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Gravity-Matter Systems in Asymptotically Safe Quantum Gravity

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Abstract

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Zusammenfassung

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Introduction

- Current understanding of Gravity
- Need of NP approach due to failure of perturbative quantization
- Some words on Wilson, Weinberg etc.
- Different approaches to Quantum Gravity (Strings, Loop QG, Causal Dynamical Triangulations etc.)
- THIS WORK: Asymptotic Safety, Matter systems etc.

The structure of this work is the following. In chapter 2 the field theoretical language and the Functional Renormalization Group (FRG) are introduced. A derivation of Wetterich's exact renormalization group equation, a. k. a. the flow equation, completes our discussion of non-perturbative approaches to quantum field theory. Chapter 3 provides the background knowledge on gravity and curved spacetimes. In chapter 4, as a first step towards quantum gravity, the Asymptotic Safety approach is motivated and the flow equation is solved within the Einstein-Hilbert truncation in a transverse-traceless spin-2 graviton approximation. Our calculation is extended in chapter 5, by taking minimally coupled scalar, fermion and gauge fields into account. In chapter 6 we critically review the background field approximation. The results are summarized and discussed in chapter 7. To conclude this work, an outlook on current progress and open questions in Asymptotic Safety research is presented.

Throughout this thesis we use natural units such that $\hbar=c\equiv 1$. Einsteins sum convention is implicitly understood: Whenever an index appears twice in a single term, summation of that term over the whole index range is implied unless stated otherwise. As usual, greek indices refer to some d-dim. spacetime coordinates, ranging from 0 to d-1, i. e. $x^{\mu}=(x^0,x^1,\cdots,x^{d-1})$. For most parts of this thesis, we work in d=4 spacetime dimensions.

Functional Methods in Quantum Field Theory

This chapter introduces a treatment of quantum field theory using functional methods. The main goal is to get familiar with the physical concepts and the notation used throughout this work and to derive the flow equation for the average effective action, introduced by Christof Wetterich in 1993 [24]. For the derivation of the flow equation we are following [8, 15].

2.1. Generating Functionals and Correlation Functions

Consider a theory setting of N real scalar fields $\varphi_a(x), a \in \{1, ..., N\}$ in d-dimensional Euclidean space. The corresponding partition sum in presence of sources $J_a(x)$ reads

$$Z[J] = \frac{1}{N} \int \mathcal{D}\varphi \, e^{-\mathcal{S}[\varphi] + J \cdot \varphi} \,. \tag{2.1}$$

The action S is specified together with an ultraviolet cutoff scale Λ , later being the momentum scale where we initialize the flow equations and some normalization factor N. In this notation, the scalar product sums over field components and integrates over all space,

$$J \cdot \varphi = \int_{x} J_{a}(x) \ \varphi_{a}(x) = \int_{p} \tilde{J}_{a}(p) \ \tilde{\varphi}_{a}(p), \tag{2.2}$$

with

$$\int_{x} = \int_{\mathbb{R}^{d}} d^{d}x \quad \text{and} \quad \int_{p} = \int_{\mathbb{R}^{d}} \frac{d^{d}p}{(2\pi)^{d}}.$$
 (2.3)

The partition sum $\mathbb{Z}[J]$ is called a *generating functional*. It directly allows us to compute field expectation values

$$\phi := \langle \varphi \rangle = \frac{1}{Z} \frac{\delta Z}{\delta J} \bigg|_{J=0} = \int \mathcal{D}\varphi \ \varphi \ e^{-\mathcal{S}[\varphi] + J \cdot \varphi}$$
 (2.4)

and higher order correlation functions

$$\langle \varphi_1 \cdots \varphi_n \rangle := \langle \varphi^n \rangle = \frac{1}{Z} \left. \frac{\delta^n Z}{\delta^n J} \right|_{J=0} = \int \mathcal{D}\varphi \left. \overbrace{\varphi_1 \cdots \varphi_n}^{:= \varphi^n} \right. e^{-\mathcal{S}[\varphi] + J \cdot \varphi}$$
 (2.5)

via functional differentiation. This means, we are basically able to compute all contributing Feynman diagrams for our theory setting, if we have knowledge of its corresponding (grand) canonical partition sum.

For a more efficient description of the theory in terms of only the *connected* correlation functions, we define the Schwinger functional W[J] as the logarithm of Z[J],

$$W[J] = \ln Z[J]. \tag{2.6}$$

It is the generating functional for the connected correlation functions. The normalization factor \mathcal{N} , introduced in (2.1) enters here as an additive constant, which drops out for all higher order correlation functions, except for the zero-point function. This term is connected to the thermodynamic quantities of the system and becomes important, when external parameters such as temperature, volume or the chemical potential are varied. For the case of quantum gravity, it is linked to the cosmological constant Λ . Nevertheless, in general we are only interested in correlation functions with $n \geq 1$ and therefore we drop this term.

Consider for example the connected two-point function $G_{ab}(x,y) = G_{\alpha\beta}^{-1}$, known as the propagator, correlating the field φ_a at spacetime point x with the field φ_b at y,

$$G_{\alpha\beta} = \frac{\delta^2 W[J]}{\delta J_{\alpha} \delta J_{\beta}} = \frac{\delta}{\delta J_{\alpha}} \left(\frac{1}{Z} \frac{\delta Z}{\delta J_{\beta}} \right)$$

$$= \frac{1}{Z} \left(\frac{\delta^2 Z}{\delta J_{\alpha} \delta J_{\beta}} \right) - \frac{1}{Z^2} \left(\frac{\delta Z}{\delta J_{\alpha}} \right) \left(\frac{\delta Z}{\delta J_{\beta}} \right)$$

$$= \langle \varphi_{\alpha} \varphi_{\beta} \rangle - \phi_{\alpha} \phi_{\beta} = \langle \varphi_{\alpha} \varphi_{\beta} \rangle_{c}.$$
(2.7)

The propagator is the key object in functional approaches to quantum field theory. It depends on the chosen background via J.

It is still possible to make our computations even more efficient, because W[J] still contains some redundant information. Connected correlation functions can be separated into so-called one-particle irreducible (1PI) and one-particle reducible ones. The 1PI correlation functions are those, whose corresponding Feynman diagrams can *not* be separated into two disconnected ones by cutting a single internal line. As an example, contributing 1PI and reducible diagrams to the connected four-point function for Yukawa theory, are depicted in figure (2.1).

The generating functional for the 1PI correlation functions, the *effective action* Γ , is obtained from the Schwinger functional via a Legendre transform,

$$\Gamma[\phi] = \sup_{I} \left\{ \int_{x} J(x)\phi(x) - W[J] \right\} = \int_{x} J_{\sup}(x)\phi(x) - W[J_{\sup}], \qquad (2.8)$$

^{1.} To save on notation, we introduce collective indices $\alpha = (x, a)$ or (q, a) in momentum space.

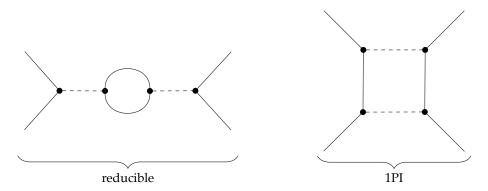


Figure 2.1.: Contributing one-particle reducible and 1PI diagrams to the four-point-function in Yukawa theory, inspired by [7].

where J_{\sup} has to be understood as a field-dependent current $J_{\sup}[\phi]$. In the following, we will drop the subscript, its meaning is implicitly understood. The quantum equation of motion derived from Γ reads

$$J(x) = \frac{\delta\Gamma[\phi]}{\delta\phi(x)}. (2.9)$$

It allows us to understand the dynamics of field expectation values, taking the effects of all quantum fluctuations into account. From a physical point of view, the effective action Γ is the quantum analogue of the classical action $\mathcal S$. The performed Legendre transform leads us to a mean field description of our theory with $\phi=\langle\varphi\rangle$ on a given background, as introduced before. The symmetries of the classical action are in general still present in the effective action.

In terms of the effective action, higher order correlation functions are again obtained by performing functional derivatives, but now w.r.t. the mean field ϕ ,

$$\Gamma^{(n)}(x_1, \dots, x_n) = \frac{\delta^n \Gamma}{\delta \phi(x_1) \cdots \delta \phi(x_n)}.$$
 (2.10)

With the definition of the effective action (2.8), we find

$$e^{-\Gamma[\phi]} = \int_{\Lambda} \mathcal{D}\varphi \exp\left(-\mathcal{S}[\phi + \varphi] + \int_{x} \frac{\delta\Gamma[\phi]}{\delta\phi(x)}\varphi(x)\right). \tag{2.11}$$

The solution of such functional integro-differential equations is highly non-trivial. To solve this problem, we want to make use of the Functional Renormalization Group. The general idea of this approach is to introduce a scale-dependent action Γ_k , interpolating between the bare, microscopic action \mathcal{S} and the full quantum effective action Γ . A more formal motivation and a derivation of the equation governing this interpolation process is presented in the next section.

2.2. Functional Renormalization Group

The Functional Renormalization Group (FRG) is a mathematical tool, allowing us to investigate the dynamics of physical systems on different energy (momentum) scales. This idea is based on a continuous version of Leo P. Kadanoffs block spin model on the lattice [11] and was developed by Kenneth G. Wilson in 1971 [25]. It aims at solving the theory by integrating successively momentum shell by momentum shell, being the reason why the path integral approach to quantum field theory provides a suitable framework. The main advantage of the FRG approach is, that no regularization or renormalization procedure has to be applied. The latter one is already implemented systematically, which secures the self-consistency of the approach. As this section is only supposed to introduce the basics of the FRG, we refer the interested reader to more complete reviews, e.g. [8, 14], particularly for applications in different areas of physics.

As a first step towards a FRG equation we need to introduce an infrared cutoff scale k in our theory, below which the modes are not integrated out. A common way to introduce such a scale is by adding a scale-dependent cutoff term ΔS_k in the definition of the partition sum (2.1) and therefore automatically also in the definition of the Schwinger functional (2.6):

$$W_k[J] = \ln Z_k[J] = \ln \int \mathcal{D}\varphi \, e^{-\mathcal{S}[\varphi] + J \cdot \varphi - \Delta \mathcal{S}_k[\varphi]} \,. \tag{2.12}$$

The physical scale k we introduced here is known as *renormalization scale* and has units of inverse length, meaning large k correspond to small distances and vice versa. The cutoff term ΔS_k is a quadratic functional depending on the field φ :

$$\Delta S_k[\varphi] = \frac{1}{2} \varphi \cdot R_k \cdot \varphi = \frac{1}{2} \int_{x,y} \varphi_\alpha R_{k,\alpha\beta} \varphi_\beta. \tag{2.13}$$

The function R_k is called regulator. It plays an important role for this formulation of quantum field theory. The regulator is chosen such that only the propagation for momentum modes with $p^2 \lesssim k^2$ is suppressed. The most important physical limits are summarized in the following:

$$R_k(p^2) \to \begin{cases} k^2 & \text{for } p \to 0\\ 0 & \text{for } p \to \infty\\ 0 & \text{for } k \to 0\\ \infty & \text{for } k \to \Lambda \end{cases}$$
 (2.14)

A convenient choice of the regulator is given by

$$R_k(p^2) = p^2 \cdot r_k(y),$$
 (2.15)

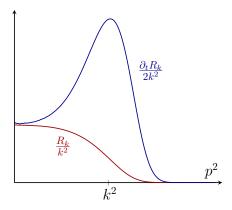


Figure 2.2.: Shape of a typical exponential regulator function $R(p^2)$ and its derivative w.r.t. the RG time t. The regulator has a finite value for momenta smaller than k^2 and therefore acts as a suppressing mass term. The peak of $\partial_t R_k$ around $k^2 = p^2$ clearly shows the implementation of Wilsons idea of shellwise momentum integration.

with $y := \frac{p^2}{k^2}$, and a dimensionless regulator shape function r_k , only depending on the dimensionless momentum ratio y. There is a plethora of different types of shape functions, but for the computations performed in this work we restrict ourselves to a class of rather simple, so-called Litim-type regulators with shape functions

$$r_k(y) = \left(\frac{1}{y} - 1\right)\theta(1 - y),\tag{2.16}$$

where θ is the Heaviside step function. This class of *sharp* regulators is a good choice for finding analytic FRG equations in simple approximations. For numerical approaches, exponential regulators such as depicted in figure (2.2) are well suited.

At this point it is quite convenient to introduce the RG time t as

$$t = \ln\left(\frac{k}{\Lambda}\right) \longrightarrow \partial_t = \frac{\partial}{\partial \ln(k/\Lambda)} = \frac{k}{\Lambda} \frac{\partial}{\partial (k/\Lambda)} = k\partial_k,$$
 (2.17)

where Λ is a fixed reference scale. Usually one chooses the ultraviolet cutoff scale, where the flow is initialized.

