

# Mateusz Jaszczuk

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## Education

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### University of Pennsylvania

*M.S.E. in Mechanical Engineering and Applied Mechanics  
with a concentration in Mechatronic and Robotic Systems*

*Aug 2024 – Present  
Philadelphia, PA*

- **Thesis** Learning to Feel: Force-Aware Data-Driven Estimation and Control for Fluid Physical Interactions  
**Committee** Dr. Nadia Figueroa (Advisor), Dr. Paris Perdikaris, Dr. Rachel Holladay
- **GPA** 4.00/4.00
- **Relevant Coursework** Learning and Control for Adaptive and Reactive Robots, Data-driven Modeling, Machine Learning, Distributed Robotics, Optimal Control, Design of Mechatronic Systems

### Purdue University

*B.S. in Aeronautical and Astronautical Engineering  
with a specialization in Autonomy and Control*

*Aug 2020 – May 2024  
West Lafayette, IN*

- **GPA:** 3.71/4.00
- **Coursework:** Applied Optimal Control and Estimation, Linear Systems Analysis and Synthesis, Spacecraft Attitude Dynamics, Control Systems Analysis, Signal Analysis, Structural Analysis

## Research Experience

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### Figueroa Robotics Lab (GRASP)

*Graduate Research Assistant*

*Jan 2025 – Present  
Philadelphia, PA*

- Developed an impedance controller with a Dynamical System-based motion policy for Franka Emika arm.
- Created Rapid Mismatch Estimation, a novel, data-driven adaptation framework that allows robotic manipulators to adapt to unknown heavy objects in real time, ensuring safe and effective task execution.
- Implemented real-time compensation module leveraging Machine Learning architectures with variational inference optimization and integrated the model into a custom ROS package for efficient system integration.
- Validated proposed approach through simulation and hardware testing, showcasing the model's robustness.
- Lead writing academic publication and presented the work at the 9th Conference on Robot Learning (CoRL).
- Designed a multi-modal perception framework that fuses proprioception and vision using a cross-attention for interaction classification and adaptive blending between load-estimation and compliant-control modes.

### Composite Manufacturing & Simulation Center

*Undergraduate Research Assistant*

*Oct 2022 – May 2024  
West Lafayette, IN*

- Developed a Bayesian model to predict the conductivity of 3D-printed, carbon-reinforced composites across varying process conditions, reducing characterization effort required for consistent, high quality prints.
- Implemented a probabilistic Physics-Guided Transfer Learning framework in Python and supported the development of Gaussian Process surrogates of the underlying composite's micromechanics model.
- Automated Abaqus FEA results post-processing pipeline and conducted experimental characterization of the thermal conductivity of 3D printed, carbon-reinforced samples, providing effective framework evaluation.
- Co-authored an academic publication and designed visualizations to demonstrate the model's evaluation.

### Air Force Research Lab - Purdue UAS Research and Test Facility

*Undergraduate Research Assistant, Project Lead*

*Aug 2023 – Dec 2023  
West Lafayette, IN*

- Developed autonomous fixed-wing aircraft for enclosed hangar-flight in collaboration with Windracers (UK), including aircraft sizing code, motion simulations, prototyping, and experimental validation.
- Supported the development of the autopilot software using pseudo-GPS signals generated via motion capture cameras, enabling reliable indoor navigation, providing the client with the platform to test aircraft systems.
- Managed communication with the project coordinator and client, presented work progress during monthly meetings, discussed the budget and development cycle, ensuring alignment with the client's requirements.

