

Lecture 11

Last time

- ▷ Best low-rank approximation
- ▷ Perturbation theory for eigenvalues
- ▷ Distances between subspaces

Today

- ▷ Distances continued.
- ▷ Davis-Kahan Sin θ Theorem

Distances and angles between subspaces

Last time we ended with 3 notions of distances between subspaces

1) Distance with optimal rotation

$$\text{dist}_{\| \cdot \|_F} (U, U^*) = \min_{R \in O(r)} \| U R - U^* \|_F.$$

e.g., Frobenius, operator

2) Distance between projections

$$\| U V^T - U^* (V^*)^T \|_F$$

This matrix projects onto U .

3) Principal angles.

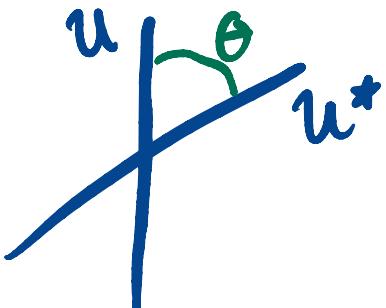
Let $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r \geq 0$ be the singular values of $V^T U^*$. Let $\theta_i = \arccos \sigma_i$ and let

$$\Theta = \begin{bmatrix} \theta_1 & & \\ & \ddots & \\ & & \theta_r \end{bmatrix}, \quad \sin \Theta = \begin{bmatrix} \sin \theta_1 & & \\ & \ddots & \\ & & \sin \theta_r \end{bmatrix}$$

We measure

$$\|\sin \Theta\|.$$

Interpretation: The angle between a couple of 1D subspaces is clearly defined



What's the angle between a couple of 2D subspaces?

The idea is to define a set of angles instead of just one angle.

The first principle angle

$$\theta_1 = \min_{\substack{u \in U \cap S^{d-1} \\ v \in U^* \cap S^{d-1}}} \angle(u, v) \quad (\alpha)$$

$$= \min_{\substack{u \in U \cap S^{d-1} \\ v \in U^* \cap S^{d-1}}} \arccos(\langle u, v \rangle)$$

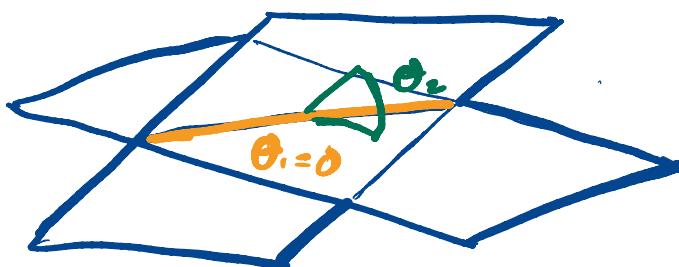
Let u_1 and v_1 be the minimizers in (a). Note that they minimize $\arccos(\langle u, v \rangle)$ iff they maximize $\langle u, v \rangle$ $\xrightarrow{\text{cose.}}$

Exercise: Convince yourself that u_1, v_1 are the top singular vectors of $U^T U^*$.

Then, we can inductively define

$$\theta_2 = \min_{\substack{u \in (u_1 \setminus \text{span}(u_1)) \cap S^{d-1} \\ v \in (v_1 \setminus \text{span}(v_1)) \cap S^{d-1}}} \arccos(\langle u, v \rangle)$$

Pictorially



Comparison between different "distances"

For our purposes any of these three distances are the "same."

Lemma 43 (Lemmas 2.5 & 2.6 in Chen, Chi, Fan & Ma 2021) Let $U \in \mathbb{R}^{n \times r}$ and $U^* \in \mathbb{R}^{n \times r}$.

Then,

$$\|UU^T - U^*U^{*T}\|_F = \|\sin \Theta\|_{op} = \|U_U^T U^*\|_{op} = \|U^T U_U^*\|_{op}$$

$$\frac{1}{\sqrt{2}} \| VV^T - V^*V^{*\top} \| = \| \sin \Theta \|_F = \| V_L^T V^* \|_F = \| V^T V_L^* \|_F$$

and, further

$$\| VV^T - V^*V^{*\top} \|_{op} \leq \min_{R \in O(r)} \| VR - R^* \|_{op} \leq \sqrt{2} \| VV^T - V^*V^{*\top} \|_{op}$$

$$\frac{1}{\sqrt{2}} \| VV^T - V^*V^{*\top} \|_F \leq \min_{R \in O(r)} \| VR - R^* \|_F \leq \| VV^T - V^*V^{*\top} \|_F$$

Thus, controlling any would be fine.

