

Atlas

Local Graph Exploration in a Global Context

IUI 2019



Fred Hohman

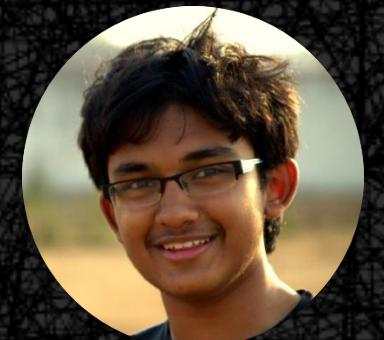
[@fredhohman](https://twitter.com/fredhohman)

Georgia Tech



James Abello

Rutgers



Varun Bezzam

Georgia Tech



Polo Chau

Georgia Tech



Graph Sensemaking



Global View

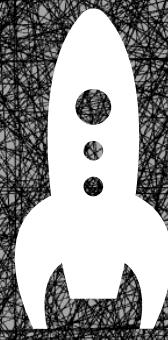
Graph Sensemaking



Local View



Global View

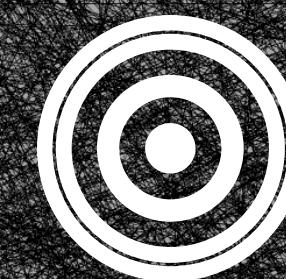


Free Exploration

Graph Sensemaking



Local View

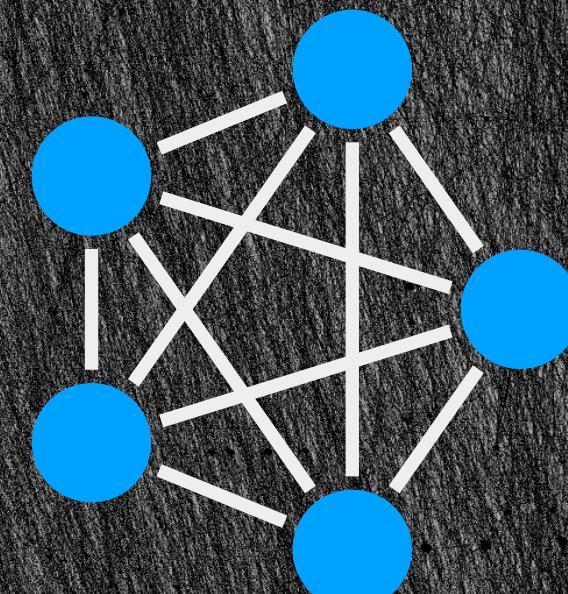


Targeted Exploration

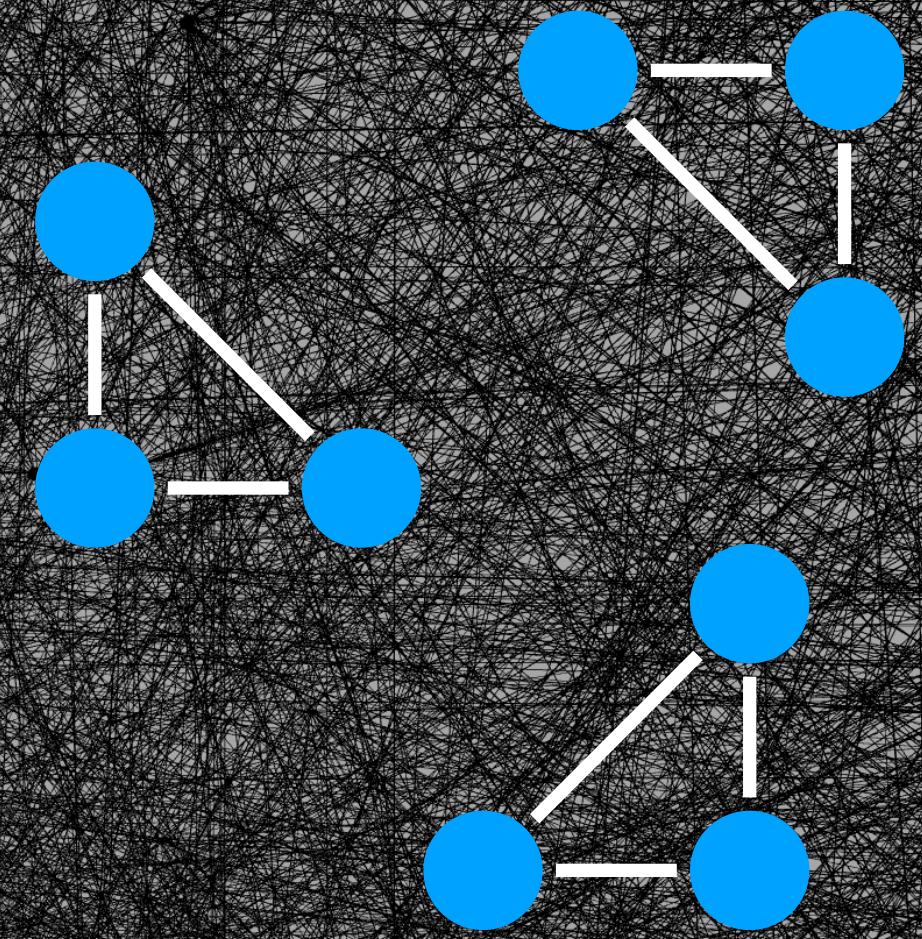
Important Structure

Graph Sensemaking

Important Nodes

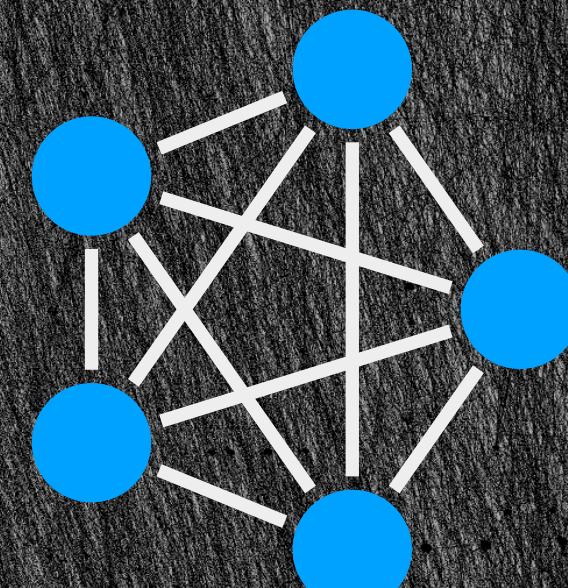


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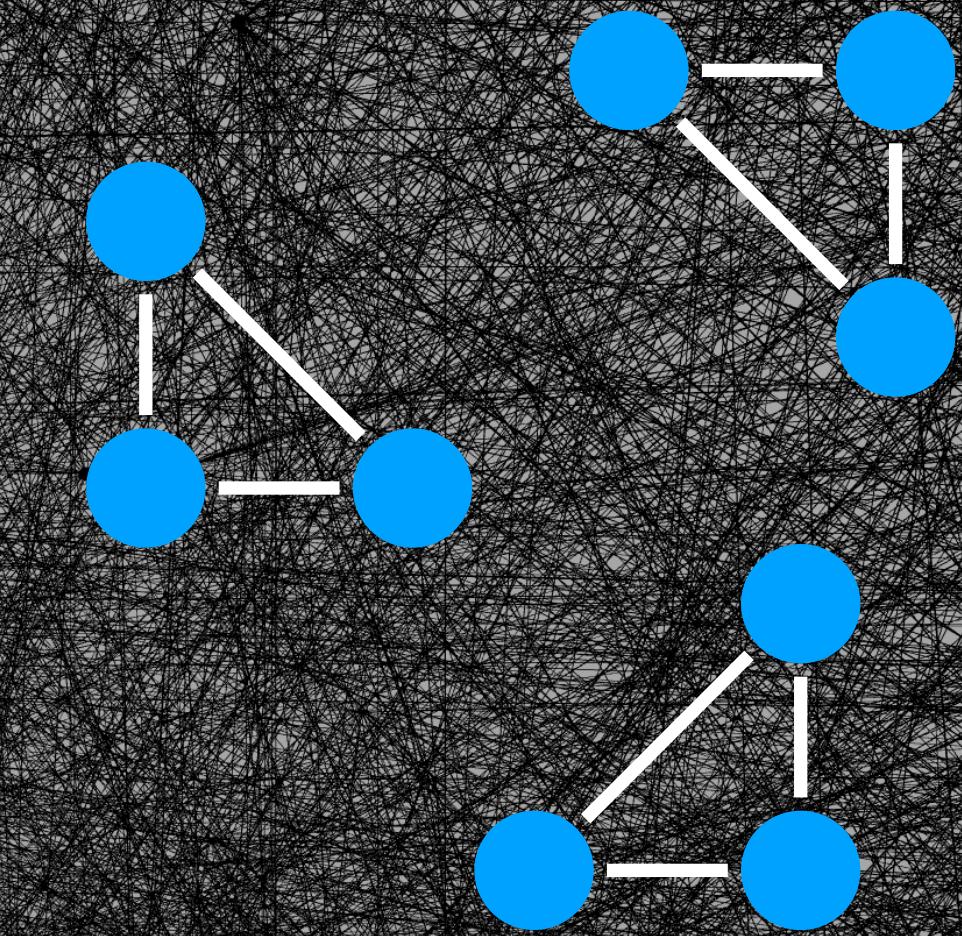


Graph Sensemaking

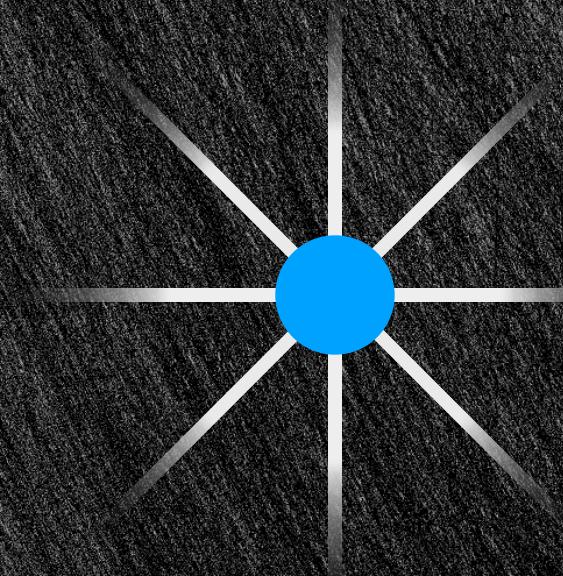
Important Nodes



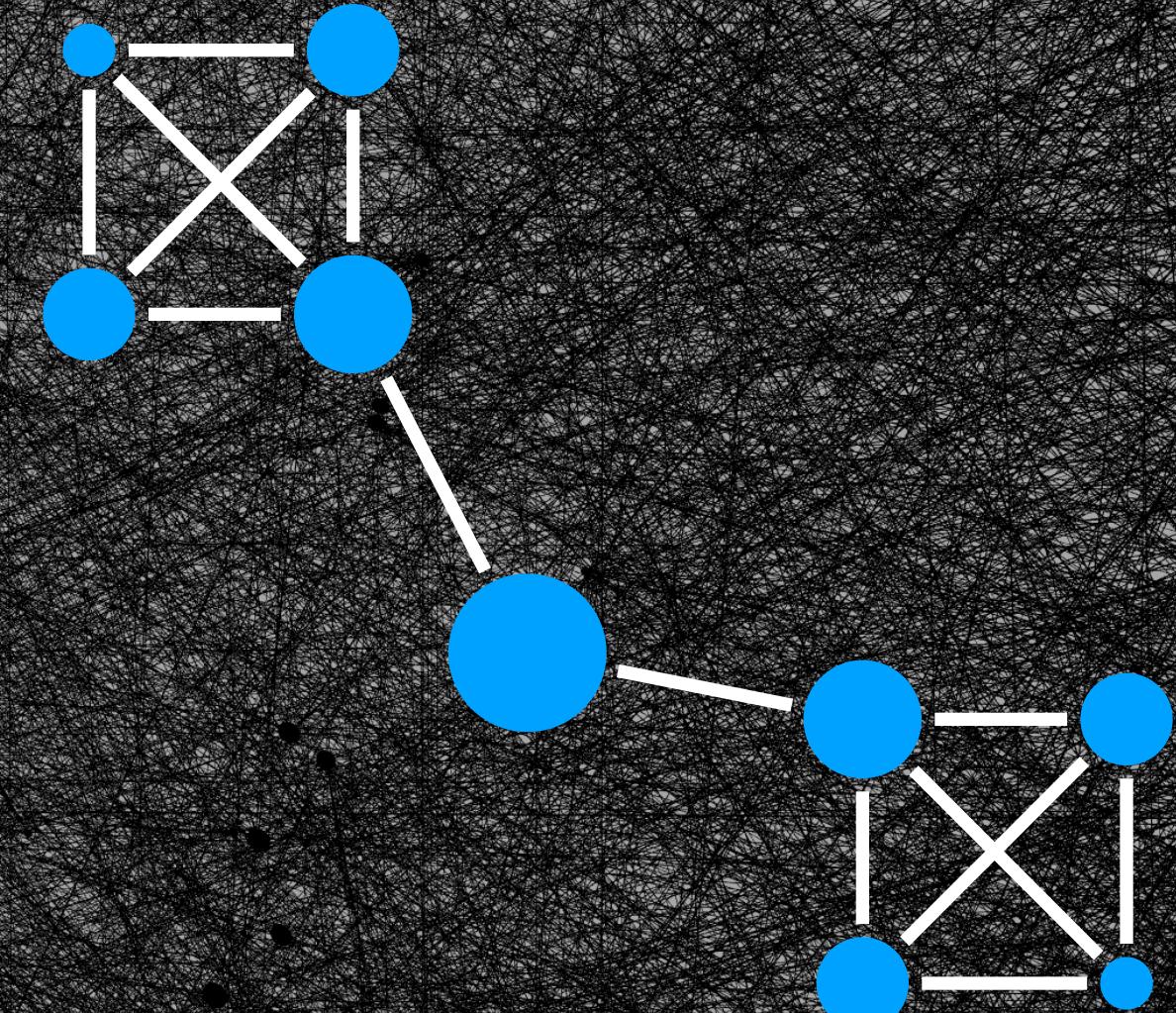
Important Structure



Graph Sensemaking



Important Nodes



Data Mining

Automatic

Summarization, clustering,
classification

Millions of nodes

HCI

Human-computer
Interaction

User-driven, iterative

Interactive, visualization

Thousands of nodes

Data Mining

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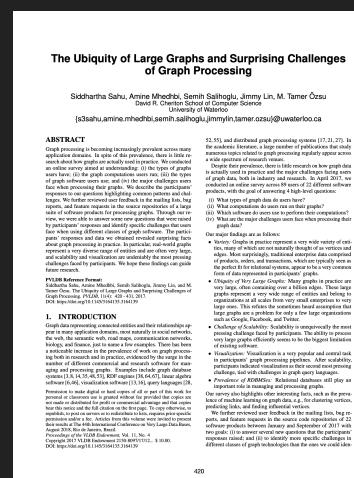
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The Ubiquity of Large Graphs and Surprising Challenges of Graph Processing.
Sahu, et al. VLDB, 2017.

