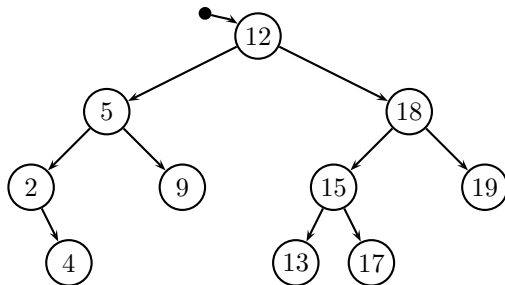
## Third case: p, x alternate sides

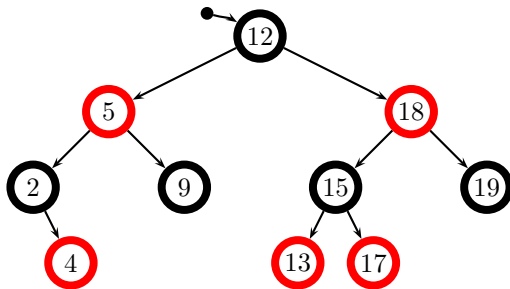


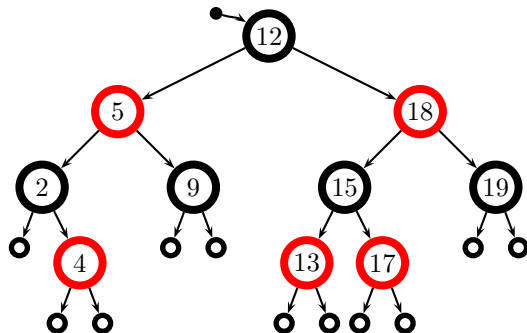
“Zigzag”

- First case: rotation.
- All cases: actually two mirror-image cases (only one shown in picture).
- Advantages: more accessed nodes closer to root. Useful for implementing caches, garbage collection.
- Disadvantages: random access worse than for other balanced BST.
- Particularly bad: access elements in sorted order.

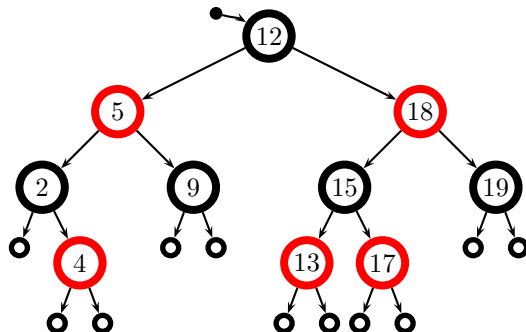




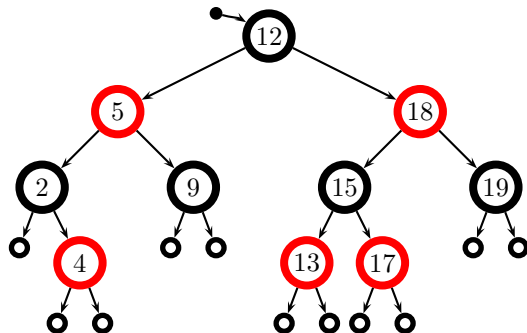




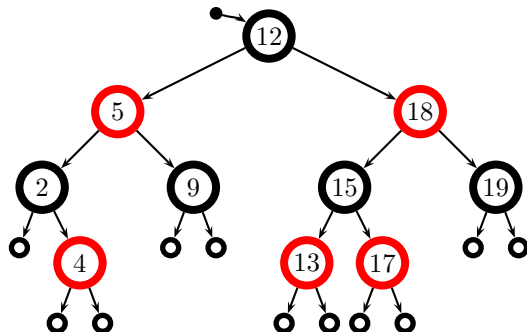




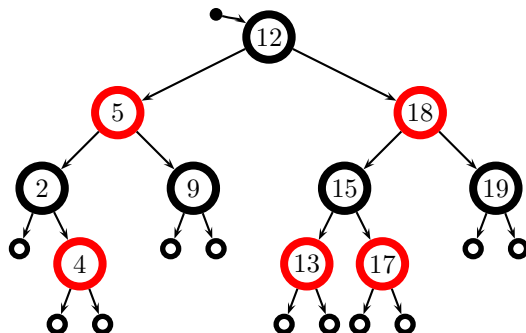
- Red-black-tree property



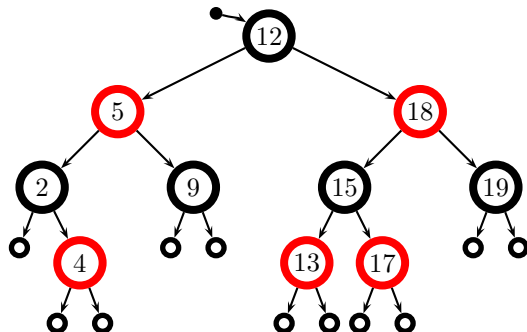
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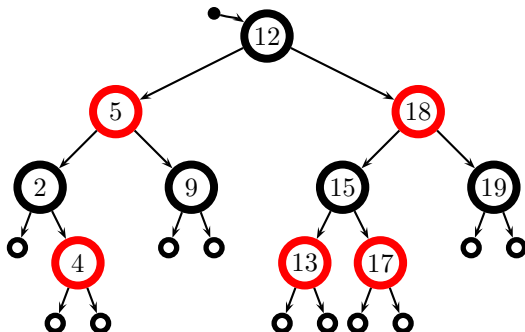
- Red-black-tree property
  - ① every node is either red or black
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- Red-black-tree property
  - 1 every node is either red or black
  - 2 the root is black
  - 3 every (NIL) leaf is black



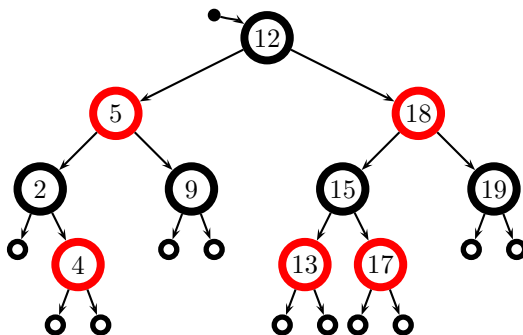
- Red-black-tree property
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  - 3 every (NIL) leaf is black
  - 4 if a node is red, then both its children are black



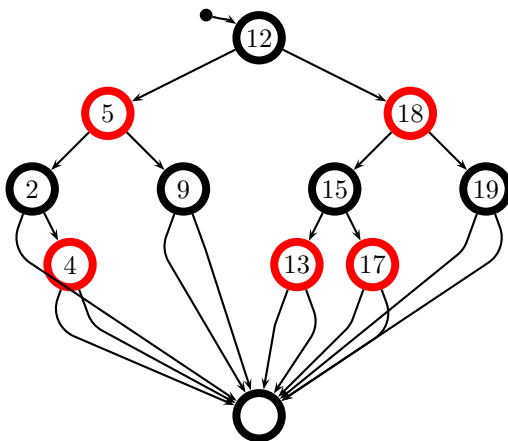
- Red-black-tree property

- every node is either red or black
- the root is black
- every (NIL) leaf is black
- if a node is red, then both its children are black
- for every node  $x$ , each path from  $x$  to its descendant leaves has the same number of black nodes  $bh(x)$  (the black-height of  $x$ )

- Implementation



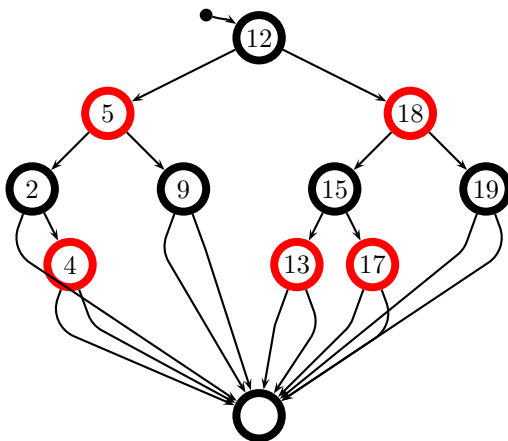
- Implementation



- ▶ we use a common “sentinel” node to represent leaf nodes



- Implementation



- ▶ we use a common “sentinel” node to represent leaf nodes
- ▶ the sentinel is also the parent of the root node

- Implementation

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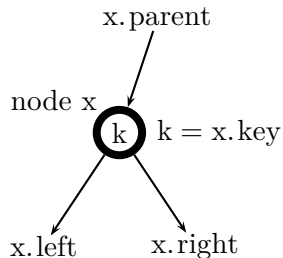
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## Nodes

- ▶ x.parent is the parent of node x
- ▶ x.key is the key stored in node x
- ▶ x.left is the left child of node x
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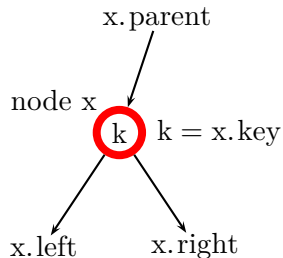


## • Implementation

- ▶  $T$  represents the tree, which consists of a set of nodes
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- ▶  $x.right$  is the right child of node  $x$
- ▶  $x.color \in \{\text{red}, \text{black}\}$  is the color of node  $x$



# Height of a Red-Black Tree

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Lemma: the height  $h(x)$  of a red-black tree with  $n = \text{size}(x)$  internal nodes is at most  $2 \log(n + 1)$ .



# Height of a Red-Black Tree

Lemma: the height  $h(x)$  of a red-black tree with  $n = \text{size}(x)$  internal nodes is at most  $2 \log(n + 1)$ .

Proof:

① prove that  $\forall x : \text{size}(x) \geq 2^{bh(x)} - 1$  by induction:

① **base case:**  $x$  is a leaf, so  $\text{size}(x) = 0$  and  $bh(x) = 0$

# Height of a Red-Black Tree

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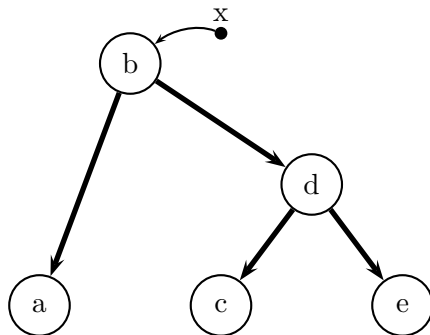
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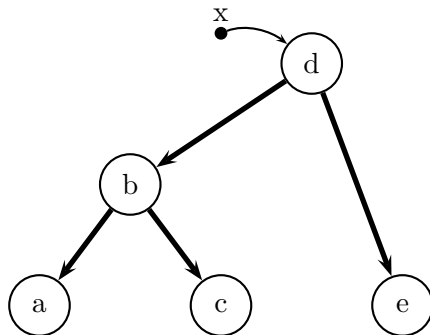
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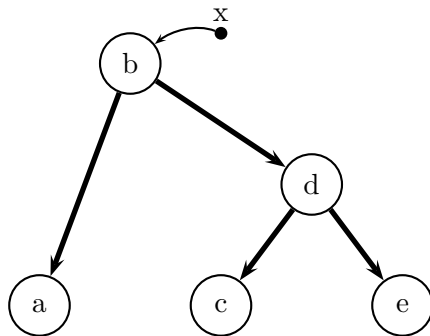
- A red-black tree works as a binary search tree for search, etc.
- So, the complexity of those operations is  $T(n) = O(h)$ , that is

