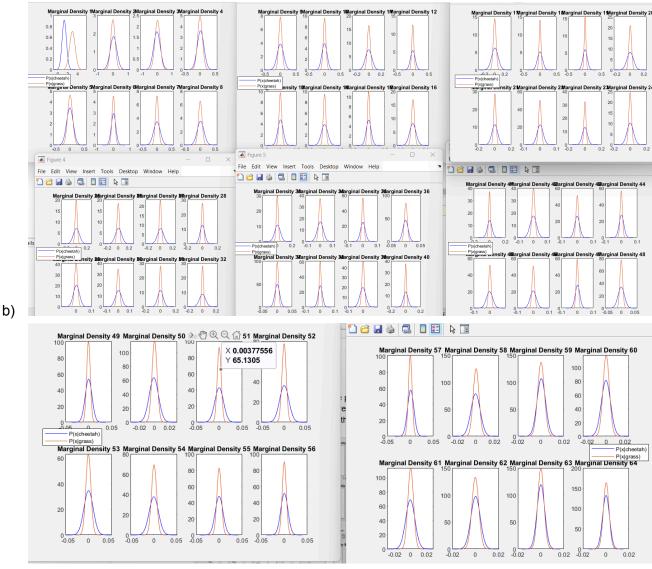
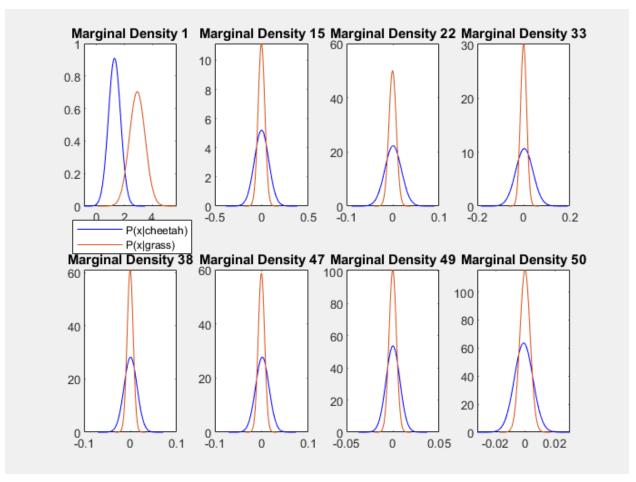
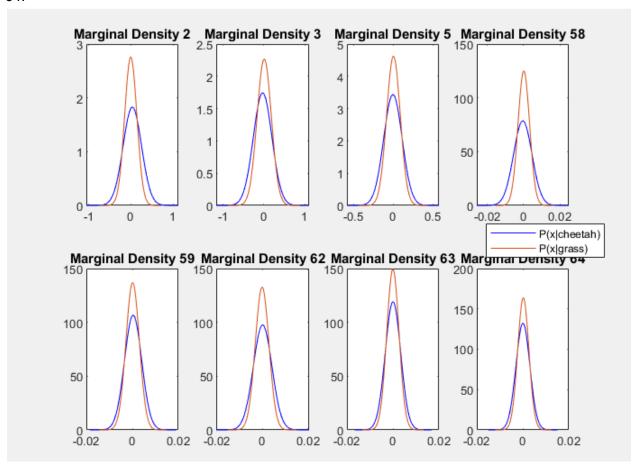
a) The maximum likelihood estimates of the prior probabilities are P(cheetah) = 0.1919 and P(grass) = 0.8081. These are the same results as HW1 and this means that the maximum likelihood priors are based on the proportion of the samples of the individual class with the total number of samples.



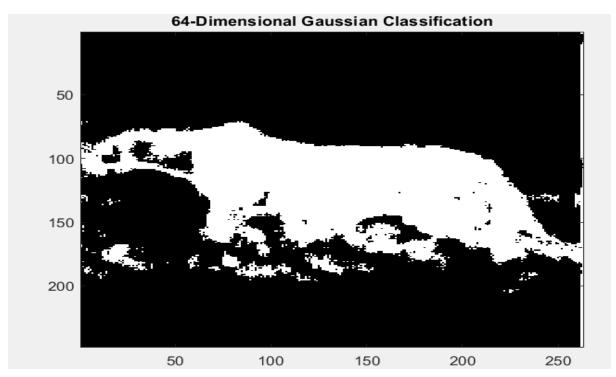
The best 8 features that I selected from visual inspection were Marginal Densities 1,15, 22, 33, 38, 47, 49, and 50.



