

A simple time-dependent model of kidney

Chanoknun Sintavanuruk

April 11, 2023

1 Model equations

In this model, we consider the medulla of the kidney as a multiphasic continuum consisting of luminal compartments of nephrons and a single combined interstitium-vessel compartment, which we will refer to as simply the interstitium. We assume that there is no variation across the medullary tissue of the same depth so that the model can be represented in a one-dimensional spatial domain $(0, L)$, where $x = 0$ is the most superficial part of the outer medulla. Further, we suppose that the population of nephrons is homogeneous, so that we have three distinct luminal compartments: the descending tubules, the ascending tubules, and the collecting tubules.

For each compartment, the occupied volume is given by the volume density (per unit depth) α_k , as a function of space and time, where we use k to identify the compartment; $k = 0, D, A, C$ are for the interstitium, the descending, ascending, and collecting tubules respectively. By assuming the total volume of the medulla is constant, we have

$$\sum_k \alpha_k = \alpha_* \quad (1)$$

where $\alpha_* : (0, L) \rightarrow \mathbb{R}_+$ is the total volume density of the medulla.

The dynamics of α_k are given by

$$\frac{\partial \alpha_k}{\partial t} + \frac{\partial}{\partial x} (\alpha_k u_k) = -\gamma_k w_k, \quad k = D, A, C, \quad (2)$$

$$\frac{\partial \alpha_0}{\partial t} + \frac{\partial}{\partial x} (\alpha_0 u_0) = \sum_{k=D, A, C} \gamma_k w_k. \quad (3)$$

Here, u_k is the water flow velocity, w_k is the transmural flux of the water reabsorbed into the interstitium, and γ_k describes the area of the luminal wall per unit depth. For each compartment k , the flow velocity u_k depends on the hydrostatic pressure p_k , and is described by the Poiseuille equation:

$$\frac{\rho_k u_k}{\alpha_k} = -\frac{\partial p_k}{\partial x}, \quad k = 0, D, A, C, \quad (4)$$

with ρ_k is a constant so that ρ_k/α_k represents the hydraulic resistivity which depends on the volume density α_k . The transmural fluxes w_k on the right-hand side of (2) depend on the difference of both the hydrostatic pressures p_k and the osmotic pressures π_k between the luminal and the interstitial compartments. That is,

$$w_k := \zeta_w^k (\psi_k - \psi_0), \quad \psi_k := p_k - \pi_k, \quad k = D, A, C \quad (5)$$

where ζ_w^k are the water permeability of the tubules, and ψ_k are called the ‘water potential’.

We describe the hydrostatic pressure p_k by considering a mechanical property of the nephrons. We assume that this can be captured by the compliance ν_k , $k = D, A, C$, of the tubular walls, and we have

$$\nu_k(p_k - p_0) = \frac{\alpha_k}{\bar{\alpha}_k} - 1, \quad k = D, A, C, \quad (6)$$

where $\bar{\alpha}_k$ are the resting volume density for which $p_k = p_0$. Note that the interstitial hydrostatic pressure is determined by the volume conservation given by (1).

The osmotic pressure π_k , on the other hand, depends on the total concentration of the solutes. In this model, for each compartment k , we will only consider two unknown concentrations of solute species: the salt concentration c_s^k , and the urea concentration c_u^k . The rest of the solute species will be treated as a fixed immobile solute, and we denote the total amount (per unit depth) by a_k . We define the osmotic pressure by

$$\pi_k := \sum_{i=s,u} c_i^k + \frac{a_k}{\alpha_k}, \quad k = 0, D, A, C. \quad (7)$$