$T(n) = O(\log n)$

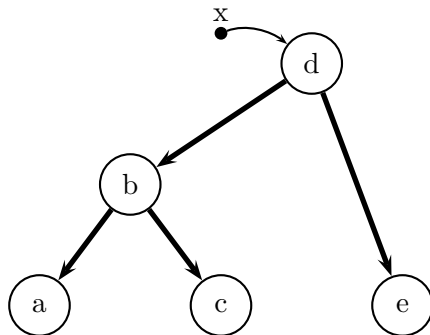
- which is also the worst-case complexity







- $x = \text{Right-Rotate}(x)$



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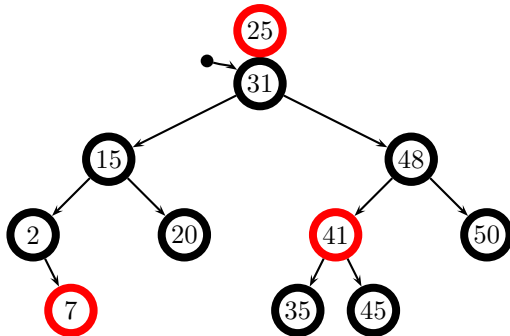
- $\text{RB-Insert}(T, z)$  works as in a binary search tree
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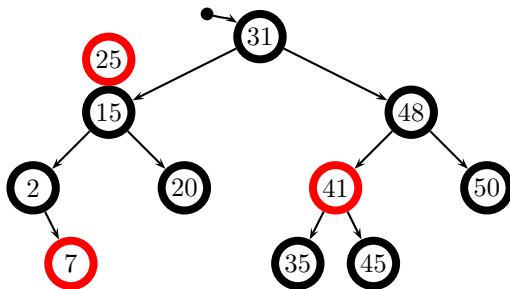
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- General strategy
  - ① insert  $z$  as in a binary search tree
  - ② color  $z$  **red** so as to preserve property 5
  - ③ fix the tree to correct possible violations of property 4

```
RB-Insert(T, z) 1  y = T.nil
                 2  x = T.root
                 3  while x  $\neq$  T.nil
                 4      y = x
                 5      if z.key < x.key
                 6          x = x.left
                 7      else x = x.right
                 8  z.parent = y
                 9  if y == T.nil
                10      T.root = z
                11  else if z.key < y.key
                12      y.left = z
                13      else y.right = z
                14  z.left = z.right = T.nil
                15  z.color = red
                16  RB-Insert-Fixup(T, z)
```

## Red-Black Insertion (2)

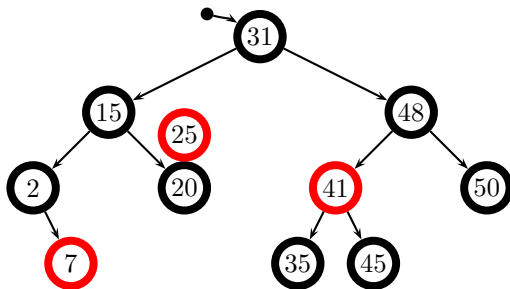


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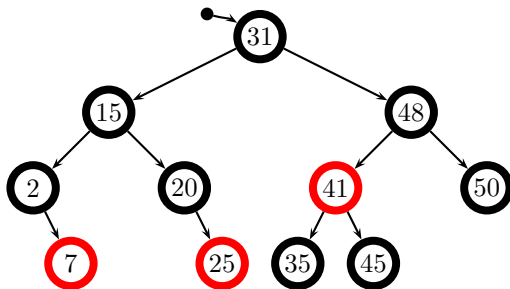




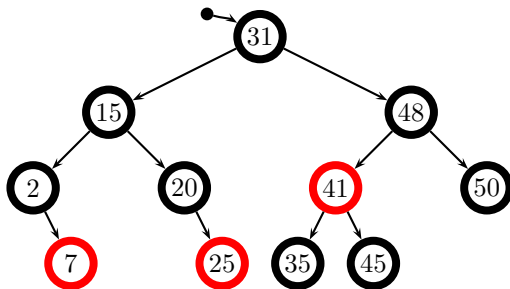
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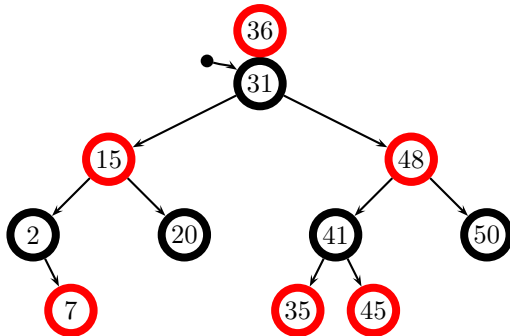
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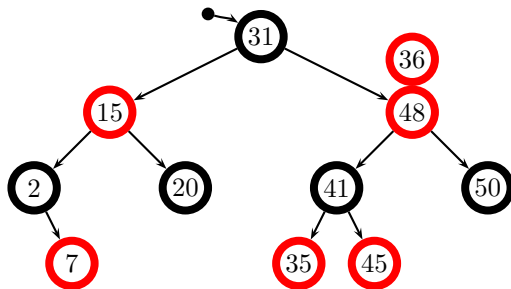
- z's father is black, so no fixup needed

# Red-Black Insertion (3)

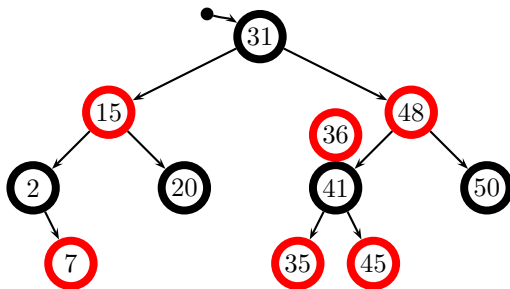
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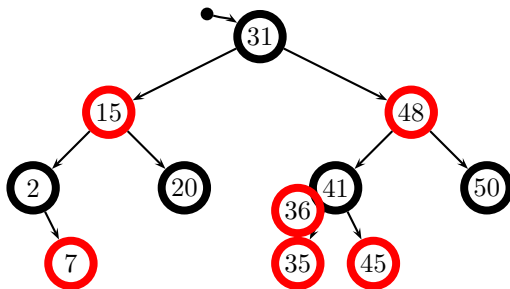
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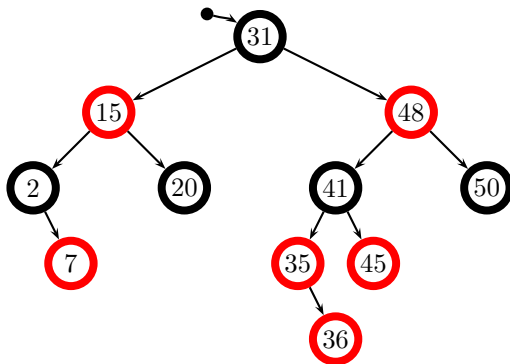


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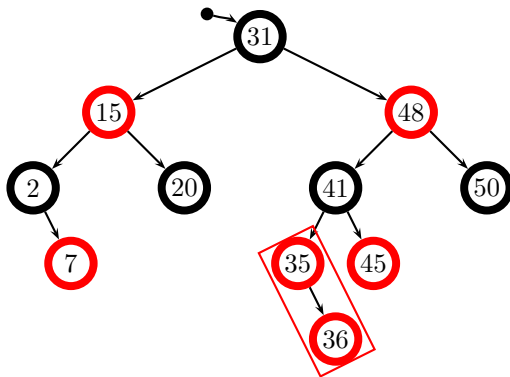




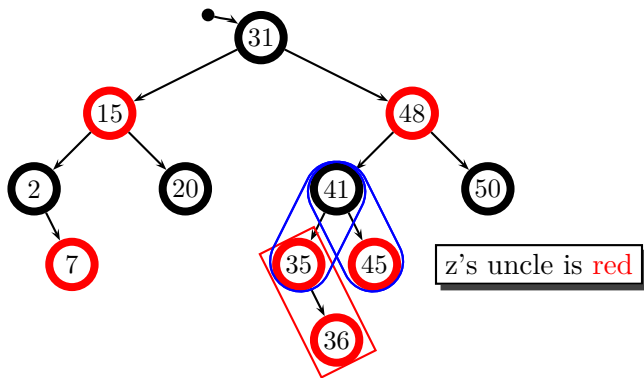
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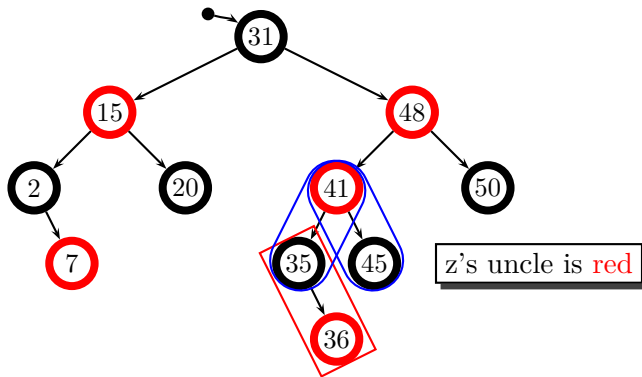
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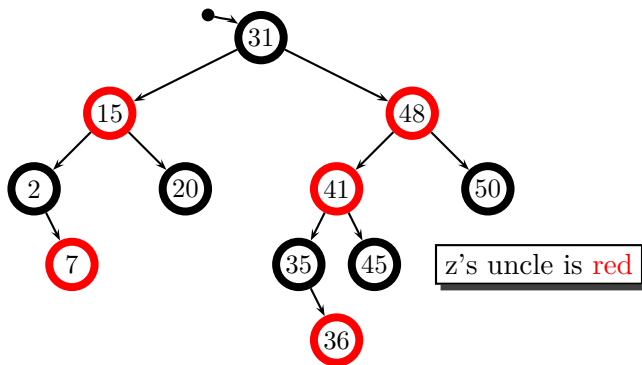
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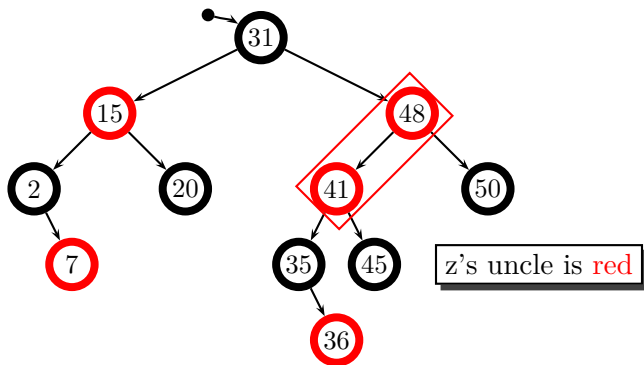
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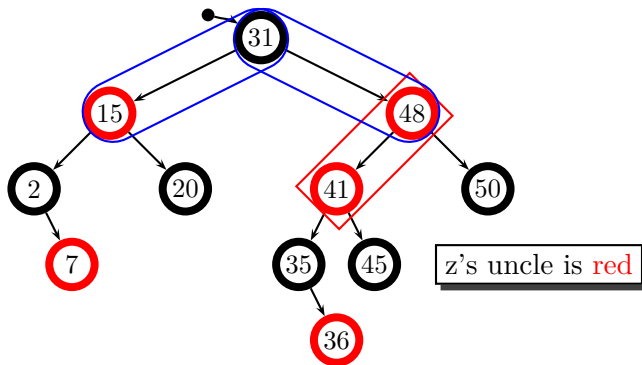
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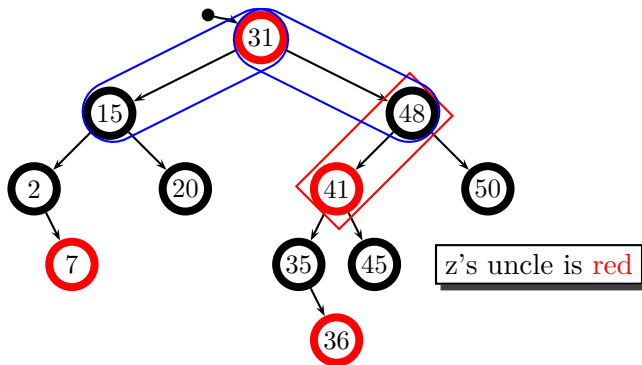
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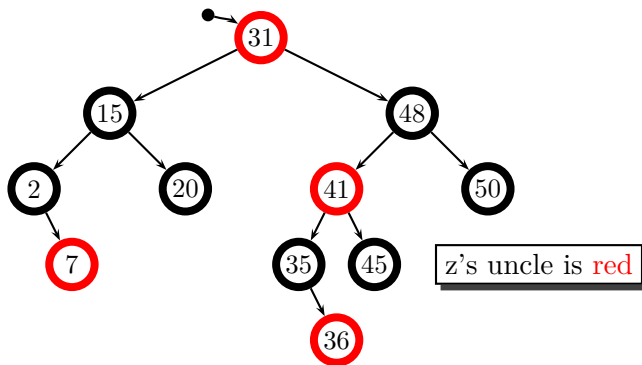


