

PRIJENOS I DISTRIBUCIJA ELEKTRIČNE ENERGIJE

**6. NADOMJESNI MODELI  
ELEKTROENERGETSKIH VODOVA**

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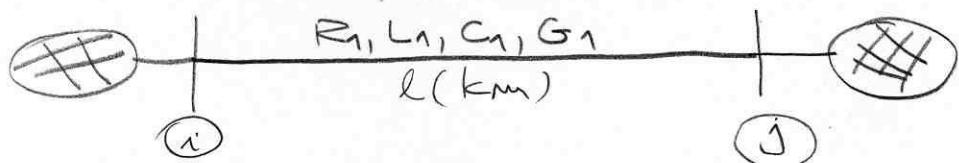
## 6. NADOMESNI MODEL

### ELEKTRONERGERSKIH VOLDA

- 6.1 Nadomesni model elektronergereskih volda
- 6.2 Pravljeno teorije centropsa
- 6.3 Točan  $\pi$  model te vola
- 6.4 Točan T model te vola
- 6.5 Pribuzan  $\pi$  i T model te vola
- 6.6 Nadomesni modeli sinkronih generatora
- 6.7 Nadomesni modeli energetskih transformatora

## 6.1 NADOMJESNI MODELI (SCHEM) ELEKTRONERGETSKI VODA

### ELEKTRONERGETSKI VOD



- MATRICA JEDINICNIH KONSTANTI EE VODA
- PRIMJENOM METODE SIMETRICALI KOMPONENTA  
VODA Simetricali ee vod, odredi se:

a) Uzdužni rednični  
impedancijski komponenti  
ee voda

$$\begin{bmatrix} \vec{Z}_{012} \\ \vec{Z}_1 \end{bmatrix} = \begin{bmatrix} \vec{Z}_1^{00} & \vec{Z}_1^{11} \\ \vec{Z}_1^{11} & \vec{Z}_1^{22} \end{bmatrix}$$

b) Uzdužni jedinici  
admitancijski komponenti  
ee voda

$$\begin{bmatrix} \vec{Y}_{012} \\ \vec{Y}_1 \end{bmatrix} = \begin{bmatrix} \vec{Y}_1^{00} & \vec{Y}_1^{11} \\ \vec{Y}_1^{11} & \vec{Y}_1^{22} \end{bmatrix}$$

Pri čemu je:  $\vec{Z}_1^m = \vec{Z}_1^{22} = \vec{Z}_1$        $\vec{Y}_1^m = \vec{Y}_1^{22} = \vec{Y}_1$

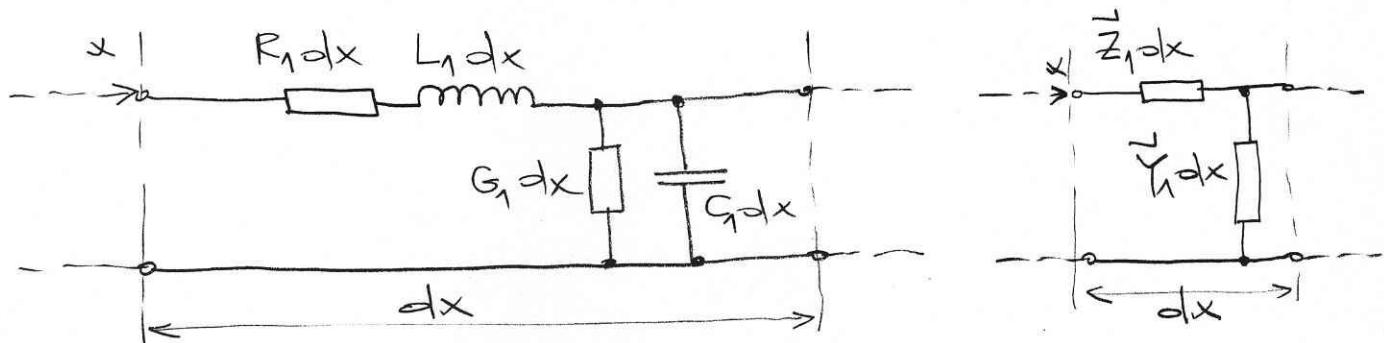
$\vec{Z}_1$  = jedinica uzdužna početna impedancija voda

$\vec{Y}_1$  = jedinica početna početna admittanca voda

- EE vod zadane jedinice konstanti i zadane  
dubine voda  $l(\text{km})$  pravozvemo:
  - Nadomjescnim operacijama za direktni sustav
  - Nadomjescnim operacijama za milti sustav
- Ako je ee vod simetričan i homogen, tada  
je nadomjescni operaciji ee voda simetričan:
  - T zengrabil
  - T četverabil

# TETTELYNI (IZVORNI) NADODJESNI MODEL EE VODA

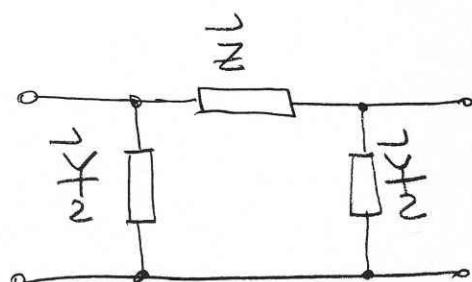
1. MODEL EE VODA SA RASPREDJENIM  
PARAMETRIMA



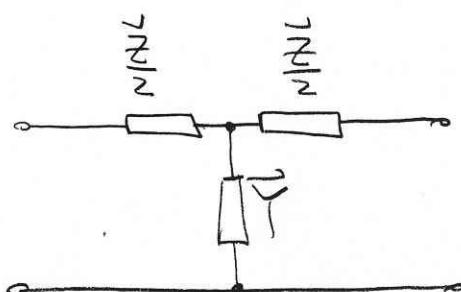
TELEGRAPSKIE JESENADZBE  
PRIDENOŠNE JESENADZBE I / II / III OBlik

$$\begin{aligned} \text{II. OBlik} \quad \vec{V} &= \vec{V}_2 \operatorname{ch} \gamma x + \vec{Z}_c \vec{I}_2 \operatorname{sh} \gamma x \\ \vec{I} &= \vec{I}_2 \operatorname{ch} \gamma x + \frac{\vec{V}_2}{\vec{Z}_c} \operatorname{sh} \gamma x \end{aligned}$$

2. MODEL EE VODA SA KONCENTRIRANIM  
PARAMETRIMA



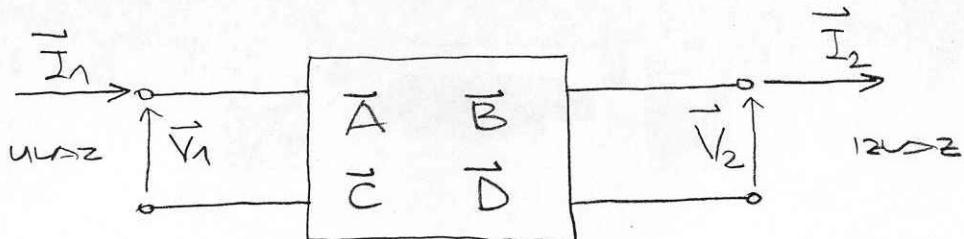
$\Pi$ -model



T-model

## 6.2 PRIMJENA TEORIJE ČETVEROPOLA

### PRIJEMOSNE JEDNAĐEŽBE ČETVEROPOLA



$\vec{A}, \vec{B}, \vec{C}, \vec{D}$  opće konstante prezenosa

PREZENOSNE JEDNAĐEŽBE ČETVEROPOLA:

$$\begin{aligned}\vec{V}_1 &= \vec{A} \vec{V}_2 + \vec{B} \vec{I}_2 \\ \vec{I}_1 &= \vec{C} \vec{V}_2 + \vec{D} \vec{I}_2\end{aligned}\quad \begin{bmatrix} \vec{V}_1 \\ \vec{I}_1 \end{bmatrix} = \begin{bmatrix} \vec{A} & \vec{B} \\ \vec{C} & \vec{D} \end{bmatrix} \begin{bmatrix} \vec{V}_2 \\ \vec{I}_2 \end{bmatrix}$$

$$[L] = \begin{bmatrix} \vec{A} & \vec{B} \\ \vec{C} & \vec{D} \end{bmatrix} \quad \text{LANČANO MATRICA}$$

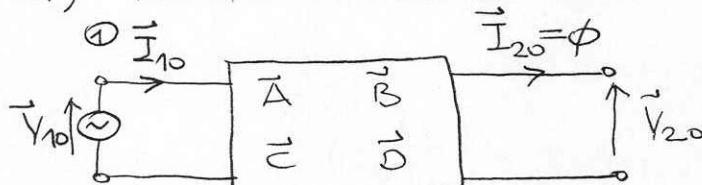
SIMETRIČAN ČETVERPOL:  $\vec{A} = \vec{D}$

RECIPROČAN ČETVERPOL:  $\det \begin{bmatrix} \vec{A} & \vec{B} \\ \vec{C} & \vec{D} \end{bmatrix} = \vec{AD} - \vec{BC} = 1$

PASIVAN ČETVERPOL:  $\begin{bmatrix} \vec{V}_2 \\ \vec{I}_2 \end{bmatrix} = [L]^{-1} \begin{bmatrix} \vec{V}_1 \\ \vec{I}_1 \end{bmatrix}$

ODREĐIVANJE OPĆIH KONSTANTI PREZENOSA  
(parametri četveropola)

a) POKUS PRAZNOG HODA



$$\begin{bmatrix} \vec{V}_{10} \\ \vec{I}_{10} \end{bmatrix} = [L] \begin{bmatrix} \vec{V}_{20} \\ \phi \end{bmatrix}$$

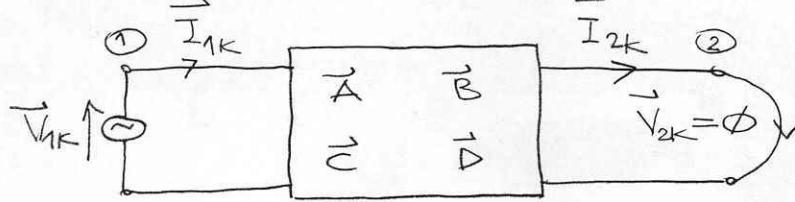
$$\vec{V}_{10} = \vec{A} \vec{V}_{20}$$

$$\vec{A} = \frac{\vec{V}_{10}}{\vec{V}_{20}}$$

$$\vec{I}_{10} = \vec{C} \vec{V}_{20}$$

$$\vec{C} = \frac{\vec{I}_{10}}{\vec{V}_{20}}$$

b) FOKUS KRATKOG SPADA



$$\begin{bmatrix} \vec{V}_{1K} \\ \vec{I}_{1K} \end{bmatrix} = \begin{bmatrix} \vec{A} & \vec{B} \\ \vec{C} & \vec{D} \end{bmatrix} \begin{bmatrix} \emptyset \\ \vec{I}_{2K} \end{bmatrix}$$

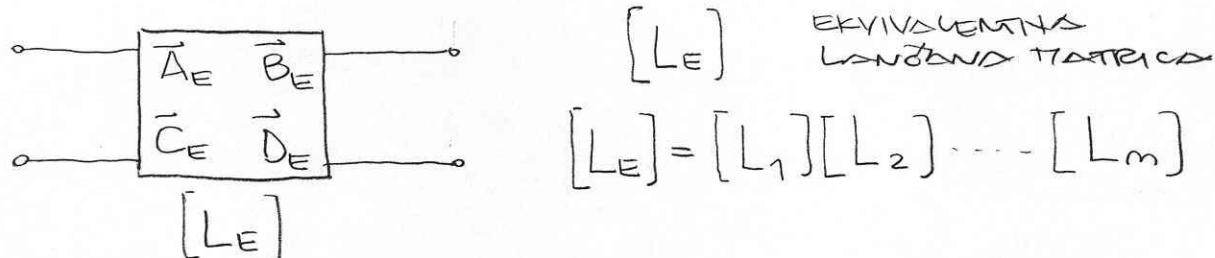
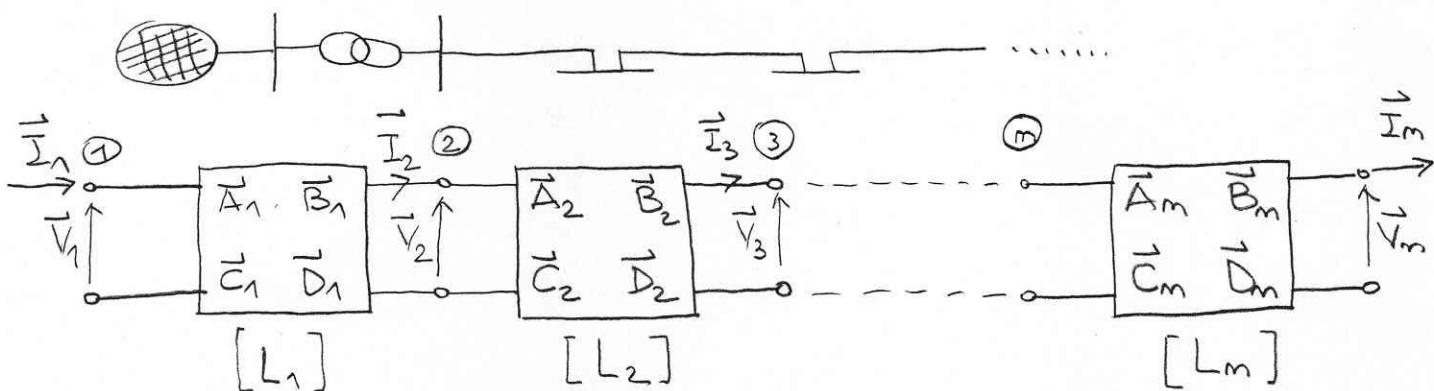
$$\vec{V}_{1K} = \vec{B} \vec{I}_{2K}$$

$$\vec{I}_{1K} = \vec{D} \vec{I}_{2K}$$

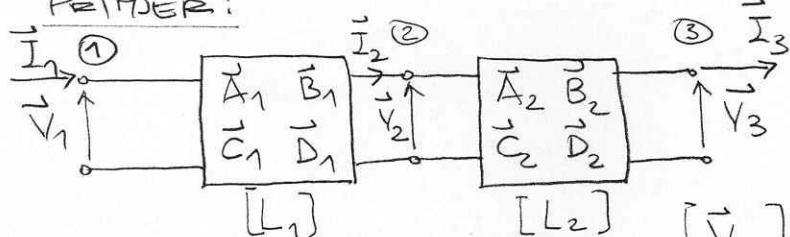
$$\vec{B} = \frac{\vec{V}_{1K}}{\vec{I}_{2K}}$$

$$\vec{D} = \frac{\vec{I}_{1K}}{\vec{I}_{2K}}$$

LÄHDAK ÖVERFÖR



PRIMER:



