

# Lecture 3

Sep/03/2024

## Recap

- Optimality conditions
  - ↳ First order necessary cond.
  - ↳ First order sufficient cond. for convex functions.

## Agenda

- ...
  - ↳ second order necessary cond.
  - ↳ second order sufficient cond.
- Basic convex analysis.
  - Convex sets
  - Smooth convex functions
  - Subdifferentials.

## Optimality conditions

## Theorem (1<sup>st</sup>-order sufficient condition)

Assume that  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  is a smooth convex function.

Then,  $x^*$  satisfies  $\nabla f(x^*) = 0$   
iff  $x^*$  is a global minimizer.

Proof: " $\Leftarrow$ " Done. ✓

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" $\Rightarrow$ " Assume  $\nabla f(\bar{x}^*) = 0$ . Then,

Let  $\bar{y} \in \mathbb{R}^d \setminus \{\bar{x}^*\}$ .

Define  $\phi(t) = f(\bar{x}^* + t(\bar{y} - \bar{x}^*))$ .

By chain rule

$$\phi'(0) = (\bar{y} - \bar{x}^*)^\top \nabla f(\bar{x}^*) = 0$$

For any  $t \in [0, 1]$  we have

$$\frac{f(\bar{x}^* + t(\bar{y} - \bar{x}^*)) - f(\bar{x}^*)}{t \|\bar{y} - \bar{x}^*\|}$$

(convexity)  $\leq \frac{(1-t)f(\bar{x}^*) + t f(\bar{y}) - f(\bar{x}^*)}{t \|\bar{y} - \bar{x}^*\|}$

$$= \frac{t(f(\bar{y}) - f(\bar{x}^*))}{\cancel{t \|\bar{y} - \bar{x}^*\|}}$$

Taking limits on both sides

$$0 = \phi'(0) \leq \frac{f(\bar{y}) - f(\bar{x}^*)}{\|\bar{y} - \bar{x}^*\|}$$

□

Theorem (2<sup>nd</sup>-order necessary cond)

Suppose  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  twice diff ( $C^2$ ).

If  $\bar{x}^*$  is a local min

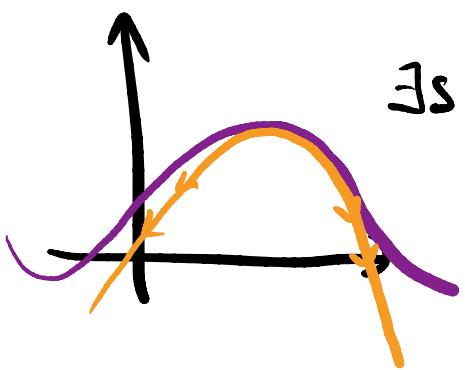
$\Rightarrow \nabla f(\bar{x}^*) = 0$  and  $s^\top \nabla^2 f(\bar{x}^*) s \geq 0$

$$\forall s \in \mathbb{R}^d$$

$\nabla^2 f(\bar{x}^*)$  is positive semidefinite

$$\nabla^2 f(\bar{x}^*) \succeq 0.$$

## Intuition



If  $\nabla f(\bar{x}^*) = 0$ , but  
 $\exists s \in \mathbb{R}^d \nabla^2 f(\bar{x}^*) s < 0$   
 $\Rightarrow$  Exists direction  
downhill (2<sup>nd</sup>-order)  
 $\Rightarrow$  Better point.

Proof: Suppose seeking contradiction

$$\nabla f(\bar{x}^*) = 0 \quad \text{and} \quad \exists \bar{s} : \bar{s}^\top \nabla^2 f(\bar{x}^*) \bar{s} < 0.$$

Define:  $\phi(t) = f(\bar{x}^* + t\bar{s})$ .

↑ norm 1.

Then by def

$$0 > \frac{1}{2} \phi''(0) = \lim_{t \rightarrow 0} \frac{\phi(t) - \phi(0)}{t^2}$$

For small enough  $t > 0$

$$0 > \frac{1}{4} \phi''(0) \geq \frac{\phi(t) - \phi(0)}{t^2}$$

$$\Rightarrow f(\bar{x}^*) > f(\bar{x}^* + t\bar{s}) .$$

Q

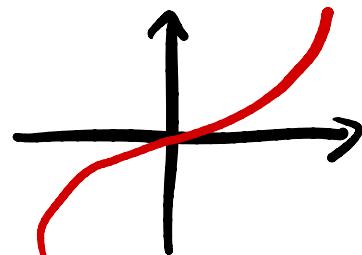
□

Is this sufficient?

