Fizika 1

Grupa 1.03
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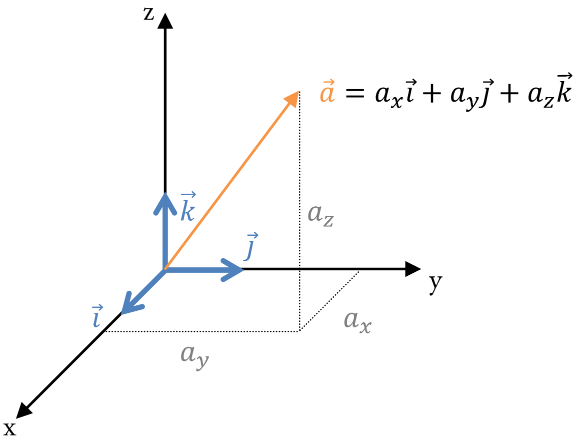
FIZIKALNE VELIČINE: -**SKALARI** (imaju samo iznos ~ temperatura, tlak, gustoća...)
-**VEKTORI** (imaju iznos i smjer ~ brzina, akceleracija, struja...)
-TENZORI

VEKTORI

PRAVOKUTNI KOORDINATNI SUSTAV (desno orijentirani)



$\vec{\imath}, \vec{\jmath}, \vec{k}$ - jedinični vektori
a_x, a_y, a_z - komponente vektora a

ZBRAJANJE VEKTORA

$$\vec{a} + \vec{b} = (a_x + b_x)\vec{\imath} + (a_y + b_y)\vec{\jmath} + (a_z + b_z)\vec{k}$$

MNOŽENJE VEKTORA SKALAROM

$$\lambda\vec{a} = \lambda a_x\vec{\imath} + \lambda a_y\vec{\jmath} + \lambda a_z\vec{k}$$

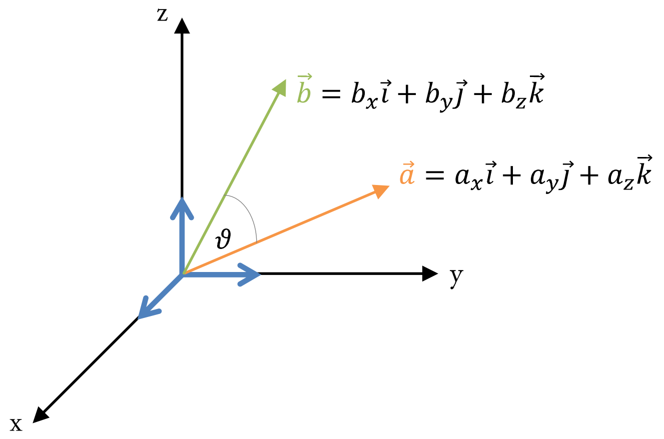
skalar

SKALARNO MNOŽENJE VEKTORA

$$\vec{a} \cdot \vec{b} \equiv \underbrace{a_x b_x + a_y b_y + a_z b_z}_{\text{skalar}}$$

$$\vec{a} \cdot \vec{a} = a_x^2 + a_y^2 + a_z^2$$

$$a = |\vec{a}| = \sqrt{\vec{a} \cdot \vec{a}} = \sqrt{a_x^2 + a_y^2 + a_z^2}$$



$\vec{a} \cdot \vec{b} = |\vec{a}||\vec{b}|\cos\vartheta$

theta, kut među vektorima

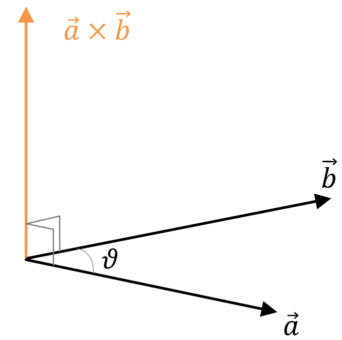
$|\vec{a} + \vec{b}|^2 = |\vec{a}|^2 + 2|\vec{a}||\vec{b}|\cos\vartheta + |\vec{b}|^2$

