

# Fast Approximations of High-Rank Hessians: Applications to Seismic Inversion and Uncertainty Quantification

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IMAGE24 - W-7: Exposing our Errors

Houston, TX

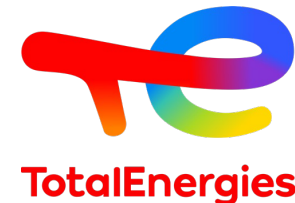
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The University of Texas at Austin

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**OPTIMUS**  
BEYOND FORWARD SIMULATION

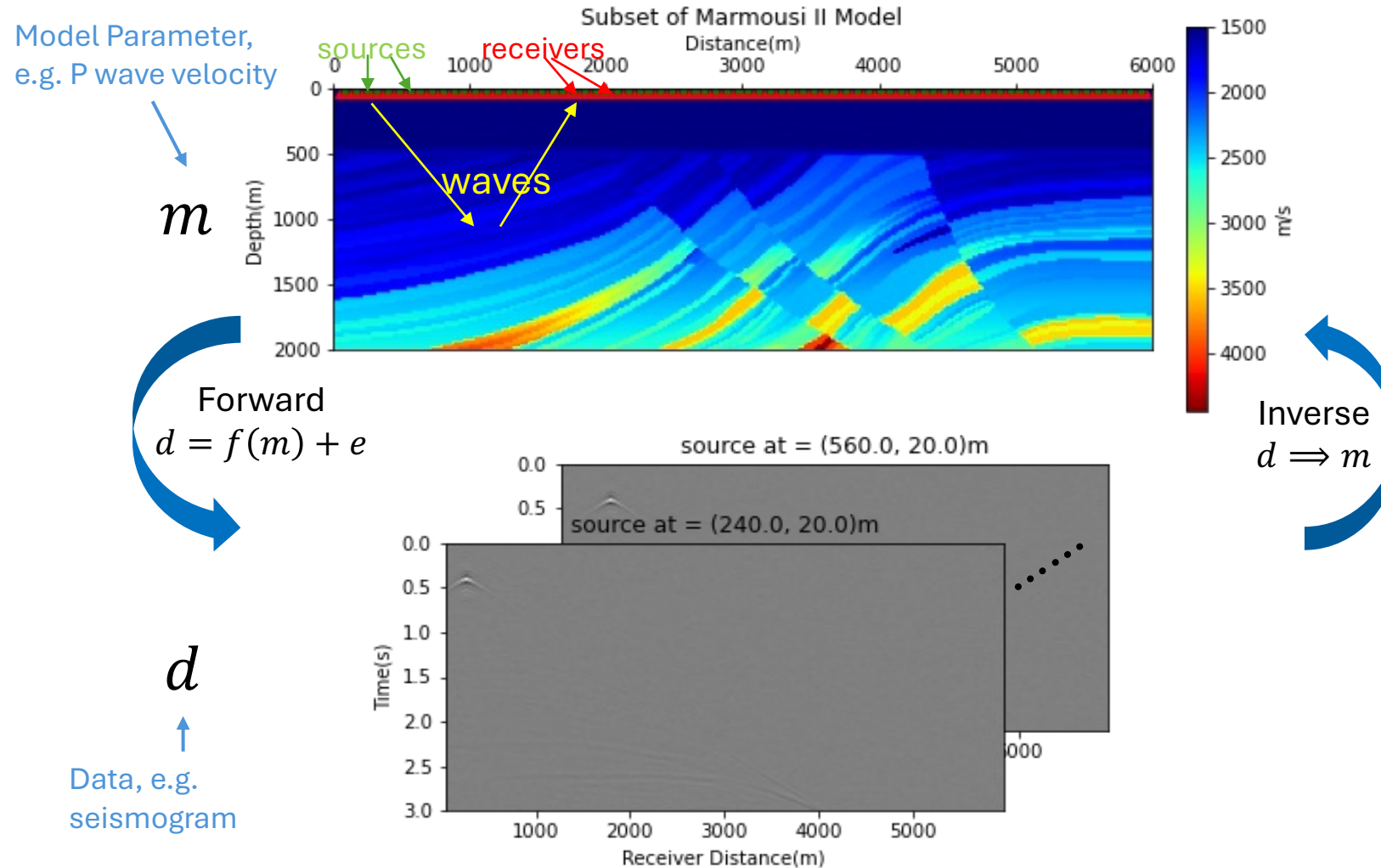


# Introduction

Seismic Inversion  $\rightarrow$  Uncertainty Quantification

Hessian

# Seismic Inversion



# Seismic Inversion

- Full-waveform inversion:  

$$\min_m \Phi(m) := \| f(m) - d \|_2^2 + \mathcal{R}(m)$$
- Quasi-Newton methods (Newton-CG, L-BFGS) require many iterations (wave simulations).
- Need a preconditioner for the Hessian of  $\Phi$ :

$$\mathcal{H} = \frac{d^2}{dm^2} \Phi(m)$$

# Uncertainty Quantification

- Bayesian inference framework:  

$$d\mu_{post}(m|d) \propto \pi_{like}(d|m)d\mu_{prior}(m)$$
- Information extraction is challenging.
- The Hessian contains crucial local curvature information to accelerate the Monte Carlo sampling.

$$\mathcal{H} = -\frac{d^2}{dm^2} \log d\mu_{post}(m|d)$$

# Hessian Operator

- The whole Hessian matrix is intractable for large-scale problems.
- Hessian matrix-vector multiplication is available via the Adjoint Method ( $\approx 4$  Forward computations).
- Conventional low-rank methods are not suitable for seismic Hessian which is high-rank (with informative data from multiple sources and receivers).

# Research Questions

1. How to approximate the seismic Hessian which is high-rank?
2. How to utilize the approximation to accelerate the seismic inversion?
3. How to utilize the approximation to accelerate seismic uncertainty quantification and hence make it tractable?

# Hessian Approximation Methods

$\Psi$ DO Probing Method + PSF Method  $\Rightarrow$  Low-rank Symbol Method

# Pseudo-differential Operator ( $\Psi$ DO) Probing

$$(Hv)(x) = \int e^{ix \cdot \xi} s(x, \xi) \hat{v}(\xi) d\xi, \quad v \in L^2(\mathbb{R}^d)$$

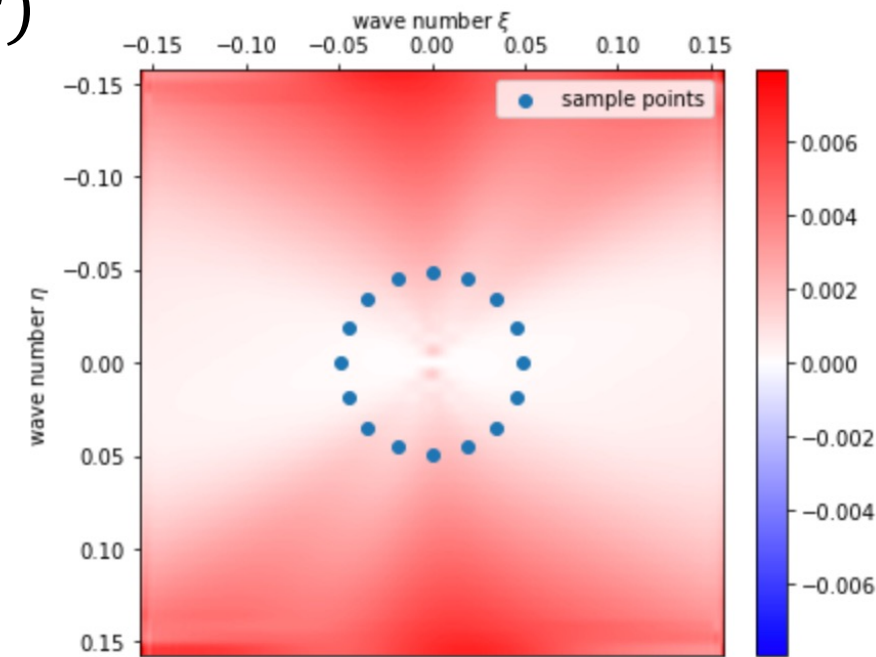
- Symbol  $s(x, \xi): \mathbb{R}^d \times \mathbb{R}^d \setminus \{0\} \rightarrow \mathbb{R}$  (smooth in  $x, \xi$ , asymptotically polynomial in  $\xi$ )

$$s(x, \xi) = e^{-ix \cdot \xi} (H e^{ix \cdot \xi})(x)$$

Bao and Symes (1996) use the symbol's asymptotic behavior to apply it in  $\mathcal{O}(N^d \log N)$  vs  $\mathcal{O}(N^{d+1})$  for simulation:

$$s(x, \xi) \approx |\xi| s_1(x, \arg \xi) \approx |\xi| \sum_{k,l} c_k(x) e^{il \arg \xi}$$

$\Rightarrow$  Only need to compute symbol  $s$  on angles.





