- A Complete Solution Guide to Introduction to Nonlinear Optimization Theory, Algorithms, and Applications with
- MATLAB

Youming Zhao

Email: youming0.zhao@gmail.com

First draft: May 24, 2022 Last update: September 9, 2023

6 Contents

7	1	Chapter 1	Mathematical Preliminaries	2
8		1.1 Some	important concepts	2
9		1.1.1	Induced matrix norm and several equivalent definitions	2
10		1.1.2	Accumulation point	3
11		1.1.3	Closed set	3
12		1.1.4	Boundary point	3
13		1.1.5	Closure	3
14		1.1.6	Interior point and interior of a set	3
15		1.1.7	De Morgan's Law/Theorem	4
16		1.2 Exerci	ses	4
17	2	Chapter 2	Optimality Conditions for Unconstrained Optimization	15
18	3	Chapter 3	Least Squares	17
19	4	Chapter 4	The Gradient Method	17
20	5	Chapter 5	Newton's Method	18
21	6	Chapter 6	Convex Sets	18
22	7	Chapter 7	Convex Functions	18
23	8	Chapter 8	Convex Optimization	22
24	9	Chapter 9	Optimization over a Convex Set	23
25	Bi	bliography		2 4

6 1 Chapter 1 Mathematical Preliminaries

27 1.1 Some important concepts

1.1.1 Induced matrix norm and several equivalent definitions

Here we introduce the definition of the induced matrix norm from the textbook. That is, the induced matrix norm $||A||_{a,b}$ is defined by

$$\|\mathbf{A}\|_{a,b} = \max_{\mathbf{x}} \{ \|\mathbf{A}\mathbf{x}\|_b \colon \|\mathbf{x}\|_a \le 1 \}. \tag{1}$$

 $\|\mathbf{A}\|_{a,b}$ can also be computed in the following alternative ways (Horn and Johnson, 2013, p. 343, Definition 5.6.1):

$$\|\mathbf{A}\|_{a,b} = \max_{\mathbf{x}} \{ \|\mathbf{A}\mathbf{x}\|_b \colon \|\mathbf{x}\|_a = 1 \} = \max_{\|\mathbf{x}\|_a \neq \mathbf{0}} \frac{\|\mathbf{A}\mathbf{x}\|_b}{\|\mathbf{x}\|_a}.$$
 (2)

- Now we show that they are valid alternatives of (1) by proving two lemmas. The first alternative is exactly the following lemma.
- Lemma 1.1. The maximum points \mathbf{x}^* of the RHS of (1) must satisfy $\|\mathbf{x}^*\|_a = 1$.

Proof. We will prove it by contradiction. Given $\mathbf{A} \neq \mathbf{0}$, it is obvious that $\mathbf{x}^* \neq \mathbf{0}$ must hold, otherwise $\|\mathbf{A}\mathbf{x}^*\|_b = 0$ which is the minimum value and it is easy to find an \mathbf{x} such that $\|\mathbf{A}\mathbf{x}\|_b > 0$. Suppose that the maximum points satisfy $\|\mathbf{x}^*\|_a < 1$, then there exists real numbers k such that $\|k\mathbf{x}^*\|_a = 1$ in which $|k| = 1/\|\mathbf{x}^*\|_a > 1$. Let $\mathbf{y} = k\mathbf{x}^*$, then we get

$$\|\mathbf{A}\mathbf{y}\|_{b} = \|\mathbf{A}(k\mathbf{x}^{*})\|_{b} = |k|\|\mathbf{A}\mathbf{x}^{*}\|_{b} > \|\mathbf{A}\mathbf{x}^{*}\|_{b}$$
 (3)

- which contradicts that \mathbf{x}^* are the maximum points. Thus, $\|\mathbf{x}^*\|_a = 1$ holds.
- We directly present the second alternative as a lemma as follows and prove it through Lemma 1.1.

Lemma 1.2. For any $\mathbf{x} \in \mathbb{R}^n$,

$$\|\mathbf{A}\|_{a,b} = \max_{\|\mathbf{x}\|_a \neq \mathbf{0}} \frac{\|\mathbf{A}\mathbf{x}\|_b}{\|\mathbf{x}\|_a}.$$
 (4)

Proof. An equivalent form of Lemma 1.1 is

$$\|\mathbf{A}\|_{a,b} = \max_{\mathbf{y}} \left\{ \frac{\|\mathbf{A}\mathbf{y}\|_b}{\|\mathbf{y}\|_a} : \|\mathbf{y}\|_a = 1 \right\} = \max_{\|\mathbf{y}\|_a = 1} \frac{\|\mathbf{A}\mathbf{y}\|_b}{\|\mathbf{y}\|_a}.$$
 (5)

By letting $\mathbf{y} = k\mathbf{x}$ where $k \in \mathbb{R} \setminus \{0\}$, we have

$$\|\mathbf{A}\|_{a,b} = \max_{|k|\|\mathbf{x}\|_a = 1} \frac{|k|\|\mathbf{A}\mathbf{x}\|_b}{|k|\|\mathbf{x}\|_a} = \max_{\|\mathbf{x}\|_a = 1/|k|} \frac{\|\mathbf{A}\mathbf{x}\|_b}{\|\mathbf{x}\|_a} = \max_{\|\mathbf{x}\|_a \neq 0} \frac{\|\mathbf{A}\mathbf{x}\|_b}{\|\mathbf{x}\|_a}$$
(6)

where the last equality follows from that k is an *arbitrary* nonnegative real number. This completes our proof.

The textbook gives a result about the induced matrix norm without a proof right after its definition. Here, we will present it as a proposition with a proof. The proof is an immediate result of Lemma 4.

Proposition 1.3. For any $\mathbf{x} \in \mathbb{R}^n$ the inequality

$$\|\mathbf{A}\mathbf{x}\|_b \le \|\mathbf{A}\|_{a,b} \|\mathbf{x}\|_a \tag{7}$$

39 holds.

Proof. According to Lemma 4, for any $\mathbf{x} \neq \mathbf{0}$, it follows that

$$\frac{\|\mathbf{A}\mathbf{x}\|_b}{\|\mathbf{x}\|_a} \le \|\mathbf{A}\|_{a,b} \Longleftrightarrow \|\mathbf{A}\mathbf{x}\|_b \le \|\mathbf{A}\|_{a,b} \|\mathbf{x}\|_a \tag{8}$$

П

40 completing the proof.

41 1.1.2 Accumulation point

Definition 1.4 (accumulation points). If any open ball of a point x contains infinitely many points of a set S, then x is called an accumulation point of S. The set of all accumulation points of S is denoted by S'.

42

$_{43}$ 1.1.3 Closed set

- We describe the definition of closed sets in a slightly different way than the textbook. However, in essence, they are the same thing.
 - **Definition 1.5 (closed sets).** If a set S contains all of its accumulation points, then we call S a closed set.

46

47 1.1.4 Boundary point

Definition 1.6 (boundary points). Given a set $U \subseteq \mathbb{R}^n$, a **boundary point** of U is a point $\mathbf{x} \in \mathbb{R}^n$ satisfying the following: any neighborhood of \mathbf{x} contains at least one point in U and at least one point in its complement U^c . The set of all boundary points of a set is denoted by $\mathrm{bd}(U)$ or ∂U and is called the boundary of U.

4

⁴⁹ 1.1.5 Closure

Definition 1.7 (closure of a set). The closure of a set $U \subseteq \mathbb{R}^n$ is the smallest closed set containing U:

$$cl(U) = \bigcap \{T : U \subseteq T, \ T \ is \ closed\}. \tag{9}$$

Another equivalent definition of cl(U) is given by

$$cl(U) = U \cup bd(U). \tag{10}$$

50

The closure set is indeed a closed set as an intersection of closed sets (see Exercise 1.16(ii)).

1.1.6 Interior point and interior of a set

Definition 1.8 (interior points). Given a set $U \subseteq \mathbb{R}^n$, a point $\mathbf{c} \in U$ is an interior point of U if there exists r > 0 for which $B(\mathbf{c}, r) \subseteq U$.

55

Definition 1.9 (interior of a set). The set of all interior points of a given set U is called the interior of a set and is denoted by int(U):

$$int(U) = \{ \mathbf{x} \in U : B(\mathbf{x}, r) \subseteq U \text{ for some } r > 0 \}.$$
(11)

$_{55}$ 1.1.7 De Morgan's Law/Theorem

Here we present a generalized form of De Morgan's Law which is also known as De Morgan's Theorem from Wikipedia¹.

Theorem 1.10 (De Morgan's Law/Theorem).

$$\left(\bigcup_{i\in I} A_i\right)^c = \bigcap_{i\in I} A_i^c \tag{12}$$

$$\left(\bigcap_{i\in I} A_i\right)^c = \bigcup_{i\in I} A_i^c \tag{13}$$

where I is some, possibly countably or uncountably infinite, indexing set.

1.2 Exercises

54

Exercise 1.1

Show that $\|\cdot\|_{1/2}$ is not a norm.

Proof. To show that a function is not a norm, it suffices to find a counterexample which does not satisfy at least one of the three properties of a norm. For $\|\cdot\|_{1/2}$, we let

$$\mathbf{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

Then we have

$$\begin{aligned} &\|\mathbf{x} + \mathbf{y}\|_{1/2} = \| \begin{pmatrix} 1 \\ 1 \end{pmatrix} \|_{1/2} = (\sqrt{1} + \sqrt{1})^2 = 4 \\ &\|\mathbf{x}\|_{1/2} = (\sqrt{1} + \sqrt{0})^2 = 1 \\ &\|\mathbf{y}\|_{1/2} = (\sqrt{0} + \sqrt{1})^2 = 1 \end{aligned}$$

However,

$$\|\mathbf{x} + \mathbf{y}\|_{1/2} = 4 > \|\mathbf{x}\|_{1/2} + \|\mathbf{y}\|_{1/2} = 1 + 1 = 2.$$

- Hence, $\|\cdot\|_{1/2}$ does not satisfy the triangle inequality. This completes the proof.
- In fact, when $0 , <math>\|\cdot\|_p$ satisfies the reverse of Minkowski's inequality within the domain of \mathbb{R}^n_+ . Formally, we have the following theorem.

