

## 2. Domaća zadaća – Grupa A

### ak.god. 2009./2010.

1. Zadana je nelinearna diferencijalna jednačba drugog reda:

$$y''(t)y(t) + 4y'(t) + 2y(t) = \frac{3}{4}u^2(t)$$

a) Potrebno je linearizirati nelinearnu diferencijalnu jednačbu u okolini radne točke određene s  $u_0 = 2$ .

$$2y_0 = \frac{3}{4}u_0^2, \quad y_0 = \frac{3}{8}u_0^2 = \frac{3}{2}, \quad (y_0'' = y_0' = 0)$$

$$y = \Delta y + y_0, \quad y' = \Delta y', \quad y'' = \Delta y'', \quad u = \Delta u + u_0$$

$$y'' = \frac{3}{4} \frac{u^2}{y} - 4 \frac{y'}{y} - 2 = f(u, y, y')$$

$$\Delta y'' = \underbrace{f(u_0, y_0, 0)}_0 + \left. \frac{\partial f}{\partial u} \right|_{s.T.} \Delta u + \left. \frac{\partial f}{\partial y} \right|_{s.T.} \Delta y + \left. \frac{\partial f}{\partial y'} \right|_{s.T.} \Delta y'$$

$$\Delta y'' = \frac{3}{2} \frac{u_0}{y_0} \Delta u + \left( -\frac{3}{4} \frac{u_0^2}{y_0^2} + 4 \frac{y_0'}{y_0^2} \right) \Delta y + \left( -4 \frac{1}{y_0} \right) \Delta y'$$

$$\Delta y'' + \frac{8}{3} \Delta y' + \frac{4}{3} \Delta y = 2 \Delta u$$

b) Primjeniti Laplaceovu transformaciju na diferencijalnu jednačbu dobivenu pod a) te odrediti prijenosnu funkciju  $G(s) = \frac{Y(s)}{U(s)}$ , pri čemu je  $Y(s) = \mathcal{L}\{\Delta y(t)\}$  i  $U(s) = \mathcal{L}\{\Delta u(t)\}$ .

$$\mathcal{L}\{\Delta y(t)'\} = sY(s), \quad \mathcal{L}\{\Delta y(t)''\} = s^2Y(s)$$

$$s^2Y(s) + \frac{8}{3}sY(s) + \frac{4}{3}Y(s) = 2U(s)$$

$$\frac{Y(s)}{U(s)} = G(s) = \frac{2}{s^2 + \frac{8}{3}s + \frac{4}{3}}$$

- c) Odrediti odziv lineariziranog modela na pobudu  $\Delta u$  prikazanu slikom 2.1. te na temelju aproksimacije linearizacijom skicirati odziv nelinearnog modela na pobudu  $u = \Delta u + u_0$ .

$$\Delta u(t) = \begin{cases} 0 & t < 0 \\ t & 0 \leq t \leq 2, \\ 2 & 2 \leq t \end{cases} \quad \Delta u(t) = t[S(t) - S(t-2)] + 2S(t-2) = tS(t) - (t-2)S(t-2)$$

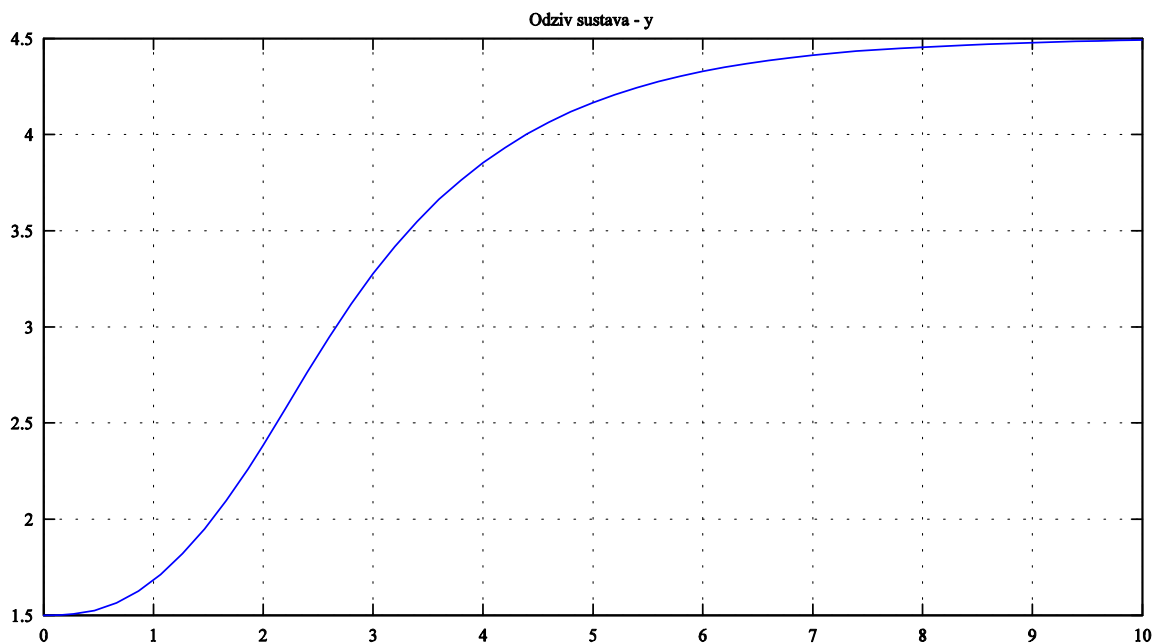
$$\mathcal{L}\{\Delta u(t)\} = U(s) = \frac{1}{s^2} - \frac{1}{s^2} e^{-2s}$$

