

Inverse Problems meets Statistical Learning

Gabriel Peyré



www.numerical-tours.com





Mathematical Coffees

Huawei-FSMP joint seminars

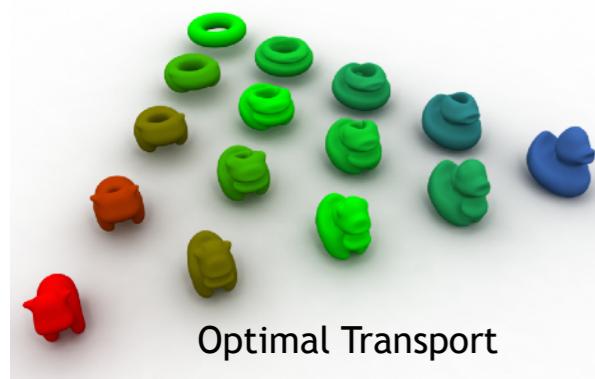
<https://mathematical-coffees.github.io>



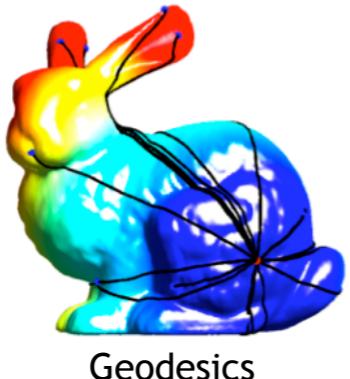
FSMP

Fondation Sciences
Mathématiques de Paris

Organized by: Mérouane Debbah & Gabriel Peyré



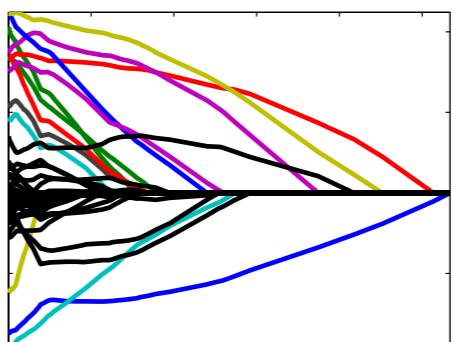
Optimal Transport



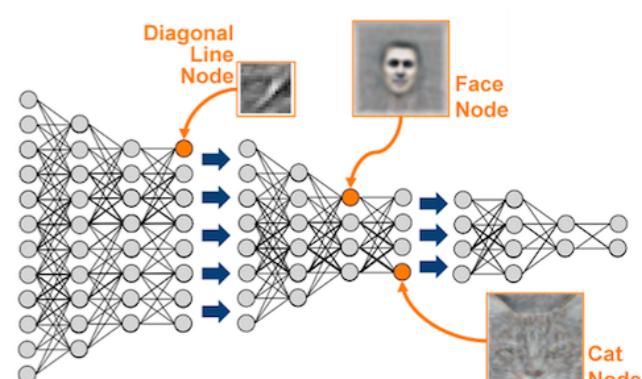
Geodesics



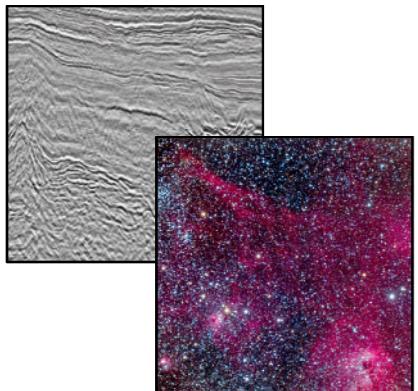
Mesches



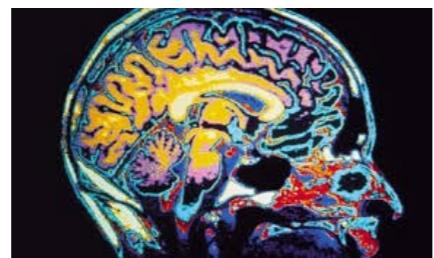
Optimization



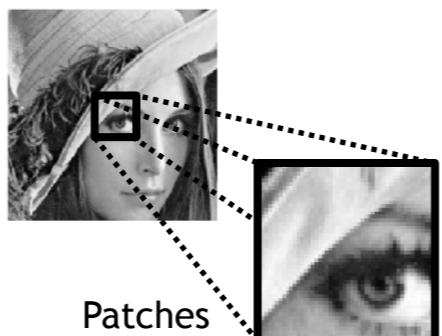
Deep Learning



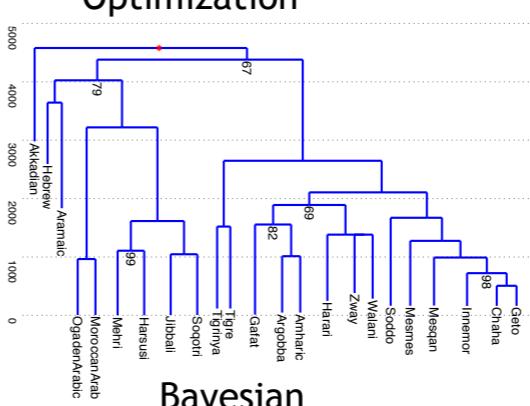
Sparsity



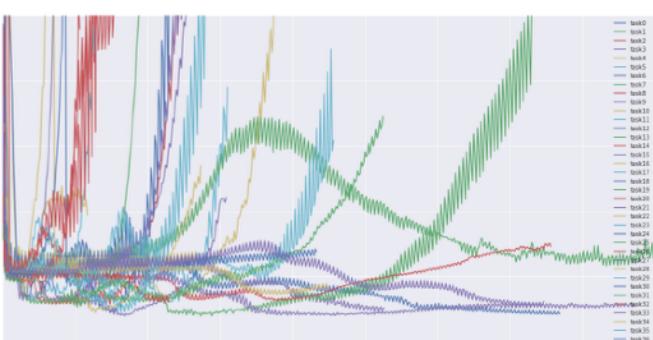
Neuro-imaging



Patches



Bayesian



Parallel/Stochastic

Alexandre Allauzen, Paris-Sud.
Pierre Alliez, INRIA.
Guillaume Charpiat, INRIA.
Emilie Chouzenoux, Paris-Est.

Nicolas Courty, IRISA.
Laurent Cohen, CNRS Dauphine.
Marco Cuturi, ENSAE.
Julie Delon, Paris 5.

Fabian Pedregosa, INRIA.
Guillaume Lecué, CNRS ENSAE
Julien Tierny, CNRS and P6.
Robin Ryder, Paris-Dauphine.
Gael Varoquaux, INRIA.

Jalal Fadili, ENSICAEN.
Alexandre Gramfort, INRIA.
Matthieu Kowalski, Supelec.
Jean-Marie Mirebeau, CNRS, P-Sud.



Inverse Problems

Forward model:

Observations

$$y = A f + w \in \mathbb{R}^m$$

Operator

$$A \in \mathbb{R}^{m \times p} : \mathbb{R}^p \rightarrow \mathbb{R}^m$$

(Unknown)
Input

Noise

$$y = A f + w \in \mathbb{R}^m$$

Inverse Problems

Forward model:

$$y = A f + w \in \mathbb{R}^m$$

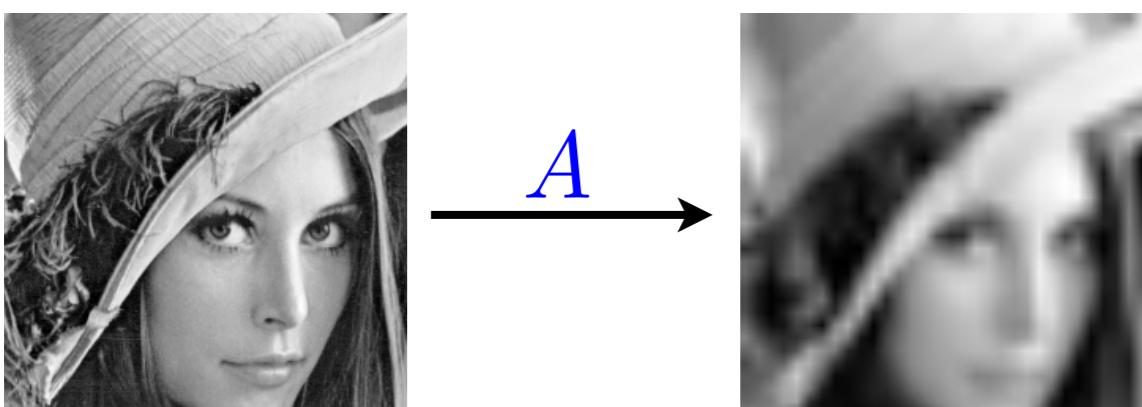
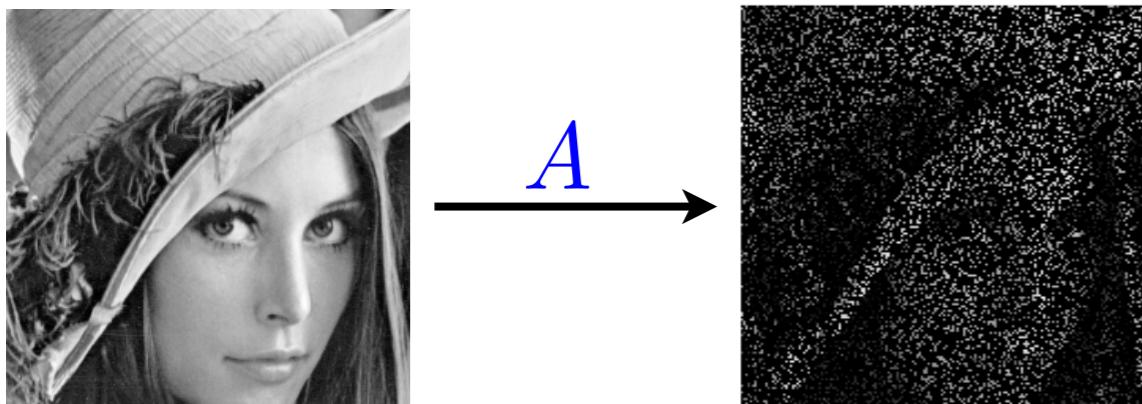
$A \in \mathbb{R}^{m \times p} : \mathbb{R}^p \rightarrow \mathbb{R}^m$