¹https://en.wikipedia.org/wiki/De_Morgan%27s_laws

Theorem 1.11 (reversed Minkowski's inequality). For any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n_+$ and 0 , the following inequality

$$\|\mathbf{x} + \mathbf{y}\|_{p} \ge \|\mathbf{x}\|_{p} + \|\mathbf{y}\|_{p}$$

holds.

64

65

The following proof largely follows Jax (2016) but in greater detail.

Proof. Obviously, the claim holds when either $\mathbf{x} = 0$ or $\mathbf{y} = 0$. We only need to consider the case when $\mathbf{x} \neq 0$ and $\mathbf{y} \neq 0$, which guarantees $\|\mathbf{x} + \mathbf{y}\|_p \neq 0$. Let $f(x) = x^p$ with x > 0 and $0 . Since <math>f''(x) = p(p-1)x^{p-2} < 0$ for any x > 0, f(x) is concave. Thus, we have

$$(x_i + y_i)^p = \left(t \cdot \frac{x_i}{t} + (1 - t) \cdot \frac{y_i}{1 - t}\right)^p, \quad 0 < t < 1, i \in \{1, 2, \dots, n\}$$

$$\ge t \cdot \frac{x_i^p}{t^p} + (1 - t) \cdot \frac{y_i^p}{(1 - t)^p}.$$

Taking summation over i gives

$$\sum_{i=1}^{n} (x_i + y_i)^p \ge t \sum_{i=1}^{n} \frac{x_i^p}{t^p} + \frac{y_i^p}{(1-t)^p}$$
$$\|\mathbf{x} + \mathbf{y}\|_p^p \ge t \frac{\|\mathbf{x}\|_p^p}{t^p} + (1-t) \frac{\|\mathbf{y}\|_p^p}{(1-t)^p}$$

Letting $t = \frac{\|\mathbf{x}\|_p}{\|\mathbf{x}\|_p + \|\mathbf{y}\|_p}$ yields

$$\begin{aligned} \|\mathbf{x} + \mathbf{y}\|_{p}^{p} & \geq t \frac{\|\mathbf{x}\|_{p}^{p}}{\|\mathbf{x}\|_{p}^{p}} + (1 - t) \frac{\|\mathbf{y}\|_{p}^{p}}{\|\mathbf{y}\|_{p}^{p}} \\ & = t(\|\mathbf{x}\|_{p} + \|\mathbf{y}\|_{p})^{p} + (1 - t)(\|\mathbf{x}\|_{p} + \|\mathbf{y}\|_{p})^{p} \\ & = (\|\mathbf{x}\|_{p} + \|\mathbf{y}\|_{p})^{p} + (1 - t)(\|\mathbf{x}\|_{p} + \|\mathbf{y}\|_{p})^{p} \\ & = (\|\mathbf{x}\|_{p} + \|\mathbf{y}\|_{p})^{p} \\ \implies \|\mathbf{x} + \mathbf{y}\|_{p} & \geq \|\mathbf{x}\|_{p} + \|\mathbf{y}\|_{p}, \end{aligned}$$

67 as desired.

Remark 1.12. You may observe that the reversed Minkowski's inequality does not hold when $\mathbf{x} = -\mathbf{y} \neq 0$. The reason is that in the above proof, the condition $x_i, y_i \geq 0, \forall i$ is required to ensure that f(x) is concave and well defined. Concretely speaking, $\sqrt[3]{x}$ is convex on \mathbb{R}_- and $\sqrt[4]{x}$ is not well defined on \mathbb{R}_- . Hence, the reversed Minkowski's inequality only works for both vectors with nonnegative entries. Note that Minkowski's inequality works not only for $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ but also for $\mathbf{x}, \mathbf{y} \in \mathbb{C}^n$.

Extensions

Since $\|\cdot\|_0$ does not satisfy the positive homogeneity, it is not a true norm.

Exercise 1.2

Prove that for any $\mathbf{x} \in \mathbb{R}^n$ one has

$$\|\mathbf{x}\|_{\infty} = \lim_{p \to \infty} \|\mathbf{x}\|_p.$$

70

Proof. Since the definitions $\|\mathbf{x}\|_{\infty} \equiv \max_{i=1,2,...,n} |x_i|$ and $\|\mathbf{x}\|_p \equiv \sqrt[p]{\sum_{i=1}^n |x_i|^p}$, we only need to show $\lim_{p\to\infty} \|\mathbf{x}\|_p = \max_{i=1,2,...,n} |x_i|$. Given any $\mathbf{x} \in \mathbb{R}^n$ where n is a finite positive integer, we have

$$\lim_{p \to \infty} \sqrt[p]{\left(\max_{i=1,2,\dots,n} |x_i|\right)^p} \le \lim_{p \to \infty} \sqrt[p]{\sum_{i=1}^n |x_i|^p} \le \lim_{p \to \infty} \sqrt[p]{\left(n \cdot \max_{i=1,2,\dots,n} |x_i|\right)^p}$$

$$\lim_{i=1,2,\dots,n} |x_i| \le \lim_{p \to \infty} \sqrt[p]{\sum_{i=1}^n |x_i|^p} \le \lim_{p \to \infty} \sqrt[p]{n} \cdot \max_{i=1,2,\dots,n} |x_i|$$

$$\lim_{p \to \infty} \sqrt[p]{\sum_{i=1}^n |x_i|^p} = \max_{i=1,2,\dots,n} |x_i|.$$

This completes our proof.

Exercise 1.3

71

Show that for any $\mathbf{x}, \mathbf{y}, \mathbf{z} \in \mathbb{R}^n$

$$\|\mathbf{x} - \mathbf{z}\| \le \|\mathbf{x} - \mathbf{y}\| + \|\mathbf{y} - \mathbf{z}\|.$$

Proof. Here, $\|\cdot\|$ refers to the vector norm $\|\cdot\|_2$ whose subscript is frequently omitted for brevity. By the definition of the vector norm, $\|\cdot\|_2$ satisfies the triangle inequality as follows.

$$\|\mathbf{x} - \mathbf{z}\|_2 = \|\mathbf{x} - \mathbf{y} + \mathbf{y} - \mathbf{z}\|_2$$
$$\leq \|\mathbf{x} - \mathbf{y}\| + \|\mathbf{y} - \mathbf{z}\|_2$$

74 as desired. □

Exercise 1.4

Prove the Cauchy-Schwarz inequality (Lemma 1.5)

$$\|\mathbf{x}^T \mathbf{y}\| < \|\mathbf{x}\|_2 \cdot \|\mathbf{y}\|_2, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^n.$$
 (14)

Show that equality holds if and only if the vectors \mathbf{x} and \mathbf{y} are linearly dependent.

Proof. This lemma can be concisely proved via the following formula from geometry.

$$\mathbf{x}^T \mathbf{y} = \|\mathbf{x}\|_2 \cdot \|\mathbf{y}\|_2 \cdot \cos \theta \tag{15}$$

where θ denotes the angle between x and y. Since $|\cos \theta| < 1$, it follows that

$$-\|\mathbf{x}\|_{2} \cdot \|\mathbf{y}\|_{2} \leq \mathbf{x}^{T} \mathbf{y} = \|\mathbf{x}\|_{2} \cdot \|\mathbf{y}\|_{2} \cdot \cos \theta \leq \|\mathbf{x}\|_{2} \cdot \|\mathbf{y}\|_{2}$$

$$\tag{16}$$

where the equality holds if and only if $|\cos \theta| = 1$ which geometrically implies that \mathbf{x} and \mathbf{y} are parallel to each other, in other words, \mathbf{x} and \mathbf{y} are linearly dependent. If we express (16) in a compact way, then we get

$$|\mathbf{x}^T \mathbf{y}| \le ||\mathbf{x}||_2 \cdot ||\mathbf{y}||_2, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^n.$$
 (17)

This completes the proof.

Exercise 1.5

Suppose that \mathbb{R}^m and \mathbb{R}^n are equipped with norms $\|\cdot\|_b$ and $\|\cdot\|_a$, respectively. Show that the induced matrix norm $\|\cdot\|_{a,b}$ satisfies the triangle inequality. That is, for any $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{m \times n}$ the inequality

$$\|\mathbf{A} + \mathbf{B}\|_{a,b} \le \|\mathbf{A}\|_{a,b} + \|\mathbf{B}\|_{a,b}$$
 (18)

holds.

Proof. By the definition of the induced norm, namely (1),

$$\|\mathbf{A} + \mathbf{B}\|_{a,b} = \max_{\mathbf{x}} \{ \|(\mathbf{A} + \mathbf{B})\mathbf{x}\|_b \colon \|\mathbf{x}\|_a \le 1 \}$$

$$\tag{19}$$

$$= \max_{\mathbf{x}} \{ \|\mathbf{A}\mathbf{x} + \mathbf{B}\mathbf{x}\|_b \colon \|\mathbf{x}\|_a \le 1 \}$$
 (20)

$$\leq \max_{\mathbf{x}} \{ \|\mathbf{A}\mathbf{x}\|_b + \|\mathbf{B}\mathbf{x}\|_b \colon \|\mathbf{x}\|_a \leq 1 \}$$
 (21)

$$\leq \max_{\mathbf{x}} \{ \|\mathbf{A}\mathbf{x}\|_{b} \colon \|\mathbf{x}\|_{a} \leq 1 \} + \max_{\mathbf{x}} \{ \|\mathbf{B}\mathbf{x}\|_{b} \colon \|\mathbf{x}\|_{a} \leq 1 \}$$
 (22)

$$= \|\mathbf{A}\|_{a,b} + \|\mathbf{B}\|_{a,b} \tag{23}$$

where the first inequality follows from the triangle inequality. This completes the proof. \Box

Exercise 1.6

Let $\|\cdot\|$ be a norm on \mathbb{R}^n . Show that the norm function $f(\mathbf{x}) = \|\mathbf{x}\|$ is a continuous function over \mathbb{R}^n .