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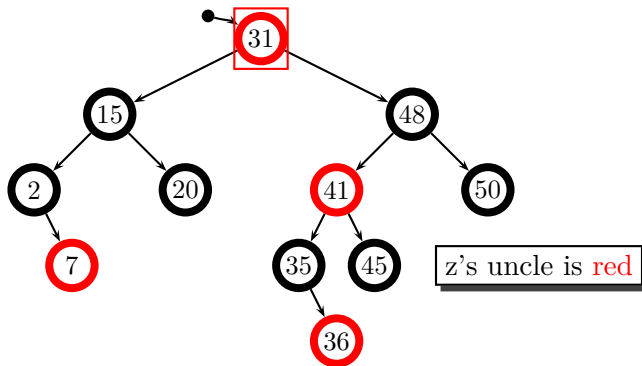




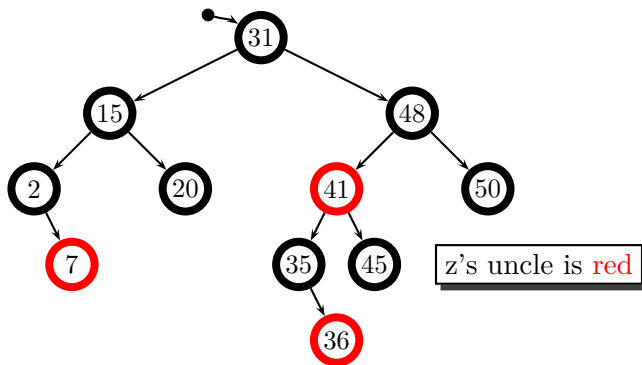
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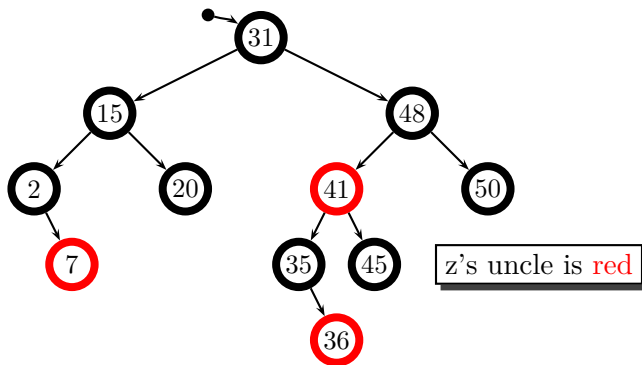
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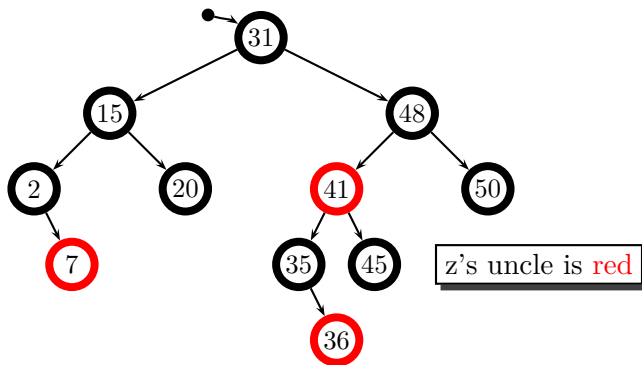


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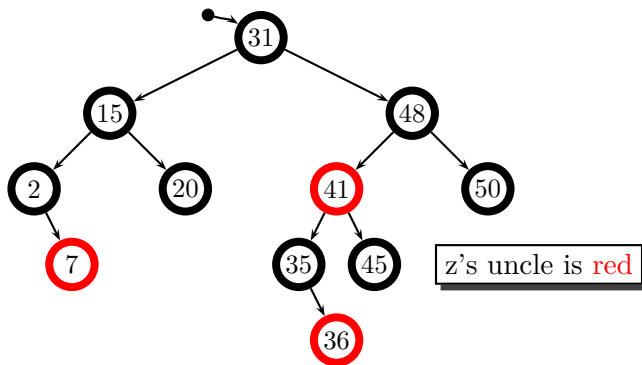
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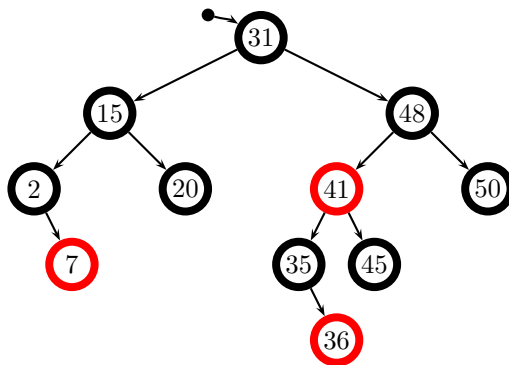
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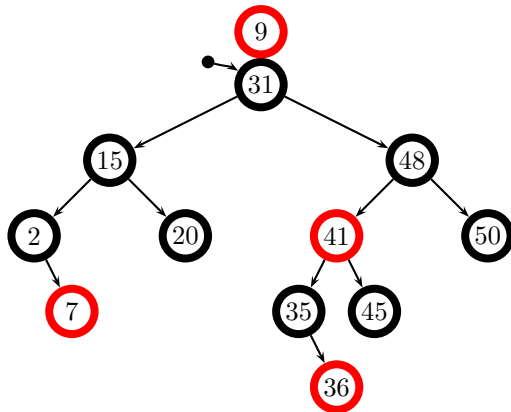


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- This may cause other red-red conflicts, so we iterate...
- The root can change to black without causing conflicts

## Red-Black Insertion (4)

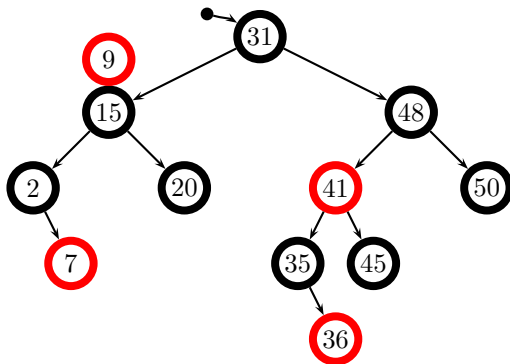


## Red-Black Insertion (4)

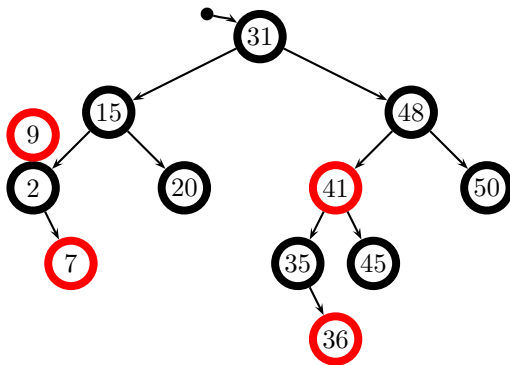




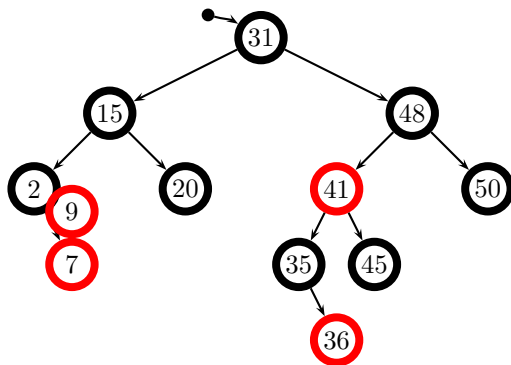
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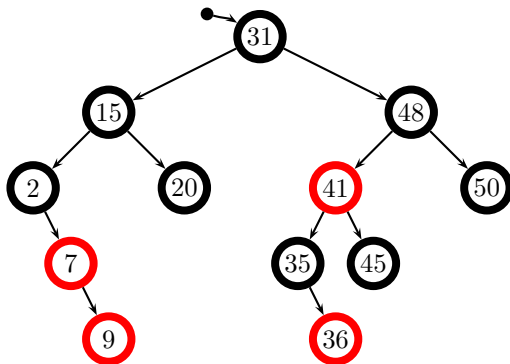
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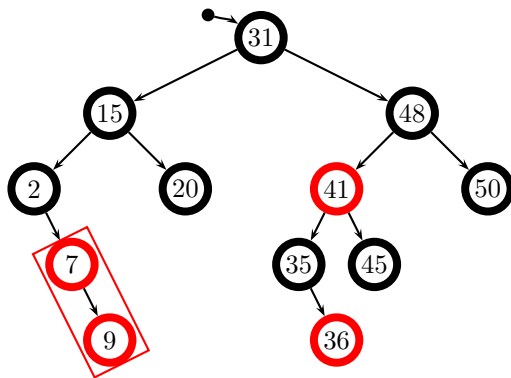
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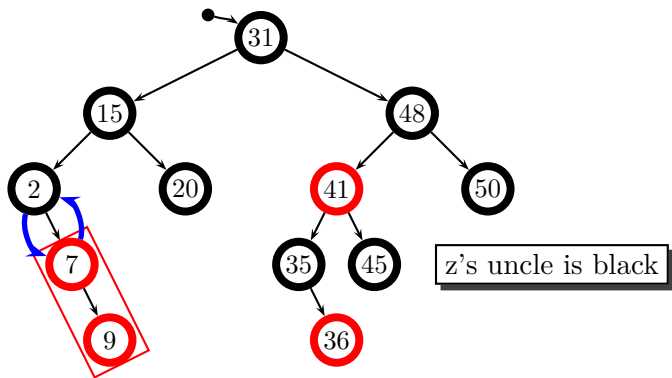
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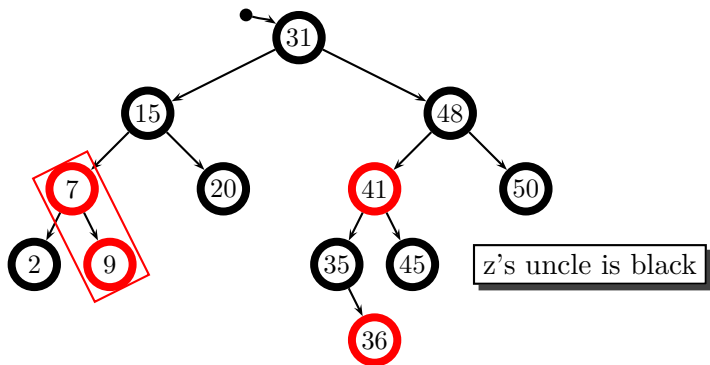
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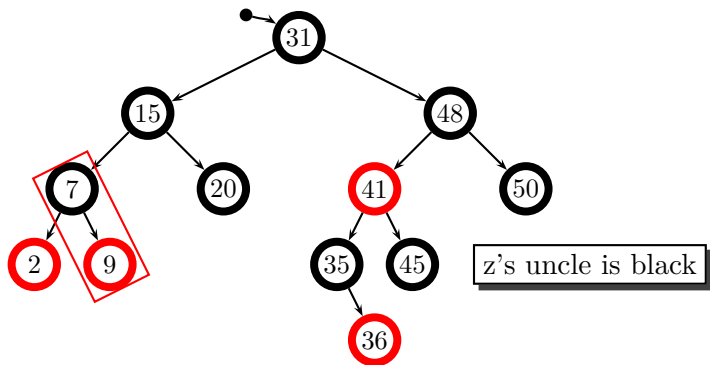
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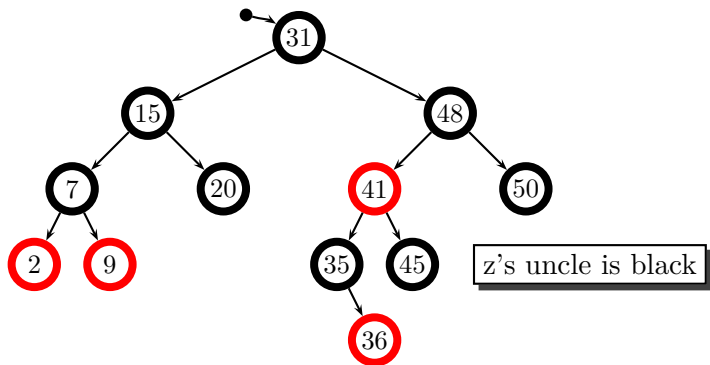


