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# Homework #1

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Sam Fleischer

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### Problem 1

Let  $L$  be the linear operator  $Lu = u_{xx}$ ,  $u_x(0) = u_x(1) = 0$ .

- (a) Find the eigenfunctions and corresponding eigenvalues of  $L$ .  
 (b) Show that the eigenfunctions are orthogonal in the  $L^2[0, 1]$  inner product

$$\langle u, v \rangle = \int_0^1 u(x)v(x)dx.$$

- (c) It can be shown that the eigenfunctions  $\phi_j(x)$ , form a complete set in  $L^2[0, 1]$ . This means that for any  $f \in L^2[0, 1]$ ,  $f(x) = \sum_j \alpha_j \phi_j(x)$ . Express the solution to

$$u_{xx} = f, u_x(0) = u_x(1) = 0,$$

as a series solution of the eigenfunctions.

- (d) Note that this BVP does not have a solution for all  $f$ . Express the condition for existence of a solution in terms of the eigenfunctions of  $L$ .

- (a) Let  $Lu = \lambda u$ . Then

$$\begin{aligned} u_{xx} - \lambda u &= 0 \\ \Rightarrow u(x) &= A \exp[\sqrt{\lambda}x] + B \exp[-\sqrt{\lambda}x] \end{aligned}$$

If  $\lambda > 0$  then  $u_x(x) = \sqrt{\lambda} [A \exp[\sqrt{\lambda}x] - B \exp[-\sqrt{\lambda}x]]$  and the boundary condition  $u_x(0) = 0$  implies  $A = B$  and so  $u_x(x) = A\sqrt{\lambda} [\exp[\sqrt{\lambda}x] - \exp[-\sqrt{\lambda}x]]$ . Then the boundary condition  $u_x(1) = 0$  implies  $A = 0$ , thus there are no solutions.

If  $\lambda = 0$  then  $u(x) = A + Bx$  and the boundary conditions implies  $B = 0$ . Thus  $u(x) = A$  where  $A$  is a constant is an eigenfunction.

If  $\lambda < 0$  then  $u(x) = A \sin(\sqrt{-\lambda}x) + B \cos(\sqrt{-\lambda}x)$  and thus  $u_x(x) = \sqrt{-\lambda} [A \cos(\sqrt{-\lambda}x) - B \sin(\sqrt{-\lambda}x)]$ . Then the boundary conditions imply  $A = 0$  and  $\sqrt{-\lambda} = k\pi$  for  $k \in \mathbb{N}$ . Thus the eigenfunctions are

$$u_k(x) = \cos(k\pi x) \quad \text{for } k = 0, 1, 2, \dots \text{ with corresponding eigenvalues } \lambda_k = -k^2\pi^2$$

- (b) Assume  $k \neq j$ . Then

$$\begin{aligned} \langle \cos(k\pi x), \cos(j\pi x) \rangle &= \int_0^1 \cos(k\pi x) \cos(j\pi x) dx \\ &= \frac{1}{2} \int_0^1 \cos((k+j)\pi x) + \cos((k-j)\pi x) dx \\ &= \frac{1}{2} \left[ \frac{\sin((k+j)\pi x)}{(k+j)\pi} \Big|_0^1 + \frac{\sin((k-j)\pi x)}{(k-j)\pi} \Big|_0^1 \right] \\ &= \frac{1}{2(k+j)\pi} [\sin((k+j)\pi)] + \frac{1}{2(k-j)\pi} [\sin((k-j)\pi)] \end{aligned}$$

Since  $k \neq j$  then  $k+j$  and  $k-j$  are nonzero integers and thus  $\langle u_k, u_j \rangle = 0$ . If  $k = j$ , then

$$\langle \cos(k\pi x), \cos(k\pi x) \rangle = \int_0^1 \cos^2(k\pi x) dx = \frac{1}{2} \int_0^1 1 + \cos(2k\pi x) dx = \frac{1}{2}$$

Thus  $\sqrt{2}u_k$  are orthonormal.