Proof. As we know, the continuity of $f(\mathbf{x})$ at a point \mathbf{x}_0 requires that, for any $\epsilon > 0$ and the point \mathbf{x}_0 in the domain \mathcal{D} of f, there always exists a δ such that $|f(\mathbf{x}) - f(\mathbf{x}_0)| < \epsilon$ whenever $\mathbf{x} \in \mathcal{D}$ and $||\mathbf{x} - \mathbf{x}_0|| < \delta$. Here, any nonnegative $\delta < \epsilon$ will satisfy this requirement. To see this, we need to analyze two cases. For the case when $||\mathbf{x}|| > ||\mathbf{x}_0||$,

 $|f(\mathbf{x}) - f(\mathbf{x}_0)| = ||\mathbf{x}|| - ||\mathbf{x}_0|| \tag{24}$

$$= \|\mathbf{x} - \mathbf{x}_0 + \mathbf{x}_0\| - \|\mathbf{x}_0\| \tag{25}$$

$$\leq \|\mathbf{x} - \mathbf{x}_0\| + \|\mathbf{x}_0\| - \|\mathbf{x}_0\| \tag{26}$$

$$= \|\mathbf{x} - \mathbf{x}_0\| < \delta < \epsilon. \tag{27}$$

The case of $\|\mathbf{x}\| = \|\mathbf{x}_0\|$ is trivial. For the case when $\|\mathbf{x}\| < \|\mathbf{x}_0\|$,

$$|f(\mathbf{x}) - f(\mathbf{x}_0)| = ||\mathbf{x}_0|| - ||\mathbf{x}|| \tag{28}$$

$$= \|\mathbf{x}_0 - \mathbf{x} + \mathbf{x}\| - \|\mathbf{x}\| \tag{29}$$

$$\leq \|\mathbf{x} - \mathbf{x}_0\| + \|\mathbf{x}\| - \|\mathbf{x}\| \tag{30}$$

$$= \|\mathbf{x} - \mathbf{x}_0\| < \delta < \epsilon. \tag{31}$$

Since the above argument holds for any $\mathbf{x}_0 \in \mathbb{R}^n$, it follows that $f(\mathbf{x}) = \|\mathbf{x}\|$ is continuous over \mathbb{R}^n .

This completes the proof.

Exercise 1.7

(attainment of the maximum in the induced norm definition) Suppose that \mathbb{R}^m and \mathbb{R}^n are equipped with norms $\|\cdot\|_b$ and $\|\cdot\|_a$, respectively, and let $\mathbf{A} \in \mathbb{R}^{m \times n}$. Show that there exists $\mathbf{x} \in \mathbb{R}^n$ such that $\|\mathbf{x}\|_a \leq 1$ and $\|\mathbf{A}\mathbf{x}\|_b = \|\mathbf{A}\|_{a,b}$.

82 83

Proof. Define the set $C = \{\mathbf{x} \in \mathbb{R}^n | \|\mathbf{x}\|_a \le 1\}$. It is easy to see that C contains all the limits of convergent sequences of points in C, so C is closed. We can find a positive number M, say 2, such that $C \subset B(\mathbf{0}, M)$, so C is bounded. Since $\mathbf{0} \in C$, C is nonempty. Thus, C is a nonempty and compact set. From Exercise 1.6, since $\|\cdot\|_b$ is a norm, $\|\mathbf{A}\mathbf{x}\|_b$ is continuous. According to Weierstrass theorem (see Theorem 2.30 in the textbook), there exists a global minimum of f and a global maximum of f over C. By the definition of the induced norm, the maximum is denoted $\|\mathbf{A}\|_{a,b}$. This completes our proof.

Exercise 1.8

Suppose that \mathbb{R}^m and \mathbb{R}^n are equipped with norms $\|\cdot\|_b$ and $\|\cdot\|_a$, respectively. Show that the induced matrix norm $\|\cdot\|_{a,b}$ can be computed by the formula

$$\|\mathbf{A}\|_{a,b} = \max_{\mathbf{x}} \{ \|\mathbf{A}\mathbf{x}\|_b : \|\mathbf{x}\|_a = 1 \}.$$
 (32)

9

Proof. By the definition of the induced norm, the claim is equivalent to proving that the maxima are achieved at \mathbf{x}^* satisfying $\|\mathbf{x}^*\| = 1$, which has been shown in Lemma 1.1.

Exercise 1.9

Suppose that \mathbb{R}^m and \mathbb{R}^n are equipped with norms $\|\cdot\|_b$ and $\|\cdot\|_a$, respectively. Show that the induced matrix norm $\|\cdot\|_{a,b}$ can be computed by the formula

$$\|\mathbf{A}\|_{a,b} = \max_{\mathbf{x} \neq \mathbf{0}} \frac{\|\mathbf{A}\mathbf{x}\|_b}{\|\mathbf{x}\|_a}.$$
 (33)

9:

Proof. This is exactly Lemma 2 which includes a proof.

Exercise 1.10

Let $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{B} \in \mathbb{R}^{n \times k}$ and assume that \mathbb{R}^m , \mathbb{R}^n , \mathbb{R}^k are equipped with the norms $\|\cdot\|_c$, $\|\cdot\|_b$, and $\|\cdot\|_a$, respectively. Prove that

$$\|\mathbf{A}\mathbf{B}\|_{a,c} \le \|\mathbf{A}\|_{b,c} \|\mathbf{B}\|_{a,b}.$$
 (34)

95

Proof. From Exercise 1.9, we have

$$\|\mathbf{A}\mathbf{B}\|_{a,c} \le \frac{\|\mathbf{A}\mathbf{B}\mathbf{x}\|_c}{\|\mathbf{x}\|_a} \tag{35}$$

where $\mathbf{x} \neq \mathbf{0}$. For every $\mathbf{x} \neq \mathbf{0}$, if $\mathbf{B}\mathbf{x} = \mathbf{0}$, then $\mathbf{B} = \mathbf{0}$ must hold, in which case the claim is obviously true. When $\mathbf{B}\mathbf{x} \neq \mathbf{0}$, let $\mathbf{y} = \mathbf{B}\mathbf{x}$ and then,

$$\|\mathbf{A}\mathbf{B}\|_{a,c} \le \frac{\|\mathbf{A}\mathbf{y}\|_c}{\|\mathbf{y}\|_b} \frac{\|\mathbf{B}\mathbf{x}\|_b}{\|\mathbf{x}\|_a} \le \|\mathbf{A}\|_{b,c} \|\mathbf{B}\|_{a,b}.$$
 (36)

This completes the proof.

Exercise 1.11

Prove the formula of the ∞ -matrix norm given in Example 1.9 of the textbook. Specifically, given $\mathbf{A} \in \mathbb{R}^{m \times n}$,

$$\|\mathbf{A}\|_{\infty} = \max_{i=1,2,\dots,m} \sum_{j=1}^{n} |A_{i,j}|. \tag{37}$$

Proof. From Exercise 1.8, the induced norm $\|\mathbf{A}\|_{\infty}$ can also be computed by

$$\|\mathbf{A}\|_{\infty} = \max_{\mathbf{x}} \{ \|\mathbf{A}\mathbf{x}\|_{\infty} \colon \|\mathbf{x}\|_{\infty} = 1 \}$$
(38)

$$= \max_{\mathbf{x}} \left\{ \max_{i=1,\dots,m} |\sum_{j=1}^{n} A_{ij} x_j| : \max_{j=1,\dots,n} |x_j| = 1 \right\}$$
 (39)

$$= \max_{\mathbf{x}} \left\{ \max_{i=1,\dots,m} \sum_{j=1}^{n} |A_{ij}x_{j}| : \max_{j=1,\dots,n} |x_{j}| = 1 \right\}$$
 (40)

$$= \max_{i=1,\dots,m} \sum_{j=1}^{n} |A_{ij} \operatorname{sign}(A_{ij})| = \max_{i=1,\dots,m} \sum_{j=1}^{n} |A_{ij}|$$
(41)

where $sign(A_{ij}) = 1$ if $A_{ij} \ge 0$ otherwise $sign(A_{ij}) = -1$. Note that, besides the last line, (40) also makes use of the constraint $|x_j| \le 1$ for every $j \in \{1, ..., n\}$.

Exercise 1.12

Let $\mathbf{A} \in \mathbb{R}^{m \times n}$. Prove that

(i)
$$\frac{1}{\sqrt{n}} \|\mathbf{A}\|_{\infty} \le \|\mathbf{A}\|_{2} \le \sqrt{m} \|\mathbf{A}\|_{\infty}$$
,

(ii)
$$\frac{1}{\sqrt{m}} \|\mathbf{A}\|_1 \le \|\mathbf{A}\|_2 \le \sqrt{n} \|\mathbf{A}\|_1$$
.

Proof. Before we prove the claimed 4 inequalities, we have

$$\|\mathbf{A}\|_{2} = \max_{\|\mathbf{x}\|_{2}=1} \|\mathbf{A}\mathbf{x}\|_{2}$$
 (Definition of $\|\mathbf{A}\|_{2}$)

$$= \max_{\|\mathbf{x}\|_2 = 1} \sqrt{\sum_{i=1}^m \left(\sum_{j=1}^n A_{ij} x_j\right)^2}$$
 (Definition of $\|\mathbf{A}\|_2$) (43)

$$= \max_{\|\mathbf{x}\|_{2}=1} \sqrt{\sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}| |x_{j}|\right)^{2}}$$
 (\forall j, sgn(x_{j}) does not change \|\mathbf{x}\|_{2}) \] (44)

Given this, for Part (i), we first show the second inequality.

$$\max_{\|\mathbf{x}\|_{2}=1} \sqrt{\sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}| |x_{j}|\right)^{2}} \leq \max_{\|\mathbf{x}\|_{\infty}=1} \sqrt{\sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}| |x_{j}|\right)^{2}} \quad (\{\mathbf{x} \mid \|x\|_{2}=1\} \subset \{\mathbf{x} \mid \|x\|_{\infty}=1\})$$

$$(45)$$

$$= \sqrt{\sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}|\right)^{2}}$$
 (Maximum is attained at $|x_{i}| = 1 \ \forall i$)
$$\leq \sqrt{\sum_{i=1}^{m} \left(\max_{i=1,\dots,m} \sum_{j=1}^{n} |A_{ij}|\right)^{2}}$$
 ($u_{i} \leq \max_{i} |u_{i}|, \ \forall i$) (47)
$$= \sqrt{\sum_{i=1}^{m} (\|\mathbf{A}\|_{\infty})^{2}} = \sqrt{m} \|\mathbf{A}\|_{\infty}$$
 (Definition of $\|\mathbf{A}\|_{\infty}$) (48)

as desired. Now we prove the first inequality of Part (i).

