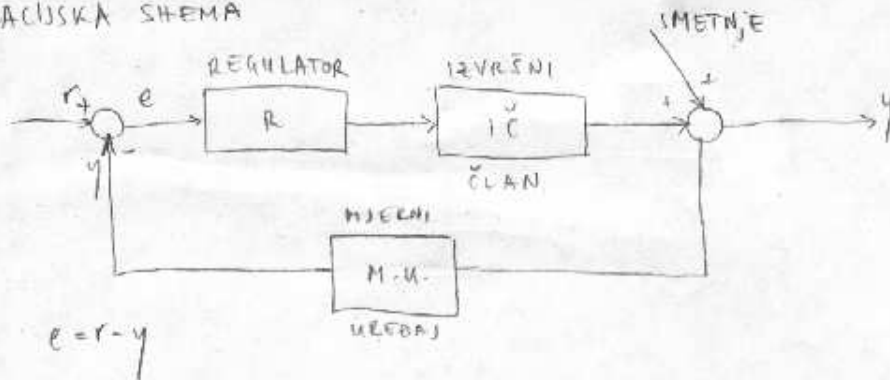
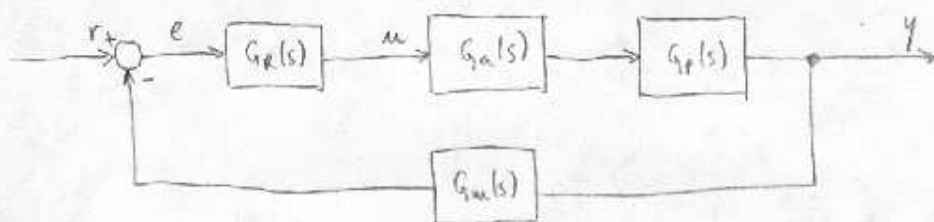


# REGULACIJSKA SHEMA

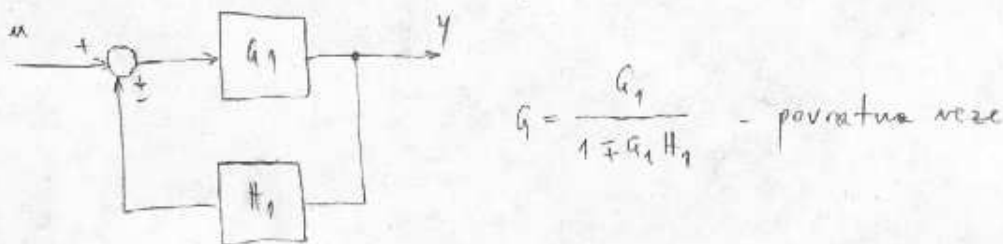
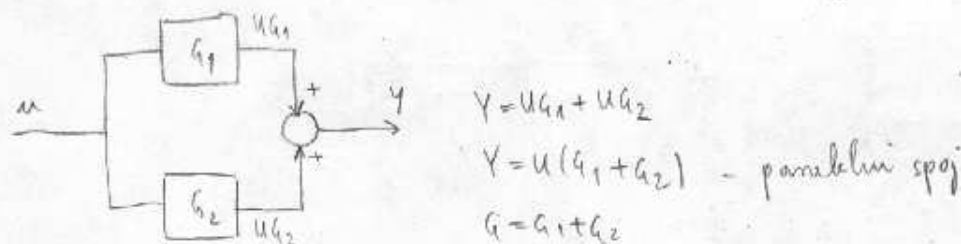
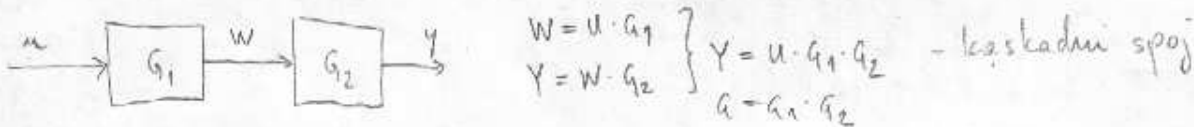
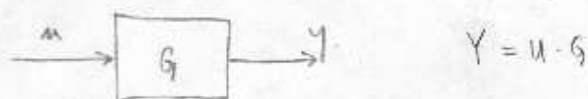


ZADATAK 1. 1. M. 2007./2008.

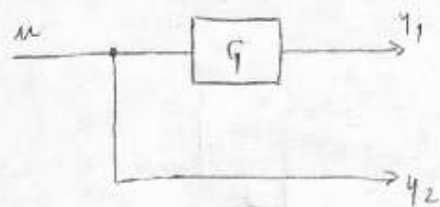
Zadano f: IZVRŠNI ČLAN  $G_a(s)$   
 REGULATOR  $G_R(s)$  u  
 MJERNI ČLAN  $G_m(s)$   
 OBJEKT UPRAVLJANJA  $G(s)$  y



## BLOKOVSKI DIAGRAMI



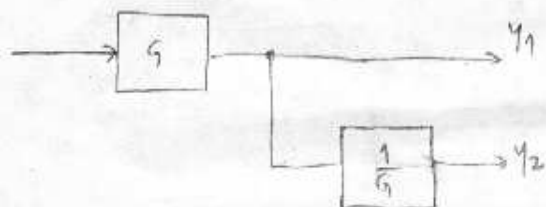
## ZADATK 2.



$$Y_1 = u \cdot G$$

$$Y_2 = u$$

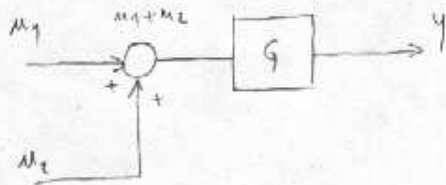
$\Rightarrow$



$$Y_1 = u \cdot G$$

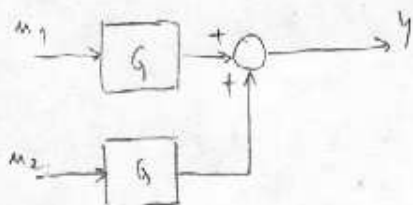
$$Y_2 = u \cdot G \cdot \frac{1}{G} = u$$

