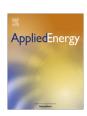


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# A short-term building cooling load prediction method using deep learning algorithms



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#### HIGHLIGHTS

- Deep learning-based methods are developed for building cooling load prediction.
- Accurate predictions on 24-h ahead building cooling load profiles are achieved.
- The potentials of supervised and unsupervised deep learning is investigated.
- Features extracted by unsupervised deep learning can improve model performance.
- Supervised deep learning does not show obvious advantages in model development.

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#### ABSTRACT

Short-term building cooling load prediction is the essential foundation for many building energy management tasks, such as fault detection and diagnosis, demand-side management and control optimization. Conventional methods, which heavily rely on physical principles, have limited power in practice as their performance is subject to many physical assumptions. By contrast, data-driven methods have gained huge interests due to their flexibility in model development and the rich data available in modern buildings. The rapid development in data science has provided advanced data analytics to tackle prediction problems in a more convenient, efficient and effective way.

This paper investigates the potential of one of the most promising techniques in advanced data analytics, i.e., deep learning, in predicting 24-h ahead building cooling load profiles. Deep learning refers to a collection of machine learning algorithms which are powerful in revealing nonlinear and complex patterns in big data. Deep learning can be used either in a supervised manner to develop prediction models with given inputs and output (i.e., cooling load), or in an unsupervised manner to extract meaningful features from raw data as model inputs. This study exploits the potential of deep learning in both manners, and compares its performance in cooling load prediction with typical feature extraction methods and popular prediction techniques in the building field. The results show that deep learning can enhance the performance of building cooling load prediction, especially when used in an unsupervised manner for constructing high-level features as model inputs. Using the features extracted by unsupervised deep learning as inputs for cooling load prediction can evidently enhance the prediction performance. The findings are enlightening and could bring more flexible and effective solutions for building energy predictions.

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# 1. Introduction

The building sector has become the largest energy consumer worldwide, accounting for 32% of global final energy consumption and one third of the Green House Gas emissions [1]. Compared to

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the transportation and industry sectors, the energy saving potential in buildings is much more significant and could reach 30–80% using currently available building technologies [2]. Among various building services systems, the Heating, Ventilation and Air-Conditioning (HVAC) system is responsible for the largest proportion of building energy consumption (e.g., around 50% in U.S.) and has the largest energy saving potential (e.g., 15–30% for commercial buildings) [3,4]. As a result, the current energy

conservation measures in building operations mainly focus on the HVAC system. Reliable prediction of short-term (i.e., with a prediction horizon of shorter than 1-week) cooling load profile is the essential foundation for many building energy management tasks [4,5], including optimal control and fault detection and diagnosis (FDD) strategies [6-8]. Ben-Nakhi and Mahmoud adopted artificial neural networks to predict next-day cooling load for optimizing the HVAC thermal energy storage system operation [7]. It was shown that optimal control strategies can increase the operating flexibilities while reducing the operating costs. Lu et al. utilized artificial intelligence for building cooling load predictions with the aim of optimizing HVAC system operations [8]. Energyefficient operations were achieved by optimizing the set points of chilled water supply temperature, chilled water pump head and supply air pressure in duct networks. Shan et al. developed a robust chiller sequencing control strategy relying on building cooling load predictions [9]. The strategy was validated and could achieve 3% energy saving compared to conventional strategies. Predicted cooling load has been used either directly or indirectly as an indicator for FDD. As examples, previous studies have used cooling load for detecting and diagnosing the low delta-T syndrome in chilling system [10], reducing energy consumption in air-handling units [5], and detecting abnormal energy use at the buildinglevel [11]. Building cooling load prediction is also critical to building demand-side management. A large number of studies have been carried out to investigate the most cost-effective demand response measures (e.g., load shifting) considering the interactions between buildings and smart-grids [6]. An essential assumption of these studies is that reliable predictions of short-term building cooling load profiles are available to use.

Existing methods for short-term cooling load prediction can generally be classified into two types, i.e., physical-model based methods and data-driven methods. Physical-model based methods rely on physical principles and detailed information on building and its systems to characterize building thermal behaviors. The models developed are usually referred as white-box models. Admittedly, they can capture the actual building thermal response to various influential factors, such as outdoor and indoor environment. However, it requires a large amount of detailed building information (e.g., information on building envelop and the selection of building equipment) and the model performance may not be consistent if assumptions of physical principles are not fulfilled [12].

The other type of prediction methods, i.e., data-driven methods, mainly relies on building operational data to discover the relationship between building cooling load and relevant variables (e.g., the outdoor temperature and relative humidity, and indoor occupancy). The models developed in such a manner are known as either grey-box or black-box models [13,14]. The main advantage of data-driven models, especially black-box models, is that the modeling process is more efficient and flexible. The use of advanced data analytics, such as machine learning and artificial intelligence, enables data-driven models to achieve high accuracy and discover potentially useful yet previously unknown relationships with efficient computation. The performance of data-driven methods is mainly affected by two factors, i.e., the prediction techniques used for model development and the features used as model inputs. Previous research showed that the prediction techniques from the field of machine learning and artificial intelligence, such as support vector regression [15,16] and artificial neural networks [17,18], worked very well in building energy prediction. Various studies have also shown that nonlinear techniques could achieve more accurate results compared with linear ones, e.g., multiple linear regression and autoregressive moving average [19,20]. Regarding to the model inputs, previous studies mainly relied on engineering knowledge or simple statistical methods (e.g.,