Observations Operator (Unknown) Input Noise

Denoising: $A = \text{Id}_p$, $m = p$

Inpainting: set Ω of available pixels, $m = |\Omega|$, $Af = (f_i)_{i \in \Omega}$

Super-resolution: $Af = (f \star k) \downarrow_\tau$, $m = p/\tau$.



Inverse Problems

Forward model:

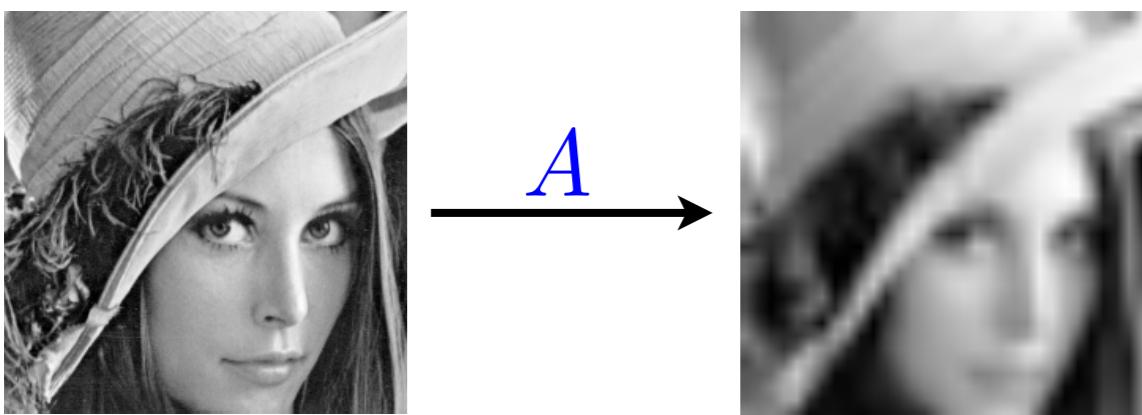
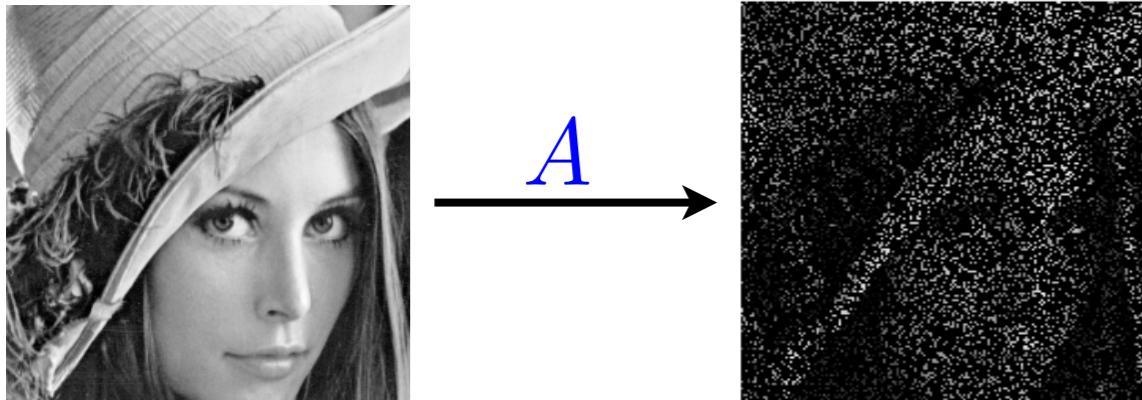
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Observations Operator (Unknown) Input
 $A \in \mathbb{R}^{m \times p} : \mathbb{R}^p \rightarrow \mathbb{R}^m$ Noise

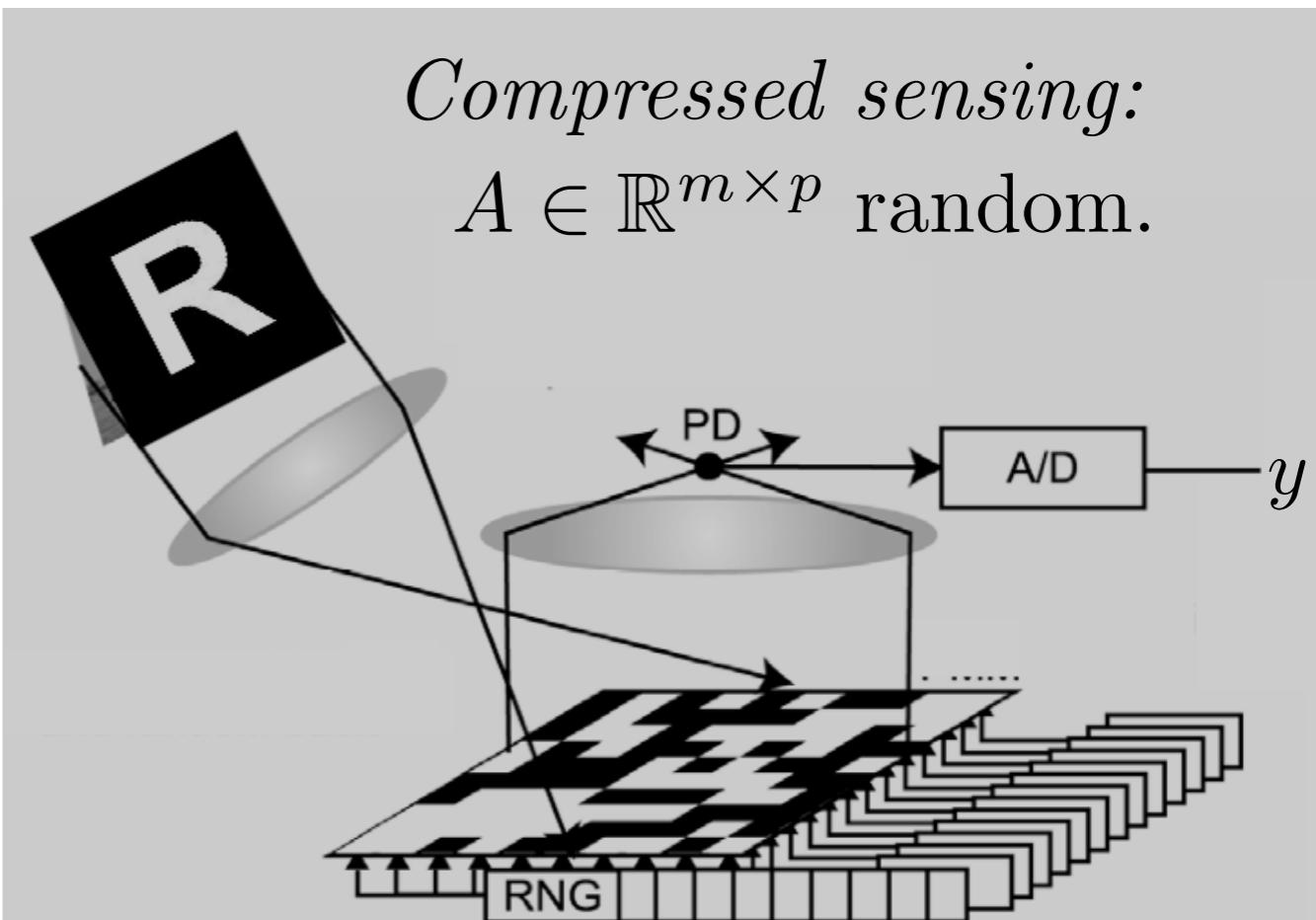
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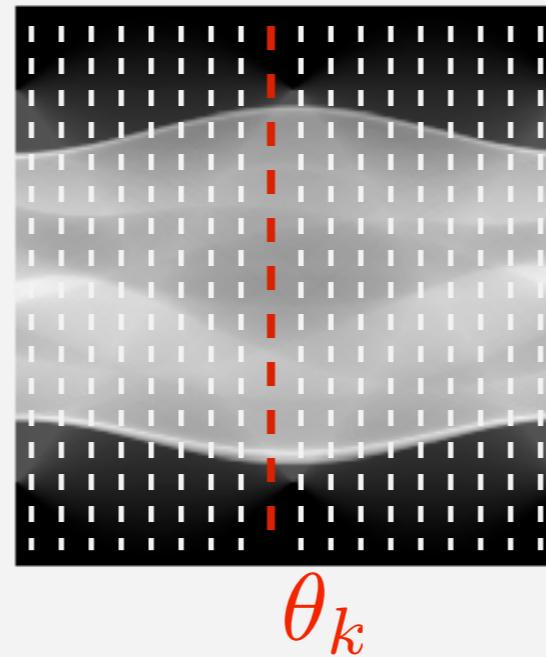
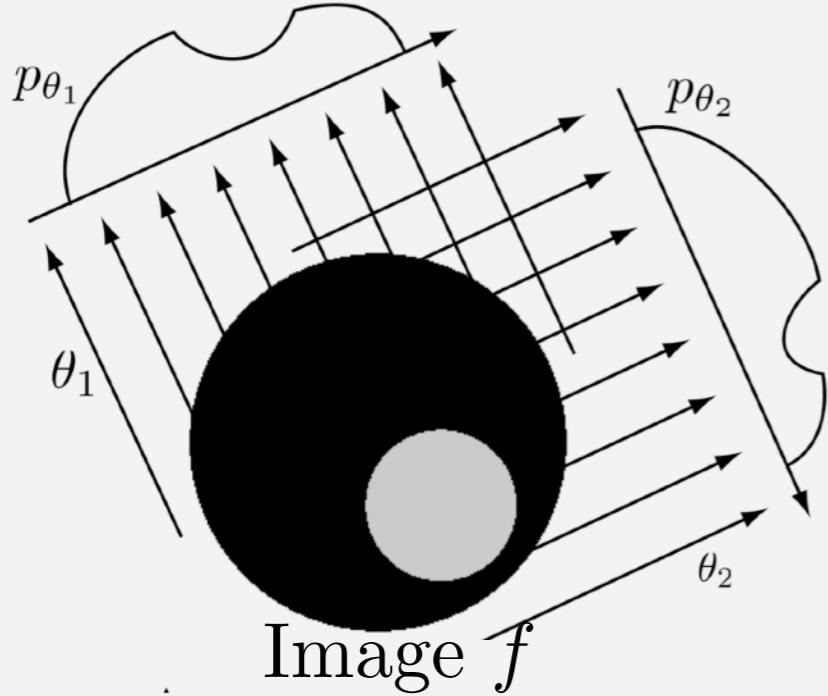
Compressed sensing:
 $A \in \mathbb{R}^{m \times p}$ random.



