

# Learning, Hypothesis Testing and Nash Equilibrium

Foster & Young (2003)

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# Introduction

## 1. Context

## 2. Paper

- Main Result

- Helper results

- Tools

- Lemma

## 3. Getting further

# Previously in Game Theory

- If players are rational, good predictors, and learn deterministically, there are many games for which neither beliefs nor actions converge to a Nash equilibrium.
- Trivial algorithm (search the space of mixed strategies) dynamically converging to NE
- For some games, using fictitious play leads to Nash equilibrium.
- Knowing the appropriate Bayesian NE prior makes all limit points of the posterior to be also Bayesian NE.
- Assigning positive probabilities in players' prior belief to all events with actual positive probability leads to guarantee of reaching  $\varepsilon$ -equilibrium with probability one.
- Predicting the past i.e. conditional regret minimization.

# Main result

## Theorem (Foster & Young, 1998-2003)

*Let  $G$  be a finite, normal-form,  $n$ -person game and let  $\varepsilon \geq 0$ . If the players are almost rational, use sufficiently powerful hypothesis tests with comparable amount of data, and are flexible in their adoption of new hypothesis, then at least  $1 - \varepsilon$  of the time:*

- I Their repeated-game strategies are  $\varepsilon$ -close to subgame perfect equilibrium,*
- II All players are  $\varepsilon$ -good predictors.*

Implied the assumption of continuity of  $A_i^{\sigma_i}$

# Towards the proof

1. Powerful family of tests
2. Upper bounds on errors
3. Fairly good model
4. Guarantees for responses

Then prove convergence in probability and  $\varepsilon$ -closeness to beliefs.

Two points of anchor:

- Fixed-point theorem
- Hypothesis testing tools

# Bounds

$$\alpha_{i,s_i} \leq k_i(\tau) e^{-r_i(\tau)s_i} \quad (\text{Upper bound on type-I error})$$

$$\beta_{i,s_i,\tau} \leq k_i(\tau) e^{-r_i(\tau)s_i} \quad (\text{Upper bound on type-II error})$$

$$\alpha_{i,s} \leq \sum_{j=\lceil \kappa/2 \rceil}^{\kappa} \binom{\kappa}{j} \alpha^j (1-\alpha)^{\kappa-j} \leq [\dots] \leq \alpha (4\alpha(1-\alpha))^{\lceil \kappa/2 \rceil}$$

$$\text{Diffusion: } \forall \tau > 0 \quad \alpha_{i,s_i,\tau} \leq \left(1 + \frac{\tau}{\xi}\right)^{s_i} \alpha_{i,s_i}$$

$$q(R) = \sum_{\bar{\omega}^{t-1} \in R} \prod_t q(\omega^t | \bar{\omega}^{t-1}) \leq \sum_{\bar{\omega}^{t-1} \in R} \prod_t p(\omega^t | \bar{\omega}^{t-1}) \cdot \left(1 + \frac{\tau}{\xi}\right) = \left(1 + \frac{\tau}{\xi}\right)^{s_i} p(R)$$

Why we needed that?

$$\beta_{i,s_i,\tau} \leq k_i(\tau) e^{-r_i(\tau)s_i/2}$$

There exists  $c_i(\tau) \leq \tau$  such that

$$\alpha_{i,s_i,c_i(\tau)} \leq k_i(\tau) e^{-r_i(\tau)s_i/2}$$

# Lemma

We call model vector  $\vec{\phi}$  to be fairly good if it is good for all responsive players. We denote it to be good if it is good for all players, meaning  $|\phi_i - P_i(A^{\vec{\sigma}}(\vec{\phi}))| \leq \tau$  holds for player  $i$  (otherwise it is bad for  $i$ ). Finally, we call it bad if it is not fairly good.

## Theorem

*The model vector  $\vec{\phi}^t$  is fairly good at least  $1 - \varepsilon$  of the time.*

Consider the following process to reach a great state from a bad state.

1. Player 1 alone is testing and rejects his hypothesis and accepts a model reasonably close to  $\phi_i^*$  but still wrong.
2. Then one after another the other players test their hypothesis and adopt a model within  $\gamma$  of  $\phi_j^*$
3. Player 1 starts a new test and now adopts  $\phi_1^*$
4. Don't start a test for  $(n + 2)s_*$

# Almost done

## Theorem

*We assume that for the conditions described in the main theorem, the participants use  $M$  memory hypotheses for which they employ suitable hypothesis tests with comparable amount of data.*

*Moreover we assume that the engaged players have  $\sigma_i$ -smoothed best response functions. Let  $\varepsilon > 0$ . There exist functions  $\sigma(\varepsilon)$ ,  $\tau(\varepsilon, \sigma)$  and  $s(\varepsilon, \sigma, \tau)$  bounding the corresponding parameters.*

*Then at least  $1 - \varepsilon$  of the time  $t$ :*

- I  $|a^t - A^{\vec{\sigma}}(P(\vec{a}^t))| \leq \varepsilon/2$  *the responses are close to being a fixed point*
- II  $|U_i^t(a_i^t, P_i(\vec{a}^t)) - \max_{a'_i} U_i^t(a'_i, P_i(\vec{a}^t))| \leq \varepsilon$  for all players  $i$  *the responses are  $\varepsilon$ -optimal*
- III  $|\phi_i^t - P_i(A^{\sigma_i}(\vec{\phi}^t))| \leq \varepsilon$  for all players  $i$  *the models are within  $\varepsilon$  of being correct*

Due to the previous result, we have that  $\vec{\phi}^t$  is fairly good at least  $1 - \varepsilon$  of the time. Thus  $|\phi_i - P_i(A^{\vec{\sigma}}(\vec{\phi}))| \leq \tau$ . Now use continuity!



# Several extra ideas

- More practical guarantees
- Unscrupulous diner's dilemma (gambit)
- Better bounds

Room for discussion