# $\Psi$ DO in One Hessian Action

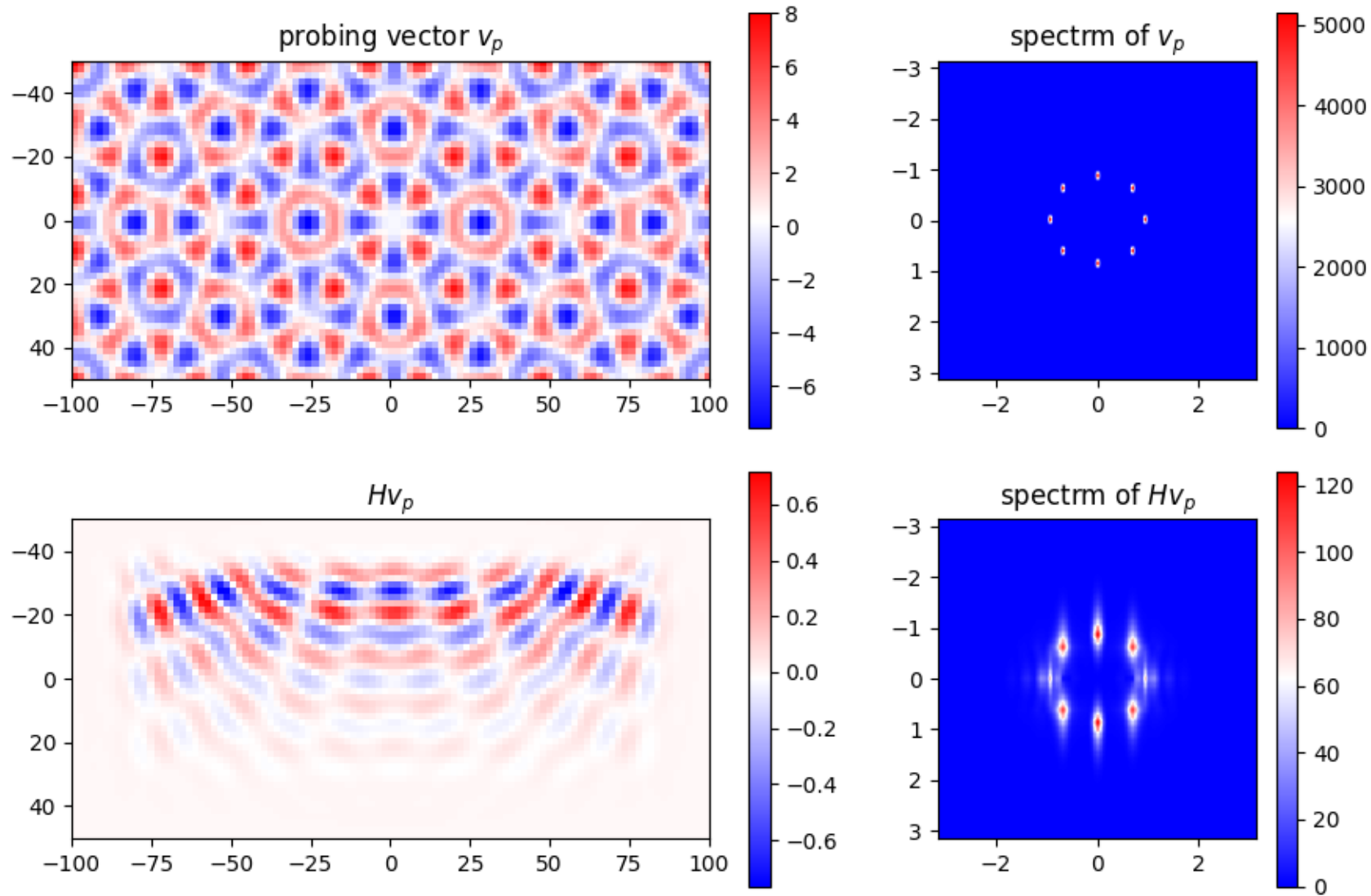
Pick sample points  $\xi_k$  in different directions.

- Naive scheme: Compute symbol columns  $s(x, \xi_1), s(x, \xi_2), \dots, s(x, \xi_n)$  individually ( $n$  Hessian actions).
- Advanced scheme: The angles are preserved in frequency space  
 $\Rightarrow$  Compute on all angles together (one Hessian action).

$$v(x) = \sum_{k=1}^n e^{ix \cdot \xi_k} \Rightarrow (Hu)(x) = \sum_{k=1}^n (He^{ix \cdot \xi_k})(x) = \sum_{k=1}^n s(x, \xi_k) e^{ix \cdot \xi_k}$$

Then extract each symbol column  $s(x, \xi_k)$  from the product  $Hv$ .

# $\Psi$ DO in One Hessian Action (Example)



# Point Spread Function Method (PSF)

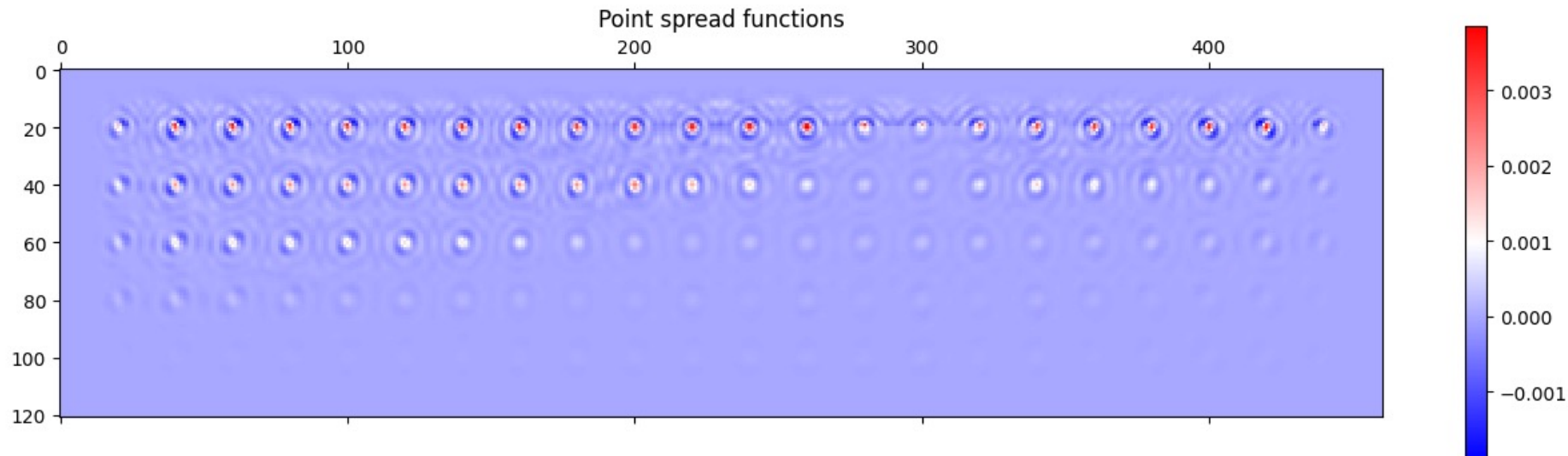
- PSFs are local  $\Rightarrow$  Compute multiple PSFs in one Hessian action.
  - PSFs are translation invariant  $\Rightarrow$  Approximate PSFs with nearby PSFs.
- $\Rightarrow$  Approximate  $H$  as a sum of Product-Convolutions.

