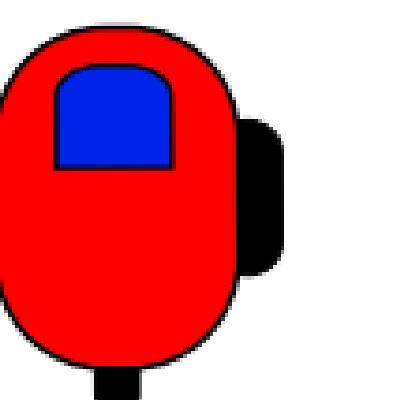


CAPTION



Real
robot
pose



Estimate
of robot
pose



Real
object
pose