$$\max_{\|\mathbf{x}\|_{2}=1} \sqrt{\sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}| |x_{j}|\right)^{2}} \ge \sqrt{\sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}| \cdot \frac{1}{\sqrt{n}}\right)^{2}} \qquad \left(\sum_{j=1}^{n} \left(\frac{1}{\sqrt{n}}\right)^{2} = 1\right) \qquad (49)$$

$$= \sqrt{\frac{1}{n} \sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}|\right)^{2}} \qquad \left(\left(\frac{1}{\sqrt{n}}\right)^{2} = \frac{1}{n}\right) \qquad (50)$$

$$\ge \sqrt{\max_{i=1,\dots,m} \frac{1}{n} \left(\sum_{j=1}^{n} |A_{ij}|\right)^{2}} \qquad \left(\sum_{i} |u_{i}| \ge \max_{i} |u_{i}| \, \forall i\right) \qquad (51)$$

$$= \frac{1}{\sqrt{n}} \max_{i=1,\dots,m} \sum_{j=1}^{n} |A_{ij}| = \frac{1}{\sqrt{n}} \|\mathbf{A}\|_{\infty} \quad (\text{Definition of } \|\mathbf{A}\|_{\infty}) \qquad (52)$$

For part (ii), we first consider the left inequality.

$$\max_{\|\mathbf{x}\|_{2}=1} \sqrt{\sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}| |x_{j}|\right)^{2}} = \sqrt{m} \cdot \max_{\|\mathbf{x}\|_{2}=1} \frac{\sum_{i=1}^{m} \sum_{j=1}^{n} |A_{ij}| |x_{j}|}{m} \qquad (AM-QM \text{ inequality})$$

$$= \frac{1}{\sqrt{m}} \cdot \max_{\|\mathbf{x}\|_{2}=1} \sum_{j=1}^{n} |x_{j}| \left(\sum_{i=1}^{m} |A_{ij}|\right) \qquad \left(\forall m, n < \infty, \sum_{i=1}^{m} \sum_{j=1}^{n} = \sum_{j=1}^{n} \sum_{i=1}^{m} \right)$$

$$= \frac{1}{\sqrt{m}} \cdot \max_{\|\mathbf{x}\|_{2}=1} \sqrt{\sum_{j=1}^{n} |x_{j}|^{2}} \sqrt{\sum_{j=1}^{n} \left(\sum_{i=1}^{m} |A_{ij}|\right)^{2}} \qquad (Cauchy-Schwarz inequality)$$

$$= \frac{1}{\sqrt{m}} \sqrt{\sum_{j=1}^{n} \left(\sum_{i=1}^{m} |A_{ij}|\right)^{2}} \qquad (\|\mathbf{A}\|_{2}=1) \qquad (56)$$

$$\geq \frac{1}{\sqrt{m}} \sqrt{\max_{j=1,...,n} \left(\sum_{i=1}^{m} |A_{ij}|\right)^{2}} \qquad \left(\sum_{i=1}^{m} |u_{i}| \forall i\right)$$

$$(57)$$

$$= \frac{1}{\sqrt{m}} \max_{j=1,\dots,n} \sum_{i=1}^{m} |A_{ij}| = \frac{1}{\sqrt{m}} \|\mathbf{A}\|_{1}$$
 (Definition of $\|\mathbf{A}\|_{1}$)
(58)

When applying the AM-GM inequality, the equality holds if and only if $\sum_{j=1}^{n} |A_{1j}x_j| = \cdots = 1$ $\sum_{j=1}^{n} |A_{mj}x_j|$, which is attainable. For Cauchy-Schwarz inequality, the equality holds if and only if $\sum_{i=1}^{m} |A_{ij}| = k|x_j|$ for all $j = 1, \ldots, n$ where k is a constant, which is attainable too. Now we show the inequality on the right hand side.

$$\max_{\|\mathbf{x}\|_{2}=1} \sqrt{\sum_{i=1}^{m} \left(\sum_{j=1}^{n} |A_{ij}| |x_{j}|\right)^{2}} \leq \max_{\|\mathbf{x}\|_{2}=1} \sqrt{\sum_{i=1}^{m} \sum_{j=1}^{n} A_{ij}^{2}} \sum_{j=1}^{n} x_{j}^{2} \quad \text{(Cauchy-Schwarz inequality)} \tag{59}$$

$$= \sqrt{\sum_{i=1}^{m} \sum_{j=1}^{n} A_{ij}^{2}} \qquad (\|\mathbf{x}\|_{2} = 1) \qquad (60)$$

$$= \sqrt{\sum_{j=1}^{n} \sum_{i=1}^{m} |A_{ij}|^{2}} \qquad \left(\forall m, n < \infty, \sum_{i=1}^{m} \sum_{j=1}^{n} = \sum_{i=1}^{n} \sum_{i=1}^{m}\right)$$

$$\leq \sqrt{\sum_{j=1}^{n} \left(\sum_{i=1}^{m} |A_{ij}|\right)^{2}} \qquad \left(\forall a_{i} \geq 0, \sum_{i=1}^{m} a_{i}^{2} \leq \left(\sum_{i=1}^{m} a_{i}\right)^{2}\right) \tag{62}$$

$$\leq \sqrt{\sum_{j=1}^{n} \left(\max_{j=1,\dots,n} \sum_{i=1}^{m} |A_{ij}|\right)^{2}} \qquad (u_{i} \leq \max_{i} |u_{i}|, \forall i) \qquad (63)$$

$$= \sqrt{n} \cdot \max_{j=1,\dots,n} \sum_{i=1}^{m} |A_{ij}| \qquad \left(\sum_{j=1}^{n} c = nc\right)$$

$$= \sqrt{n} \|\mathbf{A}\|_{1} \qquad \text{(Definition of } \|\mathbf{A}\|_{1})$$
(65)

where in the first line the equality holds if and only if $|A_{ij}| = k_i |x_j|$ for all $i = 1, \ldots, m$ and $j=1,\ldots,n$, and k_i is a constant, which is not necessarily attainable. This completes the proof. \square

Exercise 1.13

Let $\mathbf{A} \in \mathbb{R}^{m \times n}$. Show that (i) $\|\mathbf{A}\| = \|\mathbf{A}^T\|$ (here $\|\cdot\|$ is the spectral norm),

(ii) $\|\mathbf{A}\|_F^2 = \sum_{i=1}^n \lambda_i(\mathbf{A}^T \mathbf{A}).$

Proof. For part (i), the spectral norm is defined by

$$\|\mathbf{A}\|_{2} = \sqrt{\lambda_{\max}(\mathbf{A}^{T}\mathbf{A})} = \sigma_{\max}(\mathbf{A})$$
(66)

where $\lambda_{\max}(\mathbf{A}^T\mathbf{A})$ is the maximum eigenvalue of $\mathbf{A}^T\mathbf{A}$, and $\sigma_{\max}(\mathbf{A})$ is the largest singular values of A. Similarly,

$$\|\mathbf{A}^T\|_2 = \sqrt{\lambda_{\max}(\mathbf{A}\mathbf{A}^T)} = \sigma_{\max}(\mathbf{A}^T)$$
(67)

By the Theorem 2.6.3(a) in Horn and Johnson (2013), the singular values are supposed to be nonnegative. And by the Theorem 2.6.3(b) in Horn and Johnson (2013), the nonzero eigenvalues of $\mathbf{A}\mathbf{A}^T$ and $\mathbf{A}^T\mathbf{A}$ are identical. Thus,

$$\|\mathbf{A}\|_{2} = \sqrt{\lambda_{\max}(\mathbf{A}^{T}\mathbf{A})} = \sqrt{\lambda_{\max}(\mathbf{A}\mathbf{A}^{T})} = \|\mathbf{A}^{T}\|_{2}$$
(68)

as desired.

Now we consider part (ii).

$$\|\mathbf{A}\|_F^2 = \sum_{i=1}^m \sum_{j=1}^n A_{ij}^2 \qquad \text{(Definition of Frobenius norm)}$$

$$= Tr(\mathbf{A}^T \mathbf{A}) \qquad (Definition of trace) \tag{70}$$

$$= \sum_{n=1}^{n} \lambda_i(\mathbf{A}^T \mathbf{A}) \tag{71}$$

where the last line follows from the following argument². By definition, the characteristic polynomial of $\mathbf{A}^T \mathbf{A}$ is given by

$$p(t) = \det(t\mathbf{I} - \mathbf{A}^T \mathbf{A}) \tag{72}$$

$$=t^{n}-\operatorname{Tr}(\mathbf{A}^{T}\mathbf{A})t^{n-1}+\cdots+(-1)^{n}\operatorname{det}(\mathbf{A}^{T}\mathbf{A})$$
 (Definition of determinant) (73)

Also, by the definition, eigenvalues are the roots of p(t). Hence,

$$p(t) = (t - \lambda_1)(t - \lambda_2) \cdots (t - \lambda_n)$$
(74)

By comparing coefficients, we have

$$Tr(\mathbf{A}^T \mathbf{A}) = \sum_{i=1}^n \lambda_i(\mathbf{A}^T \mathbf{A})$$
 (75)

which completes the proof.

Exercise 1.14

109

110

Let $\mathbf{A} \in \mathbb{R}^{n \times n}$ be a symmetric matrix. Show that

$$\max_{\mathbf{x}} \{ \mathbf{x}^T \mathbf{A} \mathbf{x} : ||\mathbf{x}||^2 = 1 \} = \lambda_{\max}(\mathbf{A}).$$
 (76)

The inspiration of the following proof is from the proof of Lemma 1.11 in the textbook.