$$Y(s) = U(s)G(s) = \frac{1}{s^2} \frac{2}{s^2 + \frac{8}{3}s + \frac{4}{3}} - \frac{1}{s^2} \frac{2}{s^2 + \frac{8}{3}s + \frac{4}{3}} e^{-2s}$$

$$\frac{2}{s^2 \left(s + \frac{2}{3}\right)(s+2)} = \frac{C_{11}}{s} + \frac{C_{12}}{s^2} + \frac{C_{21}}{s + \frac{2}{3}} + \frac{C_{31}}{s+2} = \frac{-3}{s} + \frac{\frac{3}{2}}{s^2} + \frac{\frac{27}{8}}{s + \frac{2}{3}} + \frac{-\frac{3}{8}}{s+2}$$

$$\mathcal{L}^{-1} \left\{ \frac{-3}{s} + \frac{\frac{3}{2}}{s^2} + \frac{\frac{27}{8}}{s + \frac{2}{3}} + \frac{-\frac{3}{8}}{s+2} \right\} = \left[ -3 + \frac{3}{2}t + \frac{27}{8}e^{-\frac{2}{3}t} - \frac{3}{8}e^{-2t} \right] S(t)$$

$$\begin{aligned} \mathcal{L}^{-1}\{\Delta y(t)\} &= \left[ -3 + \frac{3}{2}t + \frac{27}{8}e^{-\frac{2}{3}t} - \frac{3}{8}e^{-2t} \right] S(t) \\ &\quad - \left[ -3 + \frac{3}{2}(t-2) + \frac{27}{8}e^{-\frac{2}{3}(t-2)} - \frac{3}{8}e^{-2(t-2)} \right] S(t-2) \end{aligned}$$

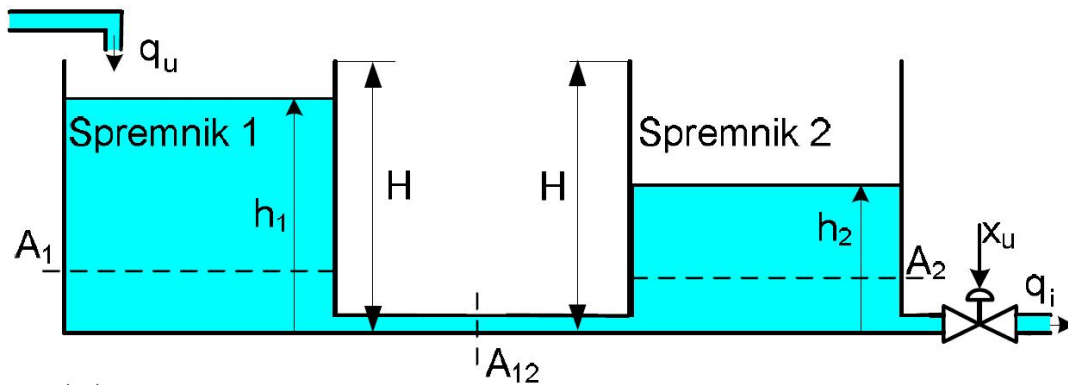


Slika 2.1. Odziv lineariziranog sustava -  $y(t) = y_0 + \Delta y(t)$

- d) Odrediti stacionarnu vrijednost odziva lineariziranog modela te nagibe tog odziva u 5trenucima  $t = 0$  s i  $t = 2$  s.