## ZADATK 3.



$$Y = (u_1 + u_2) G$$

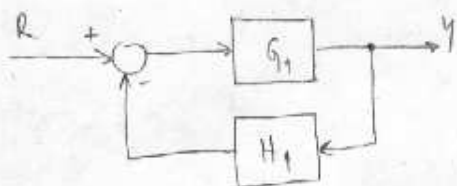
$$= u_1 G + u_2 G$$



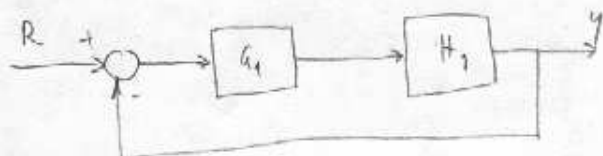
$$Y = u_1 G + u_2 G$$

$$= (u_1 + u_2) G$$

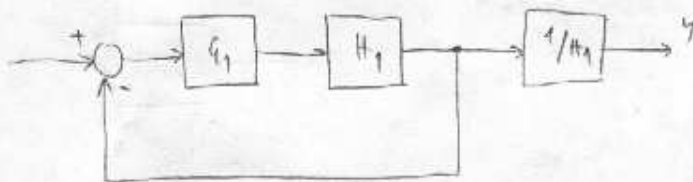
## ZADATK 4.

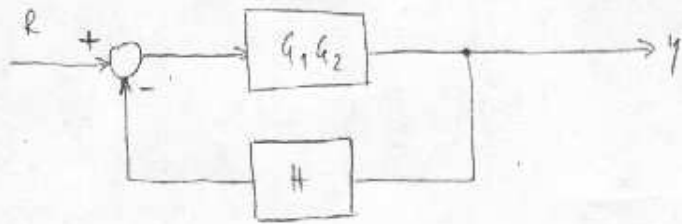
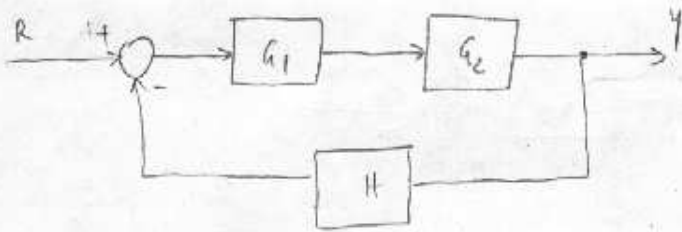


$$G_X = \frac{G_1}{1 + G_1 H_1}$$



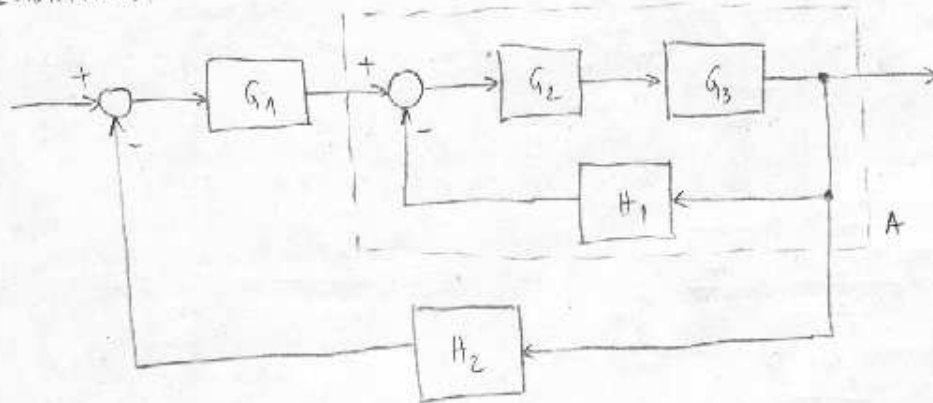
$$G_Y = \frac{G_1 H_1}{1 + G_1 H_1 \cdot 1} = \frac{G_1 H_1}{1 + G_1 H_1}$$



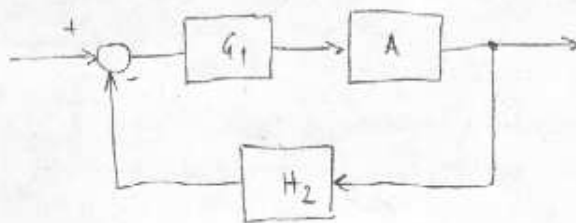


$$G = \frac{G_1 G_2}{1 + G_1 G_2 H}$$

ZADATOK 6.