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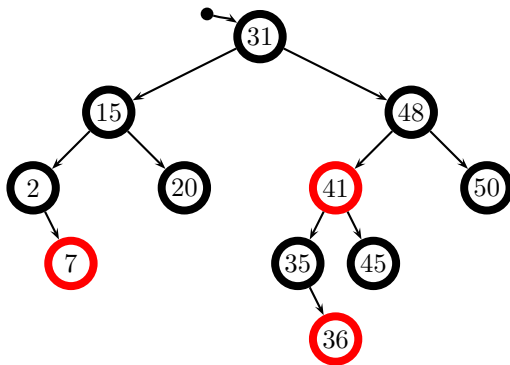


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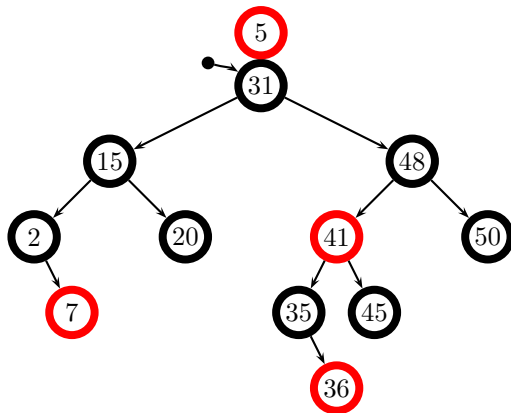


- An in-line **red-red** conflicts can be resolved with a rotation plus a color switch

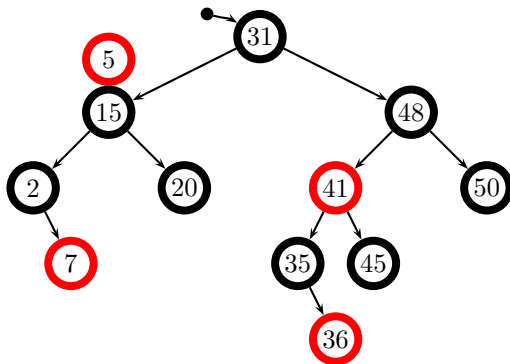
## Red-Black Insertion (5)



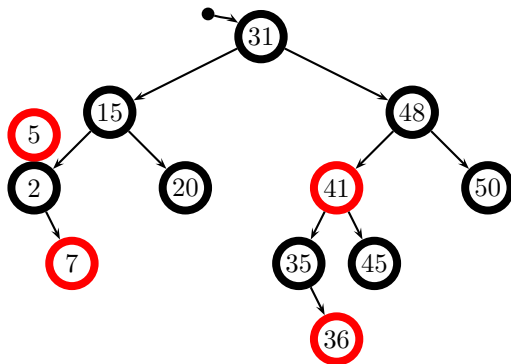
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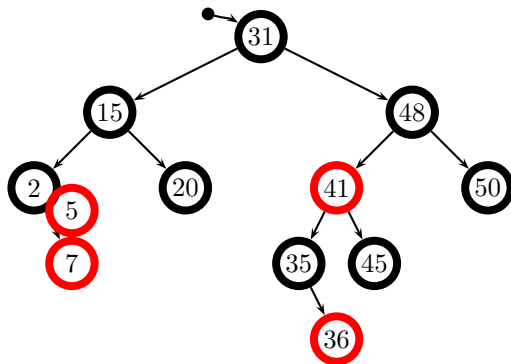
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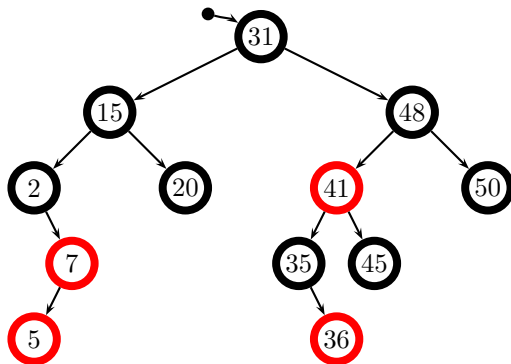
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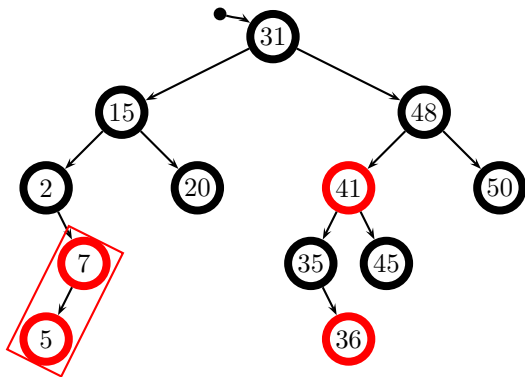
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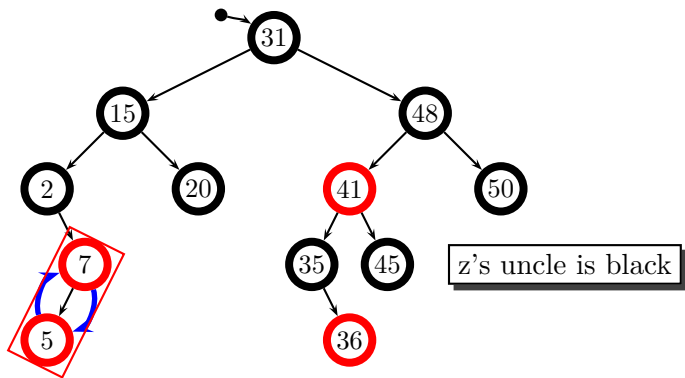


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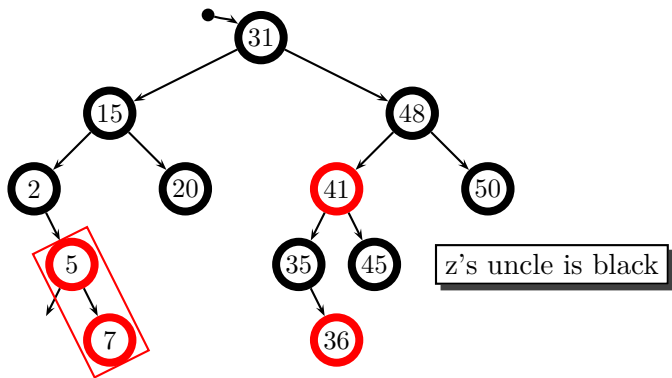




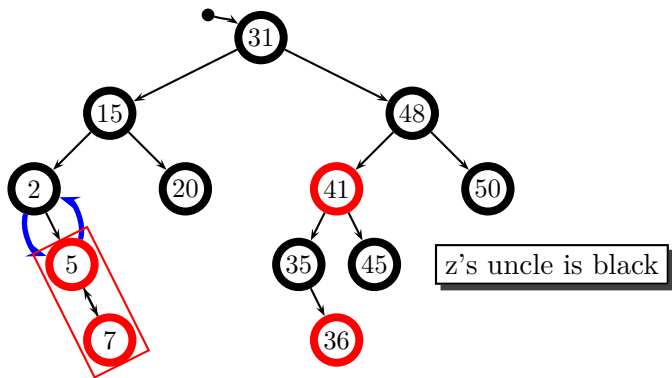
## Red-Black Insertion (5)



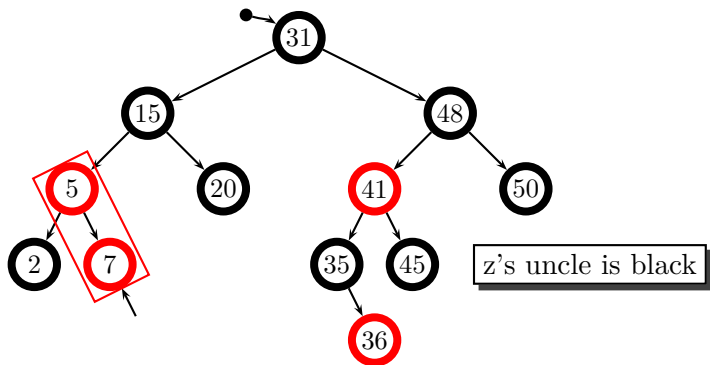
## Red-Black Insertion (5)



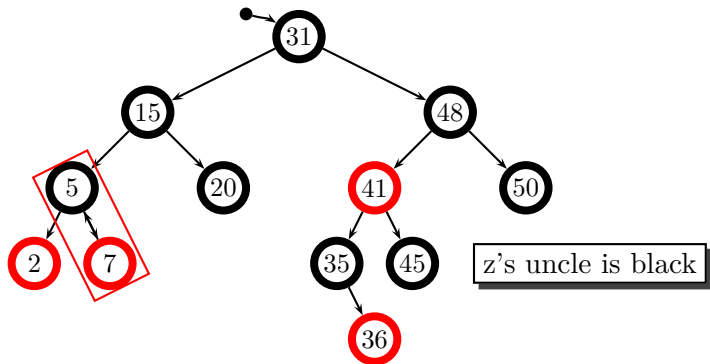
## Red-Black Insertion (5)



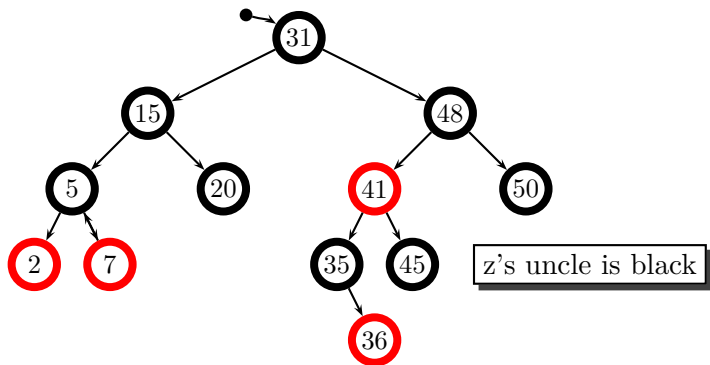
## Red-Black Insertion (5)