In this setting, (2.12) provides a good starting point for solving the theory by successively lowering the cutoff scale k infinitesimally and integrating out all momentum modes $\varphi_{p\approx k}$. This procedure can be formalized by taking a scale derivative of our scale-dependent functional (2.12):

$$\partial_{t}W_{k}[J] = -\frac{1}{2} \int \mathcal{D}\varphi \,\varphi(-p)\partial_{t}R_{k}(p)\varphi(p) \,\mathrm{e}^{-\mathcal{S}[\varphi] + J \cdot \varphi - \Delta \mathcal{S}_{k}[\varphi]}$$

$$= -\frac{1}{2} \int_{p} \partial_{t}R_{k}(p)G_{k}(p) + \partial_{t}\Delta S_{k}[\phi], \qquad (2.18)$$

where we used the definition of the connected propagator:

$$G_k = \frac{\delta^2 W_k[\phi]}{\delta \phi(x) \delta \phi(y)}.$$
 (2.19)

The *flowing* or *effective average action* Γ_k is then again defined via a modified Legendre transform, including the insertion of ΔS_k :

$$\Gamma_k[\phi] = \sup_J \left(\int_x J(x)\phi(x) - W_k[J] \right) - \Delta S_k[\phi]. \tag{2.20}$$

This yields the modified, scale-dependent quantum equation of motion:

$$J(x) = \frac{\delta \Gamma_k[\phi]}{\delta \phi(x)} + (R_k \phi)(x). \tag{2.21}$$

Compared to the scale-independent version (2.9), we find an additional, regulator dependent term, but with the properties of the regulator presented in (2.14) in mind, we see that in the limit $k \to 0$, the initial equation of motion is restored. We find

$$\frac{\delta J(x)}{\delta \phi(y)} = \frac{\delta^2 \Gamma_k[\phi]}{\delta \phi(x) \delta \phi(y)} + R_k(x, y). \tag{2.22}$$

With the help of these relations we are able to show that

$$\delta\left(x - x'\right) = \frac{\delta J(x)}{\delta J(x')} = \int_{y} \frac{\delta J(x)}{\delta \phi(y)} \frac{\delta \phi(y)}{\delta J(x')}$$

$$= \int_{y} \left(\Gamma_{k}^{(2)}[\phi] + R_{k}\right) (x, y) G_{k}\left(y - x'\right).$$
(2.23)

Here, we used (2.22) and the definition of G_k (2.19). This yields the following important identity:

$$G_k = \left(\Gamma_k^{(2)} + R_k\right)^{-1}.\tag{2.24}$$

All together, we arrive at the *flow equation* a.k.a. the *Wetterich equation* for the average effective action:

$$\partial_{t}\Gamma_{k}[\phi] = -\partial_{t}W_{k} + \int (\partial_{t}J) \phi - \partial_{t}\Delta S_{k}[\phi] = -\partial_{t}W_{k}[J] - \partial_{t}\Delta S_{k}[\phi]$$

$$\stackrel{(2.18)}{=} \frac{1}{2} \int_{p} G_{k}(p) \partial_{t}R_{k}(p)$$

$$\stackrel{(2.24)}{=} \frac{1}{2} \operatorname{STr} \left[\left(\Gamma_{k}^{(2)}[\phi] + R_{k} \right)^{-1} \partial_{t}R_{k} \right]$$

$$(2.25)$$

The supertrace STr sums over all internal indices and integrates over momentum space. For Grassmann fields, it also involves the inclusion of a minus sign. We will drop the S

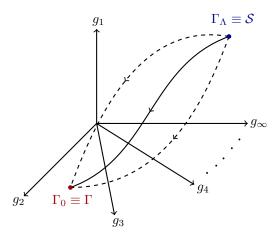


Figure 2.3.: Flow of Γ_k through infinite-dimensional theory space for different regulators, inspired by [8]. Although the trajectories in theory space, governed by the flow equation (2.25) may be different, they flow towards the same quantum effective action $\Gamma_{k\to 0} \equiv \Gamma$.

for the rest of this work, its meaning should be understood implicitly. The flow equation can be represented diagrammaticaly as a 1-loop equation:

$$\partial_t \Gamma_k[\phi] = \frac{1}{2} \sum_{i,j=1}^N \int_{p,q} \partial_t R_{k,ij}(p,q) \bigotimes_q \left[\Gamma_k^{(2)}[\phi] + R_k \right]_{ji}^{-1}(q,p). \tag{2.26}$$

The full propagator $\left[\Gamma_k^{(2)} + R_k\right]^{-1}$ is represented as usual as a single, double, dashed etc. line, dependent on the field content. The crossed circle \otimes denotes the insertion of the respective regulator or more precisely its derivative w.r.t. the RG time t. Here $\partial_t R_{k,ij}(p,q) = \partial_t R_k(p^2)(2\pi)^d \, \delta_{ij} \, \delta(p-q)$ and therefore the trace on the r.h.s. effectively sums over just one index i and integrates over one loop momentum p.

It is important to mention, that the Wetterich equation is an *exact* equation, no approximations have been made. The only modification, the implementation of ΔS_k vanishes in the limit $k \to 0$. Solutions of the flow equation correspond to trajectories in *theory space*, the space spanned by all (= infinitely many) dimensionless couplings g_{α} . The choice of the regulator has direct impact on the exact form of the trajectory. This is often referred to as *scheme dependence*. Nevertheless, for all regulators satisfying the properties (2.14) it is guaranteed, that the flow will lead to the same quantum effective action Γ . For a visualization of this idea, have a look at figure (2.3). In principle this means, that $\lim_{k\to 0} \Gamma_k \equiv \Gamma$, but in most practical cases it is unavoidable to employ truncation schemes to be able to solve the flow equation. A plethora of different truncation schemes has been developed recently, details concerning the most important schemes can be found e. g. in the reviews

about the FRG we referred to at the beginning of this section. We want to conclude this chapter with a more formal discussion of the concept of theory space, before proceeding with an introduction of the basic concepts of gravity.

2.3. Renormalization Group Flow and Theory Space

We want to use this section to formalize the concept of theory space we introduced in the last section and to discuss important characteristics of the renormalization group flow such as the beta functions and their zeros, the fixed points of the flow. For this part, we mainly follow [18].

The theory space has been defined as the space, spanned by all dimensionless couplings of the theory. To be more precisely, it consists of all (action) functionals $A:\Phi\mapsto A[\Phi]$, that are compatible with the imposed symmetries of the theory such as e.g. diffeomorphism invariance in the case of (quantum) gravity.

The flow equation (2.25) defines a vector field $\vec{\beta}$ in theory space whose integral curves are the trajectories Γ_k parametrized by the scale k. Assuming the existence of a complete set of basis functionals $\{P_{\alpha}[\cdot]\}$, we can expand Γ_k as follows:

$$\Gamma_k[\Phi, \bar{\Phi}] = \sum_{\alpha=1}^{\infty} \bar{g}_{\alpha}(k) P_{\alpha}[\Phi, \bar{\Phi}]. \tag{2.27}$$

Here, the expansion coefficients $\bar{g}_{\alpha}(k)$ are given by the generalized couplings. Inserting this ansatz into the flow equation (2.25), yields a set of infinitely many coupled differential equations for the couplings:

$$k\partial_k \bar{g}_{\alpha}(k) = \bar{\beta}_{\alpha} \left(\bar{g}_1, \bar{g}_2, \cdots; k \right), \qquad \alpha = 1, 2, \cdots$$
 (2.28)

The *beta functions* $\bar{\beta}_{\alpha}$ $(\bar{g}_1, \bar{g}_2, \dots; k)$ are the components of the vector field $\vec{\beta}$ and arise from an expansion of the trace on the r. h. s. of the flow equation in terms of the functional basis². Up to this point, we are still dealing with dimensionful couplings \bar{g} , but as mentioned earlier usually the flow equation is reexpressed in terms of *dimensionless couplings*

$$g_{\alpha} \equiv k^{-d_{\alpha}} \bar{g}_{\alpha}, \tag{2.29}$$

where d_{α} is the canonical mass dimension of the respective coupling. The *essential* couplings³ provide a set of coordinates for the theory space. This allows us to interpret the idea of renormalization theory in a new, geometrical way: We need to construct "infinetely long" trajectories Γ_k , that lie *entirely* in theory space. In this case, the couplings are prevented from diverging and we are able to define a consistent quantum field theory.

^{2.} The expansion reads: $\frac{1}{2} \operatorname{Tr} [\cdots] = \sum_{\alpha=1}^{\infty} \bar{\beta}_{\alpha} (\bar{g}_1, \bar{g}_2, \cdots; k) P_{\alpha} [\Phi, \bar{\Phi}]$ 3. Essential in this sense means, that they can not be absorbed into the fields via a rescaling.

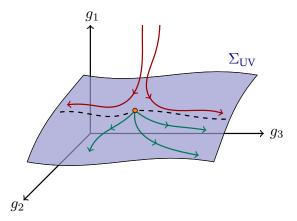


Figure 2.4.: Visualization of a fixed point g^* (orange dot) with its corresponding UV hypersurface $\Sigma_{\rm UV}$ and trajectories starting at g^* (green) in theory space. The flow points towards the IR. Trajectories starting off the surface (red) are pulled towards the FP along the irrelevant direction (here: g_3) until the IR repulsive directions g_1 and g_2 dominate and drive the flow away from g^* . This figure is inspired by [6].

A *fixed point* g^* of the flow is a zero of the vector field $\vec{\beta}$, i. e. $\beta_{\alpha}(g^*) \equiv 0 \ \forall \alpha$. The existence of such fixed points is crucial for our discussion of Asymptotic Safety as an approach to quantum gravity, based on the concepts we introduced here.

In general, one distinguishes different classes of fixed points. The *Gaussian* or *non-interacting* fixed points (GFP) are classified by $g_{\alpha}^* = 0 \ \forall \alpha$. This class of fixed points is relevant for the idea of perturbation theory, where the limit $k \to \infty$ is taken. If at least one of the couplings $g_{\alpha}^* \neq 0$, the fixed point is classified as *Non-Gaussian* or *interacting* (NGFP). The idea of Asymptotic Safety relies on the existence of such a NGFP, rendering the theory "safe" from divergencies in the ultraviolet (UV) regime⁴. An important characteristic of a fixed point is its stability or more precisely if he is *attractive* or *repulsive* for near RG trajectories. Additionally one distinguishes between infrared ($k \to 0$) and ultraviolet ($k \to \infty$) attractive (repulsive) fixed points. To analyze this behavior, the flow near a fixed point is linearized i. e.

$$\partial_t g_{\alpha}(k) = \sum_{j=1}^{\infty} B_{\alpha j} \left(g_j - g_j^* \right), \tag{2.30}$$

where we defined the *stability matrix* $\mathbf{B} = B_{\alpha j} = \partial_j \beta_\alpha(g_\alpha^*)$. The solution of the differential equation (2.30) reads:

$$g_{\alpha}(k) = g_{\alpha}^* + \sum_{j=1}^{\infty} C_j V_{\alpha}^j \left(\frac{k}{k_0}\right)^{\theta_j}.$$
 (2.31)

Here, the V^i are the eigenvectors of the stability matrix with eigenvalues θ_j a. k. a. *critical exponents*. In general, the θ_j are complex numbers. We use the real part of the critical

^{4.} E. g. in Yang-Mills theory, the concept of *Asymptotic freedom*, where the couplings tend to zero in the limit $k \to \infty$ is based on the existence of an UV attractive Gaussian fixed point, rendering the theory pertubatively renormalizable [10].

exponents to classify the coupling as *relevant* (= attractive) or *irrelevant* (= repulsive):

$$g_{\alpha}^{*}$$
 is
$$\begin{cases} \text{relevant} & \text{for } \mathfrak{Re}\left(\theta_{j}\right) > 0\\ \text{irrelevant} & \text{for } \mathfrak{Re}\left(\theta_{j}\right) < 0 \end{cases}$$
 (2.32)

Fixed points with critical exponents $\theta_j=0$ are called *marginal*. Based on this classification, it follows quite naturally to define an UV (or IR) *critical hypersurface* $\Sigma_{\rm UV}$ in theory space for a NGFP, consisting of all points that are pulled into the NGFP for increasing k. The dimension of $\Sigma_{\rm UV}$ is equal to the number of UV relevant couplings. This means, that trajectories lying on such a hypersurface are tend to flow towards the fixed point in the UV limit. To visualize this idea, a schematic sketch of such a hypersurface in a 3-dim. theory space is depicted in figure (2.4).

