Math 231, Fri 12-Feb-2021 -- Fri 12-Feb-2021 Differential Equations and Linear Algebra Spring 2020

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Topic:: Column space

Topic:: Linear independence

Read:: ODELA 1.6

## One new term:

- so far

/ Is b in the span of set of vectors

Are there weights such that a linear combination of vectors produces b?

Does a system of m equations in n unknowns have a solution?

 $\langle$  Is Ax = b consistent?

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Is b in the column space of A

Col(A) is same as range of the map  $f:R^n \rightarrow R^m$  given by f(x) = Ax

When we solve Ax=b we

are successful only if b is in this range (Col(A))

find all x in the domain that "map" to b

Null(A) consists of those x in domain that map to 0 vector

- Determine whether any/all are true by doing GE on augmented [A | b]

Can use GE to describe the column space of A\_{mxn}

- if RREF(A) has a pivot in every row, then col(A) = R^m
- when RREF(A) has a row of zeros at hottom, the story is more interesting example: A = [2 -1 5; 1 1 1; -1 2 -4]

Take a nonzero vector u\_1 in R^n

- What would a vector w in R^n look like if it were in span(u\_1)?
  What would RREF([u\_1 w]) look like?
  span(u\_1, w) = span(u\_1) = line through origin in R^4
- Suppose u\_2 is in R^4 and is not in span(u\_1).
  Note how this means u\_2 goes off in another direction besides u\_1 span(u\_1, u\_2), a plane, is different from span(u\_1), a line

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u_1, u_2 are linearly independent
What would RREF([u_1 u_2]) look like?
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Do a null space problem

- make it a matrix with a nontrivial nullspace, perhaps #{rows} > #{cols}
- Write equivalent form of problem: generating  ${\bf 0}$  vector as lin.comb. cols of A Why does a nontrivial soln exist?

Geometrically, a nontrivial soln describe nontrivial paths to 0

- Defn: linear independence

Same as saying, with vectors at hand, only path to 0 is never to leave A statement about a collection

linear dependence is the opposite

Test for it

collection containing just one vector?

two L.I./L.D. vectors

RREF as a test

· null space - consists of vectors  $\vec{x} \in \mathbb{R}^n$ satisfying  $A\vec{x} = \vec{0}$ 

. column space - consists of all rectors  $\vec{b}$  (destructions) that make  $A\vec{x} = \vec{b}$  consistent

$$A = \begin{bmatrix} 2 & -1 & 5 \\ 1 & 1 & 1 \\ -1 & 2 & -4 \end{bmatrix}$$

Want to describe possible "destructions"  $\vec{l} = \langle b_1, b_2, b_3 \rangle$  — i.e. columns we can augment to A so that the problem  $A\vec{x} = \vec{b}$  is consistent.

$$\begin{bmatrix} 2 & -1 & 5 & b_1 \\ 1 & 1 & 1 & b_2 \\ -1 & 2 & -4 & b_3 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 & b_2 \\ 2 & -1 & 5 & b_1 \\ -1 & 2 & -4 & b_3 \end{bmatrix}$$

To be consisted, need 
$$b_3 - b_1 - b_1 = 0$$
 - one constraint on the 3 components of  $b$ 

$$\vec{b} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \text{is in Col}(A)$$
So Col(A) has 2 degrees of freedom

but  $\vec{b} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \text{isn't}$ .

So Col(A) hus 2 degrees of freedom

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Say I have a vector  $\vec{v}$ ,  $\epsilon R^m$  $\vec{V}_1 = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$ 

> What would a w look like if it is in span (v,)? Perhaps:  $\vec{w} = \begin{bmatrix} 4 \\ 2 \\ -6 \\ 2 \end{bmatrix}$  /  $\begin{bmatrix} -6 \\ -3 \\ q \\ 1 \end{bmatrix}$  , etc.

What if we built a matrix from I wo and took it to echelon form? นี้ . c = นึ่

 $\begin{bmatrix}
u, & w \\
\downarrow & \downarrow
\end{bmatrix}$   $\begin{cases}
Span(\overline{u}, \overline{w}) = Span(\overline{u}, \overline{w}) \\
\vdots & \vdots \\
Span(\overline{u}, \overline{w})
\end{cases}$ 

On the other hand, if select uz not in span of u,

then building a matrix from u, uz leads to RREF KREF DI We might say i, it are linearly independent. Span ( a, uz ) includes more things then span ( a, ) Take n, nz binearly independent and a third vector w. If wis in span (n, n):  $\begin{bmatrix} u_1 & u_2 & w \\ 1 & J & J \end{bmatrix} \qquad \begin{array}{c} RREF & 1 & 0 & * & 7 \\ 0 & 1 & * & 7 \\ 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \end{array}$ If w is not in spon of vi, in then  $\begin{bmatrix} u_1 & u_2 & v_1 \\ 1 & 1 & 1 \end{bmatrix}$   $\begin{bmatrix} RREF \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$   $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ \vdots & \vdots & \vdots \end{bmatrix}$ Span ( T, T, T) includes new destinations not forms in span (v., ū2).

Say a collection of vectors  $\vec{u}_1, \vec{u}_2, ..., \vec{u}_n \in \mathbb{R}^m$  is linearly sudepullent if (precisely when) the only weights  $c_1, c_2, ..., c_n$  that produce, under linear combination

0 = C, W, + C, W,

the zero vector that werk are  $C_1 = C_2 = ... C_n = 0$ . When  $\bar{u}_1,...,\bar{u}_n$  are not linearly independent, say they are linearly dependent.

Equalitations:

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\text{\text{\$\bar{u}\_1,...,\bar{u}\_n\$}} \] \text{\text{\$\lambda}} \]

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\text{RREF} \begin{pmatrix} \bar{u}\_1 \\ \alpha\_1 \\ \alpha\_2 \\ \alpha\_2 \\ \alpha\_2 \\ \alpha\_2 \\ \alpha\_2 \\ \alpha\_3 \\ \alpha\_2 \\ \alpha\_2 \\ \alpha\_3 \\ \alpha\_4 \\ \alpha\_2 \\ \alpha\_2 \\ \alpha\_3 \\ \alpha\_4 \\ \alpha\_2 \\ \alpha\_2 \\ \alpha\_3 \\ \alpha\_4 \\ \alpha\_4 \\ \alpha\_4 \\ \alpha\_4 \\ \alpha\_5 \\ \alph