A time-dependent central core model and a schematic model for passive mechanism

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Outline

Time-dependent model

Model equations

Non-dimensionalization & numerical simulation

Schematic model for passive mechanism

Time-dependent model

Compartments

Multiphasic medulla on the domain (0, L) (superficial \rightarrow deep).

- 1. Central core (k=0)
- 2. Descending tubule (k = D)
- 3. Ascending tubule (k = A)
- 4. Collecting tubule (k = C)

Cross-sectional areas

Cross-sectional areas α_k (cm 2) satisfy

$$\sum_{k} \alpha_k = \alpha_* \tag{1.1}$$

where $\alpha_*:(0,L)\to\mathbb{R}_+$ is the fixed medullary cross-sectional area.

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$$\frac{\partial \alpha_k}{\partial t} + \frac{\partial}{\partial x} (\alpha_k u_k) = -\gamma_k w_k, \quad k = D, A, C, \tag{1.2}$$

$$\frac{\partial \alpha_k}{\partial t} + \frac{\partial}{\partial x} (\alpha_k u_k) = -\gamma_k w_k, \quad k = D, A, C,
\frac{\partial \alpha_0}{\partial t} + \frac{\partial}{\partial x} (\alpha_0 u_0) = \sum_{k=D,A,C} \gamma_k w_k.$$
(1.2)

 u_k : axial flow velocity (cm/s); w_k : transmural flux (cm/s); γ_k : total tubular circumferences (cm)

Water flow and transport

Poiseuille's equation:

$$\frac{8\pi\eta_k u_k}{\alpha_k} = -\frac{\partial p_k}{\partial x}, \quad k = 0, D, A, C, \tag{1.4}$$

 η_k : viscosity (mmHg·s), p_k : pressure (mmHg).

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Water transport:

$$w_k := \zeta_w^k (\psi_k - \psi_0), \quad k = D, A, C$$
 (1.5)

$$\psi_k := p_k - \pi_k,
\pi_k := RT \left(2c_s^k + c_u^k \right), \qquad k = 0, D, A, C.$$
(1.6)

 $\zeta_{
m w}^k$: water permeability (mmHg·s); c_i^k : concentration (mmol/cm 3)

Pressure-compliance relationship

Given tubular compliance ν_k (mmHg⁻¹), we assume

$$\nu_k(p_k - p_0) = \frac{\alpha_k}{\bar{\alpha}_k} - 1, \quad k = D, A, C.$$
 (1.7)

Note that p_0 is determined by the medullary volume conservation (1.1).

Solute dynamics

$$\frac{\partial}{\partial t} \left(\alpha_k c_i^k \right) = -\frac{\partial}{\partial x} f_i^k - \gamma_k g_i^k, \quad k = D, A, C,$$
 (1.8)

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$$\frac{\partial}{\partial t} \left(\alpha_0 c_i^0 \right) = -\frac{\partial}{\partial x} f_i^0 + \sum_{k=D,A,C} \gamma_k g_i^k,$$
(1.8)

 f_i^k : Axial solute flow (mmol/s):

$$f_i^k := \alpha_k \left(-D_i^k \frac{\partial c_i^k}{\partial x} + u_k c_i^k \right), \quad k = 0, D, A, C.$$
 (1.10)

 D_i^k : diffusion coefficient (cm²/s).

 g_i^k : transmural solute flux (mmol/cm²·s),

solute transport

 g_i^k : transmural solute flux (mmol/cm²·s), (adapted from Stephenson et al. [1987, 1989]):

$$g_i^k := j_i^k + h_i^k, \quad k = D, A, C,$$
 (1.11)

$$j_i^k = \zeta_i^k \left(c_i^k - c_i^0 \right), \quad k = 0, D, A, C.$$
 (1.12)

 ζ_i^k : solute permeability (cm/s).

 h_i^k : active transport:

$$h_{\rm s}^{\rm A} = \begin{cases} \frac{h_{\rm s,max}^{\rm A}}{1 + M/c_{\rm s}^{\rm A}} & \text{in } (0, \frac{L}{3}) \\ 0 & \text{in } [\frac{L}{3}, L), \end{cases}$$
 (1.13)

where M is the Michaelis-Menten constant.

