• There are some matrices **A** for which  $\mathbf{A}^T = \mathbf{A}$ . Such matrices are said to be **symmetric**.

# 1.3 Matrix Multiplication and Systems of Linear Equations

### 1.3.1 Several interpretations of matrix multiplication

In the previous section we saw what is required (in terms of matrix dimensions) in order to be able to produce the product **AB** of two matrices **A** and **B**, and we saw how to produce this product. There are several useful ways to conceptualize this product, and in this first sub-section we will investigate them. We first make a definition.

**Definition 3:** Let  $A_1, A_2, ..., A_k$  be matrices all having the same dimensions. For each choice of real numbers  $c_1, ..., c_k$ , we call

$$c_1\mathbf{A}_1 + c_2\mathbf{A}_2 + \cdots + c_k\mathbf{A}_k$$

a **linear combination** of the matrices  $A_1, \ldots, A_k$ . The set of all such linear combinations

$$S := \{c_1 \mathbf{A}_1 + c_2 \mathbf{A}_2 + \dots + c_k \mathbf{A}_k \, | \, c_1, \dots, c_k \in \mathbb{R} \}$$

is called the **linear span** (or simply **span**) of the matrices  $A_1, \ldots, A_k$ . We sometimes write  $S = \text{span}(\{A_1, \ldots, A_k\})$ .

Here, now, are several different ways to think about product **AB** of two appropriately sized matrices **A** and **B**.

1. **Block multiplication**. This is the first of four descriptions of matrix multiplication, and it is the most general. In fact, each of the three that follow is a special case of this one.

Any matrix (table) may be separated into **blocks** (or *submatrices*) via horizontal and vertical lines. We first investigate the meaning of matrix multiplication at the block level when the left-hand factor of the matrix product **AB** has been subdivided using only vertical lines, while the right-hand factor has correspondingly been blocked using only horizontal lines.

### Example 2:

Suppose

$$\mathbf{A} = \begin{bmatrix} 8 & 8 & 3 & -4 & 5 \\ 6 & -6 & 1 & -8 & 6 \\ 5 & 3 & 4 & 2 & 7 \end{bmatrix} = \begin{bmatrix} \mathbf{A}_1 & \mathbf{A}_2 & \mathbf{A}_3 \end{bmatrix}$$

(Note how we have named the three blocks found in A!), and

$$\mathbf{B} = \begin{bmatrix} -3 & 5 & -5 & -2 \\ 2 & -2 & 2 & -7 \\ \hline -6 & 6 & 0 & 3 \\ \hline -3 & 2 & -5 & 0 \\ 0 & -1 & -1 & 4 \end{bmatrix} = \begin{bmatrix} \mathbf{B}_1 \\ \overline{\mathbf{B}_2} \\ \overline{\mathbf{B}_3} \end{bmatrix}.$$

Then

$$\begin{array}{lll} \mathbf{AB} & = & \mathbf{A}_1\mathbf{B}_1 + \mathbf{A}_2\mathbf{B}_2 + \mathbf{A}_3\mathbf{B}_3 \\ & = & \begin{bmatrix} 8 & 8 \\ 6 & -6 \\ 5 & 3 \end{bmatrix} \begin{bmatrix} -3 & 5 & -5 & -2 \\ 2 & -2 & 2 & -7 \end{bmatrix} + \begin{bmatrix} 3 \\ 1 \\ 4 \end{bmatrix} \begin{bmatrix} -6 & 6 & 0 & 3 \end{bmatrix} + \begin{bmatrix} -4 & 5 \\ -8 & 6 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} -3 & 2 & -5 & 0 \\ 0 & -1 & -1 & 4 \end{bmatrix} \\ & = & \begin{bmatrix} -8 & 24 & -24 & -72 \\ -30 & 42 & -42 & 30 \\ -9 & 19 & -19 & -31 \end{bmatrix} + \begin{bmatrix} -18 & 18 & 0 & 9 \\ -6 & 6 & 0 & 3 \\ -24 & 24 & 0 & 12 \end{bmatrix} + \begin{bmatrix} 12 & -13 & 15 & 20 \\ 24 & -22 & 34 & 24 \\ -6 & -3 & -17 & 28 \end{bmatrix} \\ & = & \begin{bmatrix} -14 & 29 & -9 & -43 \\ -12 & 26 & -8 & 57 \\ -39 & 40 & -36 & 9 \end{bmatrix}. \end{array}$$

While we were trying to keep things simple in the previous example by drawing only vertical lines in **A**, the number and locations of those vertical lines was somewhat arbitrary. Once we chose how to subdivide **A**, however, the horizontal lines in **B** had to be drawn to create blocks with rows as numerous as the columns in the blocks of **A**.