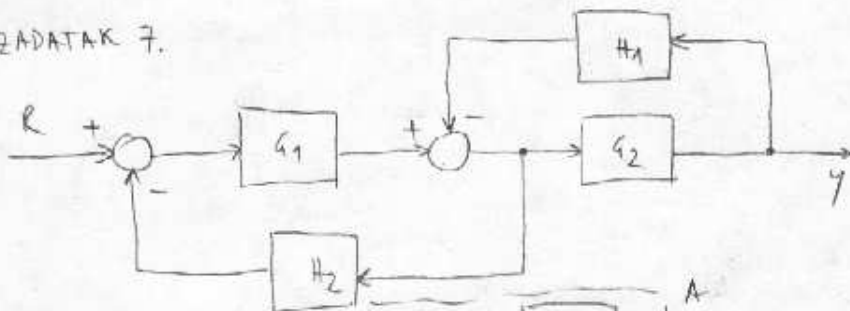


$$A = \frac{G_2 G_3}{1 + G_2 G_3 H_1}$$

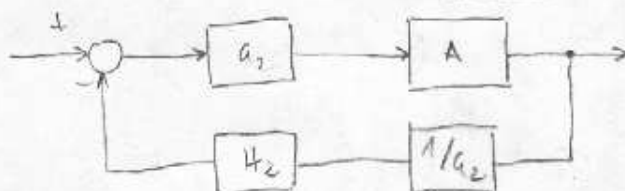
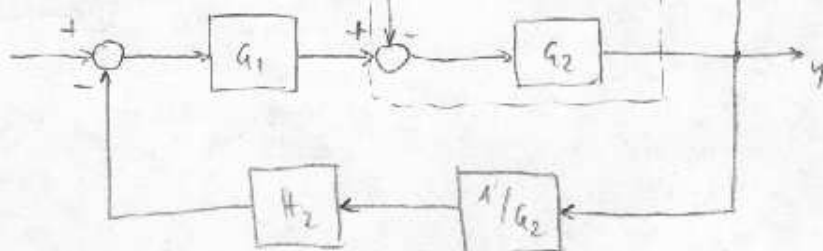


$$G = \frac{G_1 A}{1 + G_2 A H_2} = \frac{G_1 G_2 G_3}{1 + G_2 G_3 H_2 + G_1 G_2 G_3 H_1}$$

ZADATOK 7.

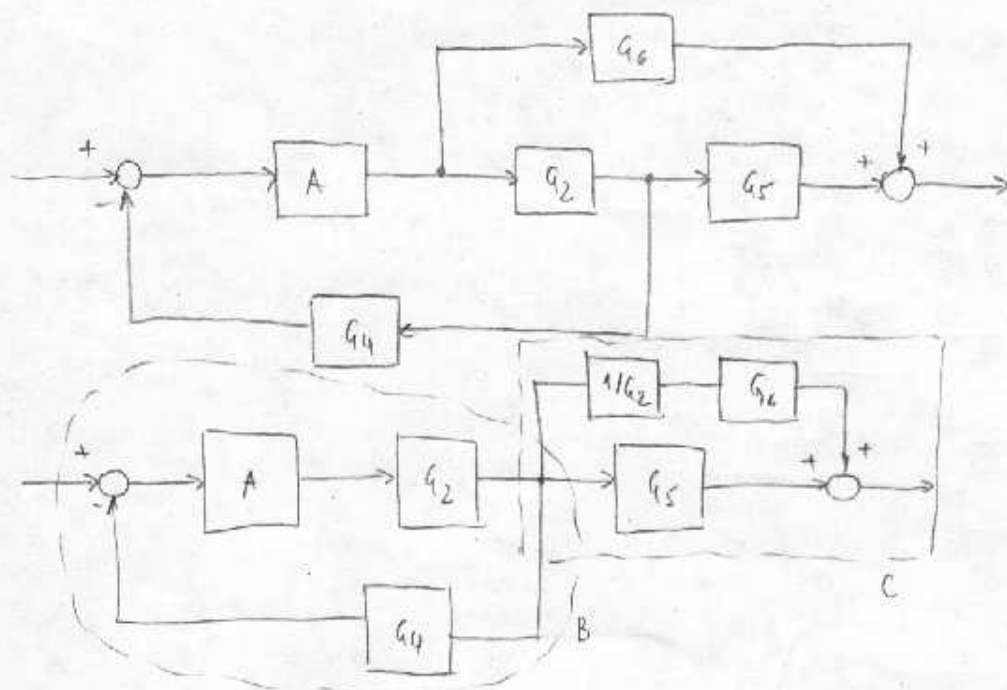
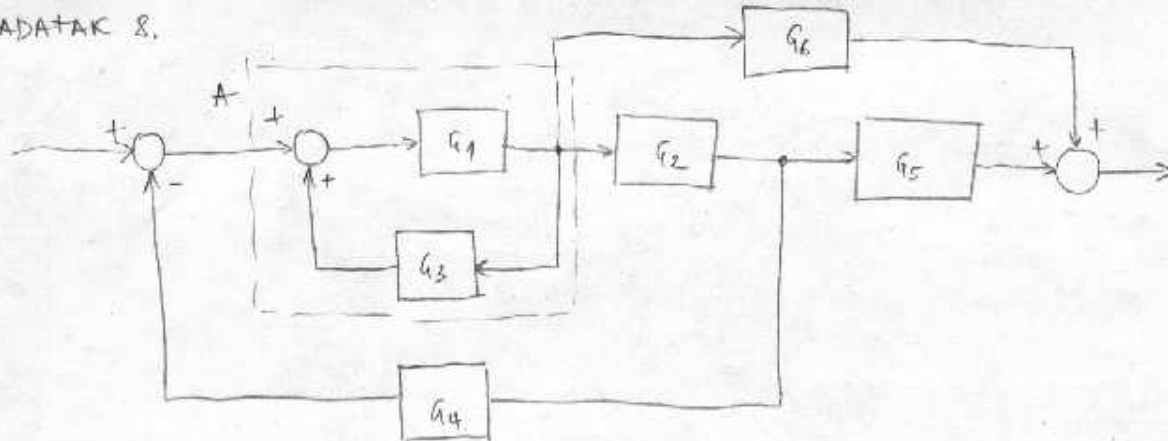


$$A = \frac{G_2}{1 + G_2 H_1}$$



- to right

# ZADATAK 8.



$$A = \frac{G_1}{1 - G_1 G_3}$$

$$B = \frac{A}{1 + A G_4}$$

$$C = \frac{G_6}{G_2} + G_5$$

$$G = B \cdot C$$

## MASONOV TEOREM

$$G(s) = \frac{1}{\Delta} \sum_i \Delta_i G_i \quad \text{DIREKTNI PUTEVI}$$

DIREKTNI PUTEVI (ZADATAK 8.)