Inverse Problem in Medical Imaging

Tomography projection:

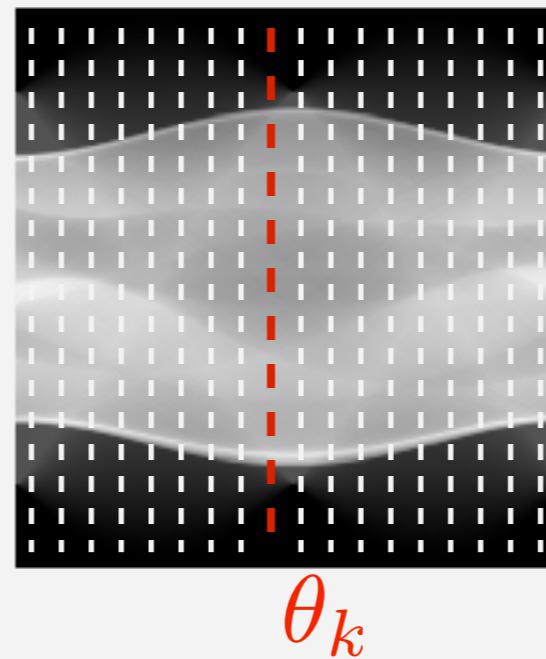
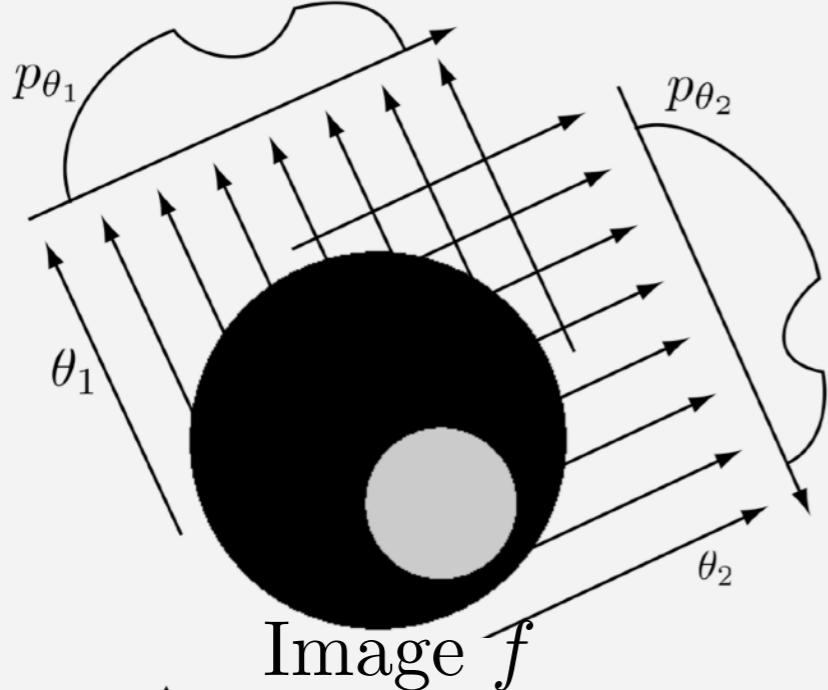
$$Af = (p_{\theta_k})_{k=1}^K$$



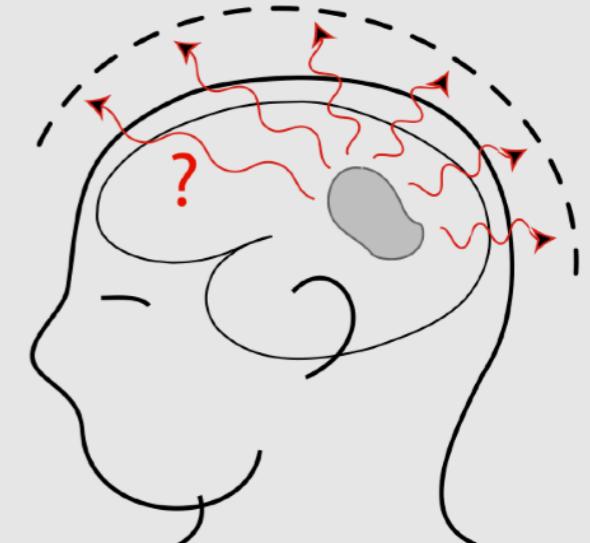
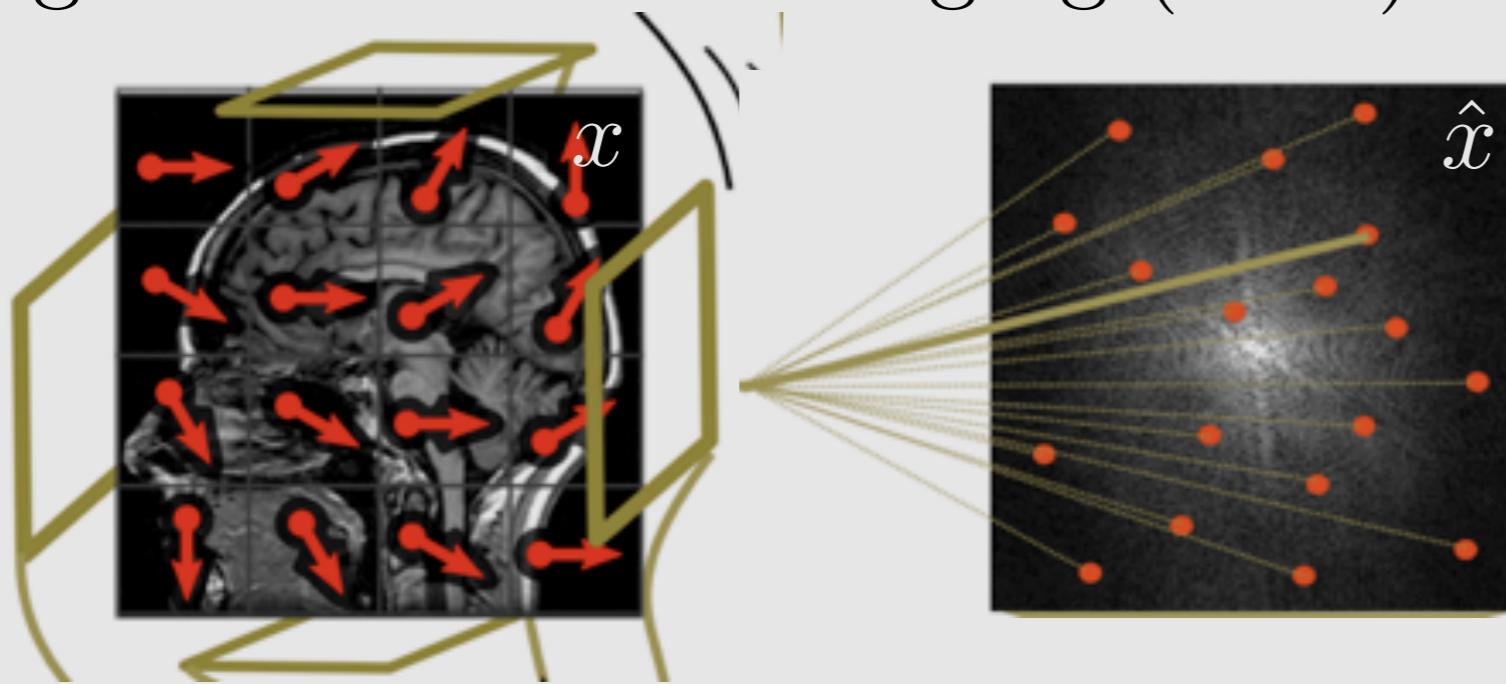
Inverse Problem in Medical Imaging

