

1. The characteristic equation: $r^2 - 2r + 10 = 0$

$$\Rightarrow r = \frac{2}{2} \pm \frac{\sqrt{4 - (4)(10)}}{2} = 1 \pm 3i$$

\Rightarrow the homogeneous DE has independent solns. $y_1 = e^t \cos(3t)$, $y_2 = e^t \sin(3t)$

$$\Rightarrow y_h(t) = c_1 e^t \cos(3t) + c_2 e^t \sin(3t) \quad (\text{No overlap with } 26\cos(2t) + 26\sin(2t))$$

For particular soln. pose the form

$$y_p(t) = A \cos(2t) + B \sin(2t) \quad \Rightarrow \begin{cases} y_p' = -2A \sin(2t) + 2B \cos(2t) \\ y_p'' = -4A \cos(2t) - 4B \sin(2t) \end{cases}$$

So

$$\begin{aligned} y_p'' - 2y_p' + 10y_p &= -4A \cos(2t) - 4B \sin(2t) \\ &\quad - 2[-2A \sin(2t) + 2B \cos(2t)] \\ &\quad + 10[A \cos(2t) + B \sin(2t)] \\ &= \underbrace{(6A - 4B)}_{\text{must} = 26} \cos(2t) + \underbrace{(4A - 6B)}_{\text{must} = 26} \sin(2t) \end{aligned}$$

$$\begin{bmatrix} 6 & -4 \\ 4 & 6 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 26 \\ 26 \end{bmatrix} \Rightarrow A = \frac{\begin{vmatrix} 26 & -4 \\ 26 & 6 \end{vmatrix}}{\begin{vmatrix} 6 & -4 \\ 4 & 6 \end{vmatrix}} = 5, \quad B = \frac{\begin{vmatrix} 6 & 26 \\ 4 & 26 \end{vmatrix}}{52} = 1$$

$$\text{Together, } y(t) = y_h(t) + y_p(t) = c_1 e^t \cos(3t) + c_2 e^t \sin(3t) + 5 \cos(2t) + \sin(2t)$$

$$y'(t) = c_1 e^t \cos(3t) - 3c_1 e^t \sin(3t) + c_2 e^t \sin(3t) + 3c_2 e^t \cos(3t) - 10 \sin(2t) + 2 \cos(2t)$$

$$\text{The ICs: } 9 = y(0) = c_1 + 5 \Rightarrow c_1 = 4$$

$$15 = y'(0) = c_1 + 3c_2 + 2 \Rightarrow c_2 = 3$$

$$\Rightarrow y(t) = 4e^t \cos(3t) + 3e^t \sin(3t) + 5 \cos(2t) + \sin(2t)$$

$$2. (a) \text{ Since } \mathcal{L}[3 \cos(2t)] = 3 \mathcal{L}[\cos(2t)] = \frac{3s}{s^2 + 4}$$

$$\text{and } \mathcal{L}[5t^2 + 7] = 5 \mathcal{L}[t^2] + 7 \mathcal{L}[1] = \frac{10}{s^3} + \frac{7}{s}$$

$$\text{we have } \mathcal{L}[(f * g)(t)] = \boxed{\frac{3s}{s^2 + 4} \left(\frac{10}{s^3} + \frac{7}{s} \right)}$$

(b) From the definition,

$$\begin{aligned} \mathcal{L}[f(t)] &= \int_0^{\infty} e^{-\lambda t} f(t) dt = \int_0^2 e^{-\lambda t} (4t+3) dt & \begin{aligned} dv &= e^{-\lambda t} dt \mid v = 4t+3 \\ u &= -\frac{1}{\lambda} e^{-\lambda t} \mid du = 4 dt \end{aligned} \\ &\stackrel{\text{by parts}}{=} -\frac{1}{\lambda} e^{-\lambda t} (4t+3) \Big|_0^2 + \frac{4}{\lambda} \int_0^2 e^{-\lambda t} dt \\ &= -\frac{11}{\lambda} e^{-2\lambda} + \frac{3}{\lambda} - \frac{4}{\lambda^2} [e^{-\lambda t}]_0^2 = \boxed{\frac{3}{\lambda} - \frac{11}{\lambda} e^{-2\lambda} + \frac{4}{\lambda^2} (1 - e^{-2\lambda})} \end{aligned}$$

Or, using the table entry $\mathcal{L}[f(t-a)u(t-a)] = e^{-\lambda a} \mathcal{L}[f(t)]$:

$$\begin{aligned} f(t) &= [1 - u(t-2)](4t+3) = 4t+3 - u(t-2)[4(t-2)+11] \\ &= 4t+3 - u(t-2) \cdot (4t+11 \mid_{t \mapsto t-2}) \end{aligned}$$

$$\Rightarrow F(\lambda) = 4\mathcal{L}[t] + 3\mathcal{L}[1] - e^{-2\lambda} \cdot \mathcal{L}[4t+11] = \boxed{\frac{4}{\lambda^2} + \frac{3}{\lambda} - e^{-2\lambda} \left(\frac{4}{\lambda^2} + \frac{11}{\lambda} \right)}$$