**No!** Same example as before

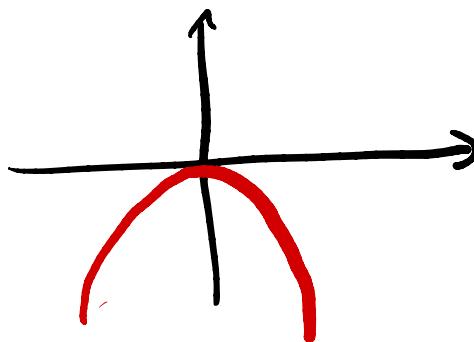
$$f(x) = x^3$$

$$f''(0) = 0$$



$$f(x) = -x^4$$

$$f''(0) = 0$$



Ex: Come up with a 2D example

where  $\nabla^2 f(0) \neq 0$ .

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Theorem: 2<sup>nd</sup>-order sufficient cond.

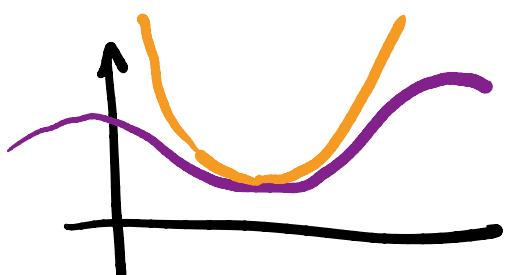
Suppose  $f: \mathbb{R}^d \rightarrow \mathbb{R}$  is twice diff.

If  $\bar{x}^* \in \mathbb{R}^d$  satisfies that

$\nabla f(\bar{x}^*) = 0 \Rightarrow x^*$  is a strict local  
 $\nabla^2 f(\bar{x}^*) > 0$  minimum

$$s^T \nabla^2 f(\bar{x}^*) s > 0 \quad \forall s \in \mathbb{R}^d.$$

Intuition:



The function curves upwards in every direction  $\Rightarrow x^*$  is strict local minimum.

Proof: Suppose  $\bar{x}^*$  satisfies the assumptions.

Let  $\bar{u} \in \mathbb{R}$ , with  $\|\bar{u}\| = 1$ .  
 Let  $\Psi(s) = f(\bar{x}^* + s\bar{u})$ .

By the Fundamental Theorem of calculus

$$\Psi(s) = \Psi(0) + \int_0^s \Psi'(\alpha) d\alpha$$

Applying it again on  $\Psi'(t)$

$$\Psi(s) = \Psi(0) + \Psi'(0) + \int_0^s \int_0^\alpha \Psi''(\beta) d\beta d\alpha$$

$\text{HW 1}$

Since  $\nabla^2 f(x^*)$  is continuous and  $\lambda := \lambda_{\min}(\nabla^2 f(x^*)) > 0$ , then for all points  $y$  close to  $x^*$

$$\lambda_{\min}(\nabla^2 f(y)) \geq \frac{\lambda}{2}.$$

Then, for small enough  $s$

$$\Psi(s) = \Psi(0) + \Psi'(0) + \int_0^s \int_0^\alpha \bar{u}^\top \nabla^2 f(\bar{x}^* + \beta \bar{u}) u d\beta d\alpha$$

$$\begin{aligned}
 &\geq \Psi(0) + \frac{\lambda}{2} \int_0^s \int_0^\alpha 1 \, d\beta \, d\alpha \\
 &= \Psi(0) + \frac{\lambda s^2}{4} \\
 &> \Psi(0)
 \end{aligned}$$

$$\Rightarrow f(\bar{x}^*) = \Psi(0) < \Psi(s) = f(\bar{x}^* + s\bar{u})$$

any point  $\rightarrow$   
 in a nearby  
 radius. □

## Basics of convexity

We already saw convex functions

Def:  $f(t\bar{x} + (1-t)\bar{y}) \leq t f(\bar{x}) + (1-t) f(\bar{y})$   
 $\forall \bar{x}, \bar{y}, t \in [0,1]$ .

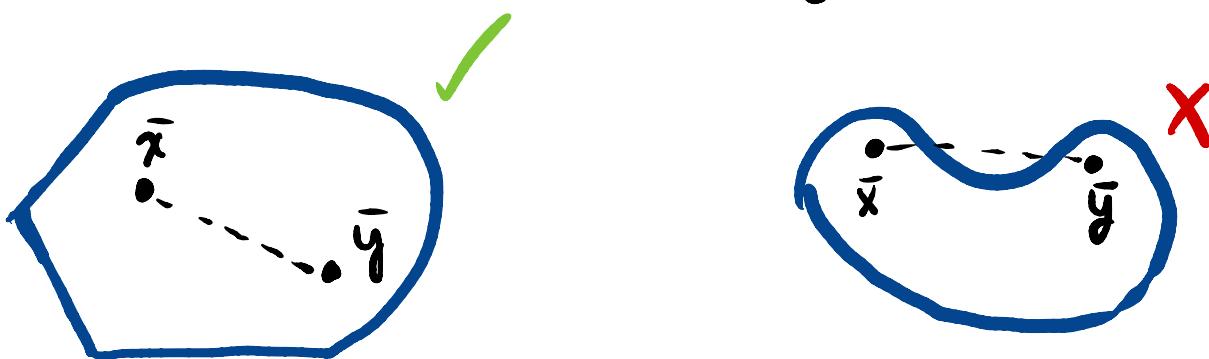
There is also a natural notion of convexity for sets

