Math 231, Mon 8-Feb-2021 -- Mon 8-Feb-2021 Differential Equations and Linear Algebra Spring 2020

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Monday, February 8th 2021

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Wk 2, Mo

Topic:: Matrix-matrix arithmetic

Read:: ODELA 1.3-1.4

Conclusions added to the end of Friday's class notes Questions/issues over homework Identifying row echelon forms

echelon form:
. first nonzero entry in each row (pivot) further to right than in previous 10005
- all completely-zeroed rows are at bothom

## Follow-up

- What if a 2-by-2 augmented matrix represents a consistent system
  - What possible echelon form?
  - What implication about the two column vectors?
  - inconsistent system
    - What possible echelon form?
    - What implication about the two column vectors?
- What if a 2-by-3 augmented matrix represents a consistent system inconsistent system
- What if a 3-by-3 augmented matrix represents a consistent system inconsistent system

## Matrix algebra

- adding
- rescaling
- multiplication
  - define it
  - do an example
  - implications on dimensions
    - may make sense as AB, but not as BA
    - ==> commutativity is out
  - a necessary (but not sufficient) condition for AB = BA is being square identity matrix
- solving Ax = b by "division"

cannot divide matrices
might conceive of a matrix C for which AC = CA = I
 A would need to be square (C, too)
 If such a C exists, then Ax = b has solution x = Cb
- Using AC = I and GE to find inverse
 Do for 2-by-2 matrix A = [a b; c d]

man metric 
$$\frac{1}{2}$$
 and  $\frac{1}{2}$  and  $\frac{1$ 

and I to melt 2 metrices

A B = A 
$$\begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \cdots & \vec{b}_p \\ \vec{v} & \vec{v} & \vec{v} \end{bmatrix}$$

$$:= \begin{bmatrix} A\vec{b}_1 & A\vec{b}_2 & \cdots & A\vec{b}_p \\ A\vec{b}_2 & \cdots & A\vec{b}_p \end{bmatrix}$$

$$:=\begin{bmatrix} A\overline{b}_1, & A\overline{b}_2 & \cdots & A\overline{b}_p \\ \downarrow & \downarrow & \downarrow \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 2 & 1 & 4 \\ 1 & 0 & -3 \end{bmatrix}$$
 $B = \begin{bmatrix} 4 & -2 \\ 1 & 2 \\ -2 & 1 \end{bmatrix}$ 
 $3x2$ 

$$B = \begin{bmatrix} 4 & -2 \\ 1 & 2 \\ -2 & 1 \end{bmatrix}$$

$$3x2$$

$$\Rightarrow \hat{J}_{1} = \begin{bmatrix} 4 \\ 1 \\ -2 \end{bmatrix}, \quad \hat{J}_{2} = \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix}$$

$$\overrightarrow{Ab}_{1} = y \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} -1 \\ 4 \\ -3 \end{bmatrix} = \begin{bmatrix} 8 \\ 1 \\ 10 \end{bmatrix}$$

$$\mathbf{A}\mathbf{\bar{b}}_{2} = -2\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + 2\begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} + 1\begin{bmatrix} -1 \\ 4 \\ -3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ -5 \end{bmatrix}$$

$$AB = \begin{bmatrix} b_1 & b_2 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 8 & 1 \\ 1 & 2 \\ 10 & -5 \end{bmatrix}_{3\times 2}$$

$$AB = \begin{bmatrix} AB & 1 \\ 1 & 2 \\ 1 & AB \end{bmatrix}$$