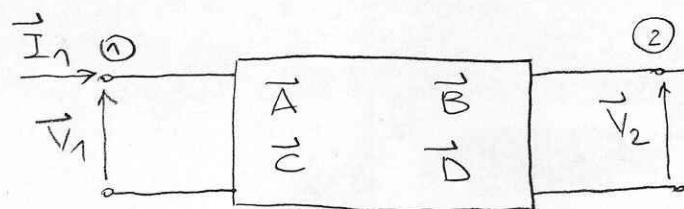
$$\begin{bmatrix} \vec{V}_1 \\ \vec{I}_1 \end{bmatrix} = \begin{bmatrix} \vec{A}_E & \vec{B}_E \\ \vec{C}_E & \vec{D}_E \end{bmatrix} \begin{bmatrix} \vec{V}_3 \\ \vec{I}_3 \end{bmatrix}$$

$$\begin{bmatrix} \vec{V}_1 \\ \vec{I}_1 \end{bmatrix} = \begin{bmatrix} \vec{A}_1 & \vec{B}_1 \\ \vec{C}_1 & \vec{D}_1 \end{bmatrix} \begin{bmatrix} \vec{A}_2 & \vec{B}_2 \\ \vec{C}_2 & \vec{D}_2 \end{bmatrix} \begin{bmatrix} \vec{V}_3 \\ \vec{I}_3 \end{bmatrix}$$



$$[L_E] = [L_1][L_2] = \begin{bmatrix} \vec{A}_E & \vec{B}_E \\ \vec{C}_E & \vec{D}_E \end{bmatrix} = \begin{bmatrix} \vec{A}_1 \vec{A}_2 + \vec{B}_1 \vec{C}_2 & \vec{A}_1 \vec{B}_2 + \vec{B}_1 \vec{D}_2 \\ \vec{C}_1 \vec{A}_2 + \vec{D}_1 \vec{C}_2 & \vec{C}_1 \vec{B}_2 + \vec{D}_1 \vec{D}_2 \end{bmatrix}$$

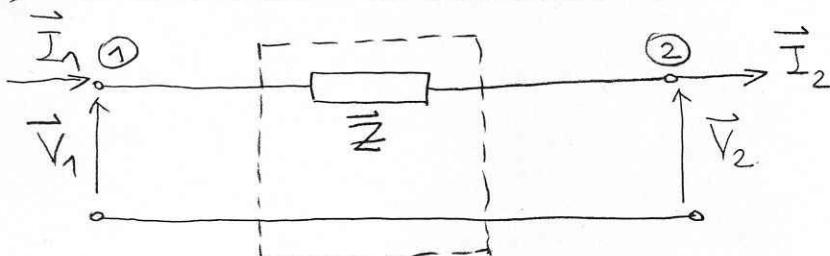
# OPĆE KONSTANTE ELEMENTARNIH ČETVERPOLA



$$\begin{bmatrix} \vec{V}_1 \\ \vec{I}_1 \end{bmatrix} = \begin{bmatrix} \vec{A} & \vec{B} \\ \vec{C} & \vec{D} \end{bmatrix} \begin{bmatrix} \vec{V}_2 \\ \vec{I}_2 \end{bmatrix}$$

PREJEMNE JEDNADŽBE

## a) UZDUŽNA IMPEDANCIJA



PREJEMNE JEDNADŽBE

$$\vec{V}_1 = \vec{A} \vec{V}_2 + \vec{B} \vec{I}_2$$

$$\vec{I}_1 = \vec{C} \vec{V}_2 + \vec{D} \vec{I}_2$$

$$\vec{A} = 1$$

$$\vec{B} = \vec{Z}$$

$$\vec{C} = 0$$

$$\vec{D} = 1$$

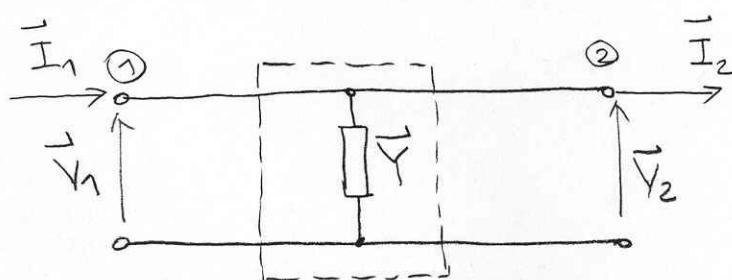
$$\vec{V}_1 = 1 \cdot \vec{V}_2 + \vec{Z} \vec{I}_2$$

$$\vec{I}_1 = 0 \cdot \vec{V}_2 + 1 \cdot \vec{I}_2$$

$$[L_z] = \begin{bmatrix} 1 & \vec{Z} \\ 0 & 1 \end{bmatrix}$$

ČETVERPOL JE SIMETRIČAN ( $\vec{A} = \vec{D}$ ) , RECIPROKN (det[Lz]=1).

## b) PREDJECNA ADMITANCIJA



PREJEMNE JEDNADŽBE

$$\vec{V}_1 = \vec{A} \vec{V}_2 + \vec{B} \vec{I}_2$$

$$\vec{I}_1 = \vec{C} \vec{V}_2 + \vec{D} \vec{I}_2$$

$$\vec{A} = 1 \quad \vec{B} = 0$$

$$\vec{C} = \vec{Y} \quad \vec{D} = 1$$

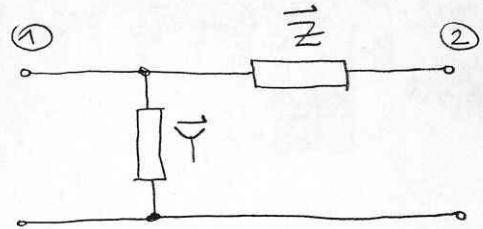
$$\vec{V}_1 = 1 \cdot \vec{V}_2 + 0 \cdot \vec{I}_2$$

$$\vec{I}_1 = \vec{Y} \vec{V}_2 + 1 \cdot \vec{I}_2$$

$$[L_Y] = \begin{bmatrix} 1 & 0 \\ \vec{Y} & 1 \end{bmatrix}$$

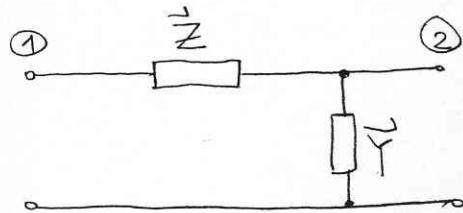
ČETVERPOL JE SIMETRIČAN ( $\vec{A} = \vec{D}$ ) , RECIPROKN (det[LY]=1).

### $\Gamma$ - ŠEMA ČEVREROBLOU



$$[L_\Gamma] = [L_Y][L_Z]$$

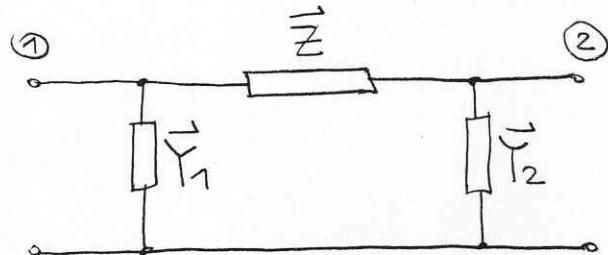
$$[L_\Gamma] = [L_Y][L_Z] = \begin{bmatrix} 1 & 0 \\ \bar{Y} & 1 \end{bmatrix} \begin{bmatrix} 1 & \bar{Z} \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & \bar{Z} \\ \bar{Y} & \bar{Y}\bar{Z} + 1 \end{bmatrix}$$



$$[L_\Gamma] = [L_Z][L_Y]$$

$$[L_\Gamma] = [L_Z][L_Y] = \begin{bmatrix} 1 & \bar{Z} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \bar{Y} & 1 \end{bmatrix} = \begin{bmatrix} 1 + \bar{Z}\bar{Y} & \bar{Z} \\ \bar{Y} & 1 \end{bmatrix}$$

### $\Pi$ - ŠEMA ČEVREROBLOU

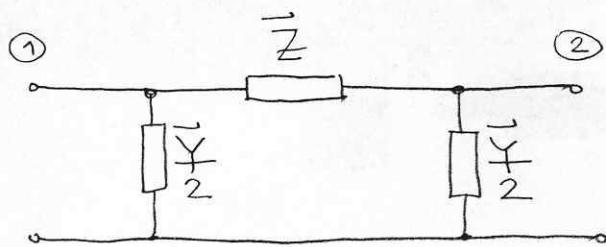


$$[L_\Pi] = [L_{Y_1}][L_Z][L_{Y_2}]$$

$$\begin{aligned} [L_\Pi] &= [L_{Y_1}][L_Z][L_{Y_2}] = \begin{bmatrix} 1 & 0 \\ \bar{Y}_1 & 1 \end{bmatrix} \begin{bmatrix} 1 & \bar{Z} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \bar{Y}_2 & 1 \end{bmatrix} = \\ &= \begin{bmatrix} 1 & \bar{Z} \\ \bar{Y}_1 & 1 + \bar{Y}_1\bar{Z} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \bar{Y}_2 & 1 \end{bmatrix} = \begin{bmatrix} 1 + \bar{Z}\bar{Y}_2 & \bar{Z} \\ \bar{Y}_1 + \bar{Y}_2(1 + \bar{Y}_1\bar{Z}) & 1 + \bar{Y}_1\bar{Z} \end{bmatrix} \end{aligned}$$

$$[L_\Pi] = \begin{bmatrix} 1 + \bar{Z}\bar{Y}_2 & \bar{Z} \\ \bar{Y}_1 + \bar{Y}_2(1 + \bar{Y}_1\bar{Z}) & 1 + \bar{Y}_1\bar{Z} \end{bmatrix}$$

## Π - SHEMA ZA EL. EN. VOD



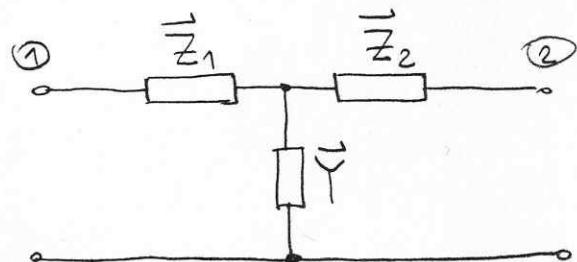
$$[L_{\Delta Y}] = [L_{Y/2}] [L_z] [L_{Y/2}]$$

$$[L_{\Delta Y}] = [L_{Y/2}] [L_z] [L_{Y/2}] = \begin{bmatrix} 1 & 0 \\ \frac{1}{Y/2} & 1 \end{bmatrix} \begin{bmatrix} 1 & \vec{z} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{1}{Y/2} & 1 \end{bmatrix} =$$

$$= \begin{bmatrix} 1 & \vec{z} \\ \frac{1}{Y/2} & 1 + \frac{\vec{z}}{2} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{1}{2} & 1 \end{bmatrix} = \begin{bmatrix} 1 + \vec{z} \frac{\vec{z}}{2} & \vec{z} \\ \frac{\vec{z}}{2} + \frac{\vec{z}}{2}(1 + \frac{\vec{z}}{2}) & 1 + \frac{\vec{z}}{2} \frac{\vec{z}}{2} \end{bmatrix}$$

$$[L_{\Delta Y}] = \begin{bmatrix} 1 + \vec{z} \frac{\vec{z}}{2} & \vec{z} \\ \frac{\vec{z}}{2} + \frac{\vec{z}}{2}(1 + \frac{\vec{z}}{2}) & 1 + \vec{z} \frac{\vec{z}}{2} \end{bmatrix}$$