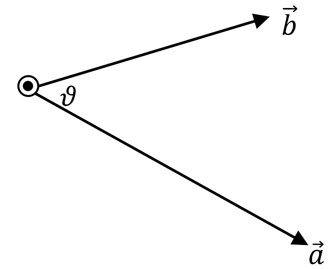
$|\vec{a} + \vec{a}|^2 = 4|\vec{a}|^2 = |\vec{a}|^2 + 2|\vec{a}||\vec{a}|\underbrace{\cos\vartheta}_{=1} + |\vec{a}|^2$ ■

$|\vec{a} - \vec{a}|^2 = 0 = |\vec{a}|^2 + 2|\vec{a}||\vec{a}|\underbrace{\cos\vartheta}_{=-1} + |\vec{a}|^2$ ■

VEKTORSKI PRODUKT

$$\vec{a} \times \vec{b} = \begin{vmatrix} \vec{\imath} & \vec{\jmath} & \vec{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$



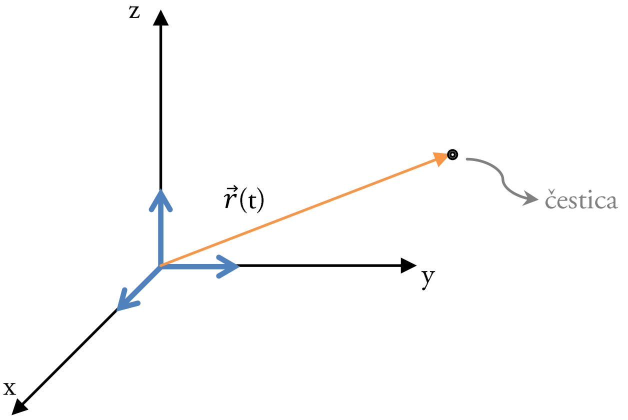


⊗ - „u ploču“
⊙ - prema nama

$\vec{a} \times \vec{b} = -(\vec{b} \times \vec{a})$

$|\vec{a} \times \vec{b}| = |\vec{a}||\vec{b}|\sin\vartheta$

KINEMATIKA TOČKE



POLOŽAJ:

$$\boldsymbol{\vec{r}(t) = x(t)\vec{\imath} + y(t)\vec{\jmath} + z(t)\vec{k}}$$

BRZINA:

$$\boldsymbol{\vec{v}(t) = \frac{d}{dt}\vec{r}(t)}$$

- vremenska derivacija vektora koji opisuje položaj

$$= \frac{d}{dt}x(t)\vec{\imath} + y(t)\vec{\jmath} + z(t)\vec{k} = \frac{dx(t)}{dt}\vec{\imath} + \frac{dy(t)}{dt}\vec{\jmath} + \frac{dz(t)}{dt}\vec{k}$$

$$= v_x(t)\vec{\imath} + v_y(t)\vec{\jmath} + v_z(t)\vec{k}$$

$$\vec{v} \equiv \dot{\vec{r}} \qquad \frac{d}{dt}$$

$$v_x\vec{\imath} + v_y\vec{\jmath} + v_z\vec{k} = \dot{x}\vec{\imath} + \dot{y}\vec{\jmath} + \dot{z}\vec{k}$$

INTEGRALNI ZAPIS:

$$\vec{v}(t) = \frac{d}{dt}\vec{r}(t) \quad /\cdot dt$$

$$d\vec{r}(t) = \vec{v}(t)dt \qquad \int_{t_0}^{t_1}$$

$$\int_{t_0}^{t_1} d\vec{r} = \int_{t_0}^{t_1} \vec{v}(t)\, dt$$

$$\vec{r}(t_1) - \vec{r}(t_0) = \int_{t_0}^{t_1} \vec{v}(t)\, dt$$

$t_1 \rightarrow t,\ \ t \rightarrow t'$

$$\boldsymbol{\vec{r}(t) - \vec{r}(t_0) = \int_{t_0}^{t} \vec{v}(t')\, dt'}$$

„početni uvjet“ brzina!