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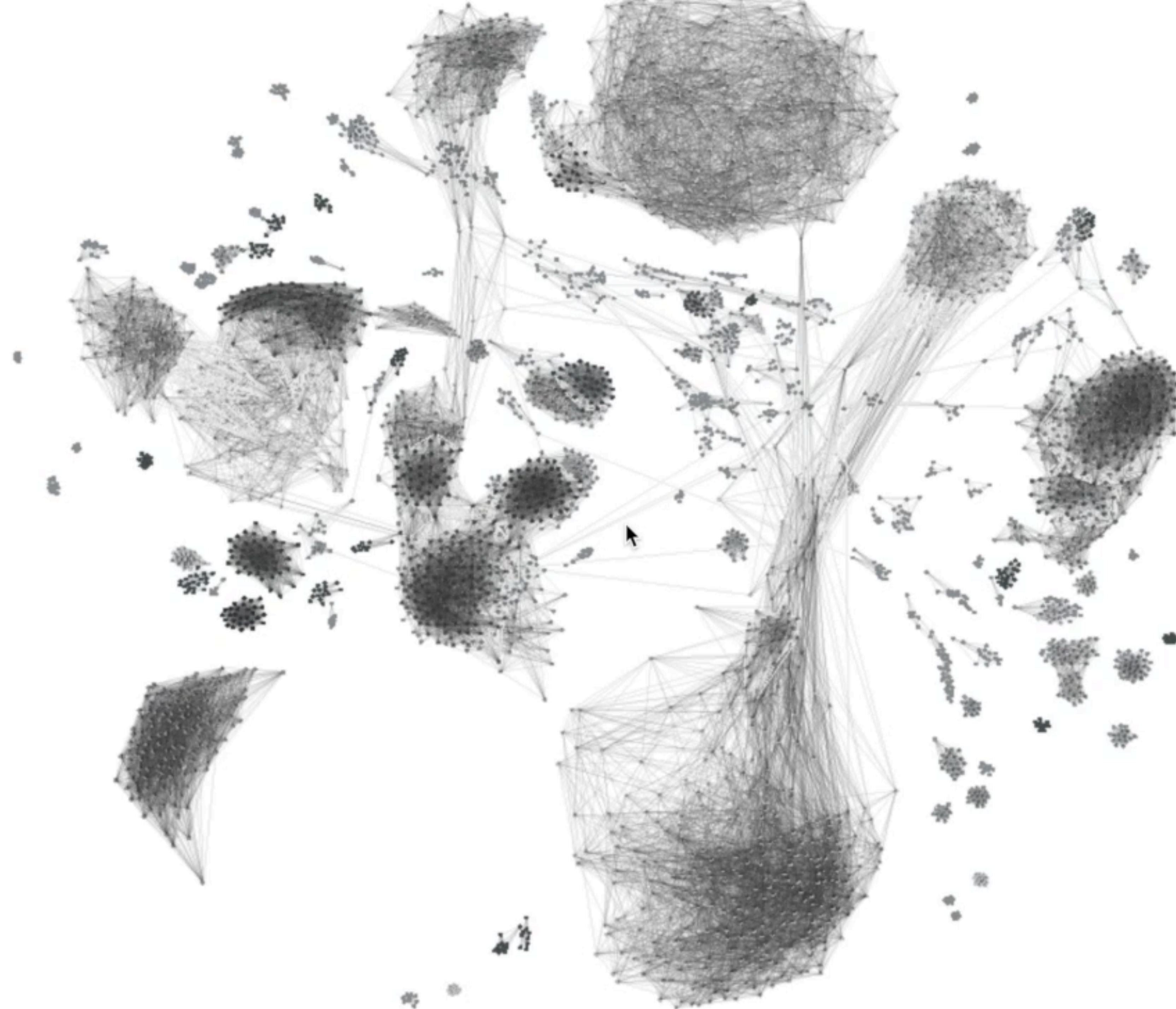
User-driven, iterative

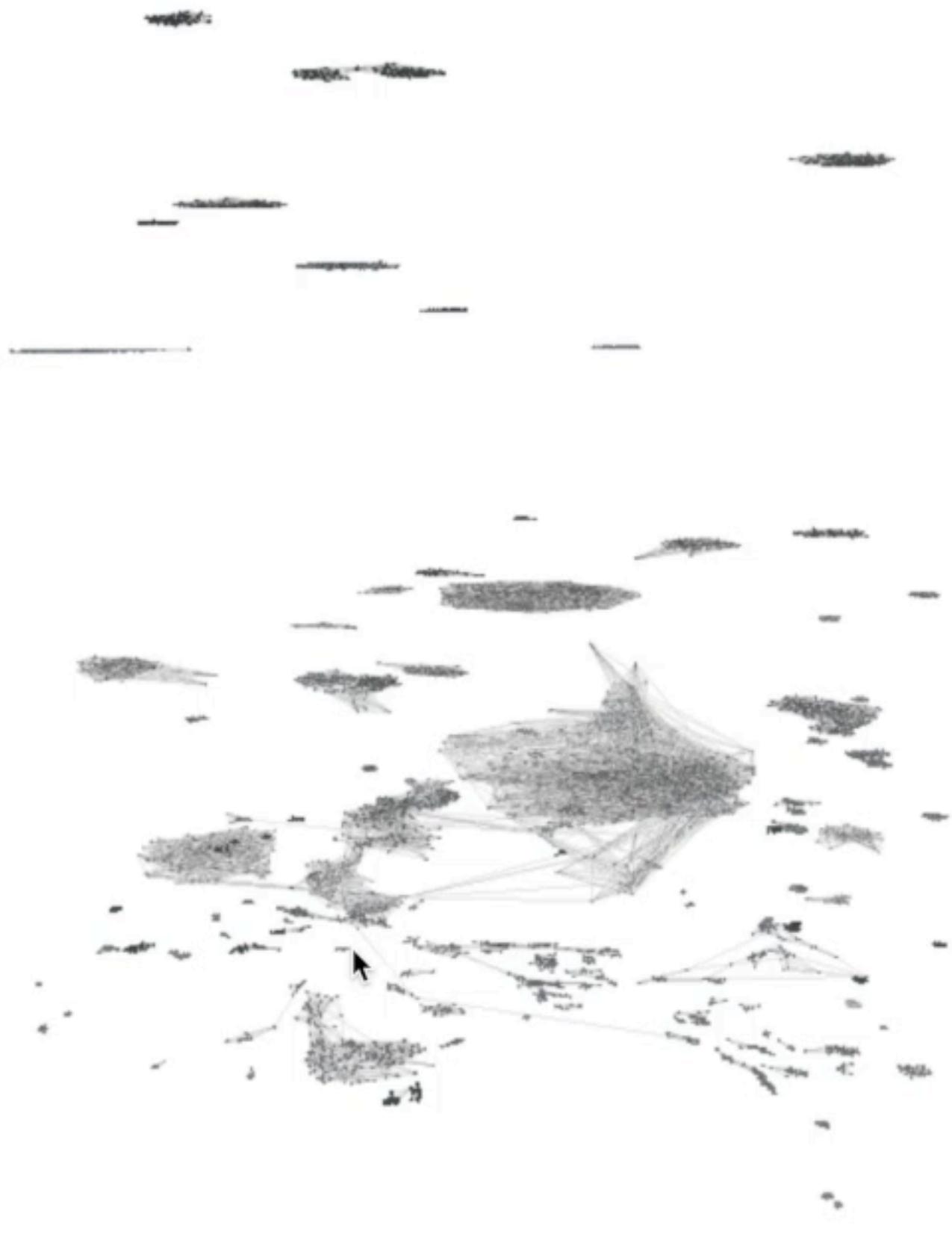
Interactive, **visualization**

Thousands of nodes



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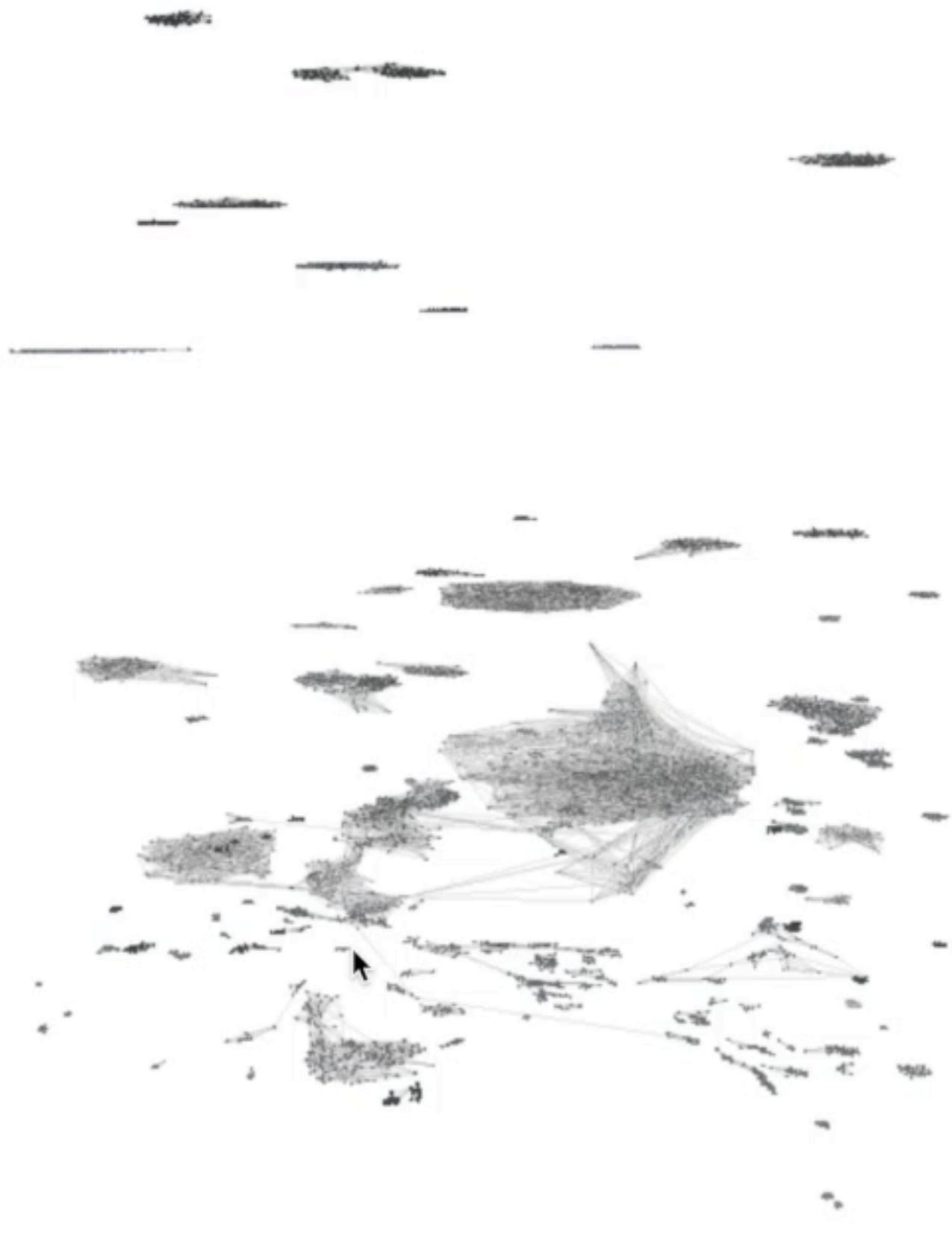


Atlas



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**interactive graph exploration via
scalable edge decomposition**



Atlas



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**interactive graph exploration via
scalable edge decomposition**

- separate graph into *graph layers*

Atlas

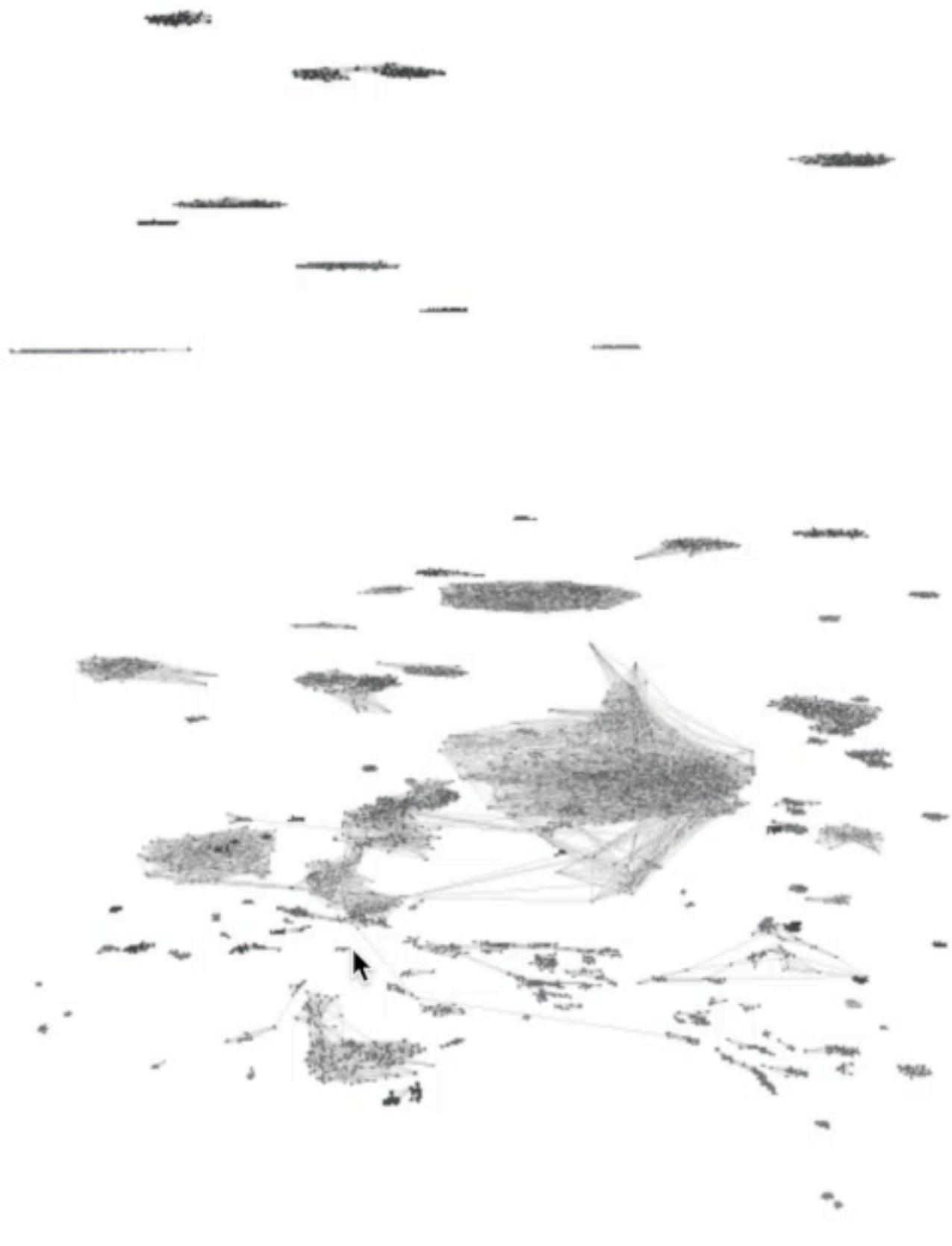


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**interactive graph exploration via
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- separate graph into *graph layers*
- reveal peculiar subgraph