Now, suppose we subdivide the left factor with *both* horizontal and vertical lines. Say that

$$\mathbf{A} = \begin{bmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} \\ \mathbf{A}_{21} & \mathbf{A}_{22} \\ \mathbf{A}_{31} & \mathbf{A}_{32} \end{bmatrix}.$$

Where the vertical line is drawn in **A** continues to dictate where a horizontal line must be drawn in the right-hand factor **B**. On the other hand, if we draw any vertical

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lines in to create blocks in the right-hand factor **B**, they can go anywhere, paying no heed to where the horizontal lines appear in **A**. Say that

$$\mathbf{B} = \begin{bmatrix} \mathbf{B}_{11} & \mathbf{B}_{12} & \mathbf{B}_{13} & \mathbf{B}_{14} \\ \mathbf{B}_{21} & \mathbf{B}_{22} & \mathbf{B}_{23} & \mathbf{B}_{24} \end{bmatrix}.$$

Then

#### Example 3:

Suppose **A**, **B** are the same as in Example 2. Let's subdivide **A** in the following (arbitrarily chosen) fashion:

$$\mathbf{A} = \begin{bmatrix} 8 & 8 & 3 & -4 & 5 \\ 6 & -6 & 1 & -8 & 6 \\ 5 & 3 & 4 & 2 & 7 \end{bmatrix} = \begin{bmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} \\ \mathbf{A}_{21} & \mathbf{A}_{22} \end{bmatrix}.$$

Given the position of the vertical divider in **A**, we must place a horizontal divider in **B** as shown below. Without any requirements on where vertical dividers appear, we choose (again arbitrarily) not to have any.

$$\mathbf{B} = \begin{bmatrix} -3 & 5 & -5 & -2 \\ 2 & -2 & 2 & -7 \\ -6 & 6 & 0 & 3 \\ -3 & 2 & -5 & 0 \\ \hline 0 & -1 & -1 & 4 \end{bmatrix} = \begin{bmatrix} \mathbf{B}_1 \\ \mathbf{B}_2 \end{bmatrix}.$$

Then

$$\mathbf{AB} = \begin{bmatrix} \frac{\mathbf{A}_{11}\mathbf{B}_{1} + \mathbf{A}_{12}\mathbf{B}_{2}}{\mathbf{A}_{21}\mathbf{B}_{1} + \mathbf{A}_{22}\mathbf{B}_{2}} \end{bmatrix}$$

$$= \begin{bmatrix} \begin{bmatrix} 8 & 8 & 3 & -4 \end{bmatrix} \begin{bmatrix} -3 & 5 & -5 & -2 \\ 2 & -2 & 2 & -7 \\ -6 & 6 & 0 & 3 \\ -3 & 2 & -5 & 0 \end{bmatrix} + 5 \begin{bmatrix} 0 & -1 & -1 & 4 \end{bmatrix} \\ \begin{bmatrix} 6 & -6 & 1 & -8 \\ 5 & 3 & 4 & 2 \end{bmatrix} \begin{bmatrix} -3 & 5 & -5 & -2 \\ 2 & -2 & 2 & -7 \\ -6 & 6 & 0 & 3 \\ -3 & 2 & -5 & 0 \end{bmatrix} + \begin{bmatrix} 6 \\ 7 \end{bmatrix} \begin{bmatrix} 0 & -1 & -1 & 4 \end{bmatrix} \\ \end{bmatrix}$$

$$= \begin{bmatrix} -14 & 29 & -9 & -43 \\ -12 & 26 & -8 & 57 \\ -39 & 40 & -36 & 9 \end{bmatrix}.$$