Curved Spacetimes and Gravity

Our current understanding of gravity is manifested in Einsteins theory of General Relativity. Different to the treatment of the other fundamental forces, all described by gauge theories and summarized in the Standard Model of Particle Physics, gravity is based on the concept of curved spacetime. This chapter summarizes some of the general concepts and notions of General Relativity, needed for a basic understanding of the subject. For most of the concepts we present here, we are following Sean Carrolls notes [1]. At the end of this chapter, we show why gravity can not be quantized in a perturbative manner, opposite to the other three fundamental forces. For this part, we follow [15].

3.1. An Introduction to Spacetime Geometry

When talking about the concept of curved spacetimes, one first needs a mathematical framework to quantify curvature and to understand how mathematical concepts such as differentiation and integration are generalized to curved spaces. The central objects in our discussion of curved spaces are differentiable manifolds, i.e. topological spaces, that are locally diffeomorphic to \mathbb{R}^n . Locally in this sense means, that we can find coordinate maps $\phi_i: M \underset{\text{open}}{\supset} U_i \to \mathbb{R}^n$, such that the image $\phi_i(U_i)$ is open in \mathbb{R}^n , for every point on M, whereas globally the manifold may have a very complicated topology. A set of such coordinate maps $\{(U_\alpha, \phi_\alpha)\}$ that covers the entire manifold and where the charts are smoothly sewed together is called an *atlas*. For overlapping charts $U_\alpha \cap U_\beta \neq \emptyset$, the maps $(\phi_\alpha \circ \phi_\beta^{-1})$, a. k. a. coordinate transformations, must be smooth and differentiable. They are directly connected to the coordinates x^μ we'll work with later on.

Further, we need to introduce additional structures, such as vectors and tensors on manifolds, since they are the objects we are interested in when it comes to the discussion of physical models. To be able to talk about vectors, one needs to associate a tangent space T_p to every point p of the manifold. The tangent space is the set of all vectors at p and has the structure of a vector space with the same dimension as M. The disjoint union of all tangent spaces on M is called the tangent bundle. To specify the concept of the tangent space we claim, that it can be identified with the space of directional derivative operators along curves $\gamma: \mathbb{R} \to M$ through p. In this case, we find a basis of T_p as the set $\{\hat{\partial}_{\mu}\}$ of directional derivatives at p. It can be shown, that the directional derivatives can be decomposed into a sum of real numbers times partial derivatives, i. e. $\frac{d}{d\lambda} = \frac{dx^{\mu}}{d\lambda} \partial_{\mu}$, where λ is the parameter of the curve γ . This allows us to represent a vector $V = V^{\mu}\partial_{\mu}$ independent of the chosen coordinates. The basis vectors in some different coordinate system $x^{\mu'}$ are

then simply related to the initial basis via $\partial_{\mu'} = \frac{\partial x^{\mu}}{\partial x^{\mu'}} \partial_{\mu}$ which yields the transformation law for vector components under general coordinate transformations,

$$V^{\mu'} = \frac{\partial x^{\mu'}}{\partial x^{\mu}} V^{\mu}. \tag{3.1}$$

Components obeying this transformation law are called *contravariant*. At this point it follows quite naturally to define the *cotangent space* T_p^* as the set of linear maps $\omega: T_p \to \mathbb{R}$. Elements of the cotangent space are called one-forms or dual vectors and similarly to the discussion of the tangent space, we find a suitable basis for T_p^* as the gradients $\{\mathrm{d}\hat{x}^\mu\}$, allowing us to represent arbitrary one-forms as $\omega = \omega_\mu \mathrm{d} x^\mu$. As before, we are interested in the transformation behavior of our basis one-forms, i. e. $\mathrm{d} x^{\mu'} = \frac{\partial x^{\mu'}}{\partial x^\mu} \mathrm{d} x^\mu$ and the dual vector components

$$\omega_{\mu'} = \frac{\partial x_{\mu}}{\partial x^{\mu'}} \omega_{\mu}. \tag{3.2}$$

This transformation behavior differs from the one found for vectors. We call components transforming as in equation (3.2) *covariant*.

Now we are able to generalize these concepts by introducing tensors T of type (k, l) as

$$T = T^{\mu_1 \cdots \mu_k}_{\nu_1 \cdots \nu_l} \partial_{\mu_1} \otimes \cdots \otimes \partial_{\mu_k} \otimes dx^{\nu_1} \otimes \cdots \otimes dx^{\nu_l}. \tag{3.3}$$

The general transformation law for tensors follows naturally as expected from equations (3.1) and (3.2),

$$T^{\mu'_1 \cdots \mu'_k}_{\nu'_1 \cdots \nu'_l} = \frac{\partial x^{\mu'_1}}{\partial x^{\mu_1}} \cdots \frac{\partial x^{\mu'_k}}{\partial x^{\mu_k}} \frac{\partial x^{\nu_1}}{\partial x^{\nu'_1}} \cdots \frac{\partial x^{\nu_l}}{\partial x^{\nu'_l}} T^{\mu_1 \cdots \mu_k}_{\nu_1 \cdots \nu_l}. \tag{3.4}$$

Having understood the basic structures and their respective behavior under coordinate transformations, we are now able to present some of the most important tensors in general relativity.

Maybe the most important object to quantify curved space is the *metric tensor* $g_{\mu\nu}^{\ 1}$ and its inverse $g^{\mu\nu}$, related via $g^{\mu\nu}g_{\nu\sigma}=\delta^{\mu}_{\ \sigma}$. The metric and its inverse can be used to raise and lower indices, e.g. $x^{\mu}=g^{\mu\nu}x_{\nu}$. Additionally we can compute path lengths and proper time via the definition of the line element

$$ds^2 = g_{\mu\nu} \mathrm{d}x^{\mu} \mathrm{d}x^{\nu}. \tag{3.5}$$

For arbitrary vector fields V and W the scalar product induced by the metric tensor reads

$$g(V,W) = g_{\mu\nu}V^{\mu}W^{\nu} = V^{\mu}W_{\mu} = g^{\mu\nu}V_{\mu}W_{\nu} = V_{\mu}W^{\mu}.$$
 (3.6)

^{1.} It is convenient to write the components $T^{\mu_1\cdots\mu_k}_{}$ when speaking about tensors T.

We will see, that the metric tensor already contains all the information on the geometrical structure of the respective manifold we need to quantify curvature. Nevertheless, we first have to think about differentiation of general tensors again.

In flat space, the partial derivative is a map from (k,l) to (k,l+1) tensor fields satisfying linearity and the Leibniz product rule. We want to generalize this concept to curved space by introducing the *covariant derivative* ∇^2 . Different to the usual partial derivative, the covariant derivative is independent on the chosen set of coordinates. Consider for example the covariant derivative of a vector field V, which can be written as a partial derivative plus some correction term due to its property to obey the Leibniz rule:

$$\nabla_{\mu}V^{\nu} = \partial_{\mu}V^{\nu} + \Gamma^{\nu}_{\ \mu\lambda}V^{\lambda}. \tag{3.7}$$

Here, the correction term is specified by the so-called *Christoffel symbols* a. k. a. *connection coefficients*. They are determined by derivatives of the metric tensor:

$$\Gamma^{\alpha}_{\ \mu\nu} = \frac{1}{2} g^{\mu\lambda} \left(\partial_{\mu} g_{\nu\lambda} + \partial_{\nu} g_{\mu\lambda} - \partial_{\lambda} g_{\mu\nu} \right)^{3}. \tag{3.8}$$

It can be shown, that the connection coefficients themselves do *not* transform like tensor components, but are constructed in a way such that the combination (3.7) does. Note, that the covariant derivative reduces to the partial when applied to scalars. With this definition of the connection, we are now finally able to introduce the remaining tensor structures needed for the understanding of the calculations presented later on in this work.

The central object in our discussion of curvature is the *Riemann tensor* $R^{\alpha}_{\beta\gamma\delta}$. It is a (1,3)-tensor given by

$$R^{\alpha}_{\beta\gamma\delta} = \partial_{\gamma}\Gamma^{\alpha}_{\beta\delta} - \partial_{\delta}\Gamma^{\alpha}_{\beta\gamma} + \Gamma^{\epsilon}_{\beta\delta}\Gamma^{\alpha}_{\epsilon\gamma} - \Gamma^{\epsilon}_{\beta\gamma}\Gamma^{\alpha}_{\epsilon\delta}. \tag{3.9}$$

It contains all the information about the curvature of the respective manifold. Another useful definition of the Riemann tensor is related to the commutator of two covariant derivatives, acting on a vector field:

$$\left[\nabla_{\mu}, \nabla_{\nu}\right] A^{\sigma} = R^{\sigma}_{\ \rho\mu\nu} A^{\rho}. \tag{3.10}$$

We are also interested in contractions of the Riemann tensor, especially the *Ricci tensor*

$$R_{\mu\nu} = R^{\alpha}_{\ \mu\alpha\nu} = g_{\alpha\beta} R^{\beta}_{\ \mu\alpha\nu} \tag{3.11}$$

^{2.} In the context of quantum field theory, the gauge covariant derivative is often written as D. Nevertheless, throughout this thesis we will use ∇ to indicate any kind of covariant derivative.

^{3.} This holds only true, if the connection is torsion free i. e. $T^{\lambda}_{\ \mu\nu} = \Gamma^{\lambda}_{\ \mu\nu} - \Gamma^{\lambda}_{\ \nu\mu} = 2\Gamma^{\lambda}_{\ [\mu\nu]} = 0$ and fullfils metric compatibility i. e. $\nabla_{\rho}g_{\mu\nu} = 0$. For the most important connection in the context of General Relativity, the Levi-Civita connection, these properties are fullfilled. The fundamental theorem of Riemannian geometry states, that for every Riemannian manifold there exists a unique Levi-Civita connection. It is determined by the Koszul formula.

and the Ricci scalar

$$\mathcal{R} = g_{\mu\nu}R^{\mu\nu} = R^{\mu}_{\ \mu}.\tag{3.12}$$

At this point, we also want to introduce the Einstein tensor, defined as

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}\mathcal{R}.$$
 (3.13)

Having introduced the setup for the calculations performed in this work, we are now ready to introduce the *Einstein-Hilbert action*, providing the starting point for an investigation of quantum gravity within the Functional Renormalization Group approach.

3.2. From Geometry to Einsteins Equations

The Einstein-Hilbert action, given by

$$S_{\rm EH} = \frac{1}{16\pi G} \int_{x} \sqrt{g} \left(\mathcal{R} - 2\Lambda \right), \tag{3.14}$$

where G is Newtons coupling and Λ is the cosmological constant, describes a minimally coupled theory of gravity, leading to a $^1/r$ gravitational potential in the non-relativistic limit. Note, that compared to the usual spacetime measure a factor of $\sqrt{g} := \sqrt{-\det g_{\mu\nu}}$ is included to preserve diffeomorphism invariance.⁴

Varying the Einstein-Hilbert action w. r. t. the inverse metric $g^{\mu\nu}$ yields Einsteins equations in absence of matter:

$$G_{\mu\nu} + \Lambda g_{\mu\nu} = 0. \tag{3.15}$$

The non-vacuum Einstein equations are obtained the same way, after the inclusion of matter in this setting by adding a matter part to the Einstein-Hilbert action:

$$S = \frac{1}{8\pi G} S_{\text{EH}} + S_{\text{matter}}.$$
 (3.16)

With the definition of the Energy-Momentum tensor $T_{\mu\nu}$, given by

$$T_{\mu\nu} = \frac{-2}{\sqrt{g}} \frac{\delta \mathcal{S}_{\text{matter}}}{\delta g^{\mu\nu}},\tag{3.17}$$

^{4.} Diffeomorphism invariance, i. e. the freedom of choosing an appropriate coordinate system, is the central symmetry in the context of General Relativity, based on the assumption, that coordinates do not exist a priori in nature, but are rather a mathematical tool used to describe it, that should not change the fundamental laws of physics.

we arrive at

$$\frac{1}{8\pi G} \left[G_{\mu\nu} + \Lambda g_{\mu\nu} \right] = T_{\mu\nu}. \tag{3.18}$$

In this form, Einsteins equations perfectly embody the direct correlation between curvature (l. h. s.) and the dynamics of the matter content of the theory (r. h. s.).

At the end of this chapter we want to emphasize the problem of perturbative non-renormalizability in the context of finding a quantum field theoretical description of gravity.