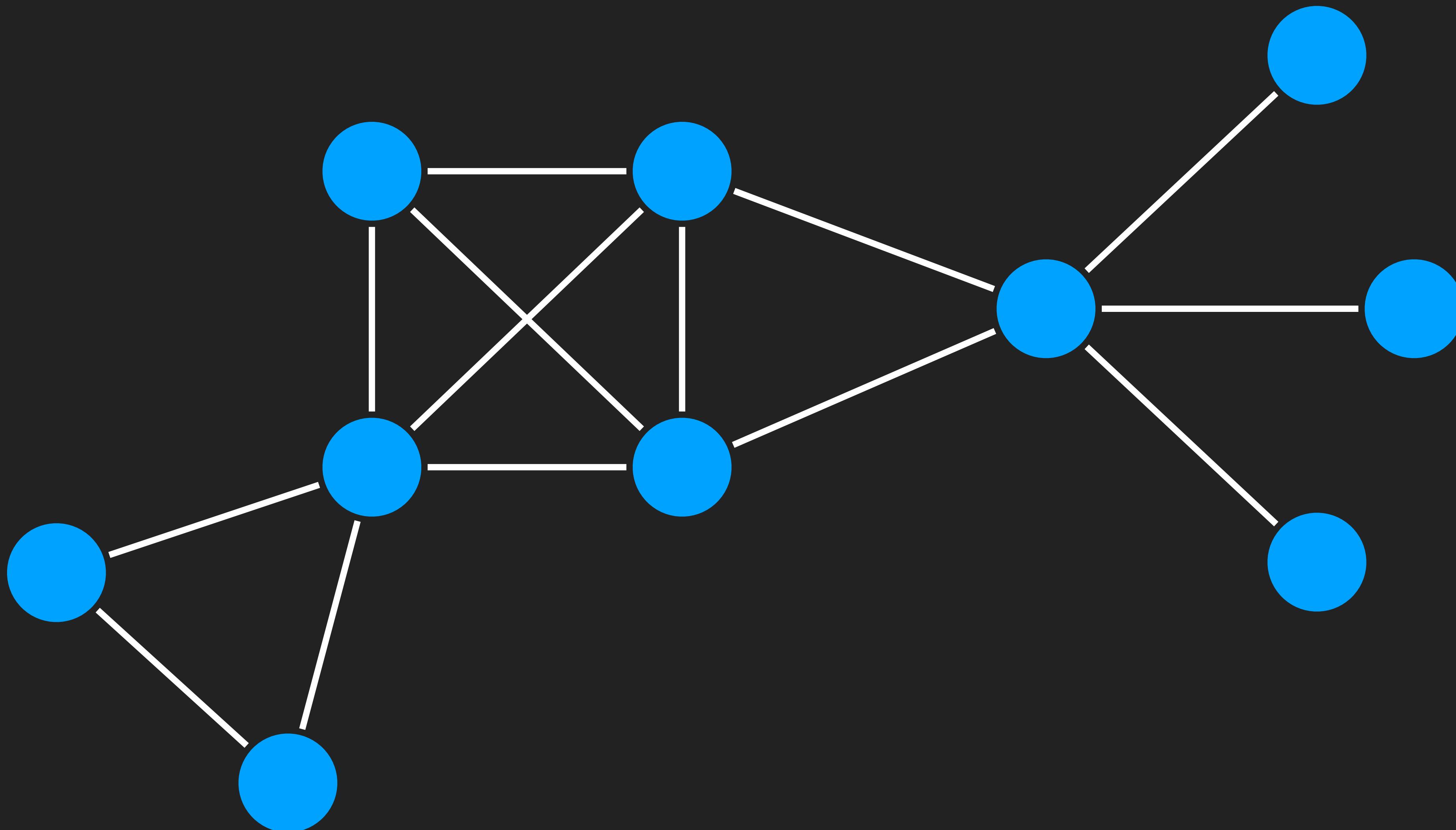
Atlas

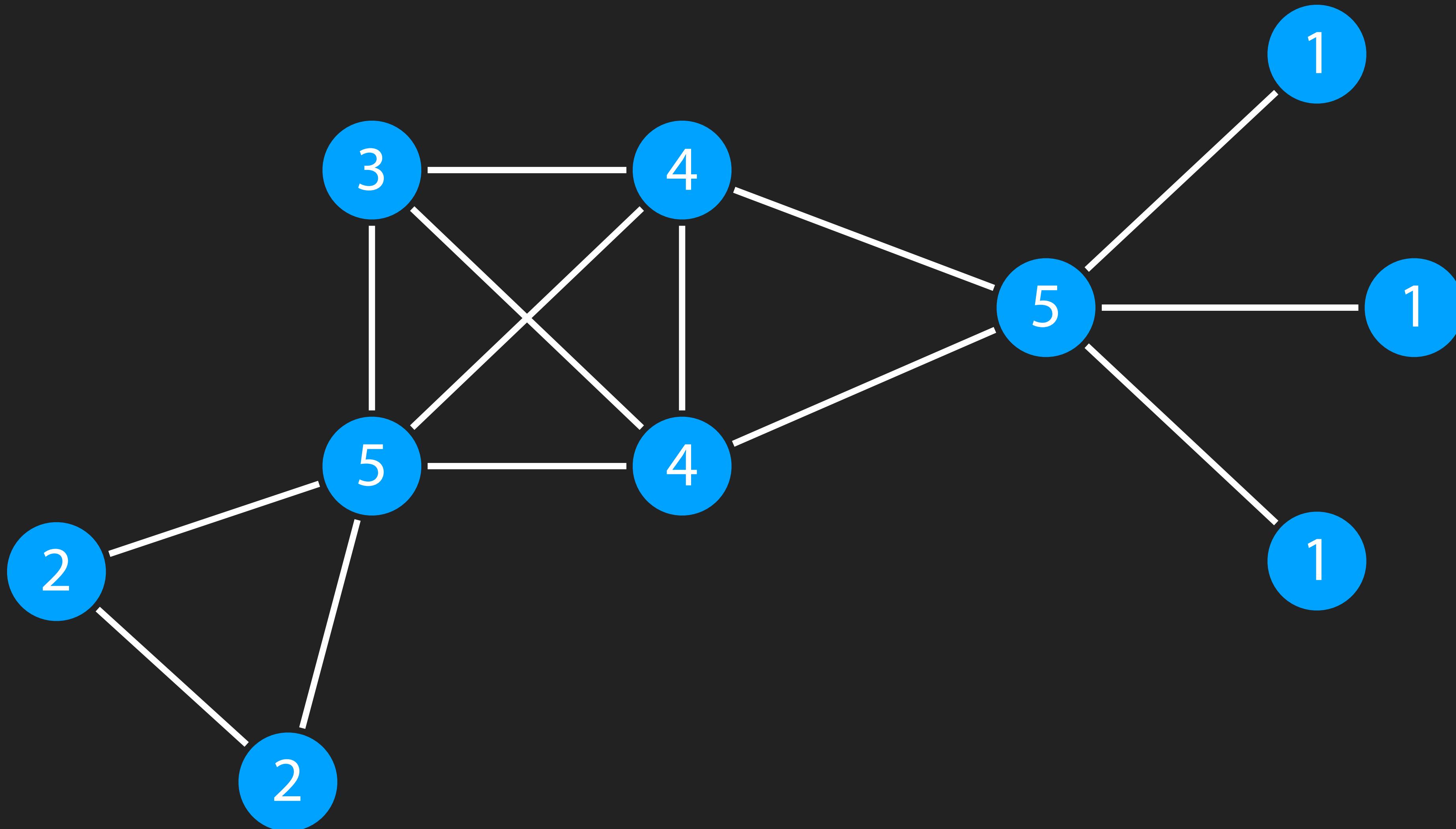


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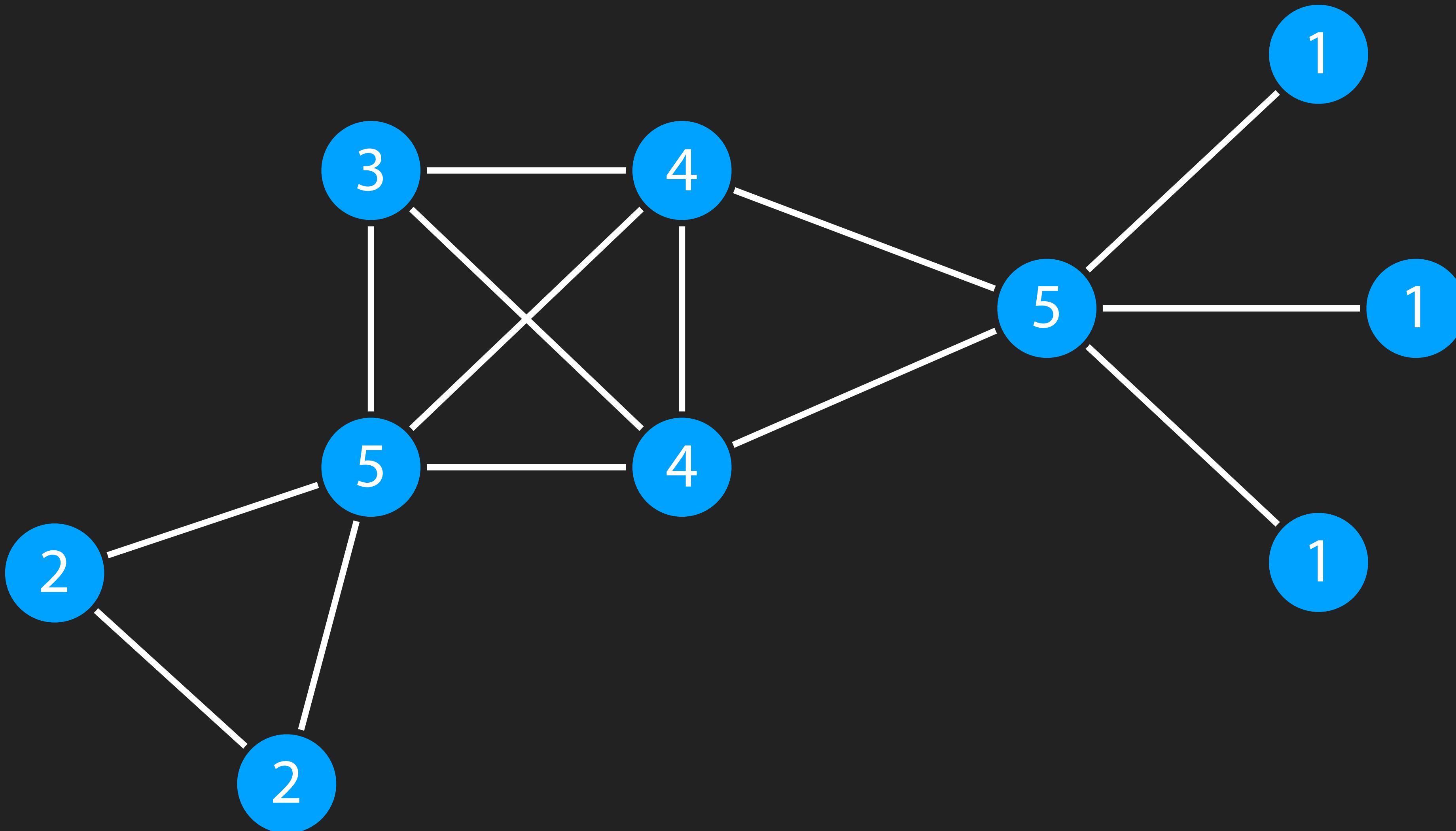
**interactive graph exploration via
scalable edge decomposition**

- separate graph into *graph layers*
- reveal peculiar subgraph
- visualize local + global structure