$$G_1 G_2 G_5 \quad G_1 G_6$$

PETLJE SUSTAVA (POVRATNE VEZE)

$$+G_1 G_3 \quad -G_1 G_2 G_4$$

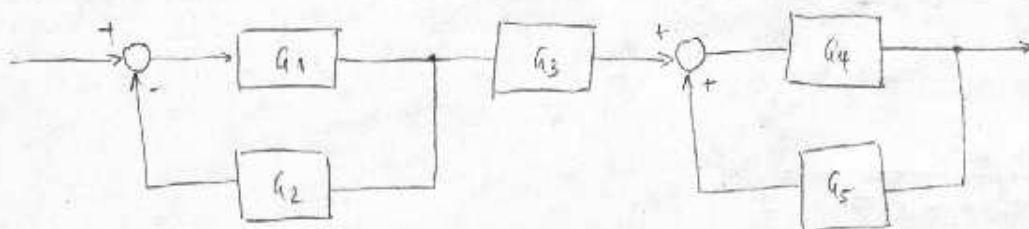
$$\Delta = 1 - \sum (\text{P.F. PETLJI}) + \sum (\text{UMNOŽAK P.F. DVAH PETLJI KOJE SE NE DODIRUJU}) -$$

$$- \sum ( \text{---||---} \text{ TRIJU ---||---} )$$

$$\Delta = 1 - (+G_1 G_3 + (-G_1 G_2 G_4)) = 1 - G_1 G_3 + G_1 G_2 G_4$$

P.F. - prijenosne funkcije

# ZADATAK 9.



D.P.  $G_1 G_3 G_4$

PETLJE  $-G_1 G_2$  ,  $+G_4 G_5$

$$\Delta = 1 - (-G_1 G_2 + G_4 G_5) + ((-G_1 G_2) G_4 G_5)$$

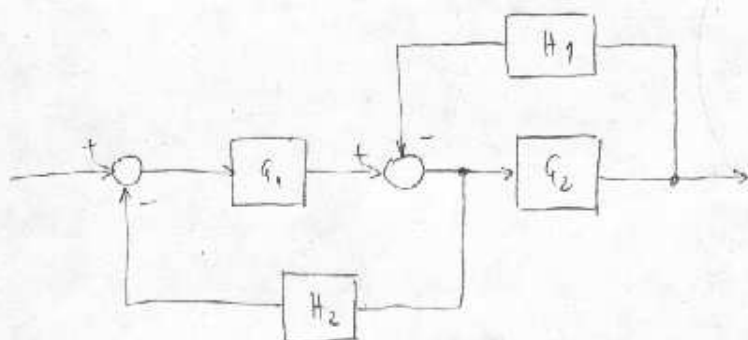
# ZADATAK 8 (nastavak)

D.P.  $G_1 G_2 G_5 \rightarrow \Delta_1 = 1$  - (izbaciti sve petlje koje taj put dodiruju)

$G_1 G_6 \rightarrow \Delta_2 = 1$

$$G(s) = \frac{G_1 G_2 G_5 - 1 + G_1 G_6 - 1}{1 - G_1 G_3 + G_1 G_2 G_4}$$

# ZADATAK 10.



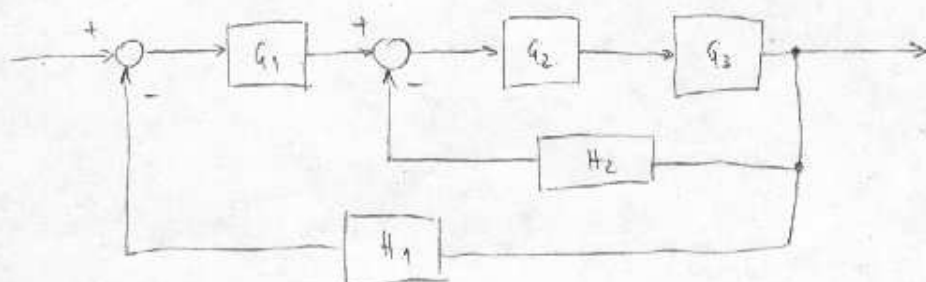
D.P.  $G_1 G_2 \rightarrow \Delta_1 = 1$

PETLJE  $-G_1 H_2$  ,  $-G_2 H_1 \rightarrow \Delta = 1 - (-G_1 H_2 - G_2 H_1) + (0) + \dots$

$$\Delta = 1 + G_1 H_2 + G_2 H_1$$

$$G = \frac{G_1 G_2 \cdot 1}{1 + G_1 H_2 + G_2 H_1}$$

# ZADATAK 11.



$$D.P. \quad G_1 G_2 G_3 \rightarrow \Delta_1 = 1$$

$$P.T.L.E. - G_1 G_3 H_2, - G_1 G_2 G_3 H_1 \rightarrow \Delta = 1 - ( \dots )$$

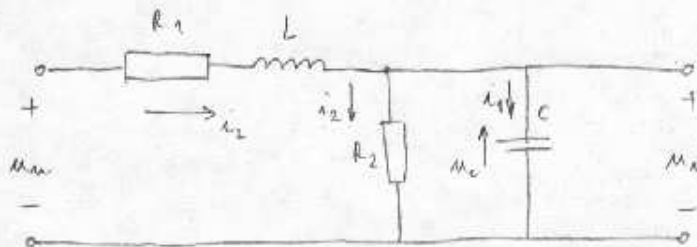
$$\Delta = 1 + G_1 G_3 H_2 + G_1 G_2 G_3 H_1$$

$$G = \frac{G_1 G_2 G_3 - 1}{1 + G_1 G_3 H_2 + G_1 G_2 G_3 H_1}$$

1. DOMAĆA ZADACA GRUPA 1

ZADATAK 12.