## T - SHEMA ČLENEROPODÁ



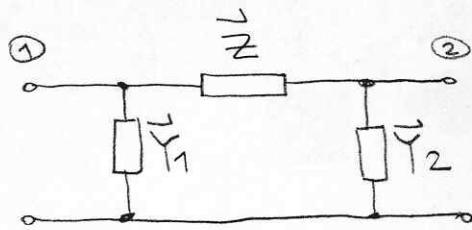
$$[L_T] = [L_{z_1}] [L_Y] [L_{z_2}]$$

$$[L_T] = [L_{z_1}] [L_Y] [L_{z_2}] = \begin{bmatrix} 1 & \vec{z}_1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \vec{Y} & 1 \end{bmatrix} \begin{bmatrix} 1 & \vec{z}_2 \\ 0 & 1 \end{bmatrix}$$

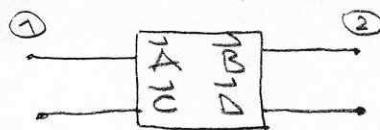
$$= \begin{bmatrix} 1 + \vec{z}_1 Y & \vec{z}_1 \\ \vec{Y} & 1 \end{bmatrix} \begin{bmatrix} 1 & \vec{z}_2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 + \vec{z}_1 Y & \vec{z}_2(1 + \vec{z}_1 Y) + \vec{z}_1 \\ \vec{Y} & \vec{Y} \vec{z}_2 + 1 \end{bmatrix}$$

$$[L_T] = \begin{bmatrix} 1 + \vec{z}_1 \vec{Y} & \vec{z}_2(1 + \vec{z}_1 \vec{Y}) + \vec{z}_1 \\ \vec{Y} & \vec{Y} \vec{z}_2 + 1 \end{bmatrix}$$

ODREĐIVANJE PARAMETARA T-SHEME ČEVRJOPA  
AKO SU POZNATE OPĆE KONSTANTE



Poznato:  $\vec{A}, \vec{B}, \vec{C}, \vec{D}$



$$[L_{\bar{T}}] = \begin{bmatrix} \vec{A} & \vec{B} \\ \vec{C} & \vec{D} \end{bmatrix} = \begin{bmatrix} 1 + \vec{Z} \vec{Y}_2 \\ \vec{Y}_1 + \vec{Y}_2 (1 + \vec{Z} \vec{Y}_1) \end{bmatrix} \begin{bmatrix} \vec{Z} \\ 1 + \vec{Z} \vec{Y}_1 \end{bmatrix}$$

$$\vec{A} = 1 + \vec{Z} \vec{Y}_2$$

$$\vec{Y}_2 = \frac{\vec{A} - 1}{\vec{Z}}$$

$$\vec{B} = \vec{Z}$$

$$\vec{Z} = B$$

$$\vec{C} = \vec{Y}_1 + \vec{Y}_2 (1 + \vec{Z} \vec{Y}_1)$$

$$\vec{D} = 1 + \vec{Z} \vec{Y}_1$$

$$\vec{Y}_1 = \frac{\vec{D} - 1}{\vec{Z}}$$

$$\vec{A}, \vec{B}, \vec{C}, \vec{D}$$

$$\vec{Z} = B \quad \vec{Y}_1 = \frac{\vec{D} - 1}{B} \quad \vec{Y}_2 = \frac{\vec{A} - 1}{B}$$

$$C = \vec{Y}_1 + \vec{Y}_2 (1 + \vec{Z} \vec{Y}_1) = \frac{\vec{D} - 1}{B} + \frac{\vec{A} - 1}{B} \left( 1 + B \frac{\vec{D} - 1}{B} \right)$$

$$= \frac{\vec{D} - 1}{B} + \frac{\vec{A} - 1}{B} \quad D = \frac{\vec{D} - 1}{B} + \frac{AD - D}{B} = \frac{\vec{D} - 1 + AD - D}{B} = \frac{AD - 1}{B}$$

$$C = \frac{AD - 1}{B}$$

$$BC = AD - 1$$

$$AD - BC = 1$$

# OPĆE KONSTANTE DUGOG EL. EN. VODA



$$\vec{V}_1 = \vec{A} \vec{V}_2 + \vec{B} \vec{I}_2$$

$$\vec{I}_1 = \vec{C} \vec{V}_2 + \vec{D} \vec{I}_2$$

PREJENOSNE JEDNADŽBE ČESTVEROPOLNA

PREJENOSNE JEDNADŽBE EL. EN. VODA (III OBLIK)

$$\vec{V}_1 = \vec{V}_2 \operatorname{ch} \Theta + \vec{Z} \vec{I}_2 \frac{\operatorname{sh} \Theta}{\Theta}$$

$$\Theta = \vec{Y} \cdot l = \sqrt{\vec{Z} \cdot \vec{Y}} \cdot l$$

$$\vec{I}_1 = \vec{V}_2 \vec{Y} \frac{\operatorname{sh} \Theta}{\Theta} + \vec{I}_2 \operatorname{ch} \Theta$$

$$\Theta = \sqrt{\vec{Z} \cdot \vec{Y}}$$

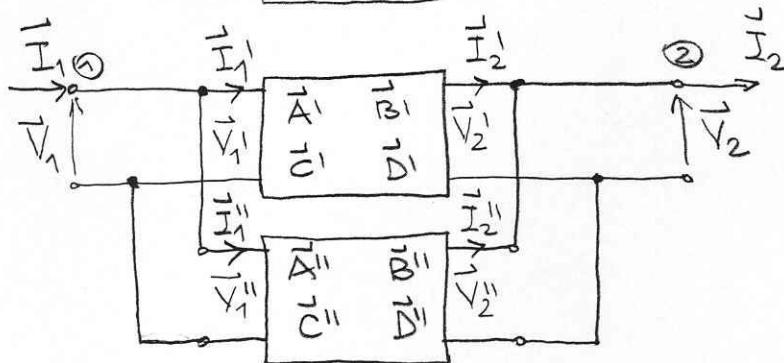
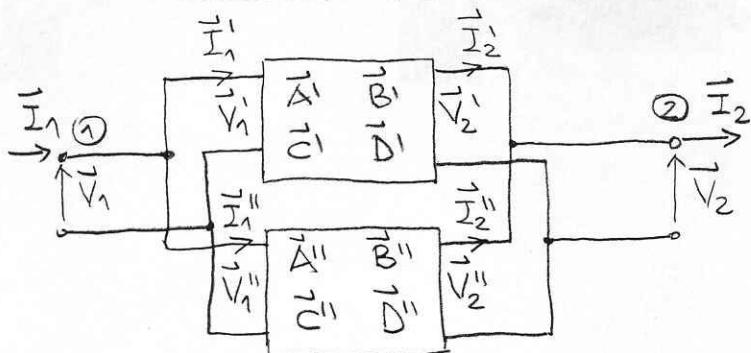
$$\vec{A} = \operatorname{ch} \Theta \quad \vec{B} = \vec{Z} \frac{\operatorname{sh} \Theta}{\Theta} = \vec{Z} \frac{\operatorname{sh} \sqrt{\vec{Z} \cdot \vec{Y}}}{\sqrt{\vec{Z} \cdot \vec{Y}}} = \sqrt{\frac{\vec{Z}}{\vec{Y}}} \operatorname{sh} \sqrt{\vec{Z} \cdot \vec{Y}}$$

$$\vec{C} = \vec{Y} \frac{\operatorname{sh} \Theta}{\Theta} = \vec{Y} \frac{\operatorname{sh} \sqrt{\vec{Z} \cdot \vec{Y}}}{\sqrt{\vec{Z} \cdot \vec{Y}}} = \sqrt{\frac{\vec{Y}}{\vec{Z}}} \operatorname{sh} \sqrt{\vec{Z} \cdot \vec{Y}} \quad \vec{D} = \operatorname{ch} \Theta$$

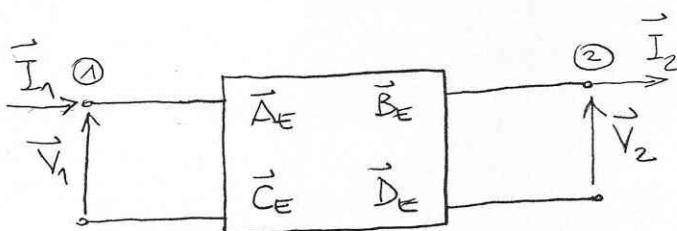
$$[L_{DY}] = \begin{bmatrix} \operatorname{ch} \Theta & \vec{Z} \frac{\operatorname{sh} \Theta}{\Theta} \\ \vec{Y} \frac{\operatorname{sh} \Theta}{\Theta} & \operatorname{ch} \Theta \end{bmatrix} = \begin{bmatrix} \operatorname{ch} \sqrt{\vec{Z} \cdot \vec{Y}} & \sqrt{\frac{\vec{Z}}{\vec{Y}}} \operatorname{sh} \sqrt{\vec{Z} \cdot \vec{Y}} \\ \sqrt{\frac{\vec{Y}}{\vec{Z}}} \operatorname{sh} \sqrt{\vec{Z} \cdot \vec{Y}} & \operatorname{ch} \sqrt{\vec{Z} \cdot \vec{Y}} \end{bmatrix}$$

# PARALELNI SPoj PREJENOSNIH SUSTAVA

## PARALELNI SPoj ČETVEROPOLA

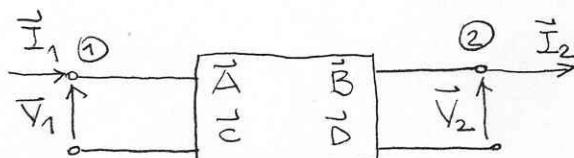


$$\begin{aligned}\vec{V}_1 &= \vec{V}_1' = \vec{V}_1'' \\ \vec{V}_2 &= \vec{V}_2' = \vec{V}_2'' \\ \vec{I}_1 &= \vec{I}_1' + \vec{I}_1'' \\ \vec{I}_2 &= \vec{I}_2' + \vec{I}_2''\end{aligned}$$



$$\begin{aligned}\vec{V}_1 &= \vec{A}_E \vec{V}_2 + \vec{B}_E \vec{I}_2 \\ \vec{I}_1 &= \vec{C}_E \vec{V}_2 + \vec{D}_E \vec{I}_2\end{aligned}$$

JEDAN ČETVEROPOL ORDENITO:



$$\begin{bmatrix} \vec{V}_1 \\ \vec{I}_1 \end{bmatrix} = \begin{bmatrix} \vec{A} & \vec{B} \\ \vec{C} & \vec{D} \end{bmatrix} \begin{bmatrix} \vec{V}_2 \\ \vec{I}_2 \end{bmatrix}$$

PRIJENOSNE JEDNADŽBE  
ČETVEROPOLA

$$\begin{aligned}\vec{V}_1 &= \vec{A} \vec{V}_2 + \vec{B} \vec{I}_2 \\ \vec{I}_1 &= \vec{C} \vec{V}_2 + \vec{D} \vec{I}_2\end{aligned}$$

$$\begin{bmatrix} \vec{I}_1 \\ \vec{I}_2 \end{bmatrix} = \underbrace{\begin{bmatrix} \vec{Y}_{11} & \vec{Y}_{12} \\ \vec{Y}_{21} & \vec{Y}_{22} \end{bmatrix}}_{\text{MATRICA ADMITANCIA ČOVORIŠTA}} \begin{bmatrix} \vec{V}_1 \\ \vec{V}_2 \end{bmatrix}$$

