

Superior Clamping and Gripping



Product Information

Anti-collision and overload protection sensor OPR 061

Compliant. Highly responsive. Automatic reset. Collision and overload sensor OPR

Collision and overload protection with automatic reset for protecting robots and handling units against damage resulting from collisions or overload conditions.

Field of application

Standard solution for all robot applications whereby the robot, the tool or the workpiece are to be protected against greater damages in case of a collision.



Advantages - Your benefits

Automatic reset for faster production restart after a collision

Triggering force and torque can be adjusted via the operating pressure for optimal protection of your robots and components

Integrated monitoring for signal transmission without delay in case of collisions so that the robot can be stopped immediately

ISO adapter plates as an option for easy assembly to most of robot types without any manufacturing costs/work

On option also with integrated springs for maintaining the position in the event of pressure loss

Mechanical flexibility in the event of collisions for compensation of the robot's reaction pathway in the event of a collision or overload







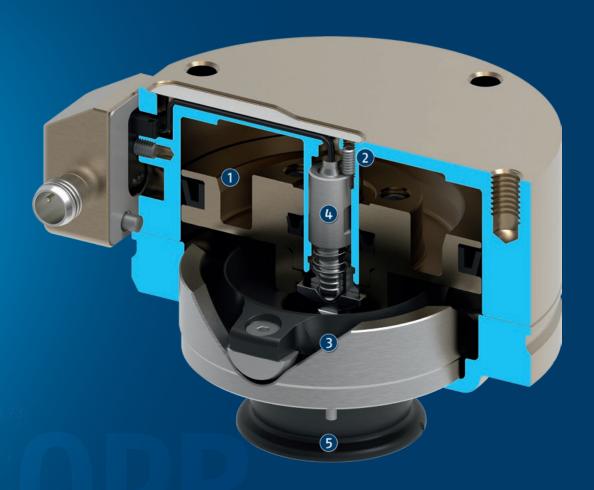




Functional description

In case of a collision, the mounting flange will be deflected. This simultaneously actuates a sensor whose signal triggers the system's emergency stop mechanism. The OPR automatically returns to zero position when the

gripper moves away from the collision object. Production can continue immediately as manual resetting is not necessary.



- Pneumatic pistons for easy responsiveness by pressure
- ② Adjustment screw for adjusting the switching point

- 3 Bearing for absorption of high forces and moments
- Monitoring via mechanical switch
- (5) **Mounting flange** deflects in the event of a collision

General notes about the series

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Operating principle: integrated cylinder pistons

Splash water protection: Optional

Scope of delivery: Angular plug with 5 m cable and open wire strand, operating and maintenance instructions, manufacturer's declaration

Warranty: 24 months

Harsh environmental conditions: Please note that use under harsh environmental conditions (e.g. in the coolant area, cast and grinding dust) can considerably reduce the service life of the units, and we will not take over any warranty. However, in many cases we can find a solution. Please contact us for assistance.

Application example

Triple transfer unit for packaging with small boxboards

- 1 2-finger angular gripper SWG
- 2 Collision sensor OPR



SCHUNK offers more ...

The following components make the product OPR even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.











Quick change system

Manual change system

Rotary feed-through

Universal gripper





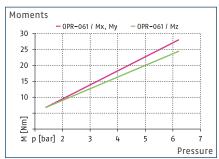
Angular gripper

Universal gripper

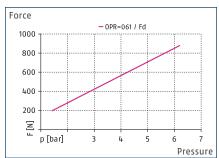
① For more information on these products can be found on the following product pages or at schunk.com. Please contact us: SCHUNK technical hotline +49-7133-103-2696



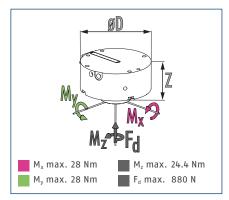
Triggering torque Mx, My, Mz



Triggering force F^d



Dimensions and maximum loads

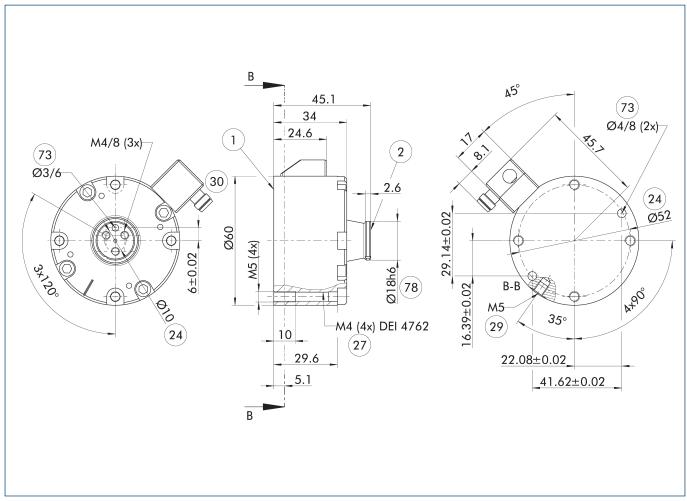


The design of a collision sensor is defined by the occuring forces and moments in your application.

Technical data

Description		OPR-061-P00	OPR-061-P05	OPR-061-P10	OPR-061-P15
ID		0321361	0321362	0321363	0321364
Axial deflection	[mm]	5.6	5.6	5.6	5.6
Angular deflection	[°]	±11	±11	±11	±11
Deflection rotatory	[°]	±20	±20	±20	±20
Min. triggering moment, angular M_x , M_y	[Nm]	6.8	8.6	10.3	12.1
Min. triggering torque, rotatory M _z	[Nm]	6.8	8.5	10.1	11.8
Spring triggering force	[N]		48	96	144
Spring release torque, angular	[Nm]		1.8	3.5	5.3
Spring release torque, rotatory	[Nm]		1.7	3.3	5
Supply voltage	[V]	10/30	10/30	10/30	10/30
Repeat accuracy	[mm]	±0.025	±0.025	±0.025	±0.025
Responsiveness	[mm]	0.5	0.5	0.5	0.5
Repeat accuracy, rotary	[min]	5	5	5	5
Min./nom./max. operating pressure	[bar]	1.4/-/6.2	1.4/-/5.9	1.4/-/5.5	1.4/-/5.2
Weight	[kg]	0.32	0.33	0.33	0.33
Min./max. ambient temperature	[°C]	5/60	5/60	5/60	5/60
Dimensions Ø D x Z	[mm]	60 x 45.1	60 x 45.1	60 x 45.1	60 x 45.1
Options and their characteristics					
Splash-proof version		OPR-061-P00-S	OPR-061-P05-S	OPR-061-P10-S	OPR-061-P15-S
ID		0321365	0321366	0321367	0321368
IP protection class		65	65	65	65

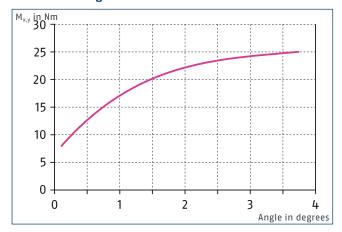
Main view



The main view shows the unit in its basic version.

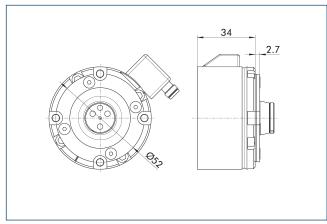
- 1 Robot-side connection
- 2 Tool-side connection
- 24 Bolt circle
- (27) Through holes for screw connections
- 29 Air connection P
- 30 Cable connector in enclosed pack with 5 m connection cable
- (73) Fit for centering pins
- 78 Fit for centering

Moment loading



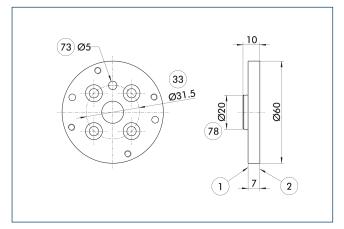
The diagram shows the angular deflection of the OPR according to the moment $M_{x,\,My}$ with maximum permissible operating pressure.

Splash-proof version



When using the splash water protection version, please be aware of the differences compared to the basic version.

Adapter plate ISO 9409-A31.5-R

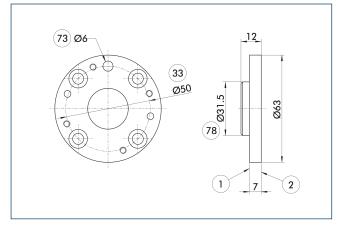


- 1 Robot-side connection
- (2) Tool-side connection
- 33) DIN ISO-9409 bolt circle
- 73 Fit for centering pins
- 78 Fit for centering

Robot–side adapter plate to mount the OPR to a mounting pattern according to ISO 9409-31.5-4-M5.

Description	ID
Robot side	
A-OPR-061-ISO-A31-R	0321369

Adapter plate ISO 9409-A50-R

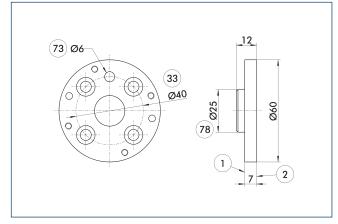


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- (73) Fit for centering pins
- (78) Fit for centering

Robot–side adapter plate to mount the OPR to a mounting pattern accoording to ISO 9409–50–4–M6.

Description	ID
Robot side	
A-0PR-061-IS0-A50-R	0321371

Adapter plate ISO 9409-A40-R



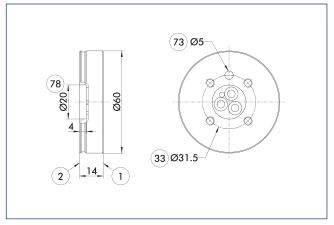
- 1 Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 73 Fit for centering pins
- 78 Fit for centering

Robot-side adapter plate for direct attachment of the OPR to an ISO

Description	ID
Robot side	
A-OPR-061-ISO-A40-R	0321370

Adapter plate ISO-9409-A31.5-T

9409-40-4-M6-compliant flange pattern.

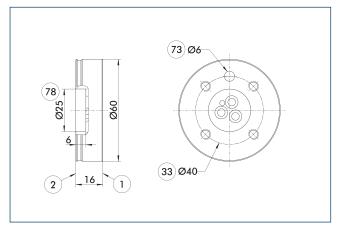


- (1) Robot-side connection
- (73) Fit for centering pins
- 2 Tool-side connection
- (78) Fit for centering
- 33 DIN ISO-9409 bolt circle

Tool-side adapter plate with ISO 9409 screw connection pattern.

Description	ID	
Tool side		
A-OPR-061-ISO-A31-T	0321372	

Adapter plate ISO 9409-A40-T

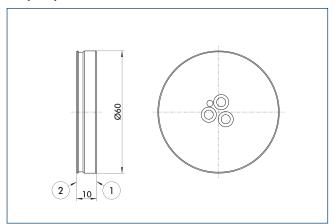


- 1 Robot-side connection
- 2 Tool-side connection
- 33) DIN ISO-9409 bolt circle
- 73 Fit for centering pins
- 78 Fit for centering

Tool-side adapter plate with ISO 9409 screw connection pattern.

Description	ID
Tool side	
A-OPR-061-ISO-A40-T	0321373

Adapter plate BLANK-T

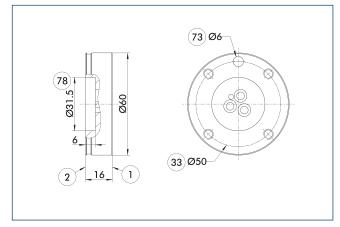


- (1) Robot-side connection
- 2 Tool-side connection

Unfinished tool-side adapter to be machined by the customer.

Description	ID	
Tool side		
A-OPR-061-BLANK-T	0321375	

Adapter plate ISO 9409-A50-T

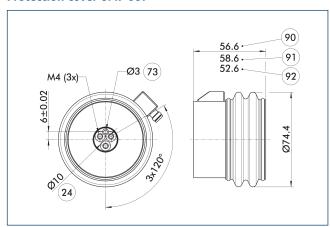


- 1 Robot-side connection
- 73 Fit for centering pins
- 2 Tool-side connection
- 78) Fit for centering
- 33 DIN ISO-9409 bolt circle

Tool-side adapter plate with ISO 9409 screw connection pattern.

Description	ID
Tool side	
A-OPR-061-ISO-A50-T	0321374

Protection cover OPR-061



- 24) Bolt circle
- 73) Fit for centering pins
- Total height with adapter plate with flange pattern according to ISO 9409-A31.5
- (91) Total height with adapter plate with flange pattern according to ISO 9409-A40/A50
- 92 Total height with adapter plate without flange pattern

The protection boot protects the OPR against coolants for use up to IP 65.

Description	ID	IP protection class
Protection cover		
OPR-061 Flexboot	0321376	65

Please note that when using the protection boot a tool side adapter
plate is also needed.

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