a)



$$u_i = i_2 R_2 \rightarrow i_2 = \frac{1}{R_2} u_i$$

$$u_i = \frac{1}{C} \int_0^t i_1(t) dt$$

$$u_u = i_1 R_1 + L \frac{di_1}{dt} + u_i$$

$$i_1 = i_1 + i_2$$

$$u_i = \frac{1}{C} \int_0^t i_1(t) dt$$

$$\int_0^t i_1(t) dt = C u_i$$

$$i_1(t) = C \cdot \dot{u}_i$$

$$i_1 = \frac{1}{R_2} u_i + C \dot{u}_i$$

$$\dot{i}_1 = \frac{1}{R_2} \dot{u}_i + C \ddot{u}_i$$

$$u_u = \left( \frac{1}{R_2} u_i + C \dot{u}_i \right) R_1 + L \left( \frac{1}{R_2} \dot{u}_i + C \ddot{u}_i \right) + u_i$$

$$C L \ddot{u}_i + \left( R_1 C + \frac{L}{R_2} \right) \dot{u}_i + \left( \frac{R_1}{R_2} + 1 \right) u_i = u_u$$

$$\ddot{u}_i + \frac{R_1 R_2 C + L}{R_2 L C} \dot{u}_i + \frac{R_1 + R_2}{R_2 L C} u_i = \frac{1}{L C} u_u$$

# PODATAK - MATRICE

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

$x$  - stanje sustava

$u$  - ulaz

$y$  - izlaz

## ZADATAK 13.

$$\dot{x}_1 = 2x_1 + x_2 + u_1$$

$$\dot{x}_2 = 5x_1 + x_3 - u_2$$

$$\dot{x}_3 = x_2 + x_3 + 2u_1 - u_2$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 \\ 5 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & -1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$y_1 = 3x_1 - 5x_2 + u_1$$

$$y_2 = u_2$$

$$\begin{bmatrix} \dot{y}_1 \\ \dot{y}_2 \end{bmatrix} = \begin{bmatrix} 3 & -5 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

## ZADATAK 12. (nastavak)

$$b) x = [u_c \ i_L]^T$$

$$u = [u_u]$$

$$y = [u_i]$$

$$u_i = u_c$$

$$y = \underbrace{\begin{bmatrix} 1 & 0 \end{bmatrix}}_C \underbrace{\begin{bmatrix} u_c \\ u_L \end{bmatrix}}_x + \underbrace{\begin{bmatrix} 0 \end{bmatrix}}_D u_u$$

$$i_q = \dot{u}_c \rightarrow \dot{u}_c = \frac{1}{C} i_q$$

$$i_L = i_q + i_2 \rightarrow i_2 = \frac{u_c}{R_2}$$

$$i_q = i_L - \frac{u_c}{R_2}$$

$$\dot{u}_c = \frac{1}{C} \left( i_L - \frac{u_c}{R_2} \right)$$

$$\dot{u}_c = -\frac{1}{CR_2} u_c + \frac{1}{C} i_L$$

$$u_u = R_1 i_L + L \frac{di}{dt} + u_i$$

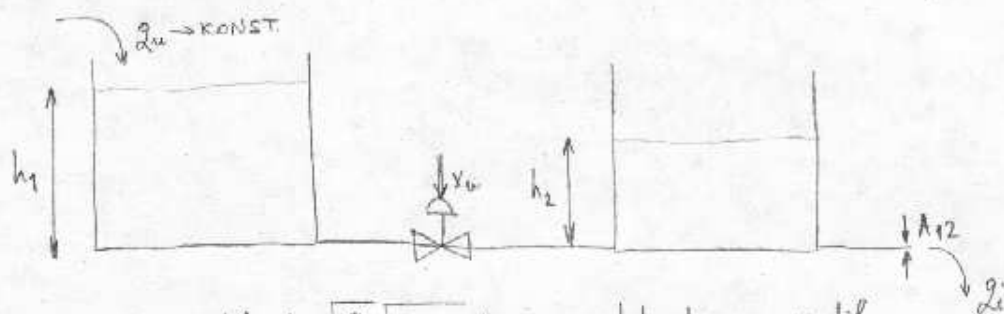
$$\dot{i}_L = \frac{1}{L} (u_u - i_L R_1 - u_c)$$

$$\dot{i}_L = -\frac{1}{L} u_c - \frac{R_1}{L} i_L + \frac{1}{L} u_u$$

$$\begin{bmatrix} \dot{u}_c \\ \dot{i}_L \end{bmatrix} = \underbrace{\begin{bmatrix} -\frac{1}{CR_2} & \frac{1}{C} \\ -\frac{1}{L} & -\frac{R_1}{L} \end{bmatrix}}_A \begin{bmatrix} u_c \\ i_L \end{bmatrix} + \underbrace{\begin{bmatrix} 0 \\ \frac{1}{L} \end{bmatrix}}_B u_u$$



a)



ventil - izvišni član

$$q(t) = A_v \sqrt{S \sqrt{2\Delta p}} x_u - \text{protok kroz ventil}$$

$$(1) \quad q_u - q(t) = A_1 \frac{dh_1}{dt} S$$

$$A \frac{dh_1}{dt} S = A \frac{dV}{dt} \rightarrow \text{volumni protok (bez S)} \\ q_u - q(t) = A \frac{dV}{dt}$$

$$q_u - A_v \sqrt{S \sqrt{2\Delta p}} x_u = A_1 S \frac{dh_1}{dt}$$

$$p_1 = \rho g h_1 + p_a$$

$$p_2 = \rho g h_2 + p_a$$

$$p_1 - p_2 = \rho g h_1 + p_a - \rho g h_2 - p_a$$

$$\Delta p = \rho g (h_1 - h_2)$$

$$q_u - A_v \sqrt{S \sqrt{S \sqrt{2g \sqrt{h_1 - h_2}}}} x_u = A_1 S \frac{dh_1}{dt} \quad / : A_1 S$$

$$\boxed{\frac{dh_1}{dt} = \frac{1}{A_1 S} q_u - \frac{A_v}{A_1} \sqrt{2g \sqrt{h_1 - h_2}} x_u}$$