Now, similarly to the dynamics of the volume density, we have equations for the salt and urea concentrations:

$$\frac{\partial}{\partial t} (\alpha_k c_i^k) = -\frac{\partial}{\partial x} f_i^k - \gamma_k g_i^k, \quad k = D, A, C, \quad (8)$$

$$\frac{\partial}{\partial t} (\alpha_0 c_i^0) = -\frac{\partial}{\partial x} f_i^0 + \sum_{k=D,A,C} \gamma_k g_i^k, \quad (9)$$

where $i = s, u$. The axial flow and transmural flux of the solute i are denoted by f_i^k and g_i^k respectively. The axial flow has two components: diffusion and advection. We write f_i^k as

$$f_i^k := -\alpha_k D_i^k \frac{\partial c_i^k}{\partial x} + \alpha_k u_k c_i^k, \quad k = 0, D, A, C, \quad (10)$$

where D_i^k are the diffusion coefficients. **Correction:** since f_i^k is a *flow* and $-D_i^k \partial c_i^k / \partial x$ is a *diffusive flux*, we should have an additional α_k as indicated above. For the transmural fluxes g_i^k , we have

$$g_i^k := j_i^k + h_i^k, \quad k = D, A, C. \quad (11)$$

where j_i^k is the passive transport of the solutes, and h_i^k is the active transport. We assume that the passive transports take the form:

$$j_i^k = \zeta_i^k (\mu_i^k - \mu_i^0), \quad k = D, A, C, \quad (12)$$

where ζ_i^k are the permeability of the solute i through the tubules, and μ_i^k is the chemical potential of the solute i in the compartment k :

$$\mu_i^k := RT \ln c_i^k, \quad k = 0, D, A, C. \quad (13)$$

Note that, since we are considering only salt and urea, we essentially eliminate the need to address the electrical potential, i.e., the electroneutrality condition requires that the movement of Na^+ ions must be accompanied by that of Cl^- ions, so we can think of salt as having no charge. The active transport h_i^k represent the transport which requires external energy. In this case, we are interested the molecular pump of salt from the ascending tubules into the interstitium. So, h_s^A is a non-negative function and $h_i^k \equiv 0$ for $k = D, C$ or $i = u$.

Now, we need to specify the boundary conditions. For the interstitial compartment, we assume no-flux boundary at $x = L$, i.e.,

$$u_0(t, L) = 0, \quad (14)$$

$$f_i^0(t, L) = 0, \quad i = s, u. \quad (15)$$

On the other hand, we allow interstitial water flow and advective solute flow at $x = 0$ in the negative direction. More precisely,

$$(\alpha_0 u_0)(t, 0) = \min \left\{ 0, \frac{P_v - p_0(t, 0)}{R_v} \right\}, \quad (16)$$

$$f_i^0(t, 0) = (\alpha_0 u_0 c_i^0)(t, 0), \quad i = s, u, \quad (17)$$

where P_v is the pressure inside larger vessels which are coupled to the interstitial compartment, and R_v is the resistance of the coupling. The rectification is so that we avoid having to specify the solute input from the outside when the pressure $p_0(t, 0)$ is less than that of the pressure P_{vessel} of larger vessels. With this same reason, we do not allow diffusive solute flow through this coupling.

For the luminal compartments, we have solute and water input from the proximal tubules in the descending compartment at $x = 0$. Formally, we write

$$(\alpha_D u_D)(t, 0) = \text{GFR}(t), \quad (18)$$

$$f_i^D(t, 0) = (\alpha_D u_D c_i^D)(t, 0), \quad i = s, u \quad (19)$$

where GFR is a non-negative function of time, which can be given or depend on other model unknowns such as the pressure of the descending tubule or the salt concentration in the ascending tubule. Furthermore, we have couplings between the descending and ascending tubules at $x = L$ and between the ascending and

collecting tubules at $x = 0$, i.e., we have

$$(\alpha_D u_D + \alpha_A u_A)(t, L) = 0, \quad (20)$$

$$(f_i^D + f_i^A)(t, L) = 0, \quad (21)$$

$$p_D(t, L) = p_A(t, L), \quad (22)$$

$$c_i^D(t, L) = c_i^A(t, L) \quad (23)$$

and, similarly,

$$(\alpha_A u_A + \alpha_C u_C)(t, 0) = 0, \quad (24)$$

$$(f_i^A + f_i^C)(t, 0) = 0, \quad (25)$$

$$p_A(t, 0) = p_C(t, 0), \quad (26)$$

$$c_i^A(t, 0) = c_i^C(t, 0), \quad (27)$$

where $i = s, u$. Note that in our simplification, we are bypassing the distal convoluted tubules in the coupling between the ascending and the collecting tubules. Finally, since the volume density of the collecting tubule is the model unknown, we need to specify the solute and water flow at $x = L$ where we use the same idea as those of the interstitium:

$$(\alpha_C u_C)(t, L) = \max \left\{ 0, \frac{p_C(t, L) - P_p}{R_p} \right\}, \quad (28)$$

$$f_i^C(t, L) = (\alpha_C u_C c_i^C)(t, L), \quad i = s, u, \quad (29)$$

where P_p is the papillary pressure and R_p is the resistance of the coupling between the collecting tubules and the renal papillae.