$$Hu = \sum_{i=1}^r \phi_{x_i} * (w_i \cdot u)$$

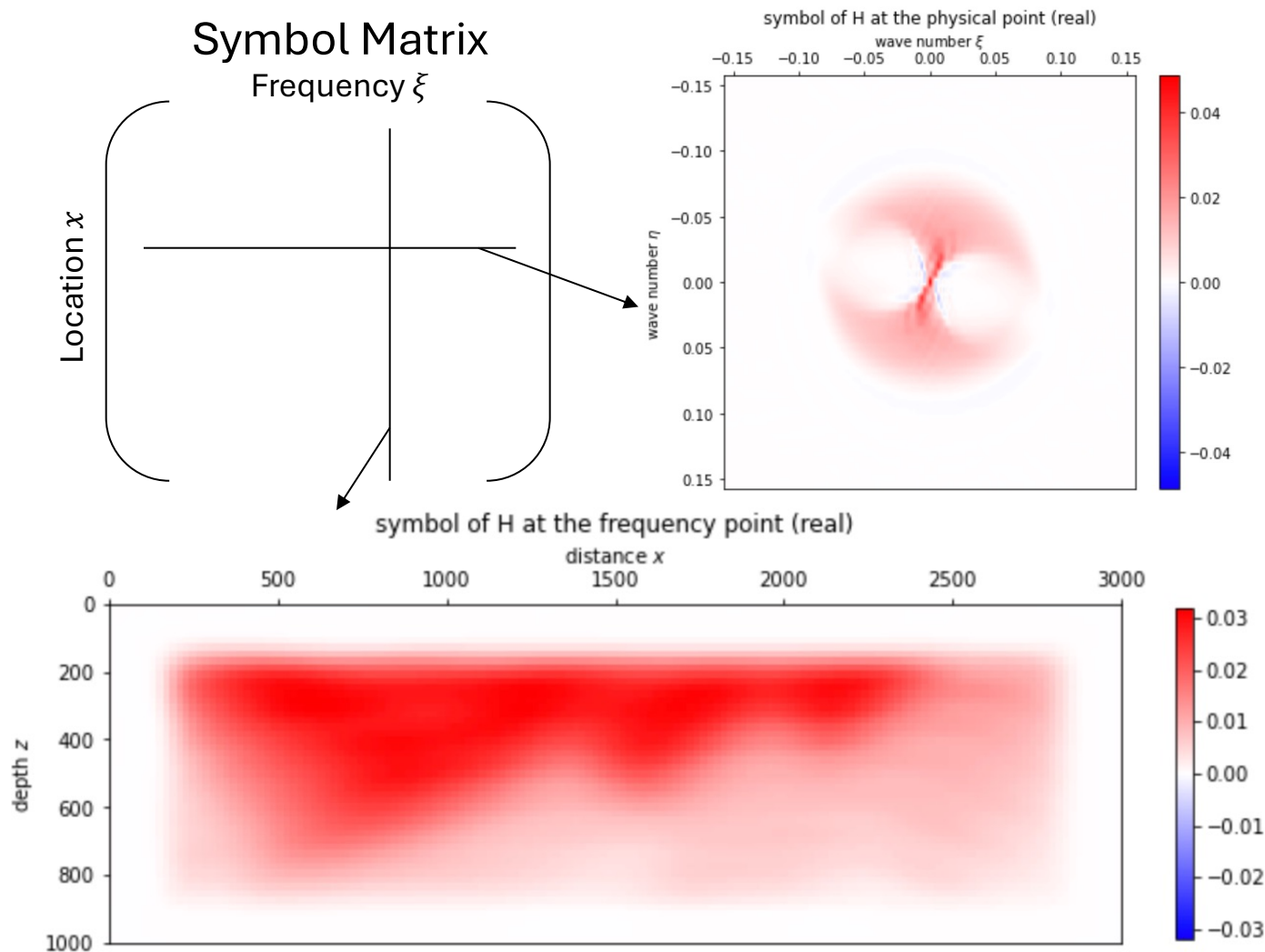
Point spread functions

sampled PSFs

RBF-weighting



# Observation: Duality between PSF and $\Psi$ DO



PSF Method: Row of symbol

$$s(x_k, \cdot) = \mathcal{F}[H^T(\delta_x)(x_k - x)]$$

PSFs

$\Psi$ DO Method: Cols of symbol

$$s(\cdot, \xi_k) = \frac{H(\mathcal{F}^{-1}[\delta_{\xi_k}])(x)}{\mathcal{F}^{-1}[\delta_{\xi_k}](x)}$$

# $\Psi$ DO + PSF = Low-Rank Symbol Method

- Both PSF and  $\Psi$ DO method utilize the fact that the symbol of the seismic Hessian (at a smooth background) is low-rank.

## XR Algorithm:

1. Convert the PSF method's result to low-rank symbol:  $S_{psf} = X_0 Q$
2. Refine  $X_0$  to fit the symbol columns  $S[:, I_c]$  from the  $\Psi$ DO method:  

$$X = \underset{X}{\operatorname{argmin}} \|XQ[:, I_c] - S[:, I_c]\|_F^2 + \alpha \|X - X_0\|_F^2$$
3. Create Hessian approximation from the low-rank symbol:  $S_{new} = XQ$

# Accelerate Seismic Inversion

$$m^* = \underset{m}{\operatorname{argmin}} \Phi(m) := \| f(m) - d \|_2^2 + \mathcal{R}(m)$$

Preconditioner  $P = (\tilde{H} + R)^{-1}$  applies to L-FBGS algorithm:

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## Algorithm 1 Preconditioned L-BFGS

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- 1: Choose starting point  $x_0$ , and integer  $m > 0$
  - 2:  $k \leftarrow 0$  ▷ Initialization
  - 3: **repeat** ▷ Newton Loop
  - 4:   Choose  $H_k^0 = \gamma_k' P$
  - 5:   Compute  $p_k = -H_k \nabla f_k$  via two-loop recursion.
  - 6:   Compute  $\alpha_k$  which satisfies Wolf conditions ▷ Line search
  - 7:    $x_{k+1} \leftarrow x_k + \alpha_k p_k$
  - 8:   **if**  $k > m$  **then**
  - 9:     Discard vector pair  $\{s_{k-m}, y_{k-m}\}$  from storage
  - 10:   **end if**
  - 11:   Compute and save  $s_k = x_{k+1} - x_k$  and  $y_k = g_{k+1} - g_k$
  - 12:    $k \leftarrow k + 1$
  - 13: **until** convergence
-

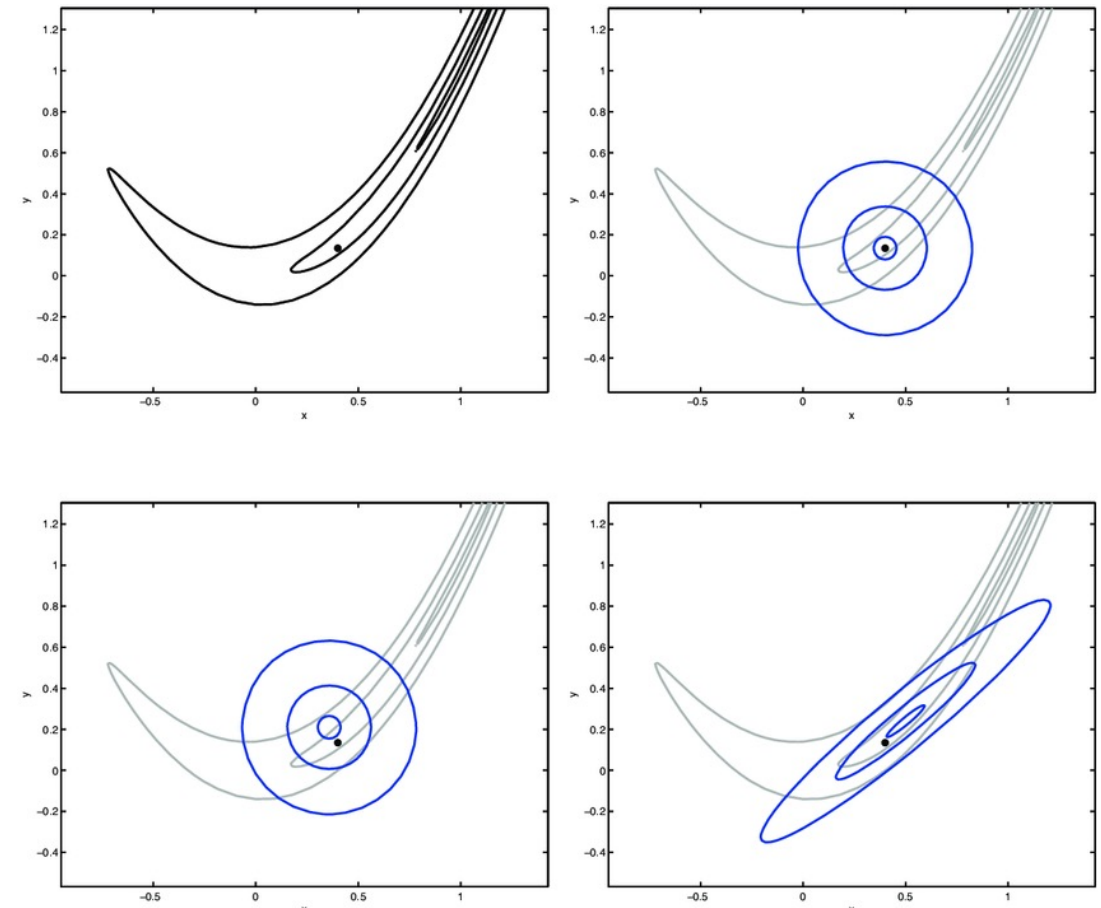
# Accelerate Uncertainty Quantification

- Build a Laplace Approximation to the posterior:

$$\mathcal{N}\left(m^*, (\tilde{H} + R)^{-1}\right)$$

- Draw samples from this distribution.
- These samples are more likely to be accepted.
- Implemented by the generalized preconditioned Crank-Nicolson algorithm (gpCN).

Visualizations of different types of proposal distributions for MCMC



Reference: Martin, James, Lucas C. Wilcox, Carsten Burstedde, and Omar Ghattas. "A stochastic Newton MCMC method for large-scale statistical inverse problems with application to seismic inversion." *SIAM Journal on Scientific Computing* 34, no. 3 (2012): A1460-A1487.