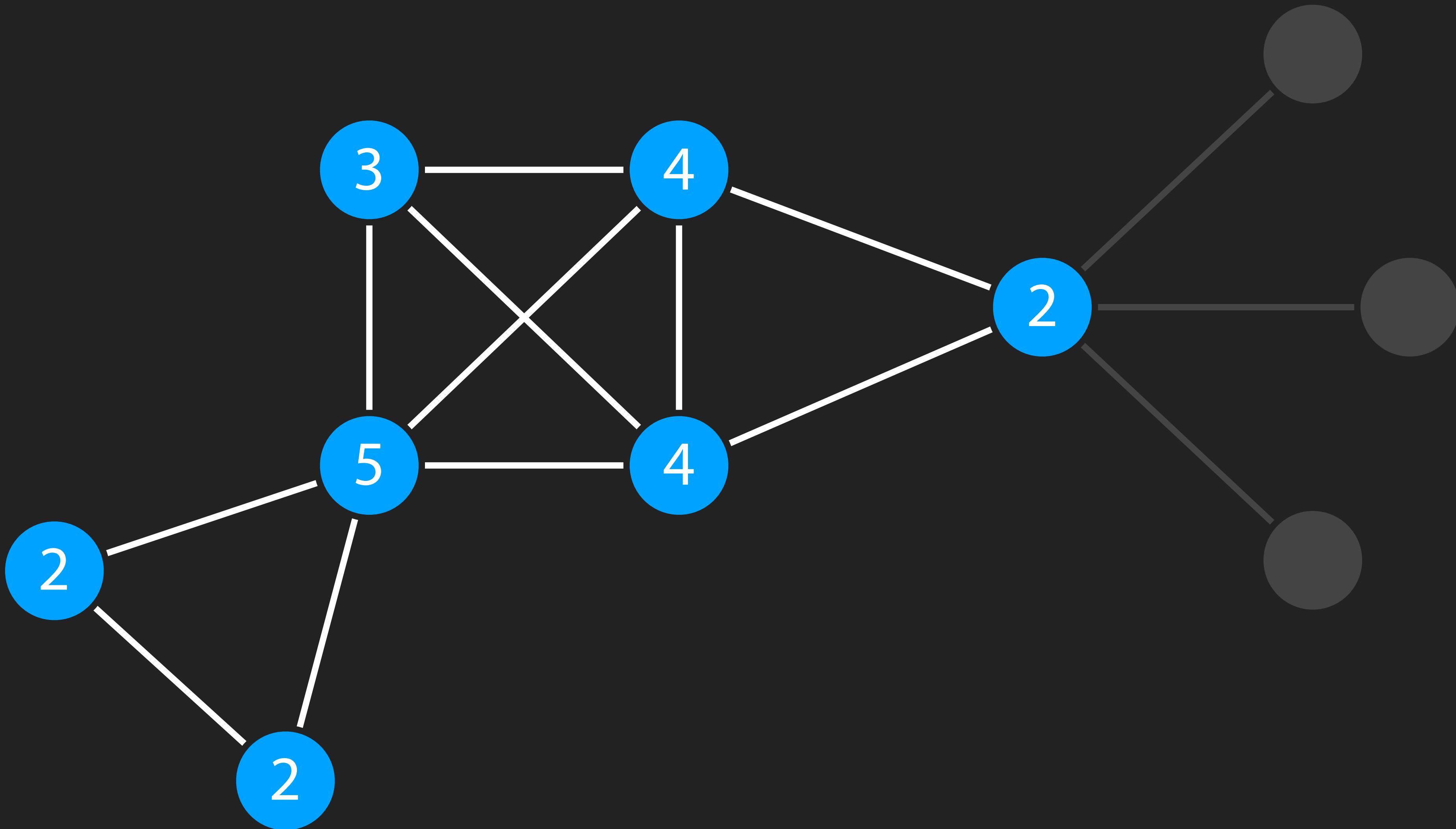




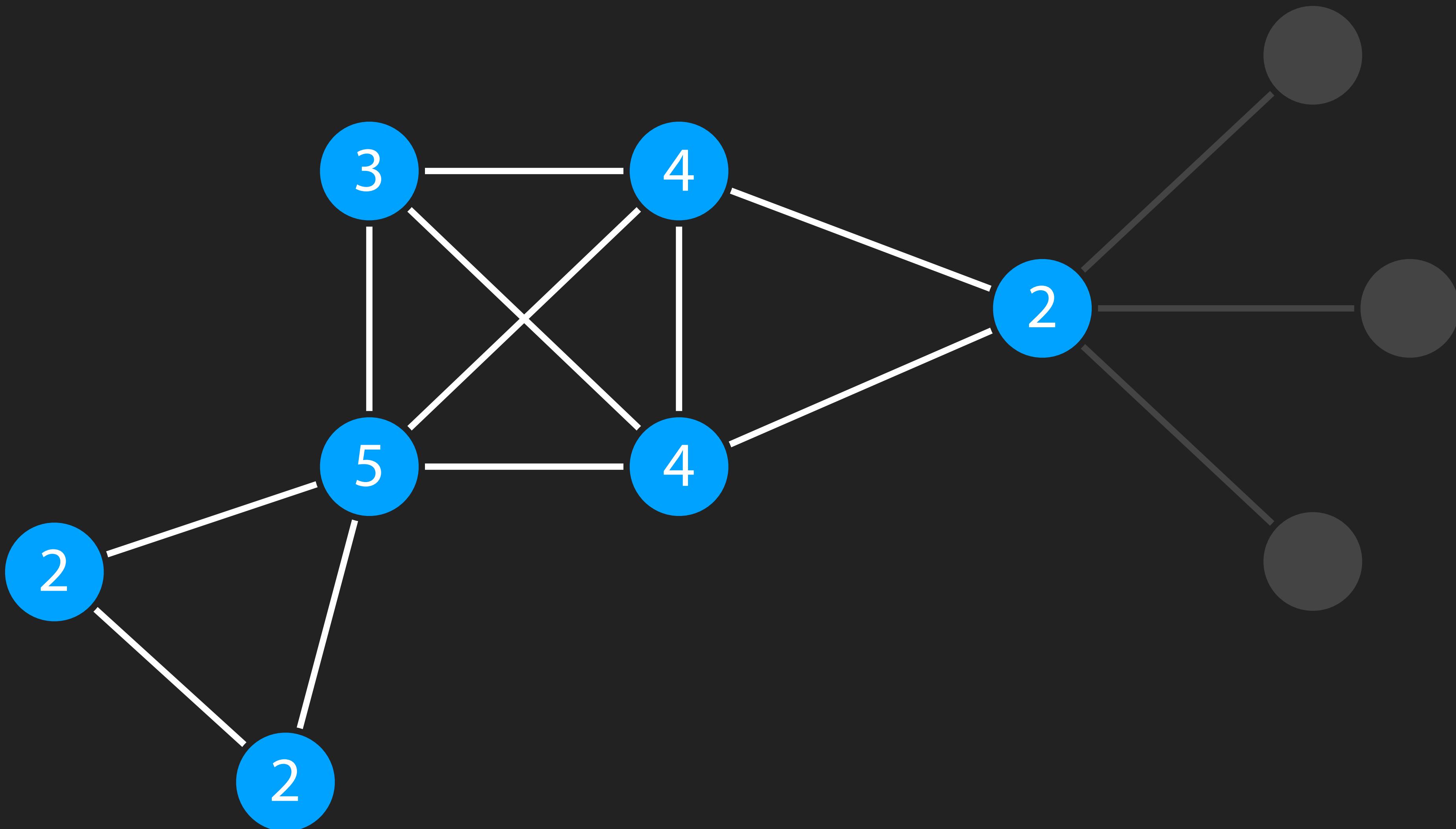
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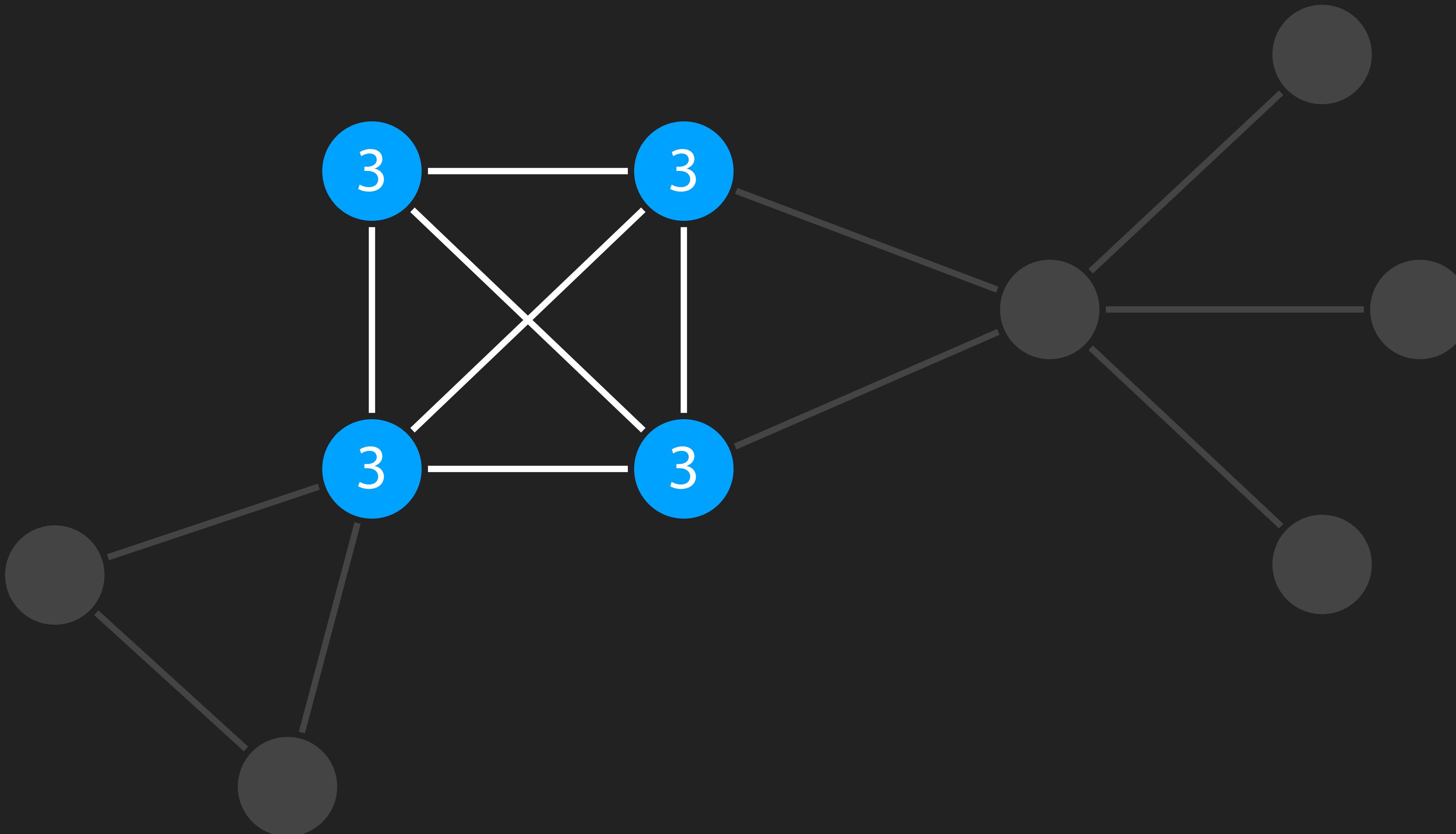
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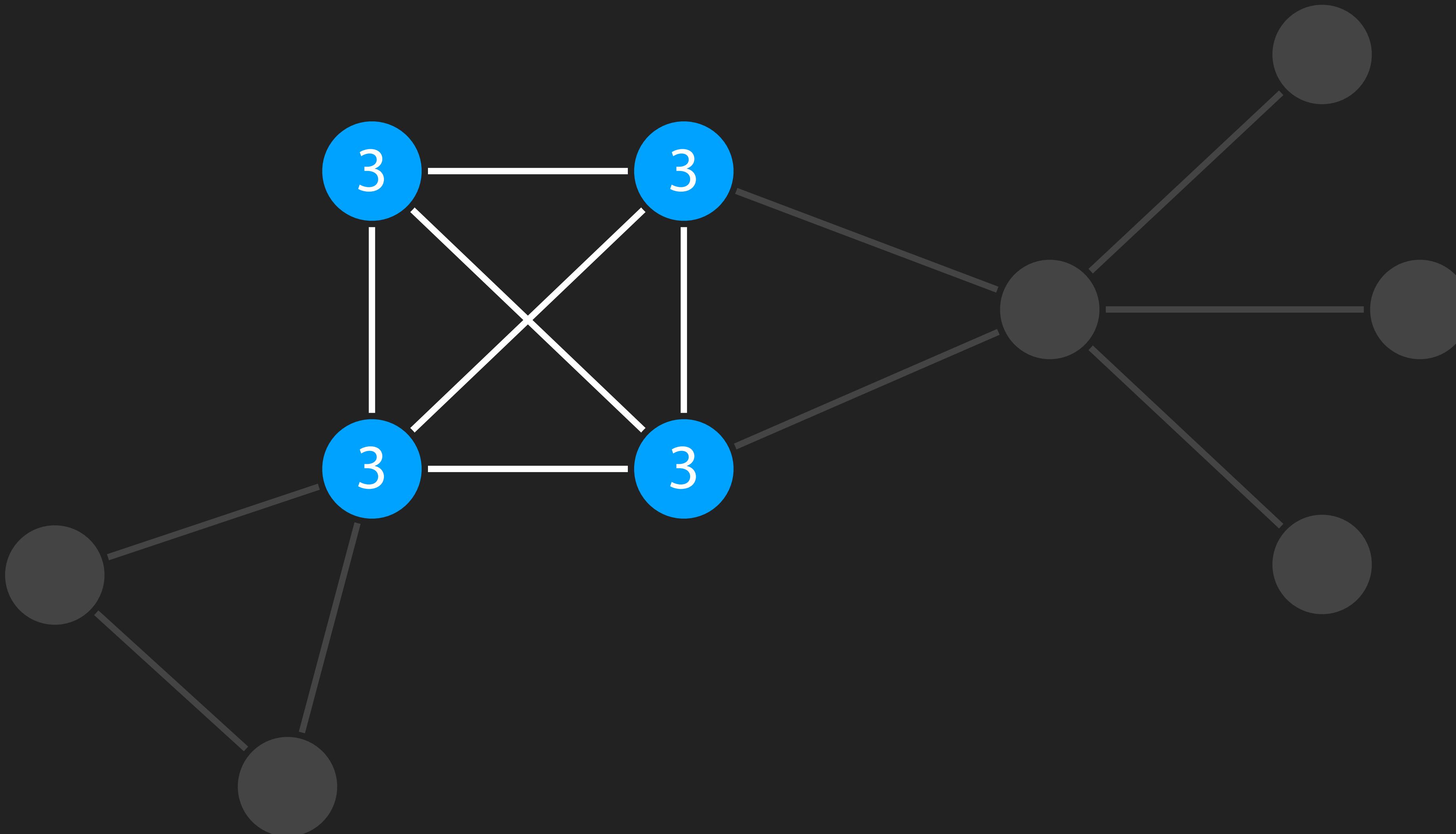
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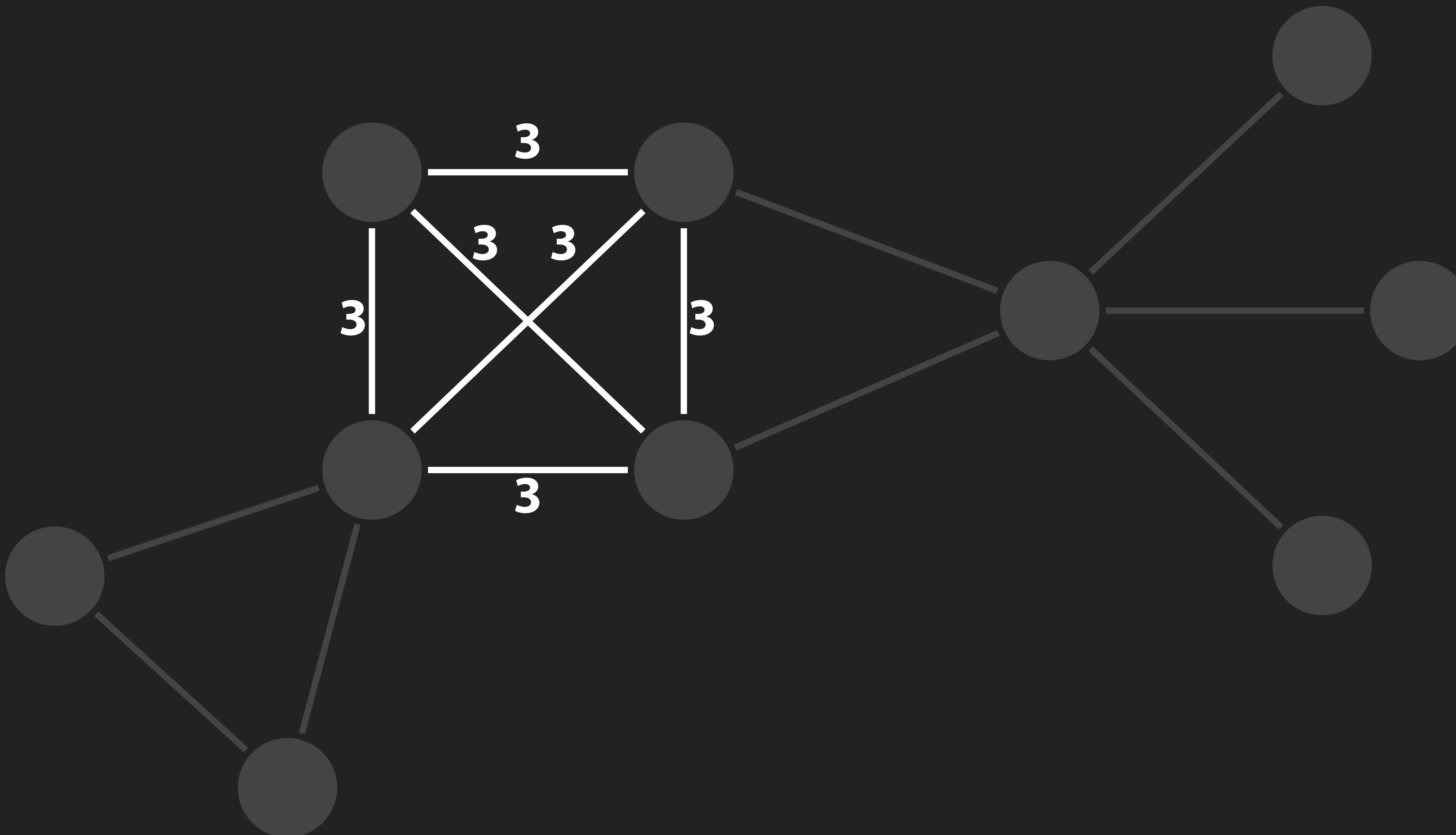
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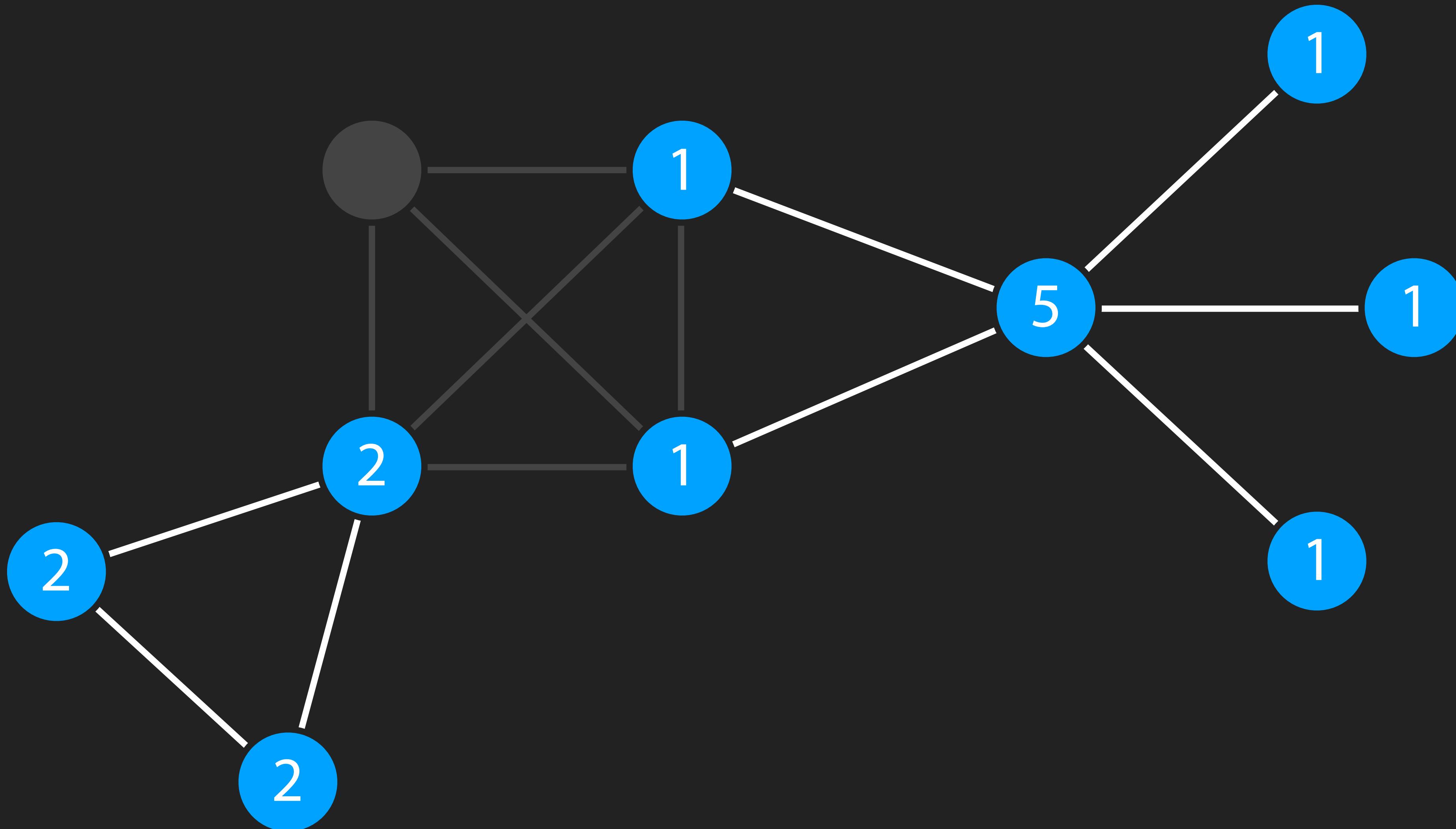
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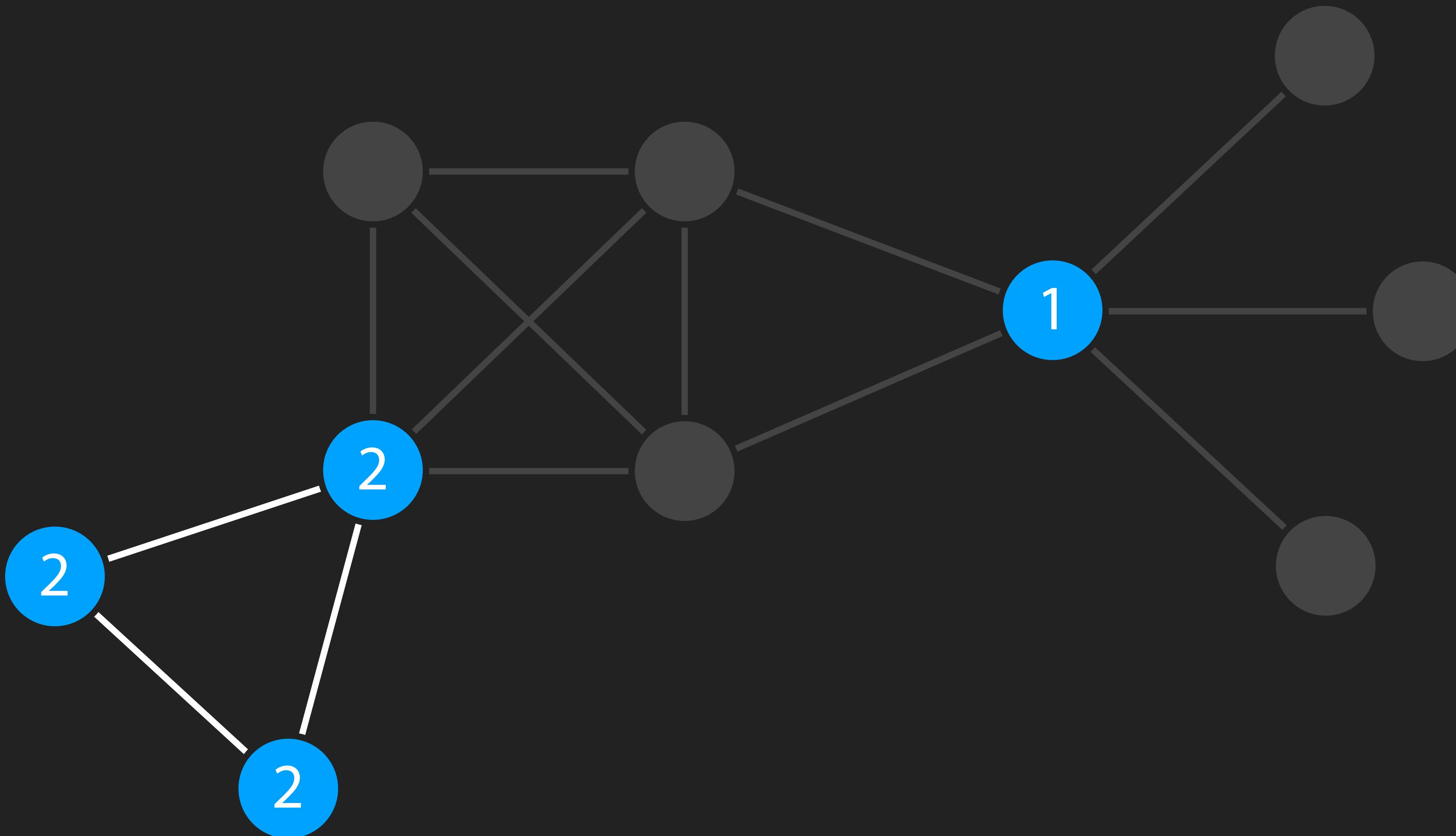