2. **Sums of rank-one matrices**. Now let us suppose that **A** has *n* columns and **B** has *n* rows. Suppose also that we block (as described allowed for in the previous case above) **A** by column—one column per block—and correspondingly **B** by row:

$$\mathbf{A} = \left[ \begin{array}{c|c} \mathbf{A}_1 & \mathbf{A}_2 & \cdots & \mathbf{A}_n \end{array} \right] \quad \text{and} \quad \mathbf{B} = \begin{bmatrix} \frac{\mathbf{B}_1}{\mathbf{B}_2} \\ \vdots \\ \hline \mathbf{B}_n \end{bmatrix}.$$

Following Example 2, we get

$$\mathbf{AB} = \mathbf{A}_1 \mathbf{B}_1 + \mathbf{A}_2 \mathbf{B}_2 + \dots + \mathbf{A}_n \mathbf{B}_n = \sum_{i=1}^n \mathbf{A}_i \mathbf{B}_i$$
 (1.1)

The only thing new here to say concerns the individual products  $\mathbf{A}_j \mathbf{B}_j$  themselves, in which the first factor  $\mathbf{A}_j$  is a vector in  $\mathbb{R}^m$  and the  $2^{\text{nd}} \mathbf{B}_j$  is the *transpose* of a vector in  $\mathbb{R}^p$  (for some m and p).

So, take  $\mathbf{u} \in \mathbb{R}^m$  and  $\mathbf{v} \in \mathbb{R}^p$ . Since  $\mathbf{u}$  is m-by-1 and  $\mathbf{v}^T$  is 1-by-p, the product  $\mathbf{u}\mathbf{v}^T$ , called the **outer product** of  $\mathbf{u}$  and  $\mathbf{v}$ , makes sense, yielding an m-by-p matrix.

#### Example 4:

Given  $\mathbf{u} = (-1, 2, 1)$  and  $\mathbf{v} = (3, 1, -1, 4)$ , their vector outer product is

$$\mathbf{u}\mathbf{v}^T = \begin{bmatrix} -1\\2\\1 \end{bmatrix} \begin{bmatrix} 3 & 1 & -1 & 4 \end{bmatrix} = \begin{bmatrix} -3 & -1 & 1 & -4\\6 & 2 & -2 & 8\\3 & 1 & -1 & 4 \end{bmatrix}.$$

If you look carefully at the resulting outer product in the previous example, you will notice it has relatively simple structure—its 2<sup>nd</sup> through 4<sup>th</sup> columns are simply scalar multiples of the first, and the same may be said about the 2<sup>nd</sup> and 3<sup>rd</sup> rows in relation to the 1<sup>st</sup> row. Later in these notes, we will define the concept of the **rank of a matrix**. Vector outer products are always matrices of rank 1 and thus, by (1.1), every matrix product can be broken into the sum of rank-one matrices.

3. **Linear combinations of columns of A**. Suppose **B** has p columns, and we partition it in this fashion (Notice that  $\mathbf{B}_j$  represents the  $j^{\text{th}}$  column of **B** instead of the  $j^{\text{th}}$  row, as it meant above!):

$$\mathbf{B} = \left[ \mathbf{B}_1 \mid \mathbf{B}_2 \mid \cdots \mid \mathbf{B}_p \right].$$

This partitioning by *vertical* lines of the right-hand factor in the matrix product **AB** does not place any constraints on how **A** is partitioned, and so we may write

$$\mathbf{A}\mathbf{B} = \mathbf{A} \left[ \begin{array}{c|c} \mathbf{B}_1 & \mathbf{B}_2 & \cdots & \mathbf{B}_p \end{array} \right] = \left[ \begin{array}{c|c} \mathbf{A}\mathbf{B}_1 & \mathbf{A}\mathbf{B}_2 & \cdots & \mathbf{A}\mathbf{B}_p \end{array} \right].$$

That is, for each j = 1, 2, ..., p, the  $j^{th}$  column of **AB** is obtained by left-multiplying the  $j^{th}$  column of **B** by **A**.