$$\Delta y_{s.s.} = \lim_{t \rightarrow \infty} \Delta y(t) = 3, \quad \Delta y'(0) = 0, \quad \Delta y'(2) = 0.9206$$

2. Za sustav skladištenja fluida modeliran nelinearnim modelom u 1. domaćoj zadaći (Slika 2.3) potrebno je:



Slika 1.2. Shema sustava skladištenja fluida

- a) Linearizirati nelinearni matematički model u stacionarnoj radnoj točki određenoj otvorenošću ventila na polovici njegovog dozvoljenog radnog područja otvorenosti.

Dozvoljeno područje otvorenosti ventila je

$$x_u \in [30.571, 100] [\%]$$

Prema tome, stacionarne vrijednosti su

$$x_{u0} = 65.285 [\%], \quad h_{10} = 3.186 [m], \quad h_{20} = 1.915 [m], \quad q_{u0} = 40 [kg/s]$$

**Spremnik 1.**

$$\frac{dh_1}{dt} = \frac{1}{A_1 \rho} q_u - \frac{A_{12} \sqrt{2g}}{A_1} \sqrt{(h_1 - h_2)}$$

$$\Delta h'_1 = \underbrace{f(h_{10}, h_{20})}_0 + \left. \frac{\partial f}{\partial h_1} \right|_{S.T.} \Delta h_1 + \left. \frac{\partial f}{\partial h_2} \right|_{S.T.} \Delta h_2$$

$$\Delta h'_1 + x_1 \Delta h_1 - x_1 \Delta h_2 = 0, \quad x_1 = \left( \frac{A_{12} \sqrt{2g}}{A_1} \frac{1}{2\sqrt{h_{10} - h_{20}}} \right)$$

**Spremnik 2.**

$$\frac{dh_2}{dt} = \frac{A_{12} \sqrt{2g}}{A_2} \sqrt{(h_1 - h_2)} - \frac{A_v \sqrt{2g}}{A_2} \sqrt{h_2} \cdot \frac{x_u}{100\%}$$

$$\Delta h'_2 = \underbrace{f(x_{u0}, h_{10}, h_{20})}_0 + \left. \frac{\partial f}{\partial x_u} \right|_{S.T.} \Delta x_u + \left. \frac{\partial f}{\partial h_1} \right|_{S.T.} \Delta h_1 + \left. \frac{\partial f}{\partial h_2} \right|_{S.T.} \Delta h_2$$

$$\Delta h'_2 + x_3 \Delta h_2 - x_2 \Delta h_1 = -y_0 \Delta x_u$$

$$x_2 = \frac{A_{12}\sqrt{2g}}{A_2} \frac{1}{2\sqrt{h_{10} - h_{20}}}, \quad x_3 = \frac{A_{12}\sqrt{2g}}{A_2} \frac{1}{2\sqrt{h_{10} - h_{20}}} + \frac{A_v\sqrt{2g}}{A_2} \frac{1}{2\sqrt{h_{20}}} \cdot \frac{x_{u0}}{100\%}$$

Vrijednosti pojedinih koeficijenata su

$$x_1 = 0.00392895, \quad x_2 = 0.00392895, \quad x_3 = 0.006541, \quad y_0 = 1.5234 \cdot 10^{-4}$$

b) Odrediti matrice A, B, C i D iz zapisa lineariziranog sustava po varijablama stanja:

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

pri čemu su vektori stanja, ulaza i izlaza definirani kao  $x = [\Delta h_1 \quad \Delta h_2]^T$ ,  $u = [\Delta x_u]$  i  $y = [\Delta h_1]$ .