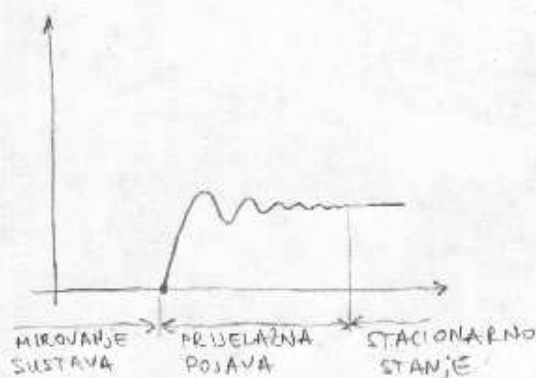
$$(2) \quad q(t) - q_i = A_2 \frac{dh_2}{dt} S$$

$$A_v \sqrt{2g \sqrt{h_1 - h_2}} x_u - A_{12} S \sqrt{2g \sqrt{h_2}} = A_2 S \frac{dh_2}{dt} \quad / : A_2 S$$

$$\boxed{\frac{dh_2}{dt} = \frac{A_v}{A_2} \sqrt{2g \sqrt{h_1 - h_2}} x_u - \frac{A_{12}}{A_2} \sqrt{2g \sqrt{h_2}}}$$

$$q = A S v \\ q_i = A_{12} S \sqrt{2g h_2}$$

b)

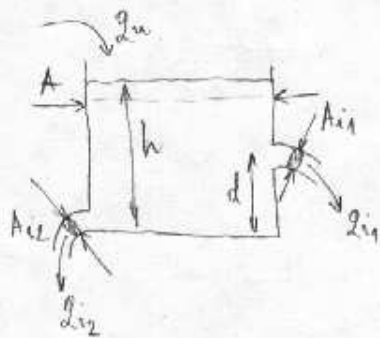


$$\frac{dh_1}{dt} = \frac{dh_2}{dt} = 0 - \text{stacionarno stanje (nema promjene } h_1 \text{ i } h_2)$$





## 1. LIV. IZLAZNI TEST.



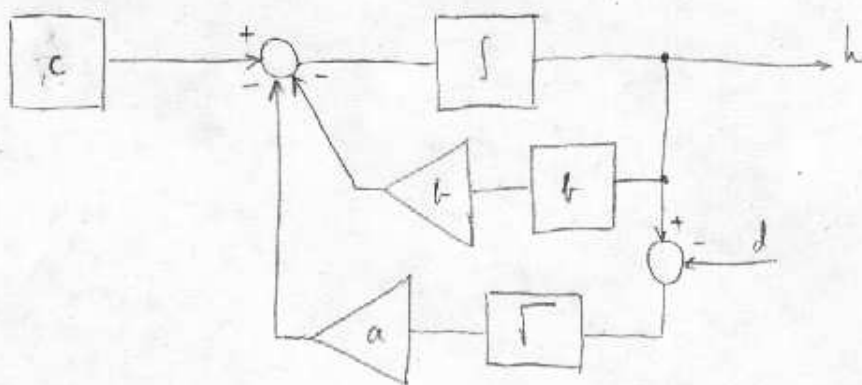
$$Q_u - (Q_{i1} + Q_{i2}) = A \frac{dh}{dt} S$$

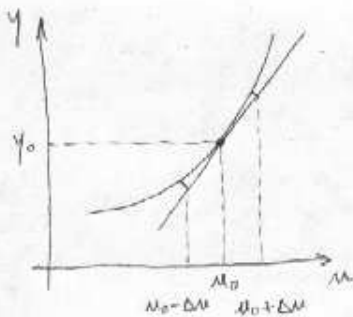
$$Q_{i1} = A_{i1} S \sqrt{2g(h-d)}$$

$$Q_{i2} = A_{i2} S \sqrt{2gh}$$

$$Q_u - A_{i1} S \sqrt{2g} \sqrt{h-d} - A_{i2} S \sqrt{2g} \sqrt{h} = AS \frac{dh}{dt} \quad | : AS$$

$$\frac{dh}{dt} = \underbrace{\frac{1}{AS} Q_u}_c - \underbrace{\frac{A_{i1}}{A} \sqrt{2g} \sqrt{h-d}}_a - \underbrace{\frac{A_{i2}}{A} \sqrt{2g} \sqrt{h}}_b$$

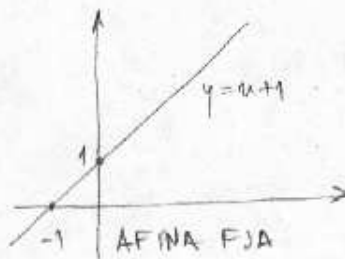
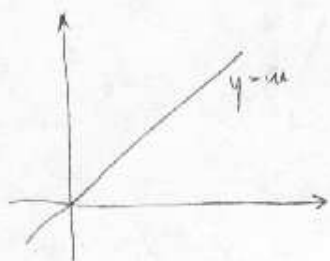




$$y = f(u)$$

$$y \sim f(u_0) + \left. \frac{df}{du} \right|_{u=u_0} (u - u_0) + \underbrace{\frac{1}{2!} \left. \frac{d^2 f}{du^2} \right|_{u=u_0} (u - u_0)^2 + \dots}_{0}$$

$$y \sim f(u_0) + \left. \frac{df}{du} \right|_{u=u_0} \Delta u - \text{TAYLOROV RED}$$



$$y_1 = u_1 + 1$$

$$y_2 = u_2 + 1$$

$$u = \alpha u_1 + \beta u_2$$

$$y = u + 1$$

$$y = \alpha u_1 + \beta u_2 + 1$$

$$y = \alpha y_1 + \beta y_2$$

$$y = \alpha u_1 + \alpha + \beta u_2 + \beta$$

$$y = \alpha u_1 + \beta u_2 + \alpha + \beta$$

ZADATAK 16.

