1. Here

$$\mathbf{B} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} - \begin{bmatrix} 3 & 1 \\ -1 & -4 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -2 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} - \begin{bmatrix} 7 & -7 \\ 5 & 6 \\ 9 & 1 \end{bmatrix} = \begin{bmatrix} -6 & 9 \\ -2 & -2 \\ -4 & 5 \end{bmatrix}.$$

2. There is more than one correct answer. Here is one such sequence:

$$\begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (1/3)\mathbf{r}_3 \to \mathbf{r}_3 \quad \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \sim \quad \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \sim \quad \begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \sim \quad \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

3. The precondition to a system of *n* equations in *n* unknowns being *inconsistent* is that the matrix be singular. So, we calculate the determinant of the matrix (I'm expanding in cofactors along the first row)

$$\begin{vmatrix} 5 & -6 & -7 \\ 4 & -3 & k \\ 1 & 6 & 13 \end{vmatrix} = 5(-1)^2 \begin{vmatrix} -3 & k \\ 6 & 13 \end{vmatrix} - 6(-1)^3 \begin{vmatrix} 4 & k \\ 1 & 13 \end{vmatrix} - 7(-1)^4 \begin{vmatrix} 4 & -3 \\ 1 & 6 \end{vmatrix}$$
$$= 5(-39 - 6k) + 6(52 - k) - 7(24 + 3)$$
$$= -195 - 30k + 312 - 6k - 168 - 21 = -72 - 36k.$$

Solving to make this determinant zero, we have 36k = -72, or k = -2. To ensure the system is consistent, we must have $k \neq -2$.

4. (a) We form a matrix whose columns are the given vectors and take it to RREF:

$$\begin{bmatrix} 2 & -6 & -8 & -22 \\ 2 & -6 & -8 & -22 \\ -1 & 2 & 3 & 7 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 & 1 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

This shows that only two of the four vectors are linearly independent, as there are just 2 pivot columns. Thus, W is a 2-dimensional subspace of \mathbb{R}^3 , a plane.

- (b) We keep linearly independent columns of the matrix above as a basis. One option is the first two columns: \mathbf{v}_1 and \mathbf{v}_2 .
- 5. (a) The system has augmented matrix

Columns 3 and 4—or variables x_3 , x_4 —are free. Rows 1 and 2 of RREF say

$$x_1 = 13x_3 + 14x_4 - 23$$
 and $x_2 = 11x_3 + 12x_4 - 19$.

So, solutions of the system take the form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -23 \\ -19 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 13 \\ 11 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 14 \\ 12 \\ 0 \\ 1 \end{bmatrix}, \quad \text{with } x_3, x_4 \in \mathbb{R}.$$

(b) The matrix is the same as in part (a), so its null space is revealed in the answer to part (a) as the part with freedoms. A basis for the null space is

$$\begin{bmatrix} 13 \\ 11 \\ 1 \\ 0 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 14 \\ 12 \\ 0 \\ 1 \end{bmatrix}.$$

6. We have

$$0 = \begin{vmatrix} -7 - \lambda & -3 \\ 9 & -5 - \lambda \end{vmatrix} = (-7 - \lambda)(-5 - \lambda) + 27 = \lambda^2 - 12\lambda + 62,$$

$$\Rightarrow \lambda = \frac{1}{2} \left(12 \pm \sqrt{144 - (4)(62)} \right) = 6 \pm i \frac{\sqrt{104}}{2} = 6 \pm i \sqrt{26}.$$

7. If we call the given matrix **A**, then using the given eigenvalue λ , the problem "solve $(\mathbf{A} - \lambda \mathbf{I})\mathbf{x} = \mathbf{0}$ " has augmented matrix

$$\begin{bmatrix} \mathbf{A} + 2\mathbf{I} \, \middle| \, \mathbf{0} \end{bmatrix} \ = \ \begin{bmatrix} 4 & 0 & -8 & 0 \\ 4 & 0 & -8 & 0 \\ 2 & 0 & -4 & 0 \end{bmatrix} \ \Rightarrow \ \begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

RREF has two free columns (so that is the dimension of the eigenspace), and we take x_2 and x_3 , components of an eigenvector, as free, leading to eigenvectors of the form

$$\begin{bmatrix} 2x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}.$$

Thus,

$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$$

span the eigenspace. They are also linearly independent, making this collection a basis.