

**Diferencialne enačbe.** Imamo tri plasti, ki drsijo ena mimo druge. Med njimi deluje viskoznost s koeficientom  $\gamma$ .

$$\begin{aligned}m\dot{v}_1 &= \gamma(v_2 - v_1) \\m\dot{v}_2 &= \gamma(v_3 - v_2) + \gamma(v_1 - v_2) = \gamma(v_3 - 2v_2 + v_1) \\m\dot{v}_3 &= \gamma(v_2 - v_3)\end{aligned}$$

Sistem zapišemo v matrični obliki:

$$\begin{aligned}\vec{v} &= \tilde{A} \vec{v} \\ \tilde{A} &= \frac{\gamma}{m} \begin{bmatrix} -1 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -1 \end{bmatrix} = \frac{\gamma}{m} A\end{aligned}$$

Diagonalizirajmo  $A$ :

$$\det(A - \lambda I) = (-1 - \lambda)((-2 - \lambda)(1 - \lambda) - 1) - (-1 - \lambda) = \dots = -\lambda(\lambda + 1)(\lambda + 2)$$

Imamo lastne vrednosti  $\lambda_1 = 0$ ,  $\lambda_2 = -1$ ,  $\lambda_3 = -3$ . Izračunamo še pripadajoče lastne vektorja:

$$\begin{aligned}\lambda_1 = 0: \quad \vec{u}_1(t) &= u_0 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \\ \lambda_2 = -1: \quad \vec{u}_2(t) &= u_0 e^{-\gamma t/m} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \\ \lambda_3 = -3: \quad \vec{u}_3(t) &= u_0 e^{-3\gamma t/m} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}\end{aligned}$$

Sledi:  $\vec{v}(t) = a\vec{u}_1(t) + b\vec{u}_2(t) + c\vec{u}_3(t)$

**Kolokvij 2019.** Imamo kroglo z gostoto toplotnih izvorov  $q$ . Velja  $q = kT^2$ . Zanima nas toplotni tok, ki izhaja iz krogle.

$$\begin{aligned}\frac{dW}{dt} &= qV - jS \\ mc \frac{dT}{dt} &= qV - \lambda \frac{D}{s} T \\ \dot{T} &= \frac{k}{\rho c} T^2 - \frac{\lambda}{k\rho c} \frac{3}{R} T\end{aligned}$$

Imamo enačbo oblike

$$\begin{aligned}\dot{T} &= A(T^2 - BT) \\ A\dot{T} &= A^2 \left( \left(T - \frac{B}{2}\right)^2 - \frac{B^2}{4} \right) = \left( A \left(T - \frac{B}{2}\right) \right)^2 - \frac{A^2 B^2}{4}\end{aligned}$$

Vzamemo novo spremenljivko  $u$ :

$$\begin{aligned}\dot{u} &= u^2 - \left(\frac{AB}{2}\right)^2 = u^2 - u_0^2 \\ dt &= \frac{du}{u^2 - u_0^2} \\ t &= \begin{cases} -\frac{1}{u_0} \operatorname{artanh} \frac{u}{u_0} + t_0 & |u| < u_0 \\ -\frac{1}{u_0} \operatorname{arcoth} \frac{u}{u_0} + t_0 & |u| > u_0 \end{cases}\end{aligned}$$

Poiščemo lahko inverz:

$$\begin{aligned}u_1 &= -u_0 \tanh[(t - t_0)u_0] \\ u_1 &= -u_0 \coth[(t - t_0)u_0]\end{aligned}$$

**Majhna nihanja.** Pri majhnih nihanjih imamo posplošene koordinate  $\underline{q}$ , v katerih mora veljati:

$$\frac{\partial V}{\partial q_i} = 0$$

Konstruiramo matriki  $\underline{\underline{V}}$  in  $\underline{\underline{T}}$ , kjer je

$$V_{jk} = \partial_j \partial_k V$$

$$T_{jk} = \partial_j \partial_k T$$

Nato poiščemo lastne frekvence  $\omega$  in pripadajoče lastne vektorje, da velja

$$\det(\underline{\underline{V}} - \omega^2 \underline{\underline{T}}) = 0$$

Tedaj je

$$\underline{q}(t) = \text{Span}\{\underline{q}_{last.} e^{i\omega t}\}$$