$$y = u^4 \text{ oko radne tocke } u_0 = 1$$

$$y_0 = u_0^4 = 1$$

$$y = \Delta y + y_0$$

$$u = \Delta u + u_0$$

$$y \sim f(u_0) + \left. \frac{df}{du} \right|_{u_0} \Delta u$$

$$\Delta y + y_0 = f(u_0) + 4u_0^3 \Delta u$$

$$\Delta y = 4 \Delta u$$

S.T. - statična točka

ZADATAK 17.

$$\dot{y}(t) + y(t)u(t) = u^2(t)$$

$$u_0 = \frac{1}{2}$$

$$\dot{y}_0 = 0 \rightarrow 0 + y_0 u_0 = u_0^2$$

$$y_0 = \frac{1}{2}$$

$$y = \Delta y + y_0 \rightarrow \dot{y} = \Delta \dot{y}$$

$$u = \Delta u + u_0$$

$$\dot{y}(t) = u^2(t) - y(t)u(t) = f(u, y)$$

$$\dot{y}(t) \sim f(u_0, y_0) + \left. \frac{\partial f}{\partial u} \right|_{S.T.} \Delta u + \left. \frac{\partial f}{\partial y} \right|_{S.T.} \Delta y$$

$$\Delta \dot{y} = (2u_0 - y_0) \Delta u + (-u_0) \Delta y$$

$$\Delta \dot{y} = \frac{1}{2} \Delta u - \frac{1}{2} \Delta y$$

$$2 \Delta \dot{y} + \Delta y = \Delta u$$

ZADATOK 18.

$$\ddot{y}(t) + 5\dot{y}(t) + y(t) + y^3(t) = \ln(u(t))$$

$$y_0 = 1$$

$$\ddot{y}_0 = \dot{y}_0 = 0$$

$$0 + 5 \cdot 0 + y_0 + y_0^3 = \ln(u_0)$$

$$2\ln(u) \Rightarrow u_0 = e^2$$

$$y = y_0 + \Delta y \rightarrow \dot{y} = \Delta \dot{y}$$

$$\ddot{y} = \Delta \ddot{y}$$

$$u = u_0 + \Delta u$$

$$\ddot{y} = \ln(u) - 5\dot{y} - y - y^3 = f(u, y, \dot{y})$$

$$\ddot{y} \sim f(u_0, y_0, 0) + \left. \frac{\partial f}{\partial u} \right|_{s.t.} \Delta u + \left. \frac{\partial f}{\partial y} \right|_{s.t.} \Delta y + \left. \frac{\partial f}{\partial \dot{y}} \right|_{s.t.} \Delta \dot{y}$$

$$\Delta \ddot{y} = \frac{1}{u_0} \Delta u + (-1 - 3y_0^2) \Delta y + (-5) \Delta \dot{y}$$

$$\Delta \ddot{y} + 5\Delta \dot{y} + 4\Delta y = e^{-2} \Delta u$$

ZADATOK 19.

$$\ddot{y} + \dot{y} - \frac{1}{y} = u - ye^{\dot{u}}$$

$$y_0 = 1$$

$$\ddot{y} = \dot{y} = \dot{u} = 0$$

$$-\frac{1}{y_0} = u_0 - y_0 \rightarrow u_0 = y_0 - \frac{1}{y_0}$$

$$u_0 = 0$$

$$y = y_0 + \Delta y \rightarrow \dot{y} = \Delta \dot{y}$$

$$\ddot{y} = \Delta \ddot{y}$$

$$u = u_0 + \Delta u \rightarrow \dot{u} = \Delta \dot{u}$$

$$\ddot{y} = u - ye^{\dot{u}} - \dot{y} + \frac{1}{y} = f(u, \dot{u}, y, \dot{y})$$

$$\ddot{y} \sim f(u_0, 0, y_0, 0) + \left. \frac{\partial f}{\partial u} \right|_{s.t.} \Delta u + \left. \frac{\partial f}{\partial \dot{u}} \right|_{s.t.} \Delta \dot{u} + \left. \frac{\partial f}{\partial y} \right|_{s.t.} \Delta y + \left. \frac{\partial f}{\partial \dot{y}} \right|_{s.t.} \Delta \dot{y}$$

$$\Delta \ddot{y} = \Delta u + (-y_0 - 1 \cdot \Delta \dot{u}) + (-1 - \frac{1}{y_0^2}) \Delta y + (-1) \Delta \dot{y}$$

$$\Delta \ddot{y} + \Delta \dot{y} + 2\Delta y = \Delta u - \Delta \dot{u}$$

# LAPLACEOVA TRANSFORMACIJA

$$F(s) = \int_0^{\infty} e^{-st} f(t) dt$$

$$f(t) \longleftrightarrow F(s)$$

$$\mathcal{L}\{f(t)\} = F(s)$$

## VREMENSKA DOMENA

$$1 \longleftrightarrow \frac{1}{s}$$

$$t \longleftrightarrow \frac{1}{s^2}$$

$$t^2 \longleftrightarrow \frac{2}{s^3}$$

$$t^n \longleftrightarrow \frac{n!}{s^{n+1}}$$

$$\sin(\omega t) \longleftrightarrow \frac{\omega}{s^2 + \omega^2}$$

$$\cos(\omega t) \longleftrightarrow \frac{s}{s^2 + \omega^2}$$

$$\delta(t) \longleftrightarrow 1$$

$$f(t) \longleftrightarrow F(s)$$

$$e^{at} f(t) \longleftrightarrow F(s-a)$$

$$e^{at} \longleftrightarrow \frac{1}{(s-a)^2}$$

$$\cos(2t) e^{at} \longleftrightarrow \frac{s-2}{(s-2)^2 + 4}$$

$$f(t-a) \longleftrightarrow F(s) \cdot e^{-as}$$

$$\cos(3t) \longleftrightarrow \frac{s}{s^2 + 9}$$

$$\cos(3(t-2)) \longleftrightarrow \frac{s}{s^2 + 9} e^{-2s}$$

$$t^n f(t) \longleftrightarrow (-1)^n \frac{d^n}{ds^n} (F(s))$$

$$t \sin(t) \longleftrightarrow (-1)^1 \frac{d}{ds} \left( \frac{1}{s^2 + 1} \right) = (-1) \frac{-2s}{(s^2 + 1)^2} = \frac{2s}{(s^2 + 1)^2}$$