Proof. According to the spectral decomposition theorem there exists an orthogonal matrix $\mathbf{U} \in \mathbb{R}^{n \times n}$ and a diagonal matrix $\mathbf{D} = \operatorname{diag}(d_1, d_2, \dots, d_n)$ such that $\mathbf{U}^T \mathbf{A} \mathbf{U} = \mathbf{D}$. Without the loss of generality, we can assume that the diagonal elements of **D**, which are the eigenvalues of **A**, are ordered nonincreasingly: $d_1 \geq d_2 \geq \cdots \geq d_n$, where $d_1 = \lambda_{\max}(\mathbf{A})$. Since **U** is an orthogonal matrix, we can make the change of variables $\mathbf{x} = \mathbf{U}\mathbf{y}$.

$$\max_{\|\mathbf{x}\|_{2}^{2}=1} \mathbf{x}^{T} \mathbf{A} \mathbf{x} = \max_{\|\mathbf{U}\mathbf{y}\|_{2}^{2}=1} (\mathbf{U}\mathbf{y})^{T} \mathbf{A} \mathbf{U} \mathbf{y}$$

$$= \max_{\|\mathbf{y}\|_{2}^{2}=1} \mathbf{y}^{T} \mathbf{U}^{T} \mathbf{A} \mathbf{U} \mathbf{y}$$

$$(\|\mathbf{U}\mathbf{y}\|_{2}^{2} = \|\mathbf{y}\|_{2}^{2})$$
(77)

$$= \max_{\|\mathbf{y}\|_{2}^{2}=1} \mathbf{y}^{T} \mathbf{U}^{T} \mathbf{A} \mathbf{U} \mathbf{y} \qquad (\|\mathbf{U} \mathbf{y}\|_{2}^{2} = \|\mathbf{y}\|_{2}^{2})$$
 (78)

²https://math.stackexchange.com/questions/546155/proof-that-the-trace-of-a-matrix-is-the-sum-of-its-eigenvalues

$$= \max_{\|\mathbf{y}\|_2^2 = 1} \mathbf{y}^T \mathbf{D} \mathbf{y} \tag{U}^T \mathbf{A} \mathbf{U} = \mathbf{D}) \tag{79}$$

$$= \max_{\|\mathbf{y}\|_{2}^{2}=1} \sum_{i=1}^{n} d_{i} y_{i}^{2} \leq d_{1} \max_{\|\mathbf{y}\|_{2}^{2}=1} \sum_{i=1}^{n} y_{i}^{2} \qquad (d_{1} \geq d_{2} \geq \dots \geq d_{n})$$
 (80)

$$=d_1 = \lambda_{\max}(\mathbf{A}) \tag{81}$$

Exercise 1.15

111

112

113

114

116

117

118

120

121

122

123

137

Prove that a set $U \subseteq \mathbb{R}^n$ is closed if and only if its complement U^c is open.

Proof. We first prove the sufficiency. Given U^c is open, we suppose that U is not closed. Then there must exist at least one accumulation point of U, say x, such that $x \notin U$, i.e., $x \in U^c$. Since U^c is open, then there exists an open ball $B(x,r) \subseteq U^c$ with r > 0, which contradicts $x \in U'$ where U' denotes the set of accumulation points of U. Specifically, since $x \in U'$, by Definition 1.4, there are infinitely many points of B(x,r) belonging to U, which is impossible for $B(x,r) \subseteq U^c$.

Now we show the necessity. Given any point $x \in U^c$, it suffices to show that x is an interior point of U^c . Obviously, $x \notin U$. Since U is closed, x is not an accumulation point of U. By Definition 1.5, this implies that there exists an open ball B(x,r) such that $B(x,r) \cap U = \emptyset$. Thus, $B(x,r) \subseteq U^c$. This completes our proof.

Exercise 1.16

- 1. Let $\{A_i\}_{i\in I}$ be a collection of open sets where I is a given index set. Show that $\bigcup_{i\in I} A_i$ is an open Set. Show that if I is finite, then $\bigcap_{i\in I} A_i$ is open.
- 2. Let $\{A_i\}_{i\in I}$ be a collection of closed sets where I is a given index set. Show that $\bigcap_{i\in I} A_i$ is a closed Set. Show that if I is finite, then $\bigcup_{i\in I} A_i$ is closed.

The following proof is taken from the proof of Theorem 11.1.5 in Chen et al. (2019).

124 Proof.

- 1. For any $\mathbf{x} \in \bigcup_{i \in I} A_i$, then there exists at least an $i \in I$ such that $\mathbf{x} \in A_i$. Since A_i is an open set, then \mathbf{x} is an interior point of A_i . Also, \mathbf{x} is an interior point of $\bigcup_{i \in I} A_i$. Thus, $\bigcup_{i \in I} A_i$ is an open set.
- Since I is finite, suppose there are k sets in total. For any $\mathbf{x} \in \bigcap_{i \in I} A_i$, $x \in A_i$ for arbitrary $i = 1, \ldots, k$. Thus, for any $i \in I$, there exists an $r_i > 0$ such that $B(\mathbf{x}, r_i) \subset A_i$. Let $r = \min_{i \in I} r_i$, then $B(\mathbf{x}, r) \subset \bigcap_{i \in I} A_i$. Therefore, $\bigcap_{i \in I} A_i$ is open.
- 2. By De Morgan's Theorem (see Theorem 1.10), $(\bigcap_{i\in I} A_i)^c = \bigcup_{i\in I} A_i^c$. Since A_i is closed, its complement A_i^c is open. From the first part of this proof, $\bigcup_{i\in I} A_i^c$ is open. Thus, its complement $\bigcap_{i\in I} A_i$ is closed.
- If each A_i is closed, then A_i^c is open. If I is finite, by the first part of this proof, $\bigcap_{i \in I} A_i^c$ is open.

 According to De Morgan's Theorem, its complement is $\bigcup_{i \in I} A_i$ which is closed. This completes the proof.

Exercise 1.17

Give an example of open sets A_i , $i \in I$ for which $\bigcap_{i \in I} A_i$ is not open.

The following solution is from Mathematics Stack Exchange³.

Solution: Let \mathbb{Z}_+ denote the set of positive integers. When A_i is defined as

$$A_i = (-\frac{1}{i}, \frac{1}{i}), \quad i \in \mathbb{Z}_+,$$

the intersection

138

139

141

142

144

145

149

$$\bigcap_{i\in\mathbb{Z}_+}A_i=[0]$$

is not open. However, it is a closed set.

Extensions

Likewise, we can construct an example of closed sets A_i , $i \in \mathbb{Z}_+$ for which $\bigcup_{i \in \mathbb{Z}_+} A_i$ is not closed. For example, the union of the closed sets $A_i = [\frac{1}{i}, 2 - \frac{1}{i}], \forall i \in \mathbb{Z}_+$ is (0, 2) which is an open set.

Exercise 1.18

Let $A, B \subseteq \mathbb{R}^n$. Prove that $\operatorname{cl}(A \cap B) \subseteq \operatorname{cl}(A) \cap \operatorname{cl}(B)$. Give an example in which the inclusion is proper.

This proof is from Mathematics Stack Exchange⁴.

Proof. By the definition of closure, i.e. Definition 1.7, $\operatorname{cl}(U) = U \cup \operatorname{bd}(U)$. since $A \cap B \subseteq A$, it follows that $\operatorname{cl}(A \cap B) \subseteq \operatorname{cl}(A)$. Likewise, $\operatorname{cl}(A \cap B) \subseteq \operatorname{cl}(B)$. Thus, $\operatorname{cl}(A \cap B) \subseteq \operatorname{cl}(A) \cap \operatorname{cl}(B)$ as desired.

Given A = (0,1) and B = (1,2), then $A \cap B = \emptyset$ and $\operatorname{cl}(A \cap B) = \emptyset$. On the other hand, $\operatorname{cl}(A) = [0,1]$ and $\operatorname{cl}(B) = [1,2]$. Thus, $\operatorname{cl}(A) \cap \operatorname{cl}(B) = \{1\}$. Obviously, $\emptyset \neq \{1\}$. Hence, the inclusion is proper in this case.

Exercise 1.19

Let $A, B \subseteq \mathbb{R}^n$. Prove that $\operatorname{int}(A \cap B) = \operatorname{int}(A) \cap \operatorname{int}(B)$ and that $\operatorname{int}(A) \cup \operatorname{int}(B) \subseteq \operatorname{int}(A \cup B)$. Show an example in which the latter inclusion is proper.

• *Proof.* The first part of the following proof is from a YouTube video⁵.

1. $int(A \cap B) \subseteq int(A) \cap int(B)$ follows from

$$A \cap B \subseteq A \Rightarrow \operatorname{int}(A \cap B) \subseteq \operatorname{int}(A)$$
 (82)

$$A \cap B \subseteq B \Rightarrow \operatorname{int}(A \cap B) \subseteq \operatorname{int}(B)$$
 (83)

 $int(A \cap B) \subseteq int(A) \cap int(B).$ (84)

 $^{^3 \}verb|https://math.stackexchange.com/questions/1460853/infinite-intersection-of-open-sets|$

⁴https://math.stackexchange.com/questions/1485869/closure-of-intersection-of-two-sets

⁵https://www.youtube.com/watch?v=uZZkMloQbd0

 $int(A) \cap int(B) \subseteq int(A \cap B)$ follows from

$$\operatorname{int}(A) \subseteq A, \quad \operatorname{int}(B) \subseteq B$$

$$\downarrow \downarrow$$

$$\operatorname{int}(A) \cap \operatorname{int}(B) \subseteq A \cap B. \tag{86}$$

(86)

Since the finite intersection of open sets is an open set (see Exercise 1.16(i)), then $int(A) \cap int(B)$ is open. By definition, the interior of a set is the largest open subset of that set, so $int(A \cap B)$ contains $\operatorname{int}(A) \cap \operatorname{int}(B)$. In other words, $\operatorname{int}(A) \cap \operatorname{int}(B) \subseteq \operatorname{int}(A \cap B)$. Therefore, $\operatorname{int}(A \cap B) =$ $int(A) \cap int(B)$.

2. $int(A) \cup int(B) \subseteq int(A \cup B)$ follows from

$$\operatorname{int}(A) \subseteq A, \quad \operatorname{int}(B) \subseteq B$$

$$\downarrow \downarrow$$

$$\operatorname{int}(A) \cup \operatorname{int}(B) \subseteq A \cup B.$$
(88)

$$int(A) \cup int(B) \subseteq A \cup B.$$
 (88)

In Exercise 1.16(i), we have shown that the union of open sets is open, so $int(A) \cup int(B)$ is an open set. By definition, the interior of $A \cup B$ is the largest open set of $A \cup B$. Thus, $\operatorname{int}(A \cup B)$ contains $\operatorname{int}(A) \cup \operatorname{int}(B)$. Hence, $\operatorname{int}(A) \cup \operatorname{int}(B) \subseteq \operatorname{int}(A \cup B)$.