$$\Delta h_1' = -x_1 \Delta h_1 + x_1 \Delta h_2$$

$$\Delta h_2' = x_2 \Delta h_1 - x_3 \Delta h_2 - y_0 \Delta x_u$$

$$y = \Delta h_1$$

Prema prikazanim jednadžbama slijedi zapis sustava u matričnom obliku

$$\begin{bmatrix} \Delta h_1' \\ \Delta h_2' \end{bmatrix} = \begin{bmatrix} -x_1 & x_1 \\ x_2 & -x_3 \end{bmatrix} \begin{bmatrix} \Delta h_1 \\ \Delta h_2 \end{bmatrix} + \begin{bmatrix} 0 \\ -y_0 \end{bmatrix} \Delta x_u$$

$$[y] = [1 \quad 0] \begin{bmatrix} \Delta h_1 \\ \Delta h_2 \end{bmatrix} + [0] \Delta x_u$$

c) Odrediti prijenosnu funkciju  $G(s) = \frac{H_1(s)}{X_u(s)}$ , uz  $H_1(s) = \mathcal{L}\{\Delta h_1\}$  i  $X_u(s) = \mathcal{L}\{\Delta x_u\}$ .

$$sH_1(s) + x_1 H_1(s) = x_1 H_2(s), \quad H_2(s) = \frac{s + x_1}{x_1} H_1(s)$$

$$sH_2(s) + x_3 H_2(s) - x_2 H_1(s) = -y_0 X_u(s), \quad H_2(s)(s + x_3) - x_2 H_1(s) = -y_0 X_u(s)$$

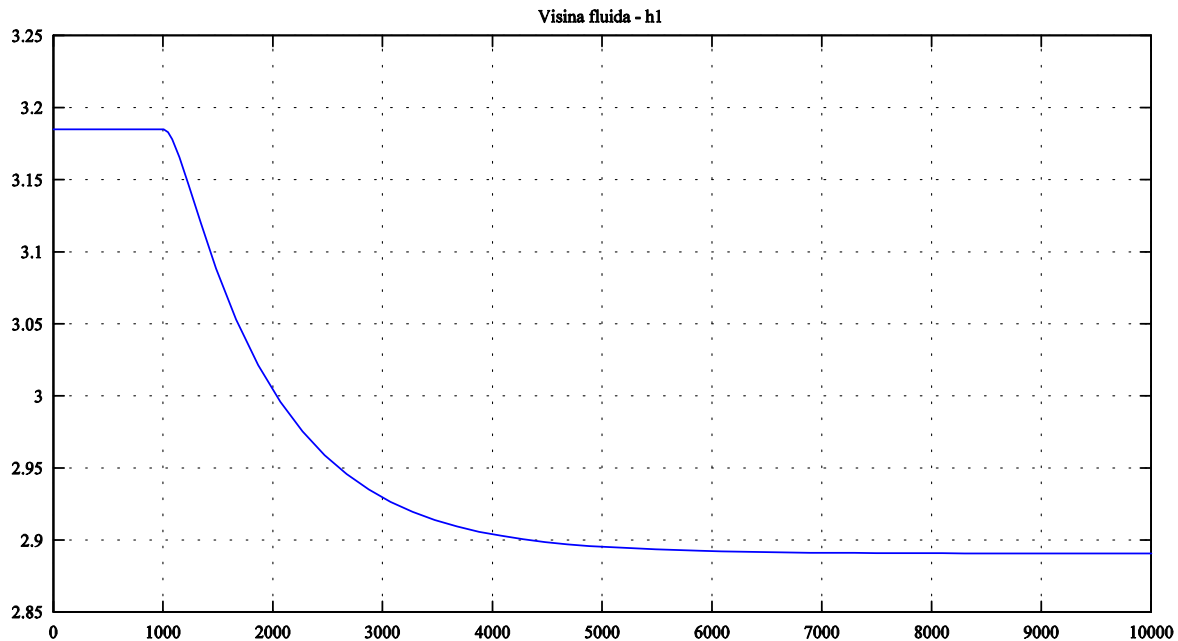
$$\frac{(s + x_3)(s + x_1)}{x_1} H_1(s) - x_2 H_1(s) = -y_0 X_u(s)$$

$$G(s) = \frac{H_1(s)}{X_u(s)} = \frac{-y_0 x_1}{s^2 + (x_1 + x_3)s + (x_1 x_3 - x_1 x_2)}$$

- d) Odrediti odziv razine fluida u prvom spremniku lineariziranog modela na skokovitu promjenu otvorenosti ulaznog ventila  $\Delta x_u = 5$  [%] te ga skicirati.

