LARSON—MATH 511—CLASSROOM WORKSHEET 26 Low-Rank and Other Matrix Updates

Sage/CoCalc

- 1. (a) Start the Chrome browser.
 - (b) Go to http://cocalc.com
 - (c) Login (likely using your VCU email address).
 - (d) You should see an existing Project for our class. Click on that.
 - (e) Click "New", then "Sage Worksheet", then call it c26.

Least Squares Update Example

2. We will talk through the example in "least_squares_updated.sage" in your CoCalc project Handouts folder.

Here is the mathematical background from last class:

Suppose we have m data points (each with k features):

$$(A_{1,1}, A_{1,2}, \dots, A_{1,k}, b_1)$$
 $(A_{2,1}, A_{2,2}, \dots, A_{2,k}, b_2)$
 \dots
 $(A_{m,1}, A_{m,2}, \dots, A_{m,k}, b_m)$

and we have already found the least-squares solution \hat{c} to $f(x) = c_1x_1 + c_2x_2 + \ldots + c_kx_k$, where:

$$f(A_{i,1}, A_{i,2}, \dots, A_{i,k}) = b_i$$

for i = 1, 2, ..., m, where $\hat{c} = (A^T A)^{-1} A^T \hat{b}$.

Suppose we then get a new data point:

$$(A_{m+1,1}, A_{m+1,2}, \dots, A_{m+1,k}, b_{m+1})$$

How can we use the Sherman-Morrison-Woodbury formula to efficiently update $(A^TA)^{-1}$ (for the *updated* data matrix A, given that we already know the $(A^TA)^{-1}$ from the original data points)?

We let \hat{r} be the column vector with entries, $A_{m+1,1}, A_{m+1,2}, \ldots, A_{m+1,k}$, the "new A" be $\begin{bmatrix} A \\ \hat{r}^T \end{bmatrix}$ and the "new \hat{b} " be $\begin{bmatrix} \hat{b} \\ b_{m+1} \end{bmatrix}$ and found that the new (updated) least-squares solution could be computed by finding:

$$(\left[A^T\hat{r}\right]\begin{bmatrix}A\\\hat{r}^T\end{bmatrix})^{-1} = (\left[A^TA + \hat{r}\hat{r}^T\right])^{-1}.$$

Then we applied the **Sherman-Morrison-Woodbury formula**:

$$(A - UV^{T})^{-1} = A^{-1} + A^{-1}U(I - V^{T}A^{-1}U)^{-1}V^{T}A^{-1}$$

We let \hat{r}^T be the new data row. Then $U = \hat{r}^T$ and $V = \hat{r}$.

The Derivative of A^{-1}

3. Let
$$A(t) = \begin{bmatrix} t & \frac{1}{t} \\ t^2 & t^2 + 1 \end{bmatrix}$$
. Find $A(1)$, $A(2)$.

- 4. Find $\frac{dA}{dt}$.
- 5. Let A = A(1) and B = A(2). Are they invertible?
- 6. Let $\Delta A = B A$. Find ΔA .
- 7. (A Very Useful Formula). Check: $B^{-1} A^{-1} = B^{-1}(A B)A^{-1}$.
- 8. Use this to find $\frac{\Delta A^{-1}}{\Delta t}$ and $\frac{dA^{-1}}{dt}$.

Interlacing Eigenvalues for Symmetric Matrices

- 9. (A Rayleigh-Ritz-type formula for symmetric matrices). Let S be a symmetric $n \times n$ matrix with (real) eigenvalues $\lambda_1 \geq \ldots \geq \lambda_q \geq \ldots \lambda_p \geq \ldots \geq \lambda_n$, and corresponding eigenvectors $\hat{u}_1, \ldots, \hat{u}_n$. If \hat{x} is a unit eigenvector in $Span(\{\hat{u}_p, \ldots, \hat{u}_q\})$ then $\lambda_p \leq \hat{u}^T S \hat{u} \leq \lambda_q$.
- 10. What are examples?
- 11. What is a *principal* submatrix of a A of a square matrix S?
- 12. (Cauchy's Interlacing Theorem) If A is a $(n-1) \times (n-1)$ principle submatrix of a symmetric matrix S with eigenvalues $\mu_1 \geq \ldots \geq \mu_{n-1}$ then $\lambda_1 \geq \mu_1 \geq \lambda_2 \geq \mu_2 \geq \ldots \geq \mu_{n-1} \geq \lambda_n$.

Getting your classwork recorded

When you are done, before you leave class...

- 1. Click the "Make pdf" (Adobe symbol) icon and make a pdf of this worksheet. (If CoCalc hangs, click the printer icon, then "Open", then print or make a pdf using your browser).
- 2. Send me an email with an informative header like "Math 511—c26 worksheet attached" (so that it will be properly recorded).
- 3. Remember to attach today's classroom worksheet!