Last name	
First name	

LARSON—OPER 731—CLASSROOM WORKSHEET 11 Duality!

Concepts

- (Sec. 2.4) basis, basic variable, nonbasic variable, basic solution, basic feasible solution, canonical form.
- (Sec. 2.8) hyperplane, halfspace, line, line segment, convex, polyhedron, tight inequality, extreme point.
- (Sec. 3.1) dual LP, Weak duality theorem.

Review

1. Claim: Let A be a matrix with linearly independent rows and b be a vector. Let $P = \{x : Ax = b, x \ge \mathbb{O}\}$ and let $\bar{x} \in P$. Then \bar{x} is an extreme point of P if and only if \bar{x} is a basic feasible solution of Ax = b.

max
$$(c_1, c_2)x$$

s.t.
$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 1 \\ -1 & 0 \\ 0 & -1 \end{pmatrix} x \le \begin{pmatrix} 3 \\ 2 \\ 2 \\ 0 \\ 0 \end{pmatrix}. \tag{1}$$

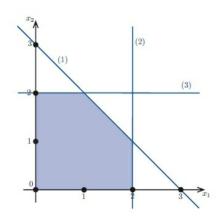
$$(2)$$

$$(3)$$

$$(4)$$

$$(6)$$

$$(5)$$



- 2. Find all extreme points.
- 3. Claim: For a polyhedron $P = \{x \in \mathbb{R}^n : Ax \leq b\}, x \in \mathbb{R}^n$, and $A^=x \leq b^=$ tight for \bar{x}, \bar{x} is an extreme point of P if and only if $rank(A^=) = n$.
- 4. Find all the basic feasible solutions for Ax = b in the example above.

Duality

5. Consider the LP: $\max\{c^T x : Ax \leq b, x \geq \mathbb{O}\}.$

$$A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \\ -1 & 1 \end{pmatrix} \quad b = \begin{pmatrix} 20 \\ 18 \\ 8 \end{pmatrix} \quad c = \begin{pmatrix} 2 \\ 3 \end{pmatrix}.$$

Find the dual. Find feasible solutions for the primal and dual. Use these to estimate the optimal value of the primal objective function.

6. What is the Weak Duality Theorem?

7. We will consider a shortest-path LP and investigate how the dual can be interpreted.