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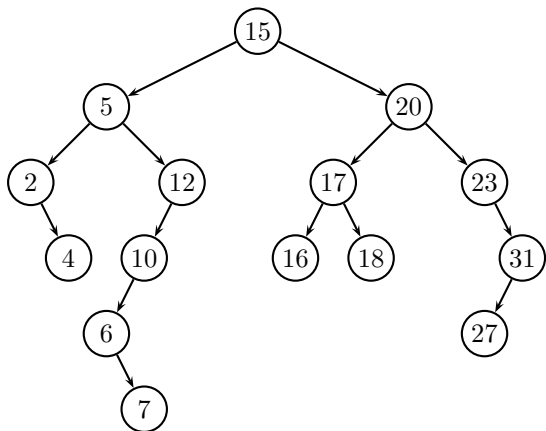
## Red-Black Insertion (5)



- A zig-zag **red-red** conflicts can be resolved with a rotation to turn it into an in-line conflict, and then a rotation plus a color switch

# Recap on Deletion in Binary Trees

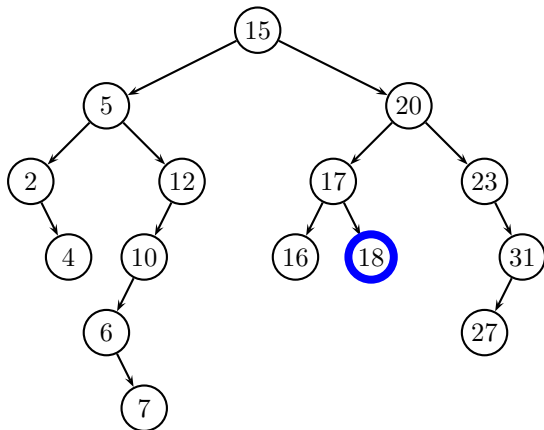
# Recap on Deletion in Binary Trees



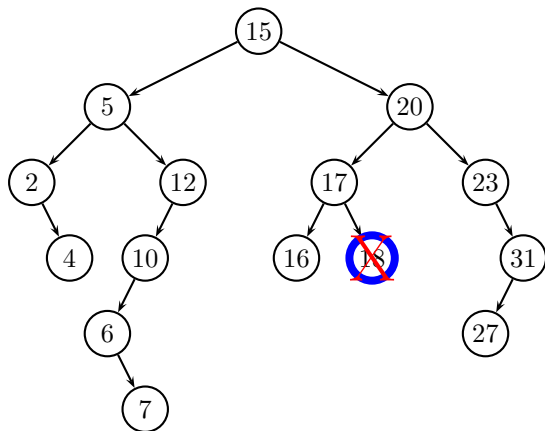


# Recap on Deletion in Binary Trees

1. z has no children

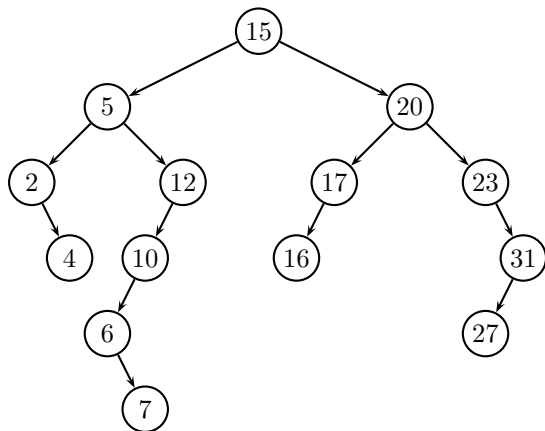


# Recap on Deletion in Binary Trees



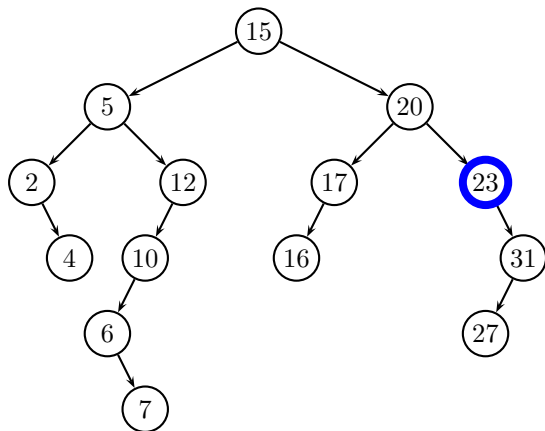
1. z has no children
  - ▶ simply remove z

# Recap on Deletion in Binary Trees



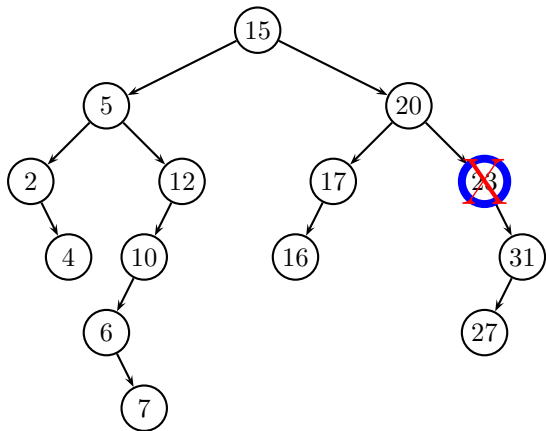
1. z has no children
  - ▶ simply remove z

# Recap on Deletion in Binary Trees



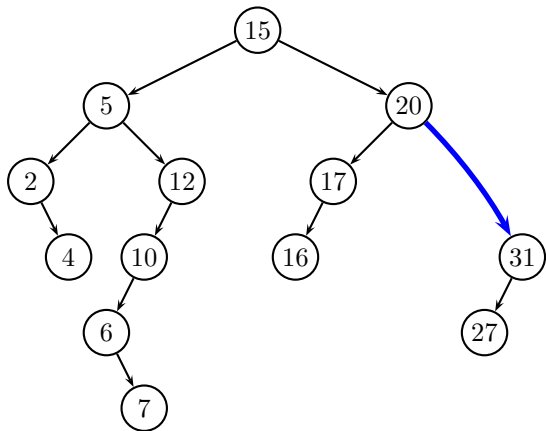
1. z has no children
  - ▶ simply remove z
2. z has one child

# Recap on Deletion in Binary Trees



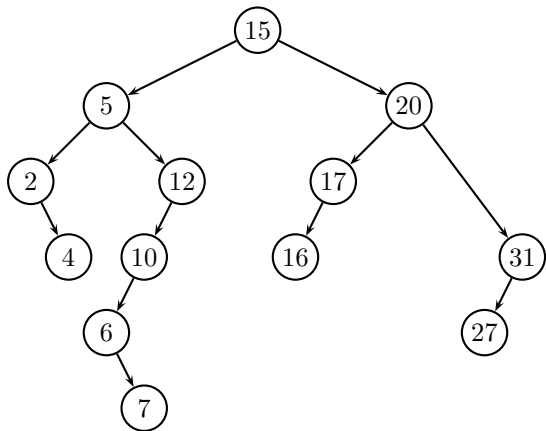
1. z has no children
  - ▶ simply remove z
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  - ▶ remove z

# Recap on Deletion in Binary Trees



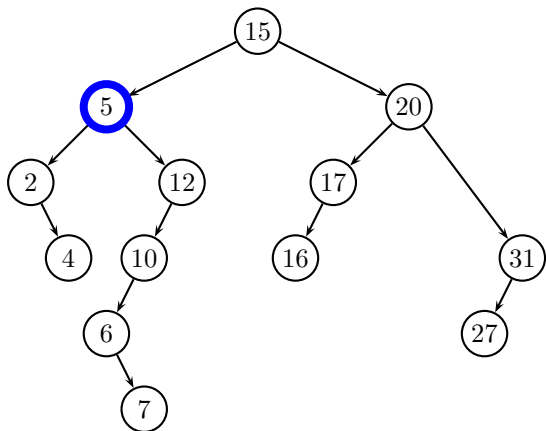
1. z has no children
  - ▶ simply remove z
2. z has one child
  - ▶ remove z
  - ▶ connect z.parent to z.right

# Recap on Deletion in Binary Trees



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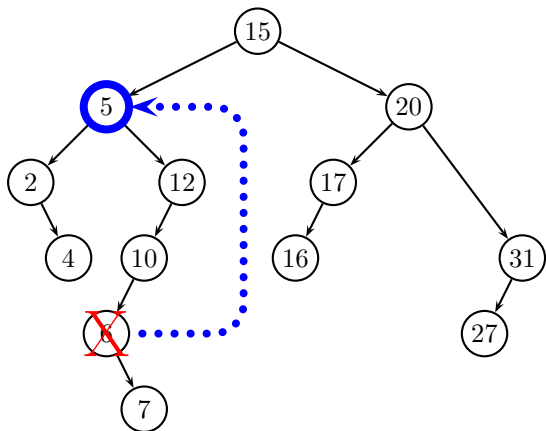
# Recap on Deletion in Binary Trees



1. z has no children
  - ▶ simply remove z
2. z has one child
  - ▶ remove z
  - ▶ connect z.parent to z.right
3. z has two children

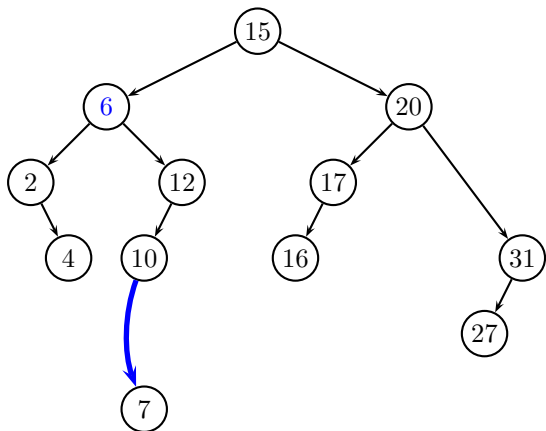


# Recap on Deletion in Binary Trees



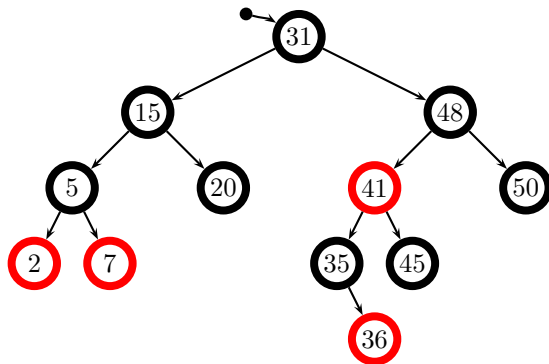
1.  $z$  has no children
  - ▶ simply remove  $z$
2.  $z$  has one child
  - ▶ remove  $z$
  - ▶ connect  $z.parent$  to  $z.right$
3.  $z$  has two children
  - ▶ replace  $z$  with  $y = \text{Tree-Successor}(z)$
  - ▶ remove  $y$  (1 child!)