3.3. Perturbative Non-Renormalizability of Gravity

Naively, one could try to quantize gravity via the path integral formalism with a generating functional, given by $\int_{g_{\mu\nu}} \mathrm{e}^{-\mathcal{S}_{\mathrm{EH}}}$, as usual. The main problem in this approach is the lack of positivity of $\mathcal{S}_{\mathrm{EH}}$ causing problems with unitarity of the theory. In quantum gravity one usually introduces a linear split of the *full* metric $g_{\mu\nu}$, to perform expansions about a given background $\bar{g}_{\mu\nu}$, comparable to classical perturbation theory, which is based on coupling or amplitude expansions about the free Gaussian theory. The linear split reads

$$g_{\mu\nu} = \bar{g}_{\mu\nu} + \sqrt{G}h_{\mu\nu},\tag{3.19}$$

with the metric fluctuation $h_{\mu\nu}$ defined as $h_{\mu\nu}=1/\sqrt{G}\left(g_{\mu\nu}-\bar{g}_{\mu\nu}\right)$. This allows us to write the path integral in terms of the fluctuation field as

$$Z\left[J^{\mu\nu}; \overline{g}_{\mu\nu}\right] \propto \int_{h_{\mu\nu}} e^{-S_{\rm EH}\left[\overline{g}_{\mu\nu} + \sqrt{G}h_{\mu\nu}\right] + \int_{x} \sqrt{\overline{g}} J^{\mu\nu}h_{\mu\nu}}.$$
 (3.20)

Note, that the source term depends on the determinant of the background metric, otherwise the usual $J^{\mu\nu}$ derivatives would not generate the n-point functions of the fluctuation field $h_{\mu\nu}$. We will come back to this problem, which is often referred to as *background independence*, at the end of this thesis in chapter 6.

After a suitable tensor decomposition of the fluctuation field and a gauge fixing procedure à la Faddeev-Popov⁵, we are left with the gauge fixed Einstein-Hilbert action

$$S_{\text{grav}}[\bar{g}, \Phi] = S_{\text{EH}}[g] + S_{\text{gf}}[\bar{g}, h] + S_{\text{gh}}[\bar{g}, \Phi]. \tag{3.21}$$

^{5.} The functional quantization of gauge theories requires a gauge fixing procedure due to redundancies in the path integral measure. The idea of Faddeev and Popov is to represent the gauge fixing condition, which is implemented in the functional integral, as an additional functional integral over a set of Grassmann fields c and \bar{c} , known as Faddeev-Popov ghosts. Even though they are anticommuting Grassmann fields, they transform as scalars under Lorentz transformations. They also violate spin statistics. Nevertheless, they can be treated as additional particles in the computation of Feynman diagrams. For a detailed discussion, see e. g. ch. 16 in [17] or sec. 5.2 in [15].

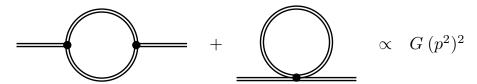


Figure 3.1.: Vacuum polarization diagrams up to 1-loop order. The double lines represent the graviton propagator.

Here the pure gravity multi-field $\Phi = (h_{\mu\nu}, c_{\mu}, \bar{c}_{\mu})$ was introduced. All together, this yields the gauge-fixed path integral representation of quantum gravity:

$$Z[J;\bar{g}] = \int_{\Phi} e^{-S_{\text{grav}}\left[\bar{g}_{\mu\nu},\Phi\right] + \int_{x} \sqrt{\bar{g}} J \cdot \Phi}.$$
 (3.22)

An analysis of the canonical momentum dimensions of the essential couplings of this theory, G and Λ results in:

$$[G] = \left[d^d x \sqrt{g} \, \mathcal{R} \right] = 2 - d, \qquad [\Lambda] = 2. \tag{3.23}$$

This implies, that the Newton coupling has a negative mass dimension in d=4 spacetime dimensions. To investigate the consequences of this, one can consider the grade of divergence $\Lambda^{\delta(\gamma)}$ for a general graph γ with E external lines, I internal propagators and L loops. Here, Λ is a UV cutoff for the momentum integrals and $\delta(\gamma)$ is the index of the graph,

$$\delta(\gamma) = dL - 2\left(I - \sum_{n=3}^{\infty} \nu_n\right),\tag{3.24}$$

where the ν_n represent n-graviton vertices. After expressing the number of loops in terms of the internal lines and the n-graviton vertices and restricting ourselves to graphs satisfying $E+2I=\sum_{n=3}^{\infty}\nu_n$, we find

$$\delta(\gamma) = d - \frac{d-2}{2}E + \sum_{n=3}^{\infty} v_n \delta(v_n), \qquad (3.25)$$

where $\delta(v_n) = \frac{1}{2}(n-2)(d-2)$. After fixing the number of external lines, e.g. to E=2, representing the case of vacuum polarizatio as depicted in figure (3.1), one is now able to investigate the grade of divergence for diagrams of different loop orders. t'Hooft and Veltman proved that the theory is renormalizable up to 1-loop order [21], but already at 2-loop order, Goroff and Sagnotti showed, that non-vanishing counterterms are generated [9]. In general, this is interpreted as the failure of perturbative quantization of gravity due to the negative mass dimension of the Newton coupling. This leads us to our discussion of Asymptotic Safety as a non-perturbative approach based on the functional renormalization group methods we presented in the last chapter.

Chapter 4.

Functional Renormalization and Quantum Gravity

In this chapter, we

4.1. Asymptotic Safety

• Taking the UV limit ..

4.2. Einstein-Hilbert Truncation

We want to solve the Flow equation ()approximately. All terms that are invariant under the imposed symmetry, i. e. invariant under diffeomorphism transformations need to be taken into account.

Easiest truncation takes only the scalar curvature \mathcal{R} and the cosmological constant Λ into account (No higher order terms ...) and was performed by Martin Reuter in 1993 [20].

This full truncation reads

$$\Gamma_k = 2\kappa^2 Z_k \int_x \sqrt{g} \left[-\mathcal{R} + 2\Lambda_k \right] + \mathcal{S}_{gf} + \mathcal{S}_{gh}. \tag{4.1}$$

with

$$\kappa^2 = \frac{1}{32\pi G}, \qquad G_k = GZ_k^{-1}$$
(4.2)

anomalous dimension:

$$\eta_g = -\frac{\partial_t Z_k}{Z_k} = -\partial_t \ln Z_k$$

dimensionless renormalized cosmological constant:

$$\lambda_k = \Lambda_k k^{-2}$$

dimensionless renormalized cosmological constant:

$$g_k = G_k k^{d-2} = \frac{Gk^{d-2}}{Z_k}$$

corresponding beta function:

$$\beta_g = \partial_t g_k = (d - 2 + \eta_g) g_k \tag{4.3}$$

maximally symmetric space:

$$\bar{\mathcal{R}}_{\mu\nu} = \frac{1}{d} \, \bar{g}_{\mu\nu} \bar{\mathcal{R}} \tag{4.4}$$

$$\bar{\mathcal{R}}_{\mu\nu\rho\sigma} = \frac{1}{d(d-1)} \left(\bar{g}_{\mu\rho} \bar{g}_{\nu\sigma} - \bar{g}_{\mu\sigma} \bar{g}_{\nu\rho} \right) \bar{\mathcal{R}}$$
(4.5)

suitable tensor basis:

As a first approximation, we only take the contribution from the spin-two graviton mode $h_{\mu\nu}^{\rm TT}$ into account. This is motivated by the fact, that this mode carries the the most degrees of freedom.

In this setting, we want to solve the Wetterich equation (2.25) by computing the l.h.s. and the r.h.s. separately and extract the β -functions for the Newton coupling g_k and the cosmological constant λ_k by a comparison of all terms of order $\sim \sqrt{g}$ and $\sim \sqrt{g} \mathcal{R}$.

In our spin-two graviton mode approximation, we don't have to deal with the gauge-fixing and ghost parts ocuring in the effective action. The simplified version of equation (4.1) reads

$$\Gamma_{k,h^{\text{TT}}} = 2\kappa^2 Z_k \int_x \sqrt{g} \left[-\mathcal{R} + 2\Lambda_k \right]. \tag{4.6}$$

We start by computing the transverse-traceless graviton two-point function

$$\Gamma_{h^{\text{TT}}h^{\text{TT}}}^{(2)} = \frac{Z_k}{32\pi} \left(\bar{\Delta} - 2\Lambda_k + \frac{2}{3}\bar{\mathcal{R}} \right). \tag{4.7}$$

Using a regulator of the form

$$R_k = \left. \Gamma_{h^{\text{TT}} h^{\text{TT}}}^{(2)} \right|_{\Lambda_k = \bar{\mathcal{R}} = 0} \cdot r_k \left(\frac{\bar{\Delta}}{k^2} \right) = \frac{Z_k}{32\pi} \bar{\Delta} \left(\frac{k^2}{\bar{\Delta}} - 1 \right) \theta \left(1 - \frac{\bar{\Delta}}{k^2} \right),$$

with a Litim-type cutoff

$$r_k(y) = \left(\frac{1}{y} - 1\right)\Theta(1 - y),\tag{4.8}$$

as discussed in chapter (2), we are directly able to compute the l.h.s. of the Wetterich equation, i.e. the scale derivative of the effective average action:

$$\partial_t \Gamma_{k,h^{\text{TT}}} = 2\kappa^2 Z_k \int_x \sqrt{g} \left\{ \eta_g \mathcal{R} + 2 \left(k^2 (\partial_t \lambda_k) + \Lambda_k (2 - \eta_g) \right) \right\}$$
(4.9)

One can extract the β -function for the Newton coupling without performing the analysis of the Wetterich equation, i. e.

$$\beta_g = \partial_t g_k = \partial_t \left(\frac{G \cdot k^2}{Z_k} \right) = g_k \left(2 + \eta_g \right). \tag{4.10}$$

The computation of the r.h.s. of the flow equation is more complicated because it involves the computation of a trace of a function depending on the Laplacian on a curved background. We can use heat-kernel techniques to solve such equations. Heat-kernel computations are based on a curvature expansion in powers of the curvature scaler \mathcal{R} . For more details, have a look at the appendix (A.2). As a first step, we simplify the trace expression as much as possible.

$$\operatorname{Tr}\left[\frac{1}{\Gamma_{k}^{(2)}+R_{k}}\partial_{t}R_{k}\right] = \operatorname{Tr}\left[\frac{\partial_{t}\left(\frac{Z_{k}}{32\pi}\bar{\Delta}\right)r_{k}}{\left(\frac{Z_{k}}{32\pi}\right)\left(\bar{\Delta}-2\Lambda_{k}+\frac{2}{3}\bar{\mathcal{R}}\right)+\left(\frac{Z_{k}}{32\pi}\bar{\Delta}\right)r_{k}}\right]$$

$$=\operatorname{Tr}\left[\frac{\bar{\Delta}\left(\partial_{t}r_{k}-\eta_{g}r_{k}\right)}{\bar{\Delta}(1+r_{k})-2\Lambda_{k}+\frac{2}{3}\bar{\mathcal{R}}}\right]$$
(4.11)

We expand this expression around vanishing curvature and get

$$\operatorname{Tr}\left[\frac{1}{\Gamma_k^{(2)} + R_k} \partial_t R_k\right] = \operatorname{Tr}\left[\frac{\bar{\Delta}(\partial_t r_k - \eta_g r_k)}{\bar{\Delta}(1 + r_k) - 2\Lambda_k}\right] - \frac{2}{3}\bar{\mathcal{R}}\operatorname{Tr}\left[\frac{\bar{\Delta}(\partial_t r_k - \eta_g r_k)}{\left(\bar{\Delta}(1 + r_k) - 2\Lambda_k\right)^2}\right] + \mathcal{O}(\mathcal{R}^2) \quad (4.12)$$

Now we are able to evaluate these two terms separately using heat-kernel techniques. One finds for the first term

$$\operatorname{Tr}\left[\frac{\bar{\Delta}\left(\partial_{t}r_{k}-\eta_{g}r_{k}\right)}{\bar{\Delta}(1+r_{k})-2\Lambda_{k}}\right] = \frac{1}{(4\pi)^{2}} \int_{x} \sqrt{g} \left[5\Phi_{2}^{1}(-2\Lambda_{k}) - \frac{5}{6}\bar{\mathcal{R}}\Phi_{1}^{1}(-2\Lambda_{k})\right],\tag{4.13}$$

with the threshold functions

$$\Phi_n^p(\omega) = \frac{1}{\Gamma(n)} \int_0^\infty dz \ z^{n-1} \frac{z(-2zr_k(z) - \eta_g r_k(z))}{(z(1 + r_k(z)) + \omega)^p}.$$
 (4.14)

