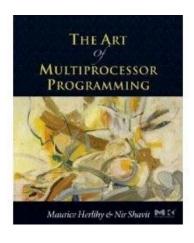
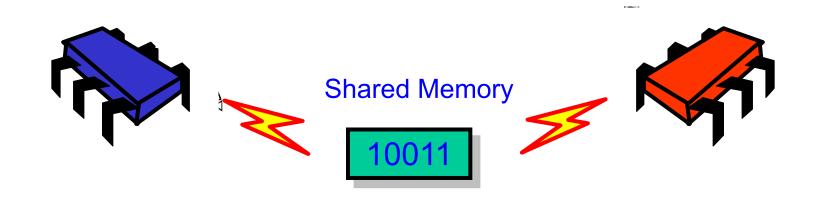
# The Relative Power of Synchronization Operations



Hyungsoo Jung



# **Shared-Memory Computability**



- Mathematical model of concurrent computation
- What is (and is not) concurrently computable
- Efficiency (mostly) irrelevant



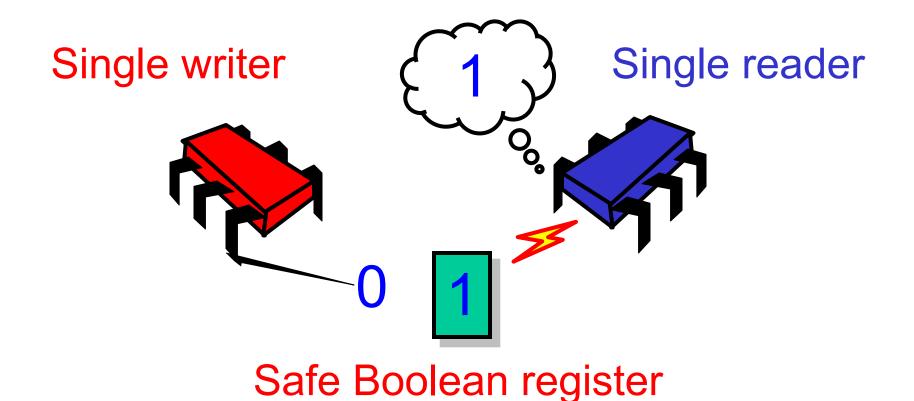
# Wait-Free Implementation

- Every method call completes in finite number of steps
- Implies no mutual exclusion



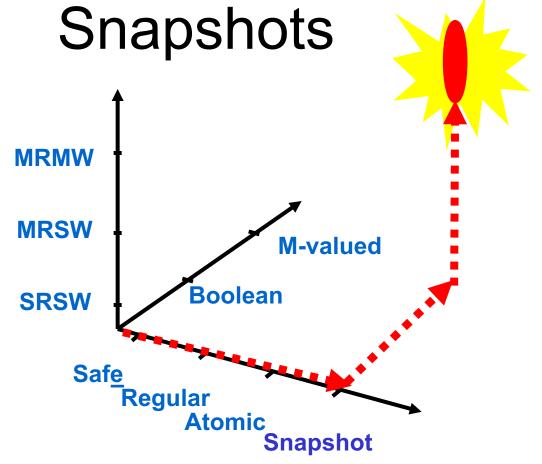


# From Weakest Register





# All the way to a Wait-free Implementation of Atomic





### Rationale for wait-freedom

 We wanted atomic registers to implement mutual exclusion



#### Rationale for wait-freedom

- We wanted atomic registers to implement mutual exclusion
- So we couldn't use mutual exclusion to implement atomic registers



#### Rationale for wait-freedom

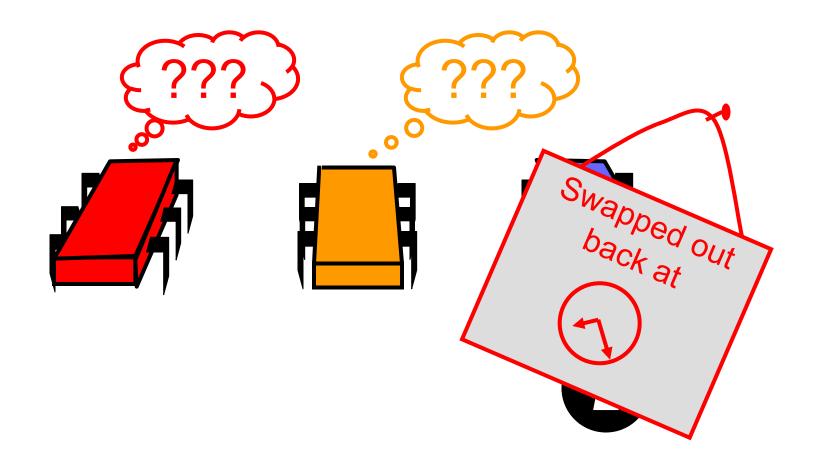
- We wanted atomic registers to implement mutual exclusion
- So we couldn't use mutual exclusion to implement atomic registers
- But wait, there's more!



# Why is Mutual Exclusion so wrong?

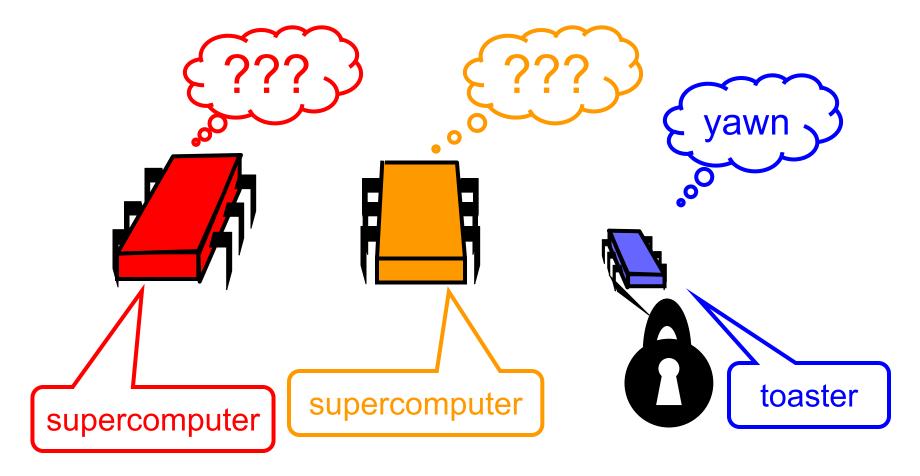


# Asynchronous Interrupts



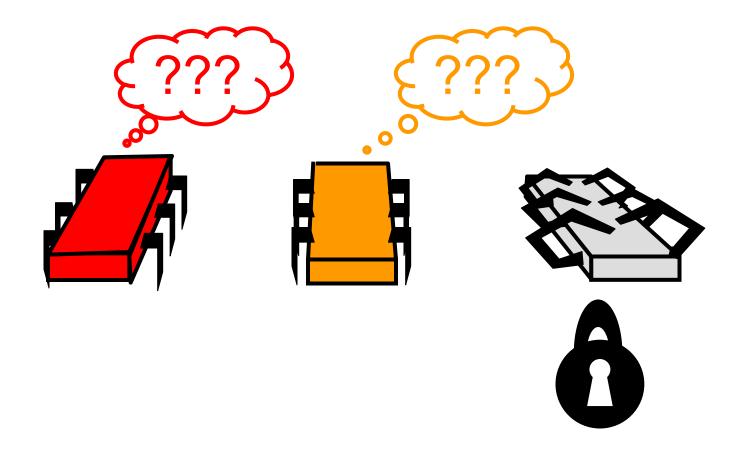


# Heterogeneous Processors



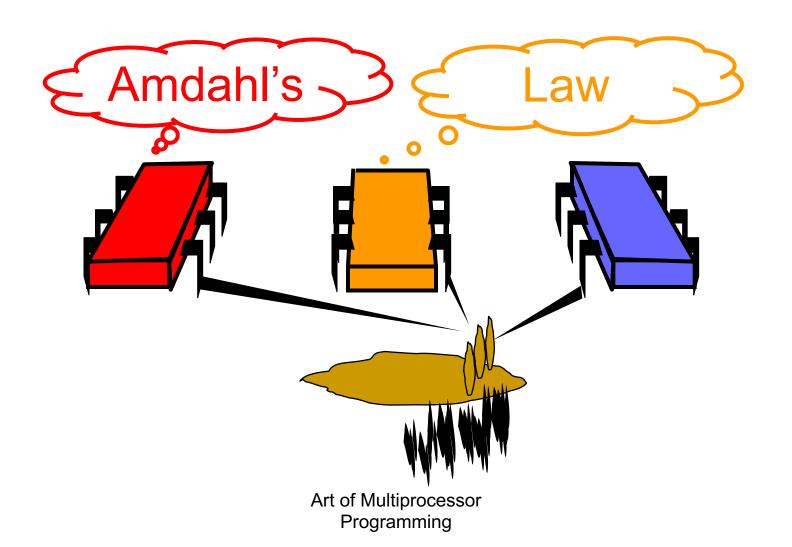


# Fault-tolerance





# Machine Level Instruction Granularity





 Wait-Free synchronization might be a good idea in principle



- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...



- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...
  - Systematically?



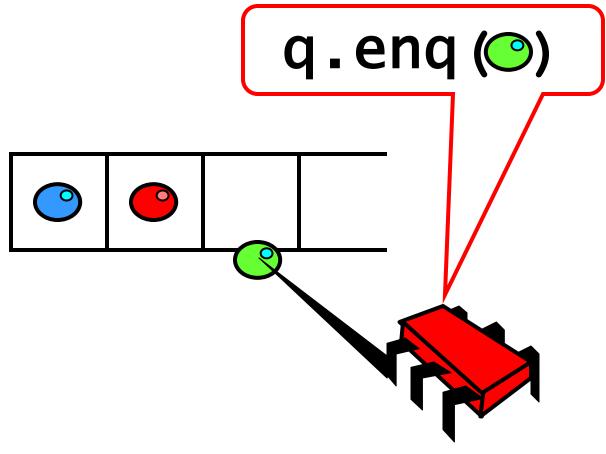
- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...
  - Systematically?
  - Correctly?



- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...
  - Systematically?
  - Correctly?
  - Efficiently?