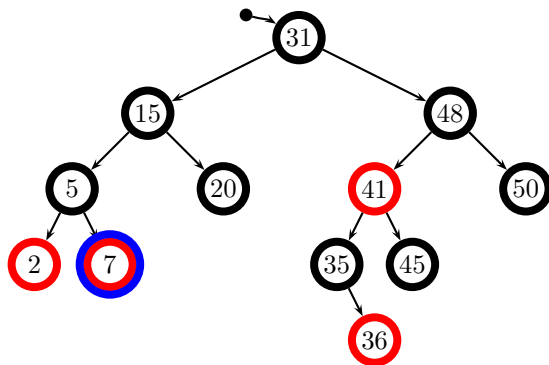
# Recap on Deletion in Binary Trees

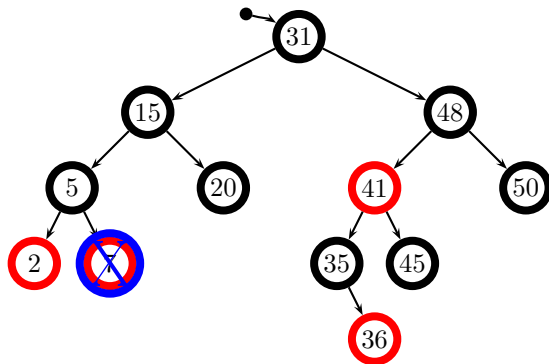


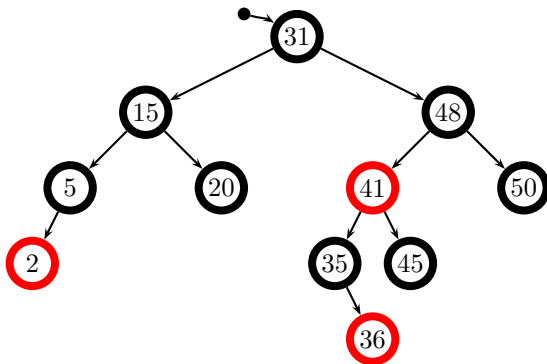
1.  $z$  has no children
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  - ▶ remove  $z$
  - ▶ connect  $z.parent$  to  $z.right$
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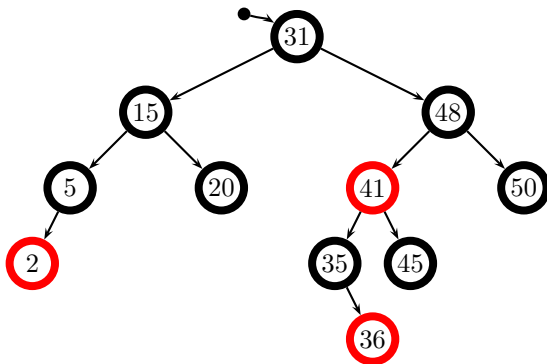
# Red-Black Deletion





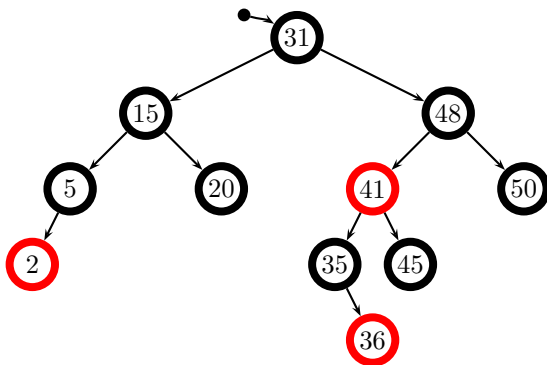




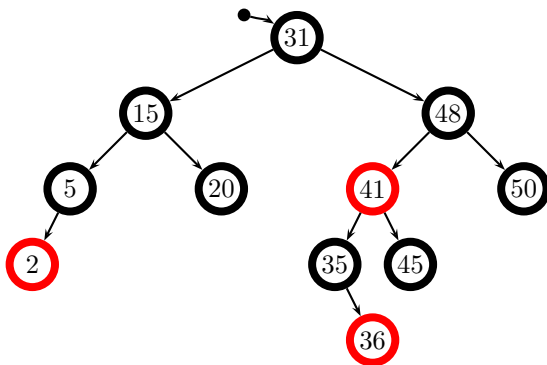


- A deleting a **red** leaf does not require any adjustment



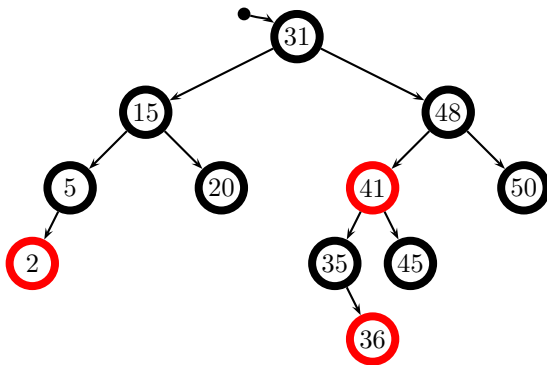


- A deleting a **red** leaf does not require any adjustment
  - ▶ the deletion does not affect the black height (property 5)

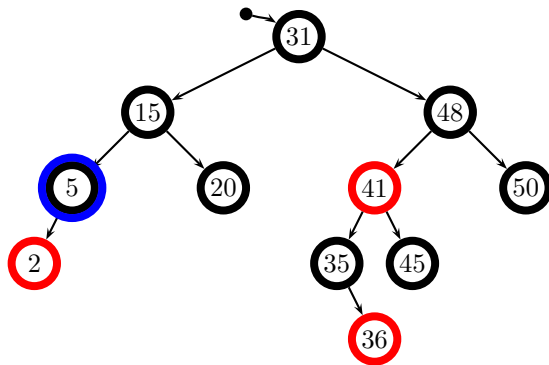


- A deleting a **red** leaf does not require any adjustment
  - ▶ the deletion does not affect the black height (property 5)
  - ▶ no two red nodes become adjacent (property 4)

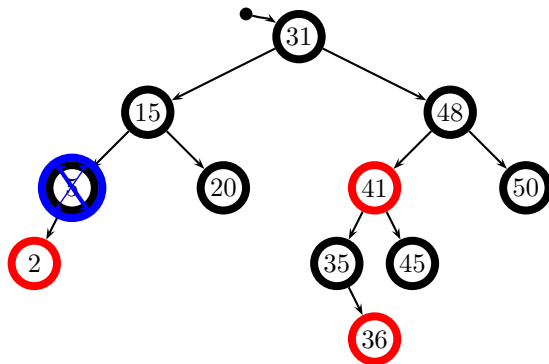
## Red-Black Deletion (2)



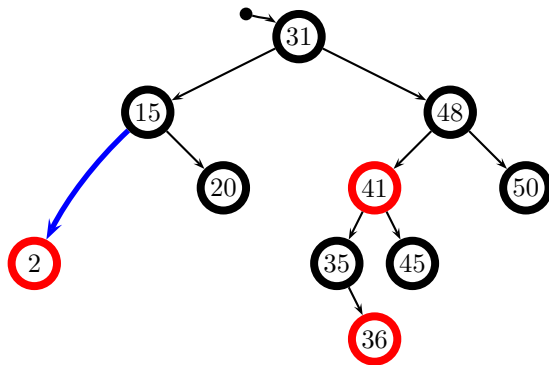
## Red-Black Deletion (2)



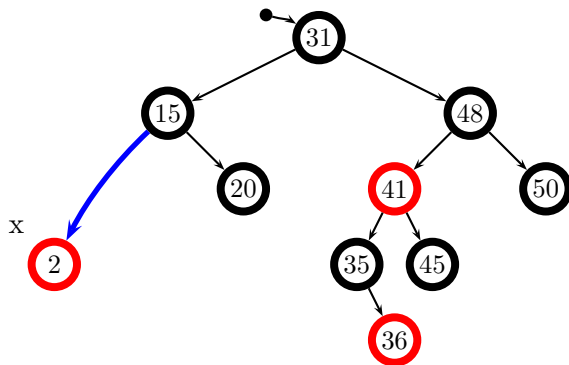
## Red-Black Deletion (2)



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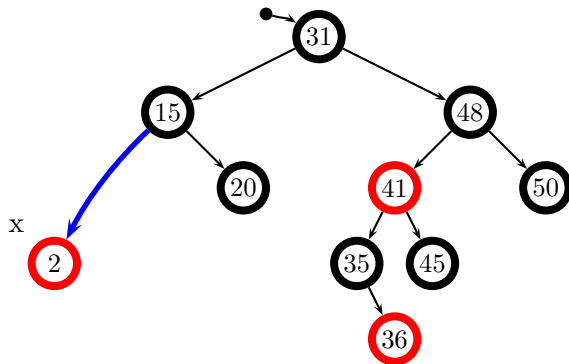


## Red-Black Deletion (2)



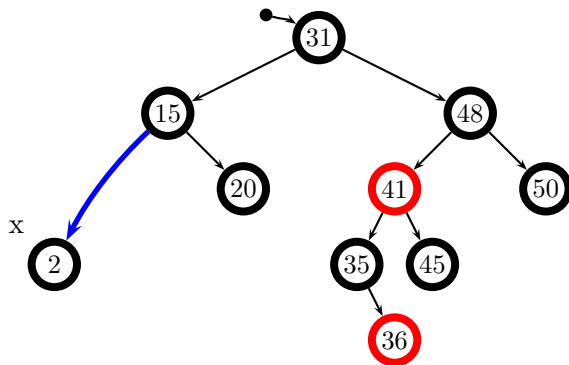
- Deleting a black node changes the balance of black-height in a subtree x

## Red-Black Deletion (2)



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  - ▶  $\text{RB-Delete-Fixup}(T, x)$  fixes the tree after a deletion





- Deleting a black node changes the balance of black-height in a subtree  $x$ 
  - ▶  $\text{RB-Delete-Fixup}(T, x)$  fixes the tree after a deletion
  - ▶ in this simple case:  $x.\text{color} = \text{black}$

# Fixup Conditions

- $y$  is the spliced node ( $y = z$  if  $z$  has zero or one child)
  - ▶ if  $y$  is red, then no fixup is necessary
  - ▶ so, here we assume that  $y$  is black

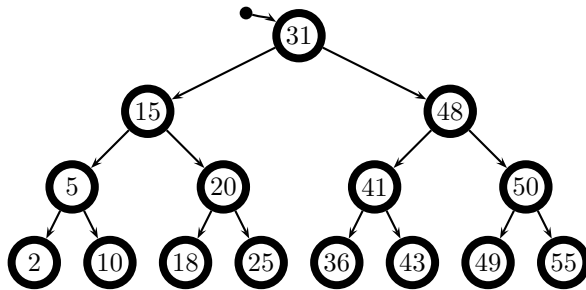
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  - ▶ if  $y$  is red, then no fixup is necessary
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- $x$  is either  $y$ 's only child or  $T.nil$ 
  - ▶  $y$  was spliced out, so  $y$  can not have two children
  - ▶  $x = T.nil$  iff  $y$  has no (key-bearing) children

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- Problem 1:  $y = T.root$  and  $x$  is red
  - ▶ violates red-black property ?? (root must be black)

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- **Problem 2:** both  $x$  and  $y.parent$  are **red**
  - ▶ violates red-black property 4 (no adjacent red nodes)

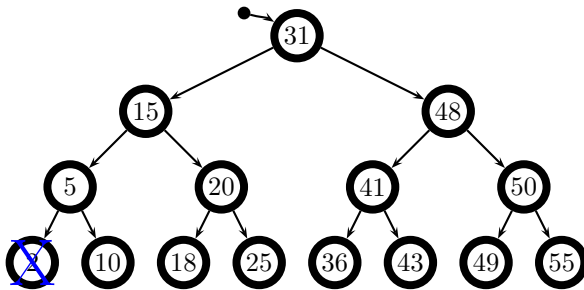
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- Problem 2: both  $x$  and  $y.parent$  are red
  - ▶ violates red-black property 4 (no adjacent red nodes)
- Problem 3: we are removing  $y$ , which is black
  - ▶ violates red-black property 5 (same black height for all paths)

