

PBG 200A Notes

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1 Reminder of Toy Example from last time

$$N_t = \begin{pmatrix} N_{1,t} \\ N_{2,t} \end{pmatrix} = A \cdot N_t \quad \text{where} \quad A = \begin{pmatrix} 0 & 1.1 \\ 0.55 & 0.55 \end{pmatrix} \quad (1)$$

We saw that if $N_0 = \begin{pmatrix} 100 & 100 \end{pmatrix}^T$ then $N_t = 1.1^t N_0$.

Definition: A scalar λ is an eigenvalue for a $k \times k$ matrix A if there is a non-zero vector v such that $Av = \lambda v$. This vector v is called an eigenvector corresponding to the eigenvalue λ .

2 Perron-Frobenius Theorem

If A is a nonnegative, primitive (A^n has all positive entries for some n) matrix, then there exists $\lambda > 0$ and v such that

1. $Av = \lambda v$
2. $\sum_{i=1}^k v_i = 1$ and $v_i > 0$ for all $i = 1, \dots, k$.
3. Let $n(t) = \sum_{i=1}^k N_i(t)$. Then

$$\frac{1}{t} \log n(t) \rightarrow \log \lambda =: r \quad \text{as} \quad t \rightarrow \infty$$

whenever $N_i(0) \geq 0$ for $i = 1, \dots, k$ and $n(0) > 0$.

4. $\frac{N_i(t)}{n(t)} \rightarrow v_i$ as $t \rightarrow \infty$. The v_i 's are called the "stable stage distribution."

An example of a nonprimitive matrix is

$$A = \begin{pmatrix} 0 & + \\ + & 0 \end{pmatrix} \quad (2)$$

which at odd n ,

$$A^n = \begin{pmatrix} + & 0 \\ 0 & + \end{pmatrix} \quad (3)$$

and at even n ,

$$A^n = \begin{pmatrix} 0 & + \\ + & 0 \end{pmatrix} \quad (4)$$

The theorem is roughly saying

$$N(t) \approx C \lambda^t v \quad \text{for large enough } t \quad (5)$$

and C is dependent on $N(0)$.

What is C ? First, **Definition:** Let $w = [w_1, \dots, w_k]$ be such that $wA = \lambda w$ and such that $\sum_{i=1}^k w_i v_i = 1$.

$$N(t) \approx C\lambda^t v \quad (6)$$

$$wN(t) \approx wC\lambda^t v \quad (7)$$

$$wN(t) \approx C\lambda^t wv \quad (8)$$

$$wN(t) = wA^t N(0) = w\lambda^t N(0) \quad (9)$$

$$= \lambda^t wN(0) \quad (10)$$

$$\implies C = wN(0) \quad (11)$$

which implies w is the vector of reproductive values of each stage. It represents the amount an individual in any stage contributes to the population.

3 Sensitivity and Elasticity Analysis

Sensitivity of λ to the $i - j^{\text{th}}$ entry of A (a_{ij}), denoted S_{ij} , is $\frac{\partial \lambda}{\partial a_{ij}}$. It turns out

$$\frac{\partial \lambda}{\partial a_{ij}} = w_i v_j =: S_{ij} \quad (12)$$

In **R**, type `w%o%v` where `%o%` is the outer product.

Elasticity of λ to a_{ij} , denoted E_{ij} is

$$E_{ij} := \frac{\partial \lambda}{\partial a_{ij}} \cdot \frac{a_{ij}}{\lambda} \left(\approx \frac{\frac{\partial \lambda}{\lambda}}{\frac{\partial a_{ij}}{a_{ij}}} \right) = S_{ij} \frac{a_{ij}}{\lambda} \quad (13)$$

In **R**, type `E = S*A/1` where `1` is λ . Note that `*` in **R** is elementwise multiplication, whereare `%*%` is matrix multiplication.

Sensitivity is about *absolute* (think $+$) changes, whereas elasticity is about *relative* (think \cdot) changes.