MATRICA ADMITANCIA  
ČOVORIŠTA

$$\begin{aligned}\vec{I}_1 &= \vec{Y}_{11} \vec{V}_1 + \vec{Y}_{12} \vec{V}_2 \\ \vec{I}_2 &= \vec{Y}_{21} \vec{V}_1 + \vec{Y}_{22} \vec{V}_2\end{aligned}$$

$$\vec{V}_1 = \vec{A} \vec{V}_2 + \vec{B} \vec{I}_2 \rightarrow \vec{I}_2 = \frac{1}{B} \vec{V}_1 - \frac{\vec{A}}{B} \vec{V}_2 \quad (1)$$

$$\begin{aligned} \vec{I}_1 &= \vec{C} \vec{V}_2 + \vec{D} \vec{I}_2 = \vec{C} \vec{V}_2 + \frac{\vec{D}}{B} \vec{V}_1 - \frac{\vec{A} \vec{D}}{B} \vec{V}_2 \\ &= \left( \vec{C} - \frac{\vec{A} \vec{D}}{B} \right) \vec{V}_2 + \frac{\vec{D}}{B} \vec{V}_1 \end{aligned}$$

$$\det \begin{vmatrix} \vec{A} & \vec{B} \\ \vec{C} & \vec{D} \end{vmatrix} = 1 \Rightarrow \vec{A} \vec{D} - \vec{B} \vec{C} = 1 \quad \frac{\vec{A} \vec{D}}{B} - \vec{C} = \frac{1}{B}$$

$$\vec{I}_1 = \frac{\vec{D}}{B} \vec{V}_1 - \frac{1}{B} \vec{V}_2 \quad (2.)$$

PARALELNI SPOJ DVA ČLENROVODA:

$$\vec{I}_1' = \frac{\vec{D}'}{\vec{B}'} \vec{V}_1 - \frac{1}{\vec{B}'} \vec{V}_2$$

$$\vec{I}_2' = \frac{1}{\vec{B}'} \vec{V}_1 - \frac{\vec{A}'}{\vec{B}'} \vec{V}_2$$

$$\vec{I}_1'' = \frac{\vec{D}''}{\vec{B}''} \vec{V}_1 - \frac{1}{\vec{B}''} \vec{V}_2$$

$$\vec{I}_2'' = \frac{1}{\vec{B}''} \vec{V}_1 - \frac{\vec{A}''}{\vec{B}''} \vec{V}_2$$

$$\vec{I}_1 = \vec{I}_1' + \vec{I}_1''$$

$$\vec{I}_2 = \vec{I}_2' + \vec{I}_2''$$

$$\vec{I}_1 = \left( \frac{\vec{D}'}{\vec{B}'} + \frac{\vec{D}''}{\vec{B}''} \right) \vec{V}_1 - \left( \frac{1}{\vec{B}'} + \frac{1}{\vec{B}''} \right) \vec{V}_2$$

$$\vec{I}_1 = (\vec{Y}_{11}' + \vec{Y}_{11}'') \vec{V}_1 - (\vec{Y}_{12}' + \vec{Y}_{12}'') \vec{V}_2$$

$$\vec{I}_2 = \left( \frac{1}{\vec{B}'} + \frac{1}{\vec{B}''} \right) \vec{V}_1 - \left( \frac{\vec{A}'}{\vec{B}'} + \frac{\vec{A}''}{\vec{B}''} \right) \vec{V}_2$$

$$\vec{I}_2 = (\vec{Y}_{21}' + \vec{Y}_{21}'') \vec{V}_1 - (\vec{Y}_{22}' + \vec{Y}_{22}'') \vec{V}_2$$

$$\vec{I}_1 = \vec{Y}_{11} \vec{V}_1 + \vec{Y}_{12} \vec{V}_2$$

$$\vec{I}_2 = \vec{Y}_{21} \vec{V}_1 + \vec{Y}_{22} \vec{V}_2$$

$$\vec{I}_2 = \vec{Y}_{21} \vec{V}_1 + \vec{Y}_{22} \vec{V}_2$$

$$\vec{V}_1 = \frac{1}{\vec{Y}_{21}} (\vec{I}_2 - \vec{Y}_{22} \vec{V}_2) = -\frac{\vec{Y}_{22}}{\vec{Y}_{21}} \vec{V}_2 + \frac{1}{\vec{Y}_{21}} \vec{I}_2$$

$$\vec{V}_1 = \vec{A}_E \vec{V}_2 + \vec{B}_E \vec{I}_2$$

$$\vec{A}_E = -\frac{\vec{Y}_{22}}{\vec{Y}_{21}} \quad \vec{B}_E = \frac{1}{\vec{Y}_{21}}$$

$$\vec{I}_1 = \vec{Y}_{11} \vec{V}_1 + \vec{Y}_{12} \vec{V}_2 = \vec{Y}_m \left( -\frac{\vec{Y}_{22}}{\vec{Y}_{21}} \vec{V}_2 + \frac{1}{\vec{Y}_{21}} \vec{I}_2 \right) + \vec{Y}_{12} \vec{V}_2$$

$$\vec{I}_1 = \left( \vec{Y}_{12} - \frac{\vec{Y}_m \vec{Y}_{22}}{\vec{Y}_{21}} \right) \vec{V}_2 + \frac{\vec{Y}_m}{\vec{Y}_{21}} \vec{I}_2$$

$$\vec{I}_1 = \vec{C}_E \vec{V}_2 + \vec{D}_E \vec{I}_2$$

$$\vec{C}_E = \vec{Y}_{12} - \frac{\vec{Y}_m \vec{Y}_{22}}{\vec{Y}_{21}} \quad \vec{D}_E = \frac{\vec{Y}_m}{\vec{Y}_{21}}$$

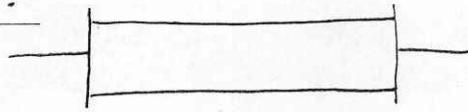
$$\vec{A}_E = -\frac{\vec{Y}_{22}}{\vec{Y}_{21}} = -\frac{-\frac{\vec{A}'}{\vec{B}'} - \frac{\vec{A}''}{\vec{B}''}}{\frac{1}{\vec{B}'} + \frac{1}{\vec{B}''}} = -\frac{\frac{\vec{A}' \vec{B}'' + \vec{A}'' \vec{B}'}{\vec{B}' \vec{B}''}}{\frac{\vec{B}' + \vec{B}''}{\vec{B}' \vec{B}''}} = \frac{\vec{A}' \vec{B}'' + \vec{A}'' \vec{B}'}{\vec{B}' + \vec{B}''}$$

$$\vec{B}_E = \frac{1}{\vec{Y}_{21}} = \frac{1}{\frac{1}{\vec{B}'} + \frac{1}{\vec{B}''}} = \frac{\vec{B}' \vec{B}''}{\vec{B}' + \vec{B}''}$$

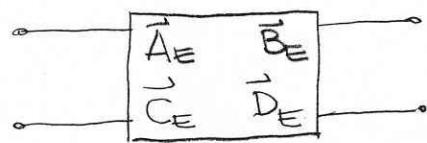
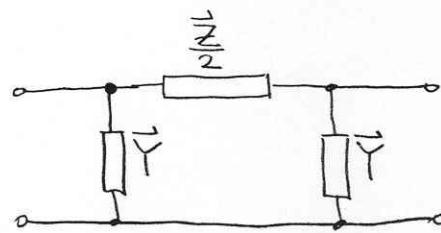
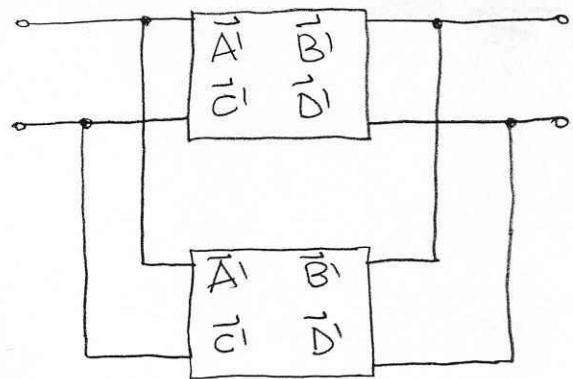
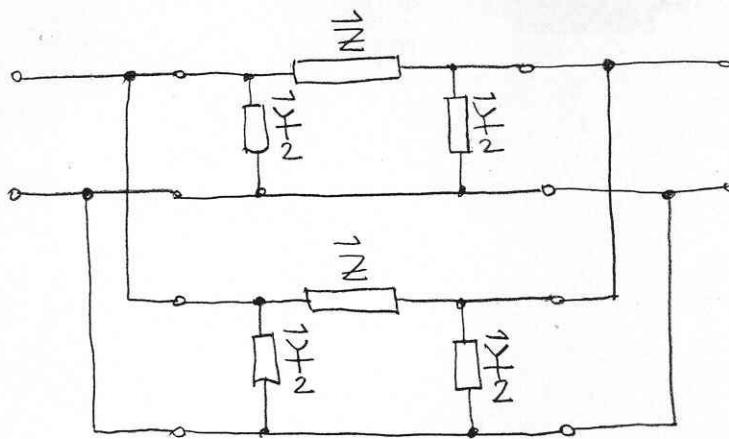
$$\vec{D}_E = \frac{\vec{Y}_m}{\vec{Y}_{21}} = \frac{\frac{\vec{D}'}{\vec{B}'} + \frac{\vec{D}''}{\vec{B}''}}{\frac{1}{\vec{B}'} + \frac{1}{\vec{B}''}} = \frac{\frac{\vec{D}' \vec{B}'' + \vec{D}'' \vec{B}'}{\vec{B}' \vec{B}''}}{\frac{\vec{B}' + \vec{B}''}{\vec{B}' \vec{B}''}} = \frac{\vec{D}' \vec{B}'' + \vec{D}'' \vec{B}'}{\vec{B}' + \vec{B}''}$$

$$\begin{aligned} \vec{C}_E &= \vec{Y}_{12} - \frac{\vec{Y}_m \vec{Y}_{22}}{\vec{Y}_{21}} = \frac{\vec{Y}_{12} \vec{Y}_{21} - \vec{Y}_m \vec{Y}_{22}}{\vec{Y}_{21}} = \frac{\vec{Y}_{12} \vec{Y}_{21}}{\vec{Y}_{21}} - \frac{\vec{Y}_m \vec{Y}_{22}}{\vec{Y}_{21}} = \frac{\vec{Y}_{12}}{\vec{B}_E} + \vec{A}_E \vec{D}_E \vec{Y}_{21} \\ &= \frac{-1}{\vec{B}_E} + \frac{\vec{A}_E \vec{D}_E}{\vec{B}_E} = \frac{\vec{A}_E \vec{D}_E - 1}{\vec{B}_E} \end{aligned}$$

PRIMER:



DVA PARALELNA  
JEDNAKA EL. EN. VODA



$$\vec{A}_E = \frac{\vec{A}' \vec{B}'' + \vec{A}'' \vec{B}'}{\vec{B}' + \vec{B}''} = \frac{2 \vec{A}' \vec{B}'}{2 \vec{B}'} = \vec{A}'$$

$$\vec{B}_E = \frac{\vec{B}' \vec{B}''}{\vec{B}' + \vec{B}''} = \frac{(\vec{B}')^2}{2 \vec{B}'} = \frac{\vec{B}'}{2}$$

$$\vec{D}_E = \frac{\vec{D}' \vec{B}'' + \vec{D}'' \vec{B}'}{\vec{B}' + \vec{B}''} = \frac{2 \vec{D}' \vec{B}'}{2 \vec{B}'} = \vec{D}'$$

$$\vec{C}_E = \frac{\vec{A}_E \vec{D}_E - 1}{\vec{B}_E} = \frac{\vec{A}' \vec{D}' - 1}{\vec{B}' / 2}$$

Π-SHEMA ČETVEROPOLNA EL. EN. VODA

$$\vec{A}' = 1 + \frac{1}{Z} \frac{\vec{Y}}{2}$$

$$\vec{B}' = \frac{1}{Z}$$

$$\vec{C}' = \frac{\vec{Y}}{2} + \frac{\vec{Y}}{2} (1 + \frac{\vec{Z} \vec{Y}}{2})$$

$$\vec{D}' = 1 + \frac{\vec{Z} \vec{Y}}{2}$$

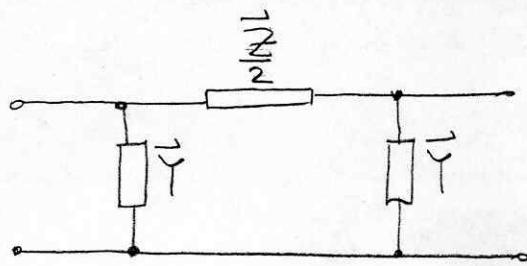
$$\vec{A}_E = \vec{A}' = 1 + \frac{1}{Z} \frac{\vec{Y}}{2}$$

$$\vec{B}_E = \frac{\vec{B}'}{2} = \frac{\vec{Z}}{2}$$

$$\vec{D}_E = \vec{D}' = 1 + \frac{1}{Z} \frac{\vec{Y}}{2}$$

$$\vec{C}_E = \frac{\vec{A}_E \vec{D}_E - 1}{\vec{B}_E} = \frac{(1 + \frac{1}{Z} \frac{\vec{Y}}{2})(1 + \frac{1}{Z} \frac{\vec{Y}}{2}) - 1}{\vec{Z}/2} =$$

$$\vec{C}_E = \frac{1 + \frac{1}{Z} \frac{\vec{Y}}{2} + \frac{1}{Z} \frac{\vec{Y}}{2} + \frac{\vec{Z} \vec{Y}}{4} - 1}{\vec{Z}/2} = \frac{\frac{1}{2} \vec{Z} (\vec{Y} + \vec{Y} + \frac{1}{2} \vec{Z} \vec{Y}^2)}{\frac{1}{2} \vec{Z}} = \vec{Y} + \vec{Y} (1 + \frac{1}{2} \vec{Z} \vec{Y})$$



$$[L_E] = \begin{bmatrix} 1 + \frac{\bar{Z}}{2} \frac{\bar{Y}}{2} & \frac{\bar{Y}}{2} \\ \bar{Y} + \bar{Y} \left( 1 + \frac{\bar{Z}}{2} \frac{\bar{Y}}{2} \right) & 1 + \frac{\bar{Z}}{2} \frac{\bar{Y}}{2} \end{bmatrix}$$