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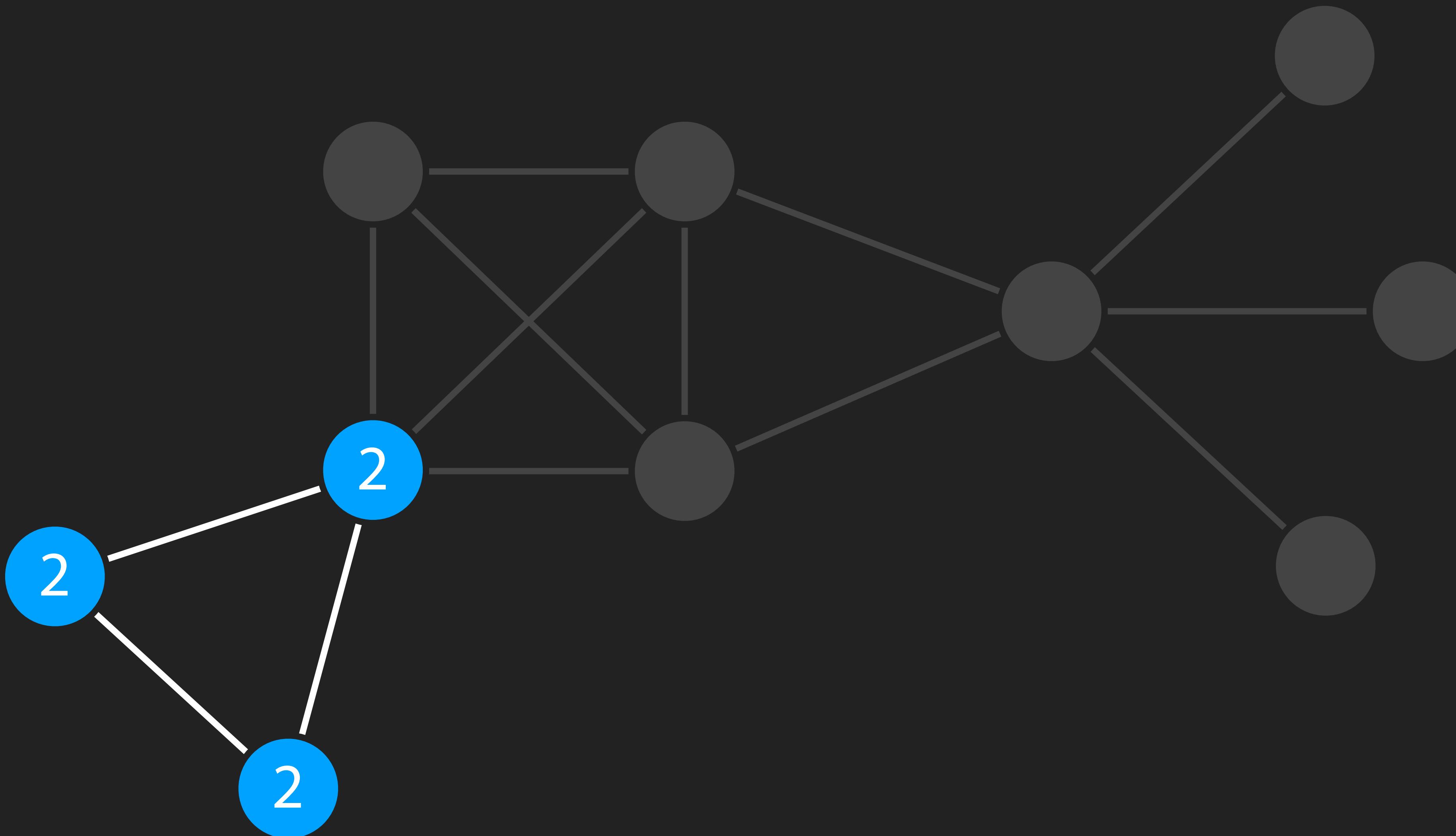
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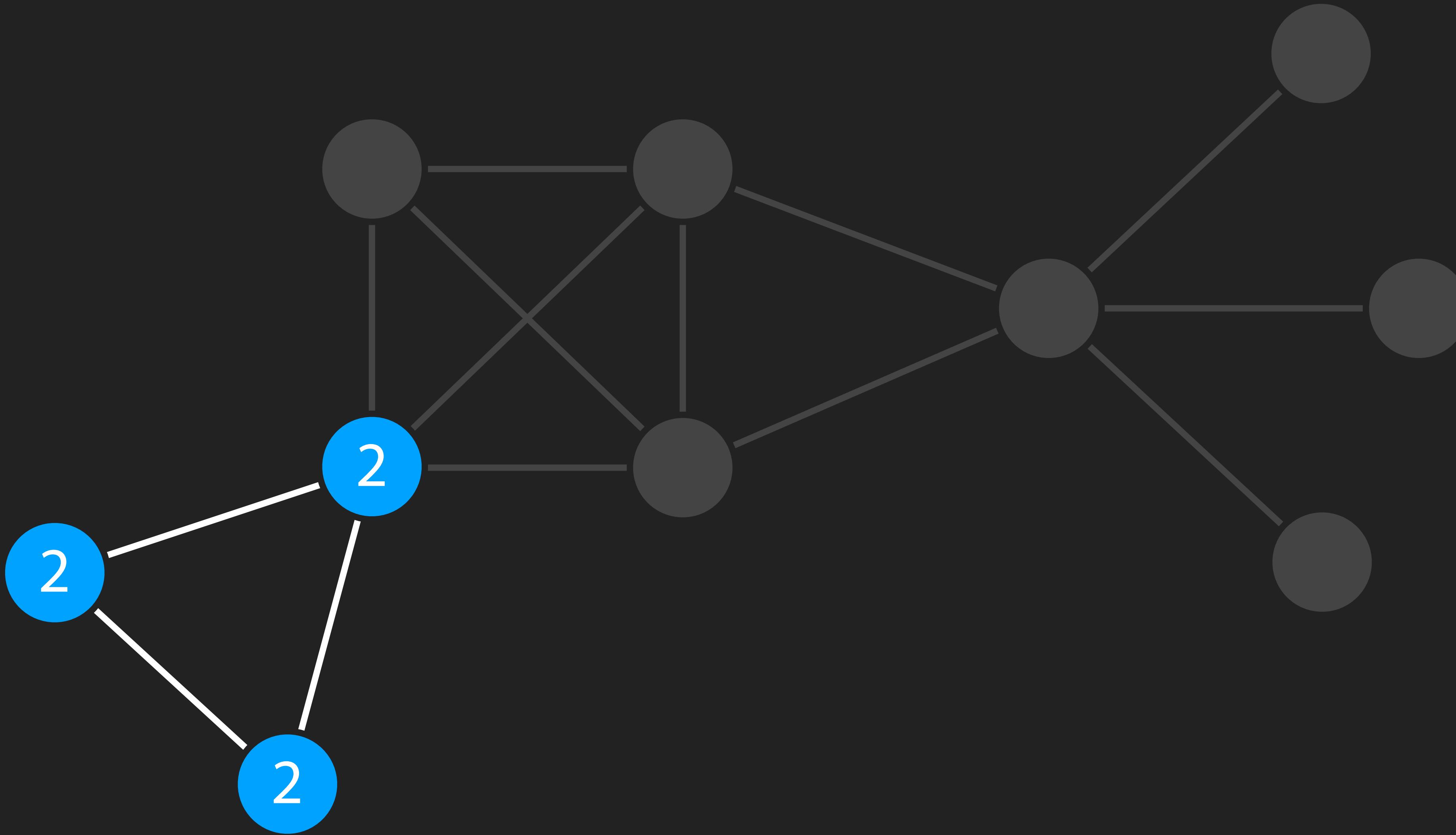
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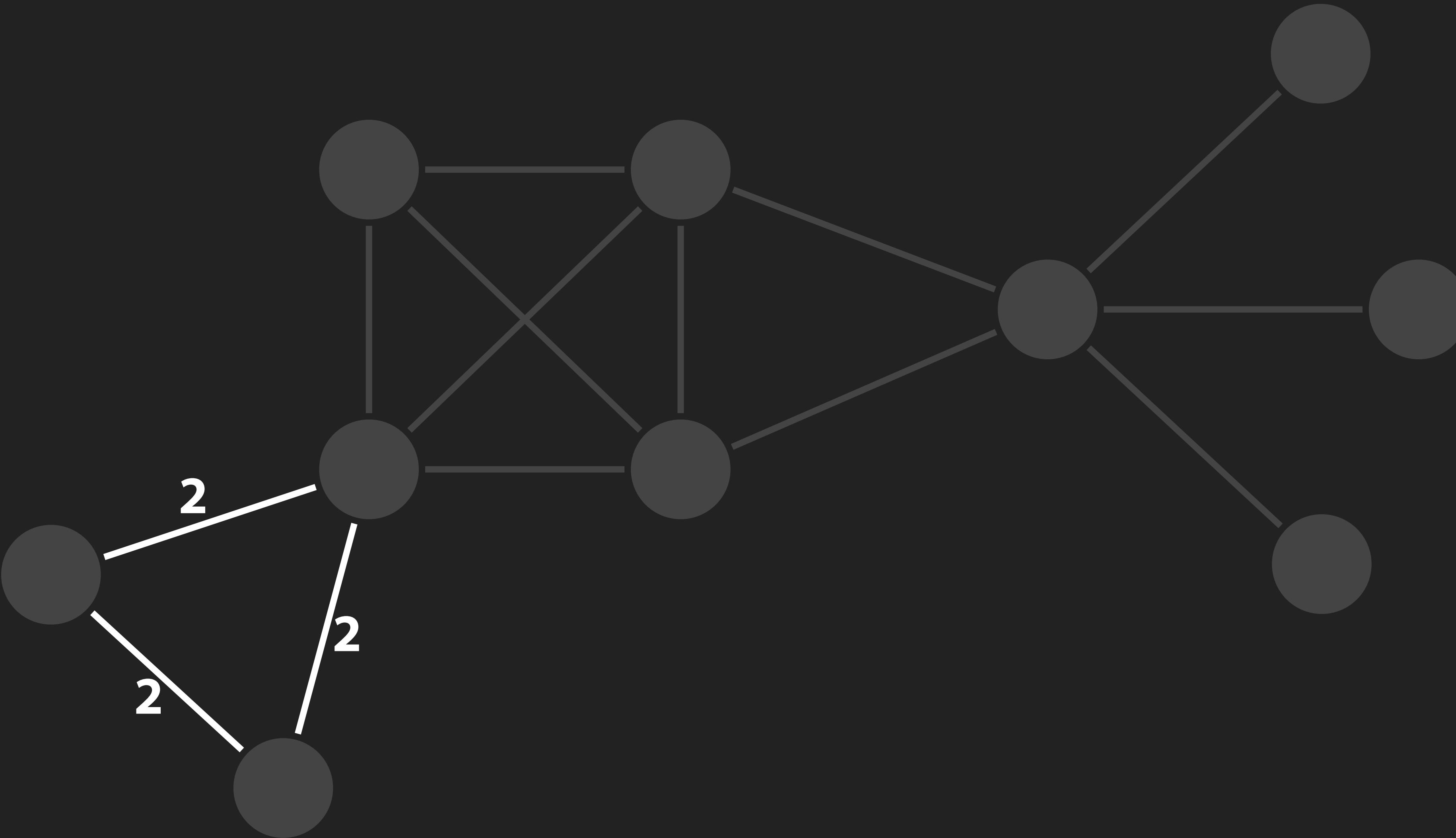
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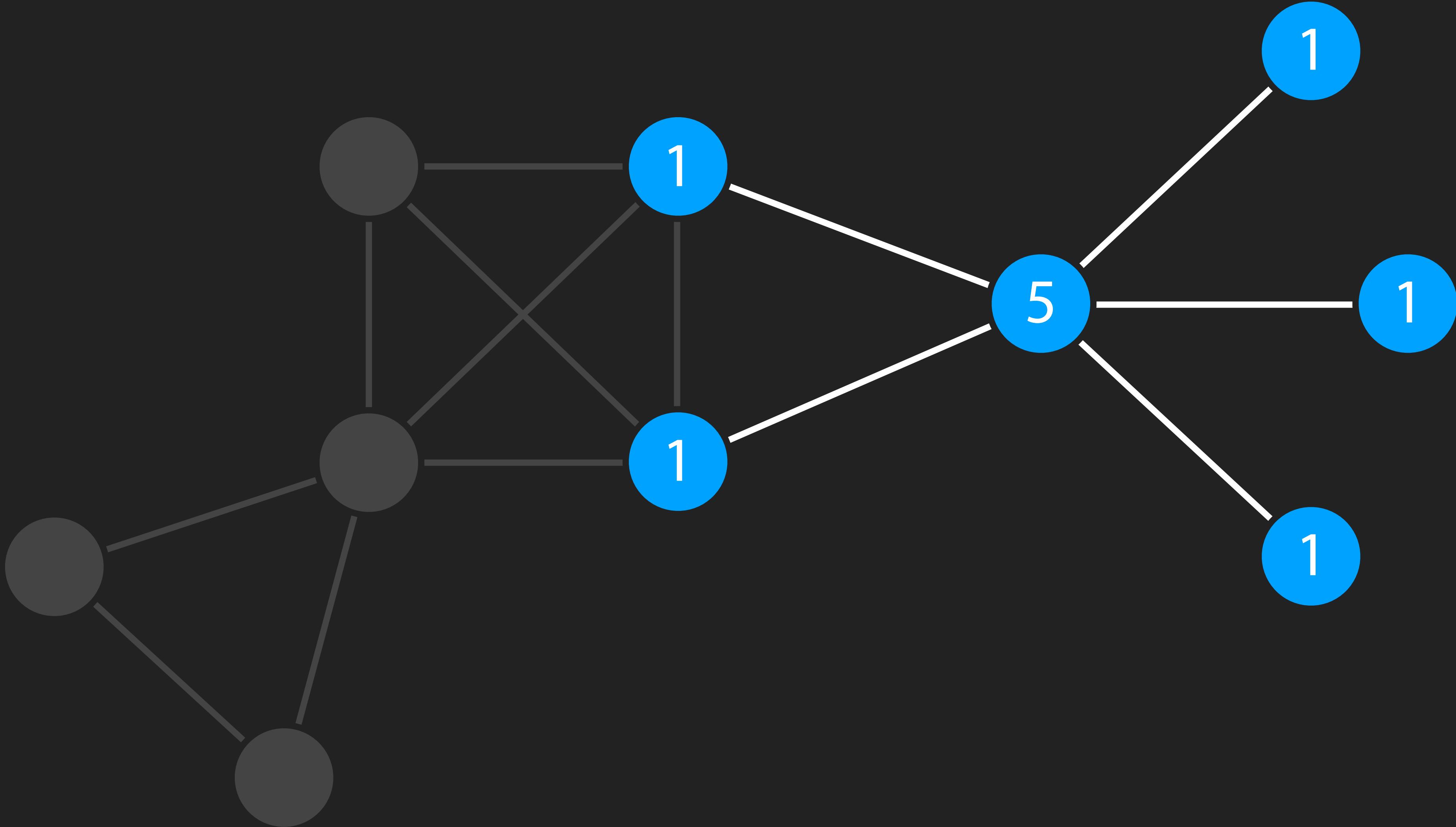
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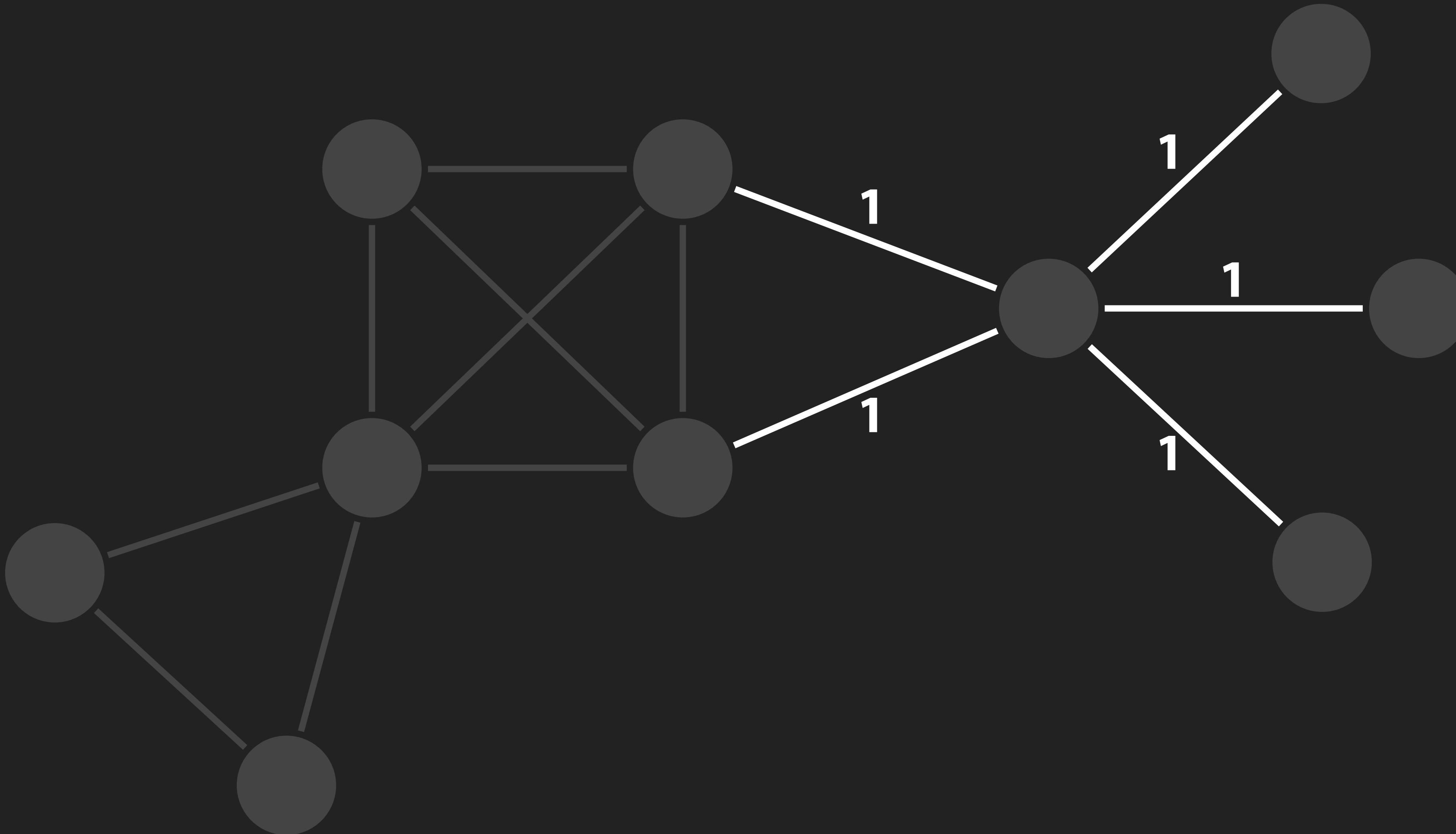
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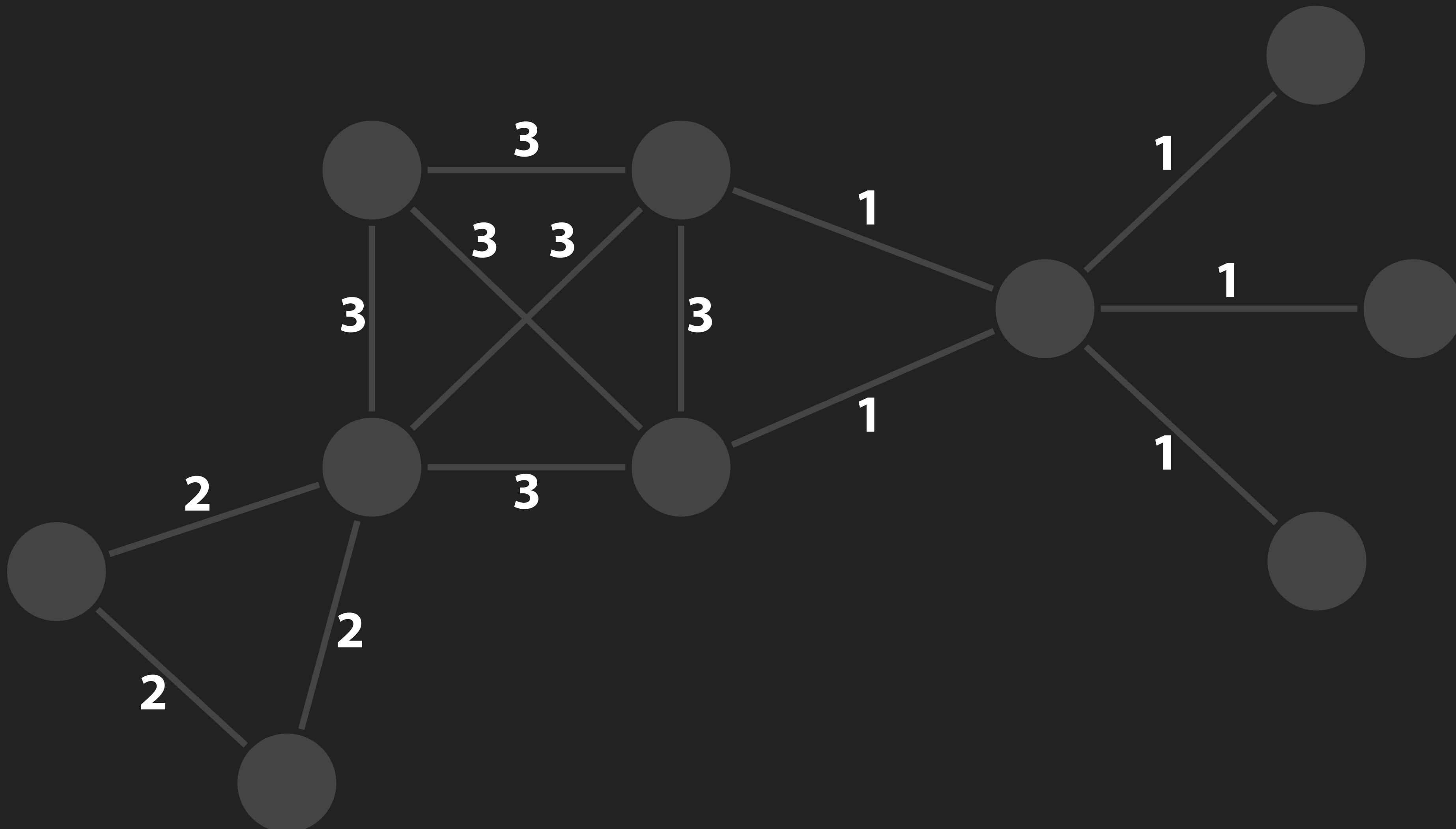