Tomography projection:

$$Af = (p_{\theta_k})_{k=1}^K$$



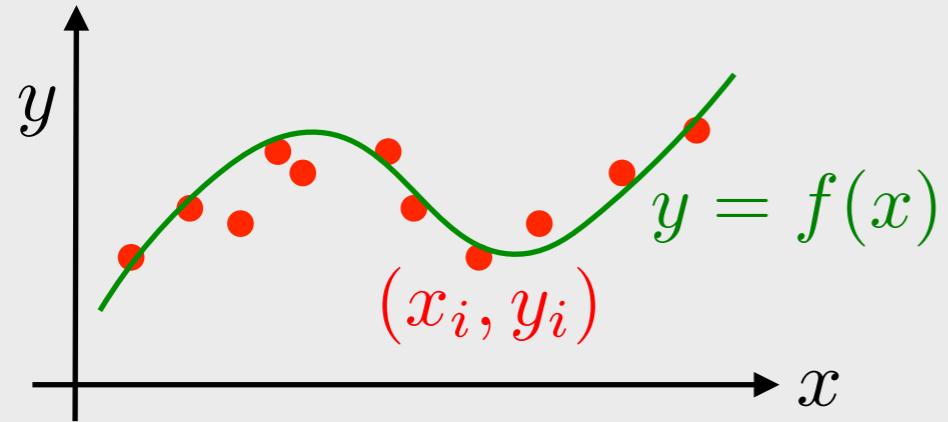
Magnetic resonance imaging (MRI): $Af = (\hat{f}(\omega))_{\omega \in \Omega}$



Other examples: MEG, EEG, ...

Regression in Statistical Learning

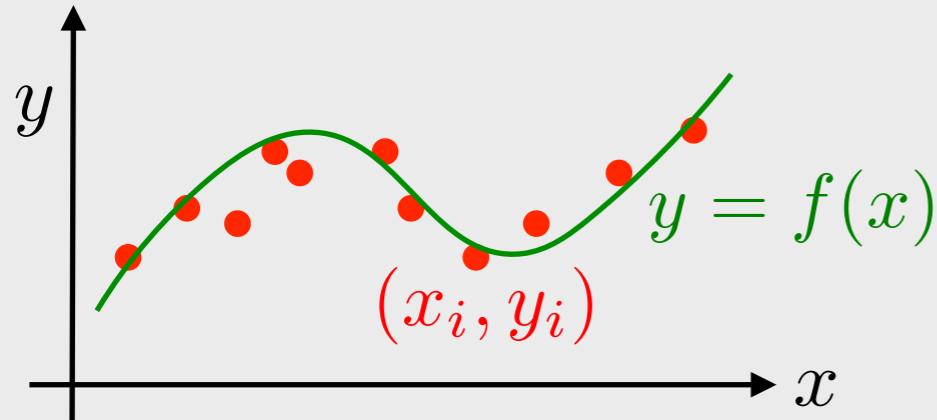
(Noisy) observations (x_i, y_j) , try to infer $y = f(x)$.



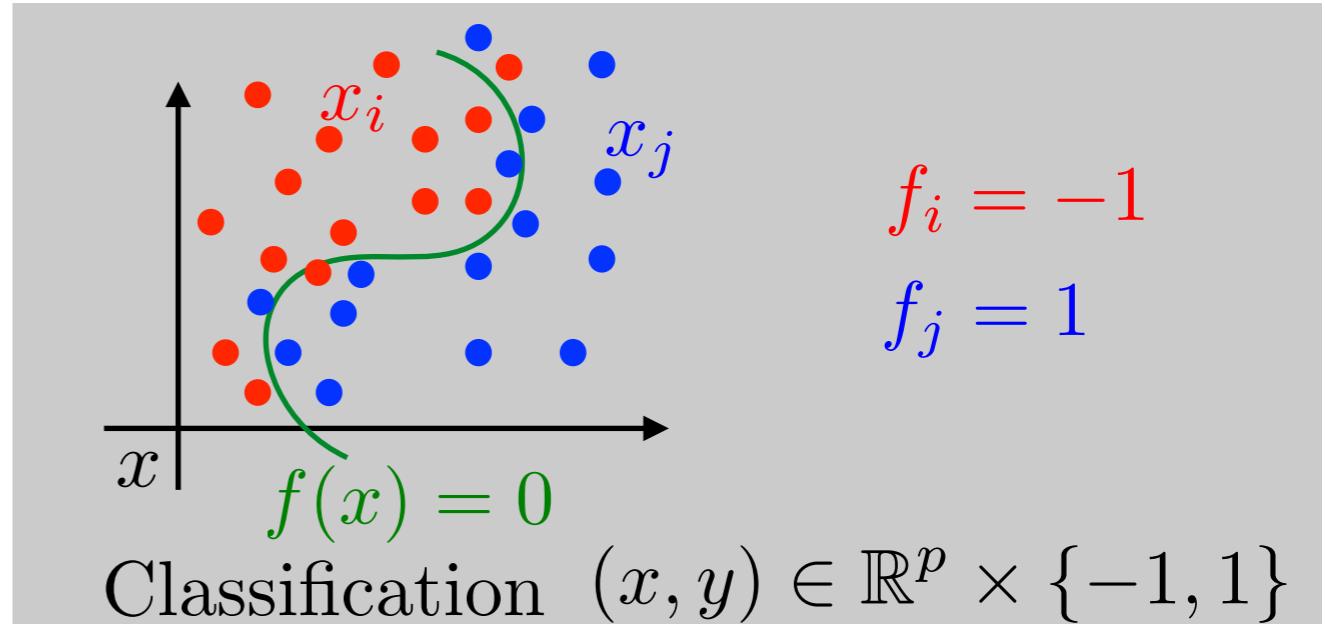
Regression $(x, y) \in \mathbb{R}^p \times \mathbb{R}$

Regression in Statistical Learning

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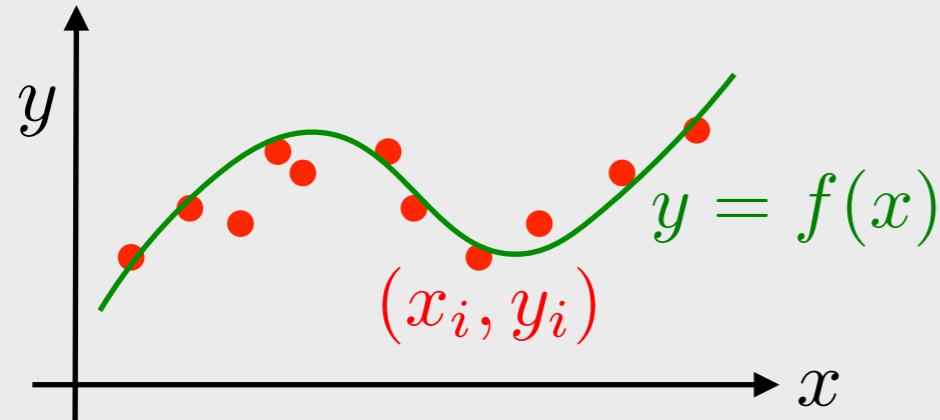
Regression $(x, y) \in \mathbb{R}^p \times \mathbb{R}$



