

### DT2118 Lab2: Hidden Markov Models with Gaussian Emissions

## 1 Objective

The objective is to implement the algorithms for evaluation and decoding of Hidden Markov Models (HMMs) combined with Gaussian emission probability distributions. The lab is designed in Python, but the same functions can be obtained in Matlab/Octave or using the Hidden Markov Toolkit (HTK).

### 2 Task

The overall task is to implement and test methods for isolated word recognition:

- implement the forward algorithm,
- use it compute the log likelihood of spoken utterances given a Gaussian HMM
- perform isolated word recognition
- compare the Gaussian HMM to a GMM (Gaussian Mixture Model)
- implement the Viterbi algorithm, and use it to compute Viterbi path and likelihood
- compare and comment Viterbi and Forward likelihoods
- Optional: implement the Baum-Welch algorithm and use it to update the model parameters

In order to pass the lab, you will need to follow the steps described in this document, and produce a report where you describe your work and answer the questions asked here. The report should be submitted in the Assignment section in the course Web on KTH Social https://www.kth.se/social/course/DT2118/. One submission should be done for each group, clearly stating all the members of that group.

#### 3 Data

The speech data used in this lab is similar but not the same as in Lab 1. You can load the array containing speech utterances with the commands:

```
import numpy as np
tidigits = np.load('lab2_tidigits.npz')['tidigits']
```

The data contains also MFCC features (mfcc key), but you are welcome to test how the algorithms perform on the MFCCs computed with your own code from Lab 1. Refer to the instructions to Lab 1 for more information about the data structures.

Page 1 (of 8)

Additionally, the lab2\_models.npz file contains the parameters of the models you are going to use to test your functions and the lab2\_example.npz file contains an example that can be used for debugging.

#### 3.1 The models

Load the model file with:

```
models = np.load('lab2_models.npz')['models']
```

The models array has length 11 each element corresponding to one of the following digits: ['o','z','1','2','3','4','5','6','7','8','9']. Each element contains the following keys:

```
models[0].keys()
['digit', 'pron', 'hmm', 'gmm']
```

| key    | description   |
|--------|---|
| digit: | the digit the model refers to   |
| pron:  | pronunciation of the digit in terms of phonemes (not needed in this exercise) |
| hmm:   | model parameters of a Gaussian HMM trained with Baum-Welch                    |
| gmm:   | model parameters of a GMM trained with EM                                     |

Both the HMMs and the GMMs were trained on the same data (different from the data in the tidigits array) and were initialized the same way. Both use diagonal covariance matrices for the Gaussian distributions. The size of the model (number of states in HMM and number of Gaussians in GMM) depends on the digit and was obtained using three states for each phoneme in models[i]['pron'] plus three states for the initial and final silence in the utterance. For example, the digit '6' is pronounced as ['s', 'ih', 'k', 's'] and will therefore have  $(4+2) \times 3 = 18$  states.

The HMM model contains the following fields:

```
models[0]['hmm'].keys()
['startprob', 'transmat', 'means', 'covars']
```

| key       | symbol                                  | description  |
|-----------|---|--|
| startprob | $\pi_i = P(z_0 = s_i)$                  | probability to start in state $i$                  |
| transmat: | $a_{ij} = P(z_n = s_j   z_{n-1} = s_i)$ | transition probability from state $i$ to $j$       |
| means:    | $\mu_{id}$                              | array of mean vectors (rows correspond to dif-     |
|           |   | ferent states)                                     |
| covars:   | $\sigma_{id}^2$                         | array of variance vectors (rows correspond to dif- |
|           |   | ferent states)                                     |

The GMM models contain the following fields:

```
models[0]['gmm'].keys()
['weights', 'means', 'covars']
```

| key      | $\operatorname{symbol}$ | description  |
|----------|-------------------------|--|
| weights: | $w_i$                   | weight of each Gaussian in the mixture                             |
| means:   | $\mu_{id}$              | array of mean vectors (rows correspond to different Gaussians)     |
| covars:  | $\sigma_{id}^2$         | array of variance vectors (rows correspond to different Gaussians) |

Check the transition matrix and the start probability for the HMM models. What can you say about their topology (transition structure)?