correlation coefficient) to select model inputs or develop features as model inputs. For instance, engineering knowledge tells that the building cooling load is closely related to the outdoor weather condition and indoor occupancy. Therefore, outdoor dry-bulb temperature, relative humidity and solar irradiation as well as the indoor occupancy schedule (e.g., Day of the week, Hour and Minute) were typically selected as model inputs [21,22]. Some studies also used historical data as model inputs considering the building thermal capacity [19,23]. Using original historical data, such the outdoor temperature and humidity at previous time steps, as model inputs is generally not recommended, as it may substantially increase the number of model inputs, making prediction models more complicated and computationally expensive. Feature extraction, which transforms raw data into a compact yet informationpreserving form, can be applied to develop features as model inputs. Three types of feature extraction methods have been found in previous studies, i.e., engineering, statistical and structural feature extraction [22-27]. Engineering features are constructed based on engineering knowledge and experience, e.g., using the data at previous one-hour as model inputs [23]. Statistical features are constructed using summarizing statistics, e.g., minimum, maximum and mean values of the measurements over a period of time [22,24]. Structural features represent the structural or temporal relationships within the data over a period of time, e.g., the cutoff lag of autocorrelation function or the dominant frequencies in the time-series data [25–27].

The data-driven approaches have gained increasing popularity in the building field, as more and more building operational data are available in modern Building Automation System (BAS). The rapid development in big data analytics offers opportunities for the effective use of big BAS data. One prominent and promising example is deep learning, which has gained huge success in the field of pattern recognition [28,29]. Deep learning refers to a collection of machine learning algorithms which adopts a 'deep' model architecture for knowledge discovery. In other words, the input data will be transformed in either a linear or a nonlinear manner multiple times before deriving the output. By contrast, conventional machine learning algorithms are 'shallow' and input data only undergo one or two rounds of transformation. Deep learning can be used either in a supervised manner for developing a prediction model or in an unsupervised manner for extracting meaningful features from raw data. The former works on two clearly defined data sets as the input set (denoted as X) and the output set (denoted as Y), while the latter works on the input data set (X) alone and aims to extract high-level abstractions of X. Deep learning has demonstrated its power in various applications, such as speech recognition and visual object detection [28,29]; however, it's potential in building cooling load prediction is still unknown. To fill this research gap, this study systematically investigates the potential of deep learning in building cooling load prediction and detailed comparisons with existing analytics are given.

The paper is organized as follows: Section 2 presents the research outline and a brief introduction of data analytics used. Section 3 describes the modeling process using the data retrieved from an educational building. The performance in terms of prediction accuracy and computation load is compared and discussed in Section 4. Conclusions are drawn in Section 5.

#### 2. Research methodology

#### 2.1. Research outline

Fig. 1 presents the general research outline. Feature extraction is firstly carried out to extract meaningful features as model inputs. Four types of feature extraction methods highlighting the unsuper-

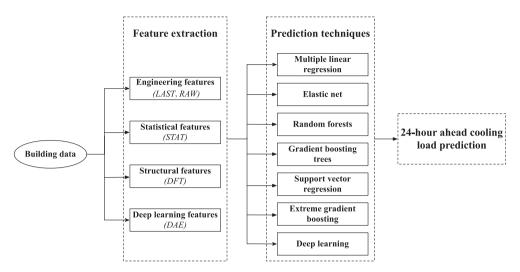


Fig. 1. Research outline.

vised deep learning are used. Seven prediction techniques featuring the supervised deep learning are adopted to develop prediction models based on different feature sets. The performance in terms of prediction accuracy and computation load is compared and discussed. This research is valuable for building professionals who need the 24-h ahead building cooling load profiles for evaluating building energy performance, developing online control, optimization and fault diagnosis strategies, developing operation strategies toward smart grid, etc. It is impossible and unnecessary to introduce all the feature extraction and data analytic methods in detail here, as most of the methods have been studied in existing literature. These methods are used to compare with the deep learning method. The following subsections presents an overview on the feature extraction methods and prediction techniques used in this study. A brief introduction on deep learning is provided in a late part.

#### 2.2. Feature extraction

The selection of the model inputs is usually the first yet the most important step in developing reliable prediction models. Feature extraction has been widely used to obtain useful and representative information from raw data as model inputs. The intuition behind is twofold. Firstly, taking the historical data in their original form might result in a large number of model inputs and the information contained could be redundant. As a result, the risk of over-fitting is increased dramatically. Secondly, feature extraction helps to reduce the dimensionality of model inputs and thereby, reducing the computation load in model development. This paper examines the performance of four feature extraction methods. Three of them, i.e., engineering, statistical and structural feature extraction methods, have been used in previous studies and are selected for comparison purposes.

The engineering methods mainly rely on engineering expertise to select model inputs. A typical engineering method is to select the *k* most recent historical data as model inputs for building cooling load predictions. Considering that building operation presents great daily seasonality, this research adopts two engineering feature sets for comparison: the first consists of historical measurements in previous 24-h and the second only consider measurements in previous hour.

Statistical feature extraction methods calculate the summarizing statistics of a time series as features. This study selects four of the most commonly used summarizing statistics as statistical

features, i.e., the minimum, maximum, mean and standard deviation of a time series.

