1. (a) Echelon form is not unique, so the answer (to part (a)) that follows is not the only correct one. For all correct answers, however, the 4th column will be free.

$$\begin{bmatrix} 1 & -2 & 1 & 1 \\ -2 & 4 & -3 & -4 \\ 0 & 0 & 3 & 6 \\ 0 & 1 & 2 & 3 \end{bmatrix} \xrightarrow{2r_1 + r_2 \to r_2} \begin{bmatrix} 1 & -2 & 1 & 1 \\ 0 & 0 & -1 & -2 \\ 0 & 0 & 3 & 6 \\ 0 & 1 & 2 & 3 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & -2 & 1 & 1 \\ 0 & 0 & 3 & 6 \\ 0 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$

(b) Augmenting A with the zero vector is a Scenario where the Gaussian elimination we have already performed is easily adapted:

$$\begin{bmatrix} 1 & -2 & 1 & 1 & 0 \\ -2 & 4 & -3 & -4 & 0 \\ 0 & 0 & 3 & 6 & 0 \\ 0 & 1 & 2 & 3 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 1 & 1 & 0 \\ 0 & 1 & 2 & 3 & 0 \\ 0 & 0 & -1 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{array}{c} \chi_1 - 2\chi_2 + \chi_3 + \chi_4 = 0 \\ \Rightarrow \chi_2 + 2\chi_3 + 3\chi_4 = 0 \\ \Rightarrow -\chi_3 - 2\chi_4 = 0 \\ \Rightarrow -\chi_3 - 2\chi_4 = 0 \\ \end{array}$$

So, xy = t is free, and using backward substitution,

$$x_3 = -2x_4 = -2t$$

 $x_2 = -2x_3 - 3x_4 = -2(-2t) - 3t = t$
 $x_1 = 2x_2 - x_3 - x_4 = 2t - (-2t) - t = 3t$

We have solutions of the homogeneous system $A\vec{x} = \vec{0}$:

$$\vec{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 3t \\ t \\ -2t \\ t \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ -2 \\ 1 \end{bmatrix}.$$

2. The augmented matrix $\begin{bmatrix} 1 & 0 & -1 & 2 & | & -4 \end{bmatrix}$ is already in RREF. We see

 $X_3 = \Delta$ and $X_4 = t$ are free variables, and solving for basic variables $X_1, X_2 = \Delta - 2t - 4$ and $X_2 = -2\Delta - 3t + 1$.

So, solutions
$$\dot{\vec{\chi}} = \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \\ \chi_4 \end{bmatrix} = \begin{bmatrix} \lambda - 2t - 4 \\ -2\lambda - 3t + 1 \\ \lambda \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -2 \\ -3 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \end{bmatrix},$$

for s, t any reals.

4. (a)
$$|AB| = Jet(A) Jet(B) = (-2)(4) = -8$$
.

(6)
$$|-2B| = (-2)^3 \det(B) = (-8)(4) = -32$$
.

(c)
$$|B^T| = |B| = 4$$
.

$$(J) |A^{-1}| = \frac{1}{|A|} = -\frac{1}{2}$$

(e)
$$|B^3| = det(B)^3 = 64$$
.

5.
$$\begin{bmatrix} -3 & -5 & | & h \\ -6 & | & k & | & -6 \end{bmatrix}$$
 $-2r_1 + r_2 \rightarrow r_2$ $\begin{bmatrix} -3 & -5 & | & h \\ 0 & | & k+10 & | & -6-2h \end{bmatrix}$

So that there is the potential of infinitely many solutions, we require

$$k+10=0$$
 \Rightarrow $k=-10$.

Infinitely many solutions arises from having a free column, so long as the system is consistent, which additionally means we require

$$-6 - 2h = 0 \Rightarrow h = -3$$

6.
$$A(-2\vec{u}-2\vec{v}) = -2A(\vec{u}+\vec{v})$$

$$= (-2)\left(\begin{bmatrix} 2\\-1\\-2 \end{bmatrix} + \begin{bmatrix} -5\\1\\4 \end{bmatrix}\right) = (-2)\begin{bmatrix} -3\\0\\2 \end{bmatrix} = \begin{bmatrix} 6\\0\\-4 \end{bmatrix}.$$