AKCELERACIJA:

$$\vec{\boldsymbol{a}}(\boldsymbol{t}) \equiv \frac{\boldsymbol{d}}{\boldsymbol{dt}}\vec{\boldsymbol{v}}(\boldsymbol{t})$$

- derivacija brzine po vremenu

$$= \frac{d^2}{dt^2}\vec{v}(t)$$

$$\vec{a}(t) = a_x(t)\vec{\imath} + a_y(t)\vec{\jmath} + a_z(t)\vec{k}$$

$$= \frac{d}{dt}v_x(t)\vec{\imath} + \frac{d}{dt}v_y(t)\vec{\jmath} + \frac{d}{dt}v_z(t)\vec{k} = \frac{d^2x(t)}{dt^2}\vec{\imath} + \frac{d^2y(t)}{dt^2}\vec{\jmath} + \frac{dz(t)}{dt}\vec{k}$$

$$\vec{a} = a_x\vec{\imath} + a_y\vec{\jmath} + a_z\vec{k} = \dot{v}_x\vec{\imath} + \dot{v}_y\vec{\jmath} + \dot{v}_z\vec{k}$$

$$= \ddot{x}\vec{\imath} + \ddot{y}\vec{\jmath} + \ddot{z}\vec{k}$$

$$\vec{a}(t) = \frac{d}{dt}\vec{v}(t) \quad /\cdot dt$$

$$d\vec{v}(t) = \vec{a}(t)dt \qquad \int_{t_0}^{t_1}$$

$$\int_{t_0}^{t_1} d\vec{v} = \int_{t_0}^{t_1} \vec{a}(t)\,dt$$

$$\vec{v}(t_1) - \vec{v}(t_0) = \int_{t_0}^{t_1} \vec{a}(t)\,dt$$

$t_1 \rightarrow t,\ t \rightarrow t'$

$$\vec{\boldsymbol{v}}(\boldsymbol{t}) = \boldsymbol{v}(\boldsymbol{t_0}) + \int_{t_0}^{t} \vec{\boldsymbol{a}}(\boldsymbol{t}')\,\boldsymbol{dt}'$$

PRIMJER 1 – HARMONIČKO TITRANJE

položaj čestice na x-osi:

$$x(t) = A\cos{(\omega t)}$$
$$A, \omega \rightarrow konstante$$
$$v(t) = ?, a(t) = ?$$

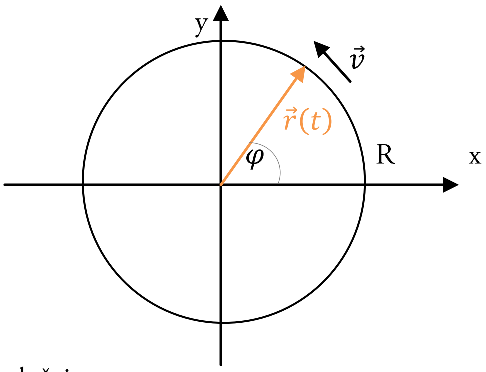
$$x(t) = A \cdot \cos{(\omega t + \Phi)}$$

amplituda frekvencija fazni pomak

$$v(t) = \frac{d}{dt}x(t) = \frac{d}{dt}\big(A\cos{(\omega t + \Phi)}\big) = \boldsymbol{-A\omega \cdot \sin{(\omega t + \Phi)}}$$

$$a(t) = \frac{d}{dt}v(t) = \frac{d}{dt}\big(-A\omega \cdot \sin{(\omega t + \Phi)}\big) = -\omega^2 A \cdot \cos(\omega t + \Phi)$$
$$= \boldsymbol{-\omega^2 x(t)}$$

PRIMJER 2 – GIBANJE PO KRUŽNICI POLUMJERA R BRZINOM STALNOG IZNOSA v



položaj:

$\vec{r}(t) = Rcos(\varphi)\vec{\imath} + Rsin(\varphi)\vec{\jmath}$

φ – raste linearno u vremenu

$\varphi = \omega t$

$$\vec{r}(t) = R\big(\vec{\imath}cos(\omega t) + \vec{\jmath}sin(\omega t)\big)$$

$$\vec{v}(t) = R\left(\vec{\imath}\big(-\omega sin(\omega t)\big) + \vec{\jmath}\big(\omega cos(\omega t)\big)\right) = -\omega R\big(\vec{\imath}sin(\omega t) - \vec{\jmath}cos(\omega t)\big)$$

$$\vec{a}(t) = -\omega^2 R\big(\vec{\imath}cos(\omega t) + \vec{\jmath}sin(\omega t)\big) = -\omega^2\vec{r}(t)$$

$$\omega T = 2\pi$$

$$v = \frac{2R\pi}{T} = \frac{2R\pi}{\frac{2\pi}{\omega}} = \omega R \rightarrow \ \omega = \frac{v}{R}$$