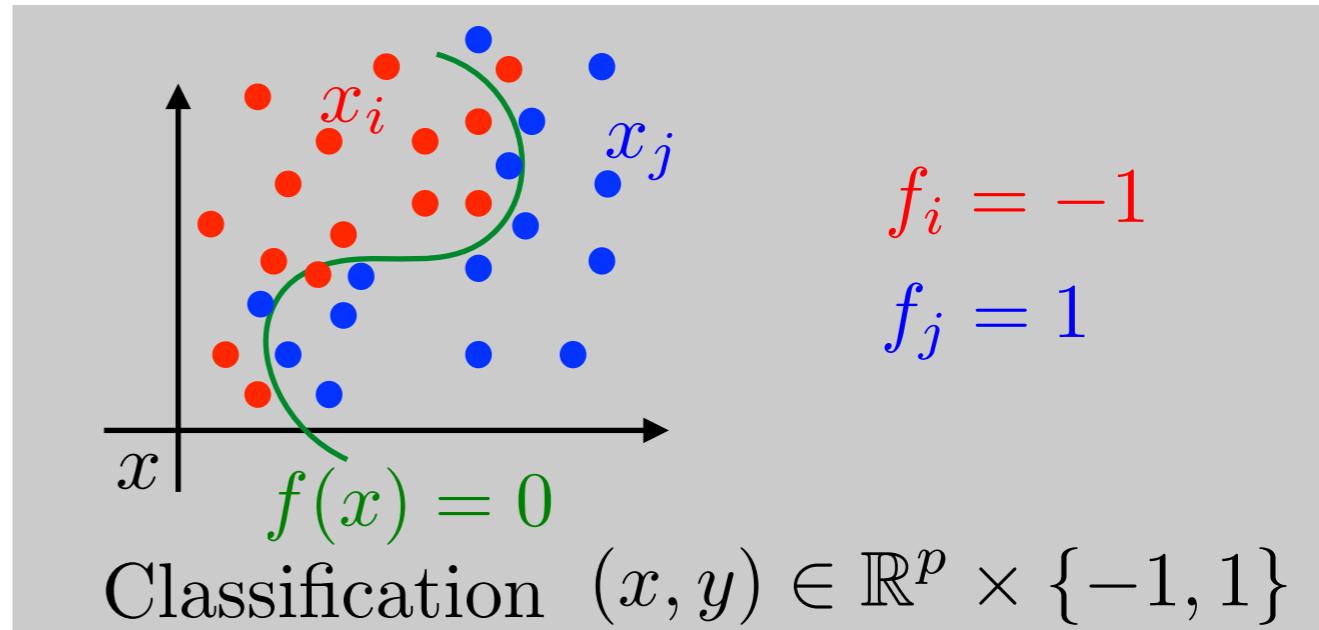
Classification $(x, y) \in \mathbb{R}^p \times \{-1, 1\}$

Regression in Statistical Learning

(Noisy) observations (x_i, y_j) , try to infer $y = f(x)$.

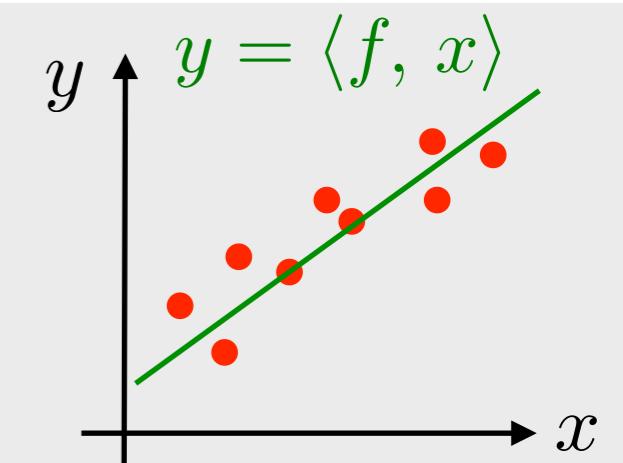


Regression $(x, y) \in \mathbb{R}^p \times \mathbb{R}$



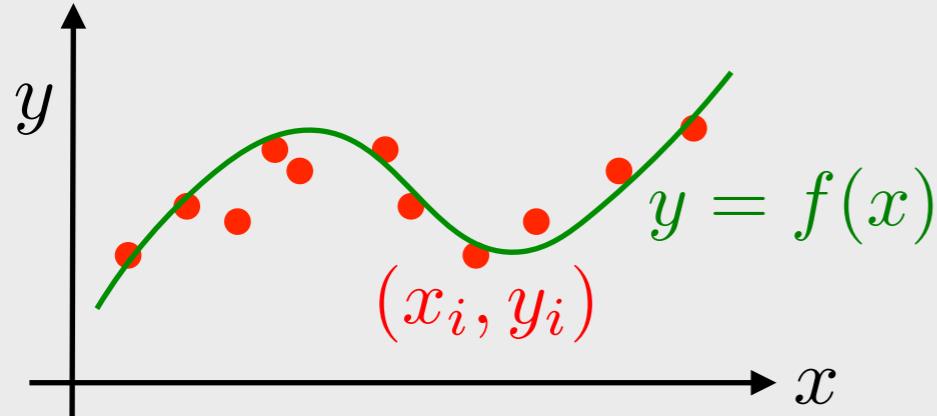
Classification $(x, y) \in \mathbb{R}^p \times \{-1, 1\}$

Linear models: $\forall i = 1, \dots, n, \quad y_i = \langle x_i, f \rangle + \begin{matrix} \text{noise} \\ \text{model error} \end{matrix}$

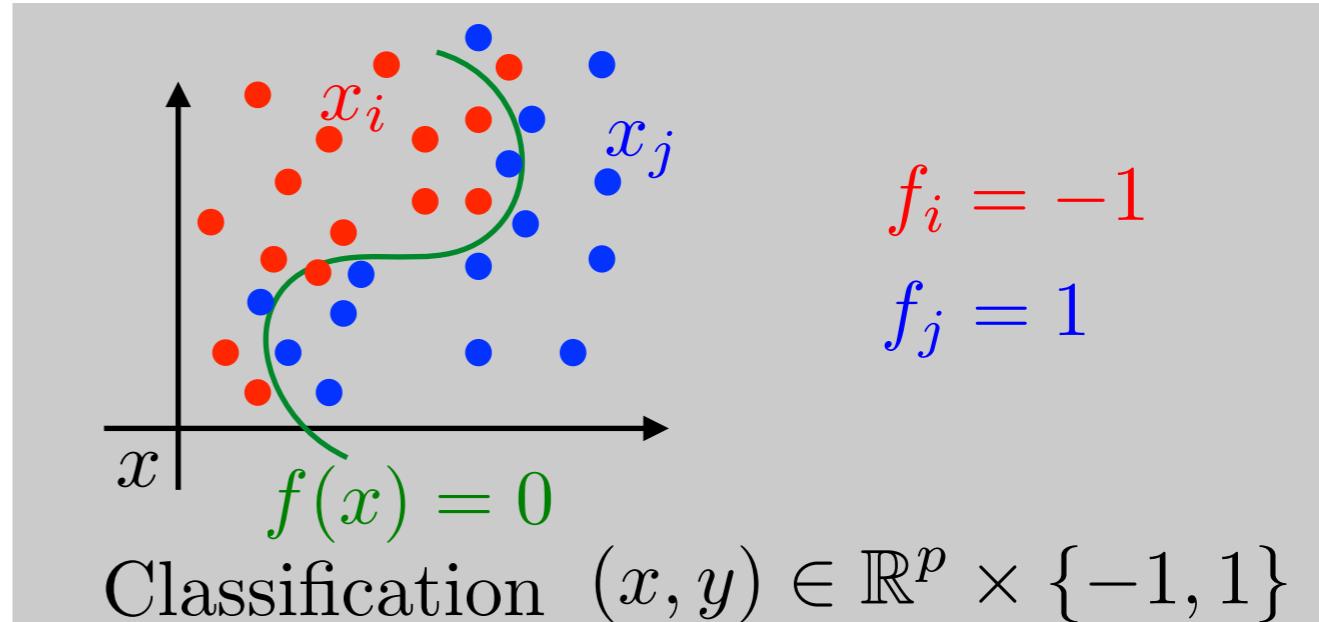


Regression in Statistical Learning

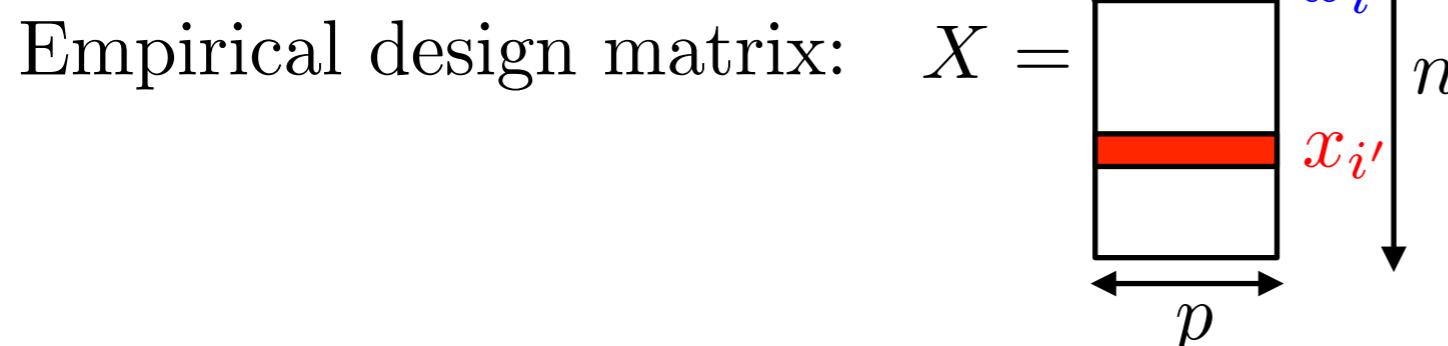
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Regression $(x, y) \in \mathbb{R}^p \times \mathbb{R}$