Structural features represent the structural information of a time series. One popular approach is to transform the time series from time domain to frequency domain, and then exploring the data in frequency domain for feature extraction. In this study, the top-*k* dominant frequencies of a time series are extracted as structural features.

The fourth feature extraction method is the main focus of this study: unsupervised deep learning models are developed to extract high-level data abstractions as features. These features obtained are in essence nonlinear combinations of raw input data. They are extracted in a purely data-driven fashion and can hardly be formulated using domain knowledge.

This study adopts an iterative approach for predicting the 24-h ahead building cooling loads. It requires the features to be updated along with the prediction process. The general idea is illustrated in Fig. 2. At the first iteration, feature extraction is performed based on the historical values in the past 24-h. The features extracted are then fed to the prediction model to generate the predicted value at the next time step. At the second iteration, this predicted value is combined with part of the historical values to form the new inputs. The following feature extraction process will update the features, based on which new prediction is made. The process stops till all predictions of the next 24-h are generated.

#### 2.3. Prediction techniques

Seven typical prediction techniques are selected to develop prediction models, including multiple linear regression (MLR), elastic net (ELN), random forests (RF), gradient boosting machines (GBM), support vector regression (SVR), extreme gradient boosting trees (XGB) and the most commonly used architecture of supervised deep learning, i.e., deep neural network (DNN). The first six techniques are selected based on their popularity in previous studies and used to compare the performance of supervised deep learning.

The first two, i.e., MLR and ELN, are linear techniques and served as performance benchmark in this study. ELN is an extended version of MLR, with extra regularization terms introduced to perform variable selection and weaken the influence of multicollinearity. It is expected to have better generalization performance than MLR when the number of inputs is large. Developing models based on these two linear techniques are computationally efficient and the

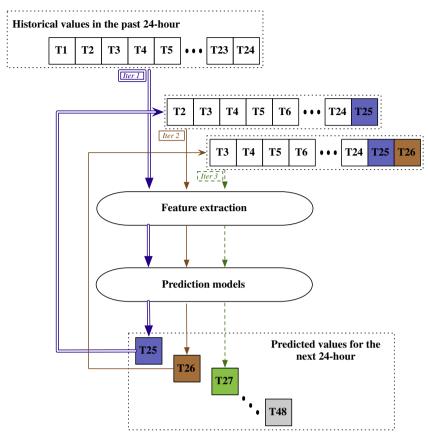


Fig. 2. Iterative process for 24-h ahead building cooling load prediction.

resulting models are easy to interpret. Nevertheless, the prediction accuracy could be poor due to their incompetence of modeling nonlinearity.

The other prediction techniques used are capable of capturing complex and nonlinear relationships. SVR, RF and GBM are powerful machine learning methods which have been successfully used for building energy predictions in previous studies [12,30]. XGB is an improved version of gradient boosting with higher computation efficiency and better capabilities in tackling the over-fitting problem [31]. This study also investigates the potential of deep learning as a prediction technique in predicting 24-h ahead building cooling load [29]. The resulting model is denoted as DNN in this study. It shares a similar representation with conventional neural networks, but with a more complex architecture and training schemes.

#### 2.4. Deep learning

As defined by LeCun et al., deep learning is a technique which allows computational models with multiple processing layers to learn representations of data with multiple levels of abstractions [29]. Oneway to understand deep learning models is to compare them to artificial neural networks, but with more complex architectures and training schemes. A typical neural network usually has three layers, i.e., one input layer, one hidden layer and one output layer. By contrast, deep learning models could have a number of hidden layers and each layer may have different functions, e.g., performing nonlinear transformations or convolution operations. The training scheme is also different from training conventional neural networks. New model parameters, such as the dropout which specifies the proportion of neurons to be randomly ignored during model training, are introduced to ensure the robustness of deep learning models.

Deep learning can be used either in a supervised manner to develop a deep neural network model (DNN) for prediction or in an unsupervised manner to develop a deep auto-encoder model for feature extraction. The latter is of special interests as it tackles the most intrinsic limitation of conventional machine learning techniques, i.e., the lack of ability to process data in their raw form [29]. In other words, to ensure the success of conventional machine learning techniques, great effort is needed to transform the raw data into meaningful features. Unsupervised deep learning has been widely and successfully used to perform the task of feature extraction in other fields [32]. By setting the output as the same as the input, a deep auto-encoder model tries to reconstruct the input by minimizing the reconstruction error. A common practice is to design the auto-encoder with a symmetric structure and the number of neurons at each layer is decreasing towards the middle hidden layer. The activations obtained at the middle hidden layer are taken as features, which in essence are nonlinear combinations of the raw input data. Compared to the three feature extraction methods introduced in Section 2.2, using unsupervised deep learning requires little domain expertise and is very promising to extract the best information-preserving features.

#### 3. Case study

#### 3.1. Data description

The data to be analyzed in this research are retrieved from an educational building in Hong Kong. The building mainly consists of offices, classrooms and a computer data center. The gross floor area is around  $11,000~\text{m}^2$  and  $8500~\text{m}^2$  are air-conditioned. One-year data in 2015 are collected with a collection interval of 30-min. The variables included in this dataset contains five time vari-

**Table 1**Summary on numeric variables in the dataset.

Variables	Min	Mean	Median	Max
Outdoor temperature (°C)	12.01	25.59	27.28	35.79
Outdoor RH (%)	20.35	82.10	83.96	98.41
Chilled water supply temperature (°C)	6.25	8.87	8.71	23.92
Chilled water return temperature (°C)	6.82	11.03	10.67	24.04
Chilled water flowrate (1/s)	0.33	34.81	29.05	168.80
Cooling load (kW)	0.0	653.3	363.7	2474.0

ables (i.e., *Month, Day, Hour, Minute* and *Day type*), the outdoor temperature, the outdoor relative humidity, the supply and return chilled water temperature and the flow rate of the chilled water temperature. The building cooling load is calculated based on the latter three variables. In total, the dataset contains 15,792 observations. Table 1 presents the summary of numeric variables in the dataset.

