線性代數沒有明確定義,但重要的Python張量操作!!

import numpy as np
import tensorflow as tf
import torch as tc

1.張量 X 資料結構間互相轉換

| X> | list | numpy | pytorch | tensorflow |
|------------|------------|-------------|--------------|-------------------------|
| list | - | np.array(X) | tc.tensor(X) | tf.convert_to_tensor(X) |
| numpy | X.tolist() | - | tc.tensor(X) | tf.convert_to_tensor(X) |
| pytorch | X.tolist() | X.numpy() | - | - |
| tensorflow | - | X.numpy() | - | - |

2.常見張量形狀操作!!

A, B表示 tensor 名稱

| 名稱 | numpy | torch | tensorflow |
|-----------|------------------------------|-----------------------|-----------------------------|
| 取得張量形狀 | A.shape | A.shape / A.size() | A.shape |
| 取得張量大小 | A.size | A.numel() | tf.size(A) |
| 轉置 | np.transpose(A,[1,0]) | A.permute(1,0) | tf.transpose(A, perm=[1,0]) |
| 攤平至1維 | A.flatten() | tc.flatten(A) | - |
| 重訂形狀 | A.reshape(m,n) | A.view(m,n) | tf.reshape(A,[m,n]) |
| 合併張量 | np.concatenate([A,B],axis=1) | tc.cat([A,B],dim=1) | tf.concat([A, B], axis=1) |
| 堆積張量 | np.stack([A,B],axis=1) | tc.stack([A,B],dim=1) | tf.stack([A,B], axis=1) |
| 壓縮維度 (去1) | np.squeeze(A,axis=0) | tc.squeeze(A,dim=0) | tf.squeeze(A,axis=1) |
| 提升維度 (加1) | np.unsqueeze(A,axis=0) | tc.unsqueeze(A,dim=0) | tf.unsqueeze(A,axis=1) |
| 內存連續化 | np.ascontiguousarray(A) | A.contiguous() | - |

轉置:

$$egin{aligned} A^T := transposeigg(A \equiv (A_{ijk}), [2,0,1]igg) = (A_{kij}) \ A_{.shape} = (I,J,K) \quad A_{.shape}^T = (K,I,J) \end{aligned}$$

———————— 備註 : 需再使用 "內存連續化 "才能讓空間儲存連續 —————————

攤平至1維:

$$B := flatten(A) \Longrightarrow B_{(iJK+jK+k)} := A_{ijk}$$

重訂形狀:

合併張量:

$$A_{.shape} = (I, J_1, K) \quad B_{.shape} = (I, J_2, K)$$
 $C := concat([A, B], dim = 1)$
 $C_{.shape} = (I, J_1 + J_2, K)$

堆積張量:

$$egin{aligned} A_{.shape} &= (I,J,K) & B_{.shape} &= (I,J,K) \ C &:= stack([A,B],dim=1) \ D &:= stack([A,B,A],dim=0) \ E &:= stack([A,A,A,A],dim=3) \ C_{.shape} &= (I,\mathbf{2},J,K) \ D_{.shape} &= (\mathbf{3},I,J,K) \ E_{.shape} &= (I,J,K,\mathbf{4}) \end{aligned}$$

壓縮維度:

$$egin{aligned} A_{.shape} &= (extbf{1}, I, J, extbf{1}, K) \ B := squeeze(A, dim = 0) \ C := squeeze(A, dim = [0, 3]) \ B_{.shape} &= (I, J, extbf{1}, K) \ C_{.shape} &= (I, J, K) \end{aligned}$$

提升維度:

$$egin{aligned} A_{.shape} &= (I,J,K) \ B := unsqueeze(A,dim=0) \ C := unsqueeze(A,dim=2) \ B_{.shape} &= (extbf{1},I,J,K) \ C_{.shape} &= (I,J, extbf{1},K) \end{aligned}$$

3. BroadCasting (定義不同形狀的張量如何運算!!)

- Numpy: https://docs.scipy.org/doc/numpy/user/basics.broadcasting.html
- Pytorch: https://pytorch.org/docs/stable/notes/broadcasting.html
- Tensorflow: https://www.tensorflow.org/xla/broadcasting

$$A_{.shape} = (8, 3, 4, 1, 5), B_{.shape} = (3, 1, 4, 5)$$

 $C := A \oplus B \Longrightarrow C_{.shape} = (8, 3, 4, 4, 5)$