(c) Let  $u = \sum_j \alpha_j \cos(j\pi x)$ , and let  $f = \sum_j \beta_j \cos(j\pi x)$ . Then  $u_{xx} = -\sum_j \alpha_j j^2 \pi^2 \cos(j\pi x)$ . Then

$$-\sum_j \alpha_j j^2 \pi^2 \cos(j\pi x) = \sum_j \beta_j \cos(j\pi x)$$

Since  $\cos(j\pi x)$  are orthonormal, each term in the series must match, and thus

$$\alpha_j = -\frac{\beta_j}{j^2 \pi^2}$$

So, the solution to  $Lu = f$  where  $f = \sum_j \beta_j \cos(j\pi x)$  is

$$u(x) = -\sum_j \frac{\beta_j}{j^2 \pi^2} \cos(j\pi x)$$

(d) Since  $L$  is self-adjoint, then  $Lu = f$  is solvable if  $f \perp \ker L$  where  $\ker L = [1]$ , that is, the kernel of  $L$  is spanned by the constant function 1.  $f \perp \ker L$  if

$$\langle f, 1 \rangle = \int_0^1 f(x) dx = 0$$

that is, the mean of  $f(x)$  is zero. In terms of the eigenfunctions,

$$\langle f, \cos(0\pi x) \rangle = 0.$$

## Problem 2

Define the functional  $F : X \rightarrow \mathbb{R}$  by

$$F(u) = \int_0^1 \frac{1}{2} (u_x)^2 + f u dx,$$

where  $X$  is the space of real-valued functions on  $[0, 1]$  that have at least one continuous derivative and are zero at  $x = 0$  and  $x = 1$ . The Frechet derivative of  $F$  at a point  $u$  is defined to be the linear operator  $F'(u)$  for which

$$F(u + v) = F(u) + F'(u)v + R(v),$$

where

$$\lim_{\|v\| \rightarrow 0} \frac{\|R(v)\|}{\|v\|} = 0.$$

One way to compute the derivative is

$$F'(u)v = \lim_{\varepsilon \rightarrow 0} \frac{F(u + \varepsilon v) - F(u)}{\varepsilon}.$$

Note that this looks just like a directional derivative.

- (a) Compute the Frechet derivative of  $F$ .
- (b)  $u \in X$  is a critical point of  $F$  if  $F'(u)v = 0$  for all  $v \in X$ . Show that if  $u$  is a solution to the Poisson equation  $u_{xx} = f$ ,  $u(0) = u(1) = 0$ , then it is a critical point of  $F$ .
- (c) Let  $X_h$  be a finite dimensional subspace of  $X$ , and let  $\{\phi_i(x)\}$  be a basis for  $X_h$ . This means that all  $u_h \in X_h$  can be expressed as  $u_h(x) = \sum_i u_i \phi_i(x)$  for some constants  $u_i$ . Thus we can identify the elements of  $X_h$  with vectors  $\vec{u}$  that have components  $u_i$ . Let  $G(\vec{u}) = F(u_h)$ . Show that the gradient of  $G$  (whos components are  $(\nabla G)_j = \frac{\partial G}{\partial u_j}$ ) is of the form  $\nabla G(\vec{u}) = A\vec{u} + \vec{b}$ , and write expressions for the elements of the matrix  $A$  and the vector  $\vec{b}$ .
- (d) Divide the unit interval into a set of  $N + 1$  equal length intervals  $I_i = (x_i, x_{i+1})$  for  $i = 0, \dots, N$ . The endpoints of the intervals are  $x_i = ih$ , where  $h = \frac{1}{N+1}$ . Let  $X_h$  be the subspace of  $X$  such that the elements  $u_h$  of  $X_h$  are linear on each interval, continuous on  $[0, 1]$ , and satisfy  $u_h(0) = u_h(1) = 0$ .  $X_h$  is an  $N$  dimensional space with basis elements

$$\phi_i(x) = \begin{cases} 1 - h^{-1}|x - x_i| & \text{if } |x - x_i| < h, \\ 0 & \text{otherwise} \end{cases}$$

for  $i = 1, \dots, N$ . Compute the matrix  $A$  from the previous problem that appears in the gradient.