For example, A = (0,1) and B = [1,2). It is easy to see that $int(A) \cup int(B) = (0,1) \cup (1,2)$, but $f(A \cup B) = (1,2)$. This inclusion is proper.

Chapter 2 Optimality Conditions for Unconstrained Opti- $\mathbf{2}$ mization

Exercise 2.1

Find the global minimum and maximum points of the function $f(x,y) = x^2 + y^2 + 2x - 3y$ over the unit ball $S = B[0,1] = \{(x,y) : x^2 + y^2 \le 1\}.$

163

151

152

153

154

155

156

157

158

159

160

161

162

Solution: By applying Cauchy-Swcharz inequality on 2x - 3y, we get

$$|2x - 3y| = \left| \begin{pmatrix} x & y \end{pmatrix} \begin{pmatrix} 2 \\ -3 \end{pmatrix} \right| \le \sqrt{2^2 + (-3)^2} \sqrt{x^2 + y^2} = \sqrt{13} \sqrt{x^2 + y^2}$$

$$\downarrow \downarrow$$

$$-\sqrt{13} \sqrt{x^2 + y^2} \le 2x - 3y \le \sqrt{13} \sqrt{x^2 + y^2}$$

where the equalities hold when -3x = 2y. Thus,

$$x^{2} + y^{2} - \sqrt{13}\sqrt{x^{2} + y^{2}} \le x^{2} + y^{2} + 2x - 3y \le x^{2} + y^{2} + \sqrt{13}\sqrt{x^{2} + y^{2}}$$

Let $t = \sqrt{x^2 + y^2}$, then the right hand side can be written as

$$f_{\text{RHS}}(t) = t^2 + \sqrt{13}t$$
, with $0 \le t \le 1$. (89)

Since $f'_{\rm RHS}(t)=2t+\sqrt{13}\geq 0$, then $f_{\rm RHS}(t)$ is increasing on [0,1]. So, the maximum can be attained at t=1. Thus, solving $x^2+y^2=1$ and -3x=2y gives $\underline{x}=2/\sqrt{13}$ and $y=-3/\sqrt{13}$ and $f(2/\sqrt{13}, -3/\sqrt{13}) = 1 + \sqrt{13}$, which is equal to $f_{RHS}(1) = 1 + \sqrt{13}$.

The left hand side is

$$f_{\text{LHS}}(t) = t^2 - \sqrt{13}t$$
, with $0 \le t \le 1$ (90)

Its derivative with respect to t is $f'_{LHS}(t) = 2t - \sqrt{13} < 0$ on [0,1], which means $f_{LHS}(t)$ is strictly decreasing on [0,1]. The minimum can be achieved at $t=\underline{1}$, i.e. $x^2+y^2=1$ and $f_{\text{LHS}}(1) = 1 - \sqrt{13}$. Given -3x = 2y, we obtain $x = -2/\sqrt{13}$ and $y = 3/\sqrt{13}$, which gives the desired 169 $f(-2/\sqrt{13}, 3/\sqrt{13}) = 1 - \sqrt{13}$. 170

To sum up, the global minimum and maximum points are $(x,y)=(2/\sqrt{13},-3/\sqrt{13})$ and 171 $(x,y) = (-2/\sqrt{13}, 3/\sqrt{13}),$ respectively.

Exercise 2.2

Let $\mathbf{a} \in \mathbb{R}^n$ be a nonzero vector. Show that the maximum of $\mathbf{a}^T \mathbf{x}$ over $B[0,1] = {\mathbf{x} \in \mathbb{R}^n :$ $\|\mathbf{x}\| \le 1$ is attained at $\mathbf{x}^* = \frac{\mathbf{a}}{\|\mathbf{a}\|}$ and that the maximal value is $\|\mathbf{a}\|$.

Proof. According to Cauchy-Schwarz inequality, we have

$$\mathbf{a}^T \mathbf{x} \le \|\mathbf{a}\| \|\mathbf{x}\| \tag{91}$$

the equality holds if and only if $\mathbf{x} = \lambda \mathbf{a}$ where $0 \neq \lambda \in \mathbb{R}$. Since $\mathbf{x} \leq 1$, the maximum of the right hand side can be achieved when $\|\mathbf{x}\| = 1$. Combining this with $\mathbf{x} = \lambda \mathbf{a}$, we get $\|\lambda \mathbf{a}\| = 1$ and $\lambda = \frac{1}{\|\mathbf{a}\|}$. 175 Thus, $\mathbf{x}^* = \lambda \mathbf{a} = \frac{\mathbf{a}}{\|\mathbf{a}\|}$ and the maximum value is $\|\mathbf{a}\| \|\mathbf{x}\| = \|\mathbf{a}\|$.

Exercise 2.3

177

181

182

Find the global minimum and maximum points of the function f(x,y) = 2x - 3y over the set $S = \{(x, y) : 2x^2 + 5y^2 \le 1\}.$

Solution: We can make use of the result in Exercise 2.2. To do this, we need to perform a change of 178 variables. Specifically, let $u = \sqrt{2}x$ and $v = \sqrt{5}y$. By doing this, the original problem is equivalently reformulated as finding the global minimum and maximum points of $\tilde{f}(u,v) = \sqrt{2}u - \frac{3\sqrt{5}}{5}v$ over the set $\tilde{S} = \{(u,v): u^2 + v^2 \le 1\}$. In this case, $\mathbf{a} = (\sqrt{2}, -\frac{3\sqrt{5}}{5})^T$. It follows from that the maximum point is $\frac{\mathbf{a}}{\|\mathbf{a}\|} = (\frac{5\sqrt{2}}{19}, -\frac{3\sqrt{5}}{19})^T$. Changing back to the original variables gives x = 5/19 and -3/19. Similarly, the minimum point is x = -5/19 and 3/19. 183

Exercise 2.4

Show that if A, B are $n \times n$ positive semidefinite matrices, then their sum A + B is also positive semidefinite.

Proof. Since \mathbf{A}, \mathbf{B} are semidefinite matrices, then $\mathbf{x}^T \mathbf{A} \mathbf{x} \geq 0$ and $\mathbf{x}^T \mathbf{B} \mathbf{x} \geq 0$ for every $\mathbf{x} \in \mathbb{R}^n$. It follows that

$$\mathbf{x}^{T}(\mathbf{A} + \mathbf{B})\mathbf{x} = \mathbf{x}^{T}\mathbf{A}\mathbf{x} + \mathbf{x}^{T}\mathbf{B}\mathbf{x} \ge 0$$
(92)

for every $\mathbf{x} \in \mathbb{R}^n$. Hence, $\mathbf{A} + \mathbf{B}$ is also positive semidefinite. This completes the proof.

Exercise 2.5

Let $\mathbf{A} \in \mathbb{R}^{n \times n}$ and $\mathbf{B} \in \mathbb{R}^{m \times m}$ be two symmetric matrices. Prove that the following two claims are equivalent:

i **A** and **B** are positive semidefinite.

ii
$$\begin{pmatrix} \mathbf{A} & \mathbf{0}_{n \times m} \\ \mathbf{0}_{m \times n} & \mathbf{B} \end{pmatrix}$$
 is positive semidefinite.

186

3 Chapter 3 Least Squares

Exercise 3.1

Let $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{b} \in \mathbb{R}^m$, $\mathbf{L} \in \mathbb{R}^{p \times n}$, and $\lambda \in \mathbb{R}_{++}$. Consider the regularized least squares problem

$$\min_{\mathbf{x} \in \mathbb{R}^n} \|\mathbf{A}\mathbf{x} - \mathbf{b}\|^2 + \lambda \|\mathbf{L}\mathbf{x}\|^2.$$
 (RLS)

Show that (RLS) has a unique solution if and only if $\text{Null}(\mathbf{A}) \cap \text{Null}(\mathbf{L}) = \{\mathbf{0}\}$, where here for a matrix \mathbf{B} , $\text{Null}(\mathbf{B})$ is the null space of \mathbf{B} given by $\{\mathbf{x} : \mathbf{B}\mathbf{x} = \mathbf{0}\}$.

188

195

Note that it is supposed to be $\mathbf{b} \in \mathbb{R}^m$ instead of $\mathbf{b} \in \mathbb{R}^n$. In the textbook, this is a typo which is not yet mentioned at http://www.siam.org/books/mo19/mo19_err.pdf.

Proof. Since the Hessian of the objective function is $2(\mathbf{A}^T\mathbf{A} + \lambda \mathbf{L}^T\mathbf{L}) \succeq \mathbf{0}$, it follows by Lemma 2.41 of the textbook that any stationary point is a global minimum point. Then, we have

(RLS) has a unique solution $\iff \mathbf{A}^T \mathbf{A} + \lambda \mathbf{L}^T \mathbf{L} \succ \mathbf{0}$

$$\mathbf{x}^{T}(\mathbf{A}^{T}\mathbf{A} + \lambda \mathbf{L}^{T}\mathbf{L})\mathbf{x} > 0, \forall \mathbf{x} \neq \mathbf{0} \iff \|\mathbf{A}\mathbf{x}\|^{2} + \lambda \|\mathbf{L}\mathbf{x}\|^{2} > 0, \forall \mathbf{x} \neq \mathbf{0}$$

There exists no nonzero ${\bf x}$ such that ${\bf A}{\bf x}={\bf 0}$ and ${\bf L}{\bf x}={\bf 0}$ hold simultaneously.

$$\mathbb{V}$$
 Null(\mathbf{A}) \cap Null(\mathbf{L}) = { $\mathbf{0}$ }.

191 This completes the proof.

Time completes the proof

¹⁹² 4 Chapter 4 The Gradient Method

Before working on the exercises of Chapter 4, we first introduce the notation of $f \in C_L^{k,p}(D)$. We write $f \in C_L^{k,p}(D)$ if

- 1. $f^{(k)}$ exists and is continuous on D.
- 2. $f^{(p)}$ is Lipschitz continuous with a constant L, namely,

$$||f^{(p)}(y_1) - f^{(p)}(y_2)|| \le L||y_1 - y_2||, \quad \forall y_1, y_2 \in D.$$

Exercise 4.1

Let $f \in C_L^{1,1}(\mathbb{R}^n)$ and let $\{\mathbf{x}^k\}_{k\geq 0}$ be the sequence generated by the gradient method with a constant stepsize $t_k = \frac{1}{L}$. Assume that $\mathbf{x}_k \to \mathbf{x}^*$. Show that if $\nabla f(\mathbf{x}_k) \neq \mathbf{0}$ for all $k \geq 0$, then \mathbf{x}^* is not a local maximum point.

