Feasibility, Optimality and Conic Duality II

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CLP Duality Theorems

The weak duality theorem shows that a feasible solution to either problem yields a bound on the value of the other problem. We call $\mathbf{c} \bullet \mathbf{x} - \mathbf{b}^T \mathbf{y}$ the duality gap.

Corollary 1 *Let $\mathbf{x}^* \in \mathcal{F}_p$ and $(\mathbf{y}^*, \mathbf{s}^*) \in \mathcal{F}_d$. Then, $\mathbf{c} \bullet x^* = \mathbf{b}^T y^*$ implies that $\mathbf{x}^*$ is optimal for (CLP) and $(\mathbf{y}^*, \mathbf{s}^*)$ is optimal for (CLD).*

Is the reverse also true? That is, given $\mathbf{x}^*$ optimal for (CLP), then there is $(\mathbf{y}^*, \mathbf{s}^*)$ feasible for (CLD) and $\mathbf{c} \bullet \mathbf{x}^* = \mathbf{b}^T \mathbf{y}^*$?

This is called the Strong Duality Theorem.

“True” when $K = \mathcal{R}^n_+$, that is, the polyhedral cone case.

Proof of Strong Duality Theorem for LP

Let (LP) have a minimizer $\mathbf{x}^* \in \mathcal{F}_p$. Then, the system

$$A\mathbf{x}' - \mathbf{b}\tau = \mathbf{0}, \quad (\mathbf{x}';\tau) \geq \mathbf{0}, \quad \mathbf{c}^T\mathbf{x}' - (\mathbf{c}^T\mathbf{x}^*)\tau = -1 < 0$$

must have no feasible solution $(\mathbf{x}';\tau)$. This is because otherwise, if $\tau > 0$, $\mathbf{x}'/\tau$ is feasible for (LP) and $\mathbf{c}^T\mathbf{x}'/\tau < \mathbf{c}^T\mathbf{x}^*$, which is a contradiction; and if $\tau = 0$, $\mathbf{x}^* + \mathbf{x}'$ is feasible for (LP) and $\mathbf{c}^T(\mathbf{x}^* + \mathbf{x}') = \mathbf{c}^T\mathbf{x}^* - 1 < \mathbf{c}^T\mathbf{x}^*$, which is also a contradiction. Thus, from the LP alternative system pair II, there is $\mathbf{y}^*$ feasible for

$$\mathbf{c} - A^T\mathbf{y}^* \geq \mathbf{0}, \quad -\mathbf{c}^T\mathbf{x}^* + \mathbf{b}^T\mathbf{y}^* \geq 0.$$

Then, $\mathbf{y}^*$ is feasible for (LD) from the first inequality; and from the weak duality theorem and the second inequality $\mathbf{c}^T\mathbf{x}^* - \mathbf{b}^T\mathbf{y}^* = 0$.

LP and LD Cases

Theorem 1 *The following statements hold for every pair of (LP) and (LD):*

i) *If (LP) or (LD) has no feasible solution, then the other is either unbounded or has no feasible solution.*

ii) *If (LP) or (LD) is feasible and bounded, then the other is feasible.*

iii) *If (LP) and (LD) both have feasible solutions then both problems have optimal solutions and the optimal objective values of the objective functions are equal, that is, optimal solutions for both (LP) and (LD) exist and there is no duality gap.*

A case that neither (LP) nor (LD) is feasible:

$$\mathbf{c} = (-1;\ 0), \quad A = (0,\ -1), \quad b = 1.$$

A pair of optimal feasible solutions can be found to the primal and dual problems with equal objective values, and there is no “gap.”

Optimality Conditions for LP

$$\left\{ (\mathbf{x}, \mathbf{y}, \mathbf{s}) \in (\mathcal{R}^n_+, \mathcal{R}^m, \mathcal{R}^n_+) : \begin{array}{rcl} \mathbf{c}^T\mathbf{x} - \mathbf{b}^T\mathbf{y} & = & 0 \\ A\mathbf{x} & = & \mathbf{b} \\ -A^T\mathbf{y} - \mathbf{s} & = & -\mathbf{c} \end{array} \right\},$$

which is a system of linear inequalities and equations. Now it is easy to verify whether or not a pair $(\mathbf{x}, \mathbf{y}, \mathbf{s})$ is optimal.

