1. (a) 
$$\overrightarrow{QP} = \langle 2-4, -1+2, -3-1 \rangle = \langle -2, 1, -4 \rangle$$
.  
 $\|\overrightarrow{QP}\| = \sqrt{(-2)^2 + 1^2 + (-4)^2} = \sqrt{21}$   
 $\Rightarrow \overrightarrow{u} = \frac{\overrightarrow{QP}}{\|\overrightarrow{QP}\|} = -\frac{2}{\sqrt{21}} \hat{i} + \frac{1}{\sqrt{21}} \hat{j} - \frac{4}{\sqrt{21}} \hat{k}$ .

(b) Take 
$$\vec{v} = \vec{QP}$$
, found in (a). Take  $\vec{w}$  to be the vector  $\vec{w} = \vec{QR} = \langle 1-4, 3+2, -2-1 \rangle = \langle -3, 5, -3 \rangle$ .

Then

 $\cos \theta = \frac{\vec{w} \cdot \vec{v}}{\|\vec{w}\| \|\vec{v}\|} = \frac{6+5+12}{\sqrt{43} \cdot \sqrt{21}} = \frac{23}{\sqrt{903}}$ 

2. (a) 
$$\vec{w} \times \vec{v} = \begin{vmatrix} \hat{\iota} & \hat{j} & \hat{k} \\ 1 & 3 & -2 \\ 4 & -2 & 1 \end{vmatrix} = \begin{vmatrix} 3 & -2 \\ -2 & 1 \end{vmatrix} \hat{\iota} - \begin{vmatrix} 1 & -2 \\ 4 & 1 \end{vmatrix} \hat{j} + \begin{vmatrix} 1 & 3 \\ 4 & -2 \end{vmatrix} \hat{k}$$

$$= \hat{\iota} - 9\hat{j} - 14\hat{k}$$