Proof. Suppose \mathbf{x}^* is a local maximum point, then there exists a ball $B(\mathbf{x}^*, r)$ with any r > 0 such that

$$f(\mathbf{x}^*) \ge f(\mathbf{x}_k), \quad \forall \mathbf{x}_k \in B(\mathbf{x}^*, r)$$

Since $t_k = \frac{1}{L}$, by the descent lemma (Lemma 4.22 in the textbook), we have

$$f(\mathbf{x}^*) \leq f(\mathbf{x}_k) + \nabla f(\mathbf{x}_k)^T (\mathbf{x}^* - \mathbf{x}_k) + \frac{L}{2} \|\mathbf{x}^* - \mathbf{x}_k\|^2$$

$$= f(\mathbf{x}_k) + \nabla f(\mathbf{x}_k)^T (-\frac{1}{L} \nabla f(\mathbf{x}_k)) + \frac{L}{2} \|-\frac{1}{L} \nabla f(\mathbf{x}_k)\|^2$$

$$= f(\mathbf{x}_k) - \frac{1}{2L} \|\nabla f(\mathbf{x}_k)\|^2$$

$$< f(\mathbf{x}_k)$$

where the last line follows from that $\nabla f(\mathbf{x}_k) \neq \mathbf{0}$ for all $k \geq 0$. This contradicts the supposition, which implies that \mathbf{x}^* is not a local maximum point. This completes the proof.

- 5 Chapter 5 Newton's Method
- 200 6 Chapter 6 Convex Sets
- 7 Chapter 7 Convex Functions

Exercise 7.36

Prove that for any $x_1, x_2, \ldots, x_n \in \mathbb{R}_+$ the following inequality holds:

$$\frac{\sum_{i=1}^{n} x_i}{n} \le \sqrt{\frac{\sum_{i=1}^{n} x_i^2}{n}}$$

Proof. According to Cauchy-Schwartz inequality which says that given two vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, $\|\mathbf{x}\|_2 \|\mathbf{y}\|_2 \ge |\mathbf{x}^T \mathbf{y}|$, we have

$$\sqrt{\frac{\sum_{i=1}^{n} x_i^2}{n}} = \sqrt{\sum_{i=1}^{n} (\frac{|x_i|}{\sqrt{n}})^2} \cdot \sqrt{\sum_{i=1}^{n} (\frac{1}{\sqrt{n}})^2}$$

$$\geq \frac{\sum_{i=1}^{n} |x_i|}{n} \geq \frac{\sum_{i=1}^{n} x_i}{n},$$

where the equalities in the first and second inequalities hold if and only if $|x_1| = |x_2| = \cdots = |x_n|$ and $x_1 = x_2 = \cdots = x_n$, respectively. This completes the proof.

Exercise 7.37

Prove that for any $x_1, x_2, \dots, x_n \in \mathbb{R}_{++}$ the following inequality holds:

$$\frac{\sum_{i=1}^{n} x_i^2}{\sum_{i=1}^{n} x_i} \le \sqrt{\frac{\sum_{i=1}^{n} x_i^3}{\sum_{i=1}^{n} x_i}}$$

Proof. Let $f(x) = x^2$ and then f''(x) = 2 > 0 implying that f is convex. Furthermore, given $\lambda_1, \lambda_2, \ldots, \lambda_n \in [0, 1]$ satisfying $\sum_{i=1}^n \lambda_i = 1$, we have

$$\left(\sum_{i=1}^{n} \lambda_i x_i\right)^2 \le \sum_{i=1}^{n} \lambda_i x_i^2$$

By letting $\lambda_i = \frac{x_i}{\sum_{i=1}^n x_i}$, we have

$$\left(\sum_{i=1}^{n} \frac{x_i}{\sum_{i=1}^{n} x_i} x_i\right)^2 \leq \sum_{i=1}^{n} \frac{x_i}{\sum_{i=1}^{n} x_i} x_i^2 \Longleftrightarrow \left(\frac{\sum_{i=1}^{n} x_i^2}{\sum_{i=1}^{n} x_i}\right)^2 \leq \frac{\sum_{i=1}^{n} x_i^3}{\sum_{i=1}^{n} x_i} \Longleftrightarrow \frac{\sum_{i=1}^{n} x_i^2}{\sum_{i=1}^{n} x_i} \leq \sqrt{\frac{\sum_{i=1}^{n} x_i^3}{\sum_{i=1}^{n} x_i}}.$$

Note that the condition $\lambda_i \in [0,1]$ is satisfied automatically since $x_i > 0, \forall i = 1, 2, ..., n$. This completes our proof.

Exercise 7.38

Let $x_1, x_2, \ldots, x_n > 0$ satisfy $\sum_{i=1}^n x_i = 1$. Prove that

$$\sum_{i=1}^{n} \frac{x_i}{\sqrt{1-x_i}} \ge \sqrt{\frac{n}{n-1}}.$$

Proof. Define $f(x) = 1/\sqrt{1-x}$ and then $f''(x) = \frac{3}{4}(1-x)^{-5/2} > 0$. So f(x) is convex. Since $\sum_{i=1}^{n} x_i = 1$, then we have

$$\sum_{i=1}^{n} x_i f(x_i) \ge f(\sum_{i=1}^{n} x_i \cdot x_i) = f(\sum_{i=1}^{n} x_i^2)$$

$$= 1/\sqrt{1 - \sum_{i=1}^{n} x_i^2}$$

$$\ge 1/\sqrt{1 - \frac{(\sum_{i=1}^{n} x_i)^2}{n}}$$

$$= 1/\sqrt{1 - \frac{1}{n}} = 1/\sqrt{\frac{n-1}{n}}$$

$$= \sqrt{\frac{n}{n-1}}$$

where the second inequality follows from the result given in Exercise 7.36.

Exercise 7.39

210

211

212

213

215

216

219

Prove that for any a, b, c > 0 the following inequality holds:

$$\frac{9}{a+b+c} \le 2\left(\frac{1}{a+b} + \frac{1}{b+c} + \frac{1}{c+a}\right)$$

To simplify the proof of Exercise 7.39, we introduce the following theorem which says that the **harmonic mean** (HM) is less than or equal to the **geometric mean** (GM).

Theorem 7.1 (HM\leqGM). For any $x_1, x_2, \dots, x_n > 0$ the following inequality holds:

$$\frac{n}{\sum_{i=1}^{n} \frac{1}{x_i}} \le \sqrt[n]{\prod_{i=1}^{n} x_i}$$

Proof. According to AGM inequality, for any $a_1, a_2, \dots, a_n \geq 0$, we have

$$\frac{1}{n}\sum_{i=1}^{n}a_{i} \geq \sqrt[n]{\prod_{i=1}^{n}a_{i}}.$$

Replacing a_i with $\frac{1}{x_i}$ where $x_i > 0$ for $i \in \{1, 2, \dots, n\}$, we get

$$\frac{1}{n}\sum_{i=1}^{n}\frac{1}{x_i} \ge \sqrt[n]{\prod_{i=1}^{n}\frac{1}{x_i}}.$$

Since both sides are positive, taking reciprocals and reversing the inequality yield

$$\frac{1}{\frac{1}{n} \sum_{i=1}^{n} \frac{1}{x_i}} \le \frac{1}{\sqrt{\prod_{i=1}^{n} \frac{1}{x_i}}}$$

$$\frac{n}{\sum_{i=1}^{n} \frac{1}{x_i}} \le \sqrt{\prod_{i=1}^{n} \frac{1}{x_i}},$$

 \Box as desired.

Naturally, we get the following corollary in which AM is short for the arithmetic mean.

Corollary 7.2 (HM \leq GM \leq AM). For any $x_1, x_2, \dots, x_n > 0$ the following inequality holds:

$$\frac{n}{\sum_{i=1}^{n} \frac{1}{x_i}} \le \sqrt[n]{\prod_{i=1}^{n} x_i} \le \frac{1}{n} \sum_{i=1}^{n} \frac{1}{x_i}$$

 217 *Proof.* The first inequality and the second inequality are exactly Theorem 7.1 and AGM inequality, respectively.

Now we prove Exercise 7.39 using Corollary 7.2.

Proof. Since HM \leq AM, letting $x_1 = \frac{2}{a+b}$, $x_2 = \frac{2}{b+c}$ and $x_3 = \frac{2}{c+a}$ yields

$$\frac{3}{\frac{1}{\frac{1}{a+b}} + \frac{1}{\frac{1}{b+c}} + \frac{1}{\frac{1}{c+a}}} \le \frac{\frac{2}{a+b} + \frac{2}{b+c} + \frac{2}{c+a}}{3}$$
$$\frac{3}{a+b+c} \le \frac{2}{3} \left(\frac{1}{a+b} + \frac{1}{b+c} + \frac{1}{c+a} \right)$$
$$\frac{9}{a+b+c} \le 2 \left(\frac{1}{a+b} + \frac{1}{b+c} + \frac{1}{c+a} \right),$$

220 as desired.

Exercise 7.40

- (i) Prove that the function $f(x) = \frac{1}{1+e^x}$ is strictly convex over $[0, \infty)$.
- (ii) Prove that for any $a_1, a_2, \ldots, a_n \geq 1$ the equality

$$\sum_{i=1}^{n} \frac{1}{1+a_i} \ge \frac{n}{1+\sqrt[n]{a_1 a_2 \cdots a_n}}$$

holds.

222

223

Proof. (i) The second derivative is given by

$$f''(x) = \frac{e^x(e^x - 1)}{(1 + e^x)^3} > 0, \quad x > 0$$

Thus, f(x) is strictly convex on $(0, +\infty)$. By Theorem 7.13 in the textbook, f''(x) > 0 is a sufficient, not necessary, condition for strict convexity. Even though f''(x) = 0 at the unique boundary point x = 0, this does not alter the strict convexity of f(x). To see this, recall the definition of strict convexity, i.e. Definition 7.2, that is, for any $x \neq y \in C$, $\lambda \in (0, 1)$,

$$f(\lambda x + (1 - \lambda)y) < \lambda f(x) + (1 - \lambda)f(y).$$

It is easy to see that for any y > x = 0, the above always holds for any $\lambda \in (0,1)$. Thus, $\frac{1}{1+e^x}$ is strictly convex over $[0,+\infty]$.