Complementarity Gap

For feasible $\mathbf{x}$ and $(\mathbf{y}, \mathbf{s})$, $\mathbf{x}^T\mathbf{s} = \mathbf{x}^T(\mathbf{c} - A^T\mathbf{y}) = \mathbf{c}^T\mathbf{x} - \mathbf{b}^T\mathbf{y}$ is called the complementarity gap.

If $\mathbf{x}^T\mathbf{s} = 0$, then we say $\mathbf{x}$ and $\mathbf{s}$ are complementary to each other.

Since both $\mathbf{x}$ and $\mathbf{s}$ are nonnegative, $\mathbf{x}^T\mathbf{s} = 0$ implies that $\mathbf{x}_. * \mathbf{s} = \mathbf{0}$ or $x_j s_j = 0$ for all $j = 1, \ldots, n$.

$$\begin{aligned} \mathbf{x}_. * \mathbf{s} &= \mathbf{0} \\ A\mathbf{x} &= \mathbf{b} \\ -A^T\mathbf{y} - \mathbf{s} &= -\mathbf{c}. \end{aligned}$$

This system has total $2n + m$ unknowns and $2n + m$ equations including n nonlinear equations.

SDP Example with a Duality Gap

The strong duality theorem may not hold for general convex cones:

$$\mathbf{c} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \mathbf{a}_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \mathbf{a}_2 = \begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

and

$$\mathbf{b} = \begin{pmatrix} 0 \\ 2 \end{pmatrix}.$$

When Strong Duality Theorems Holds for CLP

Theorem 2 *The following statements hold for every pair of (CLP) and (CLD):*

i) *Let (CLP) or (CLD) be infeasible, and furthermore the other be feasible and have an interior. Then the other is unbounded.*

ii) *Let (CLP) and (CLD) be both feasible, and furthermore one of them have an interior. Then there is no duality gap between (CLP) and (CLD).*

iii) *Let (CLP) and (CLD) be both feasible and have interior. Then, both have attainable optimal solutions with no duality gap.*

In case ii), one of the optimal solution may not attainable although no gap.

SDP Example with Zero-Duality Gap but not Attainable

$$C = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \; A_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \text{and} \quad b_1 = 2.$$

The primal has an interior, but the dual does not.

Proof of CLP Strong Duality Theorem

i) Suppose $\mathcal{F}_d$ is empty and $\mathcal{F}_p$ be feasible and have an interior. Then, we have $\bar{\mathbf{x}} \in \mathrm{int}\, K$ and $\bar{\tau} > 0$ such that $\mathcal{A}\bar{\mathbf{x}} - \mathbf{b}\bar{\tau} = \mathbf{0},\ (\bar{\mathbf{x}}, \bar{\tau}) \in \mathrm{int}(K \times R_+)$. Then, for any z^*, we have an alternative system pair

$$\mathcal{A}\mathbf{x} - \mathbf{b}\tau = \mathbf{0},\ \mathbf{c} \bullet \mathbf{x} - z^*\tau < 0,\ (\mathbf{x}, \tau) \in K \times R_+,$$

and

$$\mathcal{A}^T\mathbf{y} + \mathbf{s} = \mathbf{c},\ -\mathbf{b}^T\mathbf{y} + s = -z^*,\ (\mathbf{s}, s) \in K^* \times R_+.$$

But the latter is infeasible, so that the formal has a feasible solution for any z^*. At such an solution, if $\tau > 0$, we have $\mathbf{c} \bullet (\mathbf{x}/\tau) < z^*$; if $\tau = 0$, we have $\hat{\mathbf{x}} + \alpha\mathbf{x}$, where $\hat{\mathbf{x}}$ is any feasible solution for (CLP), being feasible for (CLP) and its objective value goes to $-\infty$ as α goes to ∞.