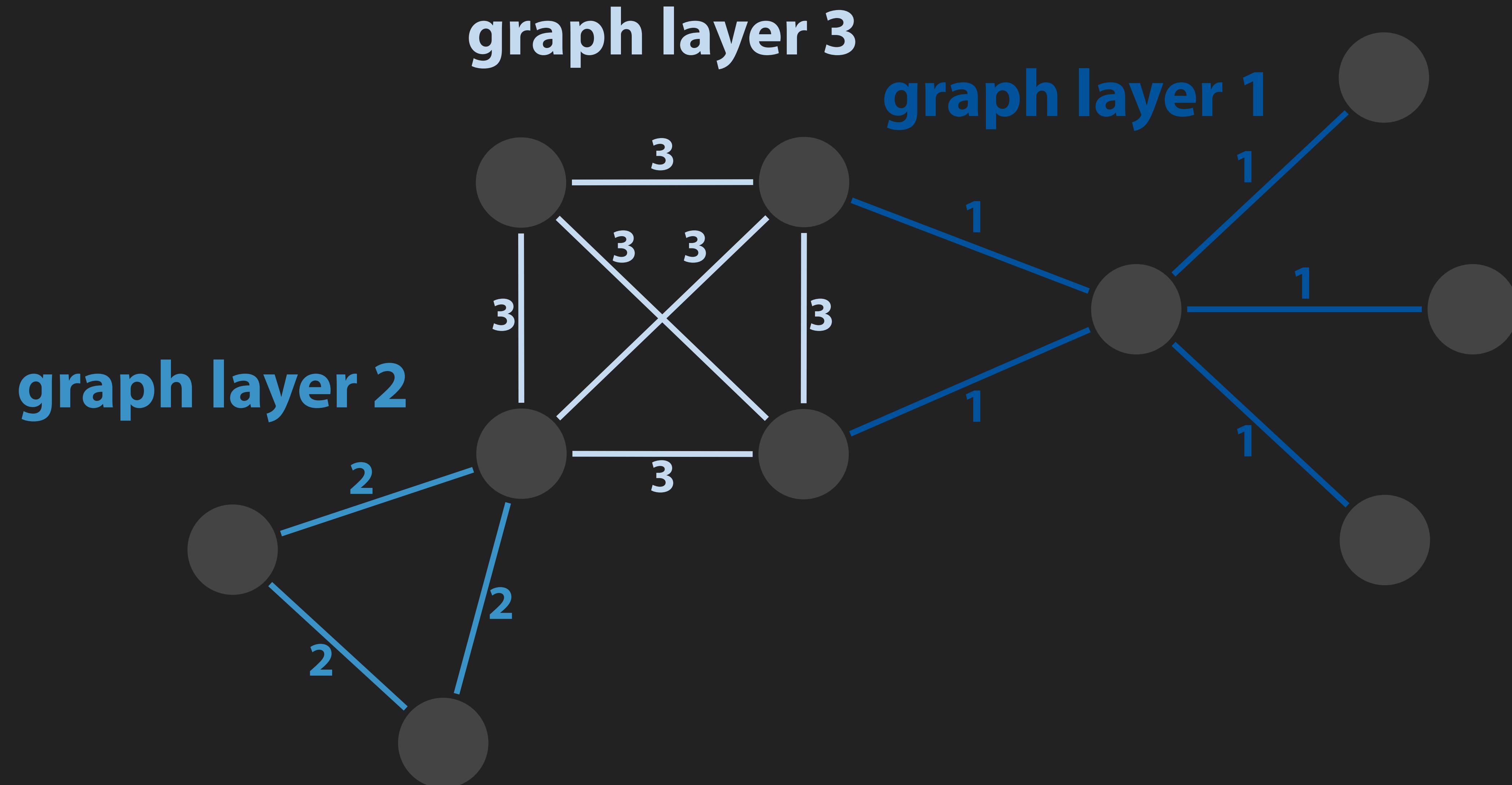
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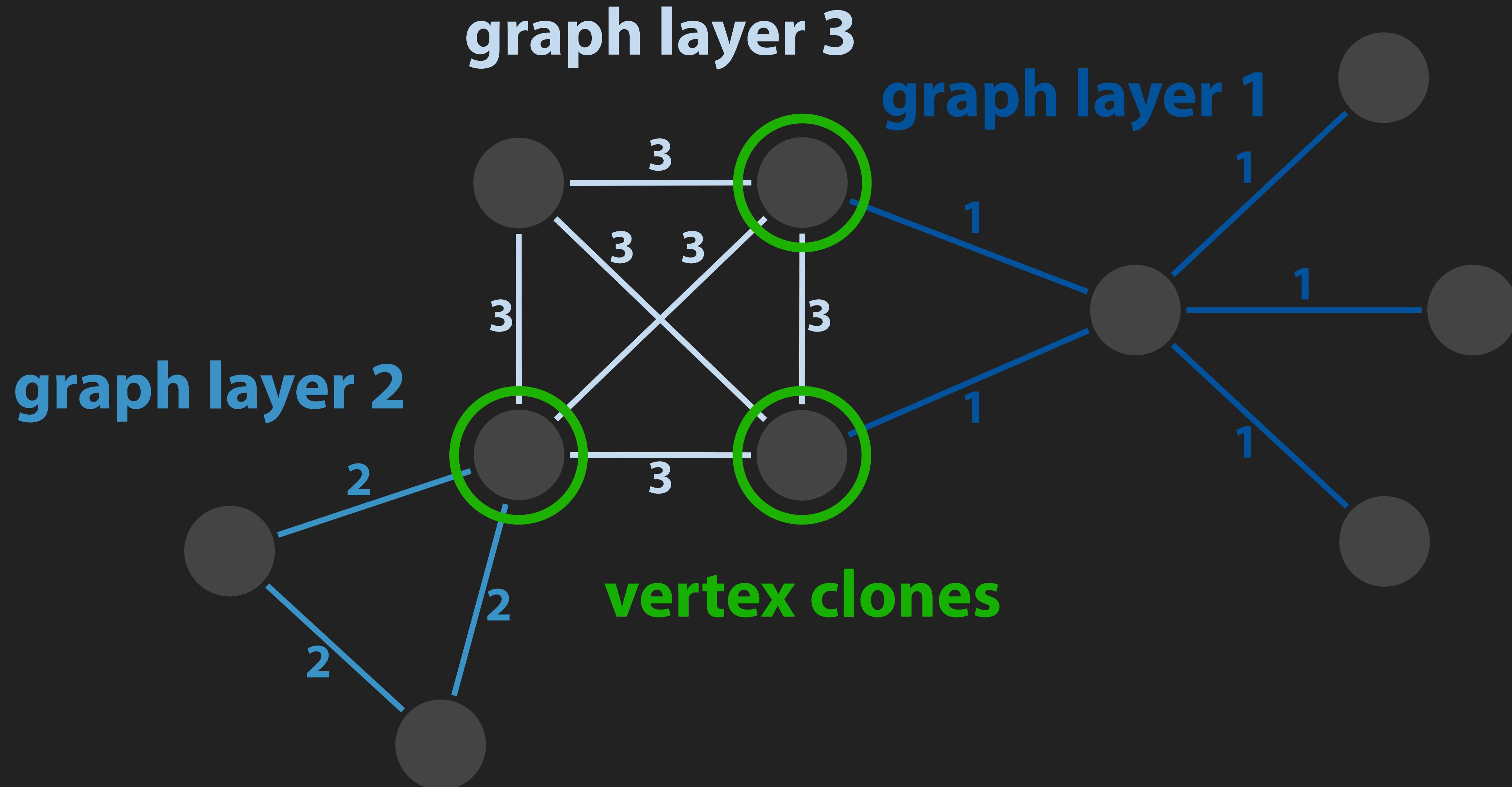


peel = 1









Graph	Vertices	Edges	Time (s)	Layers
Google+	24K	39K	~0	10
arXiv astro-ph	19K	198K	~0	47
Amazon	335K	925K	~0	6
US Patents	3.8M	17M	11	41
Wikipedia (German)	3.2M	82M	225	320
Orkut	3.1M	117M	92	91

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Time complexity: $O(\#edges \times \#layers)$
 layers << edges

Scalable K-Core Decomposition for Static Graphs Using a Dynamic Graph Data Structure

Alok Tripathy, Fred Hohman, Duen Horng Chau, and Oded Green

Georgia Institute of Technology

Abstract—The k -core of a graph is a metric used in a wide range of applications, including social network analytics, visualization, and graph coloring. We present two new parallel and scalable algorithms for finding the maximal k -core in a graph. Unlike past approaches, our new algorithms do not rebuild the graph in every iteration – rather, they use a dynamic graph data structure and avoid one of the largest performance penalties of k -core – pruning vertices and edges. We also show how to extend our algorithms to support k -core edge decomposition for different size k -cores found in the graph. While our new algorithms are architecture independent, our implementations target NVIDIA GPUs. When comparing our algorithms against several highly optimized algorithms, including the sequential igraph implementation and the multi-thread ParK implementation, our new algorithms are significantly faster. For finding the maximal k -core in the graph, our new algorithm can be up-to $58\times$ faster than igraph and up-to $4\times$ faster than ParK executed on a 36 core (72 thread) system. For the k -core decomposition algorithm, we saw even greater and more consistent speedups for our algorithm where it was up-to $130\times$ faster than igraph and up-to $8\times$ faster than ParK. Our algorithms were executed on an NVIDIA P100 GPU.

