

$$1. \quad Y(j\omega) = G(j\omega) U(j\omega) + V(j\omega)$$

$$u(t) = \mathcal{F}^{-1}\{U(j\omega)\} \quad v(t) = \mathcal{F}^{-1}\{V(j\omega)\}$$

$$u(t) = u^*(t) + w(t)$$

$$v(t) = v^*(t) + w(t)$$

$$R_{uy} = \int_0^\infty R_{uu}(\tau - \sigma) g(\sigma) d\sigma \rightarrow \text{kad nema korelacije u i v}$$

$$S_{uy}(j\omega) = S_{uu}(j\omega) \cdot G(j\omega) \Rightarrow \hat{G}(j\omega) = \frac{S_{uy}(j\omega)}{S_{uu}(j\omega)}$$

$$R_{uy}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T u(t) y(t+\tau) dt$$

$$y = y_u + w$$

$$R_{uy}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T u(t) y_u(t+\tau) dt + \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T u(t) w(t+\tau) dt$$

$$R_{uy}(\tau) = \int_0^\infty R_{uu}(\tau - \sigma) g(\sigma) d\sigma + \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T (u^*(t) + w(t)) (v^*(t+\tau) + w(t+\tau)) dt$$

$u^* \cdot u^*$  ne koreliraju ni u ni v  $\lim_T$  (lubi sum)

$$R_{uy}(\tau) = \underbrace{\int_0^\infty R_{uu}(\tau - \sigma) g(\sigma) d\sigma}_{R_{uu} * g} + \underbrace{\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T w(t) w(t+\tau) dt}_{R_{ww}(\tau)}$$

$$R_{uy}(\tau) = R_{uu} * g + R_{ww}(\tau)$$

$$S_{uy}(j\omega) = S_{uu}(j\omega) \cdot G(j\omega) + S_{ww}(j\omega) \quad / : S_{uu}$$

$$G(j\omega) = \frac{S_{uy}(j\omega)}{S_{uu}(j\omega)} - \frac{S_{ww}(j\omega)}{S_{uu}(j\omega)}$$

$$\hat{G}(j\omega) - G(j\omega) = \frac{S_{ww}(j\omega)}{S_{uu}(j\omega)}$$

Postoje izmisljeni sklopi i eliminirane frekvencijske karakteristike  
i to je manja što je manji signal smetnje  $w(t)$  i  
što je jači.

$$2. \quad L(\mu, \sigma^2; x_i) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2} \left(\frac{x_i - \mu}{\sigma}\right)^2}$$

$$\ln L(\mu, \sigma^2; x_i) = \sum_{i=1}^n \left( -\ln(\sqrt{2\pi}\sigma) - \frac{1}{2} \left(\frac{x_i - \mu}{\sigma}\right)^2 \right)$$

$$= -\frac{n}{2} \ln(2\pi) - n \ln \sigma - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 \quad \left| \frac{d}{d\mu} \right| \quad \left| \frac{d}{d\sigma} \right|$$

$$0 = -\frac{1}{2\sigma^2} \cdot 2 \sum_{i=1}^n (x_i - \mu) + \frac{1}{\sigma^2} \left( \sum_{i=1}^n x_i - n\mu \right) = 0 \quad \left( \hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i \right)$$

$$0 = -\frac{n}{\sigma^2} + \frac{2}{\sigma^3} \sum_{i=1}^n (x_i - \mu)^2 \quad / \cdot \sigma^3$$

$$n\sigma^2 = \sum_{i=1}^n (x_i - \mu)^2 \Rightarrow \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{\mu})^2$$



$$\mu = \frac{1}{n} \sum_{i=1}^n x_i$$

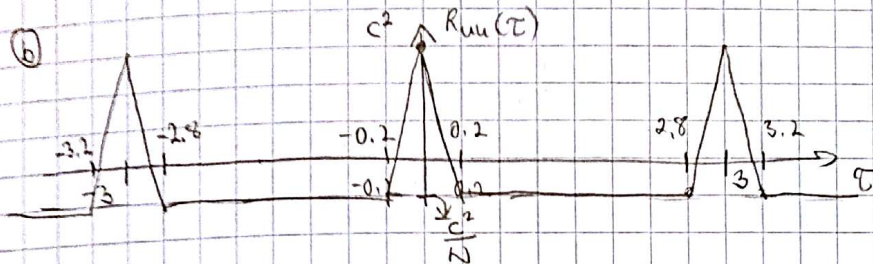
$$\sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2$$

