LP Research Topics

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Online LP: An Example

	$\operatorname{Bid} 1(t=1)$	$\operatorname{Bid}\operatorname{2}(t=2)$	 Inventory(\mathbf{b})
$Price(\pi_t)$	\$100	\$30	
Decision	x_1	x_2	
Pants	1	0	 100
Shoes	1	0	 50
T-shirts	0	1	 500
Jackets	0	0	 200
Hats	1	1	 1000

Online Linear Programming Model

The classical **offline** version of the above program can be formulated as a linear (integer) program as all information data would have arrived: compute x_t , t=1,...,n and

$$\begin{aligned} & \max \text{imize}_{\mathbf{x}} & \sum_{t=1}^n \pi_t x_t \\ & \text{subject to} & \sum_{t=1}^n a_{it} x_t \leq b_i, & \forall i=1,...,m \\ & x_t \in \{0,1\} \ (0 \leq \mathbf{x}_t \leq 1), & \forall t=1,...,n. \end{aligned}$$

Now we consider the **online or streamline** and **data-driven** version of this problem:

- We only know b and n at the start
- the bidder information is revealed sequentially along with the corresponding objective coefficient.
- an irrevocable decision must be made as soon as an order arrives.

Model Assumptions

Main Assumptions

- $0 \le a_{it} \le 1$, for all (i, t);
- $\pi_t \geq 0$ for all t
- The data (\mathbf{a}_t, π_t) arrive in a **random order**.

Denote the offline LP **maximal value** by $OPT(A,\pi)$. We call an online algorithm $\mathcal A$ to be c-competitive if and only if

$$E_{\sigma}\left[\sum_{t=1}^{n} \pi_{t} x_{t}(\sigma, \mathcal{A})\right] \geq c \cdot OPT(A, \pi) \,\forall (A, \pi),$$

where σ is the **permutation** of arriving orders.

In what follows, we let

$$B = \min_{i} \{b_i\} (>0).$$

Main Results: Necessary and Sufficient Conditions

Theorem 1 For any fixed $0<\epsilon<1$, there is no online algorithm for solving the linear program with competitive ratio $1-\epsilon$ if

$$B < \frac{\log(m)}{\epsilon^2}.$$

Theorem 2 For any fixed $0 < \epsilon < 1$, there is a $1 - \epsilon$ competitive online algorithm for solving the linear program if

$$B \ge \Omega\left(\frac{m\log\left(n/\epsilon\right)}{\epsilon^2}\right).$$

Agrawal, Wang and Y [Operations Research 2014]

Key Ideas: A Worst-Case Distribution Example

The proof of the negative result is based on a **distribution** of instances (the number of each types of columns is chosen according to certain distribution) with $m=2^k$, and then show that no allocation rule can achieve $(1-\epsilon)$ -optimality in expectation under randomized permutation.

Key Ideas: A Learning Algorithm is Needed

The proof of the positive result is **constructive** and based on a learning policy.

- There is no distribution known so that any type of stochastic optimization models is not applicable.
- Unlike dynamic programming, the decision maker does not have full information/data so that a **backward recursion** can not be carried out to find an optimal sequential decision policy.
- Thus, the online algorithm needs to be learning-based, in particular, learning-while-doing.

Price Observation of Online Learning I

The problem would be easy if there is an "ideal price" vector:

	$\operatorname{Bid} 1(t=1)$	$\operatorname{Bid}\operatorname{2}(t=2)$	 Inventory(\mathbf{b})	\mathbf{p}^*
$Bid(\pi_t)$	\$100	\$30		
Decision	x_1	x_2		
Pants	1	0	 100	\$45
Shoes	1	0	 50	\$45
T-shirts	0	1	 500	\$10
Jackets	0	0	 200	\$55
Hats	1	1	 1000	\$15

Price Observation of Online Learning II

- **Pricing the bid**: The optimal dual price vector \mathbf{p}^* of the **offline** LP problem can play such a role, that is $x_t^* = 1$ if $\pi_t > \mathbf{a}_t^T \mathbf{p}^*$ and $x_t^* = 0$ otherwise, yields a near-optimal solution.
- Based on this observation, our online algorithm works by **learning** a threshold price vector $\hat{\mathbf{p}}$ and using $\hat{\mathbf{p}}$ to price the bids.
- One-time learning algorithm: learn the price vector once using the initial ϵn input.
- Dynamic learning algorithm: dynamically update the price vector at a carefully chosen pace.