### 6.3 TOČAN $\Pi$ -MODEL VODA

Ako su zadani napon  $\vec{V}_2$  i struja  $\vec{I}_2$  na kraju voda, odredimo napon  $\vec{V}_1$ , struju  $\vec{I}_1$  na početku voda;

- PRIMENJENOJE JEDNODŽBE  $\Pi$ . OBILCA

$$\vec{V} = \vec{V}_2 \operatorname{ch} \vec{\gamma} x + \vec{Z}_c \vec{I}_2 \operatorname{sh} \vec{\gamma} x$$

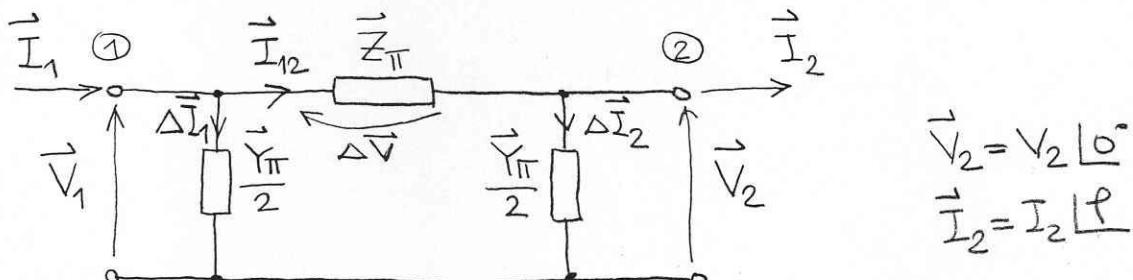
$$\vec{I} = \vec{I}_2 \operatorname{ch} \vec{\gamma} x + \frac{\vec{V}_2}{\vec{Z}_c} \operatorname{sh} \vec{\gamma} x$$

$$z \rightarrow x=l$$

$$\vec{V}_1 = \vec{V}_2 \operatorname{ch} \vec{\gamma} l + \vec{Z}_c \vec{I}_2 \operatorname{sh} \vec{\gamma} l \quad (1.)$$

$$\vec{I}_1 = \vec{I}_2 \operatorname{ch} \vec{\gamma} l + \frac{\vec{V}_2}{\vec{Z}_c} \operatorname{sh} \vec{\gamma} l \quad (2.)$$

- TOČAN  $\Pi$ -MODEL VODA



$\vec{Z}_\pi$  - IMPEDANCIJA UZDUŠNE GRANE

$\vec{Y}_\pi$  - ADMITANCIJA POPENČNE GRANE

$$\Delta \vec{I}_2 = \vec{V}_2 \frac{\vec{Y}_\pi}{2}$$

$$\vec{I}_{12} = \vec{I}_2 + \Delta \vec{I}_2 = \vec{I}_2 + \vec{V}_2 \frac{\vec{Y}_\pi}{2}$$

$$\Delta \vec{V} = \vec{I}_{12} \cdot \vec{Z}_\pi = \left( \vec{I}_2 + \vec{V}_2 \frac{\vec{Y}_\pi}{2} \right) \vec{Z}_\pi$$

$$\vec{V}_1 = \vec{V}_2 + \Delta \vec{V} = \vec{V}_2 + \vec{I}_{12} \vec{Z}_\pi = \vec{V}_2 + \left( \vec{I}_2 + \vec{V}_2 \frac{\vec{Y}_\pi}{2} \right) \vec{Z}_\pi$$

$$\vec{V}_1 = \vec{V}_2 + \vec{I}_2 \vec{Z}_\pi + \vec{V}_2 \frac{\vec{Y}_\pi}{2} \vec{Z}_\pi$$

$$\vec{V}_1 = \vec{V}_2 \left( 1 + \frac{\vec{Y}_\pi}{2} \vec{Z}_\pi \right) + \vec{I}_2 \vec{Z}_\pi \quad (3.)$$

$$\vec{I}_1 = \vec{I}_{12} + \Delta \vec{I}_1 = \vec{I}_2 + \vec{V}_2 \frac{\vec{Y}_\pi}{2} + \vec{V}_1 \frac{\vec{Y}_\pi}{2} \quad (4.)$$

USPREDJOM JEDNODŽBI (1.) i (3.), TE IZJEDNAČAVANjem KOPICIJSKIH, DOBIVAMO:

$$\vec{Z}_\pi = \vec{Z}_c \operatorname{sh} \vec{\gamma} l$$

$$1 + \frac{\vec{Y}_\pi}{2} \vec{Z}_\pi = 1 + \frac{\vec{Y}_\pi}{2} \vec{Z}_c \operatorname{sh} \vec{\gamma} l = \operatorname{ch} \vec{\gamma} l$$

$$\frac{\vec{Y}_\pi}{2} \vec{Z}_c \operatorname{sh} \vec{\gamma} l = \operatorname{ch} \vec{\gamma} l - 1$$

$$\frac{\vec{Y}_\pi}{2} = \frac{1}{\vec{Z}_c} \frac{\operatorname{ch} \vec{\gamma} l - 1}{\operatorname{sh} \vec{\gamma} l}$$

VELIČINE ELEMENTA TOČNOG  $\pi$ -MODEL VODE

$$\vec{Z}_\pi = \vec{Z}_c \operatorname{sh} \vec{\gamma} l \quad \frac{\vec{Y}_\pi}{2} = \frac{1}{\vec{Z}_c} \frac{\operatorname{ch} \vec{\gamma} l - 1}{\operatorname{sh} \vec{\gamma} l}$$

UZEVŠI U OBZIR DA JE:  $\Theta = \sqrt{\vec{Z} \cdot \vec{Y}} = \vec{\gamma} l$   $\vec{\gamma} = \sqrt{\vec{Z}_1 \cdot \vec{Y}_1}$

$$\vec{Z}_c = \sqrt{\frac{\vec{Z}}{\vec{Y}}} = \sqrt{\frac{\vec{Z}}{\vec{Y}}} \sqrt{\frac{\vec{Y}}{\vec{Z}}} = \frac{\vec{Z}}{\Theta} = \frac{\vec{Z}/2}{\Theta/2} \quad \vec{Z} = \vec{Z}_1 \cdot l \quad \vec{Y} = \vec{Y}_1 \cdot l$$

$$\frac{1}{\vec{Z}_c} = \sqrt{\frac{\vec{Y}}{\vec{Z}}} = \sqrt{\frac{\vec{Y}}{\vec{Z}}} \sqrt{\frac{\vec{Z}}{\vec{Y}}} = \frac{\vec{Y}}{\Theta} = \frac{\vec{Y}/2}{\Theta/2}$$

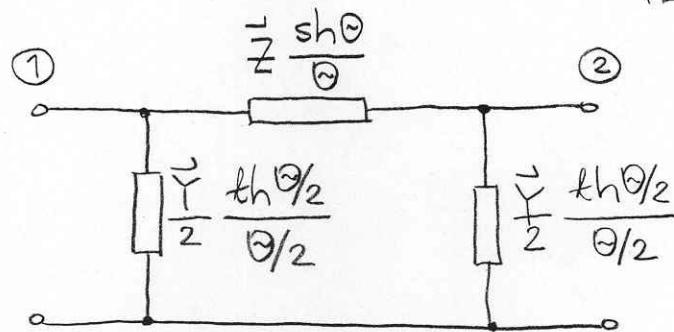
$$\frac{\operatorname{ch} \Theta - 1}{\operatorname{sh} \Theta} = \operatorname{th} \frac{\Theta}{2}$$

VELIČINE ELEMENTA TOČNOG  $\pi$ -MODEL VODE:

$$\vec{Z}_\pi = \vec{Z}_c \operatorname{sh} \vec{\gamma} l = \frac{\vec{Z}}{\Theta} \operatorname{sh} \Theta = \vec{Z} \frac{\operatorname{sh} \Theta}{\Theta}$$

$$\frac{\vec{Y}_\pi}{2} = \frac{1}{\vec{Z}_c} \frac{\operatorname{ch} \vec{\gamma} l - 1}{\operatorname{sh} \vec{\gamma} l} = \frac{\vec{Y}/2}{\Theta/2} \frac{\operatorname{ch} \Theta - 1}{\operatorname{sh} \Theta} = \frac{\vec{Y}}{2} \frac{\operatorname{th} \Theta/2}{\Theta/2}$$

TOČAN  $\pi$ -MODEL VODE (MODEL VODE S KONCENTRIRANIM PARAMETRIMA)



## 6.4 TOČAN T-MODEL VODA

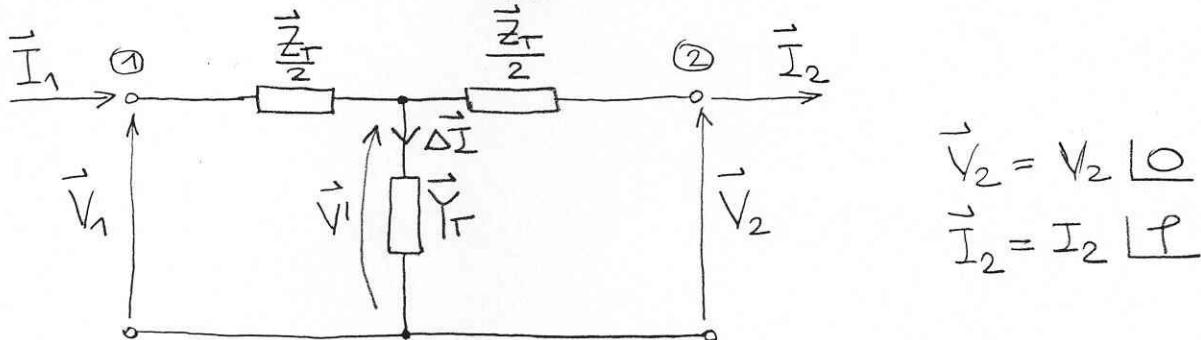
Ako su zadani napon  $\vec{V}_2$  i struja  $\vec{I}_2$  na kraju voda, odredimo napon  $\vec{V}_1$ , struju  $\vec{I}_1$  na početku voda:

- prijenosne jednadžbe II. oblika za  $x=0$

$$\vec{V}_1 = \vec{V}_2 \operatorname{ch} \gamma l + \frac{\vec{Z}_c}{\vec{Z}_T} \vec{I}_2 \operatorname{sh} \gamma l \quad (1.)$$

$$\vec{I}_1 = \vec{I}_2 \operatorname{ch} \gamma l + \vec{V}_2 \frac{1}{\frac{\vec{Z}_c}{\vec{Z}_T}} \operatorname{sh} \gamma l \quad (2.)$$

- Točan T-model voda



$\vec{Z}_T$  - impedancija uzdužne grane

$\vec{Y}_T$  - admittancija poprečne grane

$$\vec{V}' = \vec{V}_2 + \vec{I}_2 \frac{\vec{Z}_T}{2}$$

$$\vec{\Delta I} = \vec{V}' \vec{Y}_T = (\vec{V}_2 + \vec{I}_2 \frac{\vec{Z}_T}{2}) \vec{Y}_T$$

$$\vec{I}_1 = \vec{I}_2 + \vec{\Delta I} = \vec{I}_2 + (\vec{V}_2 + \vec{I}_2 \frac{\vec{Z}_T}{2}) \vec{Y}_T$$

$$\vec{I}_1 = \vec{I}_2 + \vec{V}_2 \vec{Y}_T + \vec{I}_2 \frac{\vec{Z}_T}{2} \vec{Y}_T$$

$$\vec{I}_1 = \vec{I}_2 \left( 1 + \frac{\vec{Z}_T}{2} \vec{Y}_T \right) + \vec{V}_2 \vec{Y}_T \quad (5.)$$

$$\vec{V}_1 = \vec{V}' + \vec{I}_1 \frac{\vec{Z}_T}{2} = \vec{V}_2 + \vec{I}_2 \frac{\vec{Z}_T}{2} + \vec{I}_1 \frac{\vec{Z}_T}{2} \quad (6.)$$

Usporedbom jednadžbi (2.) i (5.), te izvođenjem koeficijenata dobivamo:

$$\vec{Y}_T = \frac{1}{\frac{\vec{Z}_c}{\vec{Z}_T}} \operatorname{sh} \gamma l$$

$$1 + \frac{\vec{Z}_T}{2} \vec{Y}_T = 1 + \frac{\vec{Z}_T}{2} \frac{1}{\frac{\vec{Z}_c}{\vec{Z}_T}} \operatorname{sh} \gamma l = \operatorname{ch} \gamma l$$

$$\frac{\vec{Z}_T}{2} \frac{1}{\vec{Z}_c} \operatorname{sh} \vec{\gamma} l = \operatorname{ch} \vec{\gamma} l - 1$$

$$\frac{\vec{Z}_T}{2} = \vec{Z}_c \frac{\operatorname{ch} \vec{\gamma} l - 1}{\operatorname{sh} \vec{\gamma} l}$$