$$\begin{aligned}
|\vec{v}| &= \sqrt{\vec{v}\cdot\vec{v}} = \sqrt{\left[-\omega R\big(\vec{\imath}sin(\omega t) - \vec{\jmath}cos(\omega t)\big)\right]\cdot\left[-\omega R\big(\vec{\imath}sin(\omega t) - \vec{\jmath}cos(\omega t)\big)\right]} \\
&= \sqrt{(-\omega R)^2\cdot\big(\vec{\imath}sin(\omega t) - \vec{\jmath}cos(\omega t)\big)\cdot\big(\vec{\imath}sin(\omega t) - \vec{\jmath}cos(\omega t)\big)} \\
&= \sqrt{(-\omega R)^2\cdot[(\vec{\imath}\cdot\vec{\imath})\sin^2(\omega t) - (\vec{\imath}\cdot\vec{\jmath})\,sin(\omega t)\cos(\omega t) - (\vec{\jmath}\cdot\vec{\imath})\,sin(\omega t)\cos(\omega t) + (\vec{\jmath}\cdot\vec{\jmath})\cos^2(\omega t)} \\
&= \omega R\sqrt{\sin^2(\omega t) + \cos^2(\omega t)} = \boldsymbol{\omega R} \quad \blacksquare
\end{aligned}$$

EKSPERIMENT- SLOBODNI PAD

s/m	t/s			$\bar{t}/s$
0.2000	0.2019	0.2019		0.2019
0.8000	0.4037	0.4037		0.4037
1.8000	0.6062	0.6060	0.6066	0.6063

$s(t) = At^2$

$A = \frac{\sum_{i=1}^{N} S_i t_i^2}{\sum_{i=1}^{N} t_i}$

$s(t) = A' t^n$

$g = \bar{g} \pm \sigma_g$ $\qquad$ $\boldsymbol{\bar{g} = \frac{2\bar{s}}{t^2}}$

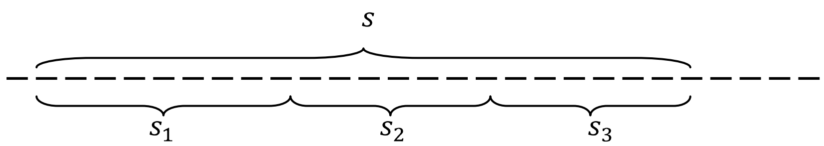
$s = (1.8000 \pm 0.0005)$

$t = (0.6063 \pm 0.0001)$

ZADATAK – HORVAT – 1.1

-pješak; pola vremena hoda v_1=2 km/h, pola preostalog puta trči 7 km/h, a drugu polovicu preostalog puta v_3=5 km/h. Izračunaj srednju brzinu gibanja tog pješaka!

$\bar{v} =?$



$s_1 = v_1 t_1 \qquad s_2 = v_2 t_2 \qquad s_3 = v_3 t_3$

$t_1 = t_2 + t_3$

$s_2 = s_3$

$\bar{v} = \frac{s}{t} = \frac{s_1 + s_2 + s_3}{t_1 + t_2 + t_3}$

$t_2 = \frac{v_3 t_3}{v_2}$

$t_3 = \frac{v_2 t_2}{v_3}$

$t_2 + t_3 = \frac{v_3 t_3}{v_2} + \frac{v_2 t_2}{v_3}$

$t_3 = t_1 - t_2 \rightarrow t_2 + t_1 - t_2 = \frac{v_3 (t_1 - t_2)}{v_2} + \frac{v_2 t_2}{v_3}$

$\left(1 - \frac{v_3}{v_2}\right) t_1 = \left(\frac{v_2}{v_3} - \frac{v_3}{v_2}\right) t_2 \qquad / \cdot v_2 v_3 \qquad (\ldots)$

$t_3 = \frac{v_2}{v_2 + v_3} t_1$

$\bar{v} = \frac{s_1 + s_2 + s_3}{t_1 + t_2 + t_3} = \frac{v_1 t_1 + v_2 t_2 + v_3 t_3}{t_1 + t_2 + t_3} = \frac{v_1 t_1 + \frac{v_2 v_3 t_1}{v_2 + v_3} + \frac{v_2 v_3 t_1}{v_2 + v_3}}{2 t_1} = \frac{v_1}{2} + \frac{v_2 v_3}{v_2 + v_3} = 1 + \frac{35}{12} = \frac{47}{12}$