(ii) Let $a_i = e^{x_i}, i = 1, ..., n$. Then for any $a_i \ge 1$, $x_i \ge 0$. Since $f(x) = \frac{1}{1 + e^x}$ is strictly convex, then

$$\sum_{i=1}^{n} \frac{1}{n} \cdot \frac{1}{1+a_i} = \sum_{i=1}^{n} \frac{1}{n} \cdot \frac{1}{1+e^{x_i}} \ge \frac{1}{1+e^{1/n*\sum_{i=1}^{n} x_i}}$$

$$= \frac{1}{1+(e^{\sum_{i=1}^{n} x_i})^{1/n}}$$

$$= \frac{1}{1+(\prod_{i=1}^{n} e^{x_i})^{1/n}}$$

$$= \frac{1}{1+(\prod_{i=1}^{n} a_i)^{1/n}} = \frac{1}{1+\sqrt[n]{a_1 a_2 \cdots a_n}}$$

Multiplying both sides by n gives the claim, namely,

$$\sum_{i=1}^{n} \frac{1}{1+a_i} \ge \frac{n}{1+\sqrt[n]{a_1 a_2 \cdots a_n}}$$

Since $\frac{1}{1+e^x}$ is strictly convex, the equality holds if and only if $a_1 = a_2 = \cdots = a_n = 1$. This completes our proof.

Convex Optimization Chapter 8 8

Exercise 8.1

Consider the problem

min
$$f(\mathbf{x})$$

s. t. $g(\mathbf{x}) \le 0$
 $\mathbf{x} \in X$ (P)

where f and g are convex functions over \mathbb{R}^n and $X \subseteq \mathbb{R}^n$ is a convex set. Suppose that \mathbf{x}^* is an optimal solution of (P) that satisfies $g(\mathbf{x}^*) < 0$. Show that \mathbf{x}^* is also an optimal solution of the problem

229

230

231

232

233

224

225

226

227

Proof. We denote the feasible sets of (P) and the second problem by C_p and C, respectively. Since $f(\mathbf{x}), g(\mathbf{x})$ and X are convex, both C_p and C are convex sets with $C_p \subseteq C$. Since $g(\mathbf{x}^*) < 0$, $\mathbf{x}^* \in \text{int}(C_p)$. This indicates that the second problem has a local optimal solution on C_p , i.e. \mathbf{x}^* . By Theorem 8.1, we know that a local minimum is also a global minimum in terms of convex optimization. Hence, \mathbf{x}^* is also an optimal solution of the problem without the constraint of $g(\mathbf{x}) \leq 0$.

Exercise 8.2

Let $C = B[\mathbf{x}_0, r]$, where $\mathbf{x}_0 \in \mathbb{R}^n$ and r > 0 are given. Find a formula for the orthogonal projection operator P_C .

Solution: Given $\mathbf{x} \in \mathbb{R}^n$, we want to find its projection onto the closed ball $B[\mathbf{x}_0, r]$. Then the optimization problem associated with the computation of $P_C(\mathbf{x})$ is given by

$$\min_{\mathbf{y}} \{ \|\mathbf{y} - \mathbf{x}\|^2 | \|\mathbf{y} - \mathbf{x}_0\|^2 \le r^2 \}.$$

If $\|\mathbf{x} - \mathbf{x}_0\| \le r$, then obviously $\mathbf{y} = \mathbf{x}$ since it corresponds to the optimal value 0. When $\|\mathbf{x} - \mathbf{x}_0\| > r$, then the optimal solution must belong to the boundary of the ball due to Theorem 2.6 in the textbook. Specifically, Theorem 2.6 says that for a differentiable function $f(\mathbf{x})$, if \mathbf{x}^* is a local optimum point, then $\nabla f(\mathbf{x}^*) = 0$. Accordingly,

$$2(\mathbf{y} - \mathbf{x}) = 0 \iff \mathbf{y} = \mathbf{x},$$

which is impossible since $\mathbf{x} \notin C$. Thus, we conclude that in the case of $\|\mathbf{x} - \mathbf{x}_0\| > r$, the projection problem is equivalent to

$$\min_{\mathbf{y}} \{ \|\mathbf{y} - \mathbf{x}\|^{2} | \|\mathbf{y} - \mathbf{x}_{0}\|^{2} = r^{2} \}
\iff \min_{\mathbf{y}} \{ \|\mathbf{y} - \mathbf{x}_{0} + \mathbf{x}_{0} - \mathbf{x}\|^{2} | \|\mathbf{y} - \mathbf{x}_{0}\|^{2} = r^{2} \}
\iff \min_{\mathbf{y}} \{ \|\mathbf{y} - \mathbf{x}_{0}\|^{2} + 2\langle \mathbf{y} - \mathbf{x}_{0}, \mathbf{x}_{0} - \mathbf{x} \rangle + \|\mathbf{x}_{0} - \mathbf{x}\|^{2} | \|\mathbf{y} - \mathbf{x}_{0}\|^{2} = r^{2} \}
\iff \min_{\mathbf{y}} \{ r^{2} + 2\langle \mathbf{y} - \mathbf{x}_{0}, \mathbf{x}_{0} - \mathbf{x} \rangle + \|\mathbf{x}_{0} - \mathbf{x}\|^{2} | \|\mathbf{y} - \mathbf{x}_{0}\|^{2} = r^{2} \}.$$

After dropping those terms that are not depend on y, we get the equivalent form as follows.

$$\underset{\mathbf{y}}{\operatorname{argmin}} \left\{ \langle \mathbf{y}, \mathbf{x}_0 - \mathbf{x} \rangle \mid \|\mathbf{y} - \mathbf{x}_0\|^2 = r^2 \right\}$$

By the Cauchy-Schwarz inequality, the objective function can be lower bounded by

$$\langle \mathbf{y}, \mathbf{x}_0 - \mathbf{x} \rangle \ge -\|\mathbf{y}\| \|\mathbf{x}_0 - \mathbf{x}\| = -r \|\mathbf{x}_0 - \mathbf{x}\|,$$

and this lower bound can be attained at $\mathbf{y} = r \frac{\mathbf{x} - \mathbf{x}_0}{\|\mathbf{x} - \mathbf{x}_0\|}$. Therefore, the orthogonal projection operator P_C is

$$P_{B[\mathbf{x}_0,r]} = \begin{cases} \mathbf{x}, & \text{if } ||\mathbf{x}|| \le r \\ r \frac{\mathbf{x} - \mathbf{x}_0}{||\mathbf{x} - \mathbf{x}_0||}, & \text{if } ||\mathbf{x}|| > r. \end{cases}$$

6 9 Chapter 9 Optimization over a Convex Set

Exercise 9.1

235

237

238

239

Let f be a continuously differentiable convex function over a closed and convex set $C \subseteq \mathbb{R}^n$. Show that $x^* \in C$ is an optimal solution of the problem

$$\min \{ f(\mathbf{x}) : \mathbf{x} \in C \} \tag{P}$$

if and only if

$$\langle \nabla f(\mathbf{x}), \mathbf{x}^* - \mathbf{x} \rangle \leq 0 \text{ for all } \mathbf{x} \in C.$$

The necessity is easy to show, but proving the sufficiency is hard. On Math StackExchange, Parasseux Nguyen provides a beautiful proof for the sufficiency⁶.

Proof. We first show the necessity. Since $x^* \in C$ is an optimal solution of (P), then we have

$$f(\mathbf{x}^*) - f(\mathbf{x}) < 0.$$

By the convexity of f, we have

$$f(\mathbf{x}) + \langle \nabla f(\mathbf{x}), \mathbf{x}^* - \mathbf{x} \rangle \le f(\mathbf{x}^*) \iff \langle \nabla f(\mathbf{x}), \mathbf{x}^* - \mathbf{x} \rangle \le f(\mathbf{x}^*) - f(\mathbf{x}) \le 0.$$

Proving the sufficiency is not trivial. For all $\mathbf{x} \in C$, let $\mathbf{v} = \mathbf{x} - \mathbf{x}^*$ and then $\mathbf{x}^* + t\mathbf{v} = (1-t)\mathbf{x}^* + t\mathbf{x} \in C$. Define $g(t) = f(\mathbf{x}^* + t\mathbf{v})$ on $t \in [0,1]$. Since f is continuously differentiable over C, then g(t) is also continuously differentiable on [0,1]. Furthermore,

$$g'(t) = \langle \nabla f(\mathbf{x}^* + t\mathbf{v}), \mathbf{v} \rangle$$

$$= \frac{1}{t} \langle \nabla f(\mathbf{x}^* + t\mathbf{v}), t\mathbf{v} \rangle$$

$$= \frac{1}{t} \langle \nabla f(\mathbf{x}^* + t\mathbf{v}), (\mathbf{x}^* + t\mathbf{v}) - \mathbf{x}^* \rangle$$

$$= -\frac{1}{t} \langle \nabla f(\mathbf{x}^* + t\mathbf{v}), \mathbf{x}^* - (\mathbf{x}^* + t\mathbf{v}) \rangle$$

$$\geq 0$$

where the inequality follows from the premise of $\langle \nabla f(\mathbf{x}), \mathbf{x}^* - \mathbf{x} \rangle \leq 0$ for all $\mathbf{x} \in C$.

Note. It is interesting to note that from the above proof, we can see that the convexity of f is not required for the sufficiency and we only used the convexity of C.

⁶https://math.stackexchange.com/questions/4178673/if-nabla-fxt-x-x-leq-0-for-all-x-in-c-then-x-is-optimal-so?

Bibliography

- ²⁴⁴ Chen, J., Yu, C., and Jin, L. (2019). Mathematical Analysis, third edition.
- Horn, R. A. and Johnson, C. R. (2013). Matrix Analysis, Second Edition.
- $_{246}$ Jax (2016). Minkowski inequality for 0 . https://math.stackexchange.com/questions/
- 73294/minkowski-inequality-for-p-le-1. [Online; accessed 25-May-2022].