Page 2 (of 8)

#### 3.2 The example

Load the example file with:

```
example = np.load('lab2_example.npz')['example'].item()
```

This is a dictionary containing all the fields as in the tidigits array, plus the following additional fields:

Here is a description of each field. You will see how to use this information in the reminder of these instructions. All the probabilities described below were obtained using the HMM model in models[0]['hmm'] and the GMM model in models[0]['gmm'] (that is, the models for digit 'o') on the sequence of MFCC vectors in example['mfcc']:

| key           | idxs  | symbol  | description  |
|---------------|-------|---|--|
| gmm_obsloglik | [i,j] | $\log \phi_j(x_i)$                            | observation log likelihood for each Gaussian         |
|               |       |   | in models[0][gmm], shape: (n_timesteps,              |
|               |       |   | $n_{gaussians}$                                      |
| gmm_loglik    | -     | $\log P(X 	heta_{	ext{GMM}})$                 | log likelihood of the observations sequence $X$      |
|               |       |   | given the full GMM model, scalar                     |
| hmm_obsloglik | [i,j] | $\log \phi_j(x_i)$                            | observation log likelihood for each Gaussians        |
|               |       |   | in models[0][hmm], shape: (n_timesteps,              |
|               |       |   | $n_{states}$   |
| hmm_logalpha  | [i,j] | $\log \alpha_j(x_i)$                          | alpha log probabilities, see definition later,       |
|               |       |   | shape: (n_timesteps, n_states)                       |
| hmm_logbeta   | [i,j] | $\log \beta_j(x_i)$                           | beta log probabilities, see definition later, shape: |
|               |       |   | $(n\_timesteps, n\_states)$                          |
| hmm_loglik    | -     | $\log P(X 	heta_{	ext{	iny HMM}})$            | log likelihood of the observations sequence $X$      |
|               |       |   | given the HMM model, scalar                          |
| hmm_vloglik   | -     | $\log P(X \theta_{	ext{HMM}}, S_{	ext{opt}})$ | Viterbi log likelihood of the observations se-       |
|               |       | 1   | quence $X$ given the HMM model and the best          |
|               |       |   | path, scalar   |

Figure 1 shows some of the relevant fields in example.

# 4 Multivariate Gaussian Density

The function log\_multivariate\_normal\_density(..., 'diag') from sklearn.mixture can be used to compute

$$\log \text{ emlik}[i, j] = \log \phi_i(x_i) = \log N(x_i, \mu_i, \Sigma_i) = \log P(x_i | \mu_i, \Sigma_i),$$

that is the log likelihood for each observation  $x_i$  and each term in a multivariate Gaussian density function with means  $\mu_j$  and diagonal covariance matrices  $\Sigma_j$ . In the case of Gaussian HMMs,  $\phi_j$  corresponds to the emission probability model for a single state j. In case of a GMM,  $\phi_j$  corresponds to a single Gaussian in the model, without considering the weights.

Page 3 (of 8)

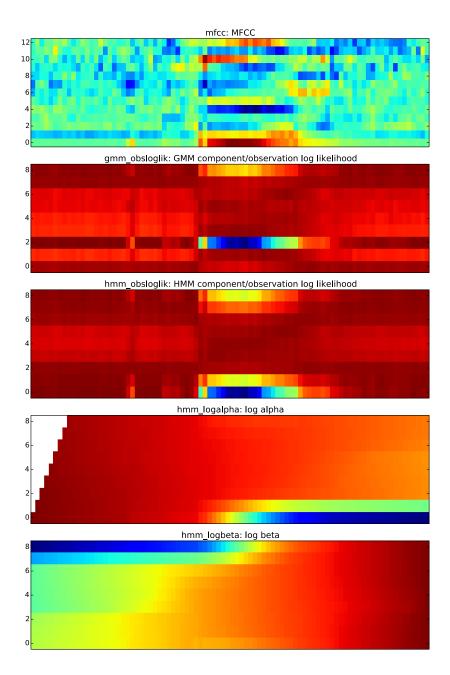


Figure 1.

Verify that you get the same results as in example['hmm\_obsloglik'] and example['gmm\_obsloglik'] when you apply the log\_multivariate\_normal\_density function to the example['mfcc'] data using the Gaussian distributions defined respectively in models[0]['hmm'] and models[0]['gmm']. Note that in these cases we are using neither the weights of the GMM, nor the time dependency structure of the HMM, but only the Gaussian distributions.