ZADATAK – „ELEKTRIJADA“ – 1

Čestica se giba duž x-osi tako da joj se brzina mijenja kao $v(x) = \frac{A}{B}(1 + B(x)$ gdje su A i B konstante,a x je koordinata čestice. Odredi ubrzanje pri položaju $x = \frac{1}{B}$!

$$a(x) = \frac{d}{dt}v(x) = \frac{d}{dt}v(x(t)) = \frac{dv}{dx}\frac{dx}{dt} = \left[\frac{d}{dx}\left(\frac{A}{B}(1 + B(x))\right)\right]\left[\frac{A}{B}(1 + B(x))\right]$$

$$= \frac{A}{B}B\frac{A}{B}(1 + Bx) = \frac{A^2}{B}(1 + Bx)$$

$$a\left(\frac{1}{B}\right) = \frac{A^2}{B}\left(1 + B\frac{1}{B}\right) = \frac{2A^2}{B}$$

ZADATAK

Brzina čestice koja se giba duž x-osi je $v(x) = v_0 e^{-x/b}$. Pri tom su v_0 i b konstante. Odredi položaj kao funkciju vremena ako je poznato da je u početnom trenutku $t_0=0$, $x(t_0)=0$!

$$v = \frac{dx}{dt} = v_0 e^{-\left(\frac{x}{b}\right)} \qquad /\cdot e^{\left(\frac{x}{b}\right)}dt$$

$$e^{\frac{x}{b}}dx = v_0 e^{-\left(\frac{x}{b}\right)} \qquad \int_{"0"}^{"1"}$$

$$\int_{x_0}^{x_1} e^{\frac{x}{b}}\, dx = \int_{t_0}^{t_1} v_0 dt$$

$$be^{\frac{x}{b}}\,|_{x_0}^{x_1} = v_0 t\,|_{t_0}^{t_1}$$

$$b\left(e^{\frac{x_1}{b}} - e^{\frac{x_0}{b}}\right) = v_0(t_1 - t_0)$$

$$b\left(e^{\frac{x_1}{b}} - 1\right) = v_0 t_1$$

konačno stanje „poopćujemo“

$$t_1 \to t, x_1 \to x(t)$$

$$b\left(e^{\frac{x(t)}{b}} - 1\right) = v_0 t$$

$$e^{\frac{x(t)}{b}} = \frac{v_0 t}{b} + 1$$

$$x(t) = b \cdot ln\left(\frac{v_0 t}{b} + 1\right)$$

NEWTONOVI AKSIOMI

Čestica **m** – ima samo masu, nema ni oblik, ni dimenzije, ni orijentaciju

KOLIČINA GIBANJA

$$\vec{p} = m\vec{v}$$

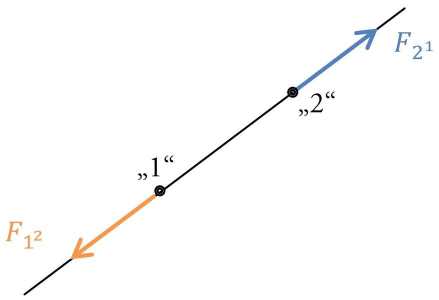
masa brzina

PRVI AKSIOM – Kad na česticu djeluje sila ona ostaje u stanju mirovanja ili jednolikog gibanja po pravcu
- vrijedi u inercijalnim sustavima

DRUGI AKSIOM – Vremenska promjena količine gibanja čestice je razmjerna sili koja na česticu djeluje

$$\frac{d\vec{p}}{dt} = \vec{F}$$

TREĆI AKSIOM – Ako tijelo/čestica djeluje na drugu česticu silom, tada druga čestica djeluje na prvu silom istog iznosa, ali suprotnog smjera. Te sile leže na istom pravcu (pravcu koji prolazi dvjema česticama).



