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LARSON—MATH 610—CLASSROOM WORKSHEET 21
Linear Transformations.

Concepts & Notation

- (Sec. 3.1) *linear transformation, range, rank, null space, nullity.*
- (Sec. 3.2) $L(V, W)$, *linear operator, invertible linear transformation, non-singular linear transformation.*
- (Sec. 3.3) *isomorphism.*
- (Sec. 3.4) *matrix of T relative to (ordered) bases*

Review

1. (**Claim:**) If V and W are finite-dimensional vector spaces over a field \mathbb{F} with $\dim V = \dim W$, and $T : V \rightarrow W$ is a linear transformation then the following are equivalent:
 - (a) T is invertible,
 - (b) T is non-singular,
 - (c) T is onto (that is, the range of T is W).

New

2. If $T : V \rightarrow W$ is a linear transformation, when is T an *isomorphism* of V onto W ? (If T is an isomorphism we say that vector spaces V and W are *isomorphic*).

3. If T an *isomorphism* of a vector space V onto a vector space W , why is T invertible and non-singular?

4. (**Claim:**) Every n -dimensional vector space over a field \mathbb{F} is isomorphic to \mathbb{F}^n .

5. (**Claim:**) Every linear transformation T from an n -dimensional vector space V to an m -dimensional vector space W can be represented by a matrix A (with respect to specific bases for V and W ; in particular, different bases yield different A 's).

6. (**Example:**) Let T be the linear transformation from \mathbb{R}^2 to \mathbb{R}^3 defined by $T(x_1, x_2) = (x_1, x_2, x_3)$. $\mathcal{B} = \{(1, 0), (0, 1)\}$ is a basis for \mathbb{R}^2 and $\mathcal{B}' = \{(1, 1, 0), (0, 1, 0), (0, 0, 1)\}$ is a basis for \mathbb{R}^3 . Find a 3×2 matrix A (with respect to these bases so that, for every $\alpha \in \mathbb{R}^2$, we have:

$$[T(\alpha)]_{\mathcal{B}'} = A[\alpha]_{\mathcal{B}}.$$