#### 3.2. Construction of feature sets as model inputs

Building cooling load is heavily influenced by two factors, i.e., building occupancy and outdoor condition. While the information of building occupancy is seldom available for direct use, it is possible to take into account the occupancy influence using time variables, as the occupancy schedule for a specific functional building is usually fixed and correlated with time. Outdoor conditions can be well-described using outdoor dry-bulb temperature, outdoor relative humidity, wind direction and speed, outdoor luminance, etc. The outdoor temperature and relative humidity are the most correlated variables to building cooling load and they are readily available in modern building automation systems. Therefore, the BASIC feature set contains all the five time variables (i.e., Month, Day, Hour, Minute and Day type), the outdoor temperature and the outdoor relative humidity at time T. These seven features are taken as model inputs to predict building cooling load at time T.

Considering that building cooling load presents daily seasonality, it is expected that the prediction accuracy could be improved using measurements in previous 24-h [22]. Compared to the *BASIC* 

feature set, additional information of building cooling load, outdoor temperature and RH during the past 24-h are added for analysis, either in their raw form or after feature extraction. If without feature extraction, each time series of building cooling load, outdoor temperature and outdoor RH during the past 24-h will result in 48 more variables (due to a collection interval of30-min). The resulting feature set therefore contains 151 (i.e., 144 + 7) variables and is denoted as the *RAW* feature dataset.

As introduced in Section 2.2, four feature extraction methods are adopted in this study for comparison purposes. Feature extraction is performed on the measurements in past 24-h. More specifically, engineering expertise tells us that the measurements at previous time step (denoted as T - 1) may have the largest impact to the building cooling load at time T [23]. Therefore, three more features representing the cooling load, outdoor temperature and RH at time T-1 are added to the BASIC feature set to form a new feature set, denoted as LAST. Statistical features are extracted by calculating the minimum, maximum, mean and standard deviation of measurements in previous 24-h. The resulting feature set is denoted as STAT and has 12 more features (four features for each of the three time series of cooling load, outdoor temperature and RH) compared to the BASIC feature set. The discrete Fourier transformation method is used to extract the structural features in past 24-h measurements. After transforming the time series from timedomain to frequency-domain, the four most dominant frequencies are selected as features for each time series. The number of dominant frequencies is selected as four to make it a fair comparison with statistical features. Similar to the STAT feature set, the result-

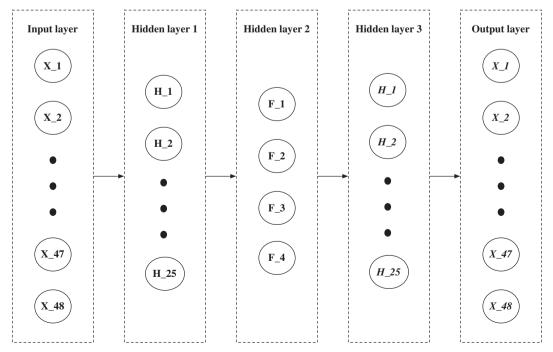


Fig. 3. Schematic of the deep auto-encoder model for feature extraction.

**Table 2** Parameter optimization results.

Method	Parameters	BASIC	RAW	LAST	STAT	DFT	DAE
ELN	Alpha	0.20	0.90	0.70	0.40	0.30	0.30
	Lambda	0.19	0.02	0.19	0.04	0.10	0.19
GBM	Learning rate	0.05	0.01	0.01	0.05	0.05	0.05
SVR	С	8192	32,768	2048	4096	4096	4096
	Sigma	0.125	0.008	0.063	0.125	0.063	0.063
XGB	Learning rate	0.1	0.1	0.1	0.1	0.1	0.1
DNN	Hidden layer	2	2	2	2	2	2
	Input dropout	0	0.05	0	0	0.05	0
	Hidden dropout	0.05	0	0	0.05	0	0
	Activation	ReLU	ReLU	ReLU	ReLU	ReLU	ReLU

ing feature set, denoted as *DFT*, has 12 more features than the *BASIC* feature set.

Another feature set is constructed using unsupervised deep learning. A deep auto-encoder model is developed for each of the three time series. An optimization process is performed to determine the optimal model architecture. As shown in Fig. 3, the deep auto-encoder model developed has a symmetric structure with five layers in total. The model uses a tanh activation function, i.e.,  $tanh(z) = \frac{e^z - e^{-z}}{e^2 + e^{-z}}$ . The first and last layers both have 48 neurons to represent the measurements in previous 24-h. The middle layer (i.e., hidden layer 2) contains the features extracted and the number of neurons is set as four in accordance with above-mentioned feature extraction methods. The optimized neuron number in the other two hidden layers is set as 25. The resulting feature set is denoted as DAE.