## Publications ad Presentations

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- [1] **M. Jaszczuk** and N. Figueroa, “Rapid mismatch estimation via neural network informed variational inference,” in *9th Annual Conference on Robot Learning (CoRL)*, 2025.
- [2] A. J. Thomas, **M. Jaszczuk**, E. Barocio, G. Ghosh, I. Bilonis, and R. B. Pipes, “Probabilistic physics-guided transfer learning for material property prediction in extrusion deposition additive manufacturing,” *Computer Methods in Applied Mechanics and Engineering*, vol. 419, p. 116660, 2024.
- [3] A. J. Thomas, **M. Jaszczuk**, E. Barocio, I. Bilonis, and R. B. Pipes, “Physics-guided transfer learning for property prediction in composite additive manufacturing.” SAMPE Japan, 2023.
- [4] **M. Jaszczuk**, “A bayesian framework for transfer of process-dependent material properties.” Purdue Fall Undergraduate Research Expo, November 2023. West Lafayette, IN, USA.

## Teaching Experience

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**University of Pennsylvania**

MEAM 5200 Introduction to Robotics - *Teaching Assistant*

*Philadelphia, PA*

*Fall 2025*

## Project Experience

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**Small-Scale Transformer for Text Generation - Graduate Course Project**

*Aug 2024 – Dec 2024*

*Student Researcher, Developer*

*Philadelphia, PA*

- Implemented a lightweight GPT-inspired transformer neural network to generate coherent artificial text.
- Designed multi-head attention, positional encoding, and MLP modules in PyTorch, trained the model on small datasets (books, screenplays) to demonstrate artificial text generation and performance evaluation.
- Conducted ablation on regularization (dropout, layer normalization) to evaluate the impact on performance.

**Autonomous Mobile Battle Robot - Graduate Course Project**

*Aug 2024 – Dec 2024*

*Robotics Engineer, Team Member*

*Philadelphia, PA*

- Designed a mobile robot for autonomous competition task execution (wall-following, navigation, attack) across a full project lifecycle: concept design, prototyping, integration, testing, and final competition.
- Integrated mechanical and electronic subsystems (platform, motors, ultrasonic/ToF sensors, ESP32 micro-controller, custom circuits) and programmed an Arduino-based embedded system for real-time control.

**NOAA Wind Tracking Satellite Constellation - Senior Design Project**

*Aug 2023 – Dec 2023*

*Attitude Dynamics and Control Engineer, Team Member*

*West Lafayette, IN*

- Developed a MATLAB 6-DOF model to simulate satellite attitude dynamics across multiple orbital planes.
- Coordinated system integration and designed active/passive attitude control strategies, ensuring the spacecraft met stability and maneuverability requirements for long-duration Earth’s surface monitoring.

**Purdue Space Program NASA Student Launch**

*Aug 2021 – May 2023*

*Project Manager (2021-2022), Launch Vehicle Construction Engineer (2022-2023)*

*West Lafayette, IN*

- Managed project workflow and resources for a 100-member interdisciplinary team, ensuring sub-systems met mission and top-level assembly requirements for NASA Student Launch competition.
- Coordinated deliverables and communications with NASA and NAR, including mission design, flight simulations (6-DOF Simulink model), competition reports, and team logistics for competition-related events.
- Designed and analyzed launch vehicle structures (motor mount, fin support, airframe), performing FEA, CFD, and physical tests to optimize strength, mass, cost, and vehicle performance.
- Led manufacturing and assembly of precision aluminum components using CNC milling and laser cutting, coordinating a student team in fabrication and integration.

## Skills

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**Programming & Tools** - Python (PyTorch, JAX), C, C++, Isaac Lab, MATLAB, ROS, PyBullet, Gazebo

**Machine Learning** - Neural Networks (MLP, CNN, Transformers), Optimization (Adam, Gradient-Based), Probabilistic Modeling (Bayesian, Variational Inference), MCMC Sampling, Regularization (Dropout/BatchNorm)

**Control & Estimation** - Impedance Control, Optimal Control & Estimation, System Identification

**Hardware** - Franka Research 3 7-DoF Manipulator, Sensor Integration, OptiTrack Motion Capture, Embedded Prototyping (Arduino), Additive Manufacturing (FDM, EDAM), CNC Manufacturing, Laser Cutting