VEĆIĆE ELEMENTI TOČNOG T-MODELA VODA:

$$\vec{Y}_T = \frac{1}{\vec{Z}_c} \operatorname{sh} \vec{\gamma} l$$

$$\frac{\vec{Z}_T}{2} = \vec{Z}_c \frac{\operatorname{ch} \vec{\gamma} l - 1}{\operatorname{sh} \vec{\gamma} l}$$

UZEVŠI U OBZIR DA JE:

$$\Theta = \sqrt{\vec{Z} \cdot \vec{Y}} = \vec{\gamma} l$$

$$\vec{\gamma} = \sqrt{\vec{Z}_1 \vec{Y}_1}$$

$$\vec{Z}_c = \frac{\vec{Z}}{\Theta} = \frac{\vec{Z}/2}{\Theta/2}$$

$$\frac{1}{\vec{Z}_c} = \frac{\vec{Y}}{\Theta} = \frac{\vec{Y}/2}{\Theta/2}$$

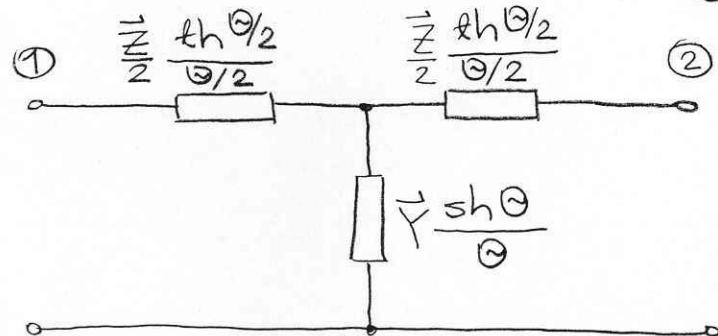
$$\frac{\operatorname{ch} \Theta - 1}{\operatorname{sh} \Theta} = \operatorname{th} \Theta/2$$

VEĆIĆNE ELEMENTI TOČNOG T-MODELA VODA:

$$\vec{Y}_T = \frac{1}{\vec{Z}_c} \operatorname{sh} \vec{\gamma} l = \vec{Y} \frac{\operatorname{sh} \Theta}{\Theta}$$

$$\frac{\vec{Z}_T}{2} = \vec{Z}_c \frac{\operatorname{ch} \vec{\gamma} l - 1}{\operatorname{sh} \vec{\gamma} l} = \frac{\vec{Z}/2}{\Theta/2} \frac{\operatorname{ch} \Theta - 1}{\operatorname{sh} \Theta} = \frac{\vec{Z}}{2} \frac{\operatorname{th} \Theta/2}{\Theta/2}$$

TOČAN T-MODEL VODA (MODEL VODA S KONCENTRIRANIM PARAMETRIMA)



$$\frac{sh\Theta}{\Theta} = 1 + \frac{\Theta^2}{3!} + \frac{\Theta^4}{5!} + \frac{\Theta^6}{7!} + \dots$$

$$\frac{th\frac{\Theta}{2}}{\Theta} = 1 - \frac{\Theta^2}{12} + \frac{\Theta^4}{120} - \frac{\Theta^6}{1186} + \frac{\Theta^8}{11700} -$$

$$ch\Theta = 1 + \frac{\Theta^2}{2!} + \frac{\Theta^4}{4!} + \dots$$

6.5

## PRIBLIŽAN T- MODEL VODA

## PRIBLIŽAN T- MODEL VODA

ZA KRATKE VODOVE  $l < 200 \text{ km}$ :

$$\operatorname{sh} \Theta \approx \Theta$$

KOREKCIJSKI FAKTORI

$$\operatorname{ch} \Theta \approx 1$$

$$\frac{\operatorname{sh} \Theta}{\Theta} \approx 1$$

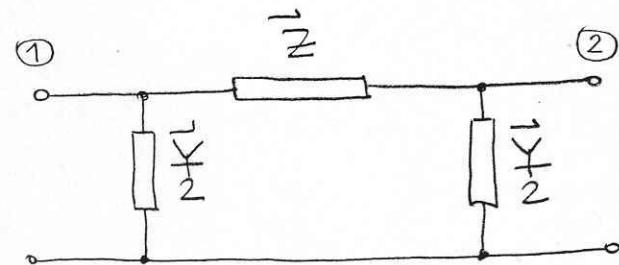
$$\frac{\operatorname{th} \Theta/2}{\Theta/2} \approx 1$$

$$\operatorname{th} \Theta \approx \Theta$$

ZA EE VODOVE  $l < 200 \text{ km}$ 

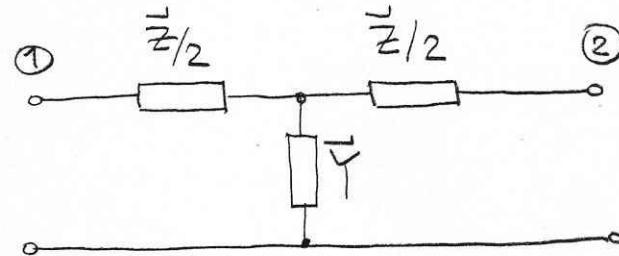
VJEĆNE ELEMENTI PRIBLIŽNOG T- MODELA VODA

$$\vec{Z}_T = \vec{Z} = \vec{Z}_1 \cdot l$$



VJEĆNE ELEMENTI PRIBLIŽNOG T- MODELA VODA

$$\vec{Y}_T = \vec{Y} = \vec{Y}_1 \cdot l$$



TOČNOST PRIBLIŽNIH MODELA

ZA VODOVE DUŽINE  $l < 200 \text{ km}$  GREŠKA  $\Delta < 0,5\%$ .

$$\frac{\operatorname{sh} \Theta}{\Theta} \approx 10^\circ$$

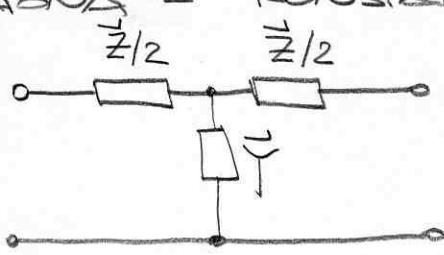
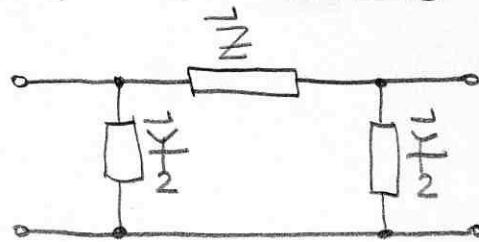
$$\frac{\operatorname{th} \Theta/2}{\Theta/2} \approx 10^\circ$$

ZA EE VODOVE  
 $l < 200 \text{ km}$ Ako su ee vodovi  $l > 200 \text{ km}$ , tada učest u dešir

- korekcijske faktore s rezultat vjećnosti
- ee vod raspisati na lanci članova sa svakim razminkom  $l' < 200 \text{ km}$

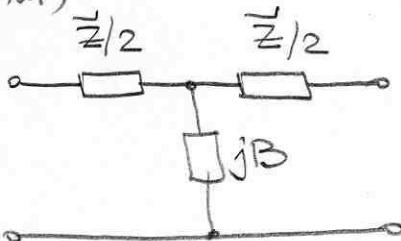
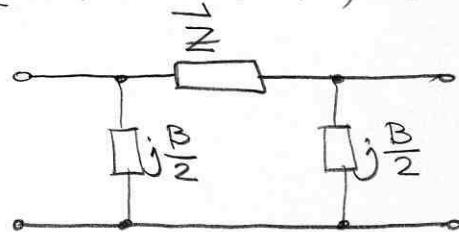
DOLJNJA ZAŠTEMARENJA U NADIMESNIM  
MODELIMA TE VOLVO

- VOLVO VESO VISOKOG NAPONA - KONSTANTE  $R, L, C, G$



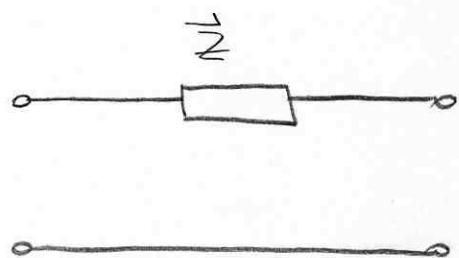
$$\begin{aligned}\vec{Z} &= R + jX \\ \vec{Y} &= G + jB\end{aligned}$$

- VOLVO VIŠOKOG NAPONA - KONSTANTE  $R, L, C$   
( $U_m < 200 \text{ km}, l < 200 \text{ km}$ )

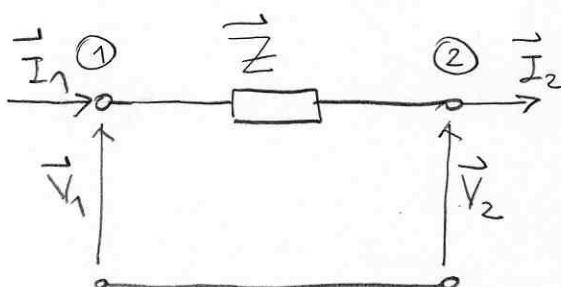


$$\begin{aligned}\vec{Z} &= R + jX \\ \vec{Y} &= jB \\ G &\approx 0\end{aligned}$$

- VOLVO SREDMEG I NIŠKOG NAPONA - KONSTANTE  $R, L$



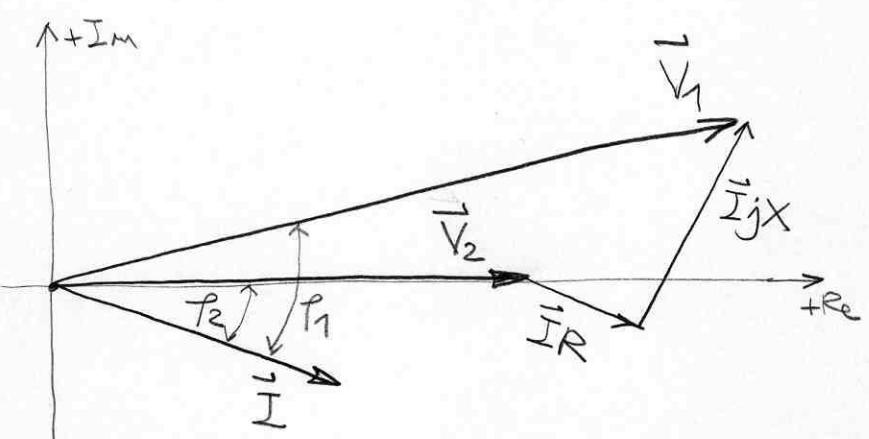
$$\begin{aligned}\vec{Z} &= R + jX \\ G &\approx 0 \quad C \approx 0\end{aligned}$$



$$\vec{I}_1 = \vec{I}_2 = \vec{I}$$

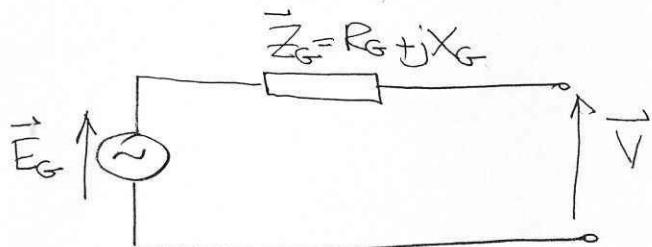
$$\vec{V}_1 = \vec{V}_2 + \vec{I} \vec{Z}$$

$$\vec{Z} = R + jX$$



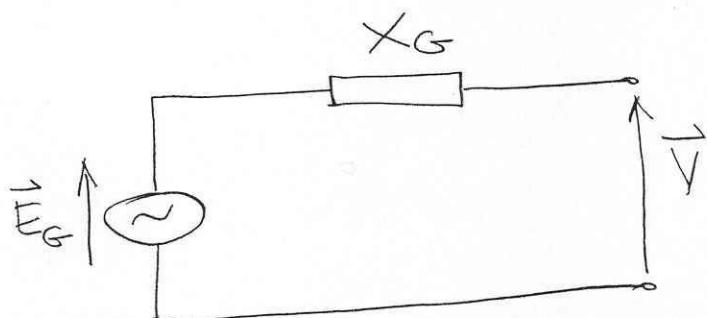
## 6.6 NADOMJESNI MODELI TRIFAZNIH SINKRONIH GENERATORA

- MATEMATIČKI MODELIRANJE U STACIONARNOM RODONU I PRIJEVZNOJ STANJU -  
SUSTAV JEDINODŽBI (PARKOVE KOMPONENTE)
  - 6 NAPONSKIH JEDINODŽBI
  - 6 JEONODŽBI ZA MAGNETSKE TAKOVE
  - 1 DINAMIČKA JEONODŽBA ROTORA
- NADOMJESNI MODEL SINKRONOG GENERATORA



$$R_G \ll X_G \quad (3-10\% X_G)$$

$R_G$  se uzima u obzir samo kad počinjaju udarnih struja KS.