Analogously, the second term in our expansion reads

$$-\frac{2}{3}\bar{\mathcal{R}}\operatorname{Tr}\left[\frac{\bar{\Delta}\left(\partial_{t}r_{k}-\eta_{g}r_{k}\right)}{\left(\bar{\Delta}(1+r_{k})-2\Lambda_{k}\right)^{2}}\right] = -\frac{10}{3}\frac{\bar{\mathcal{R}}}{(4\pi)^{2}}\int_{x}\sqrt{g}\frac{1-\frac{\eta_{g}}{6}}{(1-2\lambda_{k})^{2}}.$$
(4.15)

For the cosmological constant, comparing the $\int \sqrt{g}$ terms yields

$$\beta_{\lambda} = \partial_t \lambda_k = -4\lambda_k + \frac{\lambda_k}{g_k} \partial_t g_k + \frac{5}{4\pi} g_k \frac{1 - \frac{\eta_g}{6}}{1 - 2\lambda_k},\tag{4.16}$$

where the anomalous dimension η_g is determined by comparing the $\int \sqrt{g} \mathcal{R}$ terms:

$$\eta_g = -\frac{5}{3\pi} \left(\frac{1 - \frac{\eta_g}{4}}{1 - 2\lambda_k} + 2 \frac{1 - \frac{\eta_g}{6}}{(1 - 2\lambda_k)^2} \right). \tag{4.17}$$

The solution of this system of coupled differential equations is evaluated using Python3 and Wolfram Mathematica. We arrive at the following fixed point values for the Newton coupling and the cosmological constant:

$$(g_k^*, \lambda_k^*) = (0.86, 0.18).$$
 (4.18)

The corresponding critical exponents, i.e. minus the eigenvalues of the stability matrix evaluated at the fixed point, are given by the complex conjugated pair

$$\theta_{1,2} = 2.9 \pm 2.6i. \tag{4.19}$$

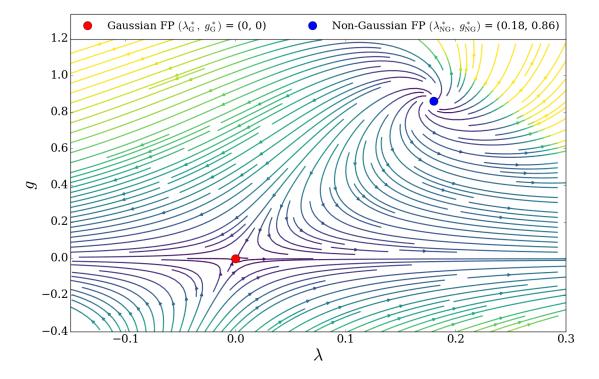


Figure 4.1.: RG flow diagram for the Einstein-Hilbert truncation in TT approximation as computed in this work. The flow points towards the infrared.

Asymptotic Safety of Gravity-Matter Systems

The calculation in $h^{\rm TT}$ approximation in the last chapter already allowed us to investigate the characteristic fixed point structure of the Einstein-Hilbert truncation. Nevertheless, in this part of the thesis, where the impact of minimally coupled matter fields is analyzed, we want to work with the full result, including also the vector and scalar modes arising after the York decomposition (??) of the fluctuation field. The gauge conditions and the results for the full solution are taken from [15].

We have to take care of an additional gauge fixing term

$$S_{\rm gf} = \frac{1}{2\alpha} \int_x \sqrt{\bar{g}} \ \bar{g}^{\mu\nu} F_{\mu} F_{\nu}, \tag{5.1}$$

with a gauge fixing parameter α and a De-Donder-type gauge condition given by

$$F_{\mu} = \bar{\nabla}^{\nu} h_{\mu\nu} - \frac{1+\beta}{4} \bar{\nabla}_{\mu} h^{\nu}_{\nu}. \tag{5.2}$$

We also have to include a ghost term $\mathcal{S}_{\mathrm{gh}}$ arising from the Faddeev-Popov procedure:

$$S_{\rm gh} = \int_x \sqrt{\bar{g}} \; \bar{g}^{\mu\mu'} \bar{g}^{\nu\nu'} \bar{c}_{\mu'} \mathcal{M}_{\mu\nu} c_{\nu'}. \tag{5.3}$$

The Faddeev-Popov operator $\mathcal{M}_{\mu\nu}(\bar{g},h)$ reads

$$\mathcal{M}_{\mu\nu} = \bar{\nabla}^{\rho} (g_{\mu\nu} \nabla_{\rho} + g_{\rho\nu} \nabla_{\mu}) - \bar{\nabla}_{\mu} \nabla_{\nu}. \tag{5.4}$$

If we choose the gauge parameters such that $\alpha=\beta\equiv 0$, we are able to reduce the dynamical degrees of freedom to two, namely the transverse-traceless mode $h^{\rm TT}$ and the trace mode $h^{\rm Tr}$. This choice allows us to simplify the full graviton propagator a lot. We are left with:

$$G_{hh} = \left[\frac{1}{\Gamma^{(2)} + R_k}\right]_{hh} = \frac{32\pi}{Z_h} \begin{pmatrix} \frac{1}{\bar{\Delta}[1+r_k] + -2\Lambda_3^2 \mathcal{R}} & 0 & 0 & 0\\ 0 & 0 & 0 & 0\\ 0 & 0 & \frac{-\frac{8}{3}}{\bar{\Delta}[1+r_k] - \frac{4}{3}\Lambda} & 0\\ 0 & 0 & 0 & 0 \end{pmatrix}$$
(5.5)

For this calculation, the regularized 2-point-function has been determined using a regulator of the form

$$\Gamma_k^{(2)} + R_k = \Gamma_k^{(2)} \left(\Delta \to \Delta \left[1 + r_k(x) \right] \right), \tag{5.6}$$

where the shape function r_k is again of Litim-type (4.8).

The inclusion of matter in this theory setting is in principle straightforward. We extend our truncation (4.1) by including an additional matter term:

$$\Gamma_k = \Gamma_{\rm EH} + S_{\rm gf} + S_{\rm gh} + \Gamma_{\rm matter},$$
(5.7)

where Γ_{matter} consists of scalar, fermion and gauge field contributions, denoted with S_S , S_D and S_V respectively:

$$\Gamma_{\text{matter}} = \mathcal{S}_S + \mathcal{S}_D + \mathcal{S}_V. \tag{5.8}$$

The different actions will be specified later on, every matter type will be treated separately. For conventions regarding the choice of the respective regulators and the general structure of this calculation, we are following [5].

In this truncation we have two essential couplings, G and Λ and five inessential wave function renormalizations Z_{Ψ} with $\Psi=(h,c,S,D,V)$. As before, the wave function renormalizations Z_{Ψ} do not enter the beta functions for G and Λ directly, but are still present in a non-trivial way via the anomalous dimension η_{Ψ} , defined as

$$\eta_{\Psi} = -\partial_t \ln Z_{\Psi}. \tag{5.9}$$

For the scalar and gauge field regulators we choose

$$R_{k,S/V}(z) = Z_{S/V} \cdot \mathbb{1}_{S/V} \cdot \tilde{\Delta} \cdot r_k \left(\frac{\tilde{\Delta}}{k^2}\right), \tag{5.10}$$

where $\tilde{\Delta} = -\nabla^2 + \mathbf{E}_{\Psi}$ is a modified Laplacian², occurring as kinetic operator in the different matter field actions. The regulator choice for the Dirac fermions is slightly different, details are discussed in the respective subsection. Nevertheless, we already present the values of \mathbf{E}_{Ψ} for all three kinetic operators:

$$\mathbf{E}_{\Psi} = \begin{cases} 0 & \text{for } \Psi = S \\ \frac{\mathcal{R}}{4} & \text{for } \Psi = D \\ R^{\mu}_{\nu} & \text{for } \Psi = V. \end{cases}$$
 (5.11)

The Litim-type shape function r_k is in this case the same as the one defined in equation (4.8), now as a function of the modified Laplacian $\tilde{\Delta}$.

^{1.} Inessential in this sense means, that they can be eliminated by field rescalings.

^{2.} A more detailed discussion on how these modified Laplacians effect the values of the heat-kernel coefficients is presented in appendix A.

$$\partial_t \Gamma_k[\bar{g},0] = \frac{1}{2} \left(\begin{array}{c} \otimes \\ \\ \end{array} \right) - \left(\begin{array}{c} \otimes \\ \end{array} \right) - \left(\begin{array}{c} \otimes \\ \end{array} \right) - \left(\begin{array}{c} \otimes \\ \end{array} \right) - \left(\begin{array}{c}$$

Figure 5.1.: Flow equation (5.12) for the average effective action Γ_k including different matter contributions in diagrammatic representation. The double, dotted, dashed, solid, wiggly and wiggly dotted lines correspond to the graviton, Non-Abelian ghost, scalar, fermion, gauge field and Abelian ghost propagators, respectively. The crossed circles denote the insertion of the respective regulator.

5.1. Matter Contributions in Background Field Approximation

After having introduced the setup for the following calculation, we are now able to determine the different contributions from the matter fields step by step, by evaluating the functional traces occurring on the r.h.s. of the flow equation separately. For the matter configuration in our setting the flow equation reads

$$\partial_{t}\Gamma_{k} = \frac{1}{2}\operatorname{Tr}\left[\left(\Gamma_{k}^{(2)} + R_{k}\right)^{-1}\partial_{t}R_{k}\right]_{hh} - \operatorname{Tr}\left[\left(\Gamma_{k}^{(2)} + R_{k}\right)^{-1}\partial_{t}R_{k}\right]_{\bar{c}c}$$

$$+\frac{1}{2}\operatorname{Tr}\left[\left(\Gamma_{k}^{(2)} + R_{k}\right)^{-1}\partial_{t}R_{k}\right]_{\phi\phi} - \operatorname{Tr}\left[\left(\Gamma_{k}^{(2)} + R_{k}\right)^{-1}\partial_{t}R_{k}\right]_{\bar{\psi}\psi}$$

$$+\frac{1}{2}\operatorname{Tr}\left[\left(\Gamma_{k}^{(2)} + R_{k}\right)^{-1}\partial_{t}R_{k}\right]_{AA} - \operatorname{Tr}\left[\left(\Gamma_{k}^{(2)} + R_{k}\right)^{-1}\partial_{t}R_{k}\right]_{\bar{c}C}$$

$$(5.12)$$

In figure (5.1), a digrammatical representation of the flow equation (5.12) is depicted.

5.1.1. Scalar fields

The action for N_S scalar fields, minimally coupled to gravity reads

$$S_{S} = \frac{Z_{S}}{2} \int_{x} \sqrt{g} g^{\mu\nu} \sum_{i=1}^{N_{S}} \partial_{\mu} \phi^{i} \partial_{\nu} \phi^{i}$$

$$= \frac{Z_{S}}{2} \int_{x} \sqrt{\bar{g}} \bar{g}^{\mu\nu} \sum_{i=1}^{N_{S}} \partial_{\mu} \phi^{i} \partial_{\nu} \phi^{i} + \mathcal{O}(h)$$

$$= \frac{Z_{S}}{2} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{S}} \phi^{i} \left(-\bar{\nabla}^{2}\right) \phi^{i} + \mathcal{O}(h).$$
(5.13)

For our computation, we expand the action on some background $\bar{g}_{\mu\nu}$ and drop all contributions of $\mathcal{O}(h)$. In the last step, we use integration by parts and assume vanishing boundary terms. Since $\mathbf{E}=0$ for scalars, we use the initial definition of the Laplacian

 $\bar{\Delta}=-\bar{\nabla}^2$ for further calculations. These simple manipulations directly allow us to read off the corresponding two-point function

$$\Gamma_{\phi\phi}^{(2)} = \frac{\delta^2 S_S}{\delta \phi^i \ \delta \phi^j} = Z_S \cdot \bar{\Delta} \cdot \mathbb{1}_S + \mathcal{O}(h), \tag{5.14}$$

where \mathbb{I}_S has to be understood as the identity in field space. Using the regulator defined in (5.10), we find the regularized two-point-function as

$$\Gamma_{k,\phi\phi}^{(2)} = \left[\Gamma_{\phi\phi}^{(2)} + R_{k,S}\right] = Z_S \cdot \bar{\Delta} \cdot \mathbb{1}_S \left(1 + r_k \left(\frac{\bar{\Delta}}{k^2}\right)\right). \tag{5.15}$$