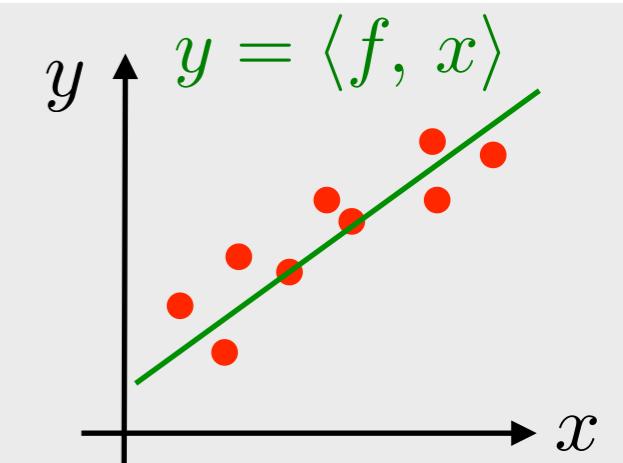


Linear models: $\forall i = 1, \dots, n, \quad y_i = \langle x_i, f \rangle + \varepsilon_i$
noise
model error



Model: $y = Xf + \varepsilon \in \mathbb{R}^n$

$$\begin{matrix} \textcolor{red}{y} \\ \end{matrix} = \begin{matrix} X \\ \end{matrix} \times \begin{matrix} f \\ \end{matrix}$$



Inverse Problems vs. Statistical Learning

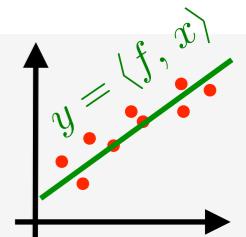
Inverse Problems

$$y = Af + w$$



Statistical Learning

$$y = Xf + \varepsilon$$



Inverse Problems vs. Statistical Learning

Inverse Problems

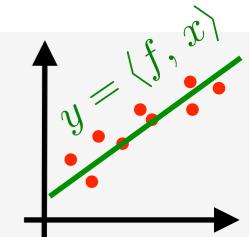
$$y = Af + w$$



$$\begin{aligned} A^\top y &= (A^\top A)f + A^\top w \\ \stackrel{\text{def.}}{=} u &\quad \stackrel{\text{def.}}{=} C \quad \stackrel{\text{def.}}{=} r \end{aligned}$$

Statistical Learning

$$y = Xf + \varepsilon$$



$$\begin{aligned} \frac{1}{n} X^\top y &= \frac{1}{n} (X^\top X)f + \frac{1}{n} X^\top \varepsilon \\ \stackrel{\text{def.}}{=} u_n &\quad \stackrel{\text{def.}}{=} C_n \quad \stackrel{\text{def.}}{=} r_n \end{aligned}$$

Inverse Problems vs. Statistical Learning

Inverse Problems

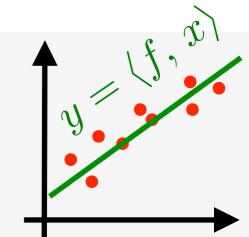
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Inverse Problems vs. Statistical Learning

Inverse Problems

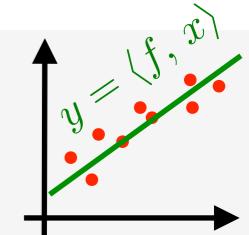
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$$\begin{array}{lcl} A^\top y & = & (A^\top A)f + A^\top w \\ \stackrel{\text{def.}}{=} \textcolor{green}{u} & \stackrel{\text{def.}}{=} & \textcolor{red}{C} \\ & & \stackrel{\text{def.}}{=} r \end{array}$$

Statistical Learning

$$y = Xf + \varepsilon$$



$$\begin{array}{lcl} \frac{1}{n} X^\top y & = & \frac{1}{n} (X^\top X)f + \frac{1}{n} X^\top \varepsilon \\ \stackrel{\text{def.}}{=} \textcolor{green}{u}_n & \stackrel{\text{def.}}{=} & \textcolor{red}{C}_n \\ & \downarrow & \downarrow \\ n \rightarrow +\infty & & (x_i, y_i)_i \text{ i.i.d.} \\ \textcolor{green}{u} = \mathbb{E}(yx) & & \textcolor{red}{C} = \mathbb{E}(xx^\top) \end{array}$$

Regularized inversion:

$$\min_f \frac{1}{2} \|Af - y\|^2 + \lambda \|f\|^2$$

$$f_\lambda = (\textcolor{red}{C} + \lambda \text{Id}_p)^{-1} \textcolor{green}{u}$$

Empirical risk minimization:

$$\min_f \frac{1}{2n} \|Xf - y\|^2 + \lambda \|f\|^2$$

$$f_{\lambda,n} = (\textcolor{red}{C}_n + \lambda \text{Id}_p)^{-1} \textcolor{green}{u}_n$$

Inverse Problems vs. Statistical Learning

Inverse Problems

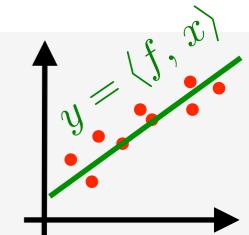
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Exact covariance $\textcolor{red}{C}$



Noisy covariance $\textcolor{red}{C}_n$

Deterministic bounded noise $\textcolor{blue}{r}$



Random noise $\textcolor{blue}{r}_n$

Noise level $\|r\|$



Noise level $\|r_n\| \sim n^{-\frac{1}{2}}$

Theory: Convergence Rates

Inverse Problems

$$y = Af_0 + w$$

Statistical Learning

$$y_i = \langle x_i, f \rangle + \varepsilon_i \quad \text{i.i.d.}$$

$$y = Xf_0 + \varepsilon$$

Theory: Convergence Rates

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Source condition: $\exists z, f_0 = \Phi^* z$

→ smoothness constraint.

→ $f_0 \perp \ker(\Phi)$

“no free lunch”

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“no free lunch”

Theorem: setting $\lambda \sim \|w\|$,

$$\|f_\lambda - f_0\| \sim \sqrt{\|w\|}$$

$$\|Af_\lambda - Af_0\| \sim \|w\|$$

Theory: Convergence Rates

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$$\|Af_\lambda - Af_0\| \sim \|w\|$$

Theorem: setting $\lambda \sim n^{-\frac{1}{2}}$,

$$\mathbb{E}(\|f_{\lambda,n} - f_0\|) \sim n^{-\frac{1}{4}}$$

$$\mathbb{E}(|\langle f - f_0, x \rangle|) \sim n^{-\frac{1}{2}}$$

Theory: Convergence Rates

Inverse Problems

$$y = Af_0 + w$$

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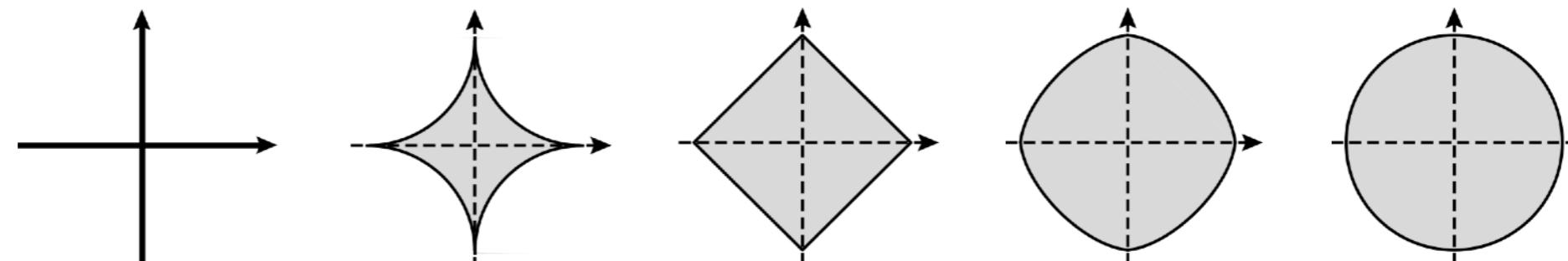
$$\mathbb{E}(\|f_{\lambda,n} - f_0\|) \sim n^{-\frac{1}{4}}$$