$$X_u(s) = \frac{5}{s}, \quad H_1(s) = X_u(s)G(s) = \frac{5}{s} \frac{-y_0 x_1}{s^2 + (x_1 + x_2)s + (x_1 x_3 - x_1 x_2)}$$

$$\mathcal{L}^{-1}\{H_1(s)\} = \Delta h_1(t) = (-0.295 + 0.403e^{-1.648 \cdot 10^{-3}t} - 0.108e^{-6.152 \cdot 10^{-3}t})S(t)$$



Slika 2.3. Visina razine fluida u prvom spremniku  $h_1(t)$

- e) Odrediti stacionarnu vrijednost odziva lineariziranog modela za pobudu pod d), kao i nagib odziva u trenutku  $t = 0$  [s]. Odredite razliku u stacionarnom stanju između odziva dobivenim aproksimacijom sustava linearnim modelom u okolini radne točke i odziva stvarno modela.

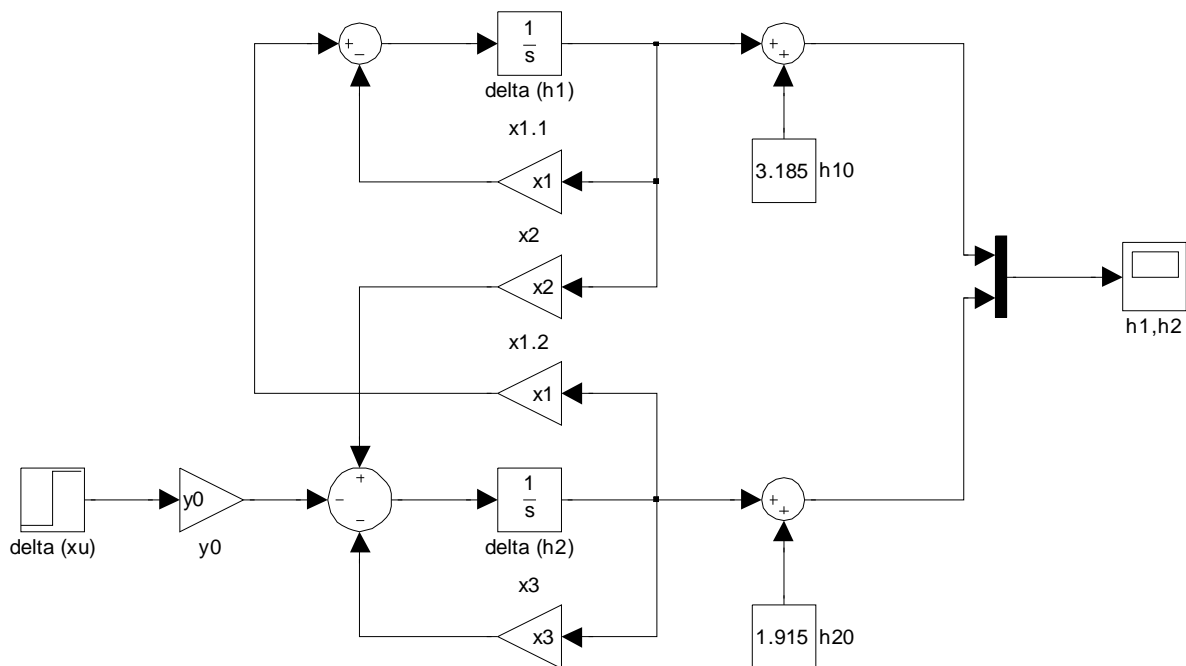
$$\Delta h_{1ss} = \lim_{s \rightarrow 0} s H_1(s) = \frac{-5y_0 x_1}{x_1 x_2 - x_1 x_3} = \frac{-5y_0}{x_3 - x_2}, \quad \Delta h_{1ss} = -0.2929 \text{ [m]}$$

$$\Delta h'_1(0) = \lim_{s \rightarrow \infty} s^2 H_1(s) = \lim_{s \rightarrow \infty} \frac{-5y_0 x_1 s}{s^2 + (x_1 + x_2)s + (x_1 x_2 - x_1 x_3)}, \quad \Delta h'_1(0) = 0$$

$$h_{1[N.M.]} = 2.924 \text{ [m]}, \quad h_{1[L.M.]} = h_{10} + \Delta h_1 = 2.891 \text{ [m]}$$

$$err. = h_{1[N.M.]} - h_{1[L.M.]} = 3.3 \text{ [cm]}$$

f) Nacrtajte simulacijsku shemu lineariziranog modela sustava skladištenja fluida.



Slika 2.4. Simulacijska shema lineariziranog modela