Boundary condition: central core

No flux at the bottom:

$$u_0(t, L) = 0, (1.14)$$

$$f_i^0(t, L) = 0, \quad i = s, u.$$
 (1.15)

Dirichlet boundary at the cortico-medullary junction:

$$p_0(t,0) = P_{\rm v}(t),$$
 (1.16)

$$c_i^0(t,0) = c_i^{\mathbf{v}}(t).$$
 (1.17)

Boundary condition: descending tubule

Input from the PCT:

$$(\alpha_{\rm D} u_{\rm D})(t,0) = F_{\rm PCT}(t), \tag{1.18}$$

$$c_i^{\rm D}(t,0) = c_i^{\rm PCT}(t), \quad i = s, u,$$
 (1.19)

Tip of the loop of Henle:

$$(\alpha_{\mathrm{D}}u_{\mathrm{D}} + \alpha_{\mathrm{A}}u_{\mathrm{A}})(t, L) = 0, \tag{1.20}$$

$$\left(f_i^{\mathrm{D}} + f_i^{\mathrm{A}}\right)(t, L) = 0, \tag{1.21}$$

$$p_{\rm D}(t,L) = p_{\rm A}(t,L),$$
 (1.22)

$$c_i^{\rm D}(t,L) = c_i^{\rm A}(t,L)$$
 (1.23)

Boundary condition: modification by distal tubules

Assumption: salt from the ascending tubule is further reabsorbed so that only a fraction of $q\in(0,1)$ are left at the collecting tubule; formally,

$$\left(f_{\mathbf{u}}^{\mathbf{A}} + f_{\mathbf{u}}^{\mathbf{C}}\right)(t,0) = 0,$$
 (1.24)

$$\left(qf_{\rm s}^{\rm A} + f_{\rm s}^{\rm C}\right)(t,0) = 0.$$
 (1.25)

Further, we assume that

$$p_{\rm A}(t,0) = p_{\rm C}(t,0),$$
 (1.26)

$$f_i^{A}(t, L) = (\alpha_A u_A c_i^{A})(t, L), \quad i = s, u,$$
 (1.27)

$$(2c_{\rm s}^{\rm C} + c_{\rm u}^{\rm C})(t,0) = osm_{\rm cortex}(t),$$
 (1.28)

where the cortical osmolarity $\operatorname{osm}_{\operatorname{cortex}}$ is given.

Boundary condition: papillary outflow

$$p_{\rm C}(t,L) = P_{\rm p}(t),$$
 (1.29)

$$f_i^{\rm C}(t,L) = (\alpha_{\rm C} u_{\rm C} c_i^{\rm C})(t,L), \quad i = \text{s, u,}$$
 (1.30)

where $P_{\rm p}$ is the papillary pressure.

Rescaling

Introduce spatial rescaling and advective timescale:

$$x = L\hat{x}, \quad t = \tau \hat{t}, \quad \tau := \frac{L}{p_*/\rho_* L} = \frac{8\pi \eta_* L^2}{\bar{\alpha} c_* RT}$$
 (1.31)

where the subscript * denotes the typical magnitude of physical quantities; here $p_*=c_*RT$ and $\rho_*=8\pi\eta_*/\bar{\alpha}$ are those of pressure and hydraulic resistivity with $\bar{\alpha}=\frac{1}{L}\int_0^L\alpha_*(x)\,dx$.

Unknowns:

$$\alpha_k = \bar{\alpha}\hat{\alpha}, \quad c_i^k = c_*\hat{c}_i^k, \quad p_k = p_*\hat{p}_k = c_*RT\hat{p}_k. \tag{1.32}$$

Dimensionless model

$$\frac{\partial \hat{\alpha}_k}{\partial \hat{t}} + \frac{\partial}{\partial \hat{x}} (\hat{\alpha}_k \hat{u}_k) = -\hat{w}_k, \tag{1.33}$$

$$\frac{\partial \hat{\alpha}_0}{\partial \hat{t}} + \frac{\partial}{\partial \hat{x}} (\hat{\alpha}_0 \hat{u}_0) = \sum_k \hat{w}_k, \tag{1.34}$$

$$\hat{\nu}_k(\hat{p}_k - \hat{p}_0) = \frac{\hat{\alpha}_k}{\hat{\alpha}_k} - 1, \tag{1.35}$$

$$\hat{\alpha}_0 + \sum_k \hat{\alpha}_k = \hat{\alpha}_*,\tag{1.36}$$

$$\frac{\partial}{\partial \hat{t}} \left(\hat{\alpha}_k \hat{c}_i^k \right) = -\frac{\partial}{\partial \hat{x}} \hat{f}_i^k - \hat{g}_i^k, \tag{1.37}$$

$$\frac{\partial}{\partial \hat{t}} \left(\hat{\alpha}_0 \hat{c}_i^0 \right) = -\frac{\partial}{\partial \hat{x}} \hat{f}_i^0 + \sum_k \hat{g}_i^k, \tag{1.38}$$

Dimensionless flows and transports

$$\hat{u}_k := -\frac{\hat{\alpha}_k}{\hat{\rho}_k} \frac{\partial \hat{p}_k}{\partial \hat{x}},\tag{1.39}$$

$$\hat{f}_i^k := \hat{\alpha}_k \left(-\hat{D}_i^k \frac{\partial \hat{c}_i^k}{\partial \hat{x}} + \hat{u}_k \hat{c}_i^k \right), \tag{1.40}$$

$$\hat{w}_k := \hat{\zeta}_{w}^k \left(\hat{\psi}_k - \hat{\psi}_0 \right), \quad \hat{\psi}_k := \hat{p}_k - \left(2\hat{c}_{s}^k + \hat{c}_{u}^k \right),$$
 (1.41)

$$\hat{g}_i^k := \hat{j}_i^k + \hat{h}_i^k, \quad \hat{j}_i^k = \hat{\zeta}_i^k (\hat{c}_i^k - \hat{c}_i^0). \tag{1.42}$$

$$\hat{h}_{s}^{A} = \begin{cases} \frac{\hat{h}_{s,max}^{A}}{1 + \hat{M}/\hat{c}_{s}^{A}} & \text{in } (0, \frac{1}{3}) \\ 0 & \text{in } [\frac{1}{3}, 1) \end{cases}$$
(1.43)

Parameters and boundary conditions

Parameters (note that γ_k is absorbed into $\hat{\zeta}_i^k, \hat{\zeta}_{\mathrm{w}}^k$):

$$\begin{split} \hat{\rho}_k &= \frac{8\pi\eta_k}{\rho_*}, \quad \hat{\nu}_k = p_*\nu_k, \quad \hat{\bar{\alpha}}_k = \frac{\bar{\alpha}_k}{\bar{\alpha}}, \quad \hat{\alpha}_* = \frac{\alpha_*}{\bar{\alpha}} \\ \hat{D}_i^k &= \frac{\tau}{L^2} D_i^k, \quad \hat{\zeta}_w^k = \frac{\gamma_k p_* \tau}{\bar{\alpha}} \zeta_w^k, \quad \hat{\zeta}_i^k = \frac{\gamma_k p_* \tau}{\bar{\alpha} c_*^2} \zeta_i^k, \\ \hat{h}_s^A &= \frac{\gamma_A \tau}{\bar{\alpha} c_*} h_s^A, \quad \hat{M} = \frac{M}{c_*}. \end{split}$$

Boundary conditions are the same but with $\hat{\cdot}$ notation where

$$F_{\text{PCT}} = \frac{\bar{\alpha}L}{\tau} \hat{F}_{\text{PCT}}, \quad P_{\text{p}} = p_* \hat{P}_{\text{p}}, \quad P_{\text{v}} = p_* \hat{P}_{\text{v}},$$
$$c_i^{\text{v}} = c_* \hat{c}_i^{\text{v}}, \quad \text{osm}_{\text{cortex}} = c_* \widehat{\text{osm}}_{\text{cortex}}.$$

Numerical simulation

- Approximation: backward difference for time derivatives and central difference for spatial derivatives. Then, use an iterative method.
- Most parameters except for D_i^k when $k \neq 0$, η_k , P_v , P_p , ν_k , q are available in Stephenson et al. [1987, 1989] which uses transfusion data in rabbit; these 6 will be chosen empirically.
- The simulated solution appears to converge to a steady state.