$$\mathbb{E}(|\langle f - f_0, x \rangle|) \sim n^{-\frac{1}{2}}$$

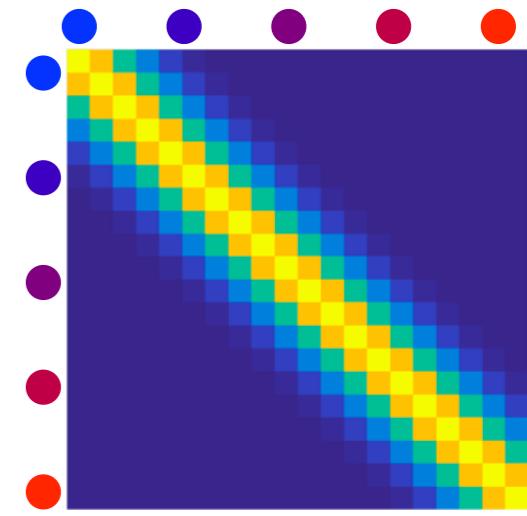
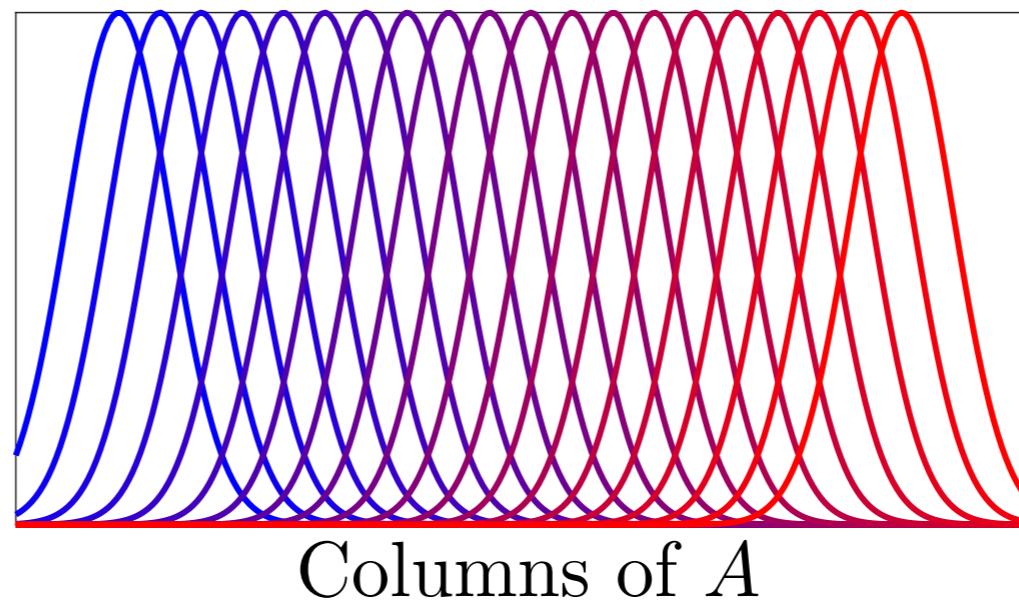
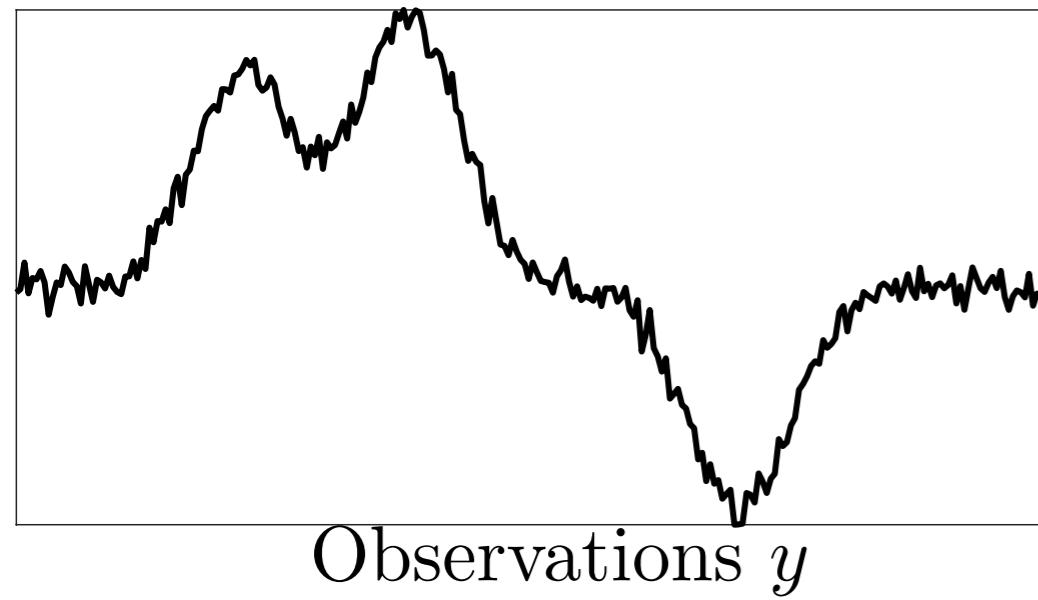
Faster $O(\|w\|, n^{-\frac{1}{2}})$ estimation rates

Super-resolution effect
(recover information in $\ker(\Phi)$)

Needs non-quadratic &
non-smooth regularization
(ℓ_1 , TV, trace norm, ...)

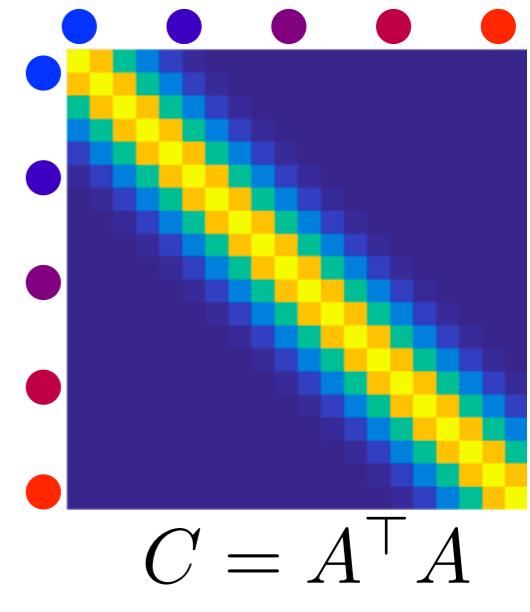
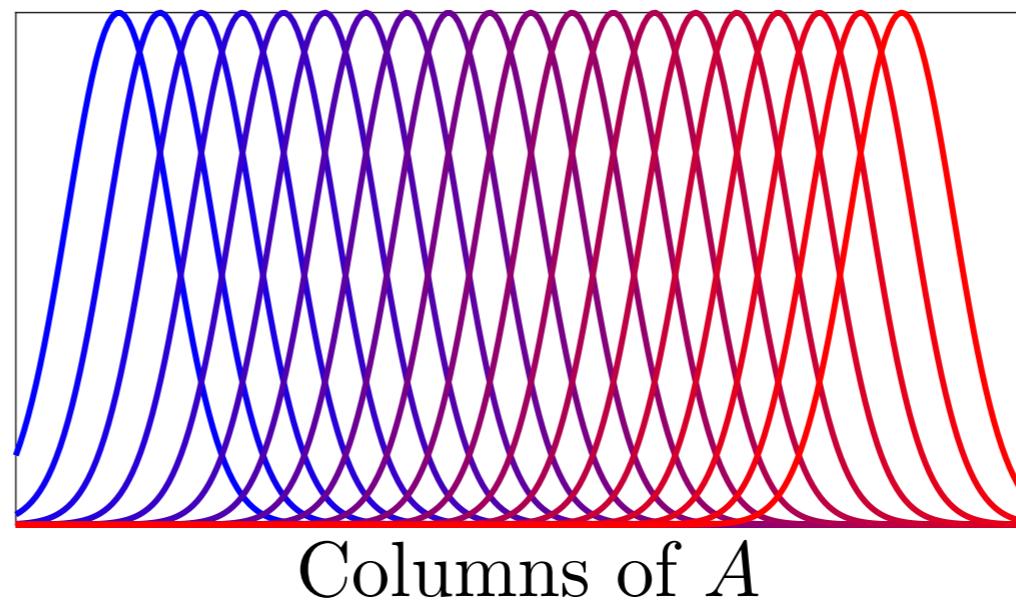
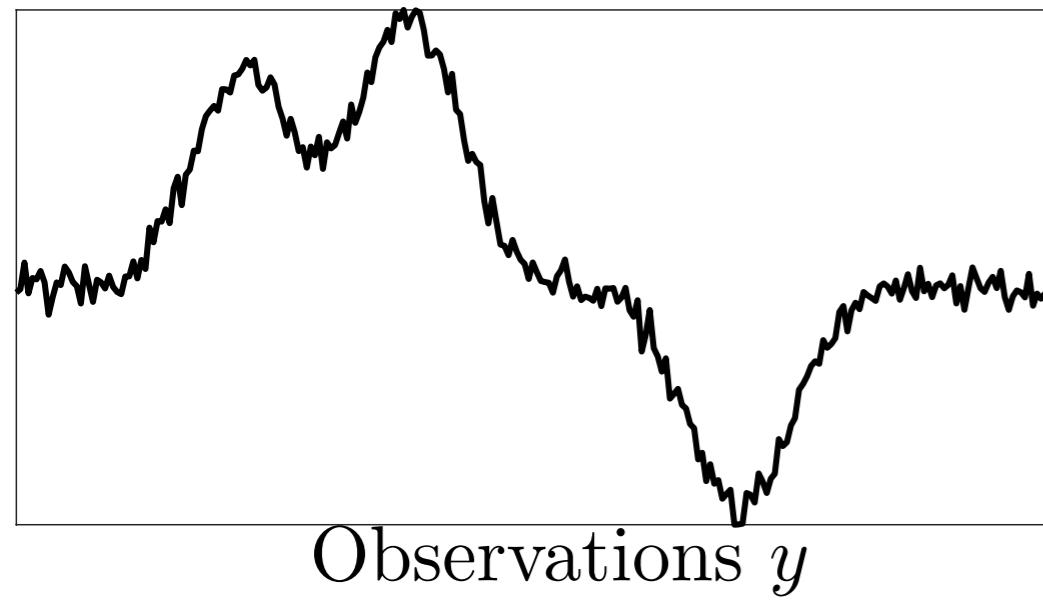