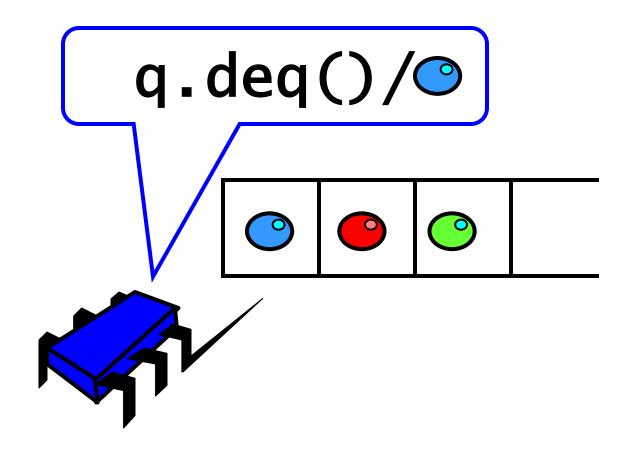


## FIFO Queue: Enqueue Method





## FIFO Queue: Dequeue Method



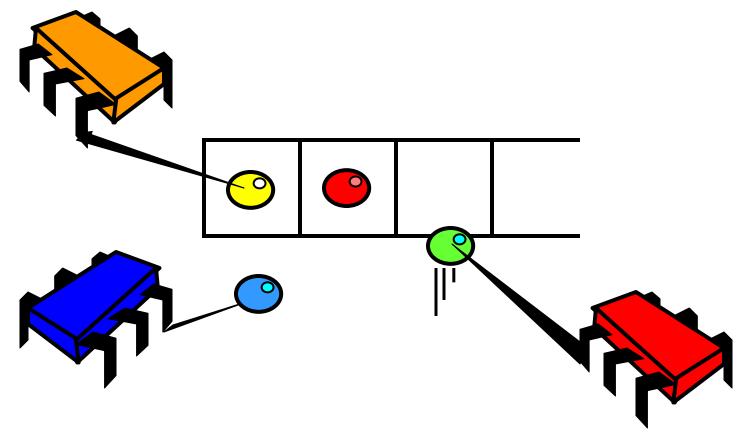


#### Two-Thread Wait-Free Queue

```
public class WaitFreeQueue {
                                           tail
 int head = 0, tail = 0;
                                capacity-1 Y Z
 Item[QSIZE] items;
 public void eng(Item x) {
 while (tail-head == QSIZE) {};
  items[tail % QSIZE] = x; tail++;
 public Item deq() {
  while (tail-head == 0) {}
  Item item = items[head % QSIZE];
  head++; return item;
}}
```



## What About Multiple Dequeuers?

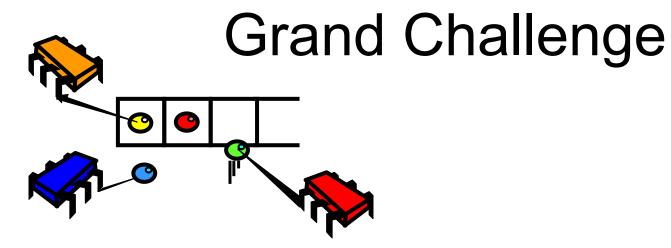




# Grand Challenge

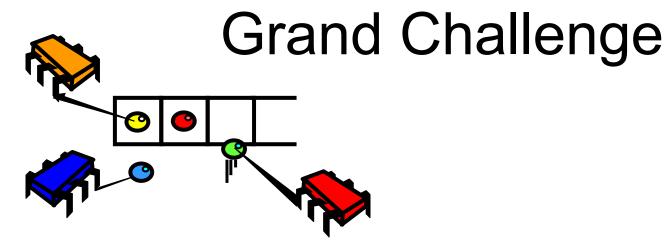
Implement a FIFO queue





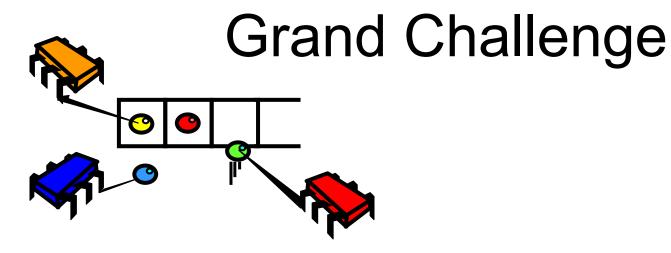
- Implement a FIFO queue
  - Wait-free





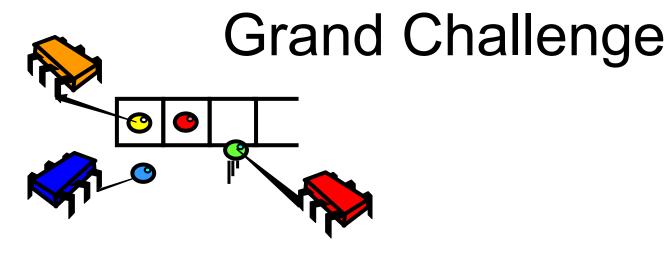
- Implement a FIFO queue
  - Wait-free
  - Linearizable





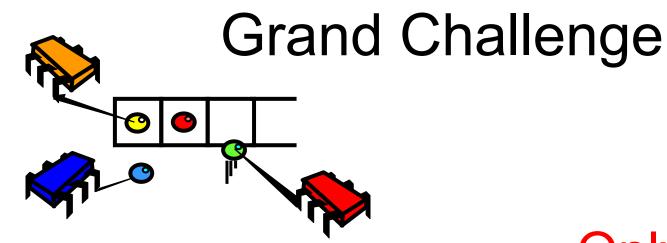
- Implement a FIFO queue
  - Wait-free
  - Linearizable
  - From atomic read-write registers





- Implement a FIFO queue
  - Wait-free
  - Linearizable
  - From atomic read-write registers
  - Multiple dequeuers





Only new aspect

- Implement a FIFO queue
  - Wait-free
  - Linearizable
  - From atomic read-write registers
  - Multiple dequeuers



#### Puzzle

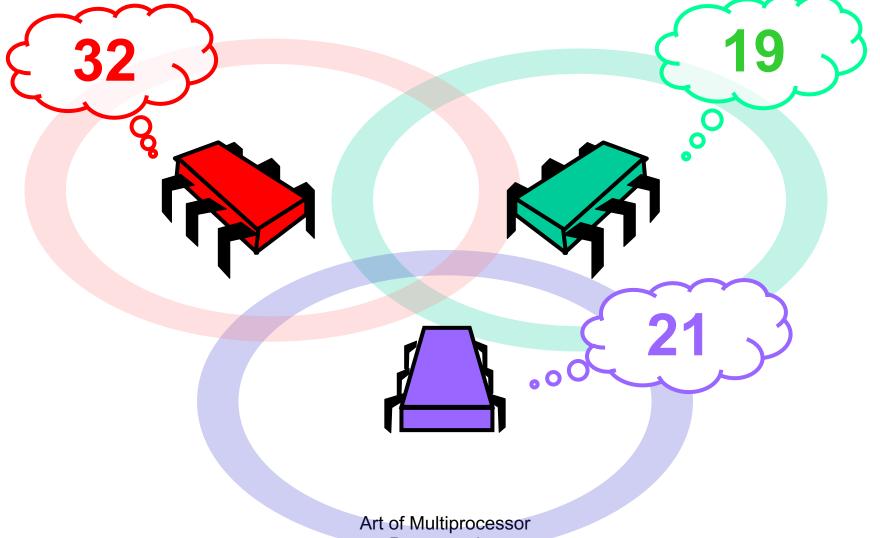
While you are ruminating on the grand challenge ...

We will give you another puzzle ...

Consensus!

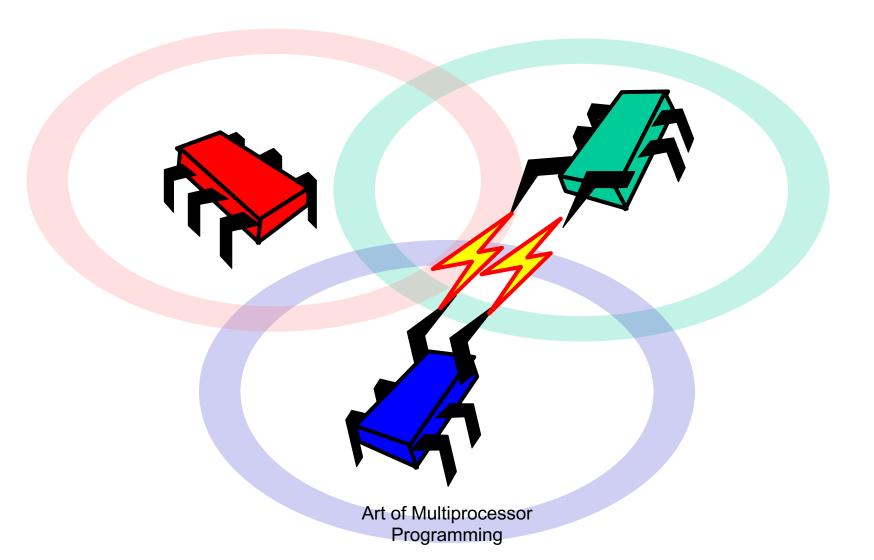


Consensus: Each Thread has a Private Input



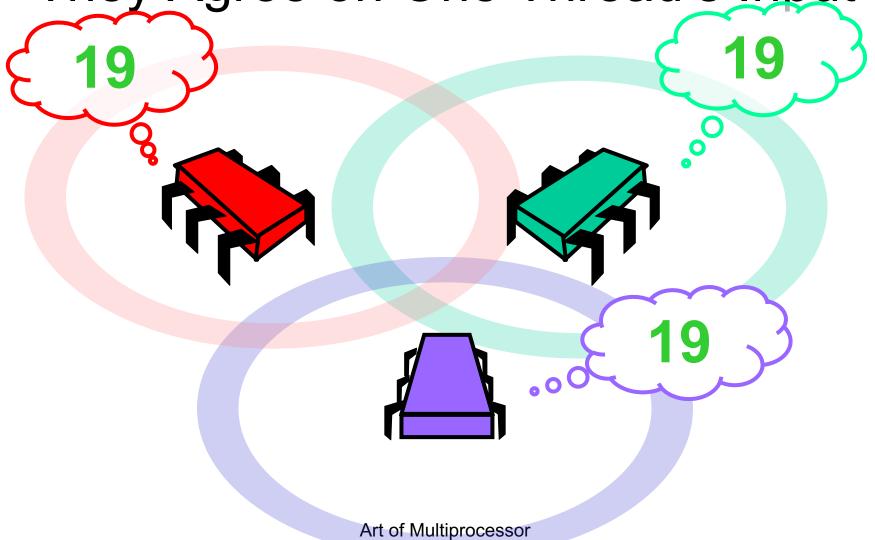


# They Communicate





# They Agree on One Thread's Input





# Formally: Consensus

- Consistent:
  - all threads decide the same value

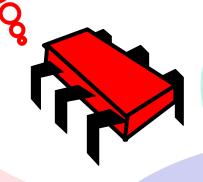


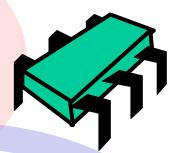
# Formally: Consensus

- Consistent:
  - all threads decide the same value
- Valid:
  - the common decision value is some thread's input



# No Wait-Free Implementation of Consensus using Registers









# Formally

- Theorem
  - There is no wait-free implementation of n-thread consensus from read-write registers



# Formally

- Theorem
  - There is no wait-free implementation of n-thread consensus from read-write registers
- Implication
  - Asynchronous computability different from Turing computability



## **Proof Strategy**

Assume otherwise ...

Reason about the properties of any such protocol ...

Derive a contradiction

Quod

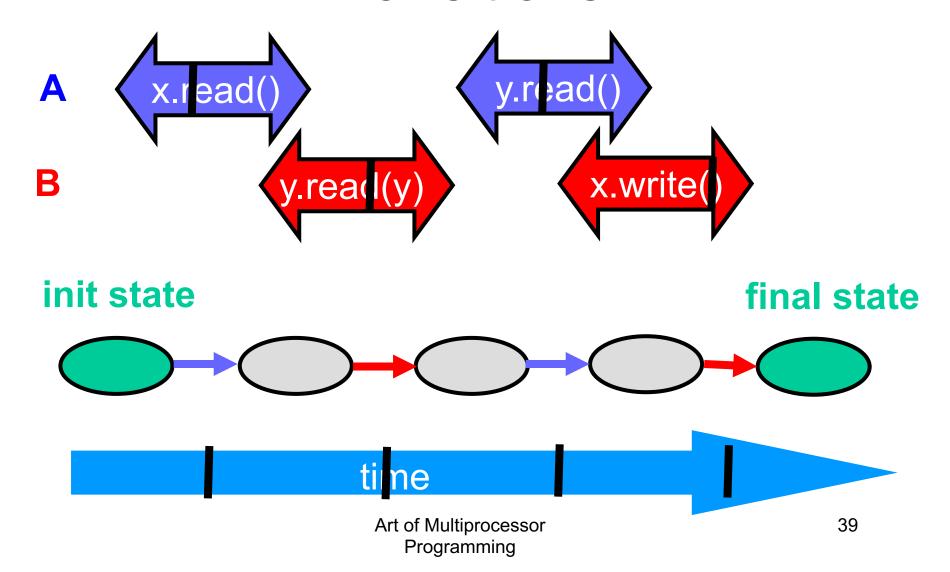
**Erat** 

**Demonstrandum** 

Enough to consider binary consensus and *n*=2

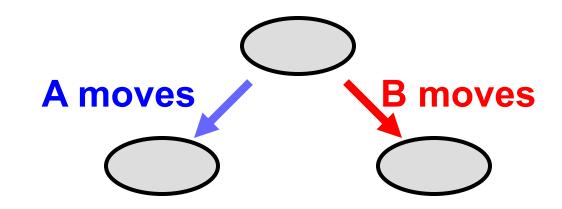


# Protocol Histories as State Transitions





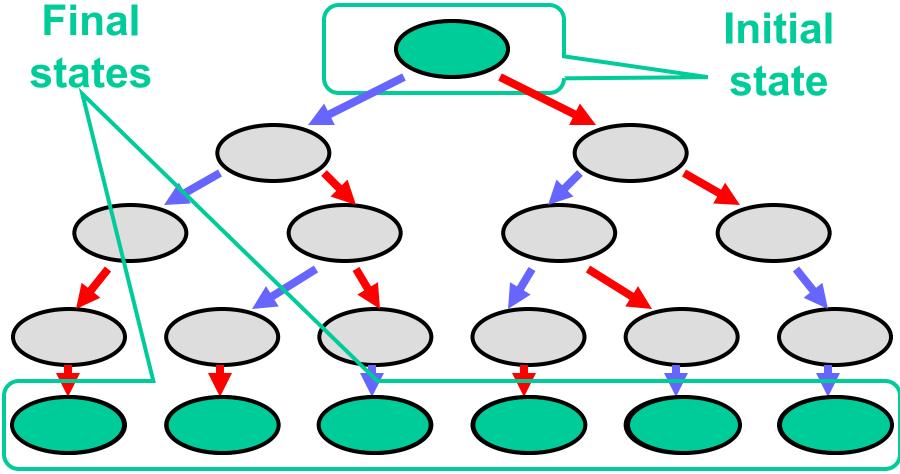
## Wait-Free Computation



- Either A or B "moves"
- Moving means
  - Register read
  - Register write

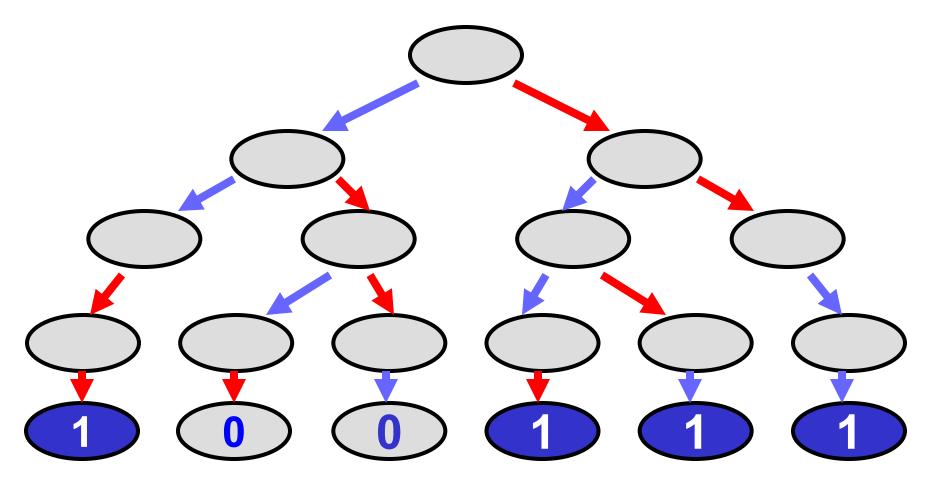


### The Two-Move Tree



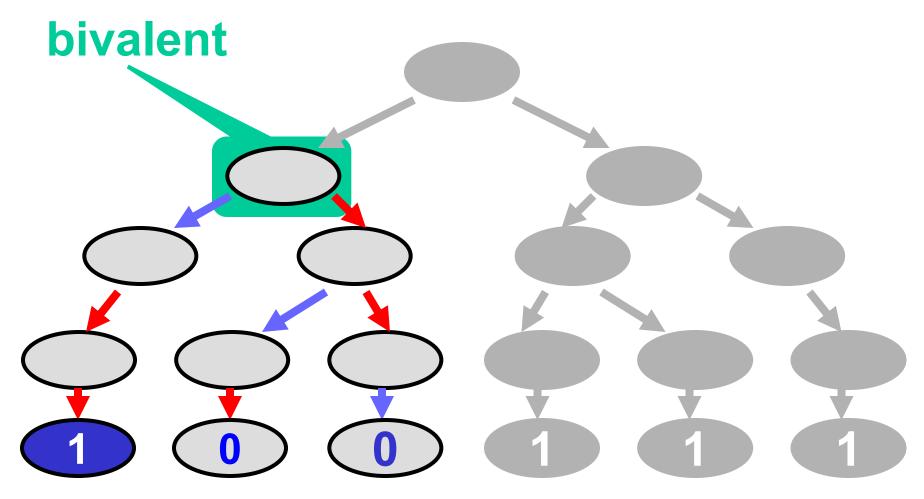


## **Decision Values**



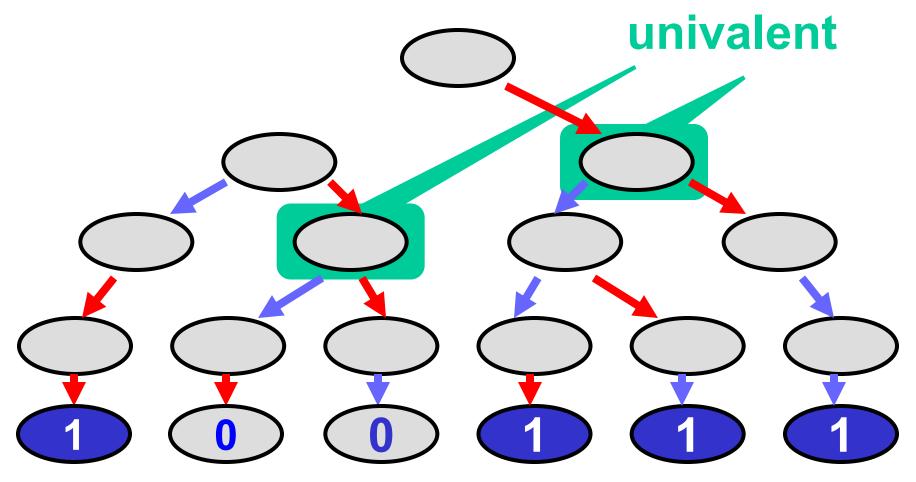


### Bivalent: Both Possible



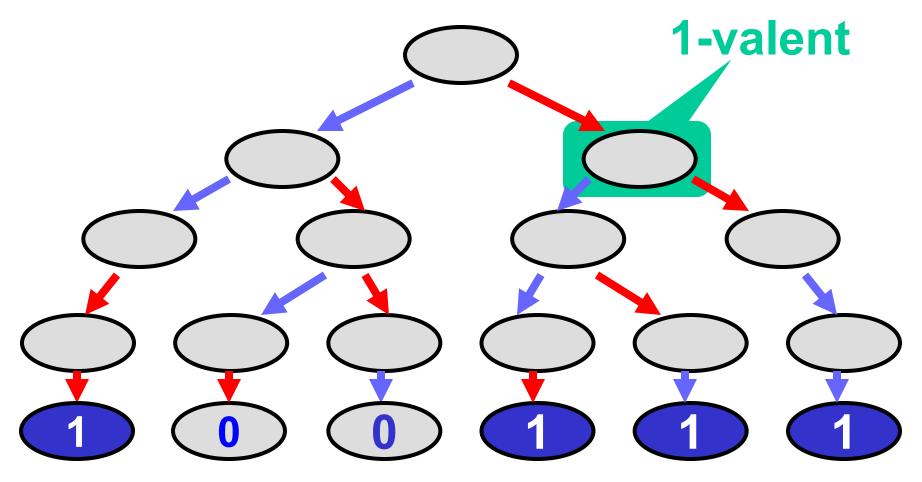


## Univalent: Single Value Possible





## x-valent: x Only Possible Decision





Wait-free computation is a tree



- Wait-free computation is a tree
- Bivalent system states
  - Outcome not fixed



- Wait-free computation is a tree
- Bivalent system states
  - Outcome not fixed
- Univalent states
  - Outcome is fixed
  - May not be "known" yet



- Wait-free computation is a tree
- Bivalent system states
  - Outcome not fixed
- Univalent states
  - Outcome is fixed
  - May not be "known" yet
- 1-Valent and 0-Valent states



Some initial state is bivalent



- Some initial state is bivalent
- Outcome depends on
  - -Chance
  - -Whim of the scheduler



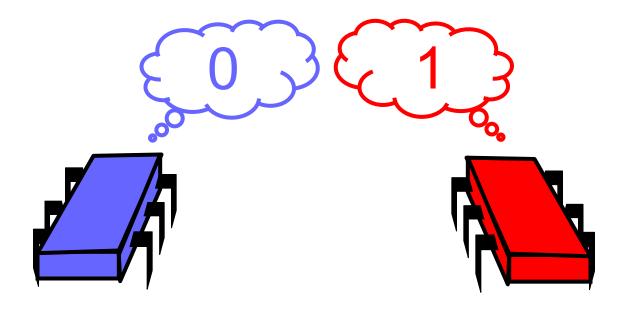
- Some initial state is bivalent
- Outcome depends on
  - -Chance
  - -Whim of the scheduler
- Multiprocessor gods do play dice ...