NEWTONOVA JEDNADŽBA GIBANJA

$$\frac{d}{dt}\vec{p} = \frac{d}{dt}(m\vec{v}) = m\frac{d\vec{v}}{dt} = \boldsymbol{m\vec{a}} = \boldsymbol{\vec{F}}$$

$$\vec{F}(\vec{r},t) = \vec{F}_0 \rightarrow konst.$$

prvi korak: BRZINA

$$\frac{d\vec{p}}{dt} = \overrightarrow{F_0} \rightarrow \frac{d\vec{v}}{dt} = \frac{\overrightarrow{F_0}}{m} \qquad / \cdot dt$$

$$d\vec{v} = \frac{\overrightarrow{F_0}}{m}dt \qquad \int_{poč}^{kon}$$

$$\int_{poč}^{kon} d\vec{v} = \int_{poč}^{kon} \frac{\overrightarrow{F_0}}{m}dt$$

$$\vec{v}\,|_{poč}^{kon} = \frac{\overrightarrow{F_0}}{m}t\,|_{poč}^{kon}$$

$$\vec{v}_{kon} - \vec{v}_{poč} = \frac{\overrightarrow{F_0}}{m}(t_{kon} - t_{poč})$$
$$t_{poč} \rightarrow t_0, \qquad t_{kon} \rightarrow t$$

$$\vec{v}(t) - \vec{v}(t_0) = \frac{\overrightarrow{F_0}}{m}(t - t_0)$$
$$\vec{v}(t) = \frac{\overrightarrow{F_0}}{m}(t - t_0) + \vec{v}(t_0)$$

početni uvjet

drugi korak: POLOŽAJ

$$\frac{d\vec{r}}{dt} = \vec{v} \qquad / \cdot dt$$

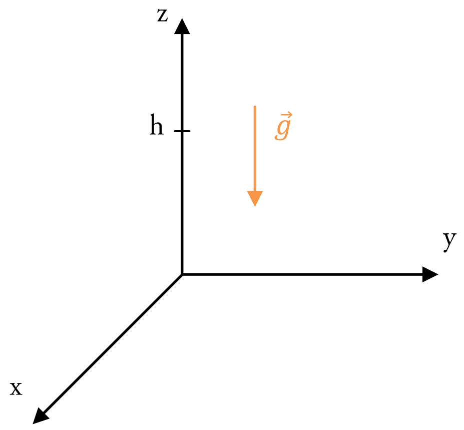
$$d\vec{r} = \vec{v}dt$$

$$\int_{poč}^{kon} d\vec{r} = \int_{poč}^{kon} \vec{v}dt$$

$$\vec{r}(t_1) - \vec{r}(t_0) = \int_{t_0}^{t} \vec{v}(t')dt' = \int_{t_0}^{t} [\vec{v}(t_0) + \frac{\overrightarrow{F_0}}{m}(t' - t_0)]\, dt'$$
$$= \vec{v}(t_0)(t' - t_0) + \frac{\overrightarrow{F_0}}{2m}(t' - t_0)^2$$

$$\vec{r}(t) = \vec{r}(t_0) + \vec{v}(t_0)(t - t_0) + \frac{\overrightarrow{F_0}}{2m}(t - t_0)^2$$

PRIMJER – SLOBODNI PAD



sila $\vec{F_0} = -mg\vec{k}$

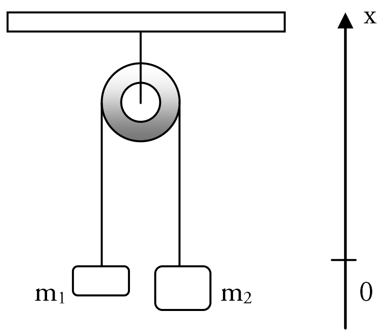
početni uvjeti u $t=t_0=0$

$\vec{v}(t_0) = \vec{v}(0) = \vec{v_0} = 0$
$\vec{r}(t_0) = \vec{r_0} = h\vec{k}$