# Numerical Results

Quadratic Toy Model

The Marmousi Model



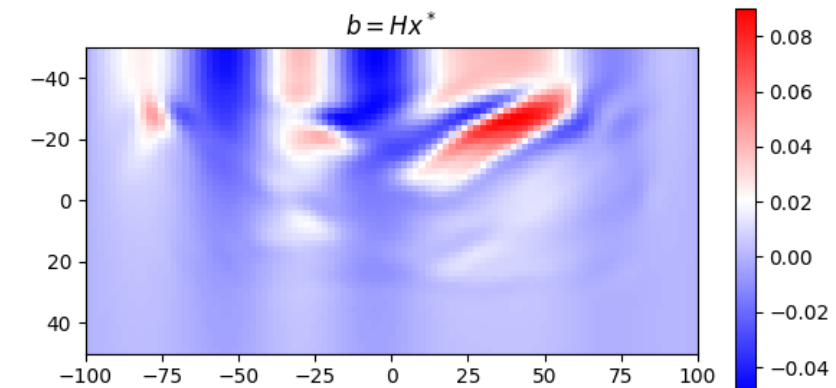
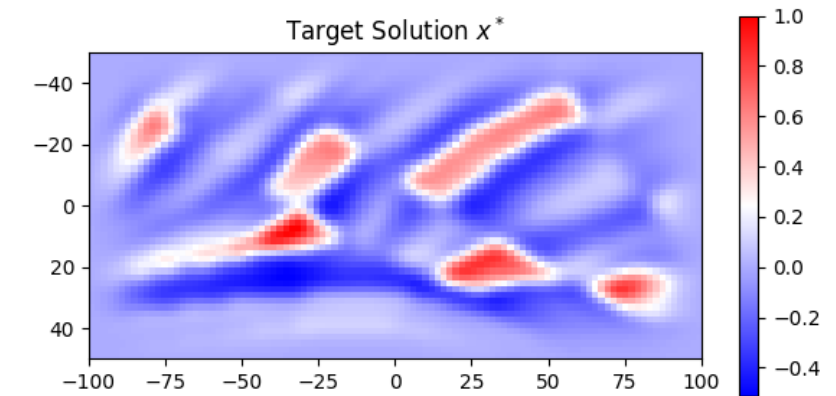
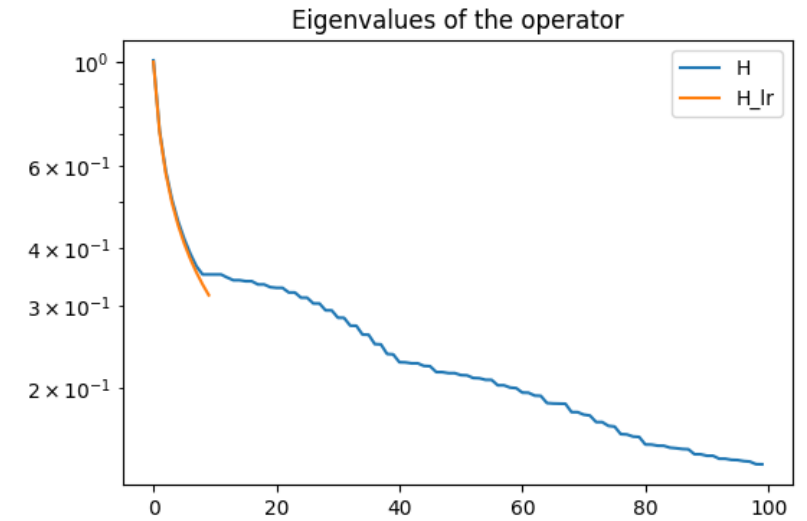
# Quadratic Toy Model

- Hessian = Low-rank matrix +  $\Psi$ DO
- True model  $x^*$ . Right hand side  $b = Hx^*$ .
- Suppose  $x = Wy$ . ( $W$  suppresses boundaries).

$$\begin{cases} \text{cost}(x) = \frac{1}{2}x^T Hx - b^T x \\ \text{grad}(x) = Hx - b \\ \text{hess}(x) = H \end{cases} \quad \begin{cases} \text{cost}(y) = \frac{1}{2}y^T WHWy - b^T Wy \\ \text{grad}(y) = WHWy - Wb \\ \text{hess}(y) = WHW \end{cases}$$

Model	Quadratic Model
Dimensions	100m $\times$ 50m
Grids	101 $\times$ 51 = 5151

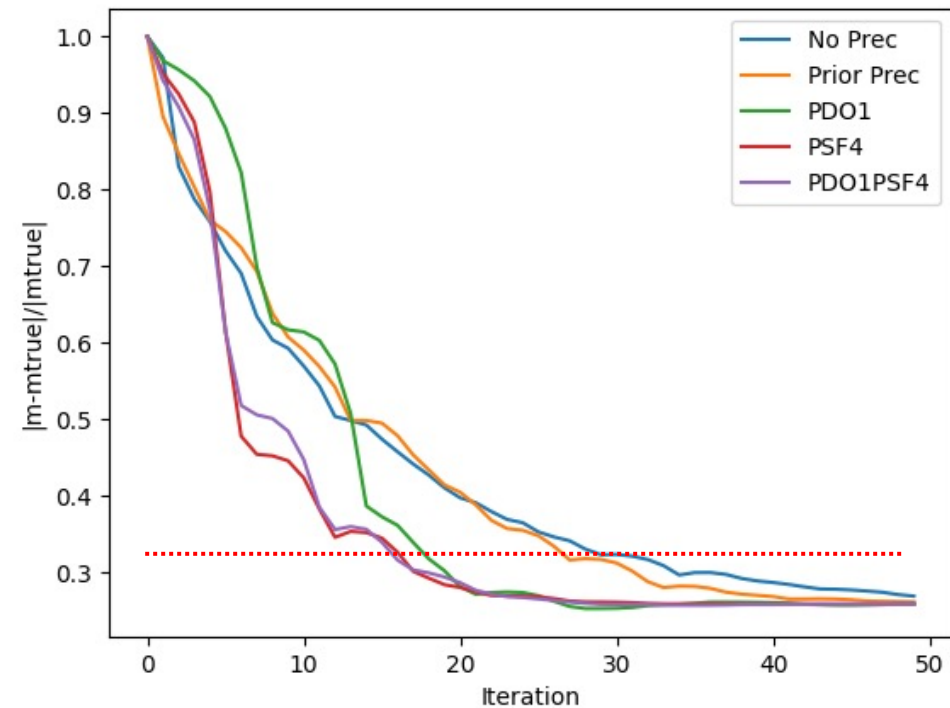
- The toy model is linear
- The posterior is Gaussian.



# Inversion Solution: Preconditioned L-BFGS

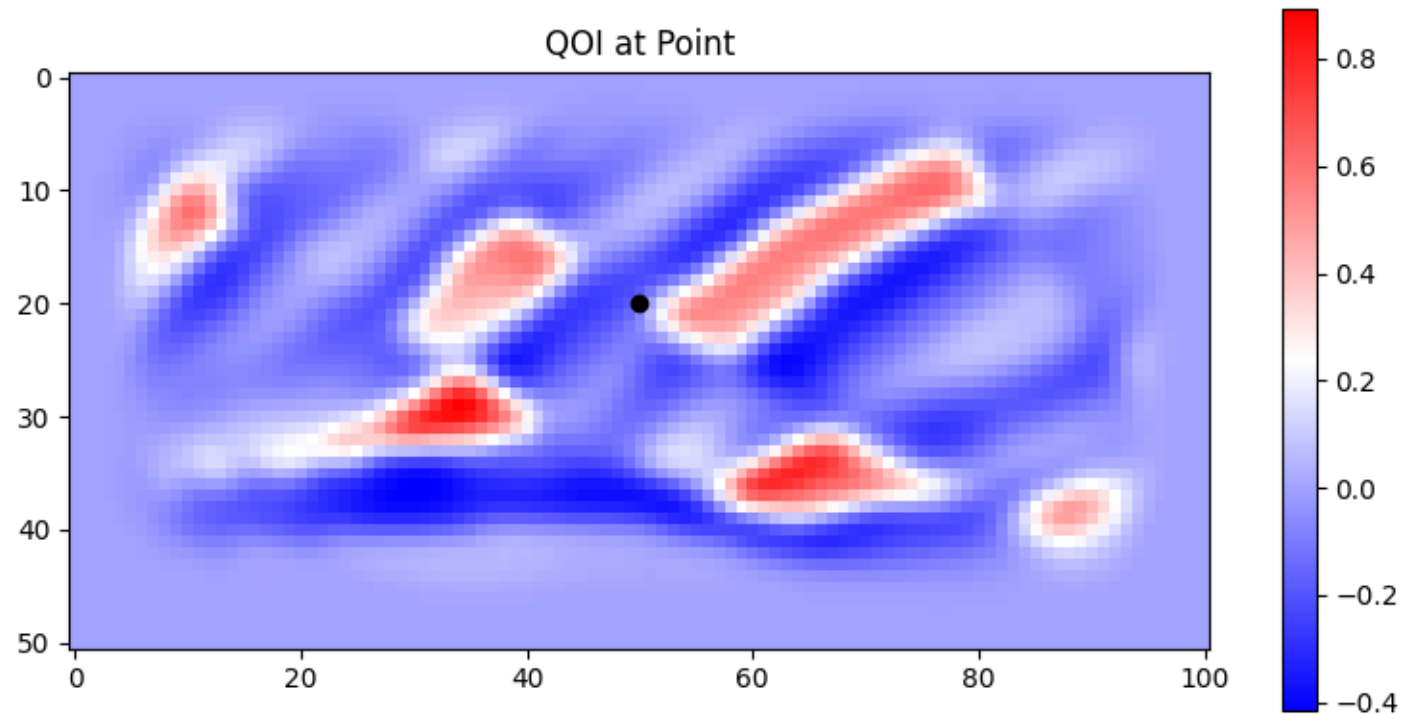
- Decay slower at beginning.
  - Our methods do not address the low-rank part.
- Decay faster later.