## Red-Black Deletion (3)

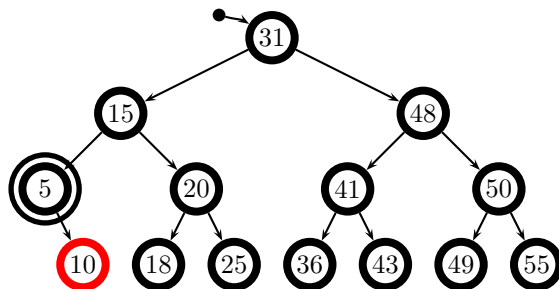




## Red-Black Deletion (3)

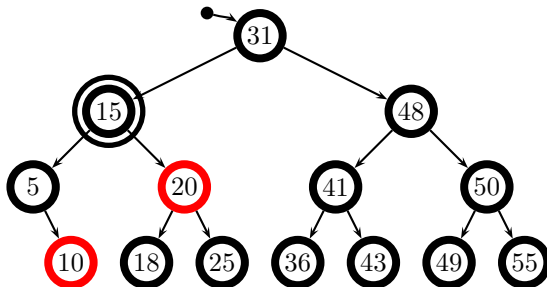


## Red-Black Deletion (3)



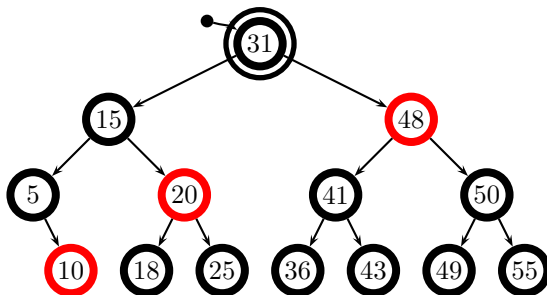
- x carries an additional black weight
  - ▶ the fixup algorithm pushes it up towards to root

## Red-Black Deletion (3)



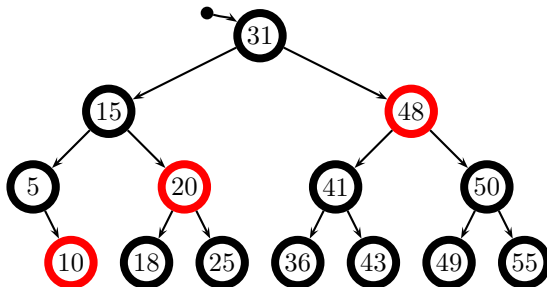
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## Red-Black Deletion (3)



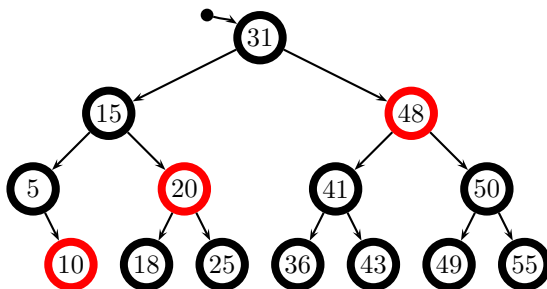
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## Red-Black Deletion (3)



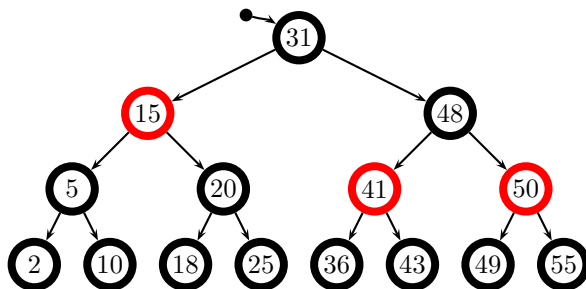
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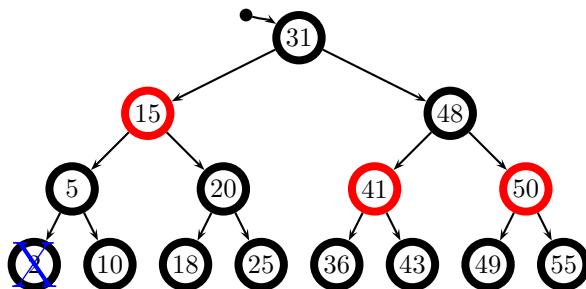


- x carries an additional black weight
  - ▶ the fixup algorithm pushes it up towards to root
- The additional black weight can be discarded if it reaches the root, otherwise...

## Red-Black Deletion (4)

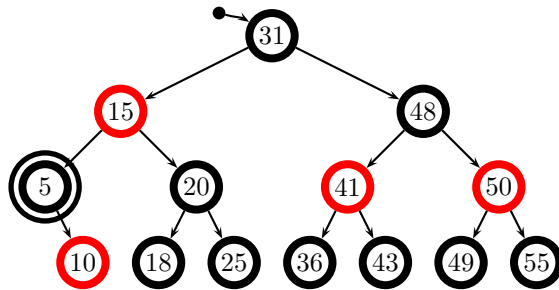


## Red-Black Deletion (4)

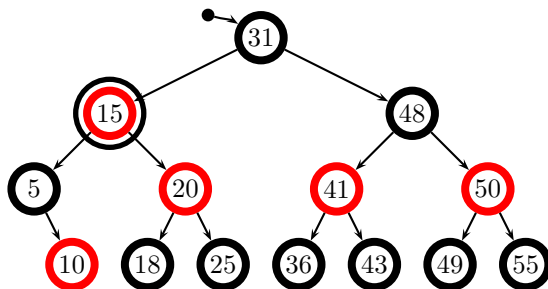




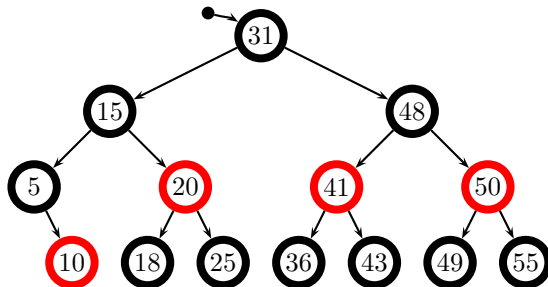
## Red-Black Deletion (4)



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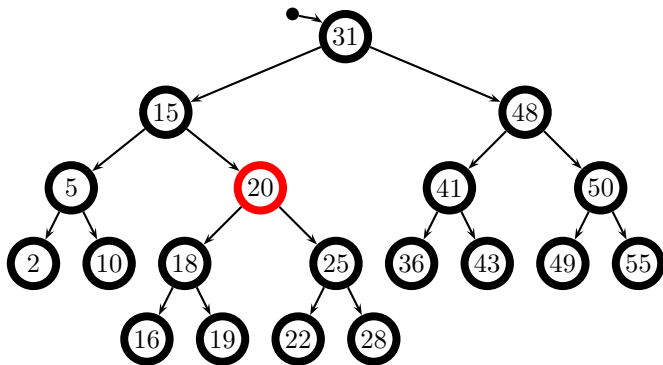


## Red-Black Deletion (4)

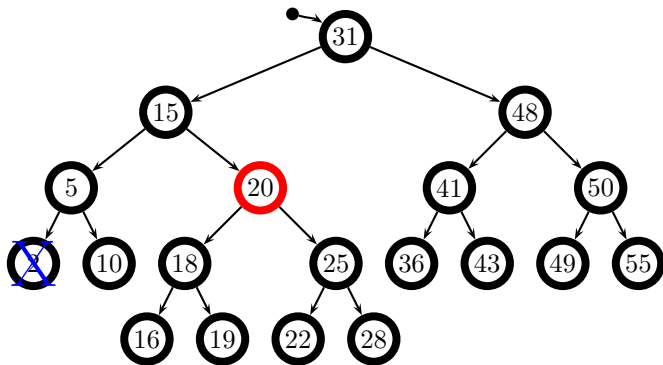


- The additional black weight can also stop as soon as it reaches a **red** node, which will absorb the extra black color

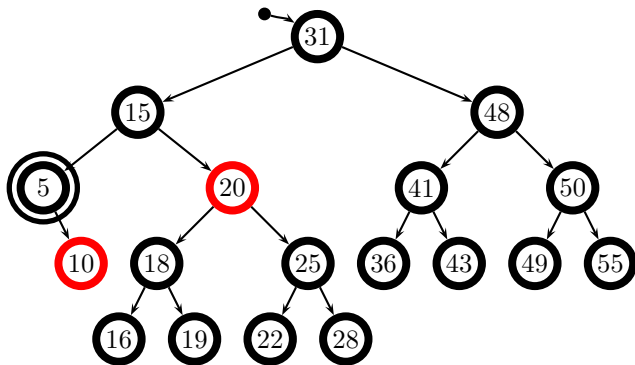
## Red-Black Deletion (5)



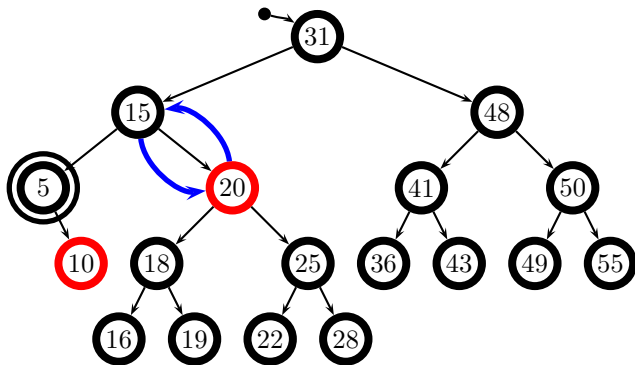
## Red-Black Deletion (5)



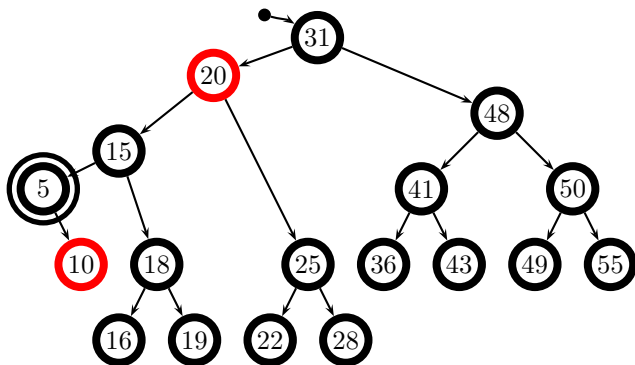
## Red-Black Deletion (5)



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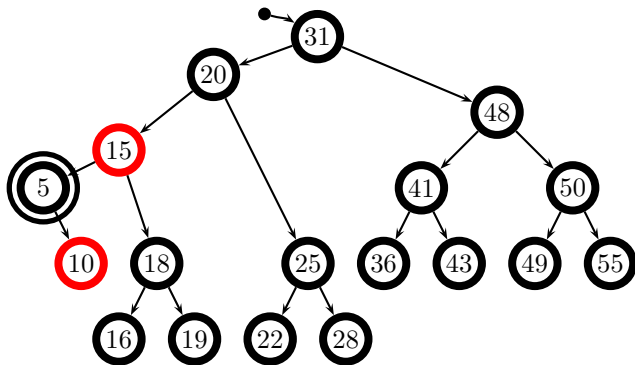


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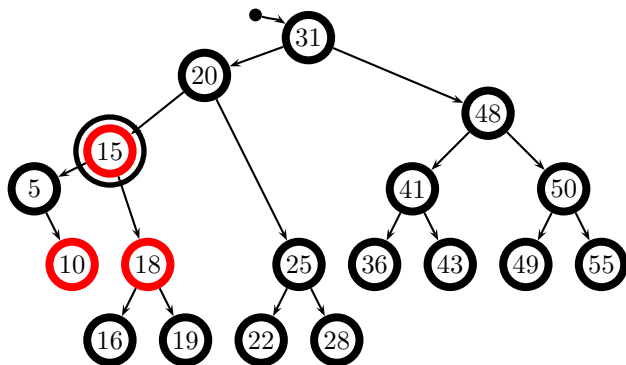