$\vec{v}(t) = -g\vec{k}t$

$\vec{r}(t) = (h - \frac{g}{2}t^2)\vec{k}$

PRIMJER – PADOSTROJ



$\vec{r_1}(t) = x_1(t)\vec{\imath}$
$\vec{r_2}(t) = x_2(t)\vec{\imath}$

$x_1(t) = -x_2(t)$

$\dot{x}_1(t) = -\dot{x}_2(t)$
$\ddot{x}_1(t) = -\ddot{x}_2(t)$

JEDNADŽBA GIBANJA

$m_1\ddot{x}_1 = T - m_1 g$
$m_2\ddot{x}_2 = T - m_2 g$

napetost niti

$m_1\ddot{x}_1 - m_2\ddot{x}_2 = (m_2 - m_1)g$

$\ddot{x}_1 = -\ddot{x}_2 = \frac{m_2 - m_1}{m_2 + m_1}g$

ZADATAK – PADOSTROJ

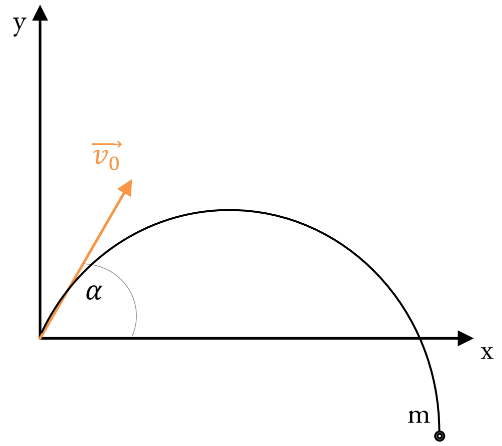
m_1=400 g
m_2=402 g
iz mirovanja
t_1-t_0=6.4 s
$x_1(t_1)$ –$x_1(t_0)$=0.5 m
izračunaj g !

$$x_1(t_1) - x_1(t_0) = \frac{a_x}{2}(t_1 - t_0)^2$$

$$x_1(t_1) - x_1(t_0) = \frac{a_x}{2}(t_1 - t_0)^2$$

$$a_x = \frac{m_2 - m_1}{m_2 + m_1} g \to g = \frac{m_2 + m_1}{m_2 - m_1} \cdot \frac{2[x_1(t_1) - x_1(t_0)]}{(t_1 - t_0)^2} = \frac{400 + 402}{402 - 400} \cdot \frac{(2 \cdot 0.5)}{(6.4)^2} = \mathbf{9.79} \frac{\boldsymbol{m}}{\boldsymbol{s^2}}$$

KOSI HITAC



početni uvjeti u t=t_0=0

$$\vec{v}(t_0) = \vec{v}(0) = \vec{v_0} = v_0(\cos\alpha\,\vec{i} + \sin\alpha\vec{j})$$

$$\vec{r}(t_0) = \vec{r}(0) = \vec{r_0} = 0$$

sila:

$$\vec{F_0} = -mg\vec{j}$$

$$\vec{v}(t) = \frac{\vec{F_0}}{m}(t - t_0) + \vec{v}(t_0)$$

$$\vec{r}(t) = \vec{r}(t_0) + \vec{v}(t_0)(t - t_0) + \frac{\vec{F_0}}{2m}(t - t_0)^2$$

uvrštavanje:

$$\to \vec{v}(t) = v_0(\cos\alpha\,\vec{i} + \sin\alpha\vec{j}) - gt\vec{j}$$

$$\to \vec{r}(t) = v_0(\cos\alpha\,\vec{i} + \sin\alpha\vec{j})t - \frac{g}{2}t^2\vec{j}$$

po komponentama:

$$v_x(t) = v_0\cos\alpha$$

$$v_y(t) = v_0\sin\alpha - gt$$

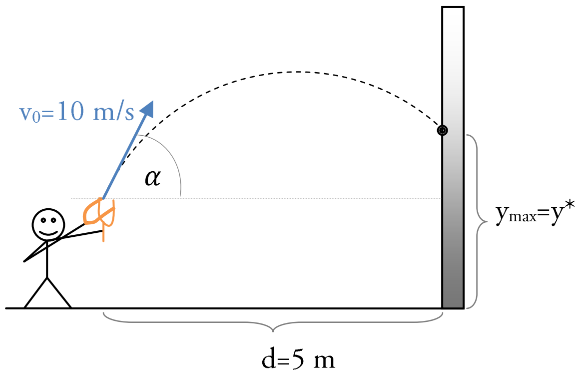
$$x(t) = v_0\cos\alpha \cdot t$$

$$y(t) = v_0\sin\alpha \cdot t - \frac{g}{2}t^2$$

$$y = v_0\sin\alpha\frac{x}{v_0 cos\alpha} - \frac{g}{2}\left(\frac{x}{v_0 cos\alpha}\right)^2 = x \cdot tg\,\alpha - \frac{g}{2}\frac{x^2}{v_0^2\cos^2\alpha}$$

$\boldsymbol{y(x) = ux - \frac{gx^2}{2v_0^2}(1 + u^2)}$ gdje je u=tg α

ZADATAK – DJEČAK S PRAĆKOM



Pod kojim kutem dječak treba iz praćke ispucati kamen brzinom 10 m/s ako stoji na 5 m od zida a da taj kamen pogodi što višu točku zida?