Plot the log likelihood for Gaussians from HMMs and GMMs models corresponding to the same digit on a test utterance of your choice. What can you say about the order of the Gaussians, and the time evolution of the likelihood along the utterance? Remember that each utterance starts and ends with silence.

### 5 GMM Likelihood and Recognition

Based on the output of the function in the previous section, write the gmmloglik function (proto2.py) that computes the log likelihood of an observation sequence  $X = \{x_0, \ldots, x_{N-1}\}$  given the full GMM model, that is, given the weights of each Gaussian density in the GMM model. Remember that the assumption in the GMM model is that the  $x_n$  vectors are independent for each  $n = [0, N)^1$ . Whenever there is an expression involving the log of a sum of exponents  $(\log \sum \exp(.))$ , make use of the logsumexp function from tools2.py.



The output of the gmmloglik function, using the model parameters in models[0]['gmm'] and the observation sequence from example['mfcc'], should correspond to example['gmm\_loglik'].

Use this function to score each of the 44 utterances in the tidigits array with each of the 11 GMM models in models[i]['gmm']. If we select for each utterance the model with the highest log likelihood, how many digits are misrecognized?

### 6 HMM Likelihood and Recognition

#### 6.1 Forward Algorithm

Write the function forward following the prototypes in proto2.py. The function should take as input a lattice of emission probabilities as in the previous section, that is an array containing:

$$\log \text{ emlik}[i, j] = \log \phi_i(x_i)$$

The output is the array:

$$logalpha[i, j] = log \alpha_i(j)$$

where i corresponds to time steps and j corresponds to states in the model. The recursion formulae for the forward probabilities in  $log\ domain$  are given here, where we have used Python convention with array indices going from 0 to len-1:

$$\log \alpha_0(j) = \log \pi_j + \log \phi_j(x_0)$$

$$\log \alpha_n(j) = \log \left( \sum_{i=0}^{M-1} \exp \left( \log \alpha_{n-1}(i) + \log a_{ij} \right) \right) + \log \phi_j(x_n)$$

In all the cases where there is an expression involving the log of a sum of exponents ( $\log \sum \exp(.)$ ), make use of the logsumexp function from tools2.py.

Page 5 (of 8)

<sup>&</sup>lt;sup>1</sup>We are using the convention to express intervals with square brackets "[" if the extreme is included and parentheses ")" if it is excluded. This corresponds to the range function in Python that includes the start value but not the end value.

Apply your function to the example['mfcc'] utterance using the model parameters in models[0]['hmm'] and verify that you obtain the same  $\log \alpha$  array as in example['hmm\_logalpha'].

The definitions of  $\alpha_n(j)$  in terms of probabilities of events are defined below (where  $\theta = \{\Pi, A, \Phi\}$  are the model parameters):

$$\alpha_n(j) = P(x_0, \dots, x_n, z_n = s_i | \theta)$$

Given the above definition, derive the formula to compute the likelihood  $P(X|\theta)$  of the whole sequence  $X = \{x_0, \dots, x_{N-1}\}$ , given the model parameters  $\theta$  in terms of  $\alpha_n(j)$ .

**Hint:** if the events  $B_j, j \in [0, M)$  form a disjoint partition of the sure event, that is:

$$P(B_i, B_j) = 0, \quad \forall i, j, \quad i \neq j, \text{ and}$$
  
$$\sum_{j=0}^{M-1} P(B_j) = 1,$$

then it is true that  $P(A) = \sum_{j=0}^{M-1} P(A, B_j)$ , that is, we can marginalize out the variable  $B_j$ .

Convert the formula you have derived into log domain. Verify that the log likelihood obtained this way using the model parameters in models[0]['hmm'] and the observation sequence in example['mfcc'] is the same as example['hmm\_loglik'].

Using your formula, score all the 44 utterances in tidigits with each of the 11 HMM models in models. How many mistakes can you count if you take the maximum likelihood model as winner? Compare these results with the GMM results obtained in the previous session.

Repeat the recognition using the Gaussian distributions in the HMM models as if they were a GMM model with equal weights for each Gaussian. What can you say about the results you obtain this way? Can you say something about the influence of the HMM transition model in this particular task?

