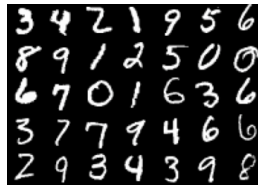
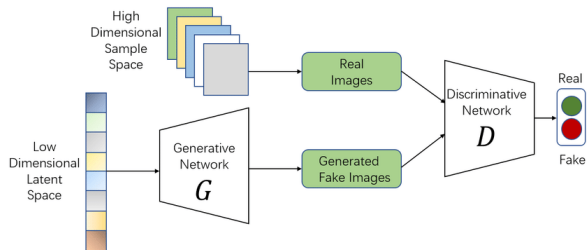


# VeGANs project presentation

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# Problem statement

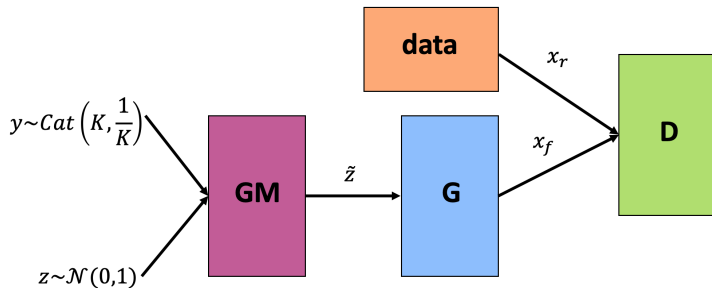
**Goal :** represent a latent (learning) space as a manner to implement image generation.



$$\min_G \max_D \mathbb{E}_{x_r \sim P} [\log D(x)] + \mathbb{E}_{x_g \sim \hat{P}_G} [\log(1 - D(x))]$$

# Gaussian Mixture Model

$K$  : number of gaussians inside the latent space



$\tilde{z} = \mu(y) + \sigma(y)z$  follows  $\mathcal{N}(\mu_k, \sigma_k)$ , the  $k^{th}$  Gaussian distribution of the latent space.

Allows backpropagation through the GM module  $\rightarrow$  dynamic implementation

## First implementation : Supervised GM-GAN

**Supervised objective:** separate real / fake samples **and** find class of real samples

Discriminator returns :

$$\begin{cases} (0, \dots, 1^{ith}, \dots, 0) & \text{if the input is of class } i \\ (0, \dots, 0, 1) & \text{if the input is a fake sample} \end{cases}$$

Generator should map each Gaussian to a unique class.

CrossEntropy Loss :

- ▶ **G training:** between  $D(G(\tilde{z}))$  and label  $y$  used to sample  $\tilde{z}$
- ▶ **D training** : between  $D(sample_{real})$  and label  $y_{real}$   
+ between  $D(G(\tilde{z}))$  and "label"  $y_{fake} = 10$

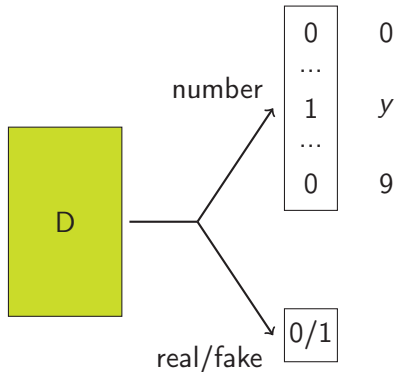
## Second implementation : alternative objective

**Change:** We separate class prediction and reality prediction objectives.

**Cross-Entropy** between first 10 dims of output and the label  $y$

**Binary CE** between last dim and fake/real

Training  $D$ , CE loss is used only on real samples  
 $G(GM(y, z))$  and  $y$  are not correlated enough



## Approaches we tested

- ▶ Mean  $\mu$  and variance  $\sigma$  are the representative parameters of our problem, we initialized them with different values :  $\mu$  is uniformly sampled in  $[-c, c]$  and  $\sigma$  is set to a constant  $\sigma$
- ▶ Hyperparameter tuning : learning rate and batch size
- ▶ Data augmentation (future)
- ▶ Dropout
- ▶ Weighting the losses (approach 2)

# Results for initial approach



Figure: Numbers generated with approach 1 (per-category mode collapse)

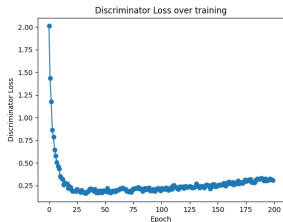


Figure: D loss



Figure: G loss

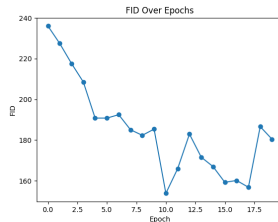


Figure: FID over epochs

## Alternative results

$\sigma$	$c$	learning rate	FID
1.7	3	8e-5	100
0.7	3	2e-4	150
1	3	2e-4	134
1	1	2e-4	210

Table: Results for approach 1 @ 150 epochs

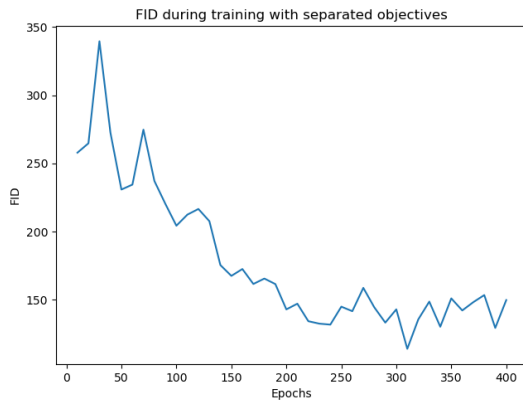


Figure: FID for approach 2



## References

Matan Ben-Yosef and Daphna Weinshall : Gaussian Mixture Generative Adversarial Networks for Diverse Datasets, and the Unsupervised Clustering of Images, 2018

Teodora Pandeve and Matthias Schubert : MMGAN: Generative Adversarial Networks for Multi-Modal Distributions, 2019