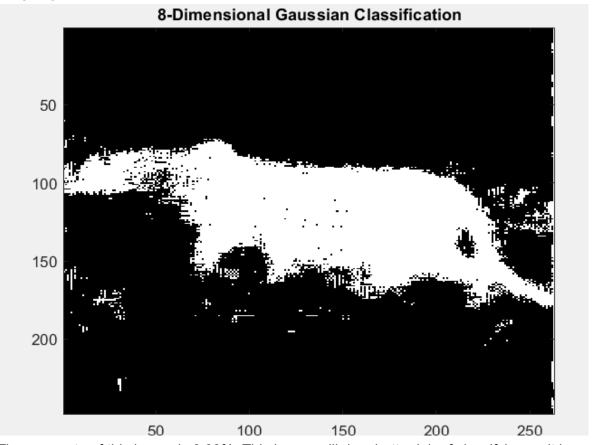
The worst 8 features that I selected were Marginal Densities 2, 3, 5, 58, 59, 62, 63, and



c) The Bayesian Decision Rule is P(x|cheetah)P(cheetah) > P(x|grass)P(grass). If this is true, then the component of the picture will be marked as the cheetah. Otherwise, it will be marked as the grass/background. The image I generate from classifying the 64 class-conditional marginal densities is:



The error rate of this image is 8.01%. When I classify using the best 8 features, the image I get is:



The error rate of this image is 6.03%. This image will do a better job of classifying as it is

proper classification.			

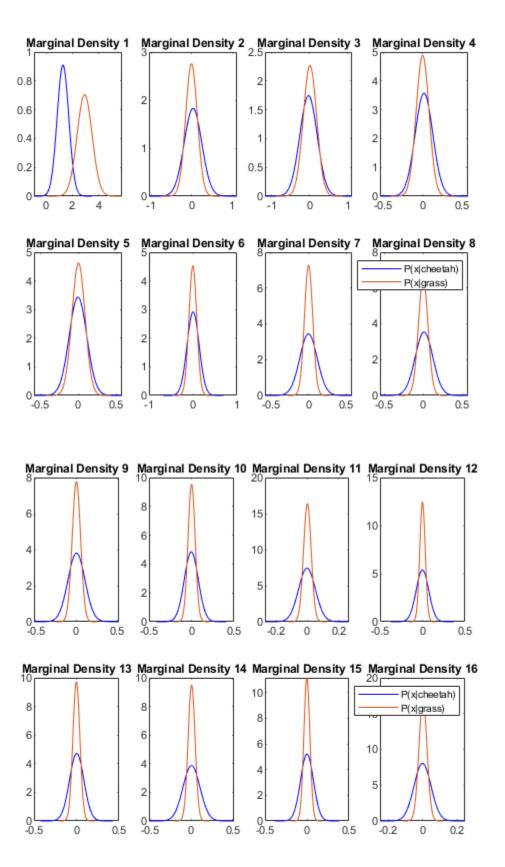
associated with the best 8 features and has less features that will come in the way of

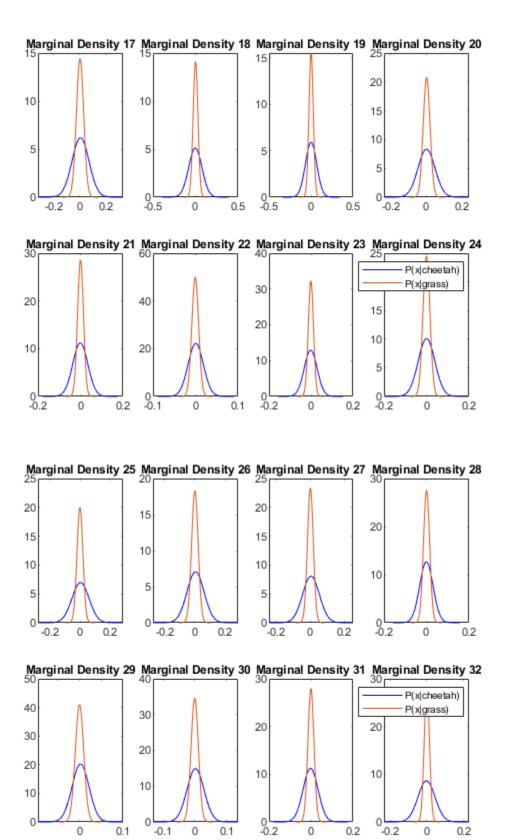
```
%a)
m = load('TrainingSamplesDCT 8 new.mat');
fg = m.TrainsampleDCT FG;
bg = m.TrainsampleDCT BG;
fg rows = size(fg, 1);
bg rows = size(bg, 1);
prior cheetah = fg rows / (fg rows + bg rows);
prior grass = bg rows / (fg rows + bg rows);
fprintf('P(Cheetah) = %.4f\n', prior cheetah);
fprintf('P(Grass) = %.4f\n', prior grass);
disp("The priors are the same as before.")
%b)
mean_fg = sum(fg) / fg rows;
mean bg = sum(bg) / bg rows;
std fg = std(fg);
std bg = std(bg);
x fg = zeros(64, 61);
y fg = zeros(64, 61);
x bg = zeros(64, 61);
y bg = zeros(64, 61);
for feature idx = 1:64
    x fg(feature idx, :) = linspace(mean fg(feature idx) - 5 *
std fg(feature idx), mean fg(feature idx) + 5 * std fg(feature idx), 61);
    y fg(feature idx, :) = normpdf(x fg(feature idx, :),
mean fg(feature idx), std fg(feature idx));
    x bg(feature idx, :) = linspace(mean bg(feature idx) - 5 *
std bg(feature idx), mean bg(feature idx) + 5 * std bg(feature idx), 61);
    y bg(feature idx, :) = normpdf(x bg(feature idx, :),
mean bg(feature idx), std bg(feature idx));
end
for fig idx = 1:8
    figure;
    for subplot idx = 1:8
        feature num = (fig idx - 1) * 8 + subplot idx;
        subplot(2, 4, subplot idx);
        plot(x fg(feature num, :), y fg(feature num, :), '-b',
x bg(feature num, :), y bg(feature num, :));
        title(['Marginal Density ', num2str(feature num)]);
    legend('P(x|cheetah)', 'P(x|grass)')
end
best features = [1, 15, 22, 33, 38, 47, 49, 50];
worst features = [2, 3, 5, 58, 59, 62, 63, 64];
figure;
for idx = 1:8
    subplot(2, 4, idx);
```