#### 3.3. Development of prediction models

The entire dataset is divided into training, validation and testing data with proportions of 70%, 15% and 15% respectively. The model parameters of each algorithm are optimized through cross-validation and parameter grid search. The parameters to be optimized for each prediction technique are briefly introduced as below.

Two parameters, i.e., *alpha* and *lambda*, are optimized for ELN models. The *alpha* ranges from zero to one and defines the combination of the Lasso and the Ridge regression methods. The *lambda* specifies the penalty strength for regularization terms and well tuning this parameter helps to avoid over-fitting. In this study, *alpha* is optimized over a sequence from zero to one with a decimal increment of 0.1, while lambda is optimized over a sequence from zero to one with a decimal increment of 0.01.

The support vector regression with a Gaussian radial basis function kernel is used in this study. Optimization is performed considering the complexity parameter C and smoothing parameter S signa. In general, a larger S tends to make the model more prone to overfitting while a smaller S is more likely to cause under-fitting. The parameter S signa controls the shape of decision boundary. A larger S signa makes the decision boundary more flexible and smooth, while a smaller S makes the decision boundary more complicated and sharp. The candidate values of these two parameters take a form of S, and S are integers ranging from 1 to 15 for S and S and S are integers ranging from 1 to 15 for S and S and S are integers ranging from 1 to 15 for S and S and S are integers ranging from 1 to 15 for S and S and S are integers ranging from 1 to 15 for S

Random forests, gradient boosting trees and extreme gradient boosting are all decision tree-based techniques. They all share two common model parameters, i.e., the number of trees to grow and the depth of each individual tree. In general, the prediction accuracy and computation load both increase with the number of trees to grow. To make a fair comparison while guarantee the model performance, the total tree number is fixed as 1000 and the depth of each individual tree is set as four. The number of variables selected as candidates for tree splitting is another parameter

needs to be optimized for random forests models. It is taken as  $\frac{No. \ of \ inputs}{3}$  as recommended in [33]. The learning rate, which specifies how quickly a tree model adapts to the errors in previous iteration, is optimized for the latter two tree-based methods. Its candidate values range from 0.025 to 0.5 with a decimal increment of 0.025

Compared to conventional neural networks, deep learning models have more hidden layers and the training scheme is more complicated. Four parameters of deep learning models are optimized in this study: (1) the number of hidden layers (ranging from 1 to 10 with an increment of 1); (2) the dropout ratio at the input layer (ranging from 0 to 0.3 with a decimal increment of 0.025); (3) the dropout ratio at the hidden layer (ranging from 0 to 0.3 with a decimal increment of 0.025); and (4) the activation function (including Tanh, ReLU and sigmoid). The dropout ratio at the input and hidden layers specifies the proportion of neurons to be randomly ignored during model training. It is a similar approach to bootstrap aggregation and has been proved to be an effective way to avoid over-fitting [34]. It should be mentioned that the number of neurons at each hidden layer is set as constant in this study to reduce the computation load associated with parameter optimization. The value is determined according to one of the rule of thumbs in neural network design, i.e.,  $\frac{No. \text{ of inputs}+No. \text{ of oututs}}{2}$  [35]. Further performance improvement might be achievable if this parameter is optimized; however, the resulting computation load can be overwhelming.

The model optimization results are summarized in Table 2.One interesting finding is that the number of hidden layers optimized for DNN models is only 2, which means the optimal DNN model developed for building cooling load prediction does not actually need a 'deep' architecture. It indicates that given this dataset and this prediction problem, supervised deep learning exhibits limited advantages when compared to conventional artificial neural networks with a 'shallow' architecture. The potential reason behind is twofold. Firstly, the increase in the number of hidden layers leads to a dramatic increase in the number of model coefficients. To develop robust and reliable estimations of these model coefficients, a huge amount of data is needed. This study adopts onevear data with a collection interval of 30-min for analysis. The data amount may not be large enough to guarantee the reliability of a 'deeper' model. Secondly, a neural network of two hidden layers was claimed to be sufficient to represent most of the functions in real world [36]. It is possible that two hidden layers are good enough to solve the cooling load prediction problem.

# 4. Results and discussions

# 4.1. Prediction performance

The prediction performance is evaluated using three metrics (as defined in Eqs. (1)–(3), where  $y_k$  and  $\widehat{y_k}$  are the actual and pre-

dicted values at time k respectively), including the mean absolute error (MAE), the root mean squared error (RMSE) and the coefficient of variation of the root mean squared error (CV-RMSE). MAE and RMSE are scale-dependent while CV-RMSE is scaleindependent. Scale-dependent metrics provide readers a straightforward way to quantify the prediction error while scaleindependent metrics are good for performance evaluation with other similar studies. It is noted that some of the scaleindependent metrics, such as the mean absolute percentage error (MAPE), are not suitable for model evaluation, as the equation denominator (i.e., actual cooling loads) may be zero. By contrast, CV-RMSE can overcome this problem, as the equation denominator is the mean of actual cooling loads over a time period. In addition, previous studies and guidelines have provided some benchmarks for model evaluation using CV-RMSE [37,38]. It is specified that if the resulting CV-RMSE is below 30% when using hourly data, the model is calibrated and sufficiently close to physical reality for engineering purposes [39].