$y(x) = ux - \frac{gx^2}{2v_0^2}(1+u^2)$ gdje je u=tg α

tražimo max funkcije y*

$$0 = \frac{dy^*}{du} = \frac{d}{du}\left(ud - \frac{gd^2}{2v_0^2}(1+u)^2\right) = d - \frac{gd^2}{2v_0^2}2u = d - \frac{gd^2}{v_0^2}u$$

$$\rightarrow u = \frac{v_0^2}{gd} = \frac{100}{9.81 \cdot 5} = \frac{20}{9.81} = 2.038$$

$arc\ tg\ u = 63.87°$

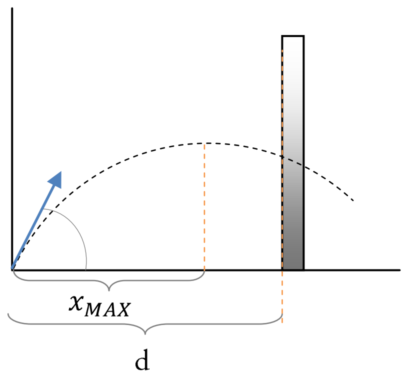
tražimo tjeme parabole

$$y(x) = u^*x - \frac{gx^2}{2v_0^2}(1+(u^*)^2) = \frac{v_0^2}{gd}x - \frac{gx^2}{2v_0^2}\left(1+\frac{v_0^4}{g^2d^2}\right) = \frac{v_0^2}{gd}x - \frac{gx^2}{2v_0^2} - \frac{v_0^2 gx^2}{2g^2d^2} \qquad y = ax^2 + bx + x$$

$$x_{MAX} = -\frac{b}{2a} \rightarrow tjeme\ parabole = \frac{\frac{v_0^2}{gd}}{2\left(\frac{g}{2v_0^2}+\frac{v_0^2}{2gd^2}\right)} = \frac{\frac{v_0^2}{gd}}{\frac{2v_0^2}{gd}\left(\frac{g^2d}{2v_0^4}+\frac{1}{2d}\right)} = \frac{1}{2\left(\frac{g^2d}{2v_0^4}+\frac{1}{2d}\right)} = \frac{1}{\frac{g^2d}{v_0^4}+\frac{1}{d}}$$

$$= \frac{d}{1+\frac{g^2d^2}{v_0^4}}$$

$\boldsymbol{x_{MAX} < d}$ a to je ono što smo dokazivali, da će kamen dosegnuti najvišu točku zida ako mu je tjeme parabole po kojoj leti ispred zida ■



Rješavanje Newtonove jednadžbe gibanja za silu razmjernu brzini

$$\boldsymbol{\vec{F} = -\gamma\vec{v}} \longrightarrow \text{brzina}$$

sila konst.

uvrštavanje:

$$\frac{d\vec{p}}{dt} = \vec{F}$$

$$m \cdot \dot{\vec{v}} = -\gamma\vec{v}$$

x komponenta –

$$m \cdot \dot{v_x} = -\gamma v_x$$

$$m\frac{dv_x}{dt} = -\gamma v_x \qquad /\cdot \frac{dt}{mv_x}$$

$$\frac{dv_x}{v_x} = -\frac{dt\gamma}{m} \qquad \int_{poč}^{kon}$$

$$\ln v_x(kon) - \ln v_x(poč) = -\frac{\gamma}{m}\big(t(kon) - t(poč)\big)$$

v(t) $\quad$ v(t_0) $\quad$ t $\quad$ t_0

$$\boldsymbol{v_x(t) = v_x(t_0) \cdot e^{-\frac{\gamma}{m}(t-t_0)}}$$

zaključno sa predavanjem 08.03.'10.