Preconditioner	L-BFGS Steps
No Preconditioner	169
Prior-Preconditioner	108
PDO1	<b>92</b>
PSF4	<b>55</b>
PDO1+PSF4	<b>69</b>



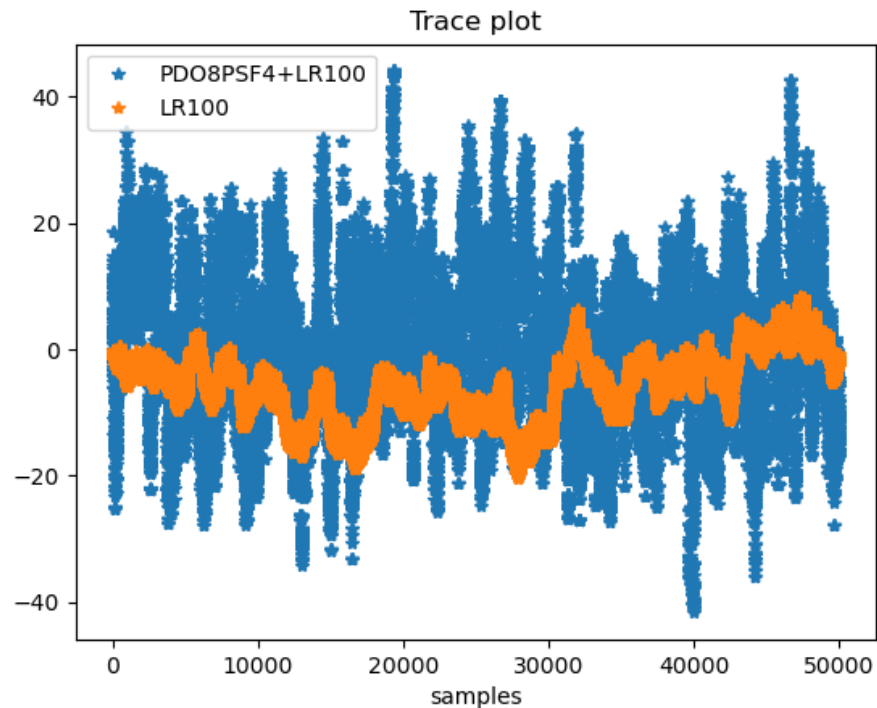
# Uncertainty Quantification: MCMC results

- We draw 50k samples from the posterior via MCMC-gpCN.
- Quantity of Interest (QoI) = The value at a certain position