L2 vs. L1 Regularization



$$C = A^\top A$$

L2 vs. L1 Regularization

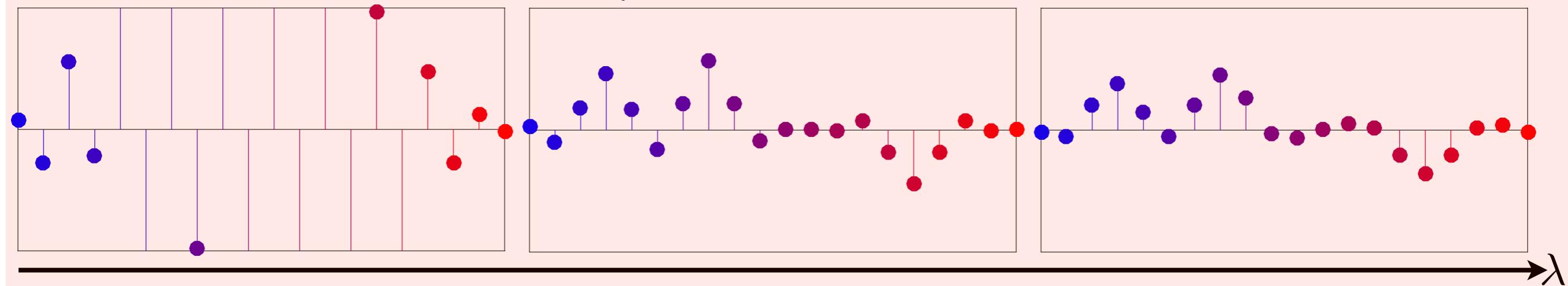


Observations y

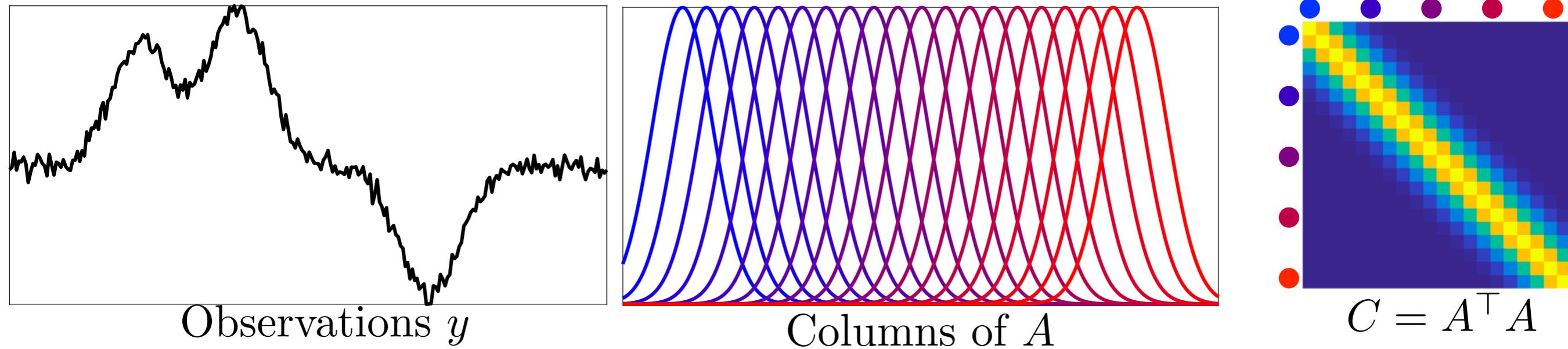
Columns of A

$$C = A^\top A$$

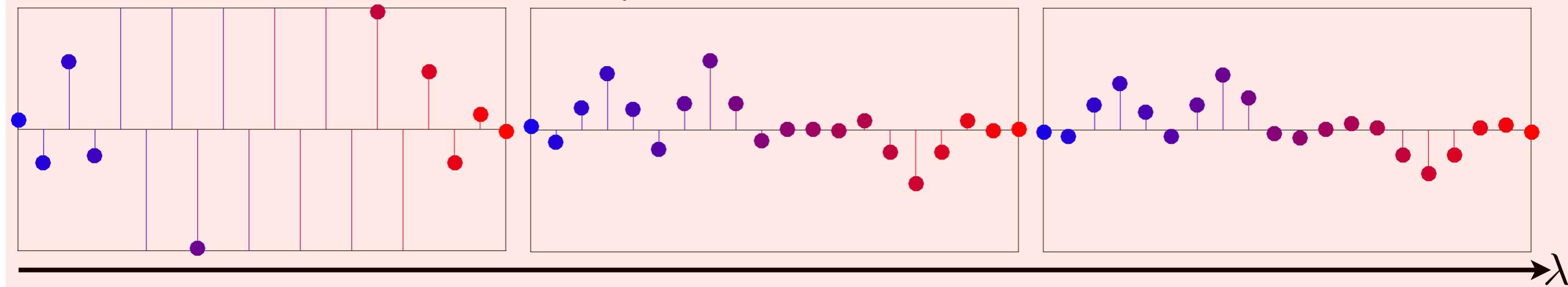
$$\min_f \|y - Af\|^2 + \lambda \|f\|_2^2$$



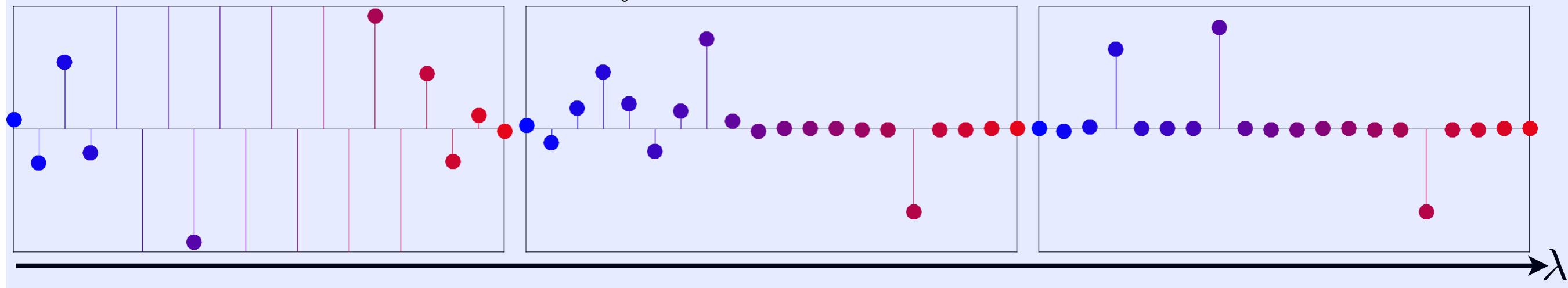
L2 vs. L1 Regularization



$$\min_f \|y - Af\|^2 + \lambda \|f\|_2^2$$

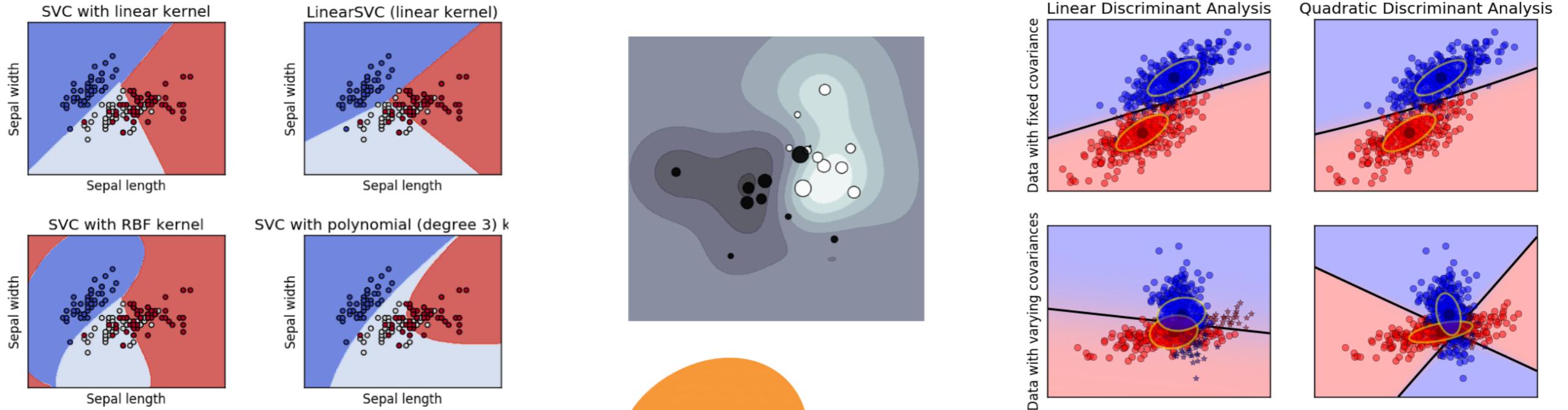


$$\min_f \|y - Af\|^2 + \lambda \|f\|_1$$



What's Next

Alexandre Gramfort: ML for classification.



Gael Varoquaux:

