Fundamentals of Neural Networks

Seminar Data Mining

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Abstract—In this paper we introduce the reader to neural networks—a beautiful, biology-inspired machine learning paradigm.

Index Terms—test

I. Introduction

blabla

A. Stochastic Gradient Descent

II. GRADIENT DESCENT

A. Introduction

Gradient Descent is an algorithm used to iteratively minimize functions $f: \mathbb{R}^n \to \mathbb{R}$ of multiple values.

B. Directional derivatives

Since f is a function of multiple values, it does not suffice to.

From the definition of the directional derivative it follows that it evaluates to $\nabla f \cdot u$. A rigorous proof can be found in [1], but as an intuition, the change of f(x) in direction u can be thought of as u_1 times the change in x_1 plus u_2 times the change in x_2 plus ... which results in $\sum_{i=0}^{n} \frac{\partial f}{\partial x_i} u_i = \nabla f \cdot u$.

Following Goodfellow et al. [2], we can find the direction in which f decreases fastest using the directional derivative:

$$\min_{u} \nabla f \cdot u$$

$$= \min_{u} ||u||_{2} ||\nabla f||_{2} \cos \theta$$

. . .

Our goal is to choose a Δv that minimizes $\Delta C \approx \nabla C \cdot \Delta v$. The Cauchy–Schwarz inequality tells us that $|\nabla C \cdot \Delta v|$ is constrained by $||v|| ||\nabla C||$ where $|\nabla C \cdot \Delta v| = ||v|| ||\nabla C||$ if and only if $\Delta v = \eta \nabla C$. Since $\nabla C \cdot \eta \nabla C = \eta ||\nabla C||^2 > 0$ we can choose $\Delta v = -\eta \nabla C$ to minimize ΔC .

Gradient Descent can further be extended to include the momentum of the function [1].

Following [2], one can represent neural networks as a directed cyclical graph.

Hornik [3] has shown that.

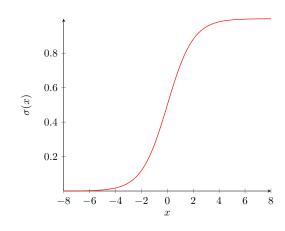
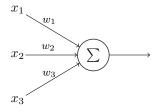


Fig. 1. The sigmoid function $\sigma(x)$



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