Def A set  $C \subseteq \mathbb{R}^d$  is convex if

for all  $\bar{x}, \bar{y} \in C$  and  $t \in [0, 1]$   
 $t\bar{x} + (1-t)\bar{y} \in C.$

### Intuition

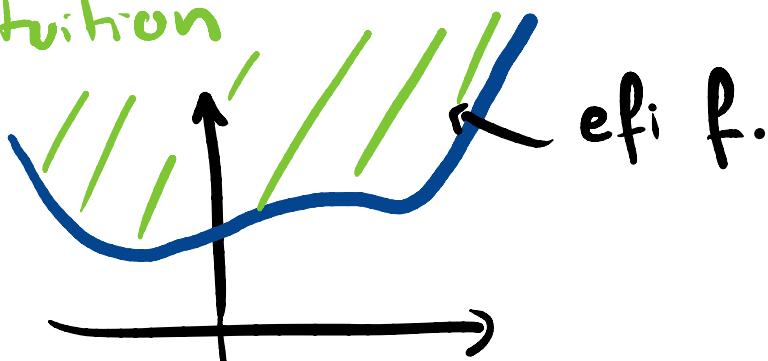
Segments never go out!



There is a deep connection between convex sets and convex functions.

Def: Given a convex function  $f: \mathbb{R}^d \rightarrow \mathbb{R}$ ,  
its epigraph is given by  
 $\text{epi } f := \{(x, t) \mid f(x) \leq t\}$

### Intuition



Proposition: A function is convex iff its epigraph is convex.

Proof: HWL .

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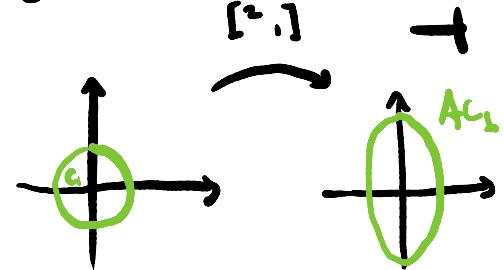
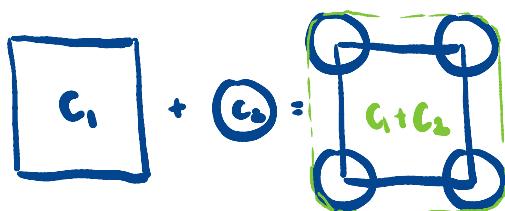
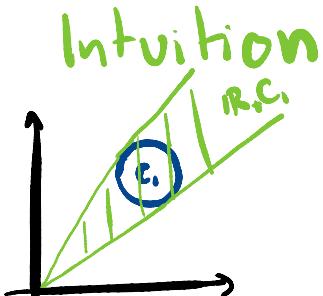
The relationship between convex functions go deeper than this. If you are interested consider taking "Intro to Convexity" with Amitabh Basu.

Lemma: Assume that  $C_1, C_2 \in \mathbb{R}^d$  convex sets. Then, the following are convex

1. (Scaling)  $\mathbb{R}_+ C_1 = \{\lambda \bar{x} \mid \lambda \geq 0 \text{ and } \bar{x} \in C_1\}$
2. (Sums)  $C_1 + C_2 = \{\bar{x}_1 + \bar{x}_2 \mid \bar{x}_1 \in C_1, \bar{x}_2 \in C_2\}$
3. (Intersections)  $C_1 \cap C_2$ .
4. (Linear images and preimages)

Let  $A: \mathbb{R}^d \rightarrow \mathbb{R}^n$  is linear,

$A C_1$  and  $A^{-1} C_3$  are convex.



# Proof: Exercise

□

## Equivalence of operations

Function	Epigraph
$\lambda f(x/\lambda)$	$\lambda \text{ epi } f$
$\max_i f_i$	$\cap_i \text{ epi } f$
$f(Ax)$	$[A \times I]^{-1} \text{ epi } f$