Davis-Kahan sin θ theorem

Going back to perturbation analysis for eigenvectors, suppose we have $M = M^* + E \in S^n$ with eigendecompositions:

$$(9) \quad M^* = \sum_{i=1}^r \lambda_i^* u_i^* u_i^{*\top} = [U^* \quad U_L^*] \begin{bmatrix} \Lambda^* \\ \Lambda_{\perp}^* \end{bmatrix} [U^{*\top} \quad U_L^{*\top}],$$

$$M = \sum_{i=1}^r \lambda_i u_i u_i^\top = [U \quad U_L] \begin{bmatrix} \Lambda \\ \Lambda_{\perp} \end{bmatrix} [U^\top \quad U_L^\top],$$

where $U = [u_1^*, \dots, u_r^*]$, $U_L^* = [u_{r+1}^*, \dots, u_n^*]$, $\Lambda^* = \text{diag}(\lambda_1^*, \dots, \lambda_r^*)$, and $\Lambda_{\perp}^* = \text{diag}(\lambda_{r+1}^*, \dots, \lambda_n^*)$

The matrices U , U_L , Λ and Λ_{\perp} are defined analogously.

Warning: Unlike for eigenvalues, eigen vectors are stable only if their associated eigenvalues are sufficiently far apart.

Example: Consider

$$M^* = \begin{bmatrix} 1+\epsilon & \epsilon \\ \epsilon & 1-\epsilon \end{bmatrix}, \quad E = \begin{bmatrix} -\epsilon & \epsilon \\ \epsilon & \epsilon \end{bmatrix}, \quad M = \begin{bmatrix} 1 & \epsilon \\ \epsilon & 1 \end{bmatrix}$$

for $\epsilon \in (0,1)$. Then, a routine computation yields that the leading eigenvectors of M^* and M are

$$u_1^* = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{and} \quad u_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

Thus, regardless of ϵ , we have

$$\|u_1 u_1^T - u_1^* u_1^{*T}\|_{op} = \frac{1}{2} (\sqrt{3} + \sqrt{2} - 1) \approx 1.07$$

$$\|u_1 u_1^T - u_1^* u_1^{*T}\|_F = \sqrt{3 - \sqrt{2}} \approx 1.26$$

The issue here is that M^* is too close to having a 2D eigenspace associated with the top eigenvalue and a small perturbation can move eigenvectors "far away." Thus, we need some control on $\lambda_1(M^*) - \lambda_2(M^*)$.

The following is a seminal result due to Davis and Kahan.

Theorem (Davis-Kahan Sin Θ) Consider M and M^* as in (B). Suppose \exists scalars $a \leq b$ and $\Delta > 0$ s.t. any of the following two conditions hold

- 1) $\{\lambda_1^*, \dots, \lambda_r^*\} \subseteq [a, b]$, and
 $\{\lambda_{r+1}, \dots, \lambda_n\} \subseteq (-\infty, a - \Delta] \cup [b + \Delta, \infty)$.
- 2) $\{\lambda_1^*, \dots, \lambda_r^*\} \subseteq (-\infty, a - \Delta] \cup [b + \Delta, \infty)$, and
 $\{\lambda_{r+1}, \dots, \lambda_n\} \subseteq [a, b]$.

Then,

$$\text{dist}_{\text{op}}(U, U^*) \leq \sqrt{2} \|\sin \Theta\|_{\text{op}} \leq \sqrt{2} \frac{\|E\|_{\text{op}}}{\Delta};$$

$$\text{dist}_F(U, U^*) \leq \sqrt{2} \|\sin \Theta\|_F \leq \sqrt{2r} \frac{\|E\|_{\text{op}}}{\Delta}.$$

This statement is a bit inconvenient because the eigenvalues of $M = M^* + E$ depend implicitly on both M^* and E .

The following corollary requires more explicit control on $\|E\|_{op}$.

Corollary (ii): Consider M and M^* as in (i). Assume

$$|\lambda_1^*| \geq \dots \geq |\lambda_n^*| \quad \text{and}$$

$$|\lambda_1| \geq \dots \geq |\lambda_n|.$$

Further, suppose

$$\|E\|_{op} < (1 - 1/\sqrt{2}) \underbrace{(|\lambda_r^*| - |\lambda_{r+1}^*|)}_{\Delta :=}.$$

Then,

$$\text{dist}_{op}(U, U^*) \leq \sqrt{2} \|\sin \Theta\|_{op} \leq \frac{2 \|E\|_{op}}{\Delta}$$

$$\text{dist}_F(U, U^*) \leq \sqrt{2} \|\sin \Theta\|_F \leq \frac{2 \sqrt{F} \|E\|_{op}}{\Delta} +$$