3. (a) PARAMETRI PRBS SIGNALA:

$$c=2$$

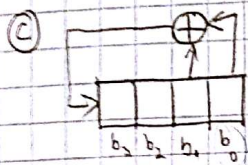
$$\Delta t = 0.2 \text{ s}$$

$$N = 2^m - 1 = 2^4 - 1 = 15$$



$$c^2 = 4$$

$$\frac{c^2}{N} = \frac{4}{15}$$



$$b_0(t) = 0 \rightarrow u(t) = -c$$

$$b_0(t) = 1 \rightarrow u(t) = c$$

podatno krunje  
1 0 1 0

$$b_0(0) = 0$$

$$b_0(1 \cdot \Delta t) = b_0(0) = 1$$

$$b_0(2 \cdot \Delta t) = b_0(\Delta t) = b_2(0) = 0$$

$$b_0(3 \cdot \Delta t) = b_0(0) = 1$$

$$b_0(4 \cdot \Delta t) = b_0(0) \oplus b_1(0)$$

$$= b_0((4-4)\Delta t) \oplus b_0((4-3)\Delta t)$$

$$b_0(k \cdot \Delta t) = b_0((k-4)\Delta t) \oplus b_0((k-3)\Delta t)$$

$$b_0(13 \cdot \Delta t) = 0 \oplus 1 = 1 \rightarrow u(13 \cdot \Delta t) = 2$$

$$b_0(14 \cdot \Delta t) = 1 \oplus 0 = 1 \rightarrow u(14 \cdot \Delta t) = 2$$

(d)  $G_s(j\omega) = \frac{3}{2j\omega + 1}$  ,  $S_{yy}(\omega) = \frac{9}{\omega^2 + 9} \cdot \frac{1}{4\omega^2 + 1}$

(a)  $S_{yy} = |G_s(j\omega)|^2 \cdot S_{uu}$   $|G_s(j\omega)| = \frac{3}{\sqrt{4\omega^2 + 1}}$

$$\frac{9}{\omega^2 + 9} \cdot \frac{1}{4\omega^2 + 1} = \frac{9}{4\omega^2 + 1} \cdot S_{uu} \Rightarrow S_{uu} = \frac{1}{\omega^2 + 9}$$

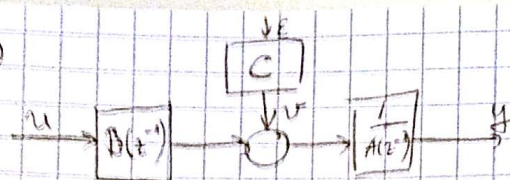
(b)  $\bar{P}_u = R_{uu}(0) = \frac{1}{\pi} \int_{-\infty}^{\infty} S_{uu}(\omega) d\omega = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{d\omega}{\omega^2 + 9} = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1}{9 \left( \left( \frac{\omega}{3} \right)^2 + 1 \right)} d\omega = \left| \frac{t = \frac{\omega}{3}}{3dt = d\omega} \right|$

$$= \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{1}{3(t^2 + 1)} dt = \frac{1}{3\pi} \cdot \arctan t \Big|_{-\infty}^{\infty} = \frac{1}{3\pi} \cdot \frac{\pi}{2} = \frac{1}{6}$$

$$\bar{P}_u = \frac{1}{6}$$



⑤ ⑥



$$Y = \frac{B}{A} U + \frac{C}{A} E, \quad V = C E$$

$$A Y = B U + C E_V \rightarrow V = A Y - B U$$

$$y(k) = -0.615 y(k-1) - 0.0851 y(k-2) + 0.2 u(k-1) + v(k)$$

$$v(k) = e(k) + 0.4 e(k-1)$$

⑤  $E[y(3)] = -0.615 y(2) - 0.0851 y(1) + 0.2 u(2) + 0.4 \cdot E(2) \stackrel{=0}{=} E[e(3)]$  *right from*