$$\frac{1}{a} f\left(\frac{t}{a}\right) \longleftrightarrow F(as)$$

$$f(t) = \cos(2t) \longleftrightarrow \frac{s}{s^2 + 4}$$

$$\frac{1}{5} \cos\left(2 \frac{t}{5}\right) \longleftrightarrow \frac{5s}{(5s)^2 + 4}$$

$$y \longleftrightarrow Y(s)$$

$$y' \longleftrightarrow sY(s) - y(0)$$

$$y'' \longleftrightarrow s^2 Y(s) - sy(0) - y'(0)$$

$$\ddot{y} + 5\dot{y} + 6y = u$$

$$u = t \quad \begin{aligned} y(0) &= 1 \\ y'(0) &= 2 \end{aligned}$$

$$y \circ \rightarrow Y(s)$$

$$y' \circ \rightarrow sY(s) - y(0) = sY(s) - 1$$

$$y'' \circ \rightarrow s^2 Y(s) - sy(0) - y'(0) = s^2 Y(s) - s - 2$$

$$s^2 Y(s) - s - 2 + s(sY(s) - 1) + 6Y(s) = U(s)$$

$$Y(s) [s^2 + 5s + 6] = U(s) + s + 2 + s$$

$$Y(s) [s^2 + 5s + 6] = U(s) + s + 7$$

$$Y(s) = \frac{U(s)}{s^2 + 5s + 6} + \frac{s+7}{s^2 + 5s + 6}$$

$$U(s) = \frac{1}{s^2}$$

$$s^2 + 5s + 6 \rightarrow \frac{-5 \pm \sqrt{25 - 24}}{2} = \frac{-5 \pm 1}{2}$$

$$-2, -3 \rightarrow (s+2)(s+3)$$

$$Y(s) = \frac{1}{s^2(s+2)(s+3)} + \frac{s+7}{(s+2)(s+3)}$$

$$g(s) = \frac{s+7}{(s+2)(s+3)} = \frac{c_{11}}{s+2} + \frac{c_{21}}{s+3} = \frac{5}{s+2} - \frac{4}{s+3} \circ \rightarrow 5e^{-2t} - 4e^{-3t}$$

$$c_{11} = g(s)(s+2) \Big|_{s=-2} = 5$$

$$c_{21} = g(s)(s+3) \Big|_{s=-3} = -4$$

$$c_{ij} = \frac{1}{(r_i - j)!} \left\{ \frac{ds^{r_i-j}}{ds^{r_i-j}} [A(s)(s-s_i)^{r_i}] \right\} \Big|_{s=s_i}$$

$$\frac{c_{11}}{s} + \frac{c_{12}}{s^2} + \frac{c_{21}}{s+2} + \frac{c_{22}}{s+3} = \frac{-5}{36} \frac{1}{s} + \frac{1}{6} \frac{1}{s} + \frac{1}{4} \frac{1}{s+2} - \frac{1}{9} \frac{1}{s+3}$$

$$c_{21} = A(s)(s+2) \Big|_{s=-2} = \frac{1}{4}$$

$$c_{22} = A(s)(s+3) \Big|_{s=-3} = -\frac{1}{9}$$

$r=2$

$$c_{11} = \frac{1}{1!} \left( \frac{d}{ds} \left( \frac{1}{(s+2)(s+3)} \right) \right) \Big|_{s=0} = \frac{-2s-5}{((s+2)(s+3))^2} \Big|_{s=0} = \frac{-5}{36}$$

$$c_{12} = \frac{1}{0!} \left[ \frac{d^0}{ds^0} \frac{1}{(s+2)(s+3)} \right] \Big|_{s=0} = \frac{1}{6}$$

$$G(s) = \frac{U(s)}{Y(s)}$$

$$y'' - 5y' + 6y = u' + 2u$$

$$G(s) = \frac{s+2}{s^2+5s+6}$$

$$Y(s) = G(s) - \text{težinska fja}$$

$$u(t) = \delta(t)$$

$$U(s) = 1$$

$$H(s) = \frac{1}{s} G(s) - \text{prikladna fja}$$

$$u(t) = u(t)$$

$$U(s) = \frac{1}{s}$$

$$G(s) = \frac{s+2}{s^2+5s+6}$$

$$u(t) = 3\delta(t) \rightarrow U(s) = \frac{3}{s}$$

$$Y(s) = U(s) G(s) = \frac{3}{s} \frac{s+2}{s^2+5s+6} = \frac{3s+6}{s^3+5s^2+6s}$$

$$y(0^+) = \lim_{s \rightarrow \infty} s Y(s) = \lim_{s \rightarrow \infty} \frac{3s^2+6s}{s^3+5s^2+6s} = \lim_{s \rightarrow \infty} s^2 Y(s)$$

$$\dot{y}(0^+) = \lim_{s \rightarrow \infty} s \cdot s Y(s) = \lim_{s \rightarrow \infty} s^2 Y(s) = \frac{3s^3+6s^2}{s^3+5s^2+6s} = 3$$

$$y(\infty) = \lim_{s \rightarrow 0} s Y(s) = \lim_{s \rightarrow 0} \frac{3s^2+6s}{s^3+5s^2+6s} = \frac{3s+6}{s^2+5s+6} = 1$$