8.
$$|A| = (2)(-2) - (-2)(3) = -4 + 6 = 2$$

Since |A| +0, A' exists. To find it,

$$\begin{bmatrix}
2 & 3 & | & 1 & 0 \\
-2 & -2 & | & 0 & 1
\end{bmatrix}$$

$$\sim$$

$$\begin{bmatrix}
2 & 3 & | & 1 & 0 \\
0 & 1 & | & 1
\end{bmatrix}$$

$$\sim$$

$$\begin{bmatrix}
2 & 0 & | -2 & -3 \\
0 & 1 & | & 1
\end{bmatrix}$$

$$\sim$$

$$\sim$$

$$\begin{bmatrix}
2 & 0 & | -2 & -3 \\
0 & 1 & | & 1
\end{bmatrix}$$

$$\sim$$

$$\sim$$

$$0 & 1 & | & 1 & 1
\end{bmatrix}$$

We get
$$A^{-1} = \begin{bmatrix} -1 & -3/2 \\ 1 & 1 \end{bmatrix}$$

9. Finding |A| via Laplace expansion along the 4th column:

$$\begin{vmatrix} A & = 0 + (-1)(-1)^{5} & 0 & -1 & 3 \\ -1 & 2 & 1 & + 0 + (-1)(-1)^{7} & 0 & -1 & 3 \\ 3 & 1 & -2 & 3 & 1 & -2 \end{vmatrix} = -22 + 37 = \boxed{15}$$

$$\begin{vmatrix} 0 & -1 & 3 \\ -1 & 2 & 1 \\ 3 & 1 & -2 \end{vmatrix} = 0 + (-1)(-1)^{3} \begin{vmatrix} -1 & 1 \\ 3 & -2 \end{vmatrix} + (3)(-1)^{4} \begin{vmatrix} -1 & 2 \\ 3 & 1 \end{vmatrix} = -1 - 21 = -22$$

$$\begin{vmatrix} 2 & 4 & 1 \\ 0 & -1 & 3 \\ 3 & 1 & -2 \end{vmatrix} = (2)(-1)^{2} \begin{vmatrix} -1 & 3 \\ 1 & -2 \end{vmatrix} + (0 + (3)(-1)^{4} \begin{vmatrix} 4 & 1 \\ -1 & 3 \end{vmatrix} = (2)(-1) + (3)(13) = 37$$

Or, finding |A| using GE:

$$\begin{vmatrix} 2 & 4 & 1 & -1 \\ 0 & -1 & 3 & 0 \\ -1 & 2 & 1 & -1 \\ 3 & 1 & -2 & 0 \end{vmatrix} = \begin{pmatrix} -1 \end{pmatrix} \begin{vmatrix} -1 & 2 & 1 & -1 \\ 0 & -1 & 3 & 0 \\ 2 & 4 & 1 & -1 \\ 3 & 1 & -2 & 0 \end{vmatrix} = \begin{pmatrix} -1 \end{pmatrix}^2 \begin{vmatrix} -1 & 2 & 1 & -1 \\ 0 & 1 & -3 & 0 \\ 2 & 4 & 1 & -1 \\ 3 & 1 & -2 & 0 \end{vmatrix} = \begin{pmatrix} -1 \end{pmatrix}^2 \begin{vmatrix} -1 & 2 & 1 & -1 \\ 0 & 1 & -3 & 0 \\ 0 & 8 & 3 & -3 \\ 0 & 7 & 1 & -3 \end{vmatrix}$$

$$5ingle \ row \ swap \qquad multiplied \ r_2 \ by \ (-1)$$

$$2r_1 + r_2 \rightarrow r_4$$

$$= (-1)^{2} \begin{vmatrix} -1 & 2 & 1 & -1 \\ 0 & 1 & -3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 7 & 1 & -3 \end{vmatrix} = (-1)^{2} \begin{vmatrix} -1 & 2 & 1 & -1 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 5 & 0 \\ 0 & 0 & 22 & -3 \end{vmatrix} = (-1)^{2} (5) \begin{vmatrix} -1 & 2 & 1 & -1 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 22 & -3 \end{vmatrix}$$

$$r_{3} - r_{4} \rightarrow r_{3}$$

$$r_{4} - 7r_{2} \rightarrow r_{4}$$

$$r_{4} - 7r_{2} \rightarrow r_{4}$$

$$= (-1)^{2}(5) \begin{vmatrix} -1 & 2 & 1 & -1 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -3 \end{vmatrix} = (-1)^{2}(5) \cdot (-1)(1)(1)(-3) = 15$$

$$r_{4} - 22r_{3} \rightarrow r_{4}$$

$$(5ame as)$$