Bilinear Transformation = warping frequency axis

- d) Billnear Transform
- e) Impulse Invariance:

$$H_1(z) = \sum_{k=-\infty}^{\infty} H_{cl}(S-5\frac{2\pi}{T_d}k)$$

$$H_2(z) = \sum_{r=-\infty}^{\infty} H_{c_2}\left(S - j\frac{2\pi}{4}k\right)$$

$$H_1(z)H_2(z) = \sum_{k=-\infty}^{\infty} \sum_{\ell=-\infty}^{\infty} H_{c_1}(s-j\frac{2\pi}{T_d}k) H_{c_2}(s-j\frac{2\pi}{T_d}\ell) + H(z)$$

Bilinears Transformation:

Bilinear Transformation:

$$H_1(z)H_2(z) = H_{c1}\left[\frac{2}{T_d} \frac{1-z^{-1}}{1+z^{-1}}\right]H_{c2}\left[\frac{2}{T_d} \frac{1-z^{-1}}{1+z^{-1}}\right] = H_{c}\left[\frac{2}{T_d} \frac{1-z^{-1}}{1+z^{-1}}\right] = H(z)$$

Bilinear Transformation

$$7.27) \omega H(e^{j\omega}) = \begin{cases} 1, & |\omega| < \frac{\pi}{4} \\ 0, & |\pi| < |\omega| \le \pi \end{cases}$$

$$h(e^{j\omega}) = \begin{cases} 1, & |\pi| < |\pi| < \pi \end{cases}$$

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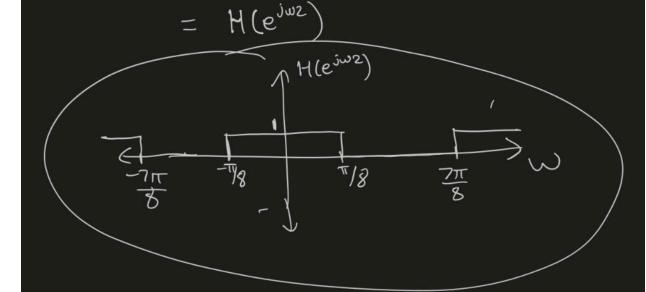
$$=$$

b)
$$h_2 I_n J = \begin{cases} h_1 V_2 J, & n = 0, \pm 2, \pm 4, \dots - 0 \end{cases}$$
 otherwise

$$H_2(e^{j\omega}) = \sum_{n=-\infty}^{\infty} h_2(n)e^{-j\omega n}$$

$$= \sum_{n=2k}^{\infty} h[n/2]e^{-j\omega n}$$

$$= \sum_{n=2k}^{\infty} h(n)e^{-j\omega 2n}$$



C)
$$h_3[n] = (-1)^n h[n]$$
 $H_3(e^{j\omega}) = \sum_{n=-\infty}^{\infty} (-1)^n h[n] e^{-3\omega n}$
 $= \sum_{n \text{ even}} h[n] e^{-j\omega n} - \sum_{n \text{ odd}} h[n] e^{-j\omega n}$
 $= H(e^{j(\omega + \pi)})$
 $H(e^{j(\omega + \pi)})$
 $H(e^{j(\omega + \pi)})$

$$0.98 < H(e^{j\omega}) < 1.02$$
, $0 \le |\omega| \le 0.63\pi$

$$-0.15 < H(e^{i\omega}) < 0.15$$
, $0.65\pi \le |w| \le \pi$

Analog Filter Specs:

$$0.98 < H(j\Omega) < 1.02$$
) $0 \le \Omega \le 2 \tan\left(\frac{0.63\pi r}{2}\right)$

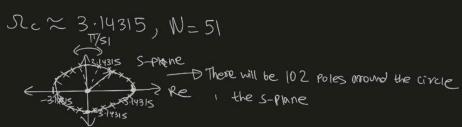
$$-0.15 < H(j\Omega) < 0.15$$
, $2 \tan\left(\frac{0.65\pi}{2}\right) \le \Omega \le \infty$

Design Constraints:

For Butterworth filter, $|H(j, \Omega)|^2 = \frac{1}{1 + (\frac{\Omega}{R})^{2N}}$ and due to its monotonic response:

$$1 + \left(\frac{2 \tan(0.315 \, \text{tr})}{52 \, \text{c}}\right)^{2 \, \text{N}} = \left(\frac{1}{0.98}\right)^{2}$$

$$1+\left(\frac{2\tan\left(0.325\pi\right)}{\mathcal{N}_{c}}\right)^{2N}=\left(\frac{1}{0.15}\right)^{2}$$



$$H_c(s) = \frac{\left(SC_c\right)^N}{\prod_{k=1}^N \left(s-s_k\right)}$$
 —D Rest of Steps are done using MATLAB code below

$$4) \quad \omega_{Pd} = \frac{2}{T_d} \tan\left(\frac{\omega_P}{2}\right)$$

$$w_{sd} = \frac{2}{T_d} \tan\left(\frac{w_s}{2}\right)$$

H₁(s) will have T_d = T₁ designed to pre-warp w_p \$ w_s

 $H_2(s)$ will have $T_0 = T_2$ with some pre-warped frequencies

$$H_2(s) = H_1\left(s\frac{T_1}{T_2}\right)$$

Storenog from $H_1(S) \longrightarrow H_1(Z) = H_1\left(\frac{2}{1}, \frac{1-z^{-1}}{1+z^{-1}}\right)$

$$H_2(z) = H_2\left(\frac{2}{T_2} \frac{1-z^{-1}}{1+z^{*}}\right) = H_1\left(\frac{2}{T_2} \frac{1-z^{-1}}{1+z^{-1}} \frac{T_1}{T_2}\right)$$

$$= H_1\left(\frac{2T_1}{T_2^2} \frac{1-z^{-1}}{1+z^{-1}}\right)$$

In the appropriate bilinear transformation:

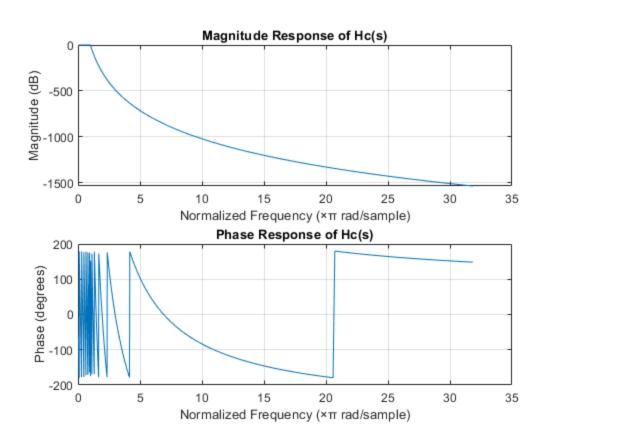
$$\frac{2}{T_1} = \frac{1 + 2^{-1}}{1 + 2^{-1}} = \frac{2T_1}{T_2^2} = \frac{1 + 2^{-1}}{1 + 2^{-1}}$$

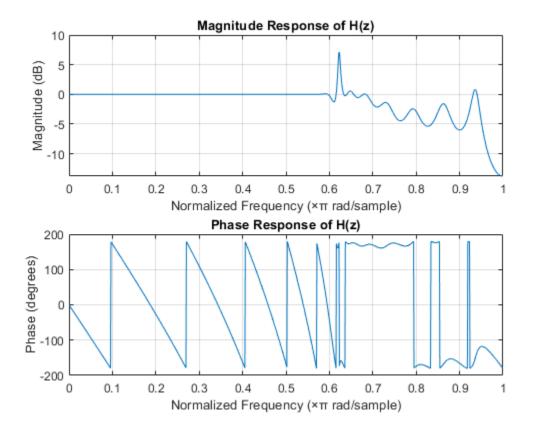
$$\frac{2}{T_{1}} = \frac{2T_{1}}{T_{2}^{2}} \longrightarrow \frac{1}{T_{1}} = \frac{T_{1}}{T_{2}^{2}} \longrightarrow T_{1}^{2} = T_{2}^{2}$$
Since $T_{1}, T_{2} \ge 0$

Given a bilinear transformation where $T_a = T_1 = T_2$, both H,(s) and Hz(s) will result in the same digital filter H(z).

```
% Given specifications
n = 51;
Omega c = 3.14315;
[z, p, k] = buttap(n); %returns poles and zeros and gain of Butterworth
filter with parameter n
p = p * Omega c;
k = k * Omega c^n;
[num, den] = zp2tf(z, p, k); %convert to transfer function form
Hc = tf(num, den); %transfer function of analog butterworth filter
[Hc freq, W c] = freqs(num, den, 1024);
magnitude = 20*log10 (abs(Hc freq));
phase = angle(Hc freq) * (180/pi);
figure;
subplot(2,1,1); % Magnitude plot
plot(W c/pi, magnitude);
title('Magnitude Response of Hc(s)');
xlabel('Normalized Frequency (×π rad/sample)');
ylabel('Magnitude (dB)');
grid on;
subplot(2,1,2); % Phase plot
plot(W c/pi, phase);
title('Phase Response of Hc(s)');
xlabel('Normalized Frequency (\times \pi rad/sample)');
ylabel('Phase (degrees)');
grid on;
fs = 1;
T = 1/fs;
[num z, den z] = bilinear(num, den, fs); % Convert Hc(s) to H(z) using
bilinear transform
Hz = tf(num z, den z, T);
disp(Hz);
[H freq, W] = freqz(num z, den z, 1024); % Compute frequency response
magnitude = 20*log10(abs(H freq)); % Convert to dB
phase = angle(H freq) * (180/pi); % Convert to degrees
figure;
subplot(2,1,1); % Magnitude plot
plot(W/pi, magnitude);
title('Magnitude Response of H(z)');
xlabel('Normalized Frequency (×π rad/sample)');
ylabel('Magnitude (dB)');
grid on;
subplot(2,1,2); % Phase plot
plot(W/pi, phase);
title('Phase Response of H(z)');
xlabel('Normalized Frequency (×π rad/sample)');
```

```
ylabel('Phase (degrees)');
grid on;
  tf with properties:
       Numerator: \{[2.4065e-09\ 1.2273e-07\ 3.0683e-06\ ...\ ]\ (1\times52\ double)\}
     Denominator: {[1 14.2001 104.7289 529.1458 2.0457e+03 ... ] (1×52 double)}
        Variable: 'z'
         IODelay: 0
      InputDelay: 0
     OutputDelay: 0
       InputName: {''}
       InputUnit: {''}
      InputGroup: [1×1 struct]
      OutputName: {''}
      OutputUnit: {''}
     OutputGroup: [1×1 struct]
           Notes: [0×1 string]
        UserData: []
            Name: ''
               Ts: 1
        TimeUnit: 'seconds'
    SamplingGrid: [1×1 struct]
```





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