#### CMPUT 654 Fa 23: Theoretical Foundations of Machine Learning

**Fall 2023** 

# Lecture 23: November 26

Lecturer: Csaba Szepesvári Scribes: Kushagra Chandak

**Note**: Large template courtesy of UC Berkeley EECS dept. (link to directory)

**Disclaimer**: These notes have <u>not</u> been subjected to the usual scrutiny reserved for formal publications. They may be distributed outside this class only with the permission of the Instructor.

# 23.1 Outline

- Introduction to neural networks.
- Function approximation.
- Depth vs width in neural networks.

### 23.2 Neural Networks

A two-layered (one hidden and one output layer) fully connected neural network with m units in the hidden layer is a map  $f: \mathbb{R}^d \to \mathbb{R}$  given by

$$f_w(x) = \sum_{i=1}^m u_i h(\theta_i^\top x + b_i),$$

where  $h: \mathbb{R} \to \mathbb{R}$  is the activation function,  $x \in \mathbb{R}^d$  is the input vector,  $\theta_i \in \mathbb{R}^d$  is the weight vector,  $b_i \in \mathbb{R}$  is the bias/threshold,  $u_i \in \mathbb{R}$  is the weight to the output, and  $w = (\theta, u, b) \in \mathbb{R}^{m(d+2)}$  are the parameters.

#### 23.2.1 Function Approximation with Neural Networks

Let  $\mathcal{F}_m^{(h)} = \{f_w : w \in \mathcal{W}_m\}$ , where  $\mathcal{W}_m = \mathbb{R}^{m(d+2)}$ , be the two-layered neural network function class with m hidden units and activation function h. The next theorem shows that  $f \in \mathcal{F}_m$  is a universal approximator.

In this section, we will see how well we can approximate functions of different kinds with neural networks.

**Theorem 23.1** (Leshno, 1993). Let  $h: \mathbb{R} \to \mathbb{R}$  be such that  $h \notin \mathbb{R}[x]$  (not a polynomial). Let  $K \subset \mathbb{R}^d$  be compact. Then  $\mathcal{F}_m^{(h)}|_K = \left\{f|_K: f \in \mathcal{F}_m^{(h)}\right\}$  is dense in C(K).

To state the next result, let us introduce a set of functions

$$\Gamma_r = \left\{ f : \mathbb{R}^d \to R : \exists \tilde{f} : \mathbb{R}^d \to C \text{ s.t. } f(x) = \int e^{i\omega^\top x} \tilde{f}(\omega) d\omega, \, \forall x \in B_r \right\},\,$$

where  $B_r = \{x^d : ||x||_2 \le r\}$  is a ball of radius r. The function  $\tilde{f}$  is the Fourier transform of f up to constant factors. We have a complexity/smoothness measure/coefficient for  $f \in \Gamma_r$  (assuming there exists a unique  $\tilde{f}$  for f):

$$C(f) = \int \|\omega\|_2 |\tilde{f}(\omega)| d\omega.$$

The quantity C(f) roughly measures the "energy" of f at high frequency. Thus, f is smooth if C(f) is small. With C(f) in hand, we state our next result:

23-2 Lecture 23: November 26

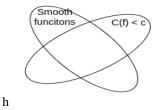


Figure 23.1: Barron's theorem (Theorem 23.2) does not hold for all smooth functions but only a "slice".

**Theorem 23.2** (Barron, 1993). Let  $h : \mathbb{R} \to \mathbb{R}$  be a measurable bounded function such that  $\lim_{z \to -\infty} h(z) = 0$  and  $\lim_{z \to \infty} h(z) = 1$ . Let  $f \in \Gamma_r$  such that  $C(f) < \infty$  and  $\mu \in \mathcal{M}_1(B_r)$ . Then for all  $m \ge 1$ 

$$\inf_{w \in \mathcal{W}_m} \|f - f(0) - f_w\|_{L_2(\mu)} \le \frac{(2rC(f))^2}{m}.$$

**Remark 23.3.** Note that the above result is independent of d. When we approximate a smooth function with polynomial, we get a rate of roughly  $(1/m)^{s/d}$ , where s is the number of continuous derivative of the target function f. So the above result does not tell us that for any smooth function, the approximation error goes down with 1/m rate. But functions with finite C(f) creates a subset of smooth functions for which we get the 1/m rate (see Fig. 23.1).

**Remark 23.4.** Some of the common choices of the activation function are sigmoid  $(h(z) = 1/(1+e^{-z}))$  and ReLU  $(h(z) = \max(0, z))$ . Note that while sigmoid satisfies the condition of Theorem 23.2, ReLU does not. However, for ReLU, we can write s(z) = h(z) - h(z-1) such that s satisfies the condition.

**Does depth in neurals networks give some advantage?** For the next result, let d = 1 and the activation function is ReLU. We also index the neural network class with number of layers:

 $\mathcal{F}_{k,m} = \{f: [0,1] \to \mathbb{R}: \ f \text{ can be implemented by a NN with} \le k \text{ layers and} \le m \text{ hidden units} \} \ .$ 

**Theorem 23.5** (Telgarsky, 2016). Let  $k \geq 3$ . Then

$$\sup_{f \in \mathcal{F}_{2k^2,2}} \inf_{g \in \mathcal{F}_{k,2^{k-2}}} \|f - g\|_{\infty} \ge \frac{1}{16}.$$

*Proof intuition.* The proof is done by constructing a function  $f_k$  which is difficult to approximate using shallow networks. Let  $f_0(x) = \max(0, \min(2x, 2(1-x)))$  on [0,1]. Note that  $f_0(x)$  can be implemented by a 2 layer neural network with m=2,  $\theta_1=2$ ,  $\theta_2=-4$ ,  $\theta_1=0$ , and  $\theta_2=-0.5$  so that

$$f_0(x) = 2 \max(0, x) - 4 \max(0, x - 0.5) = w_1 h(x) + w_2 h(x - 0.5)$$
.

Let  $f_k(x) = f_0(f_{k-1}(x))$  with  $k \ge 1$ . Then  $f_k(x)$  can be represented by a 2k layer neural network with 2 units in each hidden layer. Fig. 23.2 shows  $f_k$  for k = 0, 1, 2.

**Definition 23.6** (Crossing Number). The crossing number of a function  $f:[0,1] \to [0,1]$  is the number of segments in the graph on which f is above the line  $y=\frac{1}{2}$ .

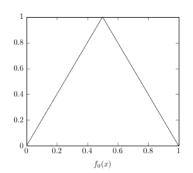
Combining the below two claims gives us the result.

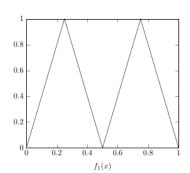
**Claim 23.7.** For every measurable  $g:[0,1] \to [0,1]$  such that  $C(g) < 2^{k-1}$ ,  $||f_k - g||_{L_1} \ge \frac{1}{16}$ .

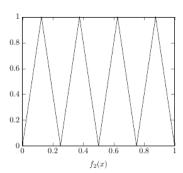
Claim 23.8. We have that

$$\max \left\{ C(g) : g \in \mathcal{F}_{l,m} \right\} \le 2(2m)^l.$$

Lecture 23: November 26 23-3







**Figure 23.2:**  $f_k(x)$  for k = 0, 1, 2.