Finite element methods are based on these “weak formulations” of the problem. The Ritz method is based on minimizing  $F$  and the Galerkin method is based on finding the critical points of  $F'(u)$ .

(a)

$$\begin{aligned} F'(u)v &= \lim_{\varepsilon \rightarrow 0} \frac{F(u + \varepsilon v) - F(u)}{\varepsilon} \\ &= \lim_{\varepsilon \rightarrow 0} \frac{\int_0^1 \frac{1}{2} (u_x + \varepsilon v_x)^2 + f(u + \varepsilon v) - \frac{1}{2} u_x^2 - f u dx}{\varepsilon} \\ &= \lim_{\varepsilon \rightarrow 0} \int_0^1 u_x v_x + \frac{1}{2} \varepsilon v_x^2 + f v dx \\ &= \int_0^1 u_x v_x + f v dx \\ &= [v u_x]_0^1 + \int_0^1 v(f - u_{xx}) dx \end{aligned}$$

But  $v \in X$ , and thus  $v(0) = v(1) = 0$ . So, for all  $v$ ,

$$F'(u)v = \int_0^1 v(f - u_{xx})dx$$

(b) Let  $u$  be a solution to the Poisson equation. Then  $u_{xx} = f$ . Then  $u_{xx} - f = 0$ . Thus,

$$F'(u)v = \int_0^1 v(f - u_{xx})dx = \int_0^1 v \cdot 0 dx = 0$$

(c)

$$\begin{aligned} G(\vec{u}) &= F(u_h) = \int_0^1 \frac{1}{2} \left( \sum_{i=1}^n u_i \phi'_i(x) \right)^2 + f(x) \sum_{i=1}^n u_i \phi_i(x) dx \\ \Rightarrow (\nabla G)_j &= \frac{\partial}{\partial u_j} G(\vec{u}) = \int_0^1 \left( \sum_{i=1}^n u_i \phi_i(x) \right) \phi'_j(x) + f(x) \phi_j(x) dx \\ &= \left[ \phi_j \sum_{i=1}^n u_i \phi'_i \right]_0^1 + \int_0^1 \phi_j(x) \left( f(x) - \sum_{i=1}^n u_i \phi''_i(x) \right) dx \end{aligned}$$

But the boundary conditions are 0 since  $\phi_j \in X_h \subset X$  and  $u(0) = u(1) = 0$  for all  $u \in X$ . Thus,

$$\begin{aligned} (\nabla G)_j &= - \int_0^1 \left( \sum_{i=1}^n u_i \phi''_i(x) \right) \phi_j(x) dx + \int_0^1 f(x) \phi_j(x) dx \\ &= A\vec{u} + \vec{b} \end{aligned}$$

$$\text{where } \vec{b} = \begin{pmatrix} \int_0^1 f(x) \phi_1(x) dx \\ \int_0^1 f(x) \phi_2(x) dx \\ \vdots \\ \int_0^1 f(x) \phi_n(x) dx \end{pmatrix} \text{ and } A = (a_{ij}) \text{ where } a_{ij} = - \int_0^1 \phi_i(x) \phi''_j(x) dx.$$

(d) Note that

$$\phi_i(x) = \begin{cases} 1 - h^{-1}|x - x_i| & \text{if } |x - x_i| < h, \\ 0 & \text{otherwise} \end{cases}$$

and thus

$$\phi'_i(x) = \begin{cases} \frac{1}{h} & \text{if } x_{i-1} < x < x_i \\ -\frac{1}{h} & \text{if } x_i < x < x_{i+1} \\ 0 & \text{otherwise} \end{cases} \quad \text{and} \quad \phi''_i(x) = \delta\left(x - \frac{i}{N+1}\right)$$

This shows

$$a_{ij} = - \int_0^1 \phi_i(x) \delta\left(x - \frac{j}{N+1}\right) dx = -\phi_i\left(\frac{j}{N+1}\right) = \begin{cases} -1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

and so  $A = -I$  where  $I$  is the  $n \times n$  identity matrix.