This expression is already diagonal in field space, meaning we are directly able to invert it to obtain the propagator. Together with the scale derivative of the regulator

$$\partial_t R_{k,S} = Z_S \cdot \mathbb{1}_S \cdot \bar{\Delta} \left(\partial_t r_k - \eta_S r_k \right), \tag{5.16}$$

we can start to evaluate the r. h. s. of the flow equation:

$$\frac{1}{2}\operatorname{Tr}\left[\left(\Gamma_{k,\phi\phi}^{(2)}\right)^{-1}\partial_{t}R_{k,S}\right] = \frac{1}{2}\operatorname{Tr}\left[\frac{Z_{S}\cdot\bar{\Delta}\left(\partial_{t}r_{k}-\eta_{s}r_{k}\right)}{Z_{S}\cdot\bar{\Delta}\left(1+r_{k}\right)}\mathbb{1}_{S}\right]$$

$$= \frac{N_{S}}{2}\operatorname{Tr}\left[\frac{\bar{\Delta}\left(\partial_{t}r_{k}-\eta_{s}r_{k}\right)}{\bar{\Delta}\left(1+r_{k}\right)}\right].$$
(5.17)

Here, we already performed the trace operation on the internal indices, leading to an overall factor of N_S . The functional trace is again evaluated using heat-kernel techniques.

$$\frac{N_S}{2} \operatorname{Tr} \left[\frac{\bar{\Delta} \left(\partial_t r_k - \eta_s r_k \right)}{\bar{\Delta} \left(1 + r_k \right)} \right] = \frac{N_S}{2} \frac{1}{(4\pi^2)} \left[\int_x \sqrt{\bar{g}} \, \Phi_2^1(0) + \frac{1}{6} \int_x \sqrt{\bar{g}} \, \bar{\mathcal{R}} \, \Phi_1^1(0) \right]
= \frac{N_S}{2} \frac{1}{(4\pi)^2} \int_x \sqrt{\bar{g}} \left[\left(1 - \frac{\eta_S}{6} \right) + \frac{\bar{\mathcal{R}}}{3} \left(1 - \frac{\eta_S}{6} \right) \right].$$
(5.18)

5.1.2. Fermionic fields

For the fermionic contribution, we proceed slightly different. First, we present the action for N_D minimally coupled Dirac fermions:

$$S_D = iZ_D \int_x \sqrt{g} \sum_{i=1}^{N_D} \bar{\psi}^i \nabla \psi^i$$

$$= iZ_D \int_x \sqrt{\bar{g}} \sum_{i=1}^{N_D} \bar{\psi}^i \bar{\nabla} \psi^i + \mathcal{O}(h).$$
(5.19)

The Dirac operator ∇ satisfies $\left(i\nabla\right)^2=-\nabla^2+\frac{\mathcal{R}}{4}=:\Delta_{\binom{1/2}{2}}$. The notation for the conjugated field $\bar{\psi}=\psi^\dagger\mathfrak{h}^3$ should not be confused with the bar referring to the background field. As usual, the slashed notation implies contraction with gamma matrices⁴, i. e. $\nabla=\gamma^\mu\nabla_\mu$. In principle, this allows us to read off the fermion two-point function

$$\Gamma_{\bar{\psi}\psi}^{(2)} = \frac{\delta^2 \mathcal{S}_D}{\delta \psi^i \ \delta \bar{\psi}^j} = Z_D \cdot \left(i \bar{\nabla} \right) \cdot \mathbb{1}_D + \mathcal{O}(h). \tag{5.20}$$

For the regularized two-point-function, we choose the following form:

$$\Gamma_{k,\bar{\psi}\psi}^{(2)} = \left[\Gamma_{\bar{\psi}\psi}^{(2)} + R_{k,D}\right] = \left(1 + r_{k,D}\left(\frac{\bar{\Delta}_{\left(1/2\right)}}{k^2}\right)\right) \cdot Z_D \cdot \left(i\bar{\nabla}\right) \cdot \mathbb{1}_D. \tag{5.21}$$

This allows to determine the expression for $R_{k,D}$ as the difference between the regularized and the initial two-point function:

$$R_{k,D} = \Gamma_{k,\bar{\psi}\psi}^{(2)} - \Gamma_{\bar{\psi}\psi}^{(2)}$$

$$= Z_D \cdot (i\bar{\nabla}) \cdot r_{k,D} \cdot \mathbb{1}_D.$$
(5.22)

When computing fermion propagators in other theory settings, it follows quite naturally to consider the Dirac dispersion as the "square root" of the scalar Klein-Gordon dispersion. For a more detailed discussion of this idea in the context of Fermi-Bose mixtures, we refer to chapter 2 of [15] or in the context of gravity-matter systems in quantum gravity to the appendix of [4].

This assumption allows us to express the shape function for the fermions as a function of the scalar shape function:

$$(1 + r_{k,D})^2 = 1 + r_{k,S} \longrightarrow r_{k,D} = \sqrt{1 + r_{k,S}} - 1$$
 (5.23)

Inserting this relation into the expression for the two-point function (5.21) and the regulator (5.22), we arrive at:

$$\Gamma_{k,\bar{\psi}\psi}^{(2)} = \sqrt{1 + r_{k,S}} \cdot Z_D \cdot \left(i\bar{\nabla}\right) \cdot \mathbb{1}_D$$

$$R_{k,D} = \left(\sqrt{1 + r_{k,S}} - 1\right) \cdot Z_D \cdot \left(i\bar{\nabla}\right) \cdot \mathbb{1}_D.$$
(5.24)

^{3.} The spin metric \mathfrak{h} satisfies $|\det \mathfrak{h}| = 1$ and $\mathfrak{h}^{-1} = -\mathfrak{h}$.

^{4.} In the discussion of Dirac fermions, the gamma matrices $\left\{\gamma^0,\gamma^1,\gamma^2,\gamma^3\right\}$ are a set of complex valued matrices, that constitute an irreducible representation of the Clifford algebra, defined by the anticommutation relation $\left\{\gamma_{\mu},\gamma_{\nu}\right\}=2g_{\mu\nu}\mathbb{1}_{d\gamma\times d\gamma}$, with $d_{\gamma}=2^{\left[d/2\right]}$. A more formal treatment of fermions in curved spacetimes is presented in [12].

To invert the Dirac operator $(i \nabla)$, we use:

$$\frac{1}{\left(i\nabla\right)} = \frac{1}{\left(i\nabla\right)} \times \frac{\left(i\nabla\right)}{\left(i\nabla\right)} = \frac{\left(i\nabla\right)}{\Delta_{\left(1/2\right)}} \tag{5.25}$$

and therefore the full fermion propagator reads

$$\left(\Gamma_{k,\bar{\psi}\psi}^{(2)}\right)^{-1} = \frac{\left(i\bar{\nabla}\right)}{Z_D \cdot \bar{\Delta}_{\left(1/2\right)}\sqrt{1 + r_{k,S}}}.$$
(5.26)

For the scale derivative of the regulator we find

$$\partial_{t}R_{k,D} = Z_{D} \cdot \left(i\bar{\nabla}\right) \cdot \mathbb{1}_{D} \left(\partial_{t}r_{k,D} - \eta_{D}r_{k,D}\right)$$

$$= Z_{D} \cdot \left(i\bar{\nabla}\right) \cdot \mathbb{1}_{D} \left(\frac{1}{2\sqrt{1 + r_{k,S}}} - \eta_{D} \left(\sqrt{1 + r_{k,S}} - 1\right)\right)$$
(5.27)

Since we have to deal with the modified spin- $\frac{1}{2}$ Laplacian $\Delta_{\binom{1}{2}}$, we have to be careful with the heat-kernel coefficients. Using equation (A.28), we find:

$$\operatorname{Tr} \mathbf{b}_{0} = 4$$

$$\operatorname{Tr} \mathbf{b}_{2} = \frac{5}{12} \bar{\mathcal{R}}.$$
(5.28)

All together, we can start to evaluate the r. h. s. of the flow equation:

$$-\operatorname{Tr}\left[\left(\Gamma_{k,\bar{\psi}\psi}^{(2)}\right)^{-1}\partial_{t}R_{k,D}\right] = -\operatorname{Tr}\left[\frac{Z_{D}\cdot\bar{\Delta}_{\left(1/2\right)}\cdot\left(\frac{1}{2\sqrt{1+r_{k,S}}} - \eta_{D}\left(\sqrt{1+r_{k,S}} - 1\right)\right)}{Z_{D}\cdot\bar{\Delta}_{\left(1/2\right)}\sqrt{1+r_{k,S}}}\mathbb{1}_{D}\right]$$

$$= -N_{D}\operatorname{Tr}\left[\cdots\right].$$
(5.29)

5.1.3. Gauge fields

The structure of the gauge field contribution is more complex than for the other fields. This is due to the fact, that we have to employ a gauge fixing procedure w.r.t. the background field $\bar{g}_{\mu\nu}$. This ensures gauge invariance w.r.t. background gauge transforma-

tions. The action for N_V gauge fields, minimally coupled to gravity reads

$$S_{V} = \frac{Z_{V}}{4} \int_{x} \sqrt{g} \sum_{i=1}^{N_{V}} g^{\mu\nu} g^{\kappa\lambda} F_{\mu\kappa}^{i} F_{\nu\lambda}^{i} + \frac{Z_{V}}{2\xi} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} \left(\bar{g}^{\mu\nu} \bar{\nabla}_{\mu} A_{\nu}^{i} \right)^{2} + \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} \bar{C}_{i} (-\bar{\nabla}^{2}) C_{i},$$
(5.30)

where the second term is the gauge fixing term with gauge parameter ξ and the third term is the Abelian ghost term. Since the two-point function is obtained from a functional derivative w. r. t. the fields A^i , we have to evaluate the ghost-term separately. We start by manipulating the first term:

$$\frac{Z_{V}}{4} \int_{x} \sqrt{g} \sum_{i=1}^{N_{V}} g^{\mu\nu} g^{\kappa\lambda} F_{\mu\kappa}^{i} F_{\nu\lambda}^{i} = \frac{Z_{V}}{4} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} \bar{g}^{\mu\nu} \bar{g}^{\kappa\lambda} \bar{F}_{\mu\kappa}^{i} \bar{F}_{\nu\lambda}^{i} + \mathcal{O}(h)$$

$$\stackrel{\text{(B.2)}}{=} \frac{Z_{V}}{2} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} A_{\lambda}^{i} \left[\bar{\nabla}^{\mu} \bar{\nabla}^{\lambda} - \bar{g}^{\mu\lambda} \bar{\nabla}^{2} \right] A_{\mu}^{i} + \mathcal{O}(h).$$
(5.31)

The steps we skipped can be found in appendix B. For the gauge fixing term we find:

$$\frac{Z_{V}}{2\xi} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} \left(\bar{g}^{\mu\nu} \bar{\nabla}_{\mu} A_{\nu}^{i} \right)^{2} = \frac{Z_{V}}{2\xi} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} \bar{g}^{\mu\nu} \bar{\nabla}_{\mu} A_{\nu}^{i} g^{\kappa\lambda} \bar{\nabla}_{\kappa} A_{\lambda}^{i}$$

$$= \frac{Z_{V}}{2\xi} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} A_{\lambda}^{i} \left[-\bar{\nabla}^{\lambda} \bar{\nabla}^{\mu} \right] A_{\mu}^{i}.$$
(5.32)

In the last step, we integrated by parts and assumed vanishing boundary terms. This allows us to write

$$S_{V} = \frac{Z_{V}}{2} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} A_{\lambda}^{i} \left[-\bar{g}^{\mu\lambda} \bar{\nabla}^{2} + \bar{\nabla}^{\mu} \bar{\nabla}^{\lambda} - \frac{1}{\xi} \bar{\nabla}^{\lambda} \bar{\nabla}^{\mu} \right] A_{\mu}^{i} + \text{ghost term}$$
 (5.33)

In Feynman gauge, where we set $\xi \equiv 1$, this simplifies to

$$S_{V} = \frac{Z_{V}}{2} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} A_{\lambda}^{i} \left[-\bar{g}^{\mu\lambda} \bar{\nabla}^{2} + \left[\bar{\nabla}^{\mu}, \bar{\nabla}^{\lambda} \right] \right] A_{\mu}^{i} + \text{ghost term}$$

$$\stackrel{\text{(B.3)}}{=} \frac{Z_{V}}{2} \int_{x} \sqrt{\bar{g}} \sum_{i=1}^{N_{V}} A_{\lambda}^{i} \left[-\bar{g}^{\mu\lambda} \bar{\nabla}^{2} + \bar{R}^{\mu\lambda} \right] A_{\mu}^{i} + \text{ghost term}$$

$$(5.34)$$

In this form, we are again directly able to read off the two-point-function:

$$\Gamma_{AA}^{(2)} = \frac{\delta^2 \mathcal{S}_V}{\delta A^i \, \delta A^j} = Z_V \underbrace{\left[-\bar{g}^{\mu\lambda} \bar{\nabla}^2 + \bar{R}^{\mu\lambda} \right]}_{=: \bar{\Delta}_{(1)}^{\mu\nu}} \mathbb{1}_V + \mathcal{O}(h), \tag{5.35}$$

where $\bar{\Delta}^{\mu\nu}_{(1)}$ is a modified spin-one Laplacian. With the respective regulator we find

$$\Gamma_{k,AA}^{(2)} = \left[\Gamma_{AA}^{(2)} + R_{k,V}\right] = Z_V \cdot \bar{\Delta}_{(1)}^{\mu\nu} \cdot \mathbb{1}_V \left(1 + r_k \left(\frac{\bar{\Delta}_{(1)}^{\mu\nu}}{k^2}\right)\right)$$
(5.36)

and

$$\partial_t R_{k,V} = Z_V \cdot \bar{\Delta}_{(1)}^{\mu\nu} \cdot \mathbb{1}_V \left(\partial_t r_k - \eta_V r_k \right). \tag{5.37}$$