$$e(k) = y(k) + 0.615 y(k-1) + 0.0851 y(k-2) - 0.2 u(k-1) - 0.4 e(k-1)$$

$$e(0) = y(0) = 0.1$$

$$e(1) = y(1) + 0.615 y(0) - 0.2 u(0) - 0.4 e(0) \stackrel{=y(0)}{=}$$

$$e(2) = y(2) + 0.615 y(1) + 0.0851 y(0) - 0.2 u(1) - 0.4 e(1)$$

$$e(1) = 0.2 + 0.215 \cdot 0.1 - 0.2 \cdot 2 =$$

$$e(2) =$$

③ Deterministički dio  $\frac{b}{A} \Rightarrow B$  ima jednu nulu

$A$  nema tu nulu

Pakle, red modela ne može se smanjiti

⑥  $Y = \frac{B}{A} U + \frac{V}{A} \quad V = \frac{1}{D} E$

$$v(k) = d_1 v(k-1) + e(k)$$

$$v(k) = y(k) + a_1 y(k-1) - b_1 u(k-1)$$

$$e(k) = y(k) + a_1 y(k-1) - b_1 u(k-1) - d_1 (y(k-1) + a_1 y(k-2) - b_1 u(k-2))$$

$$k=1, \dots, 5$$

$$E(N) = [e(3) \quad e(4) \quad e(5)]^T$$

$$Y(N) = \Phi(N) \cdot \underline{\theta} + E(N), \quad \underline{\theta} = d_1$$

$$\Phi(k) = [-y(k-1) - a_1 y(k-2) + b_1 u(k-2)]$$

$$\Phi(N) = \begin{bmatrix} \Phi(3) \\ \Phi(4) \\ \Phi(5) \end{bmatrix}$$



$$Y(N) = \begin{bmatrix} y(3) + a_1 y(2) - b_1 u(2) \\ y(4) + a_1 y(3) - b_1 u(3) \\ y(5) + a_1 y(4) - b_1 u(4) \end{bmatrix}$$

$$7. \quad G(z) = \frac{(1+a_1)z^{-1}}{1-a_1 z^{-1}}$$

$$UG + V = Y$$

$$(1+a_1)z^{-1}U + (1-a_1 z^{-1})V = (1+a_1 z^{-1})Y \quad v'(k)$$

$$y(k) = -a_1 y(k-1) + (1+a_1)u(k-1) \quad (v(k) + a_1 v(k-1))$$

Bo metodi IV mi zanimaju nas statistička registracija metode  $v'(k)$

$$y(k) - u(k-1) = a_1 (-y(k-1) + u(k-1)) \quad \underbrace{-v'(k)}_{\text{mi zanimali me}}$$

$$V' = Y - \phi \theta$$

$$V' = \begin{bmatrix} v'(2) \\ v'(3) \\ v'(4) \\ v'(5) \end{bmatrix}$$

$$Y = \begin{bmatrix} y(2) - u(1) \\ y(3) - u(2) \\ y(4) - u(3) \\ y(5) - u(4) \end{bmatrix}$$

$$\phi = \begin{bmatrix} -y(1) + u(1) \\ -y(2) + u(2) \\ -y(3) + u(3) \\ -y(4) + u(4) \end{bmatrix}$$

$$W = \begin{bmatrix} -y_+(1) + u(1) \\ -y_+(2) + u(2) \\ -y_+(3) + u(3) \\ -y_+(4) + u(4) \end{bmatrix}$$

$$y_+(1) = 0, \quad y_+(2) = 0.4u(1), \quad y_+(3) = 0.24u(1) + 0.4u(2)$$

$$y_+(k) = -\hat{a}_1 y_+(k-1) + (1+\hat{a}_1)u(k-1) \\ = 0.6y_+(k-1) + 0.4u(k-1)$$

$$y_+(4) = 0.144u(1) + 0.24u(2) + 0.4u(3)$$