### Problem 3

- (a) Using a Taylor expansion, derive the finite difference formula to approximate the second derivative at  $x$  using function values at  $x - \frac{h}{2}$ ,  $x$ , and  $x + h$ . How accurate is the finite difference approximation?
- (b) Perform a refinement study to verify the accuracy of the difference formula you derived.
- (c) Derive an expression for the quadratic polynomial that interpolates the data  $\left(x - \frac{h}{2}, u\left(x - \frac{h}{2}\right)\right)$ ,  $(x, u(x))$ , and  $(x + h, u(x + h))$ . How is the finite difference formula you derived in problem 3a related to the interpolating polynomial?

- (a) Let  $D^2$  be a finite difference formula for the second derivative. Then

$$(D^2 u)_j = au\left(x - \frac{h}{2}\right) + bu(x) + cu(x+h) \quad (0.1)$$

$$= (a+b+c)u(x) + \left(c - \frac{a}{2}\right)hu'(x) + \left(\frac{a}{8} + \frac{c}{2}\right)h^2u''(x) + \left(\frac{c}{6} - \frac{a}{48}\right)h^3u'''(x) + \dots \quad (0.2)$$

The letting  $a+b+c=0$ ,  $c=\frac{a}{2}$  and  $a=\frac{8}{3h^2}$ , we get

$$(D^2 u)_j = u''(x) + \frac{h}{6}u'''(x) + \dots \quad (0.3)$$

where  $a=\frac{8}{3h^2}$ ,  $b=-\frac{4}{h^2}$ , and  $c=\frac{4}{3h^2}$ . Thus

$$(D^2 u)_j = \frac{8}{3h^2}u\left(x - \frac{h}{2}\right) - \frac{4}{h^2}u(x) + \frac{4}{3h^2}u(x+h) \quad (0.4)$$

Note that  $\frac{c}{6} - \frac{a}{48} = \frac{1}{6h^2}$  and thus the  $u'''(x)$  term is order  $h$ . This means  $D^2$  has  $\mathcal{O}(h)$  accuracy.

- (b) **CODE**

- (c) The polynomial through the points

$$(x, u(x)) \quad (x+h, u(x+h)) \quad \left(x - \frac{h}{2}, u\left(x - \frac{h}{2}\right)\right) \quad (0.5)$$

satisfies

$$u(x) = A + Bx + Cx^2 \quad (0.6)$$

$$u(x+h) = A + B(x+h) + C(x+h)^2 \quad (0.7)$$

$$u\left(x - \frac{h}{2}\right) = A + B\left(x - \frac{h}{2}\right) + C\left(x - \frac{h}{2}\right)^2 \quad (0.8)$$

This is a simple linear algebra problem that can be solved symbolically using a symbolic solver like Maple or Python. We get:

$$A = \frac{1}{3h^2} \left( 3h^2u(x) + 4hu\left(x - \frac{h}{2}\right)x - 3hu(x)x - hu(x+h)x + 4u\left(x - \frac{h}{2}\right)x^2 - 6u(x)x^2 + 2u(x+h)x^2 \right) \quad (0.9)$$

$$B = -\frac{1}{3h^2} \left( 4hu\left(x - \frac{h}{2}\right) - 3hu(x) - hu(x+h) + 8u\left(x - \frac{h}{2}\right)x - 12u(x)x + 4u(x+h)x \right) \quad (0.10)$$

$$C = \frac{2}{3h^2} \left( 2u\left(x - \frac{h}{2}\right) - 3u(x) + u(x+h) \right) \quad (0.11)$$

Then note that  $u''(x) = 2C = \frac{8}{3h^2}u\left(x - \frac{h}{2}\right) - \frac{4}{h^2}u(x) + \frac{4}{3h^2}u(x+h)$ , which exactly matches with the finite difference formula from part (a). This means the best possible second derivative approximation using three points is precisely the quadratic through those points.