I. INTRODUCTION

Network graphs are now a ubiquitous data type and model many natural and synthetic phenomena in our modern world. However, analyzing graph data to gain insight into a network remains challenging. In a recent online survey conducted to gather information about how graphs are used in practice, researchers discovered that graph analysts rated scalability and visualization as the most pressing issues to address [1]. Modern day graphs can easily grow to billions of vertices and edges; therefore, as graphs grow in size and become more complex, the need for scalable sense-making algorithms becomes critical for gaining insight into modern day large graphs.

Modern day graph algorithms, for example *edge decomposition algorithms* based on fixed points of degree peeling, show strong potential in helping people explore unfamiliar graph data [2]. This decomposition, based on the well-studied k -core decomposition, has been shown to be useful for graph exploration, navigation, and visualization [3]. The heart of this edge decomposition algorithm requires computing the maximal k -core for a graph. From graph theory, the k -core of a graph is a maximal subgraph in which all vertices have degree at least k . k -core is not only vital to edge decomposition algorithms, but also powers a diverse set of graph exploration tools and systems with applications in large-scale visualization [4],

[5], graph clustering [6], hierarchical structure analysis [5], and graph mining [7]. It has been shown that k -core can be computed in linear time by iteratively removing minimum degree vertices from a graph using a separate list of vertices per degree [8]. This process of removing minimum degree vertices is commonly called *pruning*, and it is the primary computation by which k -core and edge decompositions rely on.

In this paper, we present two fast and scalable algorithms for finding the maximal k -core of a graph, and extend these to two edge decomposition algorithms for breaking down a graph into smaller subgraphs based on the k -core sizes. Our new algorithms do not require rebuilding the graph after pruning in each iteration of edge composition. Rather, we use a dynamic graph data structure to avoid one of the largest performance penalties of k -core decomposition.

While our new algorithms are architecture independent, our implementations target NVIDIA GPUs. Furthermore, we run extensive experiments on a wide range of graphs, with different topological properties and scales, to evaluate our algorithms. We compare against the current state-of-the-art results found in literature, including the highly optimized sequential igraph implementation and a multi-thread ParK implementation [9].

Contributions

In summary, the contributions of this paper are as follows:

- **Scalable, maximal k -core algorithms.** We introduce two fast and scalable algorithms for finding the maximal k -core of a graph. Both use a dynamic graph data structure to avoid the penalty of rebuilding the graph after each pruning phase of the algorithm. The first has parallel bottlenecks, but would likely perform well on a sequential processor. The latter performs much better in parallel and on a GPU. When compared with a sequential igraph implementation and a multi-threaded ParK[9] implementation with 72 threads, our second algorithm can be up to $58\times$ faster than igraph and up to $4\times$ faster than ParK (though it is sometimes slower than ParK).

- **Scalable k -core decomposition.** We introduce two different k -core decomposition algorithms for breaking down the graph into smaller subgraphs for different k -core sizes. These algorithms also use a dynamic graph data structure. Our first algorithm uses a large number of small edge updates, whereas our second algorithm uses a small number of large edge updates. As a GPU supports thousands of lightweight

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*IEEE International Conference on Big Data.
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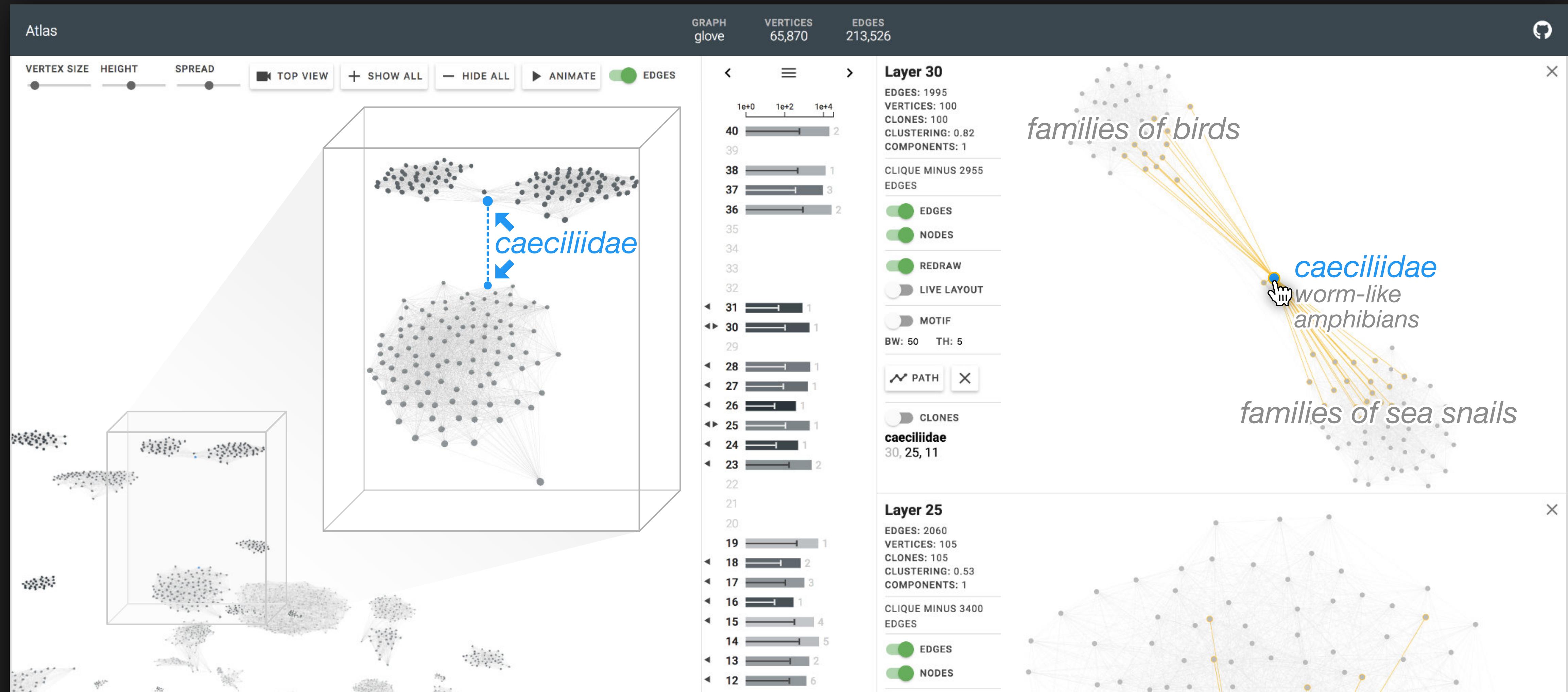
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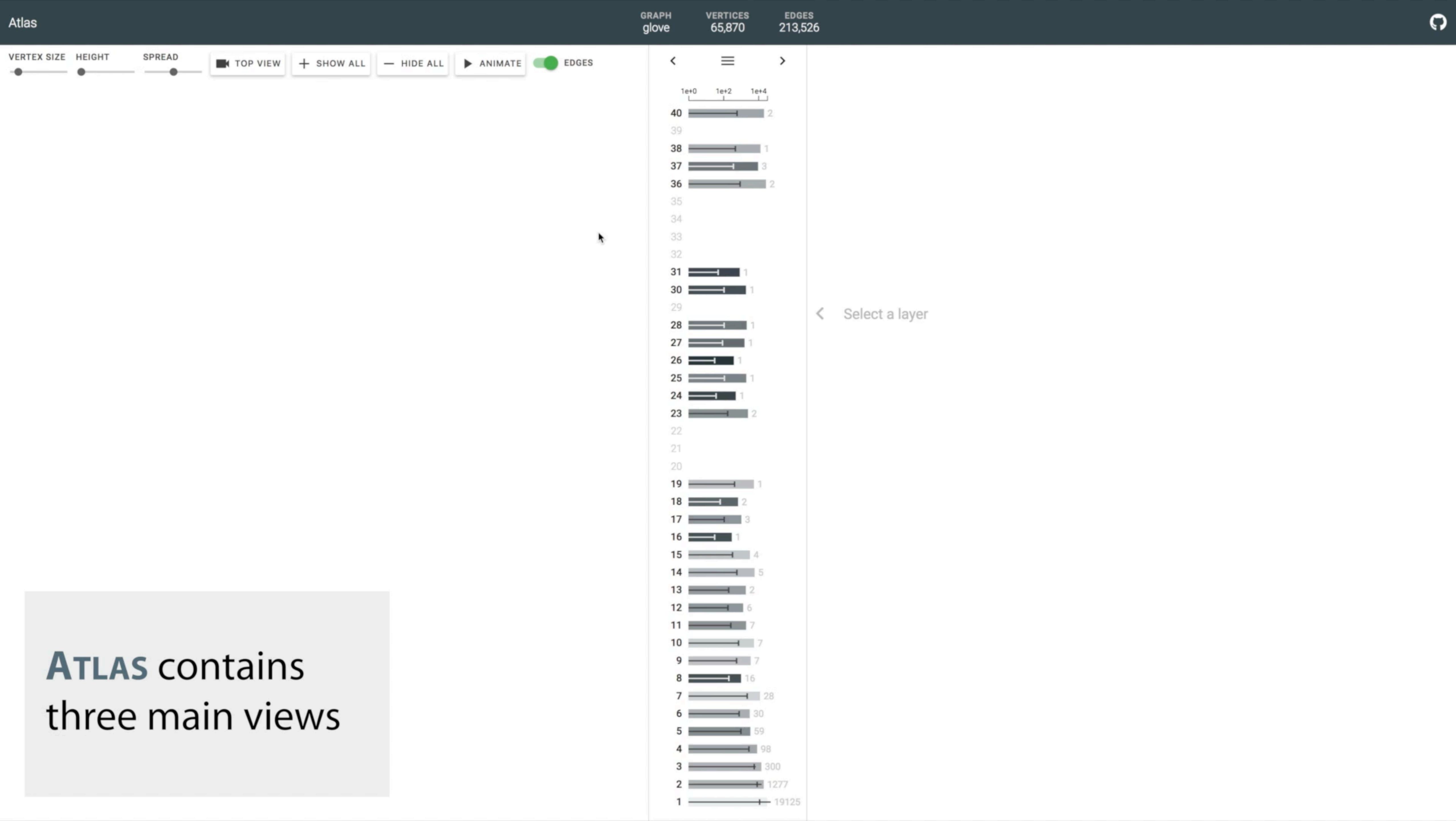
GPU + dynamic graph data structure
-> 4x - 8x speed up over Park

Demo: Understanding Word Embedding Graph

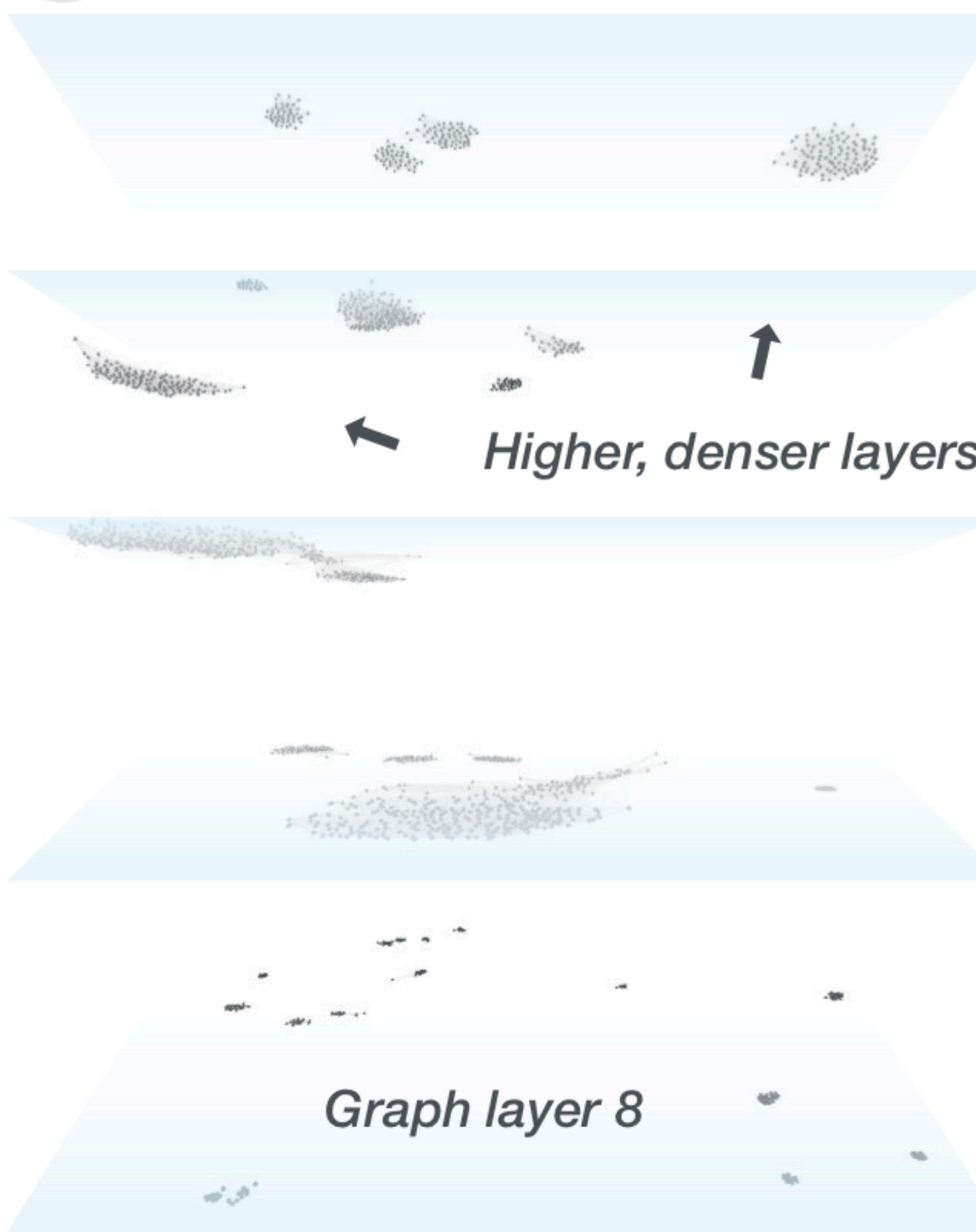
Nodes: 66K words from Wikipedia

Edges: 214K (connect words with small distance)