- Some initial state is bivalent
- Outcome depends on
  - -Chance
  - -Whim of the scheduler
- Multiprocessor gods do play dice ...
- Let's prove it ....

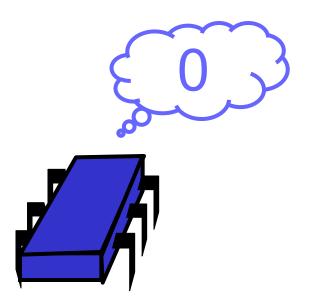


# What if inputs differ?





#### Must Decide 0

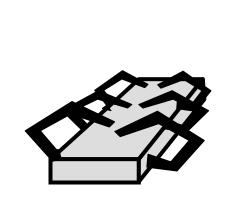


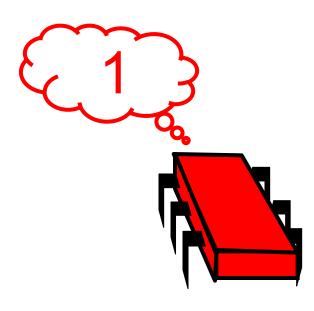


In this solo execution by A



### Must Decide 1

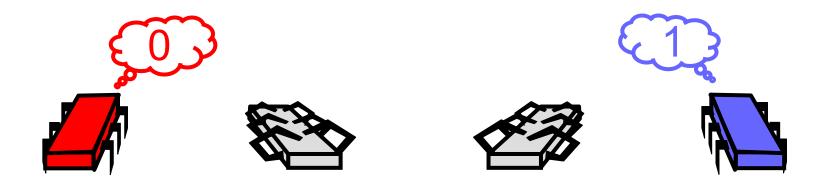




In this solo execution by B

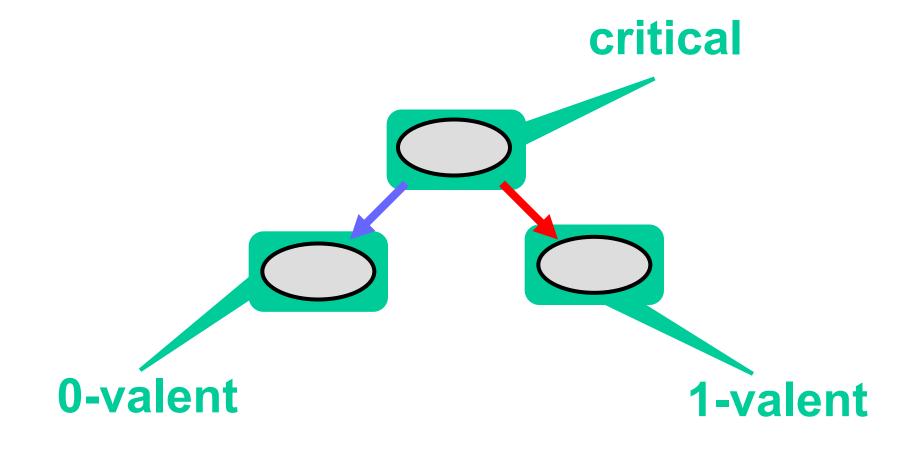


#### Mixed Initial State Bivalent



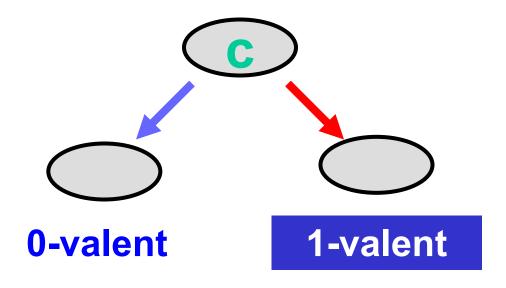
- Solo execution by A must decide 0
- Solo execution by B must decide 1







#### From a Critical State

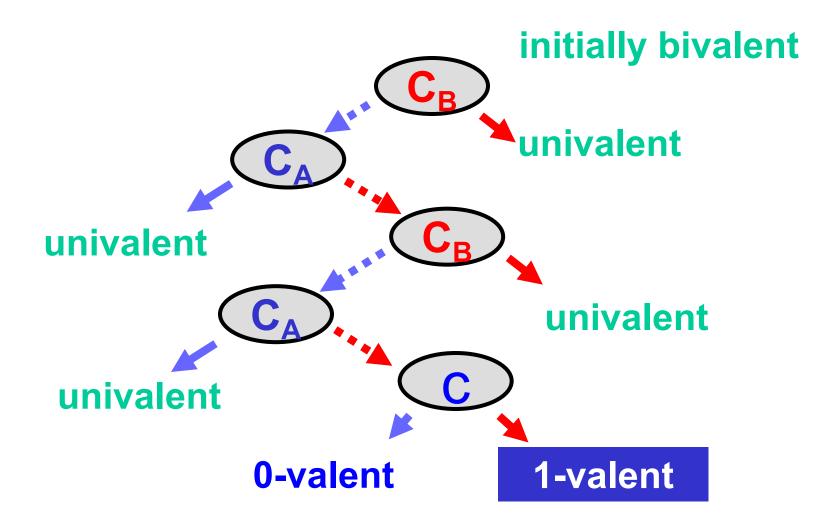


If A goes first, protocol decides 0

If B goes first, protocol decides 1



## Reaching Critical State





Starting from a bivalent initial state



- Starting from a bivalent initial state
- The protocol can reach a critical state



- Starting from a bivalent initial state
- The protocol can reach a critical state
  - Otherwise we could stay bivalent forever
  - And the protocol is not wait-free



## Model Dependency

- So far, memory-independent!
- True for
  - Registers
  - Message-passing
  - Carrier pigeons
  - Any kind of asynchronous computation



Start from a critical state



- Start from a critical state
- Each thread fixes outcome by
  - Reading or writing ...
  - Same or different registers



- Start from a critical state
- Each thread fixes outcome by
  - Reading or writing ...
  - Same or different registers
- Leading to a 0 or 1 decision ...



- Start from a critical state
- Each thread fixes outcome by
  - Reading or writing ...
  - Same or different registers
- Leading to a 0 or 1 decision ...
- And a contradiction.



### Possible Interactions

	x.read()	y.read()	x.write()	y.write()		
x.read()	?	?	?	?		
y.read()	?	?	?	?		
x.write()	?	?	?	?		
y.write()	?	?	?	?		
Art of Multiprocessor						

Programming



## Possible Interactions

A reads x

	x.read()	y.read()	x.write()	y.write()
x.read()	?	?	?	?
y.read()	?	?	?	?
x.write()	?	?	?	?
y.write()	?	?	?	?
		70		

Programming



## Possible Interactions

	I	A reads x		
			A	reads y
	x.read()	y.read()	x.write()	y.write()
x.read()	?	?	?	?
y.read()	?	?	?	?
x.write()	?	?	?	?
y.write()	?	?	?	?
	[	Art of Multiprocesso	dr	<sup> </sup> 71

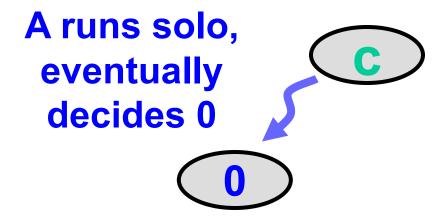
Programming



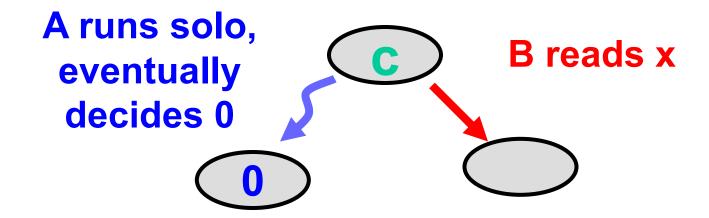
### Some Thread Reads



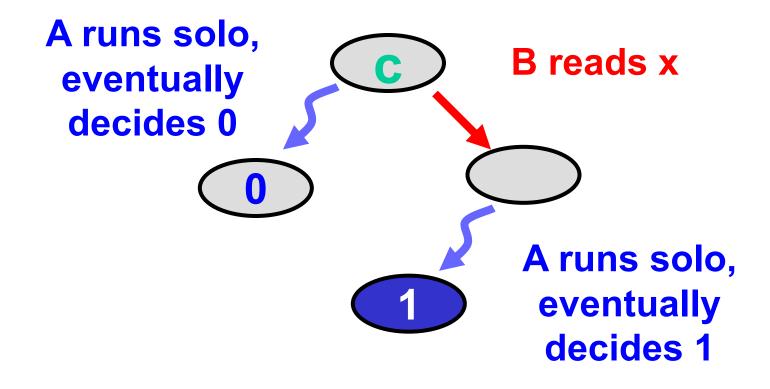




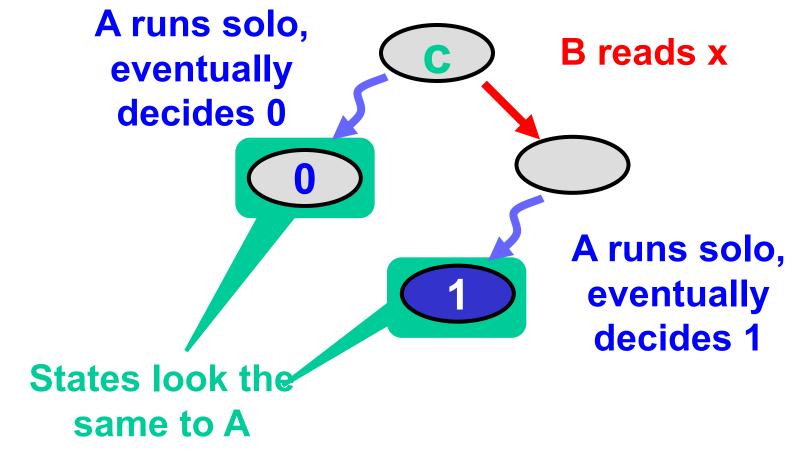




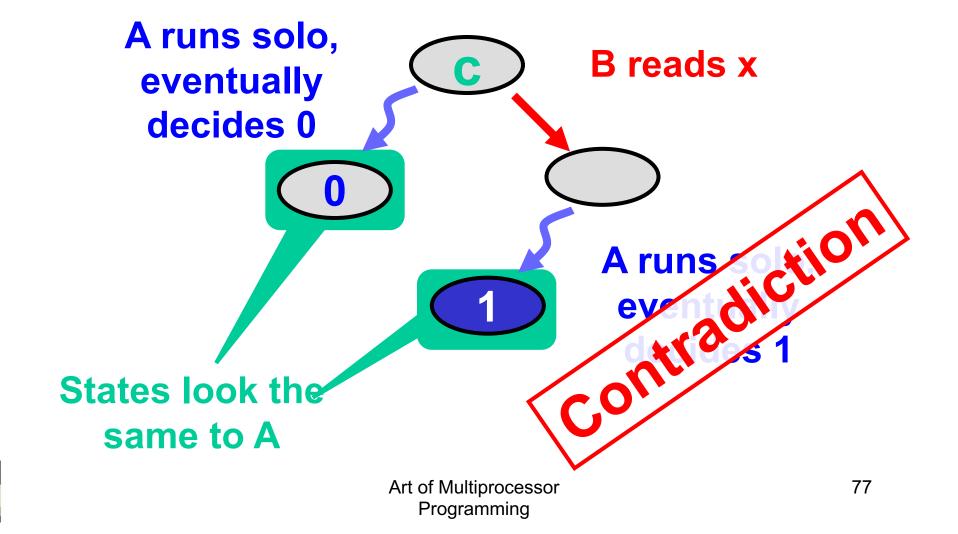














### Possible Interactions

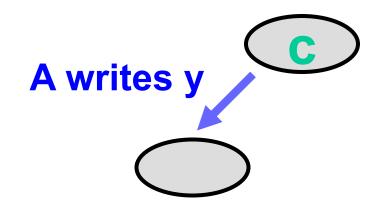
	x.read()	y.read()	x.write()	y.write()		
x.read()	no	no	no	no		
y.read()	no	no	no	no		
x.write()	no	no	?	?		
y.write()	no	no	?	?		
Art of Multiprocessor						

Programming

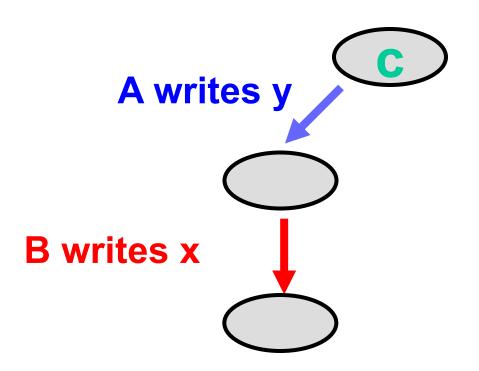




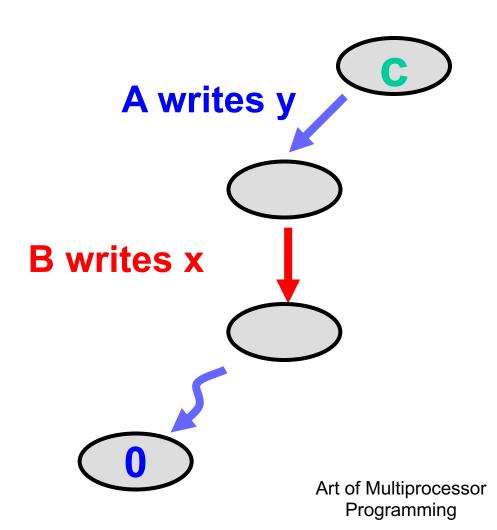




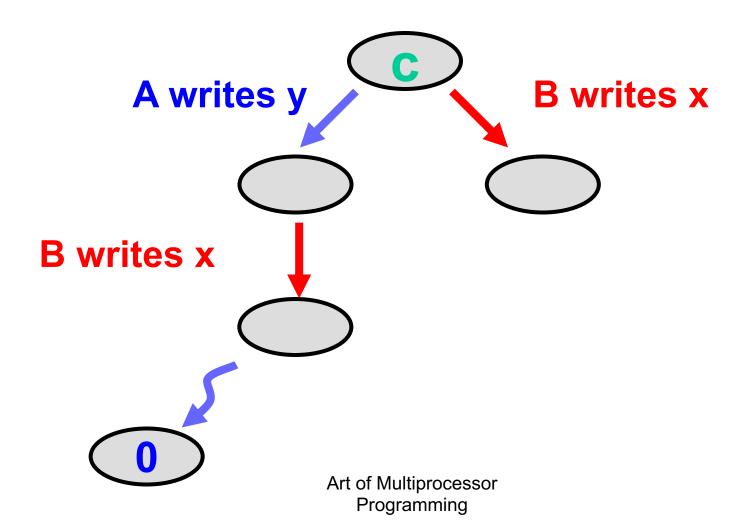




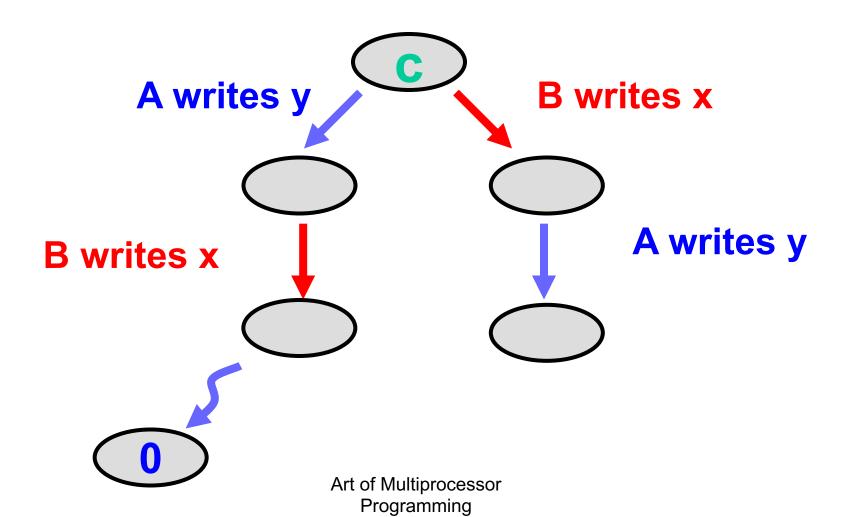




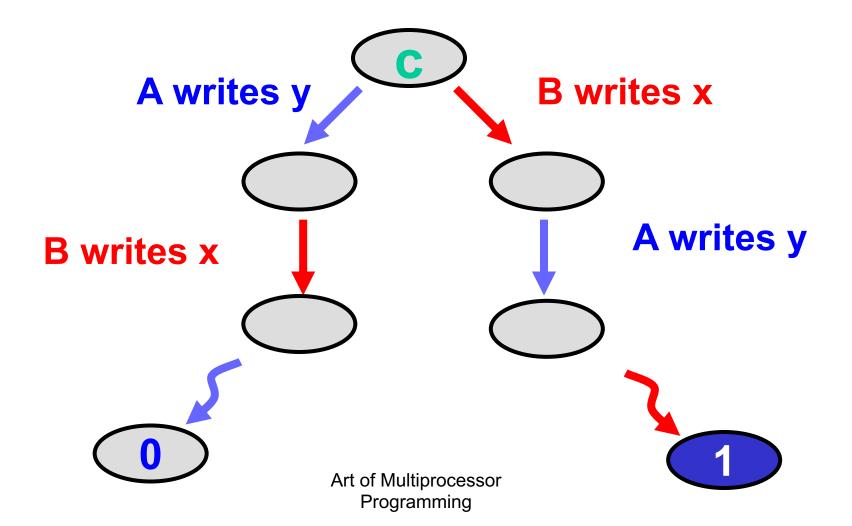




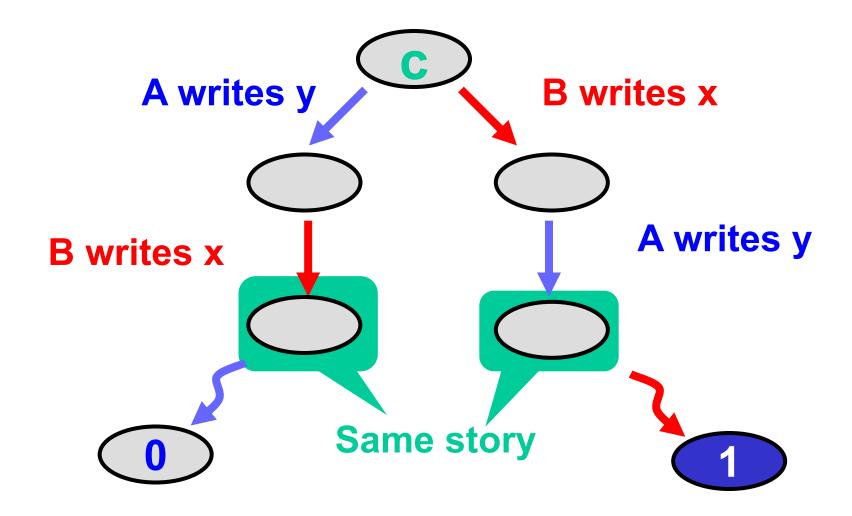




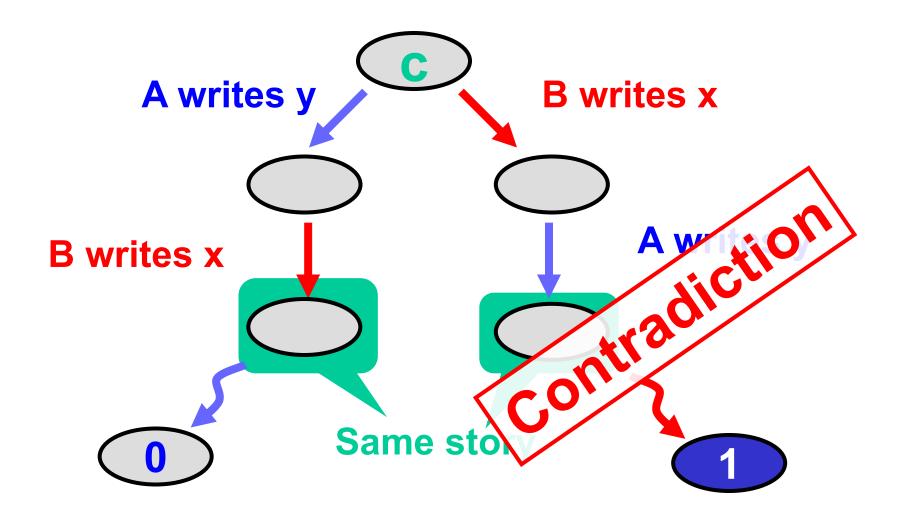












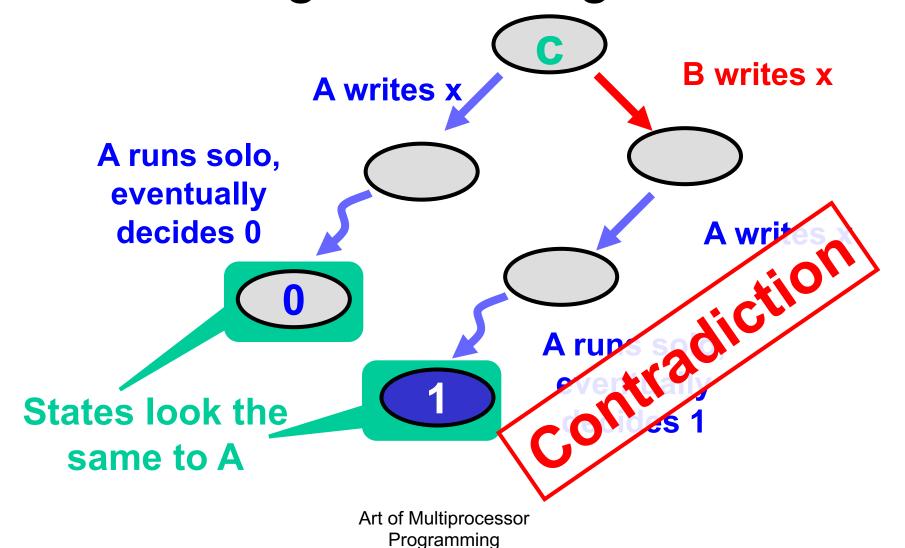


### Possible Interactions

	x.read()	y.read()	x.write()	y.write()	
x.read()	no	no	no	no	
y.read()	no	no	no	no	
x.write()	no	no	?	no	
y.write()	no	no	no	?	
Art of Multiprocessor  Programming					



## Writing Same Registers





## That's All, Folks!

	x.read()	y.read()	x.write()	y.write()		
x.read()	no	no	no	no		
y.read()	no	no	no	no		
x.write()	no	no	no	no		
y.write()	no	no	nd C	no		
Art of Multiprocessor						

Programming

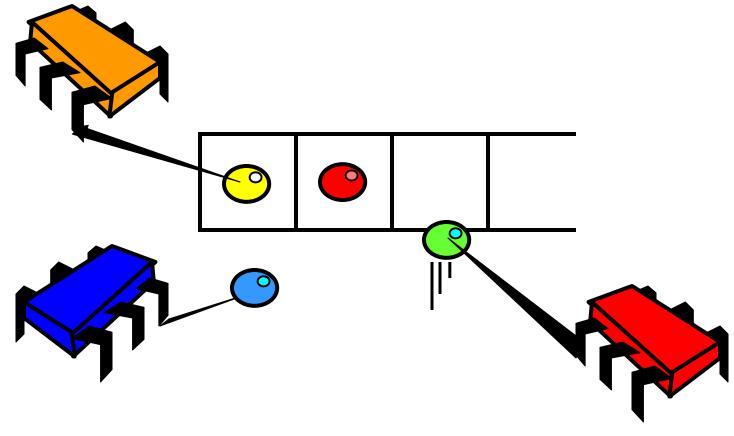


## Recap: Atomic Registers Can't Do Consensus

- If protocol exists
  - It has a bivalent initial state
  - Leading to a critical state
- What's up with the critical state?
  - Case analysis for each pair of methods
  - As we showed, all lead to a contradiction



## What Does Consensus have to do with Concurrent Objects?





## Consensus Object

```
public interface Consensus<T> {
  T decide(T value);
}
```



## Concurrent Consensus Object

- We consider only one time objects:
  - each thread calls method only once
- Linearizable to consensus object:
  - Winner's call went first



## Java Jargon Watch

- Define Consensus protocol as an abstract class
- We implement some methods
- You do the rest ...



```
abstract class ConsensusProtocol<T>
  implements Consensus<T> {
protected T[] proposed = new T[N];
protected void propose(T value) {
 proposed[ThreadID.get()] = value;
abstract public T decide(T value);
```



```
abstract class ConsensusProtocol<T>
   implements Consensus<T>
protected T[] proposed = new T[N];
protected void propose
  proposed[ThreadID.get(
                       Each thread's
abstract public T d
                      proposed value
```



```
abstract class ConsensusProtocol<T>
  implements Consensus<T> {
protected T[] proposed = new T[N];
protected void propose(T value) {
 proposed[ThreadID.get()] = value;
abstract public T decide(T //a
                      Propose a value
```



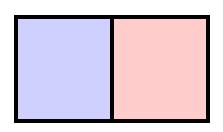
```
Decide a value: abstract method
   means subclass does the real work
protected void propose(T value) {
 proposed[ThreadID.get()] = value;
abstract public T decide(T value);
```



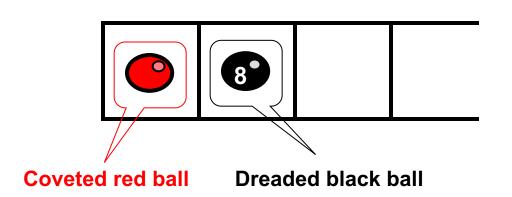
# Can a FIFO Queue Implement Consensus?



#### FIFO Consensus



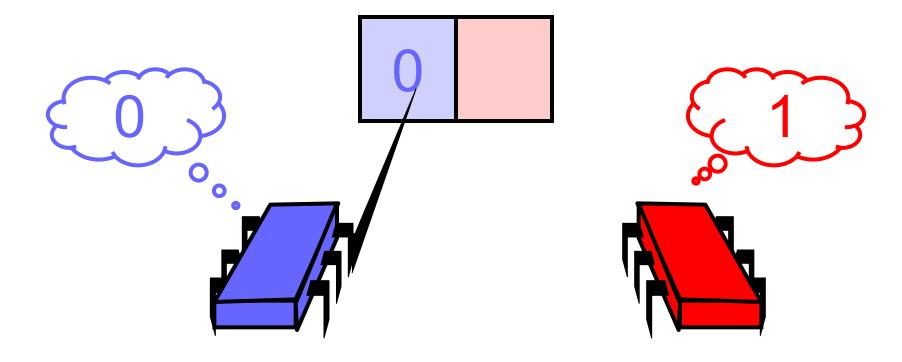
proposed array



FIFO Queue with red and black balls

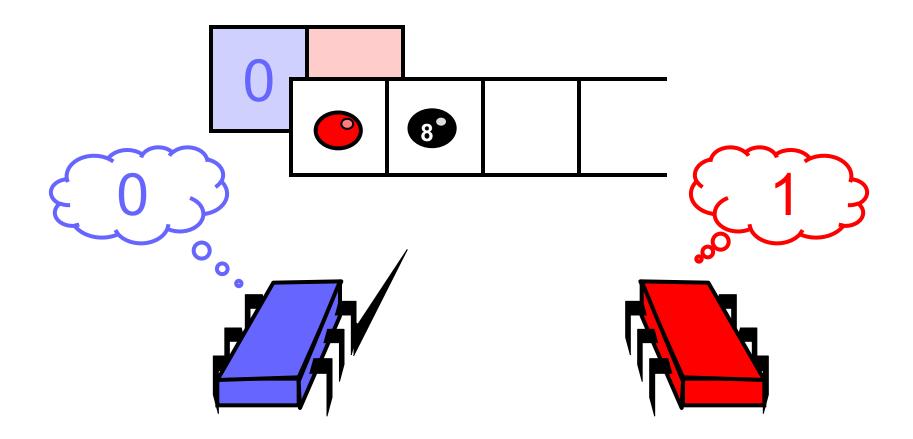


## Protocol: Write Value to Array



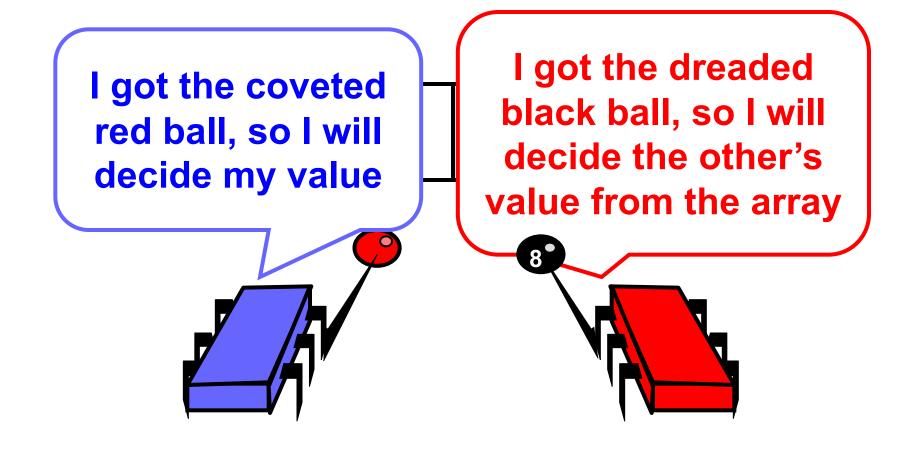


### Protocol: Take Next Item from Queue





#### Protocol: Take Next Item from Queue





## Consensus Using FIFO Queue

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public QueueConsensus() {
  queue = new Queue();
  queue.enq(Ball.RED);
  queue.eng(Ball.BLACK);
```



### Initialize Queue

```
public class QueueConsensus
 extends ConsensusProtocol {
 private Queue queue;
 public QueueConsensus()
 this.queue = new Queue();
 this.queue.enq(Ball.RED);
 this.queue.enq(Ball.BLACK);
```



### Who Won?

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose(value);
  Ball ball = queue.deq();
  if (ball == Ball.RED)
   return proposed[i];
  else
   return proposed[1-i];
```



### Who Won?

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose(value):
 Ball ball = queue.deq();
          == Ba \ . RED
   return proposed[
 else
   return proposed[1-ij];
                         Race to dequeue
                          first queue item
```



#### Who Won?

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose(value);
       ball = this.queue.deq();
 if (ball == Ball.RED)
   return proposed[i];
   return proposed[1-i
                        win if I was first
```



#### Who Won?

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
                       Other thread wins if I
 public T decide(T valux) was second
  propose(value);
  Ball ball = this.queue.deq();
  if (ball == Bal X.RED)
  else
   return proposed[1-i];
```



# Why does this Work?

- If one thread gets the red ball
- Then the other gets the black ball
- Winner decides her own value
- Loser can find winner's value in array
  - Because threads write array
  - Before dequeueing from queue



#### Theorem

- We can solve 2-thread consensus using only
  - A two-dequeuer queue, and
  - Some atomic registers



# **Implications**

- Given
  - A consensus protocol from queue and registers
- Assume there exists
  - A queue implementation from atomic registers
- Substitution yields:
  - A wait-free consensus protocol from atomic registers;



# Corollary

- It is impossible to implement
  - a two-dequeuer wait-free FIFO queue
  - from read/write memory.



#### Consensus Numbers

- An object X has consensus number n
  - If it can be used to solve n-thread consensus
    - Take any number of instances of X
    - together with atomic read/write registers
    - and implement *n*-thread consensus
  - But not (n+1)-thread consensus



#### Consensus Numbers

- Theorem
  - Atomic read/write registers have consensus number 1
- Theorem
  - Multi-dequeuer FIFO queues have consensus number at least 2



# Consensus Numbers Measure Synchronization Power

#### Theorem

- If you can implement X from Y
- And X has consensus number c
- Then Y has consensus number at least c



# Synchronization Speed Limit

- Conversely
  - If X has consensus number c
  - And Y has consensus number d < c
  - Then there is no way to construct a wait-free implementation of X by Y
- This theorem will be very useful
  - Unforeseen practical implications!



# Earlier Grand Challenge

- Snapshot means
  - Write any array element
  - Read multiple array elements atomically
- What about
  - Write multiple array elements atomically
  - Scan any array elements
- Call this problem multiple assignment



#### Multiple Assignment Theorem

- Atomic registers cannot implement multiple assignment
- Weird or what?
  - Single write/multi read OK
  - Multi write/multi read impossible



# **Proof Strategy**

- If we can write to 2/3 array elements
  - We can solve 2-consensus
  - Impossible with atomic registers
- Therefore
  - Cannot implement multiple assignment with atomic registers



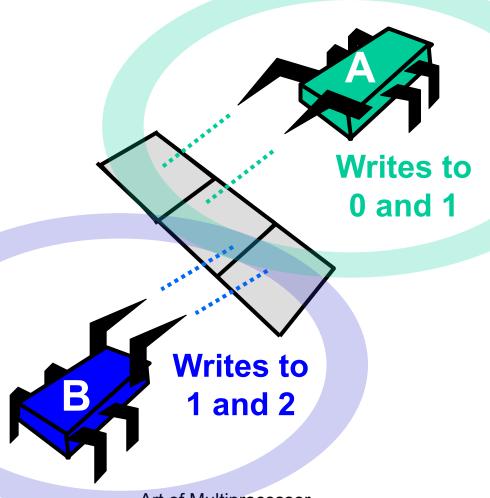
(1)

# **Proof Strategy**

- Take a 3-element array
  - A writes atomically to slots 0 and 1
  - B writes atomically to slots 1 and 2
  - Any thread can scan any set of locations

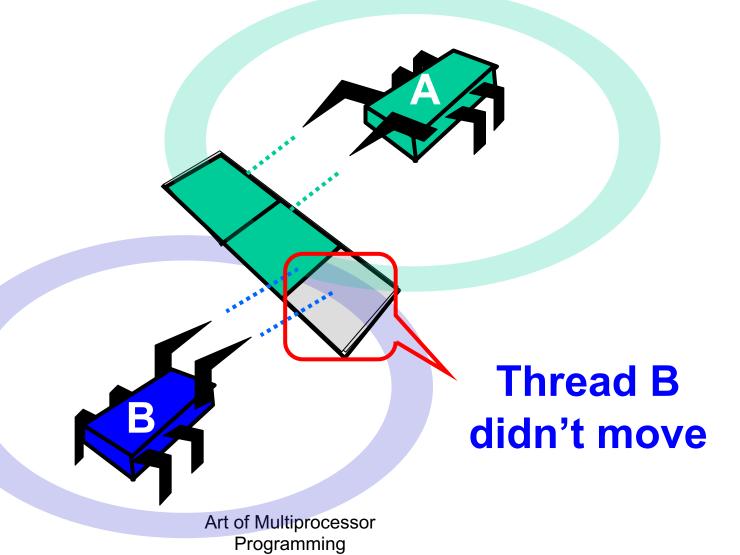


# Initially



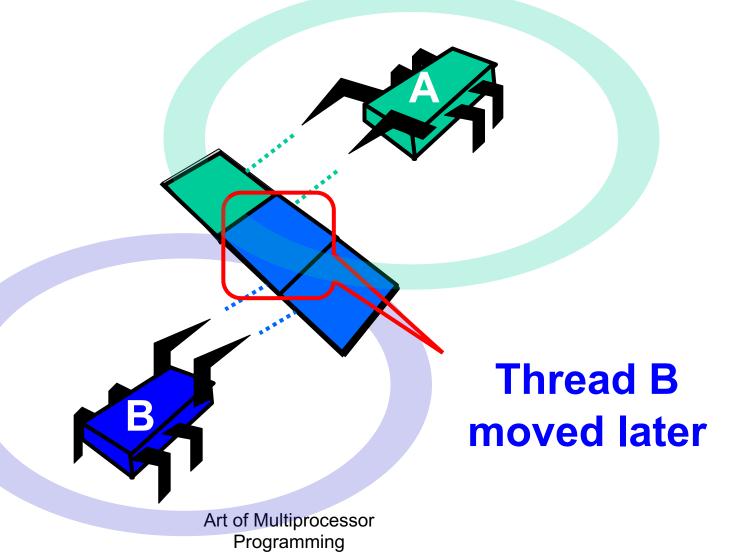


#### Thread A wins if



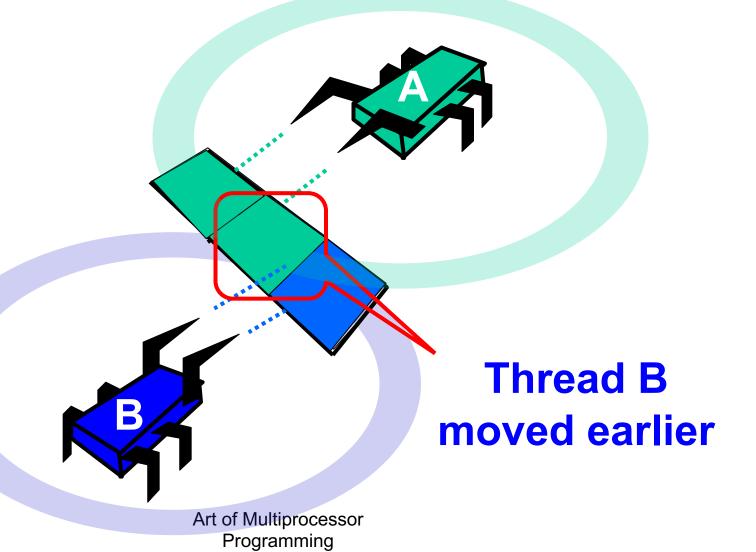


## Thread A wins if





#### Thread A loses if





# Summary

- If a thread can assign atomically to 2 out of 3 array locations
- Then we can solve 2-consensus
- Therefore
  - No wait-free multi-assignment
  - From read/write registers



# Read-Modify-Write Objects

- Method call
  - Returns object's prior value x
  - Replaces x with mumble(x)



# Read-Modify-Write

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndMumble() {
    int prior = value;
    value = mumble(value);
    return prior;
```



# Read-Modify-Write

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndMumble() {
   int prior = value;
    value = mumble(value);
    return prior;
                    Return prior value
```



# Read-Modify-Write

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndMumble() {
    int prior = value;
   value = mumble(value);
    return prior;
        Apply function to current value
```



# RMW Everywhere!

- Most synchronization instructions
  - are RMW methods
- The rest
  - Can be trivially transformed into RMW methods



# Example: Read

```
public abstract class RMWRegister {
  private int value;
  public int synchronized read() {
    int prior = value;
    value = value;
    return prior;
```



# **Example: Read**

```
public abstract class RMW {
  private int value;
  public int synchronized read() {
    int prior = this.value;
   value = value;
    return pri
             apply f(v)=v, the
             identity function
```



# Example: getAndSet

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndSet(int v) {
  int prior = value;
 value = v;
  return prior;
```



# Example: getAndSet (swap)

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
   getAndSet(int v) {
  int prior = value;
 value = v;
      F(x)=v is constant function
```



# getAndIncrement

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndIncrement() {
  int prior = value;
 value = value + 1;
  return prior;
```



# getAndIncrement

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
   getAndIncrement() {
  int prior = value;
 value = value + 1;
  return prior;
        F(x) = x+1
```



## getAndAdd

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndAdd(int a) {
  int prior = value;
 value = value + a;
  return prior;
```



# Example: getAndAdd

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
   getAndIncrement(int a) {
  int prior = value;
 value = value + a;
  return prior;
         F(x) = x+a
```



```
public abstract class RMWRegister {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                 int update) {
  int prior = value;
  if (value==expected) {
   value = update; return true;
  return false;
  } ... }
```



```
public abstract class RMWRegister {
 private int value;
 public boolean synchronized
   compareAndSet(int expected)
 int prior = value;
 if (value==expected)
    lue = update; leturn tr
 return false;
                If value is as expected, ...
 } ... }
```



```
public abstract class RMWRegister {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                  int (update)
 int prior = value;
 if (value==expected) {
 value = update; return true:
 return false;
                    ... replace it
} ... }
```



```
public abstract class RMWRegister {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                 int update) {
int prior = value;
if (value==expected)
 value = update; return true;
 return false;
                Report success
} ... }
```



## compareAndSet

```
public abstract class RMWRegister {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                 int update) {
int prior = value;
if (value==expected) {
 value = update; return true;
                       Otherwise report
return false;
                            failure
```



# Read-Modify-Write

```
public abstract class RMWRegister {
 private int value;
 public void synchronized
 getAndMumble() {
    int prior = value;
    value = mumble(value);
    return prior;
           Lets characterize F(x)...
```



#### Definition

- A RMW method
  - With function mumble(x)
  - is non-trivial if there exists a value v
  - -Such that  $v \neq \text{mumble}(v)$



# Par Example

- Identity(x) = x
  - is trivial
- getAndIncrement(x) = x+1
  - is non-trivial



#### Theorem

- Any non-trivial RMW object has consensus number at least 2
- No wait-free implementation of RMW registers from atomic registers
- Hardware RMW instructions not just a convenience



#### Reminder

- Subclasses of consensus have
  - propose(x) method
    - which just stores x into proposed[i]
    - built-in method
  - decide(object value) method
    - which determines winning value
    - customized, class-specific method



```
public class RMWConsensus
     extends ConsensusProtocol {
 private RMWRegister r = v;
 public T decide(T value) {
 propose(value);
 if (r.getAndMumble() == v)
   return proposed[i];
 else
   return proposed[j];
}}
```



```
public class RMWConsensus
     extends ConsensusProtocol {
private RMWRegister r = v;
     ic i decide(i value)
  propose(value);
 if (r.getAndMumble()
   return proposed[i];
                        Initialized to v
 else
   return proposed[j];
}}
```



```
public class RMWConsensus
     extends Consensus {
                             Am I first?
private RMWRegister r = v;
public T decide(T value)
  propose(value)
 if (r.getAndMumble() == v)
   return proposed[i];
 else
   return proposed[j];
```



```
public class RMWConsensus
     extends ConsensusProtocol {
private RMWRegister r = v;
public T decide(T value) {
                           Yes, return
  propose(value);
                          my input
  if (r.getAndMumble()
  return proposed[i];
  else
   return proposed[j];
}}
```



```
public class RMWConsensus
     extends ConsensusProtocol {
private RMWRegister r = v;
 public T decide(T value) {
 propose(value);
 if (r.getAndMumble() == v)
                             No, return
   return proposed[i];
                           other's input
  else
  return proposed[j];
```



- We have displayed
  - A two-thread consensus protocol
  - Using any non-trivial RMW object



# Interfering RMW

Let F be a set of functions such that for all f<sub>i</sub> and f<sub>j</sub>
either

- Commute:  $f_i(f_j(v))=f_j(f_i(v))$
- Overwrite:  $f_i(f_i(v))=f_i(v)$
- Claim: Any set of RMW objects that commutes or overwrites has consensus number exactly 2



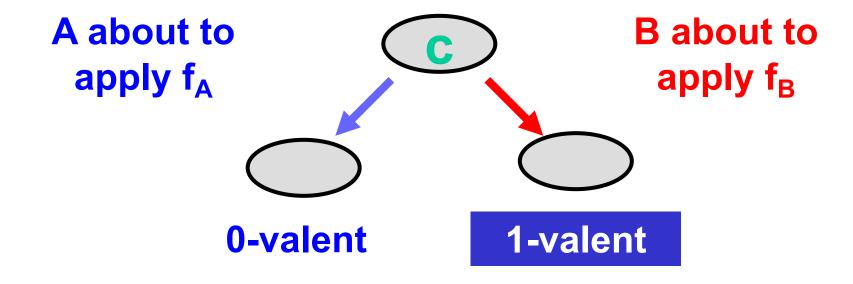
## Examples

"test-and-set" getAndSet(1) f(v)=1
 Overwrite f<sub>i</sub>(f<sub>i</sub>(v))=f<sub>i</sub>(v)

- "swap" getAndSet(x) f(v,x)=x
   Overwrite f<sub>i</sub>(f<sub>i</sub>(v))=f<sub>i</sub>(v)
- "fetch-and-inc" getAndIncrement() f(v)=v+1
   Commute f<sub>i</sub>(f<sub>i</sub>(v))= f<sub>i</sub>(f<sub>i</sub>(v))

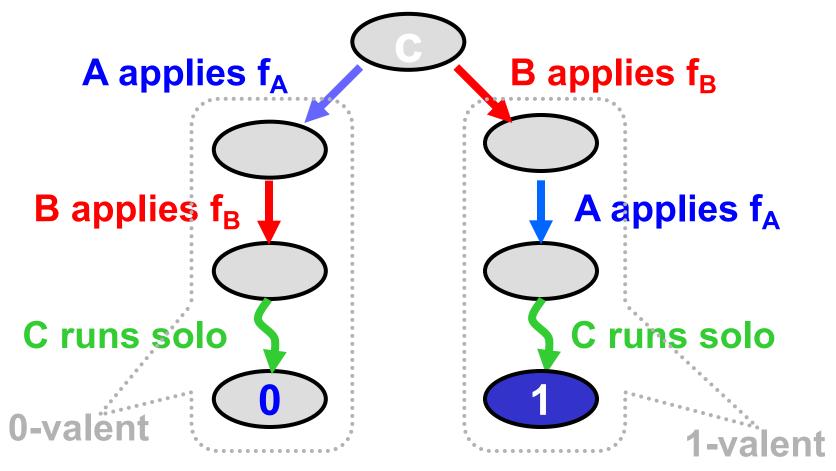


#### Meanwhile Back at the Critical State



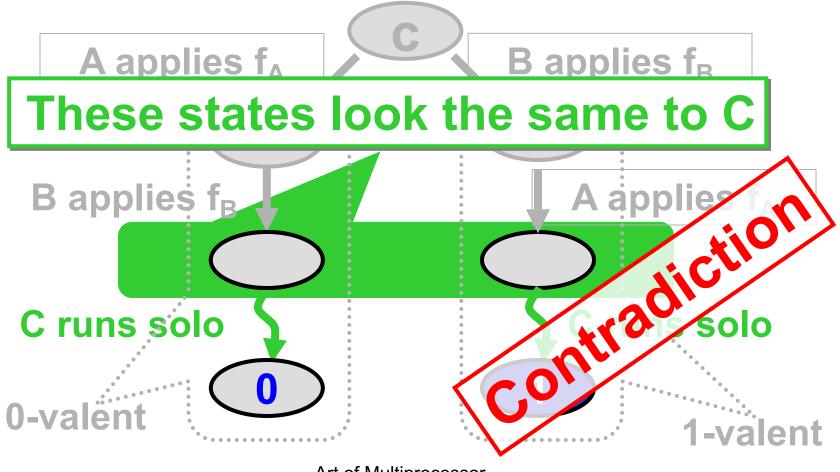


## Maybe the Functions Commute



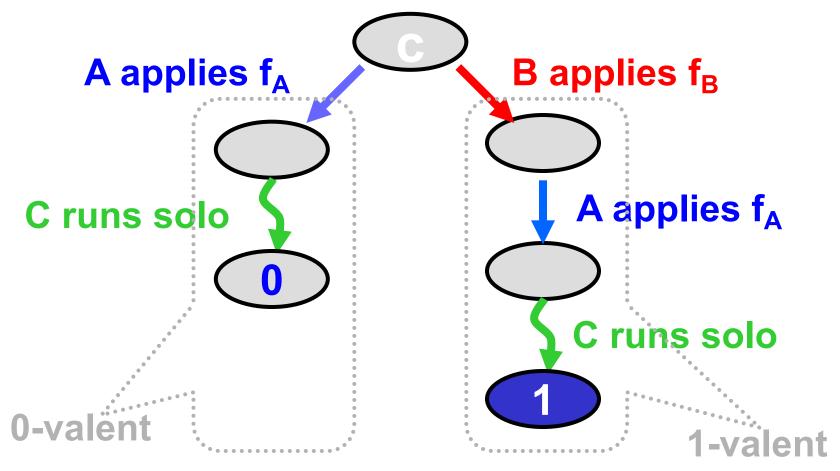


## Maybe the Functions Commute





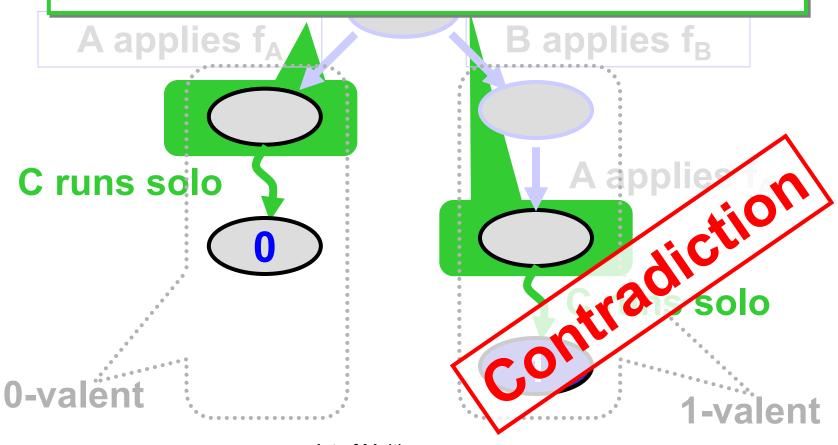
## Maybe the Functions Overwrite





## Maybe the Functions Overwrite

## These states look the same to C





## **Impact**

- Many early machines provided these "weak" RMW instructions
  - Test-and-set (IBM 360)
  - Fetch-and-add (NYU Ultracomputer)
  - Swap (Original SPARCs)
- We now understand their limitations
  - But why do we want consensus anyway?



## compareAndSet

```
public abstract class RMWRegister {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                 int update) {
  int prior = value;
  if (value==expected) {
  value = update; return true;
  return false;
  } ... }
```



## compareAndSet

```
public abstract class RMWRegister {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
 int prior = this.value;
    value==expected)
       value = update; return true;
 return false;
              replace value if it's what we
} ... }
                     expected, ...
```



```
public class RMWConsensus
     extends ConsensusProtocol {
private AtomicInteger r =
  new AtomicInteger(-1);
public T decide(T value) {
 propose(value);
  r.compareAndSet(-1,i);
  return proposed[r.get()];
```



```
public class RMWConsensus
     extends ConsensusProtocol {
private AtomicInteger r =
   new AtomicInteger(-1);
 public T decide(T valu
  propose(value)
  r.compareAndSet(-1,
  return proposed[r.ge
                       Initialized to -1
```



```
public class RMWConsensus
 extends ConsensusProtocol {
private AtomicInteger ry to swap in my
   new AtomicInteger(-1
 public T decide(T >
  propose(value)
  r.compareAndSet(-1,i);
  return proposed[r.get()];
```



```
public class RMWConsensus
extends Consensus Protocol {
private AtomicInteger Decide winner's
   new AtomicInteger(-1) preference
 public T decide(T value)
  propose(value);
  return proposed[r.get()];
```



# The Consensus Hierarchy

```
1 Read/Write Registers, Snapshots...
2 getAndSet, getAndIncrement, ...
∞ compareAndSet,...
```



# Multiple Assignment

- Atomic k-assignment
- Solves consensus for 2k-2 threads
- Every even consensus number has an object (can be extended to odd numbers)



#### Lock-Freedom

- Lock-free:
  - in an infinite execution
  - infinitely often some method call finishes
- Pragmatic approach
- Implies no mutual exclusion





## Lock-Free vs. Wait-free

 Wait-Free: each method call takes a finite number of steps to finish

 Lock-free: infinitely often some method call finishes









- Any wait-free implementation is lock-free.
- Lock-free is the same as waitfree if the execution is finite.



# Lock-Free Implementations

- Lock-free consensus is as impossible as wait-free consensus
- All these results hold for lock-free algorithms also.



# There is More: Universality

- Consensus is universal
- From *n*-thread consensus
  - Wait-free/Lock-free
  - Linearizable
  - *n*-threaded
  - Implementation
  - Of any sequentially sp