One-Time Learning Algorithm

We illustrate a simple One-Time Learning Algorithm:

- Set $x_t = 0$ for all $1 \le t \le \epsilon n$;
- Solve the ϵ portion of the problem

$$\begin{array}{ll} \text{maximize}_{\mathbf{x}} & \sum_{t=1}^{\epsilon n} \pi_t x_t \\ \text{subject to} & \sum_{t=1}^{\epsilon n} a_{it} x_t \leq (1-\epsilon)\epsilon b_i \quad i=1,...,m \\ & 0 \leq x_t \leq 1 \qquad \qquad t=1,...,\epsilon n \end{array}$$

and get the optimal dual solution $\hat{\mathbf{p}}$;

ullet While inventory remains, determine x_t as:

$$x_t = \begin{cases} 0 & \text{if } \pi_t \le \hat{\mathbf{p}}^T \mathbf{a}_t \\ 1 & \text{if } \pi_t > \hat{\mathbf{p}}^T \mathbf{a}_t \end{cases}$$

One-Time Learning Algorithm Result

Theorem 3 For any fixed $\epsilon>0$, the one-time learning algorithm is $(1-\epsilon)$ competitive for solving the linear program when

$$B \ge \Omega\left(\frac{m\log\left(n/\epsilon\right)}{\epsilon^3}\right)$$

Outline of the Proof

- With high probability, we clear the market;
- With high probability, the revenue is near-optimal if we include the initial ϵ portion revenue;
- With high probability, the first ϵ portion revenue, a learning cost, doesn't contribute too much.

Then, we prove that the one-time learning algorithm is $(1-\epsilon)$ competitive under condition $B \geq \frac{6m\log(n/\epsilon)}{\epsilon^3}$.

But this is one ϵ factor higher than the **lower bound**...

Dynamic Learning Algorithm

In the dynamic price learning algorithm, we update the price at time ϵn , $2\epsilon n$, $4\epsilon n$, ..., till $2^k\epsilon \geq 1$.

At time $\ell \in \{\epsilon n, 2\epsilon n, ...\}$, the price vector is the optimal **dual solution** to the following linear program:

$$\begin{aligned} & \max \text{imize}_{\mathbf{x}} & \sum_{t=1}^{\ell} \pi_t x_t \\ & \text{subject to} & \sum_{t=1}^{\ell} a_{it} x_t \leq (1-h_\ell) \frac{\ell}{n} b_i & i=1,...,m \\ & 0 \leq x_t \leq 1 & t=1,...,\ell \end{aligned}$$

where

$$h_{\ell} = \epsilon \sqrt{\frac{n}{\ell}};$$

and this price vector is used to determine the allocation for the next **immediate** period.

Comments on Dynamic Learning Algorithm

- In the dynamic algorithm, we **update** the prices $\log_2{(1/\epsilon)}$ times during the entire time horizon.
- The numbers h_ℓ play an important role in improving the condition on B in the main theorem. It basically **balances** the probability that the inventory ever gets violated and the lost of revenue due to the factor $1 h_\ell$.
- Choosing large h_ℓ (more conservative) at the beginning periods and smaller h_ℓ (more aggressive) at the later periods, one can now control the loss of revenue by an ϵ order while the required size of B can be **weakened** by an ϵ factor.

Related Work on Random-Permutation

	Sufficient Condition	Learning
Kleinberg [2005]	$B \geq rac{1}{\epsilon^2}$, for $m=1$	Dynamic
Devanur et al [2009]	$OPT \ge \frac{m^2 \log(n)}{\epsilon^3}$	One-time
Feldman et al [2010]	$B \geq rac{m \log n}{\epsilon^3}$ and $OPT \geq rac{m \log n}{\epsilon}$	One-time
Agrawal et al [2010]	$B \geq \frac{m \log n}{\epsilon^2}$ or $OPT \geq \frac{m^2 \log n}{\epsilon^2}$	Dynamic
Molinaro and Ravi [2013]	$B \ge \frac{m^2 \log m}{\epsilon^2}$	Dynamic
Kesselheim et al [2014]	$B \ge \frac{\log m}{\epsilon^2}$	Dynamic*
Gupta and Molinaro [2014]	$B \ge \frac{\log m}{\epsilon^2}$	Dynamic*
Agrawal and Devanur [2014]	$B \ge \frac{\log m}{\epsilon^2}$	Dynamic*

Table 1: Comparison of several existing results

Open Questions on Online LP

- Is a **Price Mechanism** similar to Prediction Market to achieve optimal learning?
- Buy-and-sell or double market?
- **Price-posting** market?