Having made that observation, let us consider more carefully what happens when **A**—suppose it has n columns  $\mathbf{A}_1, \mathbf{A}_2, \ldots, \mathbf{A}_n$ —multiplies a vector  $\mathbf{v} \in \mathbb{R}^n$ . (Note that each  $\mathbf{B}_i$  is just such a vector.) Blocking **A** by columns, we have

$$\mathbf{Av} = \left[ \begin{array}{c|c} \mathbf{A}_1 & \mathbf{A}_2 & \cdots & \mathbf{A}_n \end{array} \right] \left[ \begin{array}{c} \frac{v_1}{v_2} \\ \vdots \\ \hline v_n \end{array} \right] = v_1 \mathbf{A}_1 + v_2 \mathbf{A}_2 + \cdots + v_n \mathbf{A}_n.$$

That is, the matrix-vector product  $\mathbf{A}\mathbf{v}$  is simply a linear combination of the columns of  $\mathbf{A}$ , with the scalars multiplying these columns taken (in order, from top to bottom) from  $\mathbf{v}$ . The implication for the matrix product  $\mathbf{A}\mathbf{B}$  is that each of its columns  $\mathbf{A}\mathbf{B}_j$  is a linear combination of the columns of  $\mathbf{A}$ , with coefficients taken from the  $j^{\text{th}}$  column of  $\mathbf{B}$ .

4. **Linear combinations of rows of B**. In the previous interpretation of matrix multiplication, we begin with a partitioning of **B** via vertical lines. If, instead, we begin with a partitioning of **A**, a matrix with *m* rows, via horizontal lines, we get

$$\mathbf{AB} = \begin{bmatrix} \frac{\mathbf{A}_1}{\mathbf{A}_2} \\ \vdots \\ \mathbf{A}_m \end{bmatrix} \mathbf{B} = \begin{bmatrix} \frac{\mathbf{A}_1 \mathbf{B}}{\mathbf{A}_2 \mathbf{B}} \\ \vdots \\ \mathbf{A}_m \mathbf{B} \end{bmatrix}.$$

That is, the  $j^{th}$  row of the matrix product **AB** is obtained from left-multiplying the entire matrix **B** by the  $j^{th}$  row (considered as a submatrix) of **A**.

If **A** has n columns, then each  $\mathbf{A}_j$  is a 1-by-n matrix. The effect of multiplying a 1-by-n matrix **V** by an n-by-p matrix **B**, using a blocking-by-row scheme for **B**, is

$$\mathbf{VB} = \left[\begin{array}{c|c} v_1 & v_2 & \cdots & v_n \end{array}\right] \begin{bmatrix} \mathbf{B}_1 \\ \mathbf{B}_2 \\ \hline \cdots \\ \mathbf{B}_n \end{bmatrix} = v_1 \mathbf{B}_1 + v_2 \mathbf{B}_2 + \cdots + v_n \mathbf{B}_n ,$$

a linear combination of the rows of **B**. Thus, for each j = 1, ..., m, the  $j^{th}$  row  $\mathbf{A}_j \mathbf{B}$  of the matrix product  $\mathbf{A}\mathbf{B}$  is a linear combination of the rows of **B**, with coefficients taken from the  $j^{th}$  row of **A**.

## 1.3.2 Systems of linear equations

Motivated by Viewpoint 3 concerning matrix multiplication—in particular, that

$$\mathbf{A}\mathbf{x} = x_1\mathbf{A}_1 + x_2\mathbf{A}_2 + \dots + x_n\mathbf{A}_n$$

where  $\mathbf{A}_1, \ldots, \mathbf{A}_n$  are the columns of a matrix  $\mathbf{A}$  and  $\mathbf{x} = (x_1, \ldots, x_n) \in \mathbb{R}^n$ —we make the following definition.

**Definition 4:** Suppose  $\mathbf{A} = [\mathbf{A}_1 \mid \mathbf{A}_2 \mid \cdots \mid \mathbf{A}_n]$ , where each submatrix  $\mathbf{A}_j$  consists of a single column (so  $\mathbf{A}$  has n columns in all). The set of all possible linear combinations of these columns (also known as  $\text{span}(\{\mathbf{A}_1, \ldots, \mathbf{A}_n\}))$ 

$$\{c_1\mathbf{A}_1 + c_2\mathbf{A}_2 + \dots + c_n\mathbf{A}_n \mid c_1, c_2, \dots, c_n \in \mathbb{R}\}\$$

is called the **column space** of **A**. We use the symbol col(**A**) to denote the column space.