$$MAE = \frac{\sum_{k=1}^{n} |y_k - \widehat{y_k}|}{n} \tag{1}$$

$$RMSE = \sqrt{\frac{\sum_{k=1}^{n} (y_k - \widehat{y_k})^2}{n}}$$
 (2)

$$CV-RMSE = \frac{\sqrt{\frac{\sum_{k=1}^{n} (y - k - \widehat{y_k})^2}{n}}}{\sum_{k=1}^{n} y_k}$$
(3)

Table 3 summarizes the resulting *RMSE*, *CV-RMSE* and *MAE*. In terms of prediction techniques, MLR and ELN have the worst performance and the resulting *CV-RMSE* exceeds the 30% threshold most of the time. This is in accordance with expectation as these two are not capable of modeling complex and nonlinear relationships. Using nonlinear prediction techniques can significantly boost the prediction accuracy and the resulting *CV-RMSE* can be well below the 30% threshold. In general, XGB method has a performance edge over the GBM, SVR and the DNN methods. The performance of RF is not as good as the above-mentioned four

nonlinear methods. The best prediction performance is achieved when XGB models are developed using the *DAE* feature set and the resulting *CV-RMSE* is 17.8%.

It is observed that linear and nonlinear techniques have their own best feature set for model development. Linear techniques reach their best performance when the *RAW* feature set is used, while nonlinear methods obtain the best performance using the *DAE* feature set. A possible explanation is that the features extracted by deep auto-coders are high-level nonlinear abstractions of the raw data. Therefore, nonlinear prediction methods are needed to fully release the power of these high-level features in predicting cooling loads.

The results show that the prediction performance can be greatly enhanced by introducing the measurements in the past 24-h in RAW form. However, the engineering features, statistical features and structural features extracted do not necessarily enhance the performance when compared to using the BASIC feature set alone. It indicates that useful information is indeed hidden in the past 24-h measurements, yet it is not a trivial task to discover useful information through conventional feature extraction methods. Conventional feature extraction methods are highly dependent on domain expertise and may lead to completely different results for different buildings or different prediction techniques. By contrast, using unsupervised deep learning can almost always guarantee a performance boost, especially when nonlinear prediction techniques are used. Such feature extraction method is purely data-driven and little human intervention is involved. It can be applied as a generic approach for extracting useful information in building data.

Figs. 4–10 present the predicted and actual cooling load profiles on the 14 testing days, which are randomly selected from the testing data for visualization purposes. For the ease of interpretation, only the predictions using the *BASIC*, *RAW* and *DAE* feature sets are shown and compared with the actual building cooling loads. It is evident that the prediction performance of linear techniques is quite poor and cooling load predictions are likely to be negative when testing days are in cold seasons of Hong Kong (i.e., testing days 1, 2, 3, 4, 5, 13 and 14 are measured in January, February, March and December). Such modeling deficiency can be generally eliminated when using nonlinear prediction techniques.

**Table 3** 24-h ahead prediction accuracy on testing data.

Method	Metrics	BASIC	RAW	LAST	STAT	DFT	DAE
MLR	RMSE	286.8	166.3	244.8	315.1	347.3	216.8
	CV-RMSE	47.9%	27.8%	40.9%	52.6%	58.0%	36.2%
	MAE	230.4	117.8	202.1	242.8	280.2	177.2
ELN	RMSE	286.5	167.9	260.0	312.3	294.5	214.3
	CV-RMSE	47.8%	28.0%	43.4%	52.1%	49.2%	35.8%
	MAE	230.4	118.9	212.0	241.8	233.3	175.8
RF	RMSE	168.7	189.0	316.4	235.1	215.2	130.9
	CV-RMSE	28.2%	31.6%	52.8%	39.3%	35.9%	21.9%
	MAE	114.0	118.4	216.6	179.2	151.5	85.6
GBM	RMSE	136.8	146.3	178.4	148.5	133.2	117.8
	CV-RMSE	22.8%	24.4%	29.8%	24.8%	22.2%	19.7%
	MAE	94.2	102.5	127.7	108.1	94.0	83.9
SVR	RMSE	143.5	137.8	153.8	132.7	197.0	113.8
	CV-RMSE	24.0%	23.0%	25.7%	22.2%	32.9%	19.0%
	MAE	109.1	98.5	109.0	98.6	153.3	85.4
XGB	RMSE	129.0	116.6	227.4	148.0	122.6	106.5
	CV-RMSE	21.5%	19.5%	38.0%	24.7%	20.5%	17.8%
	MAE	85.8	82.1	139.4	104.1	83.6	71.6
DNN	RMSE	175.7	131.4	162.5	129.6	159.3	123.5
	CV-RMSE	29.3%	21.9%	27.1%	21.6%	26.6%	20.9%
	MAE	111.9	90.2	109.4	87.6	106.0	100.5

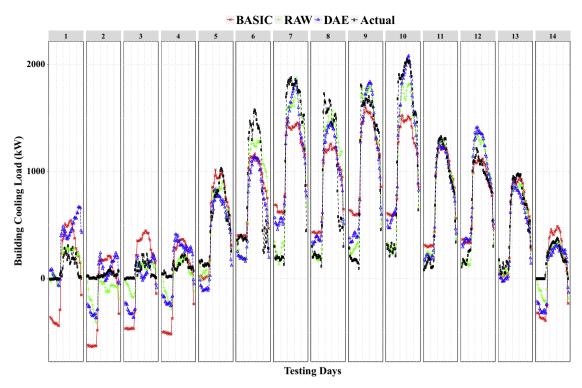


Fig. 4. Prediction performance using multiple linear regression (MLR).

