

MAT 228B Notes

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1 Last Time

- Laplacian in 2D: $\nabla^2 u = u_{xx} + u_{yy}$ $L = L_x + L_y$.
- LOD method.. think about as a fractional stepping approach
- Method of lines: $\frac{du}{dt} = L_x u + L_y u$. Solve $\frac{du}{dt} = L_x u$ and then $\frac{du}{dt} = L_y u$.

2 ADI (class of) Schemes

- This is another approach “Alternating Direction Implicit”
- For 2D diffusion, a common (Peaceman-Rachford) ADI scheme is

$$\left(I - \frac{d\Delta t}{2} L_x\right) u^* = \left(I + \frac{d\Delta t}{2} L_y\right) u^n$$

- Kind of looks like Crank Nicolson.. but y explicit and x implicit at the same time (for the intermediate step)
- The follow this up with the secondary step:

$$\left(I - \frac{d\Delta t}{2} L_y\right) u^{n+1} = \left(I + \frac{d\Delta t}{2} L_x\right) u^*.$$

- What is the work?
 - Step 1: solve N_y tridiagonal systems of size N_x (work is $\mathcal{O}(N_x N_y) = \mathcal{O}(N)$, which is optimal, (N is the number of gridpoints in 2D))
 - Step 2: solve N_x tridiagonal systems of size N_y (work is $\mathcal{O}(N_x N_y) = \mathcal{O}(N)$)
 - So the total work is $\mathcal{O}(N)$.

- Is it stable?
 - Doing the discrete Fourier transform gives

$$\begin{aligned} \left(1 + 2b\Delta t \sin^2\left(\frac{\xi_1 \Delta x}{2}\right)\right) \hat{u}^* &= \left(1 - 2b\Delta t \sin^2\left(\frac{\xi_2 \Delta y}{2}\right)\right) \hat{u}^n \\ \left(1 + 2b\Delta t \sin^2\left(\frac{\xi_1 \Delta y}{2}\right)\right) u^{\hat{n}+1} &= \left(1 - 2b\Delta t \sin^2\left(\frac{\xi_2 \Delta x}{2}\right)\right) \hat{u}^* \end{aligned}$$

- Solving this gives

$$u^{\hat{n}+1} = \underbrace{\frac{\left(1 - 2b\Delta t \sin^2\left(\frac{\xi_1 \Delta x}{2}\right)\right) \left(1 - 2b\Delta t \sin^2\left(\frac{\xi_2 \Delta y}{2}\right)\right)}{\left(1 + 2b\Delta t \sin^2\left(\frac{\xi_2 \Delta y}{2}\right)\right) \left(1 + 2b\Delta t \sin^2\left(\frac{\xi_2 \Delta x}{2}\right)\right)}}_{g(\xi_1, \xi_2)} \hat{u}^n \quad (1)$$

- Note that $g(\xi_1, \xi_2) = g_1(\xi_1)g_2(\xi_2)$ where g_1 and g_2 are the amplification factors of Crank-Nicolson.
 - So, $|g(\xi_1, \xi_2)| = |g_1(\xi_1)| \cdot |g_2(\xi_2)| \leq 1$, so it is unconditionally stable.

- Is it consistent?

- Multiply first equation by $(I + \frac{b\Delta t}{2}L_x)$, so.

$$\underbrace{\left(I + \frac{b\Delta t}{2}L_x\right)\left(I - \frac{b\Delta t}{2}L_x\right)}_{\text{these commute}} u^* = \left(I + \frac{b\Delta t}{2}L_x\right)\left(I + \frac{b\Delta t}{2}L_y\right)u^n \quad (2)$$

- So,

$$\left(I - \frac{b\Delta t}{2}L_x\right)\left(I + \frac{b\Delta t}{2}L_x\right)u^* = \left(I + \frac{b\Delta t}{2}L_x\right)\left(I + \frac{b\Delta t}{2}L_y\right)u^n \quad (3)$$

- Then we eliminate u^* by using the second step of the scheme.

$$\left(I - \frac{b\Delta t}{2}L_x\right)\left(I - \frac{b\Delta t}{2}L_y\right)u^{n+1} = \left(I + \frac{b\Delta t}{2}L_x\right)\left(I + \frac{b\Delta t}{2}L_y\right)u^n \quad (4)$$

- Expanding this gives

$$\left(I - \frac{b\Delta t}{2}L_x - \frac{b\Delta t}{2}L_y + \frac{b^2\Delta t^2}{4}L_xL_y\right)u^{n+1} = \left(I + \frac{b\Delta t}{2}L_x + \frac{b\Delta t}{2}L_y + \frac{b^2\Delta t^2}{4}L_xL_y\right)u^n \quad (5)$$

- So this is a small perturbation of Crank-Nicolson.

$$\underbrace{\left(I - \frac{b\Delta t}{2}L\right)u^{n+1}}_{\text{Crank-Nicolson, where } L \text{ is the discrete 2D Laplacian}} = \left(I + \frac{b\Delta t}{2}L\right)u^n - \frac{b^2\Delta t^2}{4}L_xL_y(u^{n+1} - u^n) \quad (6)$$

- So,

$$\frac{u^{n+1} - u^n}{\Delta t} = \frac{b}{2}Lu^n + \frac{b}{2}Lu^{n+1} - \frac{b^2\Delta t^2}{4}L_xL_y\left(\frac{u^{n+1} - u^n}{\Delta t}\right) \quad (7)$$

- How big is this (do a Taylor Series)?
- We know plugging in the solution to the PDE into

$$\frac{u^{n+1} - u^n}{\Delta t} = \frac{b}{2}Lu^n + \frac{b}{2}Lu^{n+1} \quad (8)$$

gives us LTE for CN (which is second-order).

- In the limit of $\Delta t, \Delta x \rightarrow 0$,

$$\Delta t^2 L_x L_y \left(\frac{u^{n+1} - u^n}{\Delta t} \right) \rightarrow \Delta t^2 \frac{\partial^5}{\partial y^2 \partial x^2 \partial t} u \quad (9)$$

- These extra terms contribute $\mathcal{O}(\Delta t^2)$ to the truncation error in addition to the LTE of CN.

- Thus, the Lax Equivalence Theorem says this is convergent. It is second-order in space and time and unconditionally stable $\mathcal{O}(N)$ work per timestep.
- What are the boundary conditions should hold for u^* ?
 - The first step is Forward Euler in y direction for half a timestep, and
 - Backward Euler in the x direction for half a timestep.
 - It's a consistent discretization of the PDE to take step length $\frac{\Delta t}{2}$.
 - So, $u^* = u^{n+1/2} + \mathcal{O}(\Delta t^2)$.
 - This means the single-step error in Forward or Backward Euler is $\mathcal{O}(\Delta t^2)$.