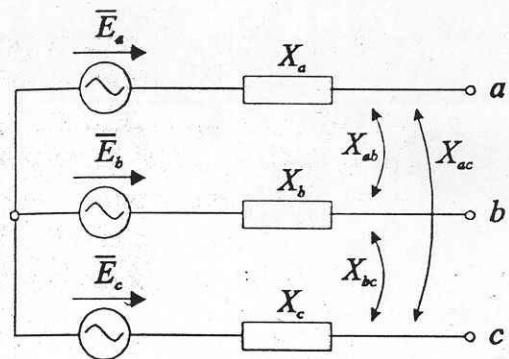
$X_G$  - REAKTANSIA GENERATORA

$E_g$  - ELEKTROMOTORNIA SILA GENERATORA

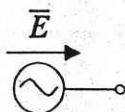
$X_G$  }  $E_g$  }   
  $\left. \begin{array}{l} \text{POZIČIĆTE VRSTO} \\ \text{VRSTO} \end{array} \right\}$  VRSTOZA  
 - POZIČIĆTE VRSTO PRAVILNE POKOVE  
 - POZIČIĆTE VRSTO ANALIZE

Za svaku vrstu analize potrebno je odrediti  
reaktansiju generatora, te onda iz vektorskog  
diagrama napona odrediti elekromotornu silu  
generatora  $\vec{E}_g$ .

NAJDOMIŠNE SHEME  
SINKRONOG GENERATORA

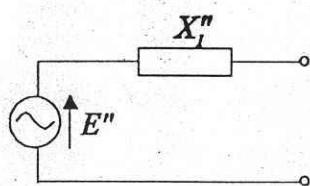


a) trofazna shema

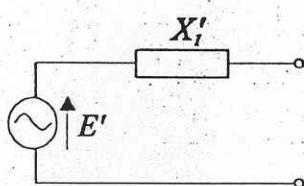


b) jednopolna shema

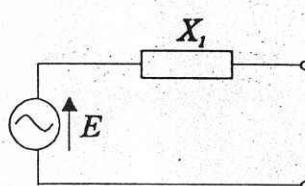
u trenutku  
nastanka KS



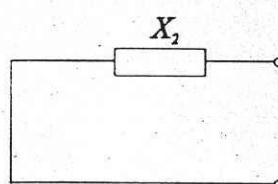
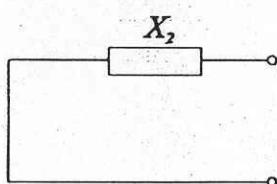
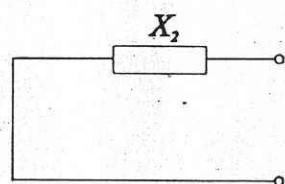
nekoliko perioda nakon  
nastanka KS



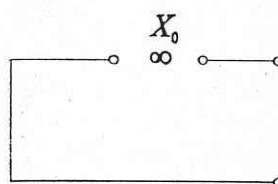
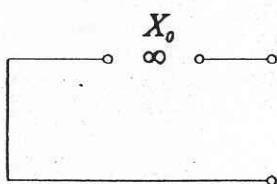
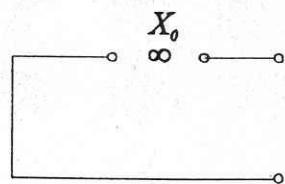
nekoliko sekundi nakon  
nastanka KS



direktni  
sustav



inverzni  
sustav



multi  
sustav

c) jednofazne sheme

ELEKTROMOTORNA  
SILA

REAKTANCIJA

POGONSKI SLUČAJ

DIREKNI SUSTAV

$$\vec{E}''$$

$$\vec{E}'$$

$$\vec{E}$$

$$X_d'', X_2''$$

$$X_d', X_2' = X_2$$

$$X_d, X_2$$

$I_K''$  početak KS

$I_K'$  dinamička stabilitet  
isklop

$I_K$  trojno strujno KS

INVERZNI  
SUSTAV

$$\vec{E}_2 = 0$$

$$X_2 = \frac{X_d'' + X_2''}{2}$$

NESIMETRISNO  
OPEREĆENJE

MULTI SUSTAV

$$\vec{E}_0 = 0$$

$$X_0 = \frac{1}{3} \dots \frac{1}{6} X_d''$$

## • TRI KARAKTERISTIČNA SINKA PREDSTAVLJENE

POLJUE:

- POČETNI (SUBTRANZIDENTNI) TRENUTAK

$X_d^0, X_2^0$  POČETNA (SUBTRANZIDENTNA) REAKTANCIJA  
 $\bar{E}^0$  ELEKTROMOTORNA SILA IZ POČETNE REAKTANCIJE  
 (SUBTRANZIDENTNA EMS)

- PREDUSTOJNO (TRANZIDENTNO) RAZDRELJE

$X_d^1, X_2^1$  PREDUSTOJNA (TRANZIDENTNA) REAKTANCIJA  
 $\bar{E}^1$  ELEKTROMOTORNA SILA IZ PREDUSTOJNE REAKTANCIJE  
 (TRANZIDENTNA EMS)

- TRDNO RAZDRELJE

$X_d, X_2$  SINKRONE REAKTANCIJA

$\bar{E}$  ELEKTROMOTORNA SILA IZ SINKRONE REAKTANCIJE  
 (SINKRONA EMS)

- BROJČANE VRIJEDNOSTI REAKTANCIJA

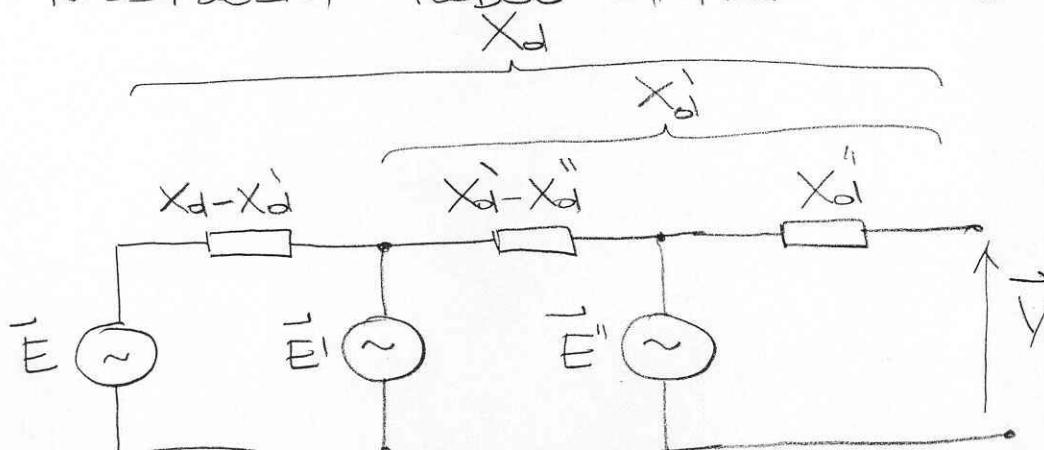
ABSOLUTNE  $X (\Omega)$

$$X = \frac{X\%}{100} \frac{U_m^2}{S_m}$$

RELATIVNE  $x = X \frac{S_m}{U_m^2}$

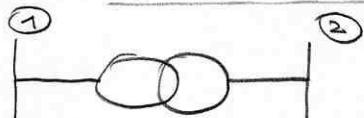
$$X_d > X_d^1 > X_d^0$$

- NEODMILJENI MODEL SINKRONOG GENERATORA



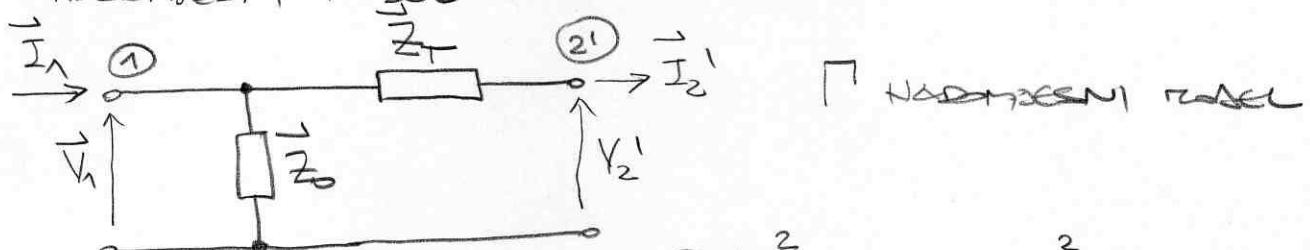
## 6.7 NADOMJESNI MODELI ENERGETSKIH TRANSFORMATORA

### 1. DVONAPLATNI TRASZNI ENERGETSKI TRANSFORMATORI



$$\begin{array}{lll} U_{m1} (\text{kV}) & U_{m2} (\text{kV}) & S_m (\text{MVA}) \\ I_{m1} (\text{A}) & I_{m2} (\text{A}) & t_m = \frac{U_{m1}}{U_{m2}} \\ M_K, P_{um} (\text{kW}) & \text{no.} & P_{em} (\text{kW}) \end{array}$$

NADOMJESNI MODEL DIREKTNOG SUSTAVA:



$$\vec{Z}_T = R_T + j X_T$$

$$R_T = \frac{P_{um} U_{m1}^2}{S_m^2}$$

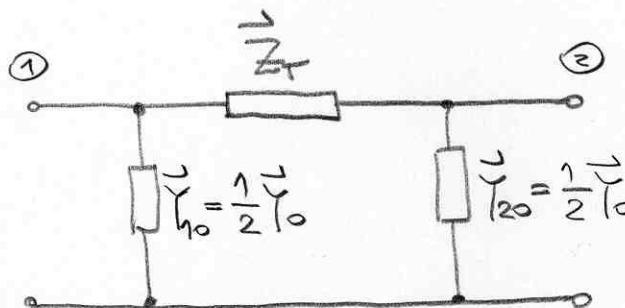
$$X_T = \frac{U_{m1}^2}{S_m} \sqrt{M_K - \left(\frac{P_{um}}{S_m}\right)^2}$$

$$\vec{Z}_0 = R_0 + j X_0$$

$$\vec{Y}_0 = \frac{1}{\vec{Z}_0} = G_0 - j B_0$$

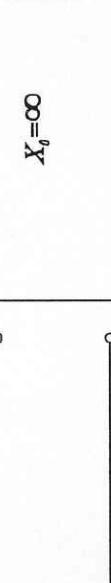
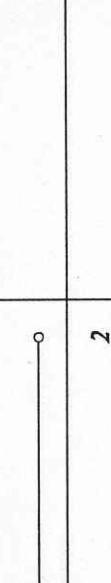
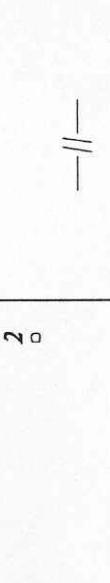
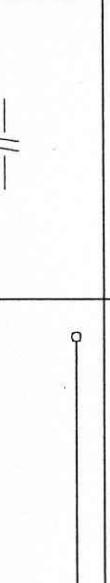
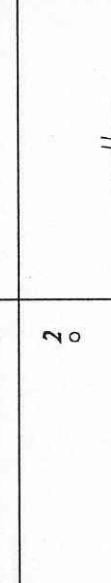
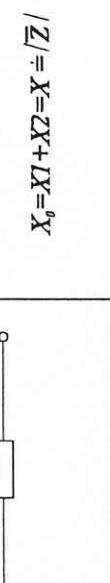
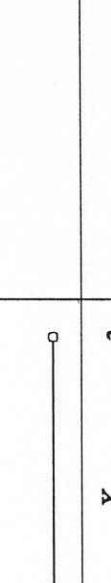
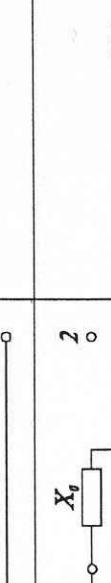
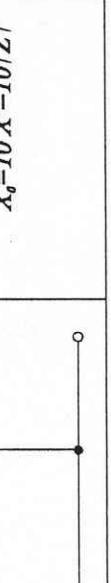
$$G_0 = \frac{P_{Fe}}{U_{m1}^2}$$