As for the fermions, we have to take care of the heat-kernel coefficients for $\bar{\Delta}_{(1)}^{\mu\nu}$. With equation (A.28), we find

$$\operatorname{Tr} \mathbf{b}_{0} = 4$$

$$\operatorname{Tr} \mathbf{b}_{2} = -\frac{\bar{\mathcal{R}}}{3},$$
(5.38)

and therefore, the result for the heat-kernel expansion for the gauge fields is given by:

$$\frac{1}{2} \operatorname{Tr} \left[\frac{Z_V \cdot \bar{\Delta}_{(1)}^{\mu\nu} (\partial_t r_k - \eta_V r_k)}{Z_V \cdot \bar{\Delta}_{(1)}^{\mu\nu} (1 + r_k)} \mathbb{1}_V \right] = \frac{N_V}{2} \operatorname{Tr} \left[\frac{\bar{\Delta}_{(1)}^{\mu\nu} (\partial_t r_k - \eta_V r_k)}{\bar{\Delta}_{(1)}^{\mu\nu} (1 + r_k)} \right]
= \frac{N_V}{2} \frac{1}{(4\pi)^2} \left[\int_x \sqrt{\bar{g}} \, \Phi_2^1(0) - \frac{1}{3} \int_x \sqrt{\bar{g}} \, \bar{\mathcal{R}} \, \Phi_1^1(0) \right] \quad (5.39)$$

$$= \frac{N_V}{2} \frac{1}{(4\pi)^2} \int_x \sqrt{\bar{g}} \left[\left(1 - \frac{\eta_V}{6} \right) - \frac{2}{3} \bar{\mathcal{R}} \left(1 - \frac{\eta_V}{6} \right) \right]$$

To finish the calculation of the gauge field contribution, we need to take the Abelian ghost term into account. Fortunately, it has already the desired form, where we can directly read off the two-point function:

$$\Gamma_{\bar{C}C}^{(2)} = \frac{\delta^2 \mathcal{S}_V}{\delta C^i \, \delta \bar{C}^j} = \mathbb{1}_V \cdot \bar{\Delta}.\tag{5.40}$$

Note, that we have the usual Laplacian $\bar{\Delta}=-\bar{\nabla}^2$ as kinetic operator and that no wave function renormalization was introduced for the Abelian ghosts. The ghost regulator $R_{k,\mathrm{gh}}$ is the same as for the scalar fields and therefore the regularized two-point function reads

$$\Gamma_{k,\bar{C}C}^{(2)} = \left[\Gamma_{\bar{C}C}^{(2)} + R_{k,\mathrm{gh}}\right] = \bar{\Delta} \cdot \mathbb{1}_V \left(1 + r_k \left(\frac{\bar{\Delta}}{k^2}\right)\right). \tag{5.41}$$

In absence of a wave function renormalization, the scale derivative only acts on the shape

function r_k and therefore the final contribution is given by

$$-\operatorname{Tr}\left[\frac{\bar{\Delta}\partial_{t}r_{k}}{\bar{\Delta}\left(1+r_{k}\right)}\mathbb{1}_{V}\right] = -N_{V}\operatorname{Tr}\left[\frac{\bar{\Delta}\partial_{t}r_{k}}{\bar{\Delta}\left(1+r_{k}\right)}\right]$$

$$= -N_{V}\frac{1}{(4\pi)^{2}}\left[\int_{x}\sqrt{\bar{g}}\,\Phi_{2}^{1}(0) + \frac{1}{6}\int_{x}\sqrt{\bar{g}}\bar{\mathcal{R}}\,\Phi_{1}^{1}(0)\right]$$

$$= -N_{V}\frac{1}{(4\pi)^{2}}\int_{x}\sqrt{\bar{g}}\left[1 + \frac{1}{3}\bar{\mathcal{R}}\right].$$
(5.42)

In the next section, we combine the obtained results and give the final expressions for the beta functions.

5.2. Beta-Functions and Perturbative Approximation

We investigate the impact of the different matter fields in a qualitative analysis.

Chapter 6.

Background independence in Quantum Gravity

- breaking of the split symmetry $\delta_{\varepsilon}g_{\mu\nu}=(\bar{g}_{\mu\nu}+\varepsilon)+(h_{\mu\nu}-\varepsilon)$ due to regulator depending only on background
- Nielsen Identities NI = $\frac{\delta\Gamma}{\delta\overline{g}_{\mu\nu}} \frac{\delta\Gamma}{\delta h_{\mu\nu}} \left\langle \left[\frac{\delta}{\delta\overline{g}_{\mu\nu}} \frac{\delta}{\delta\hat{h}_{\mu\nu}} \right] \left(S_{\rm gf} + S_{\rm gh} \right) \right\rangle = 0$
- Modified NI: mNI = NI $-\frac{1}{2} \operatorname{Tr} \left[\frac{\delta}{\sqrt{g}} \frac{\delta \sqrt{\bar{g}} R_k[\bar{g}]}{\delta \bar{g}_{\mu\nu}} G_k \right] = 0$
- Vertex Expansion in powers h: $\Gamma_k[\bar{g},h]=\sum_{n=0}^\infty \frac{1}{n!}\Gamma_k^{(0,n)}[\bar{g},h=0]h^n$

Chapter 7.

Summary and Outlook

Mathematical Background

In this part of the appendix we want to discuss some of the mathematical tools we used during the calculations presented in the scope of this thesis in a more formal manner. The part on the York decomposition is mainly inspired by [16], whereas the conventions for the heat-kernel computations are taken from [15] and extended for the matter part, using the conventions from [3].

A.1. York Decomposition

In the discussion of gauge theories, it is often very useful to decompose the gauge field A_{μ} into transversal and longitudinal parts:

$$A_{\mu} = A_{\mu}^{\mathrm{T}} + \nabla_{\mu}\phi. \tag{A.1}$$

The transversal part is characterized by the fact, that $\nabla^{\mu}A_{\mu}^{\mathrm{T}}=0$. Using this decomposition, we are able to separate the pure gauge spin-0 degrees of freedom from the physical ones, contained in the spin-1 part A_{μ}^{T} .

Assuming vanishing boundary terms, integration by parts allows us to change the integration variables in the functional integral, i. e.

$$\int_{x} \sqrt{g} A_{\mu} A^{\mu} = \int_{x} \sqrt{g} A_{\mu}^{\mathrm{T}} A^{\mathrm{T},\mu} + \int_{x} \sqrt{g} \phi \left(-\nabla^{2}\right) \phi. \tag{A.2}$$

Note, that we have to take care of the Jacobian *J* of this variable transformation:

$$(dA_{\mu}) \longrightarrow J(dA_{\mu}^{T})(d\phi).$$
 (A.3)

To be able to determine the Jacobian for our transformation, the integration measure needs to be normalized. A quite convenient choice is to evaluate the Gaussian integral over the different fields ψ and set the result to one:

$$\int (d\psi) \exp\left\{-\int dx \sqrt{g} \psi^2\right\} = 1, \tag{A.4}$$

where we are assuming an Euclidean signature and a curved background metric. With this condition we find:

$$1 = J \int \left(dA_{\mu}^{\mathrm{T}} \right) e^{-\int dx \sqrt{g} A_{\mu}^{\mathrm{T}} A^{\mathrm{T},\mu}} \int (d\phi) e^{-\int dx \sqrt{g} \phi \left(-\nabla^2 \right) \phi} = J \left(\det'_{\phi} \left(-\nabla^2 \right) \right)^{-1/2}.$$
 (A.5)

This allows us to determine the Jacobian J as follows:

$$J = \left(\det_{\phi}' \left(-\nabla^2\right)\right)^{1/2}.\tag{A.6}$$

The prime denotes the fact, that the zero mode has to be removed, when computing the determinant to obtain a consistent result. Physically this is in accordance with the fact, that a constant ϕ does not contribute to A_{μ} .

Four our computation in chapters 4 and 5, we were using the background field method, where we assume a linear split of the *full* metric $g_{\mu\nu}$ into a background metric $\bar{g}_{\mu\nu}$ and a fluctuation field $h_{\mu\nu}$. There is an analogous way of decomposing the fluctuation field in the background field formalism. First, we split $h_{\mu\nu}$ into

$$h_{\mu\nu} = h_{\mu\nu}^{\rm T} + \frac{1}{d} \, \bar{g}_{\mu\nu} h,$$
 (A.7)

where $h_{\mu\nu}^{\rm T}$ is traceless, i. e. $\bar{g}^{\mu\nu}h_{\mu\nu}^{\rm T}=0$ and $h=\bar{g}^{\mu\nu}h_{\mu\nu}$. The traceless part can be further decomposed in flat space using the irreducible representations of the Lorentz group with spins 0, 1 and 2 respectively, but in our case a more sophisticated approach, the so-called *York decomposition* is chosen:

$$h_{\mu\nu} = h_{\mu\nu}^{\rm TT} + \bar{\nabla}_{\mu}\xi_{\nu} + \bar{\nabla}_{\nu}\xi_{\mu} + \left(\bar{\nabla}_{\mu}\bar{\nabla}_{\nu} - \frac{1}{d}\,\bar{g}_{\mu\nu}\bar{\nabla}^{2}\right)\sigma + \frac{1}{d}\,\bar{g}_{\mu\nu}h. \tag{A.8}$$

Here, $h_{\mu\nu}^{\rm TT}$ is a transverse-traceless, spin-2 degree of freedom, ξ_{μ} is transverse and carries a spin-1 d. o. f. and σ and h have spin-0. As before, we want to find the Jacobian J for this variable transformation:

$$(\mathrm{d}h_{\mu\nu}) \longrightarrow J\left(\mathrm{d}h_{\mu\nu}^{\mathrm{TT}}\right) \left(\mathrm{d}\xi_{\mu}\right) \left(\mathrm{d}\sigma\right) \left(\mathrm{d}h\right).$$
 (A.9)

This is again possible after specifying a suitable normalization of the functional measure as

$$\int (\mathrm{d}h_{\mu\nu}) \exp\left\{-\mathcal{G}(h,h)\right\} = 1,\tag{A.10}$$

where \mathcal{G} is an inner product in the space of symmetric two-tensors, defined as

$$\mathcal{G}(h,h) = \int_{x} \sqrt{\bar{g}} \left(h_{\mu\nu} h^{\mu\nu} + \frac{a}{2} h^{2} \right)
= \int_{x} \sqrt{\bar{g}} \left[h^{\text{TT}}_{\mu\nu} h^{\text{TT},\mu\nu} + 2\xi_{\mu} \left(-\bar{\nabla}^{2} - \frac{\bar{R}}{d} \right) \xi^{\mu} \right]
+ \frac{d-1}{d} \sigma \left(-\bar{\nabla}^{2} \right) \left(-\bar{\nabla}^{2} - \frac{\bar{R}}{d-1} \right) \sigma + \left(\frac{1}{d} + \frac{a}{2} \right) h^{2} \right]$$
(A.11)

in the case of an Einstein type background metric¹. This yields

$$J = \left(\det_{\xi} \left(-\bar{\nabla}^2 - \frac{R}{d}\right)\right)^{1/2} \left(\det'_{\sigma} \left(-\bar{\nabla}^2\right)\right)^{1/2} \left(\det_{\sigma} \left(-\bar{\nabla}^2 - \frac{R}{d-1}\right)\right)^{1/2}. \tag{A.12}$$

Note, that the prime has the same meaning and physical interpretation as in the previous case: If σ is constant, it does not contribute to $h_{\mu\nu}$.