(c) Using partial fractions

$$\begin{aligned} \frac{2\lambda+1}{\lambda(\lambda^2+4\lambda+5)} &= \frac{A}{\lambda} + \frac{B\lambda+C}{\lambda^2+4\lambda+5} \Rightarrow 2\lambda+1 = A(\lambda^2+4\lambda+5) + B\lambda^2 + C\lambda \\ &= \underbrace{(A+B)}_{\text{must}=0} \lambda^2 + \underbrace{(4A+C)}_{\text{must}=2} \lambda + \underbrace{5A}_{\text{must}=1} \\ 5A &= 1 \Rightarrow A = 1/5 \\ A+B &= 0 \Rightarrow B = -1/5 \\ 4A+C &= 2 \Rightarrow C = 6/5 \end{aligned}$$

$$\begin{aligned} \mathcal{L}^{-1} \left[\frac{2\lambda+1}{\lambda(\lambda^2+4\lambda+5)} \right] &= \frac{1}{5} \mathcal{L}^{-1} \left[\frac{1}{\lambda} \right] + \mathcal{L}^{-1} \left[\frac{-1/5 \lambda + 6/5}{(\lambda+2)^2 + 1} \right] = \frac{1}{5} + \mathcal{L}^{-1} \left[\frac{-1/5 (\lambda+2) + 8/5}{(\lambda+2)^2 + 1} \right] \\ &= \frac{1}{5} - \frac{1}{5} \mathcal{L}^{-1} \left[\frac{\lambda+2}{(\lambda+2)^2 + 1} \right] + \frac{8}{5} \mathcal{L}^{-1} \left[\frac{1}{(\lambda+2)^2 + 1} \right] = \boxed{\frac{1}{5} - \frac{1}{5} e^{-2t} \cos t + \frac{8}{5} e^{-2t} \sin t} \end{aligned}$$

3. (a) $H(\lambda) = \frac{1}{\lambda^2 + 3\lambda + 2}$

$$\begin{aligned} (b) \quad h(t) &= \mathcal{L}^{-1} \left[\frac{1}{\lambda^2 + 3\lambda + 2} \right] = \mathcal{L}^{-1} \left[\frac{1}{\lambda+2} \cdot \frac{1}{\lambda+1} \right] \quad \left(\begin{array}{l} \text{can also write as } \frac{A}{\lambda+2} + \frac{B}{\lambda+1} \\ \text{using partial fractions} \end{array} \right) \\ &= \mathcal{L}^{-1} \left[\frac{1}{\lambda+2} \right] * \mathcal{L}^{-1} \left[\frac{1}{\lambda+1} \right] = e^{-2t} * e^{-t} \\ &= \int_0^t e^{-2w} e^{-(t-w)} dw = e^{-t} \int_0^t e^{-w} dw = -e^{-t} [e^{-w}]_0^t = -e^{-t} (e^{-t} - 1) \\ &= \boxed{e^{-t} - e^{-2t}} \end{aligned}$$

(c) The characteristic equation, $r^2 + 3r + 2 = 0$, has 2 distinct real (and negative) roots. So, it is overdamped.

$$\begin{aligned} \text{(d)} \quad y(t) &= (f * h)(t) = \int_0^t f(t-w) h(w) dw \\ &= \int_0^t f(t-w) (e^{-w} - e^{-2w}) dw \end{aligned}$$

4. Here, $y'' - \frac{12}{t^2} y = 5t^4 + 2t^{-2} = f(t)$,

and

$$W = \begin{vmatrix} t^4 & t^{-3} \\ 4t^3 & -3t^{-4} \end{vmatrix} = -3 - 4 = -7$$

$$\begin{aligned} y_p(t) &= t^4 \int \frac{1}{7} (5t^4 + 2t^{-2}) t^{-3} dt - t^{-3} \int \frac{1}{7} (5t^4 + 2t^{-2}) t^4 dt \\ &= t^4 \int \left(\frac{5}{7} t + \frac{2}{7} t^{-5} \right) dt - t^{-3} \int \left(\frac{5}{7} t^8 + \frac{2}{7} t^2 \right) dt \\ &= t^4 \left(\frac{5}{14} t^2 - \frac{1}{14} t^{-4} \right) - t^{-3} \left(\frac{5}{63} t^9 + \frac{2}{21} t^3 \right) \\ &= \frac{5}{14} t^6 - \frac{1}{14} - \frac{5}{63} t^6 - \frac{2}{21} = \boxed{\frac{5}{18} t^6 - \frac{1}{6}} \end{aligned}$$