The ADMM for LP Primal I

 $(LP) \quad \text{minimize} \quad \mathbf{c} \bullet \mathbf{x}$ $\text{subject to} \quad A\mathbf{x} = \mathbf{b}, \ \mathbf{x} \geq \mathbf{0},$

We consider an equivalent problem:

(LP) minimize $\mathbf{c} ullet \mathbf{x}_1$ subject to $A\mathbf{x}_1 = \mathbf{b}, \ \mathbf{x}_1 - \mathbf{x}_2 = \mathbf{0}, \ \mathbf{x}_2 \geq \mathbf{0},$

The ADMM for LP Primal II

Consider its Augmented Lagrangian for the primal

$$L^{p}(\mathbf{x}_{1}, \mathbf{x}_{2}, \mathbf{y}, \mathbf{s}) = \mathbf{c}^{T} \mathbf{x}_{1} - \mathbf{y}^{T} (A\mathbf{x}_{1} - \mathbf{b}) - \mathbf{s}^{T} (\mathbf{x}_{1} - \mathbf{x}_{2}) + \frac{\beta}{2} ||A\mathbf{x}_{1} - \mathbf{b}||^{2} + \frac{\beta}{2} ||\mathbf{x}_{1} - \mathbf{x}_{2}||^{2}.$$

Then, for any given $(\mathbf{x}_1^k, \mathbf{x}_2^k \in K, \mathbf{y}^k, \mathbf{s}^k)$, we compute a new iterate pair

$$\mathbf{x}_{1}^{k+1} = \arg\min_{\mathbf{x}_{1}} L^{p}(\mathbf{x}_{1}, \mathbf{x}_{2}^{k}, \mathbf{y}^{k}, \mathbf{s}^{k}), \quad \mathbf{x}_{2}^{k+1} = \arg\min_{\mathbf{x}_{2} \geq \mathbf{0}} L^{p}(\mathbf{x}_{1}^{k+1}, \mathbf{x}_{2}, \mathbf{y}^{k}, \mathbf{s}^{k})$$

and

$$\mathbf{y}^{k+1} = \mathbf{y}^k - \beta(A\mathbf{x}_1^{k+1} - \mathbf{b}), \quad \mathbf{s}^{k+1} = \mathbf{s}^k - \beta(\mathbf{x}_1^{k+1} - \mathbf{x}_2^{k+1}).$$

The minimization over \mathbf{x}_1 is a unconstrained optimization, and the minimization over \mathbf{x}_2 is easy!

The ADMM for LP Dual

Consider the dual problem and its Augmented Lagrangian

$$(LD)$$
 maximize $\mathbf{b}^T\mathbf{y}$ subject to $A^T\mathbf{y}+\mathbf{s}=\mathbf{c},\ \mathbf{s}\geq\mathbf{0},$

$$L^{d}(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{b}^{T}\mathbf{y} - \mathbf{x}^{T}(A^{T}\mathbf{y} + \mathbf{s} - \mathbf{c}) + \frac{\beta}{2}||A^{T}\mathbf{y} + \mathbf{s} - \mathbf{c}||^{2}.$$

Then, starting from y^0 , $s^0 \ge 0$, and multiplier x^0 , do the iterative update:

$$\mathbf{y}^{k+1} = \arg\min_{\mathbf{y}} L^d(\mathbf{y}, \mathbf{s}^k, \mathbf{x}^k), \quad \mathbf{s}^{k+1} = \arg\min_{\mathbf{s} \ge \mathbf{0}} L^d(\mathbf{y}^{k+1}, \mathbf{s}, \mathbf{x}^k),$$
$$\mathbf{x}^{k+1} = \mathbf{x}^k - \beta (A^T \mathbf{y}^{k+1} + \mathbf{s}^{k+1} - \mathbf{c}).$$

The minimization over y is a least-squares problem with constant matrix, and the update of s has a simple close form. (x would be non-positive since we changed maximization to minimization of the dual.)

The Interior-Point ADMM for CLP Dual I

Now consider solving CLP with the logarithmic barrier function $B(\mathbf{s}) = \sum_j \ln(s_j)$ and fixed positive constant μ :

$$(BLD) \quad \text{maximize} \quad \mathbf{b}^T\mathbf{y} + \mu B(\mathbf{s})$$
 subject to
$$A^T\mathbf{y} + \mathbf{s} = \mathbf{c}, \ \mathbf{s} > \mathbf{0},$$

and its Augmented Lagrangian

$$L_{\mu}^{d}(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{b}^{T}\mathbf{y} - \mu B(\mathbf{s}) - \mathbf{x}^{T}(A^{T}\mathbf{y} + \mathbf{s} - \mathbf{c}) + \frac{\beta}{2} ||A^{T}\mathbf{y} + \mathbf{s} - \mathbf{c}||^{2}.$$

When applying ADMM to (BCLD), again minimization over ${\bf y}$ is a least-squares problem with constant matrix, and the update of ${\bf s}>0$ has a simple close form.

The Interior-Point ADMM for CLP Dual II

Now, we gradually reduced μ as an outer iteration. That is, we start some $\mu=\mu^0$ and apply the ADMM to compute an approximate optimizer, with its multiplier, for barrier-dual (BCLD). Now set $\mu=\mu^1=\gamma\mu^0$ where $0<\gamma<1$. Then we use the approximate optimizer and multiplier as the initial point to start ADMM barrier-dual (BCLD) with the newly reduced μ .

Does it work?