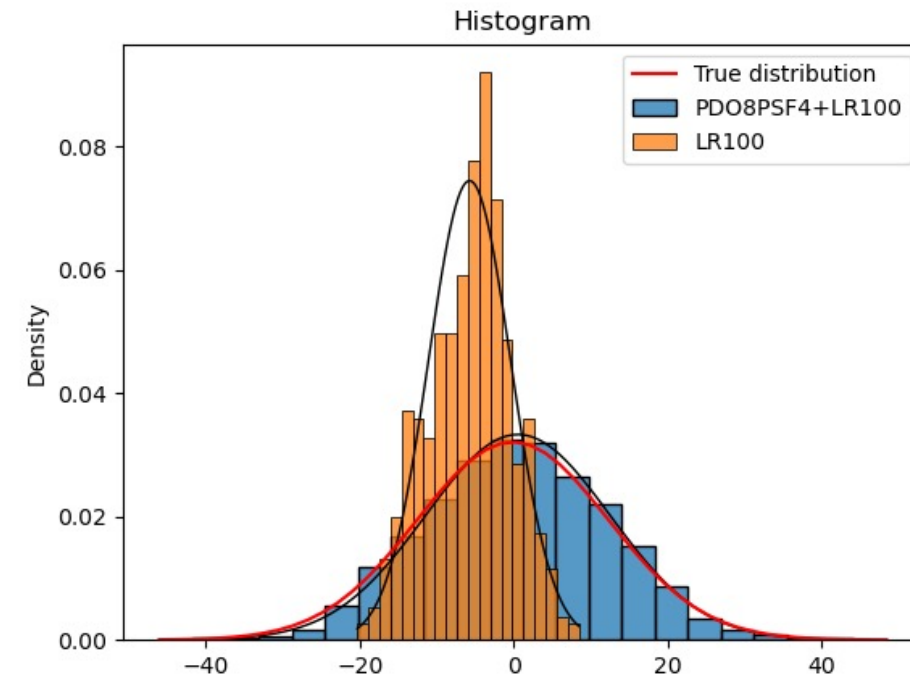


# Uncertainty Quantification: MCMC results

**Our methods draw samples with more mixture.**



**Our methods derive nearly the true distribution**

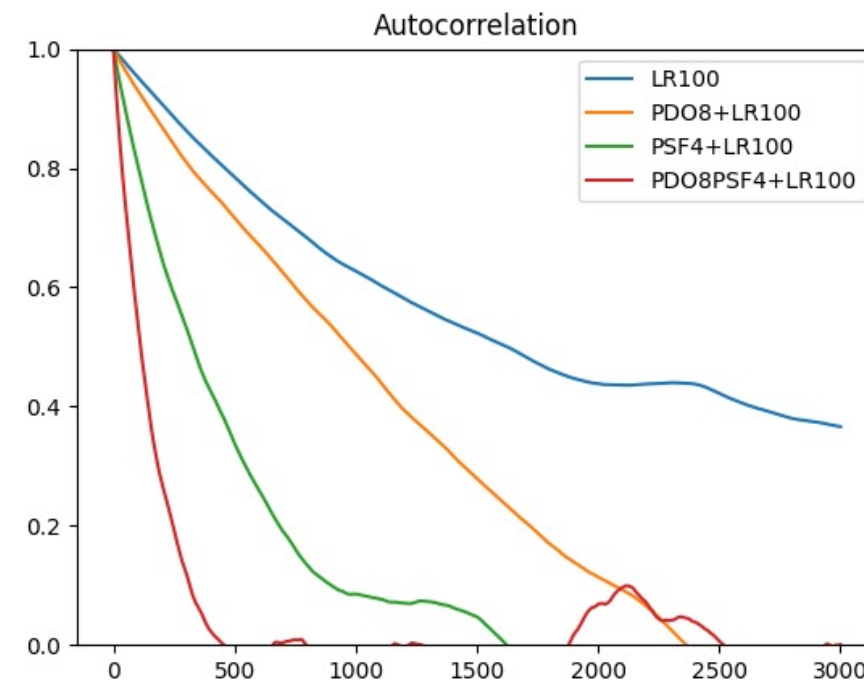


# Uncertainty Quantification: MCMC results

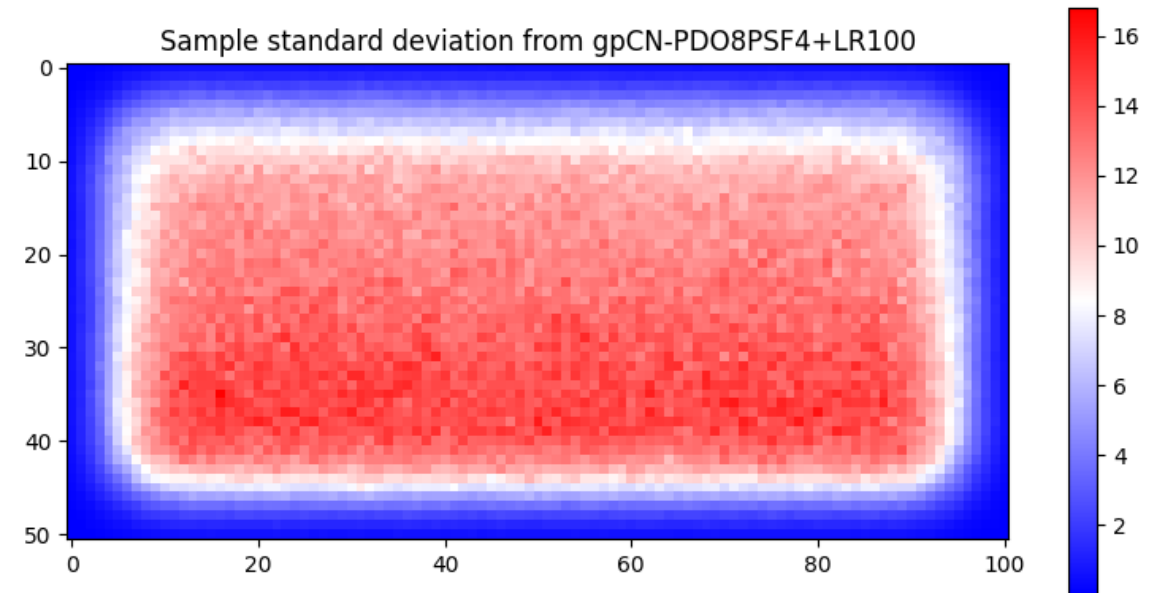
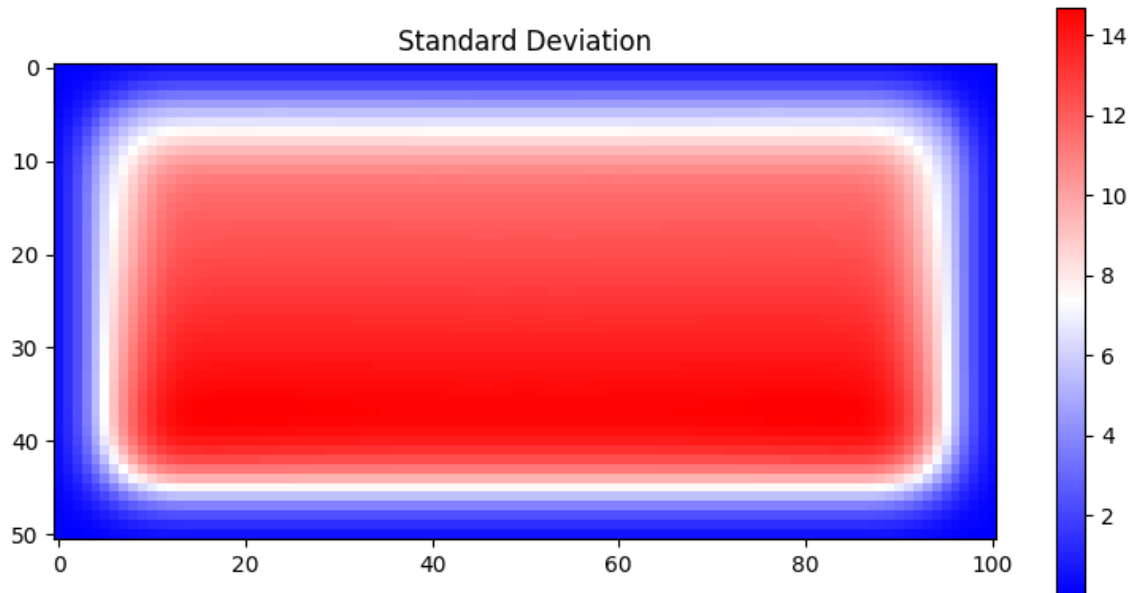
Our methods achieve larger effective samples size (ESS)

Sampling Method	Computational Cost	ESS
gpCN-LR100	200Hess+50kFwd	7.89
gpCN-PDO8+LR100	208Hess+50kFwd	24.20
gpCN-PSF4+LR100	204Hess+50kFwd	57.48
gpCN-PDO8PSF4+LR100	212Hess+50kFwd	<b>132.66</b>

Our methods draw samples with faster decaying autocorrelation.



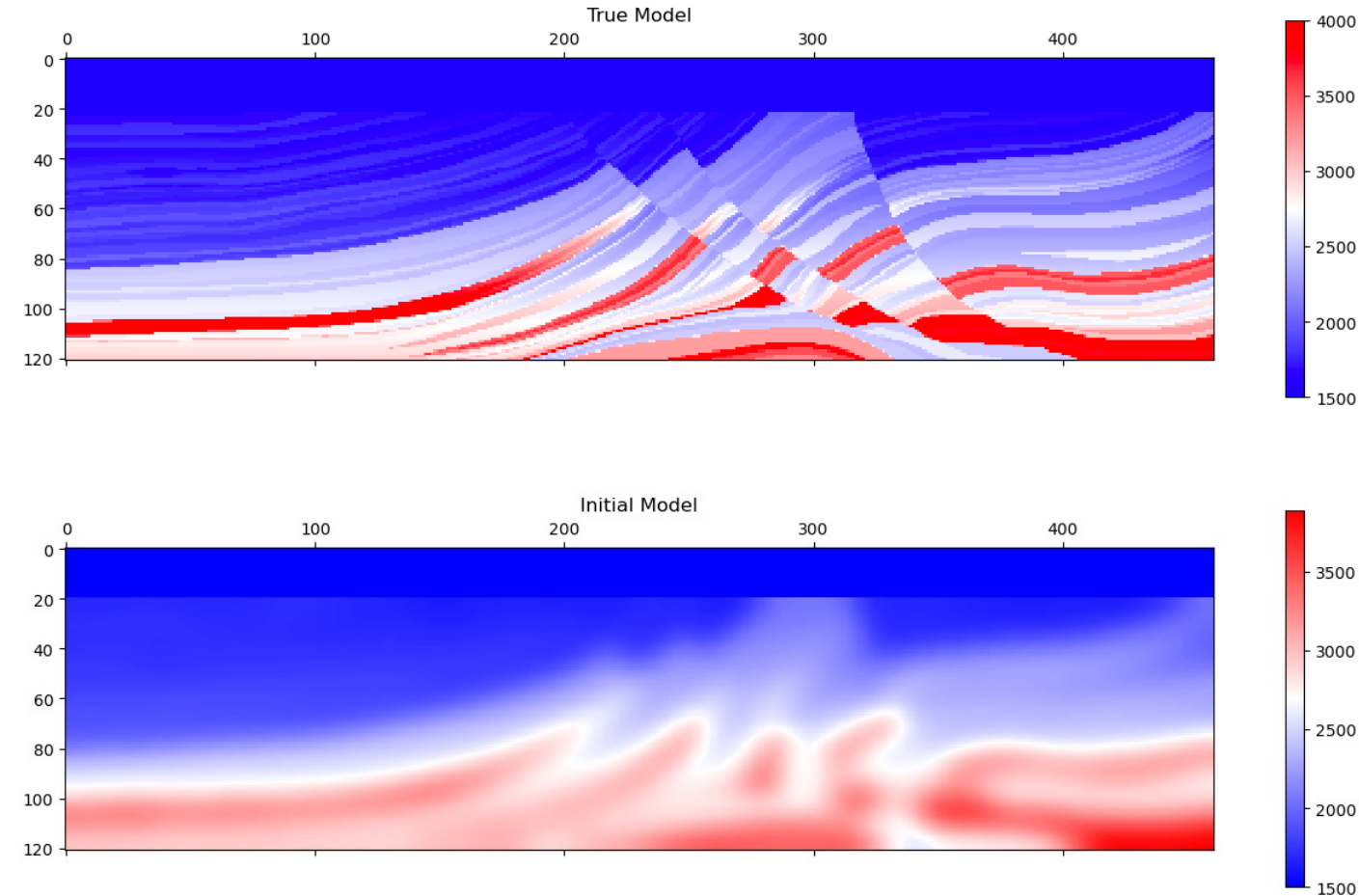
# Uncertainty Quantification: MCMC results