Parameters

Physical and geometric parameters (take $\bar{\alpha}_k=\pi r^2$, $\gamma_k=2\pi r_k$, $\alpha_*=\sum_k\bar{\alpha}_k$):

$D_{\rm s}^0$	D_{u}^{0}	D_i^k , $k \neq 0$	η_k	η_k ν_k			$r_{\rm A}$	$r_{\rm C}$
$(\times 10^{-4} \mathrm{cm}^2/\mathrm{s})$			$(\text{cP} \approx 7.5 \times 10^{-6} \text{ mmHg·s})$	$(mmHg^{-1})$	$(\times 10^{-3} \text{ cm})$			
2.5	2.5 2 0.15		0.6915	0.0517	2.5	2.5 0.8		1.2

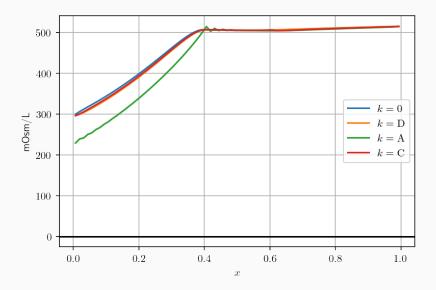
Transport parameters:

$\zeta_{ m w}^{ m D}$	$\zeta_{\mathrm{w}}^{\mathrm{A}}$	$\zeta_{ m w}^{ m C}$	$\zeta_{ m s}^{ m D}$	$\zeta_{ m s}^{ m A}$	$\zeta_{ m s}^{ m C}$	$\zeta_{\mathrm{u}}^{\mathrm{D}}$	$\zeta_{ m u}^{ m A}$	$\zeta_{\mathrm{u}}^{\mathrm{C}}$	$h_{ m s}^{ m A}$	M
$(\times 10^{-8} \text{ cm/mmHg·s})$			(×10 ⁻⁵ cm/s)					$(\frac{10^{-6}\text{mmol}}{\text{cm}^2 \cdot \text{s}})$	$(\frac{\text{mmol}}{\text{cm}^3})$	
22.5	0	3.95	1.61	6.27	0.04	1.5	0.86	0	14.2	0.15
33.8	0	3.95	1.61	26.0	0.04	1.5	6.70	0	0	
26.4	0	3.95	1.61	26.0	0.04	1.5	6.70	1.5	0	

Boundary data

$F_{ m PCT}$	$P_{\rm p}$	$P_{\rm v}$	$c_{ m s}^{ m v}$ $c_{ m u}^{ m v}$ osm		osm_{cortex}	
$(\times 10^{-7} \text{cm}^3/\text{s})$	(mm	Hg)	(mmol/L)			
1.67	6.4	0	145	5	295	

Result



Schematic model for passive mechanism

- We want to have a clean picture of what makes passive mechanism working.
- Derive a schematic model of inner medulla based on the common explanation of passive mechanism:

Concept of passive mechanism

The net water and NaCl reabsorption preceding the inner medulla collecting tubules concentrate the urea enough that it diffuses out in the inner medulla. This in turn increases osmolality in the interstitium that drives the water reabsorption from the thin descending limbs, concentrating NaCl in the process. NaCl is then passively reabsorbed at the ascending tubule.

Model derivation

Consider a steady state of the previous dimensionless model but rescale $\hat{x} \in (0,1)$ to be the inner medulla instead (from now on, we omit the $\hat{\cdot}$ notation). Writing $q_k = \alpha_k u_k$, $s_k = c_{\rm s}^k$, $u_k = c_{\rm u}^k$, and assuming that $1/\nu_k$ and D_i^k are small. (continued in the document)

References i

References

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