$$\begin{vmatrix} -1 & 0 & -2 & -7 \\ 1 & 2 & k & 0 \\ 0 & -1 & 0 & 1 \\ 3 & 0 & 2 & 5 \end{vmatrix} = (-1)(-1) \begin{vmatrix} 5 & -1 & -2 & -7 \\ 1 & k & 0 & + (-1) \end{vmatrix} \begin{vmatrix} -1 & 0 & -2 \\ 1 & k & 0 & + (-1) \end{vmatrix} \begin{vmatrix} -1 & 0 & -2 \\ 1 & 2 & k \end{vmatrix}$$

$$= (-1)^{3} \begin{vmatrix} -2 & -7 \\ 2 & 5 \end{vmatrix} + k(-1) \begin{vmatrix} 2 & -1 & -7 \\ 3 & 5 \end{vmatrix} - 2(-1)^{2} \begin{vmatrix} -1 & -2 \\ 3 & 2 \end{vmatrix} = -4 + 16k - 8 = -12 + 16k$$

$$Solve \qquad -12 + 16k = 0 \implies k = 3/4$$

2. (a) Since 
$$\operatorname{rref}(A) = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

has a free column (two, in fact), null(A) = null(A - 0.I) is nontrivial. Thus, O is an eigenvalue of A.

- (6) And because rref(A) has pivots in columns 1 and 3, it follows that  $\{\langle 1, 1, 0, 2 \rangle, \langle -1, 0, 1, -1 \rangle\}$  (columns 1 and 3 from A itself) form a basis for col(A).
- 3. (a) False. It is a subspace of R.
  - (6) True. L=l forces A to be square.
  - (c) False. The statement could be fixed by replacing "dependent" wy "independent."
  - (d) True. The condition ensures RREF of A doesn't have a row of zeros.
  - (e) True. A free column lies in the spen of its preceding columns.
  - (f) True.
- 4. Call the given matrix A. Eigenvectors corresponding to  $\lambda=-2$  are in null (A+ZI). So, we solve  $(A+ZI)\ddot{v}=\vec{0}$ :

$$\begin{bmatrix} G & -G & -G & O \\ G & -G & -G & O \\ -3 & 3 & 3 & O \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} I & -I & -I & O \\ O & O & O & O \\ O & O & O & O \end{bmatrix}$$

$$\begin{bmatrix} G_{1} & -G_{2} & -G_{3} & = 0 \\ G & O & O & O \\ G & G_{2}, G_{3} & free \end{bmatrix}$$

Eigenvectors look like

$$\vec{\mathcal{T}} = \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \mathbf{v}_3 \end{bmatrix} = \begin{bmatrix} \mathbf{v}_2 + \mathbf{v}_3 \\ \mathbf{v}_2 \\ \mathbf{v}_3 \end{bmatrix} = \mathbf{v}_2 \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_3 \\ \mathbf{v}_3 \end{bmatrix} + \mathbf{v}_3 \begin{bmatrix} \mathbf{v}_2 \\ \mathbf{v}_3 \\ \mathbf{v}_3 \end{bmatrix}.$$

Thus, basis vectors for the eigenspace  $E_{-2}$  are  $\langle 1, 1, 0 \rangle$  and  $\langle 1, 0, 1 \rangle$ .

5. 
$$0 = \det(A - \lambda I) = \begin{vmatrix} -5 - \lambda & 13 \\ -1 & 1 - \lambda \end{vmatrix} = (-5 - \lambda)(1 - \lambda) + 13$$
$$= \lambda^{2} + 4\lambda + 8 \qquad \Rightarrow \lambda = \frac{1}{2}(-4 \pm \sqrt{16 - 32})$$
$$= \frac{1}{2}(-4 \pm 4i) = -2 \pm 2i.$$

eigenvalues are -2-2i and -2+2i.

6. The system in matrix form is

$$\begin{bmatrix} 3 & -2 & 4 & 0 \\ 1 & 2 & -4 & 0 \\ 0 & 0 & 3 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 3 \end{bmatrix}$$

$$\overrightarrow{A}$$

To solve, we build the augmented matrix

Solutions sochisfy

$$x = -\frac{1}{4}$$

$$y = \frac{13}{8} - \frac{2}{3}\omega$$

$$z = 1 - \frac{1}{3}\omega$$
with where (anything in R)

with we IR.