$$B_0 = \frac{S_m}{U_{m1}^2} \sqrt{i_0^2 - \left(\frac{P_{Fe}}{S_m}\right)^2}$$



II NADOMJESNI MODEL

NADOMJESNI MODEL NORMALOG SUSTAVA

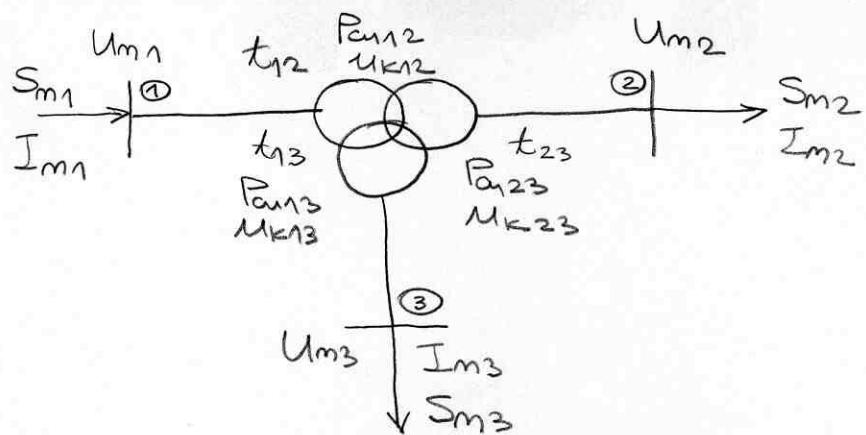
<i>Spoj</i>	<i>Kompletna nadomjesna shema</i>	<i>Nulte impedancije</i>	<i>Shema transformatora u mreži (sa zanemarenjima)</i>	<i>Nulta reaktancija</i>
<i>a</i>		$\bar{Z}_a = \bar{Z}_1$ $\bar{Z}'_a = \bar{Z}'_2$ $\bar{Z}_w \text{ VELIKO}$		$X_0 = \infty$
<i>b</i>		$\bar{Z}_a = \bar{Z}_1$ $\bar{Z}'_a = \bar{Z}'_2$ $\bar{Z}_w \text{ VELIKO}$		$X_0 = \infty$
<i>c</i>		$\bar{Z}_a = \bar{Z}_1$ $\bar{Z}'_a = \bar{Z}'_2$ $\bar{Z}_w \text{ VELIKO}$		$X_0 = \infty$
<i>d</i>		$\bar{Z}_a = \bar{Z}_1$ $\bar{Z}'_a = \bar{Z}'_2$ $\bar{Z}_w \text{ VELIKO}$		$X_0 = X_1 + X_2 = X / \bar{Z} /$
<i>e</i>		$\bar{Z}_a = \bar{Z}_1$ $\bar{Z}'_a = \bar{Z}'_2$ $\bar{Z}_w = 8 \dots 15 \bar{Z}_1$		$X_0 = 10 X = 10 / \bar{Z} /$

Nadomjesne sheme nultog sustava dvonamotnog transformatora

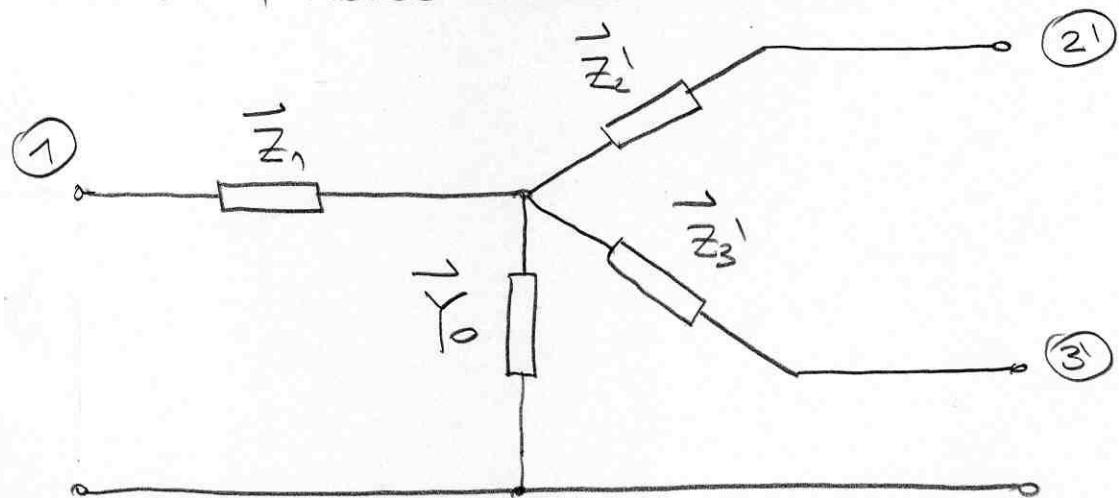
Spoj	Kompletna nadomjesna shema	Nulte impedancije	Shema transformatora u mreži (sa zamarenjima)	Nulta reaktancija
e		$\bar{Z}_{01} = \bar{Z}_1$ $\bar{Z}'_{02} = \bar{Z}_2$ $\bar{Z}'_{03} = \bar{Z}_3$ $\bar{Z}_{\infty} = \text{VELIKO}$		$X_0 = X_j \doteq / \bar{Z}_j /$ $X'_{02} = X'_2 \doteq / \bar{Z}'_2 /$ $X'_{03} = X'_3 \doteq / \bar{Z}'_3 /$
f		$\bar{Z}_{01} = \bar{Z}_1$ $\bar{Z}'_{02} = \bar{Z}_2$ $\bar{Z}'_{03} = \bar{Z}_3$ $\bar{Z}_{\infty} = \text{VELIKO}$		$X_0 = X_j + \frac{X_2' X_3'}{X_2' + X_3'} =$ $\doteq \bar{Z}_j + \frac{ \bar{Z}_2'  /  \bar{Z}_3' }{ \bar{Z}_2'  +  \bar{Z}_3'  /}$
g		$\bar{Z}_{01} = \bar{Z}_1$ $\bar{Z}'_{02} = \bar{Z}_2$ $\bar{Z}'_{03} = \bar{Z}_3$ $\bar{Z}_{\infty} = \text{VELIKO}$		$X_0 = X_j \doteq / \bar{Z}_j /$ $X'_{02} = X'_2 \doteq / \bar{Z}'_2 /$ $X'_{03} = X'_3 \doteq / \bar{Z}'_3 /$

Nadomjesne sheme nultog sustava tronamotnog transformatora

2. TRANSMISSIONI TRIFASICHE  
ENERGETICHE TRANSFORMATORI



NADODAJEMO RODEL DIREKTNOG CUSTENA:



- PARAMETRI UZDUŽNIH GRADNO JE ODREĐIVI  
IZ POKUSA KS IZMENJU PREDVODA NAMJEŠTJA

IZ ZANEMARENJE

$P_{11} = P_k$  U ODMOSH NO  $S_m$   
(PREDAZNOMJEŠTJE NO  $U_m$ )

$$R_{12} = \frac{P_{m12} U_{m1}^2}{S_{12}^2} \quad (\text{z})$$

$$\vec{Z}_{12} = R_{12} + j X_{12} \quad (\text{zv})$$

$$X_{12} = \frac{M_{k12} U_{m1}^2}{S_{12}} \quad (\text{zv})$$

$$R_{13} = \frac{P_{m13} U_{m1}^2}{S_{13}^2} \quad (\text{zv})$$

$$\vec{Z}_{13} = R_{13} + j X_{13} \quad (\text{zv})$$

$$X_{13} = \frac{M_{k13} U_{m1}^2}{S_{13}} \quad (\text{zv})$$

$$R_{23} = \frac{P_{m23} U_{m1}^2}{S_{23}^2} \quad (\text{zv})$$

$$\vec{Z}_{23} = R_{23} + j X_{23} \quad (\text{zv})$$

$$X_{23} = \frac{M_{k23} U_{m1}^2}{S_{23}} \quad (\text{zv})$$

$S_{12}$  = MJEŠAVINA VREDNOSTI OD  $(S_{m1}, S_{m2})$

$S_{13}$  = ——————  $(S_{m1}, S_{m3})$

$S_{23}$  = ——————  $(S_{m2}, S_{m3})$

FREMA JEDNOFАЗНОМ НАДОМјЕСНОМ МДЕЛУ:

$$\begin{aligned}\vec{Z}_{12} &= \vec{Z}_1 + \vec{Z}_2 \\ \vec{Z}_{13} &= \vec{Z}_1 + \vec{Z}_3 \\ \vec{Z}_{23} &= \vec{Z}_2 + \vec{Z}_3\end{aligned}$$

}

$\vec{Z}_1 = \frac{1}{2} (\vec{Z}_{12} + \vec{Z}_{13} - \vec{Z}_{23})$
$\vec{Z}_2 = \frac{1}{2} (\vec{Z}_{12} + \vec{Z}_{23} - \vec{Z}_{13})$
$\vec{Z}_3 = \frac{1}{2} (\vec{Z}_{13} + \vec{Z}_{23} - \vec{Z}_{12})$

$$Y_0 = G_0 + j B_0$$

ADMITANCIJA PREDVODNE GRANE  
(POKUS PH) ISTE REZULTATE KAO  
ZA DVOJNAMJENI EN. TR.

# NADOMESNI MODEL TRANSPORTNOG EN. TR. U ENERGETSKIH TRANSFORMATORA U NULTOM SUSTAVU

- NADOMESNI MODEL TRANSPORTNOG EN. TR. U NULTOM SUSTAVU - JEDNOKI KAO U DIREKTNOM SUSTAVU AKO SE MOGU RAZVITI NULTE STRUJE, A ŠTO OVISE O:
  - VRSTI SPJEDA FIZNITA MATERIJA
  - NAČINU KREMLJENJA ZVEZDISTVA

	<i>Spoj</i>	<i>Kompletna nadomjesna shema</i>	<i>Nulte impedancije</i>	<i>Shema transformatora u mreži (sa zanemarenjima)</i>	<i>Nulta reaktancija</i>
<i>a</i>			$\bar{Z}'_{a1} = \bar{Z}_1$ $\bar{Z}'_{a2} = \bar{Z}'_2$ $\bar{Z}'_{a3} = \bar{Z}'_3$ $\bar{Z}'_{b0}$ VELIKO	$I$ ○ ○ ○ ○	$X_o = \infty$
<i>b</i>			$\bar{Z}'_{a1} = \bar{Z}_1$ $\bar{Z}'_{a2} = \bar{Z}'_2$ $\bar{Z}'_{a3} = \bar{Z}'_3$ $\bar{Z}'_{b0}$ VELIKO	$I$ ○ ○ ○ ○	$X_o = X_i + X_{z'} = X_{i2} = \frac{1}{ Z_{i2} }$
<i>c</i>			$\bar{Z}'_{a1} = \bar{Z}_1$ $\bar{Z}'_{a2} = \bar{Z}'_2$ $\bar{Z}'_{a3} = \bar{Z}'_3$ $\bar{Z}'_{b0}$ VELIKO	$I$ ○ ○ ○ ○	$X_{o1} = X_i \dot{=}  \bar{Z}_i $ $X_{o2} = X_z \dot{=}  \bar{Z}_i $ $X_{o3} = X_j \dot{=}  \bar{Z}_j $
<i>d</i>			$\bar{Z}'_{a1} = \bar{Z}_1$ $\bar{Z}'_{a2} = \bar{Z}'_2$ $\bar{Z}'_{a3} = \bar{Z}'_3$ $\bar{Z}'_{b0}$ VELIKO	$I$ ○ ○ ○ ○	$X_o = X_i + X_{z'} = X_{i2} = \frac{1}{ Z_{i2} }$

Nadomjesne sheme nultog sustava tronamotnog transformatora

	Spoj	Kompletna nadomjesna shema	Nulte impedancije	Shema transformatora u mreži (sa zanemarenjima)	Nulta reaktancija
f	3 jednofazna transformatora		$\bar{Z}_a = \bar{Z}_i$ $\bar{Z}'_a = \bar{Z}'_i$ $\bar{Z}_{\infty} \text{ VELIKO}$	$I$ ○	$X_o = \infty$
g	1		$\bar{Z}_a = \bar{Z}_i$ $\bar{Z}'_a = \bar{Z}'_i$ $\bar{Z}_{\infty} \text{ VELIKO}$	$I$ ○	$X_o = X \doteq / \bar{Z} /$
h	1		$\bar{Z}_a \doteq \bar{Z}_i$ $\bar{Z}'_a = 0,1 \bar{Z}$ $\bar{Z}_{\infty} \text{ VELIKO}$	$I$ ○	$X_o \doteq 0,1 X \doteq 0,1 / \bar{Z} /$
i	1		$\bar{Z}_a \doteq \bar{Z}_i$ $\bar{Z}'_a = \bar{Z}'_i$ $\bar{Z}_{\infty} \text{ VELIKO}$	$I$ ○	$X_o = \infty$
j	1		$\bar{Z}_a = \bar{Z}_i$ $\bar{Z}'_a = \bar{Z}'_i$ $\bar{Z}_{\infty} \text{ VELIKO}$	$I$ ○	$X_o = X \doteq / \bar{Z} /$

Nadomjesne sheme nultog sustava dvonamotnog transformatora (nastavak) i autotransformatora

## LITERATURA:

1. Narus i Karin Oskarovic':  
Euklidske energetiske nregne I, II  
~~Fors~~ Split