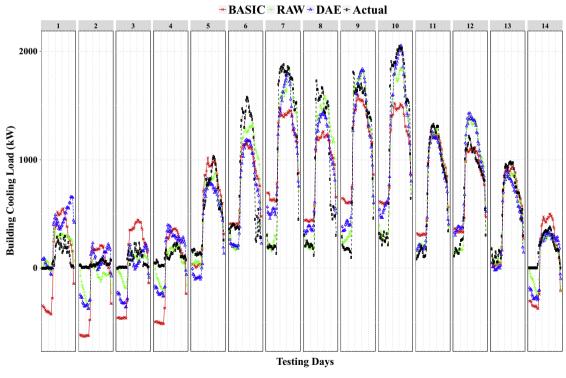


Fig. 5. Prediction performance using elastic net (ELN).

#### 4.2. Computation load

The computation load is evaluated from two perspectives, i.e., (1) the computation time spent in model development using the training data set; (2) the computation time spent in generating 24-h cooling load profiles for 14 days. The computation tool used

for this research is a MacBook Pro with a processor of 2.5 GHz Intel Core i7. All the computation is performed using the open source software R [40].

As summarized in Table 4, linear prediction techniques account for the least computation time for model development. By contrast, nonlinear techniques spend much more time. The XGB method is

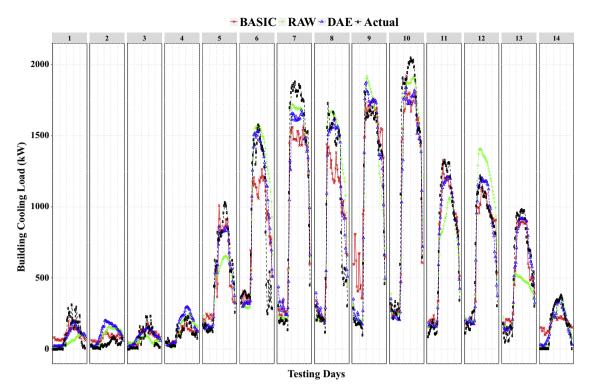


Fig. 6. Prediction performance using random forests (RF).

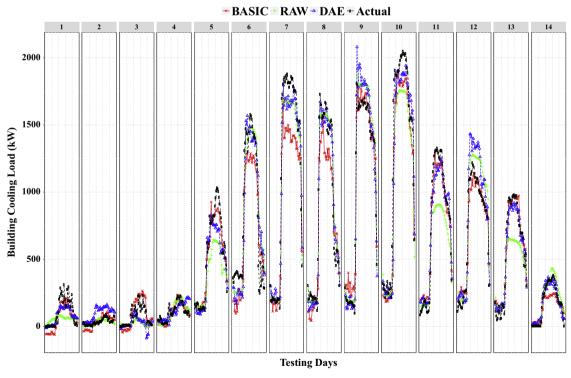


Fig. 7. Prediction performance using gradient boosting machines (GBM).

the most efficient nonlinear method. Its computation time is at least four times faster than the other four nonlinear methods, except when the *RAW* feature set is used. The RF and DNN methods are the most computational expensive ones.

The computation time generally increases with feature numbers. As shown in Table 4, the model development time reaches

maximum when the *RAW* feature set is used. It contains 151 features, which is much larger than feature numbers in other feature sets (i.e., 7 for *BASIC*, 10 for *LAST*, 19 for *STAT*, *DFT* and *DAE*). In addition, when a feature is categorical rather than numerical, the one-hot-encoding method is usually performed for data preprocessing. In such a case, a categorical variable with *k* unique values will be

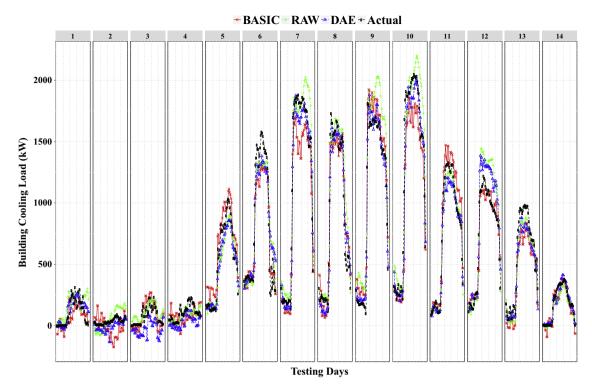


Fig. 8. Prediction performance using support vector regression (SVR).

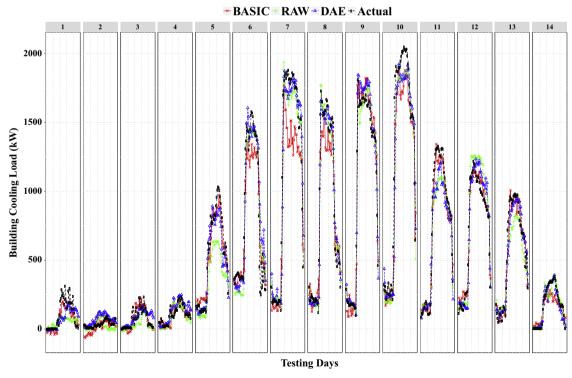


Fig. 9. Prediction performance using extreme gradient boosting (XGB).

transformed into k columns containing either 0 or 1 for value indication. This explains why the computation time using *DFT* features are much larger than that using *STAT* and *AE* features, even though all these three feature sets have the same feature number, i.e., 19.