# Marmousi Model

$$\Phi(x) := \| f(m_0 + Wx) - d \|_2^2 + \mathcal{R}(m)$$

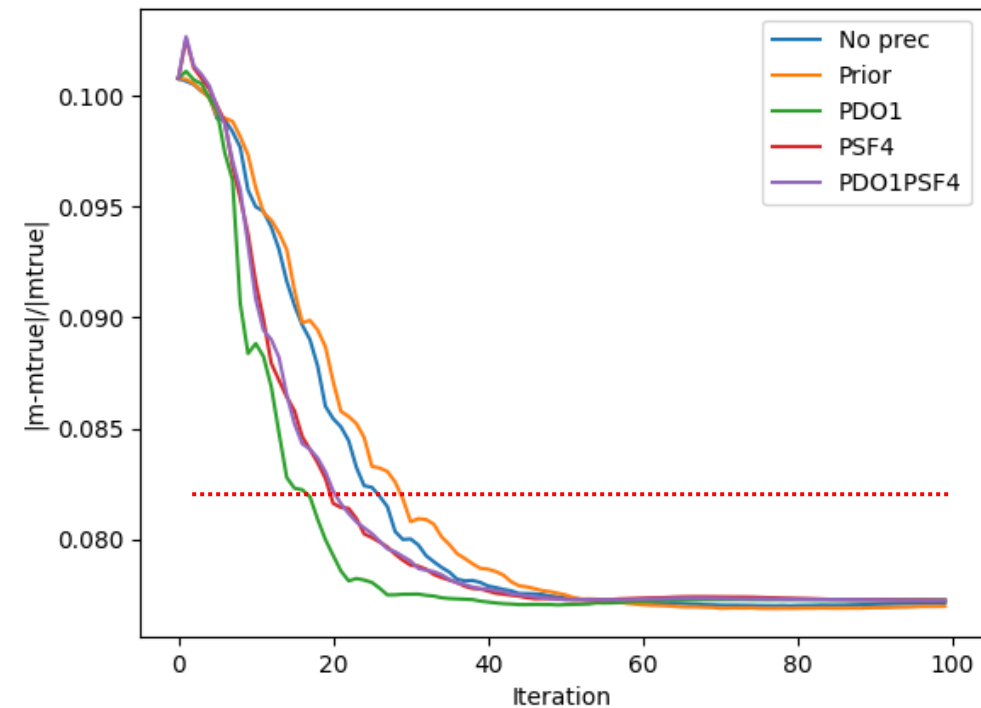
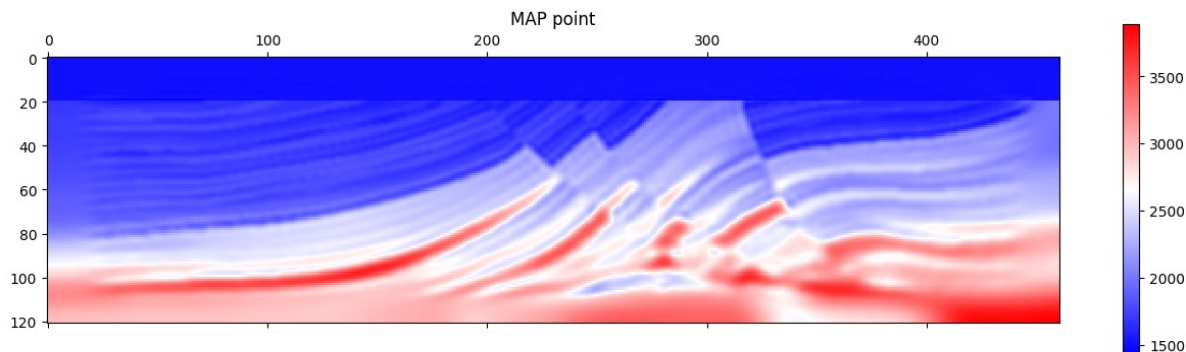
Model	Marmousi + water layer
Dimensions	9200m × 2400m
Grids	461 × 121 = 55781
Grid Size	20m × 20m
Simulation Time $T$	8s
Time Interval $dt$	0.0025s
Number of Sources $N_s$	92
Number of Receivers $N_r$	153
Source wave frequency	4-12Hz



# Inversion Solution: Preconditioned L-BFGS

- Our methods achieve faster decaying solution errors.

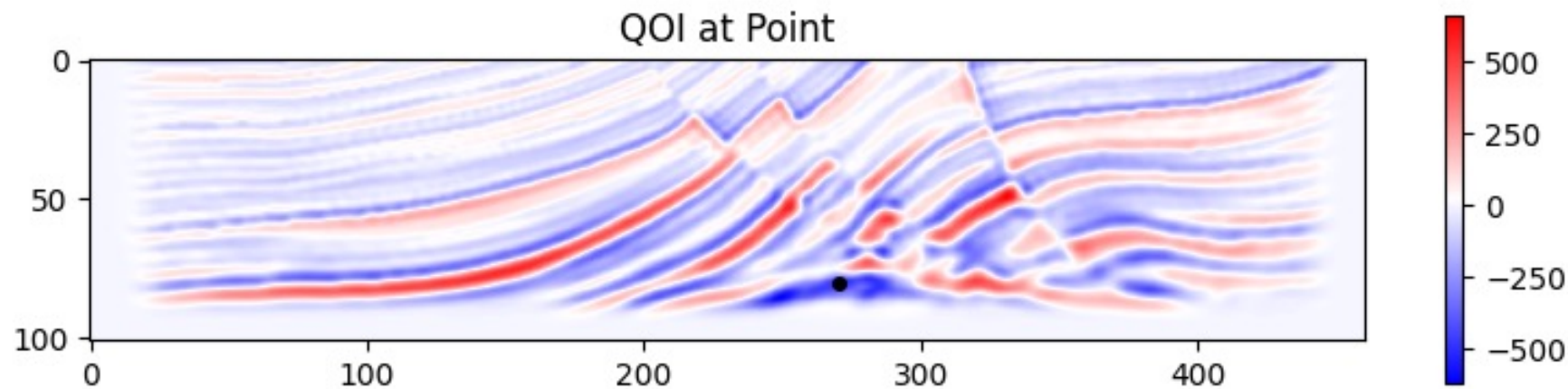
Preconditioner	L-BFGS Steps
No Preconditioner	333
Prior-Preconditioner	465
PDO1	<b>267</b>
PSF4	<b>231</b>
PDO1+PSF4	<b>238</b>





# Uncertainty Quantification: MCMC results

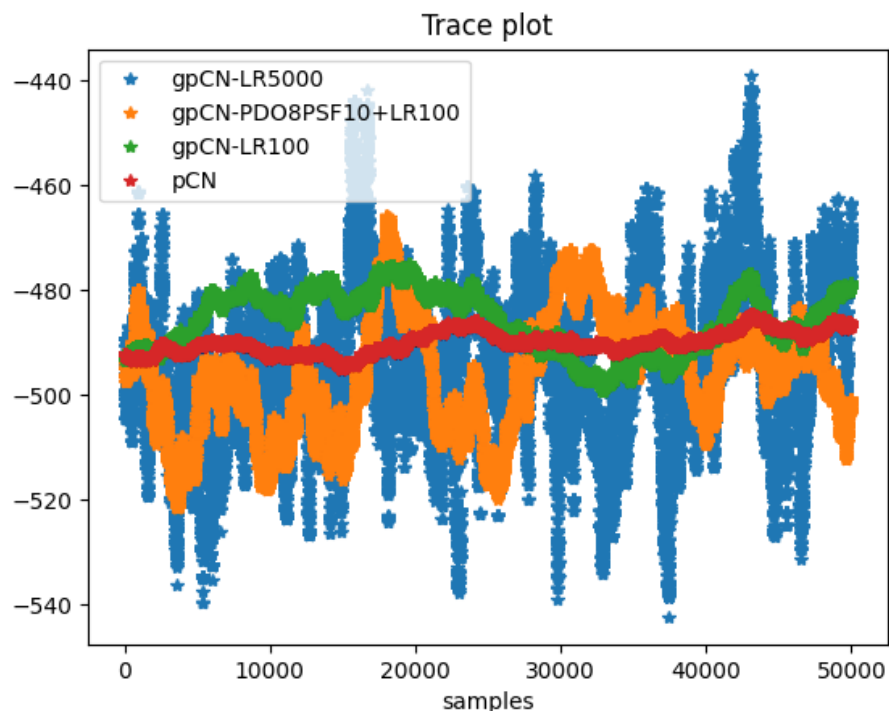
- We draw 50k samples from the posterior via MCMC-pCN/gpCN.
- Quantity of Interest (QoI) = The value  $m - m_0$  at a certain position



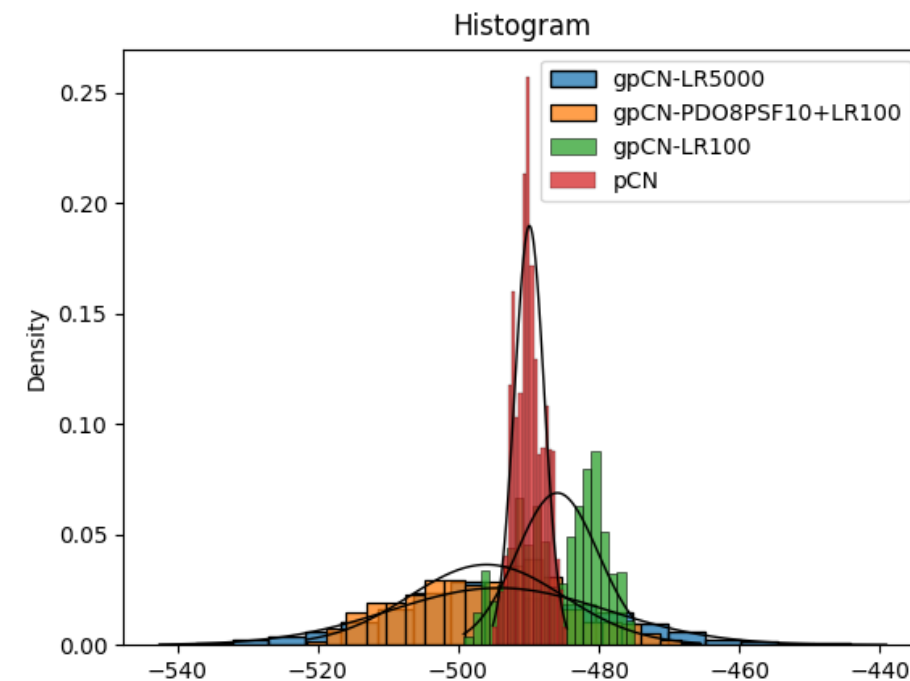
- The Marmousi model is non-linear (FWI). The correct UQ is unavailable.
- We benchmark against the low-rank approximation with 5000 eigenvalues.

