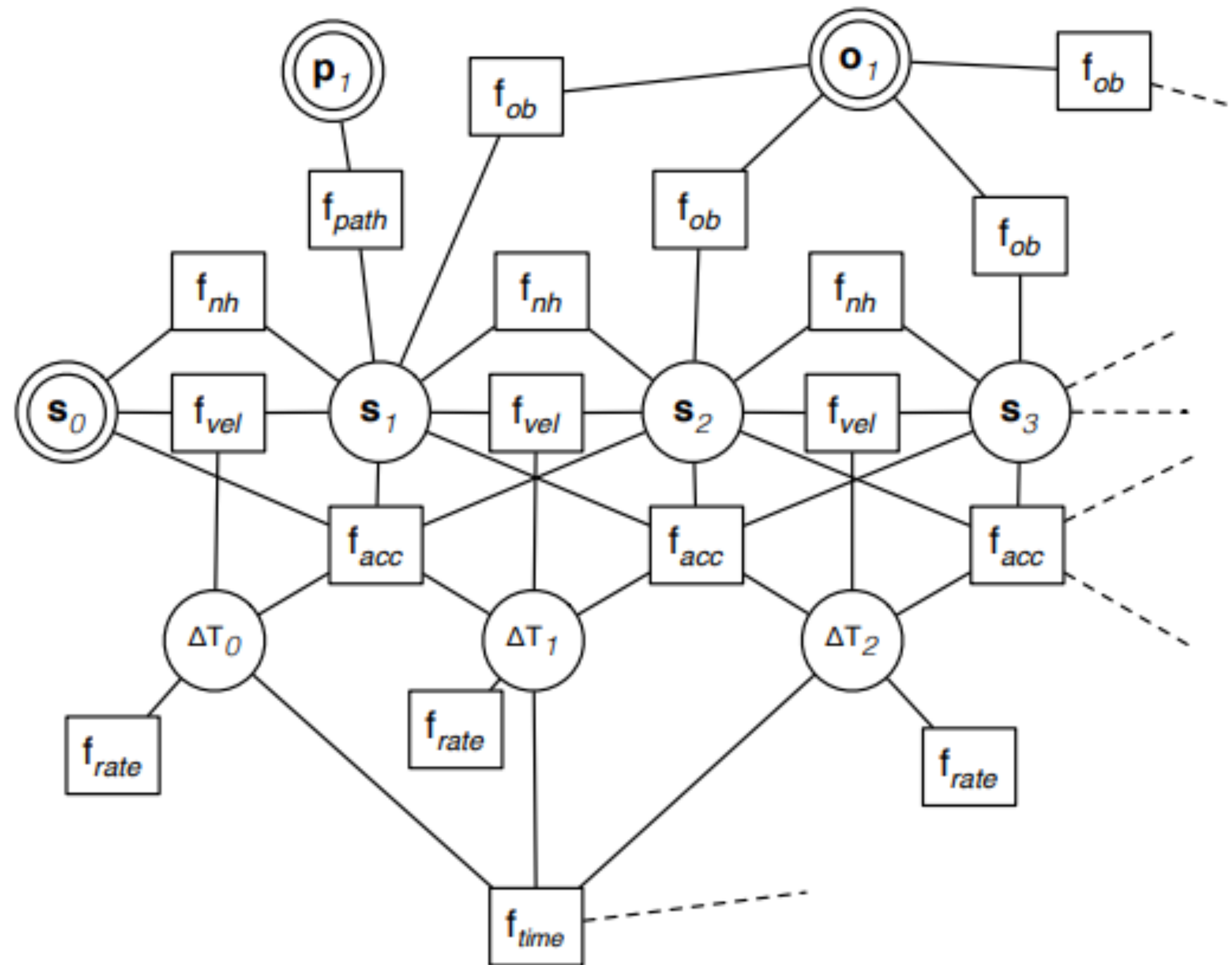


轨迹规划



对偶