Table 5 summarizes the computation time when predicting the fourteen 24-h cooling load profiles. Except for the models using the

*BASIC* feature set, all the other models adopts an iterative process to make predictions (as shown in Fig. 2), i.e., the cooling load prediction at time T is used to predict cooling load at later time. Similar to the computation time used for model development, the RF and DNN require the largest time for prediction. The models based on *DAE* features result in the largest prediction time, as deep autoencoders spend more time in updating features.

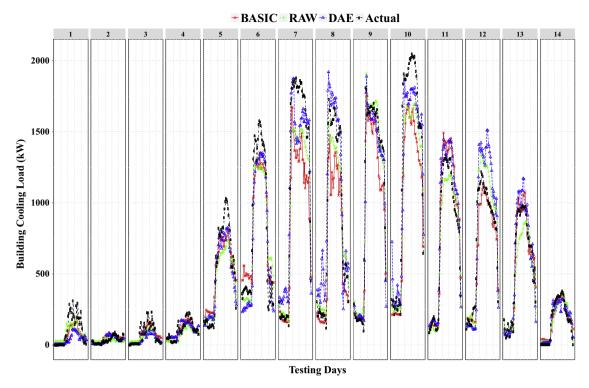


Fig. 10. Prediction performance using deep neural networks (DNN).

**Table 4** Computation time for model development.

Time (s) MLR	ELN	RF	GBM	SVR	XGB	DNN
BASIC 0.10	0.05	210.94	73.80	85.64	10.20	206.74
RAW 0.61	0.36	489.34	279.53	151.05	203.66	258.76
LAST 0.10	0.05	193.60	80.01	25.40	14.20	218.93
STAT 0.12	0.07	214.24	89.53	96.91	39.36	208.86
DFT 0.60	0.31	449.80	208.97	127.63	18.24	196.64
DAE 0.12	0.06	199.20	90.72	91.61	36.46	218.82

**Table 5**Computation time for predicting 24-h profiles for 2-week data.

Time (s)	MLR	ELN	RF	GBM	SVR	XGB	DNN
BASIC	0.005	0.002	0.209	0.022	0.253	0.093	0.016
RAW	8.988	3.126	33.553	3.917	21.794	3.463	13.864
LAST	5.120	5.120	35.414	1.769	8.274	1.678	11.897
STAT	4.208	1.822	35.017	2.335	9.524	2.175	11.242
DFT	8.782	2.881	35.990	3.654	21.280	3.229	11.769
DAE	221.795	221.134	232.615	227.491	226.377	236.169	229.402

#### 5. Conclusions

This paper systematically investigates the potential of deep learning in building cooling load prediction from two perspectives, i.e., extracting meaningful features and developing prediction models. The deep learning-based method is compared with the state-of-the-art prediction techniques and existing feature extraction methods used in the building field in terms of accuracy and computation efficiency. To the best of the authors' knowledge, this is the first attempt in the building field to examine the potential of deep learning in building energy prediction. The research results show that deep learning-based methods do help to enhance the prediction performance.

In terms of prediction techniques, the research results show that nonlinear prediction techniques perform much better than the linear ones. The extreme gradient boosting (XGB) method shows its superiority in prediction when compared with others. The best prediction performance is obtained by adopting XGB models using features extracted by unsupervised deep learning models (i.e., deep auto-encoders). Supervised deep learning models do not show evident advantages in developing cooling load prediction models. The hidden layer number optimized shows that supervised deep learning models do not actually need a 'deep' architecture and a 'shallow' architecture with two hidden layers works well. The potential reasons are twofold:(1) the data used in this study is not large enough to ensure the reliable training of a 'deeper' model; (2) two hidden layers are sufficient to describe the underlying patterns of building cooling load in this data set. Nevertheless, the newly developed training techniques associated with supervised deep learning, including using the dropout

method for model regularization and the *ReLU* as the activation function, do help to enhance the prediction performance of neural networks.

One interesting finding of this research is that significant improvement in prediction performance can be achieved when using features extracted by unsupervised deep learning models. The features extracted can almost always lead to the best prediction performance, no matter which nonlinear prediction technique is used. By contrast, the three other conventional feature extraction methods do not always guarantee the discovery of useful features and negative influence on prediction performance can be observed. Feature extraction is one of the most challenging tasks in predictive modeling, especially when the volume of data variables is large and domain expertise is lacking. The success of using unsupervised deep learning for feature extraction provides great flexibilities in practical applications. It enables a purely data-driven approach to extract meaningful features and therefore, greatly reduces the complexity in building energy prediction.

The deep learning-based methods proposed in this study can achieve accurate and reliable prediction of 24-h ahead building cooling load profiles. It is of high practical value, as the 24-h ahead building cooling load profile is the foundation for many building operation management tasks. It can be used to develop demandside management (DSM) programs, optimal control strategies, as well as fault detection and diagnosis methods. As examples, with the predicted 24-h ahead cooling load profiles, chiller sequencing control schemes can be developed to maximize the energy efficiency of chiller plants. The deviation between the observed and predicted cooling load can be used as indicators for detecting anomalies in building operations. Control strategies can be developed to regulate the demand response operations and thereby, facilitate the interactions between building operations and smart-grid. Further studies using data from various sources will be valuable for testing the proposed methods and promoting their applications in practice.

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