1. 
$$\begin{vmatrix} 2 & 1 & 0 & -1 \\ 0 & 3 & -1 & 0 \end{vmatrix} = (3)(-1)^{4} \begin{vmatrix} 2 & 0 & -1 \\ -2 & k & 0 & 2 \\ -4 & 0 & -1 & 6 \end{vmatrix} = (3)(-1)^{4} \begin{vmatrix} 2 & 0 & -1 \\ -2 & 0 & 2 \\ -4 & -1 & 6 \end{vmatrix} + (-1)(-1)^{5} \begin{vmatrix} 2 & 1 & -1 \\ -4 & 0 & 6 \end{vmatrix}$$

$$= 3(-1)(-1)^{5} \begin{vmatrix} 2 & -1 \\ -2 & 2 \end{vmatrix} + (-1)^{3} \begin{vmatrix} -2 & 2 \\ -4 & 6 \end{vmatrix} + k(-1)^{4} \begin{vmatrix} 2 & -1 \\ -4 & 6 \end{vmatrix} = 6 + 4 + 8k = 10 + 8k$$
Solve  $10 + 8k = 0 \implies k = -5/4$ .

2. (a) Since 
$$\operatorname{rref}(A) = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

has a free column (two, in fact),  $\operatorname{null}(A) = \operatorname{null}(A - 0.I)$  is nontrivial. Thus, O is an eigenvalue of A.

- (b) And because rref(A) has pivots in columns 1 and 3, it follows that  $\{\langle 1,2,0,0\rangle,\langle 0,0,1,2\rangle\}$  (columns 1 and 3 from A itself) form a basis for col(A).
- 3, (a) True. Any free column is in the span of its preceding columns.
  - (b) True.
  - (c) False. There are plenty of singular square matrices.
  - (d) True. A trivial null space coincides with no free columns.
  - (e) False. The column space of an lak matrix is a subspace of R.
  - (f) True. The condition ensures RREF of A doesn't have a row of zeros.
- 4. Call the given matrix A. Eigenvectors corresponding to  $\lambda=-$  are in null (A+I). So, we solve  $(A+I)\vec{v}=\vec{0}$ :

$$\begin{bmatrix} -4 & 0 & -2 & 0 \\ -10 & 0 & -5 & 0 \\ 8 & 0 & 4 & 0 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{I_1 + \frac{1}{2}I_3 = 0}$$

Eigenvectors look like

$$\vec{\nabla} = \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2}\sigma_3 \\ \sigma_2 \\ \sigma_3 \end{bmatrix} = \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \end{bmatrix} + \begin{bmatrix} \sigma_2 \\ \sigma_3 \\ \sigma_4 \end{bmatrix}.$$

Thus, basis vectors for the eigenspace  $E_{-2}$  are (0,1,0) and (-1,0,2)

5. 
$$0 = \det(A - \lambda I) = \begin{vmatrix} 5 - \lambda & 5 \\ -5 & -3 - \lambda \end{vmatrix} = (5 - \lambda)(-3 - \lambda) + 25$$

$$= \lambda^2 - 2\lambda + 10 \qquad \Rightarrow \lambda = \frac{1}{2}(2 \pm \sqrt{4 - 40})$$

$$= \frac{1}{2}(2 \pm 6i) = 1 \pm 3i$$

eigenvalues are 1+3; and 1-3;

6. The system in matrix form is

$$\begin{bmatrix} 3 & -2 & 2 & 0 \\ -1 & 2 & 6 & 0 \\ 2 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ x \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 2 \\ \hline x \end{bmatrix}$$

To solve, we build the augmented matrix

$$\begin{bmatrix} 3 & -2 & 2 & 0 & | & -1 \\ -1 & 2 & 6 & 0 & 0 \\ 2 & 0 & 0 & 1 & | & 2 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & \frac{1}{2} & | & 1 \\ 0 & 1 & 0 & \frac{5}{8} & | & \frac{13}{8} \\ 0 & 0 & 1 & -\frac{1}{8} & | & -\frac{3}{8} \end{bmatrix}$$

$$\times y = 3$$

$$\times$$

Solutions satisfy  $\Rightarrow \begin{vmatrix} x \\ y \\ z \end{vmatrix} = \begin{vmatrix} 13/8 \\ -3/8 \end{vmatrix} + 3 \begin{vmatrix} -1/2 \\ -5/8 \\ 1/8 \end{vmatrix}$ x = 1 - 1/2 w y = 13/8 - 5/8 w Z = -3/8 + 1/8 W with w free (anything in R)

with well.