ii) Let $\mathcal{F}_p$ be feasible and have an interior, and let z^* be its infimum. Again, we have an alternative system pair

$$\mathcal{A}\mathbf{x} - \mathbf{b}\tau = \mathbf{0},\ \mathbf{c} \bullet \mathbf{x} - z^*\tau < 0,\ (\mathbf{x}, \tau) \in K \times R_+,$$

and

$$\mathcal{A}^T\mathbf{y} + \mathbf{s} = \mathbf{c},\ -\mathbf{b}^T\mathbf{y} + s = -z^*,\ (\mathbf{s}, s) \in K^* \times R_+.$$

But the former is infeasible, so that we have a solution for the latter. From the Weak Duality theorem, we must have $s = 0$, that is, we have a solution $(\mathbf{y}, \mathbf{s})$ such that

$$\mathcal{A}^T\mathbf{y} + \mathbf{s} = \mathbf{c},\ \mathbf{b}^T\mathbf{y} = z^*,\ \mathbf{s} \in K^*.$$

iii) We only need to prove that there exist a solution $\mathbf{x} \in \mathcal{F}_p$ such that $\mathbf{c} \bullet \mathbf{x} = z^*$, that is, the infimum of (CLP) is attainable. But this is just the other side of the proof given that $\mathcal{F}_d$ is feasible and has an interior, and z^* is also the supremum of (CLD).

Optimality Conditions for SDP

$$\begin{array}{rcl} \mathbf{c} \bullet X - \mathbf{b}^T \mathbf{y} & = & 0 \\ \mathcal{A}X & = & \mathbf{b} \\ -\mathcal{A}^T \mathbf{y} - S & = & -\mathbf{c} \\ X, S & \succeq & \mathbf{0} \end{array} , \qquad (1)$$

$$\begin{array}{rcl} XS & = & \mathbf{0} \\ \mathcal{A}X & = & \mathbf{b} \\ -\mathcal{A}^T \mathbf{y} - S & = & -\mathbf{c} \\ X, S & \succeq & \mathbf{0} \end{array} \qquad (2)$$

LP, SOCP, and SDP Examples

$$\begin{array}{ll} \text{min} & 2x_1 + x_2 + x_3 \\ \text{s. t.} & x_1 + x_2 + x_3 = 1, \\ & (x_1; x_2; x_3) \geq \mathbf{0}. \end{array} \qquad \begin{array}{ll} \text{max} & y \\ \text{s.t.} & \mathbf{e} \cdot y + \mathbf{s} = (2;\ 1;\ 1), \\ & (s_1; s_2; s_3) \geq \mathbf{0}. \end{array}$$

$$\begin{array}{ll} \text{min} & 2x_1 + x_2 + x_3 \\ \text{s.t.} & x_1 + x_2 + x_3 = 1, \\ & x_1 - \sqrt{x_2^2 + x_3^2} \geq 0. \end{array} \qquad \begin{array}{ll} \text{max} & y \\ \text{s.t.} & \mathbf{e} \cdot y + \mathbf{s} = (2;\ 1;\ 1), \\ & s_1 - \sqrt{s_2^2 + s_3^2} \geq 0. \end{array}$$

$$
\begin{array}{ll}
\text{minimize} & \begin{pmatrix} 2 & .5 \\ .5 & 1 \end{pmatrix} \cdot \begin{pmatrix} x_1 & x_2 \\ x_2 & x_3 \end{pmatrix} \\
\text{subject to} & \begin{pmatrix} 1 & .5 \\ .5 & 1 \end{pmatrix} \cdot \begin{pmatrix} x_1 & x_2 \\ x_2 & x_3 \end{pmatrix} = 1, \\
& \begin{pmatrix} x_1 & x_2 \\ x_2 & x_3 \end{pmatrix} \succeq \mathbf{0},
\end{array}
$$

$$
\begin{array}{ll}
\text{maximize} & y \\
\text{subject to} & \begin{pmatrix} 1 & .5 \\ .5 & 1 \end{pmatrix} y + \mathbf{s} = \begin{pmatrix} 2 & .5 \\ .5 & 1 \end{pmatrix}, \\
& \mathbf{s} = \begin{pmatrix} s_1 & s_2 \\ s_2 & s_3 \end{pmatrix} \succeq \mathbf{0}.
\end{array}
$$