2 Non-dimensionalization

We now consider the rescaling of space and time:

$$x = L\hat{x}, \quad t = \frac{L^2}{D_*} \hat{t}, \quad (30)$$

where D_* is the typical magnitude of the diffusion coefficients across all solutes and compartments. With this, we rescale the model unknowns as follows:

$$\alpha_k = \bar{\alpha} \hat{\alpha}, \quad c_i^k = c_* \hat{c}_i^k, \quad p_k = p_* \hat{p}_k, \quad (31)$$

where $\bar{\alpha} = \frac{1}{L} \int_0^L \alpha_*(x) dx$, and c_*, p_* are the typical magnitudes of solute concentrations and hydrostatic pressures. Here, the dimensionless unknowns with $\hat{\cdot}$ notation are functions in the rescaled space and time (\hat{t}, \hat{x}) .

We have the model equations in the dimensionless form:

$$\frac{\partial \hat{\alpha}_k}{\partial \hat{t}} + \text{Pe} \frac{\partial}{\partial \hat{x}} (\hat{\alpha}_k \hat{u}_k) = -\hat{w}_k, \quad (32)$$

$$\frac{\partial \hat{\alpha}_0}{\partial \hat{t}} + \text{Pe} \frac{\partial}{\partial \hat{x}} (\hat{\alpha}_0 \hat{u}_0) = \sum_k \hat{w}_k, \quad (33)$$

$$\hat{\nu}_k (\hat{p}_k - \hat{p}_0) = \frac{\hat{\alpha}_k}{\hat{\alpha}_k} - 1, \quad (34)$$

$$\hat{\alpha}_0 + \sum_k \hat{\alpha}_k = \hat{\alpha}_*, \quad (35)$$

$$\frac{\partial}{\partial \hat{t}} (\hat{\alpha}_k \hat{c}_i^k) = -\frac{\partial}{\partial \hat{x}} \hat{f}_i^k - \hat{g}_i^k, \quad (36)$$

$$\frac{\partial}{\partial \hat{t}} (\hat{\alpha}_0 \hat{c}_i^0) = -\frac{\partial}{\partial \hat{x}} \hat{f}_i^0 + \sum_k \hat{g}_i^k, \quad (37)$$

where

$$\hat{u}_k := -\frac{\hat{\alpha}_k}{\hat{\rho}_k} \frac{\partial \hat{p}_k}{\partial \hat{x}}, \quad (38)$$

$$\hat{f}_i^k := -\hat{\alpha}_k \hat{D}_k \frac{\partial \hat{c}_i^k}{\partial \hat{x}} + \text{Pe} (\hat{\alpha}_k \hat{u}_k \hat{c}_i^k), \quad (39)$$

$$\hat{w}_k := \hat{\zeta}_w^k (\hat{\psi}_k - \hat{\psi}_0), \quad \hat{\psi}_k := \hat{p}_k - \hat{\pi}_k, \quad \hat{\pi}_k := \frac{\hat{\alpha}_k}{\hat{\alpha}_k} + \sum_i \hat{c}_i^k, \quad (40)$$

$$\hat{g}_i^k := \hat{j}_i^k + \hat{h}_i^k, \quad \hat{j}_i^k := \hat{\zeta}_i^k (\hat{\mu}_i^k - \hat{\mu}_i^0), \quad \hat{\mu}_i^k := \ln \hat{c}_i^k. \quad (41)$$