Plot the  $\alpha$  lattice (that is the array of  $\alpha$ s for each time step and state). What can you say about the influence of the HMM topology on the first time steps? How about the last ones?

#### 6.2 Viterbi Approximation

Here you will compute the log likelihood of the observation X given a HMM model and the best sequence of states. This is called the Viterbi approximation. Implement the function viterbi in proto2.py. The Viterbi recursion formulas are as follows:

$$\log V_0(j) = \log \pi_j + \log \phi_j(x_0) \log V_n(j) = \max_{i=0}^{M-1} \left( \log V_{n-1}(i) + \log a_{ij} \right) + \log \phi_j(x_n)$$

In order to recover the best path, you will also need an array storing the best previous path for each time step and state (this needs to be defined only for  $n \in [1, N)$ , that is not for the first time step):

$$B_n(j) = \arg \max_{i=0}^{M-1} \left( \log V_{n-1}(i) + \log a_{ij} \right)$$

Consult the course book [1], Section 8.2.3, to see the details of the implementation (note that the book uses indices from 1, instead of 0).

Page 6 (of 8)

Compute the Viterbi log likelihood for models[0]['hmm'] and example['mfcc'], and verify that you obtain the same result as in example['hmm\_vloglik'].

Plot the alpha array that you obtained in the previous Section and overlay the best path obtained by Viterbi decoding. Can you explain the reason why the path looks this way?

Using the Viterbi algorithm, score all the 44 utterances in tidigits with each of the 11 HMM models in models. How many mistakes can you count if you take the maximum likelihood model as winner? Compare these results with the results obtained in previous sections.

### 6.3 Optional: Backward Algorithm

Write the function backward following the prototypes in proto2.py. Similarly to the function forward in the previous section, the function should take as input a lattice of emission probabilities as in the previous section, that is an array containing:

$$\log_{\min}[i,j] = \log \phi_i(x_i)$$

The output is the array:

$$logbeta[i, j] = log \beta_i(j),$$

where i corresponds to time steps and j corresponds to states in the model. The recursion formulae for the backward probabilities in  $log\ domain$  are given here, where we have used Python convention with array indices going from 0 to len-1:

$$\log \beta_{N-1}(i) = 0 \log \beta_n(i) = \log \left( \sum_{j=0}^{M-1} \exp \left( \log a_{ij} + \log \phi_j(x_{n+1}) + \log \beta_{n+1}(j) \right) \right)$$

Note also that the initialization of the  $\beta_{N-1}(i)$  is different from the one defined in the course book [1] (Section 8.2.4) but corresponds to the one used in [2].

In all the cases where there is an expression involving the log of a sum of exponents ( $\log \sum \exp(.)$ ), make use of the logsumexp function in tools2.py.

Apply your function to the example['mfcc'] utterance using the model parameters in models[0]['hmm'] and verify that you obtain the  $\log \beta$  arrays as in example['hmm\_logbeta'].

The definitions of  $\beta_n(j)$  in terms of probabilities of events are defined below (where  $\theta = \{\Pi, A, \Phi\}$  are the model parameters):

$$\beta_n(i) = P(x_{n+1}, \dots, x_{N-1} | z_n = s_i, \theta)$$

Advanced: Derive the formula that computes  $P(X|\theta)$  using the betas  $\beta_n(i)$  instead of the alphas.

- **Hint 1:** only the  $\beta_0(i)$  are needed for the calculation.
- **Hint 2:** note that the definition of  $\alpha_n(j)$  is a *joint* probability of observations and state at time step n whereas  $\beta_n(i)$  is a *conditional* probability of the observations given the state at time step n.
- **Hint 3:** the calculation will not only involve the betas, but also some of the observation likelihoods  $\phi_i(x_n)$  and some of the model parameters,  $\pi_i$  or  $a_{ij}$ .

Verify that also this method gives you the same log likelihood and that they both are

equal to example['hmm\_loglik'].

## References

- [1] Xuedong Huang, Alex Acero, and Hsiao-Wuen Hon. Spoken Language Processing: A Guide to Theory, Algorithm and System Development. Prentice Hall PTR, 2001.
- [2] L. R. Rabiner. "A tutorial on hidden Markov models and selected applications in speech recognition". In: *Proceedings of the IEEE* 77.2 (Feb. 1989), pp. 257–286.