# Uncertainty Quantification: MCMC results

**Our methods draw samples with more mixture.**



**Our methods derive a distribution that is closer to the baseline.**

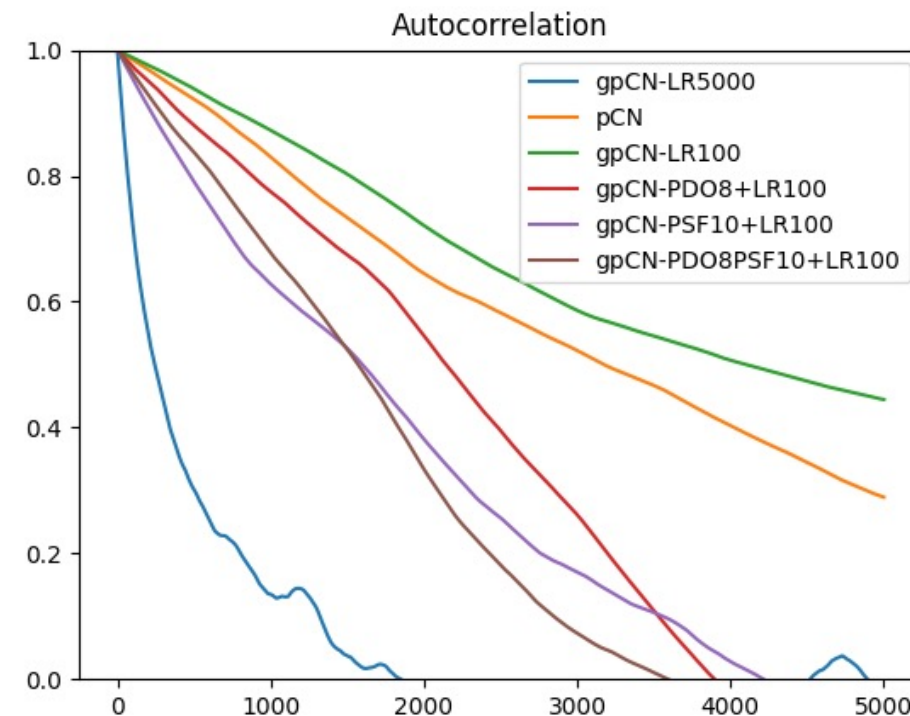


pCN & gpCN-LR100 are trapped in a small region  $\Rightarrow$  Under-estimated variation  $\Rightarrow$  non-interpretable UQ

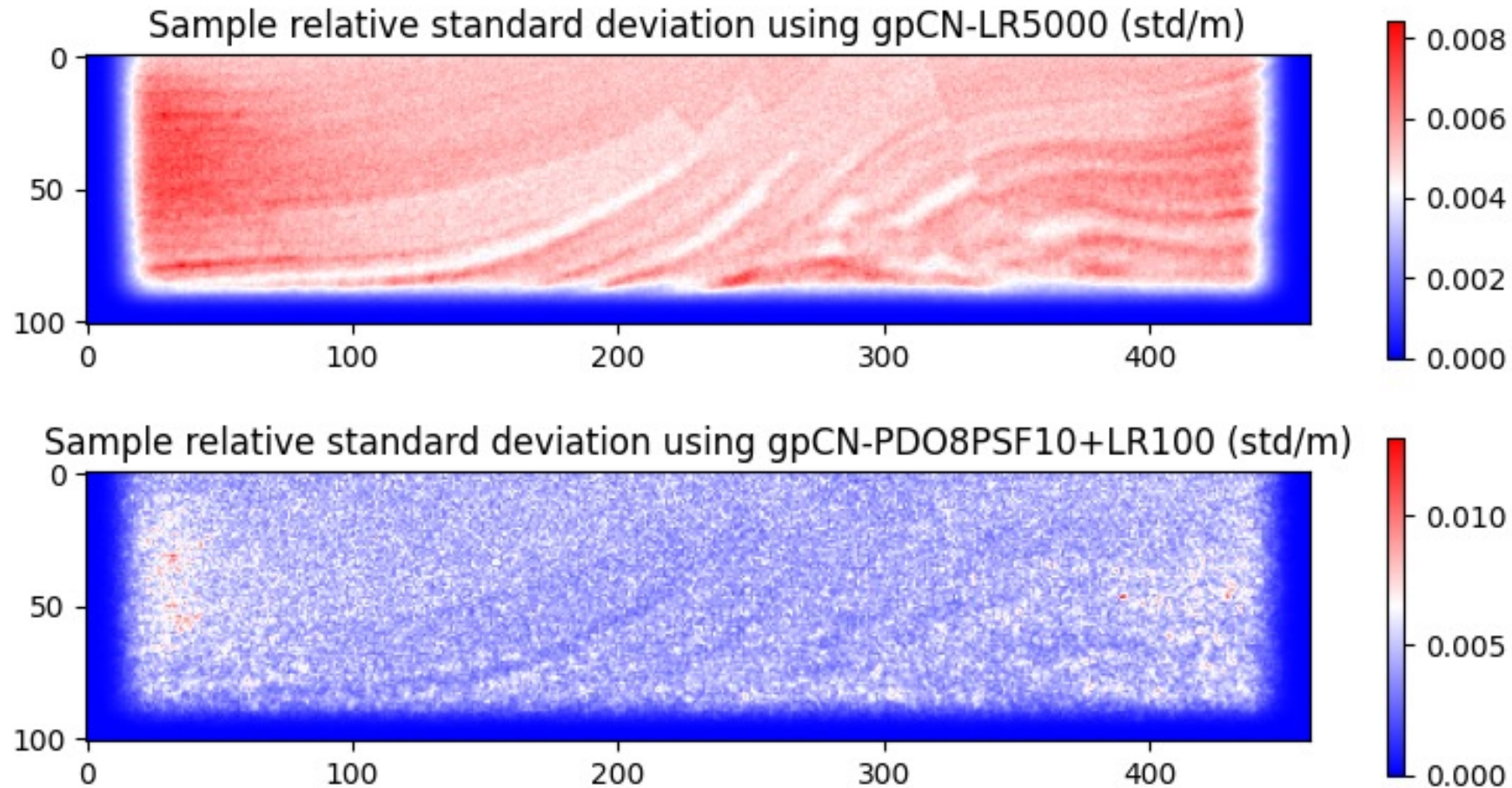
# Uncertainty Quantification: MCMC results

- The autocorrelation seems to indicate that pCN and gpCN-LR100 are well, but they underestimate the uncertainty in fact.

Algorithm	Computational Cost	ESS
gpCN-LR5000 (Baseline)	10kHess+50kFwd	53.12
pCN	0Hess+50kFwd	7.03
gpCN-LR100	200Hess+50kFwd	6.11
gpCN-PDO8+LR100	208Hess+50kFwd	12.10
gpCN-PSF10+LR100	210Hess+50kFwd	12.32
gpCN-PDO8+PSF10+LR100	218Hess+50kFwd	<b>13.49</b>



# Uncertainty Quantification: MCMC results



# Contributions

- Develop novel Hessian approximation algorithms based pseudo-differential operators, which also applies to general hyperbolic problems.
- Accelerate the solution of deterministic seismic inversions via preconditioned quasi-Newton methods.
- Enable large-scale seismic inversion uncertainty quantification via Markov Monte-Carlo with generalized preconditioned Crank-Nicolson kernel.

# Future Direction

- Investigate the trade-off between the cost of Hessian approximation and the cost of sampling.
- Test on other benchmark models (e.g. Salt Model).
- Compare with Variational Bayesian Inference.

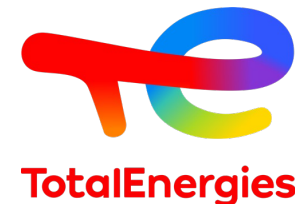
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- **Dr. Nick Alger, Dr. Stefan Henneking, and Dr. Lianghao Cao** for helpful discussions.



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