Correction: as in the previous section, the diffusive term should have an additional $\hat{\alpha}_k$. Note that we have $\hat{h}_i^k = \gamma_k \hat{h}_i^k$ for the dimensionless active transport \hat{h}_i^k . In this dimensionless formulation, we have identified parameters:

$$\text{Pe} = \frac{\bar{\alpha} p_* / \rho_*}{D_*}, \quad \hat{\rho}_k = \frac{\rho_k}{\rho_*}, \quad \hat{\nu}_k = p_* \nu_k, \quad \hat{\alpha}_k = \frac{\bar{\alpha}_k}{\bar{\alpha}}, \quad (42)$$

$$\hat{D}_k = \frac{D_k}{D_*}, \quad \hat{\zeta}_w^k = \frac{\gamma_k c_* L^2}{\bar{\alpha} D_*} \zeta_w^k, \quad \hat{\zeta}_i^k = \frac{\gamma_k R T L^2}{\bar{\alpha} c_* D_*} \zeta_i^k, \quad (43)$$

where the subscript $*$ denotes the typical magnitudes of the parameters described in the previous section. We have the Péclet number Pe which can be interpreted as the ratio between the rate of advection $\bar{\alpha} p_* / \rho_* L$ and the rate of diffusion D_* / L . The mechanical parameters, which are the hydraulic resistivity $\hat{\rho}_k$, the tubular compliances $\hat{\nu}_k$, the resting volume density $\hat{\alpha}_k$, and the diffusion coefficients \hat{D}_k persist through the non-dimensionalization. The transport parameters, however, are now reduced to only $\hat{\zeta}_w^k$ and $\hat{\zeta}_i^k$ which combine the geometric parameters γ_k with the solute and water permeabilities.

For the boundary conditions, we have the same form as previously described, but with $\hat{\cdot}$ notations, where we have

$$\text{GFR} = \frac{\bar{\alpha}^2 p_*}{\rho_* L} \widehat{\text{GFR}}, \quad P = p_* \hat{P}, \quad R = \frac{\rho_* L}{\bar{\alpha}^2} \hat{R}, \quad (44)$$

where the subscript \cdot represents v and p.

3 Numerical method

We now give an implicit scheme to numerically solve the dimensionless system (33) - (41) described in the previous section. To simplify the notation, we will omit the $\hat{\cdot}$ notation in these equations.

Let $N \in \mathbb{N}$ be the number of uniformly spaced grids in $(0, 1)$, and $\delta x = 1/N$ be the spatial grid size. Similarly, we denote δt as the size of time steps. We will use the notation $\alpha_{kl}^n, c_{il}^{kn}, p_{kl}^n$ for the discretization of α_k, c_i^k and p_k at the l -th spatial grid and time $t = n\delta t$.

We define difference quotient operators:

$$\mathcal{D}_x^+ y_l^n := \frac{y_{l+1}^n - y_l^n}{\delta x}, \quad \mathcal{D}_x^- y_l^n := \frac{y_l^n - y_{l-1}^n}{\delta x}, \quad \mathcal{D}_t y_l^n = \frac{y_l^n - y_l^{n-1}}{\delta t}. \quad (45)$$

and an average operator:

$$\mathcal{A}y_l^n := \frac{y_{l+1}^n + y_l^n}{2}. \quad (46)$$

We start with known values of $\alpha_{kl}^{n-1}, c_{il}^{k,n-1}, p_{kl}^{n-1}$, $l = 1, \dots, N$. The first step is to update the unknowns for the next time step n . We have

$$\begin{aligned} \mathcal{D}_t \alpha_{kl}^n + \text{Pe}(\alpha_{kl}^n u_{kl}^n) &= -w_{kl}^n, \quad w_{kl}^n := \zeta_w^k (\psi_{kl}^n - \psi_{0l}^n) \\ \psi_l^n &:= p_l^n - \pi_l^n, \quad \pi_l^n := \sum_i c_{il}^n. \end{aligned} \quad (47)$$

4 Simulation of the countercurrent mechanism

In this simulation, we will use $\alpha_* = 1$, $a = 0$, and $\bar{\alpha}_k = 1/4$. For the transport parameters, we have ζ_k, γ_i^k ; we assume $\zeta_A = 0$ and γ . For illustrating purpose, we assume that

$$h_{\text{salt}}^A = h_*(c_{\text{salt}}^A)^+, \quad \text{on } (0, 1/2), \quad (48)$$

where $h_* > 0$ is the pump strength, and $h_{\text{salt}}^A = 0$ elsewhere. Also, we assume no active transport other than the pump in the ascending tubule.