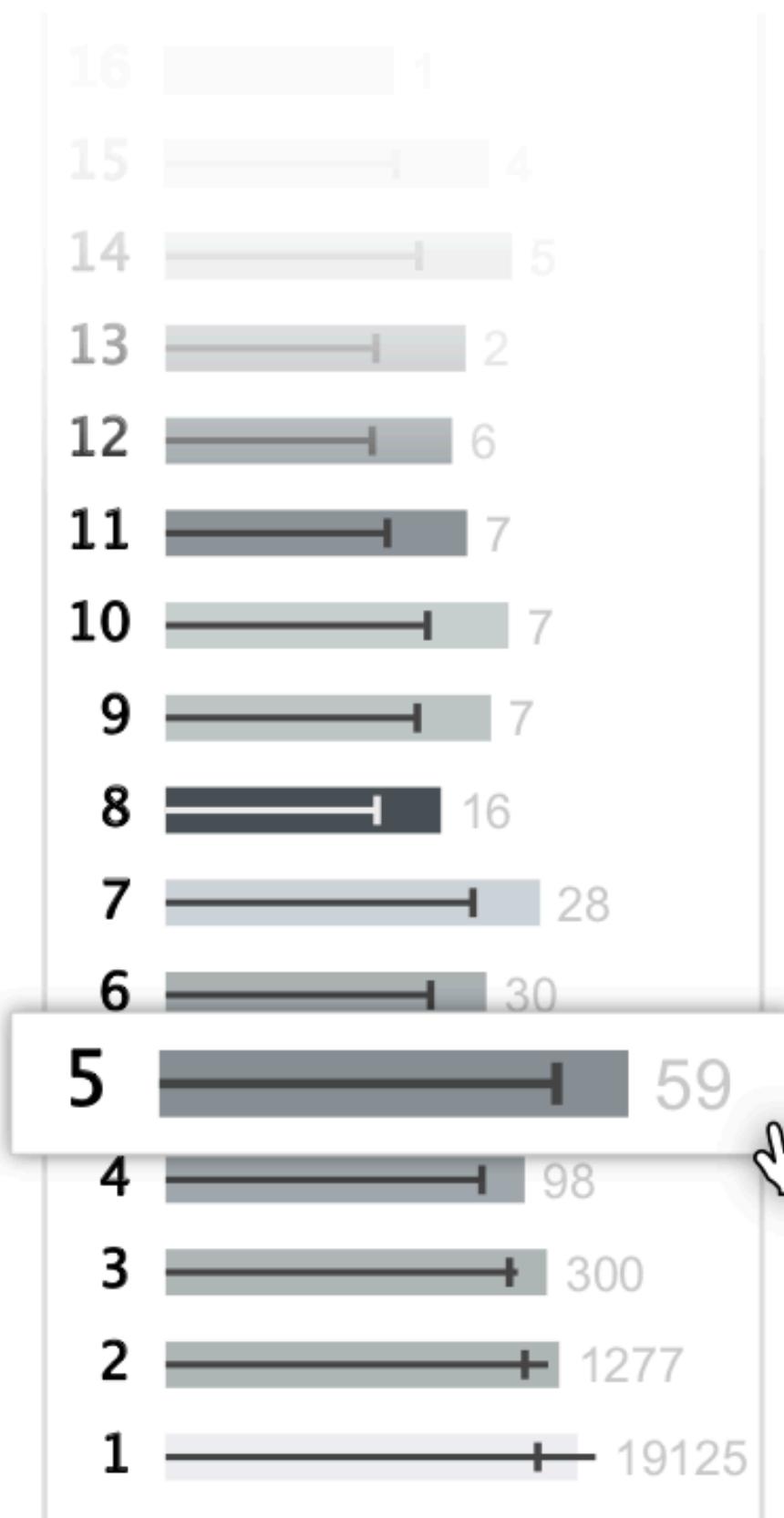


A 3D Decomposition Overview



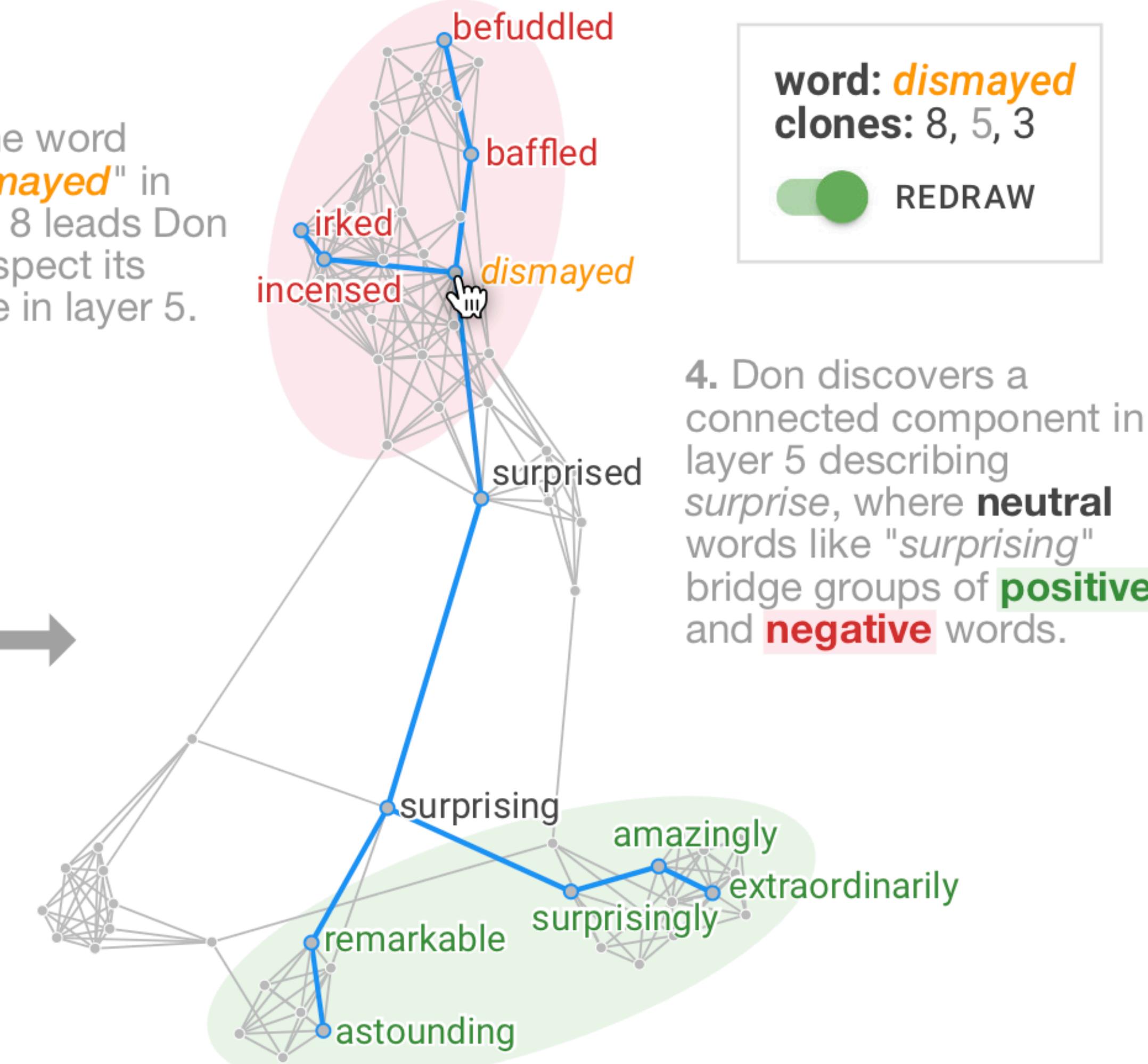
1. Don explores a word embedding graph using the 3D edge decomposition overview.

B Graph Ribbon



2. Don inspects the graph ribbon, a summarization of the graph layers using common graph measures.

C Layers and Clone View



3. The word "**dismayed**" in layer 8 leads Don to inspect its clone in layer 5.

4. Don discovers a connected component in layer 5 describing *surprise*, where **neutral** words like "surprising" bridge groups of **positive** and **negative** words.

User Study

*Goal: use **Atlas** to spot interesting patterns, mimicking their own work*

Graph Analysts



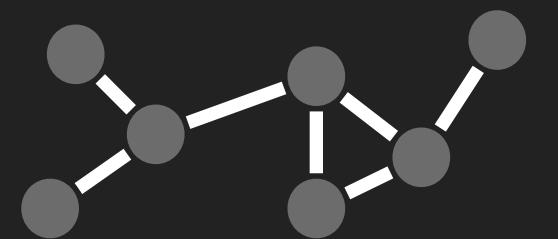
Researcher, Symantec

Researcher, NASA

Systems engineer, NASA

All PhDs + use graphs daily or weekly

Graphs



Yelp Reviews Network

SEC Insider Trading Graph

GloVe Word Embed. Graph

Intro questionnaire → **Atlas** tutorial → Study → Exit questionnaire

User Study Findings

User Study Findings

3D for overview, 2D for details

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3D for overview, 2D for details

- 3D useful for intro to new data → get a “feel” for the graph

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Identifying and linking meaningful graph substructures

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Identifying and linking meaningful graph substructures

- Vertex clones as traversal mechanism between layers

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Application to anomaly detection

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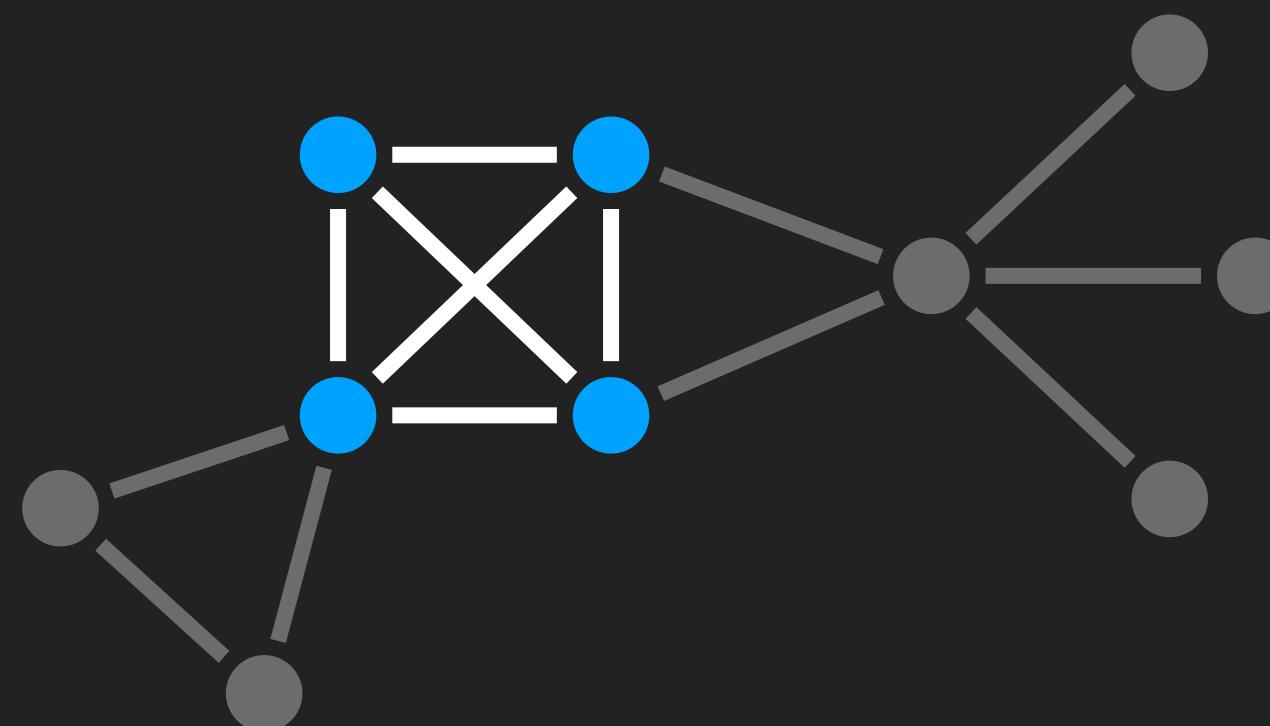
Application to anomaly detection

- *“...analysis (using [both] vertex clones and layers) naturally reveals potentially anomalous substructures and vertices. This is highly useful from a cybersecurity perspective.”*

Future Work

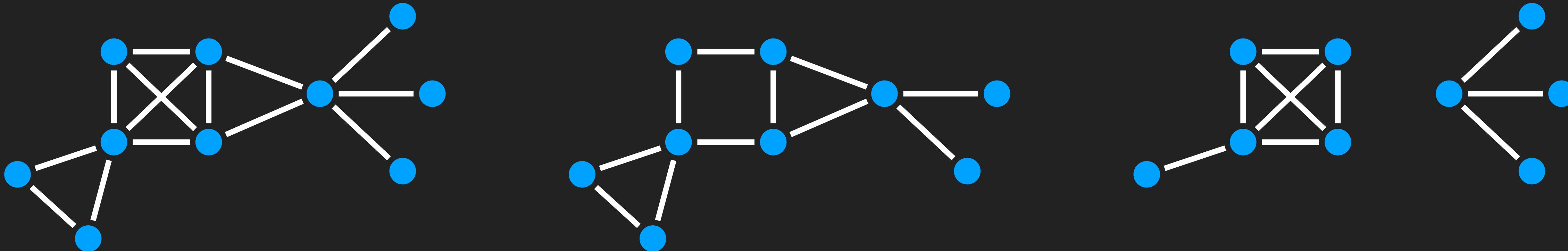
Future Work

- Automatically suggest interesting layers



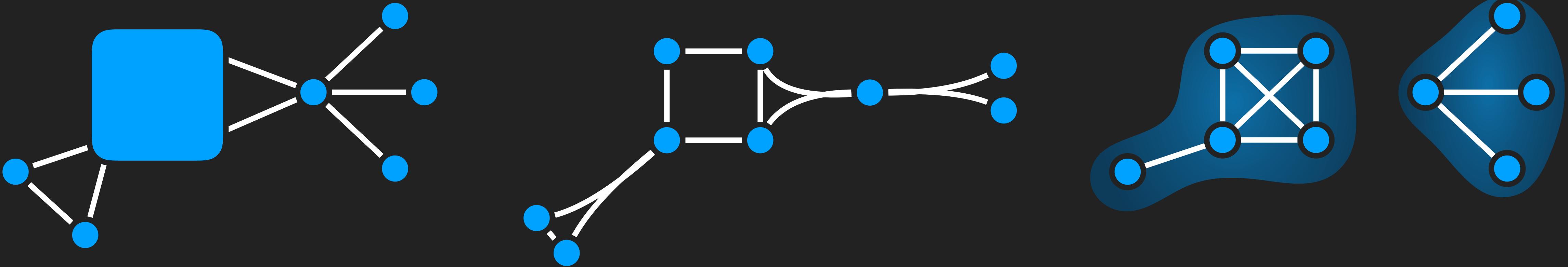
Future Work

- Automatically suggest interesting layers
- Dynamic graph decomposition visualization



Future Work

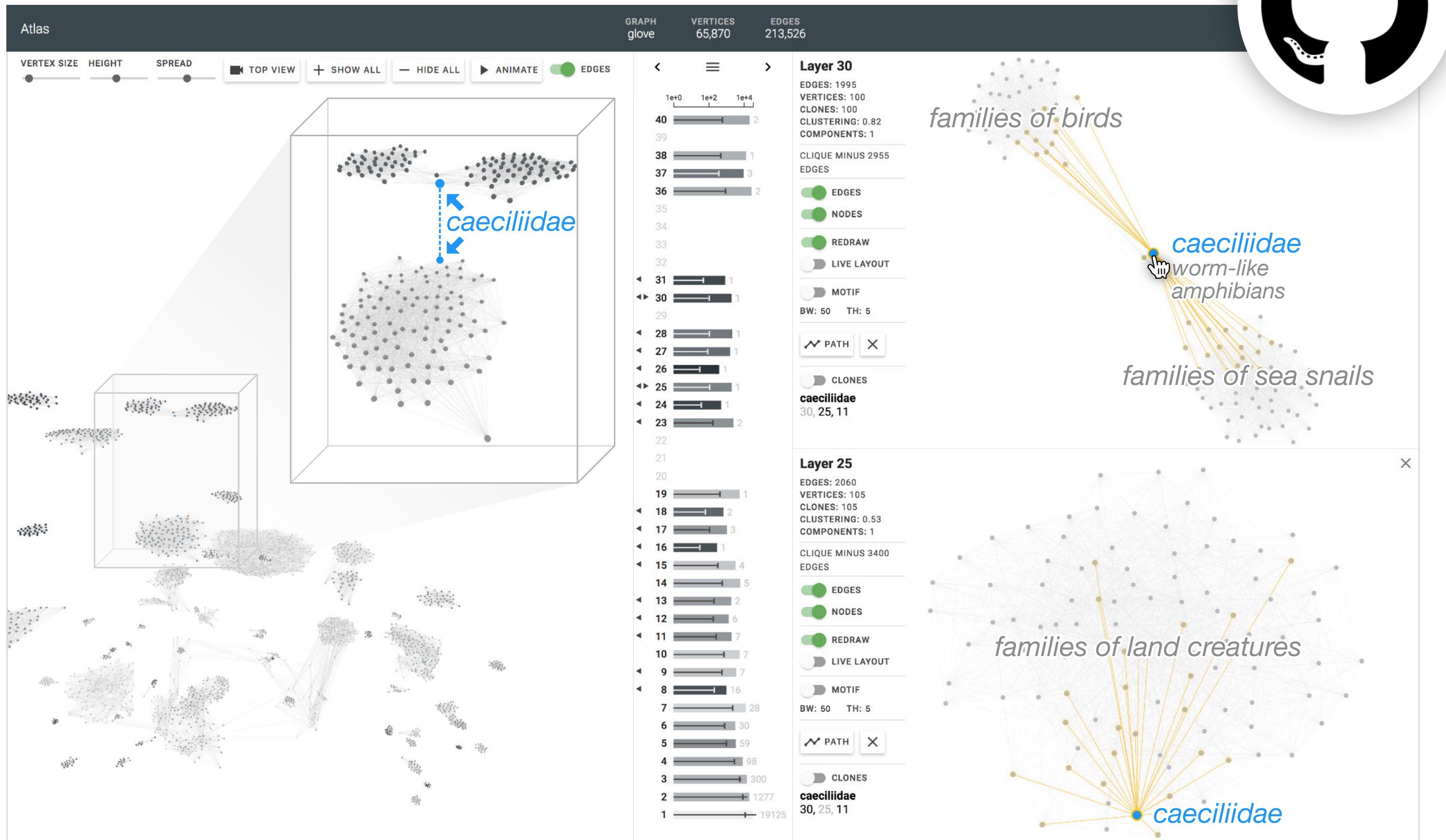
- Automatically suggest interesting layers
- Dynamic graph decomposition visualization
- Visual scalability (e.g., super-noding, edge bundling, graph motif)



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Fred Hohman

@fredhohman

fredhohman@gatech.edu



James Abello

abelloj@cs.rutgers.edu



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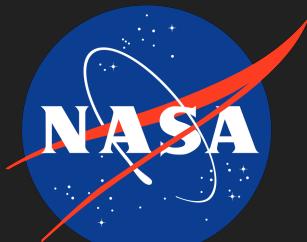


Polo Chau

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Georgia Tech

RUTGERS
THE STATE UNIVERSITY
OF NEW JERSEY



We thank the anonymous reviewers for their constructive feedback.

Thanks!