Convex Optimization or Convex Programming

Convex Optimization: minimize a convex function over a convex constraint set/region:

$$
\begin{array}{lll}
(CO) & \text{minimize} & c_0(\mathbf{x}) \\
 & \text{subject to} & c_i(\mathbf{x}) \le b_i, i = 1, 2, ..., m,
\end{array}
$$

where $c_i(\mathbf{x})$, $i = 0, 1, ..., m$, are convex functions of $\mathbf{x}$.

An important fact for CO: any local minimizer is a global minimizer.

Sketch of Proof. Let $\hat{\mathbf{x}}$ be a local minimizer and $\mathbf{x}^*$ be the global minimizer such that $c_0(\hat{\mathbf{x}}) > c_0(\mathbf{x}^*)$. Let $\mathbf{x}(\alpha) = \alpha\mathbf{x}^* + (1-\alpha)\hat{\mathbf{x}}$. Then it is feasible and

$$c_0(\mathbf{x}(\alpha)) \le \alpha c_0(\mathbf{x}^*) + (1-\alpha)c_0(\hat{\mathbf{x}}) < c_0(\hat{\mathbf{x}}), \ \forall \alpha > 0.$$

Convex Optimization and CLP

The convex program can be rewritten as

$$\begin{array}{lll} (CO) & \text{minimize} & \alpha \\ & \text{subject to} & c_0(\mathbf{x}) - \alpha \le 0, \\ & & c_i(\mathbf{x}) \le 0, i = 1, 2, ..., m. \end{array}$$

Thus, it is sufficient to consider convex optimization in a form

$$\begin{array}{lll} (CO) & \text{minimize} & \mathbf{c}^T\mathbf{x} \\ & \text{subject to} & c_i(\mathbf{x}) \le 0, i = 1, 2, ..., m, \end{array}$$

where $c_i(\mathbf{x})$, $i = 1, ..., m$, are convex functions of $\mathbf{x}$.

Convex Optimization and CLP continued

Consider set

$$\{(\tau; \mathbf{x}) : \ \tau > 0, \ \tau c_i(\mathbf{x}/\tau) \le 0, \}$$

and K_i be its closure. Then, it is a closed and pointed convex cone !

Then, (CO) can be written as

$$\begin{array}{ll} \text{minimize} & (0; \mathbf{c}) \bullet (\tau; \mathbf{x}) \\ \text{subject to} & (1; \mathbf{0}) \bullet (\tau; \mathbf{x}) = 1, \\ & (\tau; \mathbf{x}) \in K = K_1 \cap, ..., \cap K_m, \end{array}$$

The Dual Cone

The dual cone is the set of all points $(\kappa; \mathbf{s})$ such that

$$\kappa\tau + \mathbf{s}^T\mathbf{x} \geq 0,\ \forall(\tau; \mathbf{x}) \text{ s.t. } \tau > 0,\ \tau c_i(\mathbf{x}/\tau) \leq 0,\ i = 1, ..., m.$$

Without loss of generality, we can set $\tau = 1$ and the condition becomes

$$\kappa + \mathbf{s}^T\mathbf{x} \geq 0,\ \forall\mathbf{x} \text{ s.t. } c_i(\mathbf{x}) \leq 0,\ i = 1, ..., m.$$

Then, consider the optimization problem

$$\begin{array}{rll} \psi(\mathbf{s}) := & \inf & \mathbf{s}^T\mathbf{x} \\ & \text{s.t.} & c_i(\mathbf{x}) \leq 0, i = 1, 2, ..., m, \end{array}$$

Then, the dual cone can be represented as

$$K^* = \{(\kappa; \mathbf{s}) : \ \kappa + \psi(\mathbf{s}) \geq 0\}.$$