For both cases, the decomposition of the general gauge field and the York decomposition of the fluctuation field, appropriate rescalings of the fields ϕ , ξ_{μ} and σ respectively, help us to cancel the non-trivial Jacobians and to achieve, that all modes have the same mass dimension. For the sake of completeness, we present the rescaled versions of the fields:

$$\hat{\phi} = \sqrt{-\nabla^2} \,\phi \tag{A.13}$$

$$\hat{\xi}_{\mu} = \sqrt{-\bar{\nabla}^2 - \frac{\bar{R}}{d}} \, \xi_{\mu} \tag{A.14}$$

$$\hat{\sigma} = \sqrt{-\bar{\nabla}^2} \sqrt{-\bar{\nabla}^2 - \frac{\bar{R}}{d-1}} \, \sigma. \tag{A.15}$$

The resulting graviton two-point function, after decomposition of the fluctuation field has the following structure:

$$\Gamma_{hh}^{(2)} = \begin{pmatrix}
\Gamma_{h^{\text{TT}}h^{\text{TT}}}^{(2)} & 0 & 0 & 0 \\
0 & \Gamma_{\xi\xi}^{(2)} & 0 & 0 \\
0 & 0 & \Gamma_{h^{\text{Tr}}h^{\text{Tr}}}^{(2)} & \Gamma_{h^{\text{Tr}}\sigma}^{(2)} \\
0 & 0 & \Gamma_{\sigma h^{\text{Tr}}}^{(2)} & \Gamma_{\sigma\sigma}^{(2)}
\end{pmatrix}$$
(A.16)

This concludes our discussion of the York decomposition, as a useful tool to simplify calculations in the background field method.

^{1.} A metric is of Einstein type, if $R_{\mu\nu}$ is a constant multiple of $g_{\mu\nu}$, i. e. $R_{\mu\nu} = \frac{1}{d} \mathcal{R} g_{\mu\nu}$.

A.2. Heat-Kernel Techniques

We use heat-kernel techniques to evaluate the r.h.s. of the flow equation (2.25), where we need to compute the functional trace over functions depending on the Laplacian on a curved background. In general, the method can be understood as a curvature expansion about a flat background.

The general formula to compute such traces is given by

$$\operatorname{Tr} f(\Delta) = N \sum_{\ell} \rho(\ell) f(\lambda(\ell)), \tag{A.17}$$

with some normalization N, the spectral values $\lambda(\ell)$ and their corresponding multiplicities $\rho(\ell)$.

On flat backgrounds, the computation of (A.17) is simply a standard momentum integral, whereas on curved backgrounds, consider for example a four-sphere \mathbb{S}^4 with constant background curvature $r=\frac{\bar{R}}{k^2}>0$, the spectrum of the Laplacian is discrete and we need to sum over all spectral values.

For our example of \mathbb{S}^4 , we have

$$\lambda(\ell) = \frac{\ell(3+\ell)}{12}r$$
 and $\rho(\ell) = \frac{(2\ell+3)(l+2)!}{6\ell!}$. (A.18)

The normalization is then given by the inverse of the four-sphere-volume $(V_{\mathbb{S}^4})^{-1} = \frac{k^4 r^2}{384\pi^2}$. This leads us to the formula for our computation of the r.h.s. of the flow equation on a background with constant positive curvature:

$$\operatorname{Tr} f(\Delta) = \frac{k^4 r^2}{384\pi^2} \sum_{\ell=0}^{\infty} \frac{(2\ell+3)(\ell+2)!}{6\ell!} f\left(\frac{\ell(3+\ell)}{12}r\right). \tag{A.19}$$

This is called spectral sum. For large curvatures r the convergence of the series is rather fast, whereas in the limit $r \to 0$ one finds exponentially slow convergence.

The master equation for heat kernel computations reads

$$\operatorname{Tr} f(\Delta) = \frac{1}{(4\pi)^{\frac{d}{2}}} \left[\mathbf{B}_0(\Delta) Q_2[f(\Delta)] + \mathbf{B}_2(\Delta) Q_1[f(\Delta)] \right] + \mathcal{O}\left(\mathcal{R}^2\right), \tag{A.20}$$

with the heat-kernel coefficients

$$\mathbf{B}_{n}(\bar{\Delta}) = \int_{x} \sqrt{g} \operatorname{Tr} \mathbf{b}_{n}(\bar{\Delta})$$
 (A.21)

and

$$Q_n[f(x)] = \frac{1}{\Gamma(n)} \int \mathrm{d}x \ x^{n-1} f(x). \tag{A.22}$$

For computations on \mathbb{S}^4 , the values for the heat kernel coefficients $\mathbf{B}_n(\bar{\Delta})$ are presented in the following.

$$\begin{array}{c|cccc} & TT & TV & S \\ \hline Tr \, \mathbf{b}_0 & 5 & 3 & 1 \\ Tr \, \mathbf{b}_2 & -\frac{5}{6} \mathcal{R} & \frac{1}{4} \mathcal{R} & \frac{1}{6} \mathcal{R} \end{array}$$

Table A.1.: Heat-kernel coefficients for transverse-traceless tensors (TT), transverse vectors (TV) and scalars (S) for computations on \mathbb{S}^4 .

The basic idea of the proof of equation (A.17) is based on the Laplace transform

$$f(\Delta) = \int_0^\infty ds \ e^{-s\Delta} \, \tilde{f}(s). \tag{A.23}$$

We insert this definition of the Laplace transform into equation (A.17) and find

$$\operatorname{Tr} f(\Delta) = \int_0^\infty ds \, \tilde{f}(s) \operatorname{Tr} e^{-s\Delta}. \tag{A.24}$$

The trace on the r.h.s. is explicitly the trace of the heat kernel. We expand this term as follows:

$$\operatorname{Tr} e^{-s\Delta} = \frac{1}{(4\pi)^{\frac{d}{2}}} \sum_{n=0}^{\infty} s^{\frac{n-d}{2}} \mathbf{B}_n(\Delta). \tag{A.25}$$

This is where the heat-kernel coefficients \mathbf{B}_n become important. We proceed by inserting this expanded version of the heat-kernel trace into equation (A.24) and find:

$$\operatorname{Tr} f(\Delta) = \frac{1}{(4\pi)^{\frac{d}{2}}} \sum_{n=0}^{\infty} \mathbf{B}_{n}(\Delta) \int_{0}^{\infty} ds \, s^{\frac{n-d}{2}} \tilde{f}(s)$$

$$= \frac{1}{(4\pi)^{\frac{d}{2}}} \sum_{n=0}^{\infty} \frac{1}{\Gamma\left(\frac{d-k}{2}\right)} \mathbf{B}_{n}(\Delta) \int_{0}^{\infty} dt \, t^{\frac{d-n}{2}-1} f(t)$$

$$= \frac{1}{(4\pi)^{\frac{d}{2}}} \sum_{n=0}^{\infty} \mathbf{B}_{n}(\Delta) Q_{\frac{d-n}{2}} [f(t)].$$
(A.26)

This completes the derivation of the master equation (A.20) for heat-kernel computations. Note, that we used the definition of the Q-functionals, given in equation (A.22) and the relation $\int_s s^{-x} \tilde{f}(x) = \frac{1}{\Gamma(x)} \int_z z^{x-1} f(z)$.

When investigating matter fields, such as in chapter 5, we often encounter kinetic operators of the form $\tilde{\Delta} = -\nabla^2 \cdot \mathbb{1} + \mathbf{E}$, where \mathbf{E} is a linear map acting on the spacetime and the internal indices of the fields. In this notation, $\mathbb{1}$ has to be understood as the identity

in the respective field space.

If $[\Delta, \mathbf{E}] = 0^2$, we can relate the coefficients of the modified Laplacian $\tilde{\Delta}$ and those of the initially considered operator $-\nabla^2$ via

$$\operatorname{Tr} e^{-s\left(-\nabla^2 + \mathbf{E}\right)} = \frac{1}{(4\pi)^{\frac{d}{2}}} \sum_{k,l=0}^{\infty} \frac{(-1)^{\ell}}{\ell!} \int_{x} \sqrt{g} \operatorname{Tr} \mathbf{b}_{k}(\Delta) \mathbf{E}^{\ell} s^{k+\ell-2}. \tag{A.27}$$

This results in the following, modified values for the coefficients we are interested in:

$$\mathbf{b}_0 = \mathbb{1}$$

$$\mathbf{b}_2 = \frac{\mathcal{R}}{6} \cdot \mathbb{1} - \mathbf{E}. \tag{A.28}$$

For further study and a more general treatment of the modified Laplacians, including higher order coefficients, [3, 16] are recommended.

^{2.} In the case of $[\Delta, \mathbf{E}] \neq 0$, there would be additional terms including (higher order) commutators of Δ and \mathbf{E} due to the Baker-Campbell-Hausdorff formula.

Additional calculations

For the sake of completeness, we present some auxiliary calculations and important steps, that were used to obtain the results presented in scope of this work, but were in general too long or unsuitable to be included in the main part.

B.1. Matter calculations

Fermion part

In the part on fermions, we are confronted with operators contracted with gamma matrices, represented as usual in Feynman slash notation. Here, we present the proof of an identity we used in the derivation of the fermion two-point function:

$$\nabla^{2} = \nabla_{\mu} \nabla_{\nu} \gamma^{\mu} \gamma^{\nu}$$

$$= \frac{1}{2} \nabla_{\mu} \nabla_{\nu} (\gamma^{\mu} \gamma^{\nu} + \gamma^{\nu} \gamma^{\mu})$$

$$= g^{\mu\nu} \nabla_{\mu} \nabla_{\nu}$$

$$= \nabla^{2}$$
(B.1)

The third line follows from the definition of the Clifford algebra $\{\gamma^{\mu}, \gamma^{\nu}\} = 2g^{\mu\nu}\mathbb{1}$.

Gauge field part

During the computation of the gauge field contribution to the running of G and Λ , we encounter the following term, which can be simplified a lot after a few manipulations:

$$\int g^{\mu\nu} g^{\kappa\lambda} F_{\mu\kappa} F_{\nu\lambda} = \int F_{\mu}{}^{\lambda} F^{\mu}{}_{\lambda} = \int F_{\mu\lambda} F^{\mu\lambda}
= \int (\partial_{\mu} A_{\lambda} - \partial_{\lambda} A_{\mu}) F^{\mu\lambda} + \mathcal{O}\left(A^{3}\right)
\stackrel{(\star)}{=} \int 2\partial_{\mu} A_{\lambda} F^{\mu\lambda}
= \int 2\partial_{\mu} A_{\lambda} \left(\partial^{\mu} A^{\lambda} - \partial^{\lambda} A^{\mu}\right)
= \int 2 \left(\partial_{\mu} A_{\lambda} \partial^{\mu} A^{\lambda} - \partial_{\mu} A_{\lambda} \partial^{\lambda} A^{\mu}\right)
\stackrel{(\dagger)}{=} -\int 2 \left(A_{\lambda} \partial^{2} A^{\lambda} - A_{\lambda} \partial_{\mu} \partial^{\lambda} A^{\mu}\right)
= \int 2A_{\lambda} \left[\partial^{\mu} \partial^{\lambda} - g^{\mu\lambda} \partial^{2}\right] A_{\mu}$$
(B.2)

For the first non-trivial step (*) we use that $2\partial_{\mu}A_{\lambda}=\partial_{(\mu}A_{\lambda)}+\partial_{[\mu}A_{\lambda]}$, where (\cdots) and $[\cdots]$ denote symmetrization and antisymmetrization w. r. t. the indices, respectively. The symmetric part vanishes due to the fact, that $F^{\mu\lambda}$ is antisymmetric under $\mu \rightleftharpoons \lambda$. This allows us to write $2\partial_{\mu}A_{\lambda}F^{\mu\lambda}=\partial_{[\mu}A_{\lambda]}F^{\mu\lambda}=\left(\partial_{\mu}A_{\lambda}-\partial_{\lambda}A_{\mu}\right)F^{\mu\lambda}$. The second non-trivial step (†) results from integrating by parts and assuming vanishing boundary terms.

Later on in the gauge field calculation, after specifying the gauge parameter $\xi = 1$, we encounter a commutator of covariant derivatives acting on A_{μ} . With the definition of the curvature tensor, given in equation (3.10), we find

$$\begin{bmatrix} \nabla^{\mu}, \nabla^{\lambda} \end{bmatrix} A_{\mu} = R_{\mu}^{\rho\mu\lambda} A_{\rho}$$

$$= R^{\rho\lambda} A_{\rho}$$
(B.3)

Now, one simply has to rename the dummy indices $\rho \rightleftharpoons \mu$ to find the wanted expression.

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Declaration of Authorship

I hereby certify that this thesis has been composed	d by me and is based on my own work
unless stated otherwise.	
Heidelberg, $8^{ m th}$ of July 2019	 Mathieu Kaltschmidt