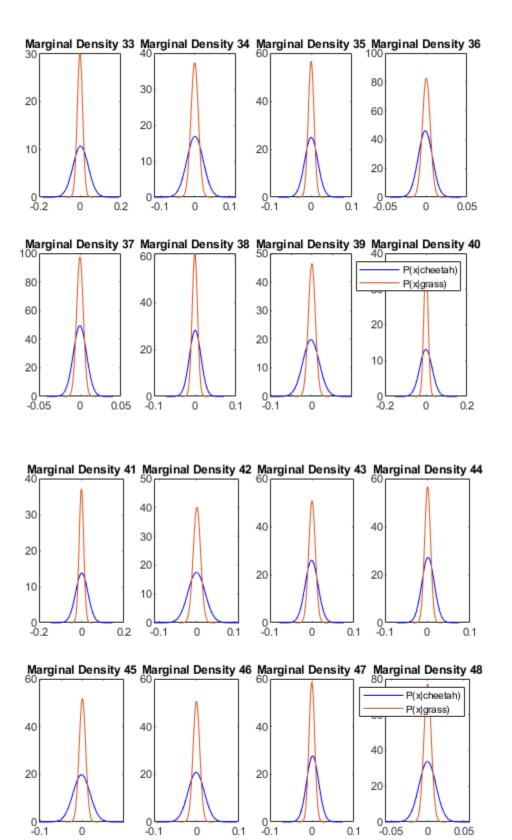
```
plot(x fg(best features(idx), :), y fg(best features(idx), :), '-b',
x_bg(best_features(idx), :), y_bg(best_features(idx), :));
    title(['Marginal Density ', num2str(best features(idx))]);
legend('P(x|cheetah)', 'P(x|grass)');
figure;
for idx = 1:8
    subplot(2, 4, idx);
    plot(x fg(worst features(idx), :), y fg(worst features(idx), :), '-b',
x bg(worst features(idx), :), y bg(worst features(idx), :));
    title(['Marginal Density ', num2str(worst features(idx))]);
end
legend('P(x|cheetah)', 'P(x|grass)');
응C)
zigzag indices = load('Zig-Zag Pattern.txt') + 1;
cheetah image = im2double(imread('cheetah.bmp'));
[image rows, image cols] = size(cheetah image);
small constant = 1e-5;
bg mean matrix = repmat(mean bg, bg rows, 1);
fg mean matrix = repmat(mean fg, fg rows, 1);
covariance bg = (bg - bg mean matrix)' * (bg - bg mean matrix) / bg rows +
small constant * eye(64);
covariance fg = (fg - fg mean matrix)' * (fg - fg mean matrix) / fg rows +
small constant * eye(64);
result 64D = zeros(image rows - 7, image cols - 7);
result 8D = zeros(image rows - 7, image cols - 7);
for row = 1:(image rows - 7)
    for col = 1: (image cols - 7)
        dct block = dct2(cheetah image(row:row+7, col:col+7));
        feature vector 64 = zeros(1, 64);
        for idx = 1:64
            [x pos, y pos] = find(zigzag indices == idx);
            feature vector 64(idx) = dct block(x pos, y pos);
        end
        prob bg = mvnpdf(feature vector 64, mean bg, covariance bg) *
prior grass;
        prob fg = mvnpdf(feature vector 64, mean fg, covariance fg) *
prior cheetah;
        result 64D(row, col) = prob fg > prob bg;
    end
end
% Display image for 64-dimensional features
figure;
imagesc(result 64D);
title('64-Dimensional Gaussian Classification');
colormap gray (255);
```