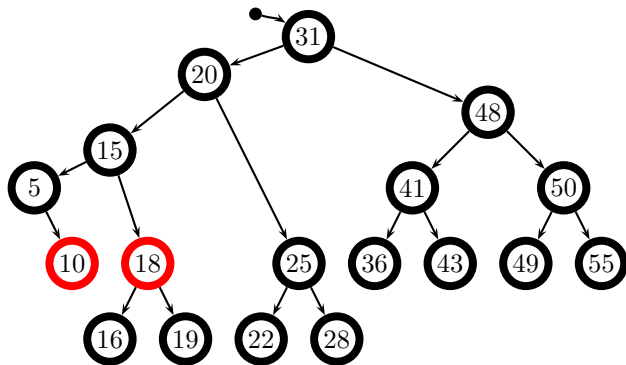
## Red-Black Deletion (5)

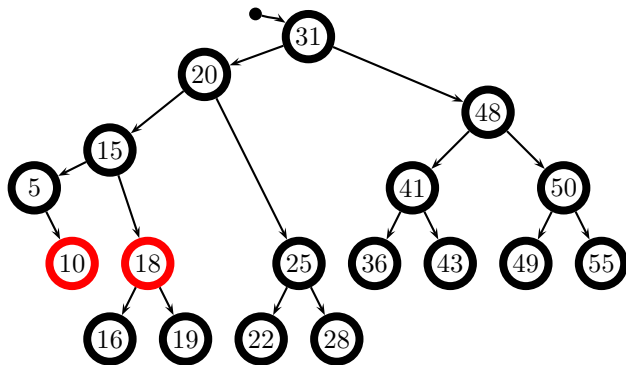


## Red-Black Deletion (5)



## Red-Black Deletion (5)





- In other cases where we can not push the additional black color up, we can apply appropriate rotations and color transfers that preserve all other red-black properties

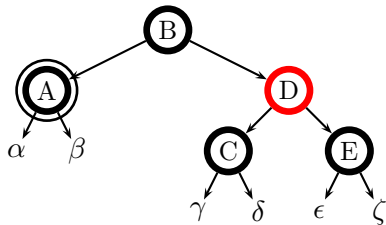
# Basic Fixup Iteration (1)

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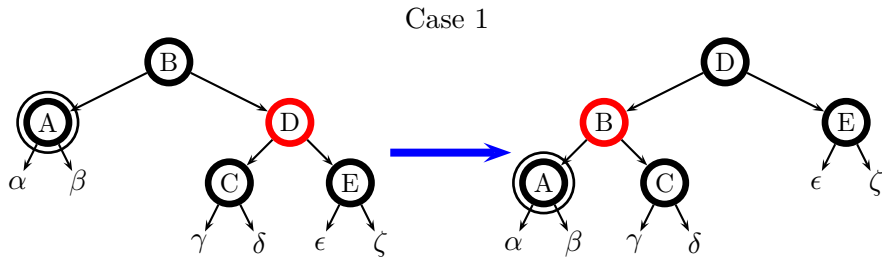
Case 1

# Basic Fixup Iteration (1)

Case 1

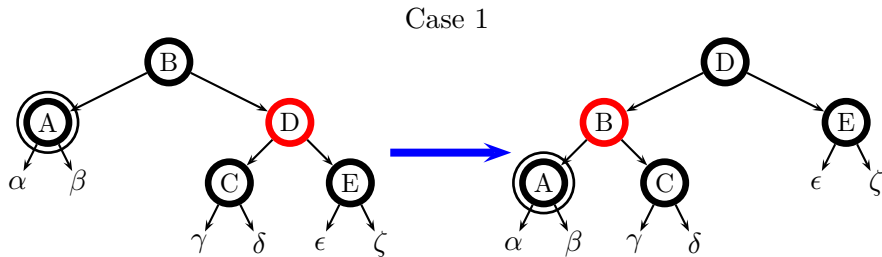


# Basic Fixup Iteration (1)





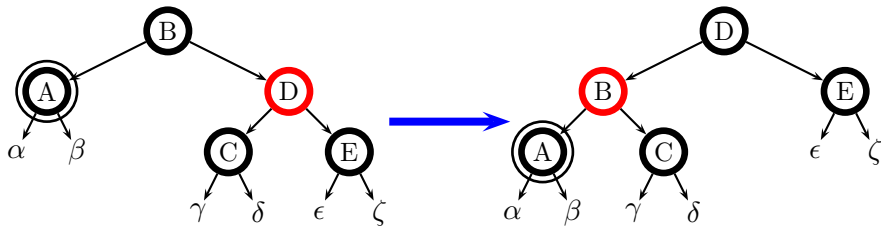
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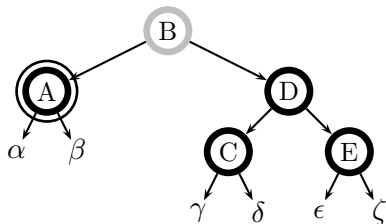
Case 2

# Basic Fixup Iteration (1)

Case 1

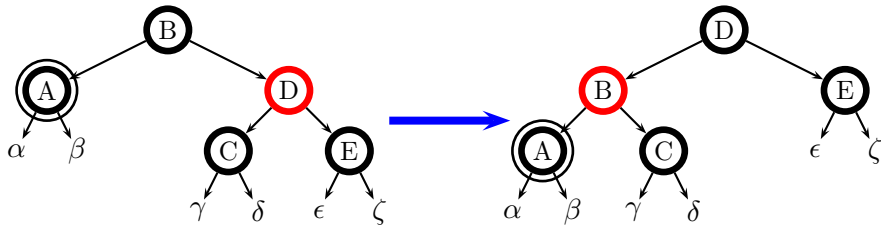


Case 2

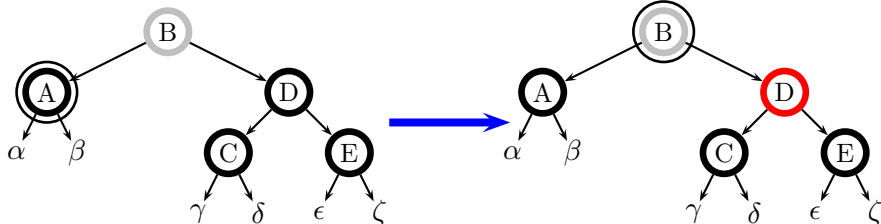


# Basic Fixup Iteration (1)

Case 1



Case 2

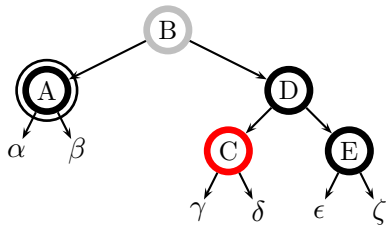


# Basic Fixup Iteration (2)

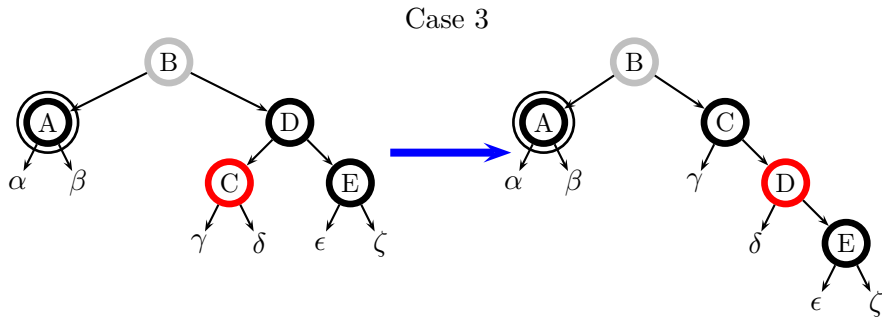
## Case 3

## Basic Fixup Iteration (2)

Case 3

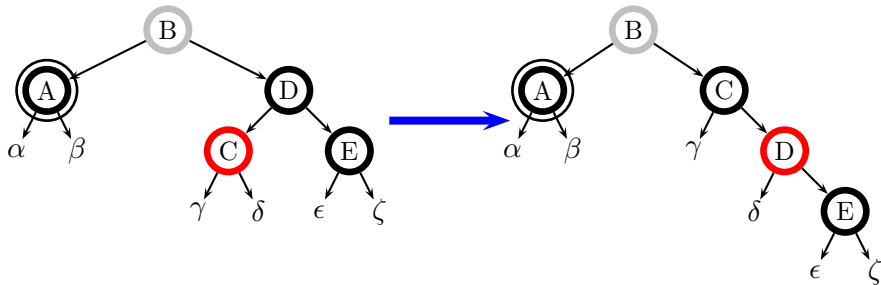


## Basic Fixup Iteration (2)

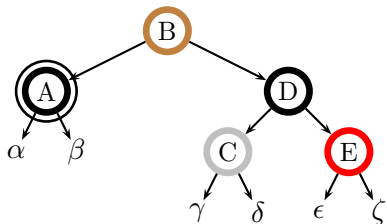


## Basic Fixup Iteration (2)

Case 3

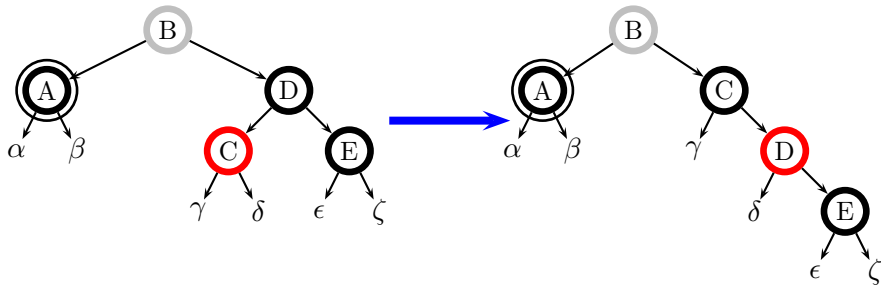


Case 4

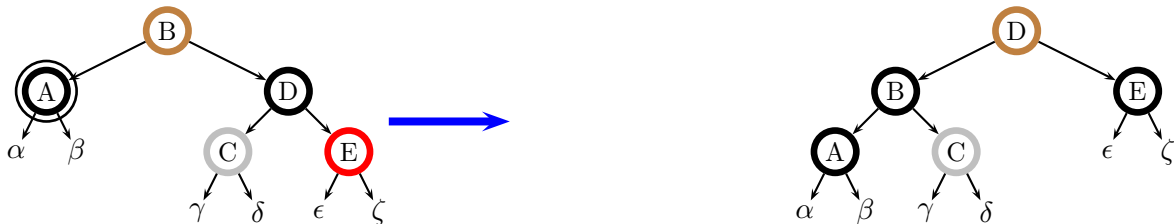


## Basic Fixup Iteration (2)

Case 3



Case 4





# Red-Black Delete Fixup

```
RB-Delete-Fixup(T, x) 1 while  $x \neq T.root \wedge x.color = black$ 
                        2     if  $x == x.parent.left$ 
                        3          $w = x.parent.right$ 
                        4         if  $w.color == red$ 
                        5             case 1...
                        6         if  $w.left.color == black \wedge w.right.color = black$ 
                        7              $w.color = red$  // case 2
                        8              $x = x.parent$ 
                        9         else if  $w.right.color == black$ 
                        10             case 3...
                        11             case 4...
                        12         else same as above, exchanging right and left
                        13      $x.color = black$ 
```