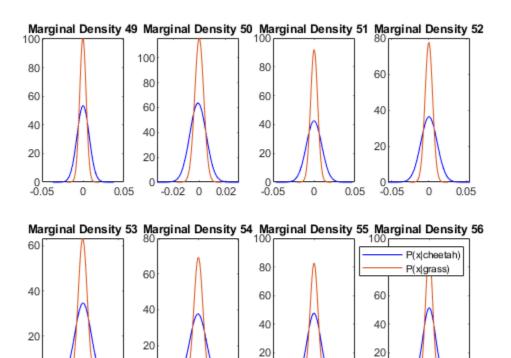
```
for row = 1:(image rows - 7)
    for col = 1:(image cols - 7)
        dct block = dct2(cheetah image(row:row+7, col:col+7));
        feature vector 8 = zeros(1, 8);
        for idx = 1:8
            [x pos, y pos] = find(zigzag indices == best features(idx));
            feature vector 8(idx) = dct block(x pos, y pos);
        end
        prob bg = mvnpdf(feature vector 8, mean bg(best features),
covariance bg(best features, best features)) * prior_grass;
        prob fg = mvnpdf(feature vector 8, mean fg(best features),
covariance fg(best features, best features)) * prior cheetah;
        result 8D(row, col) = prob fg > prob bg;
    end
end
% Display image for 8-dimensional features
figure;
imagesc(result 8D);
title('8-Dimensional Gaussian Classification');
colormap gray (255);
true mask = im2double(imread('cheetah mask.bmp'));
error 64D = sum(sum(abs(true mask(1:image rows-7, 1:image cols-7) -
result 64D)));
error 8D = sum(sum(abs(true mask(1:image rows-7, 1:image cols-7) -
result 8D)));
error rate 64D = error 64D / ((image rows - 7) * (image cols - 7));
error rate 8D = error 8D / ((image rows - 7) * (image cols - 7));
fprintf('Error Rate (64D) = %.4f\n', error rate 64D);
fprintf('Error Rate (8D) = %.4f\n', error rate 8D);
P(Cheetah) = 0.1919
P(Grass) = 0.8081
The priors are the same as before.
Error Rate (64D) = 0.0801
Error Rate (8D) = 0.0603
```

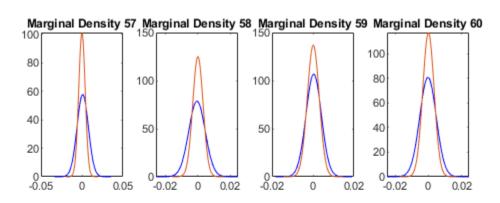
3











-0.05

0

0.05

0

-0.05

0.05

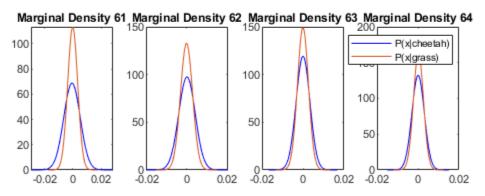
0.05

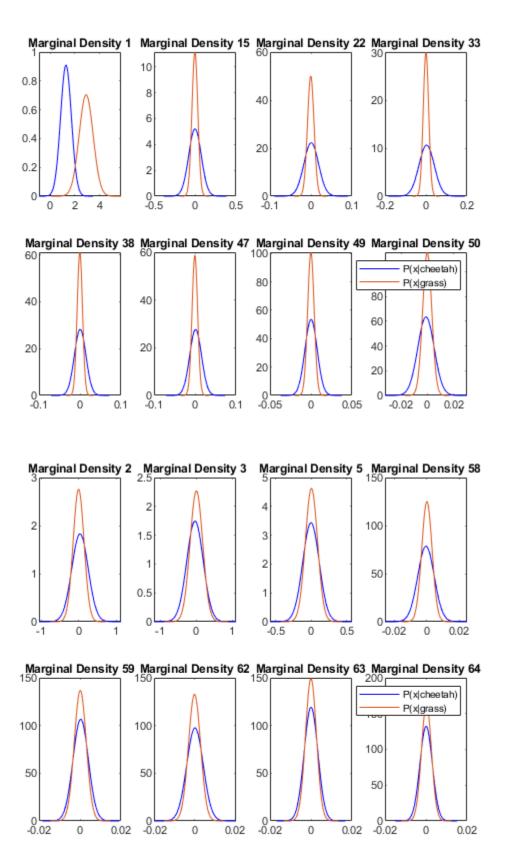
-0.05

0

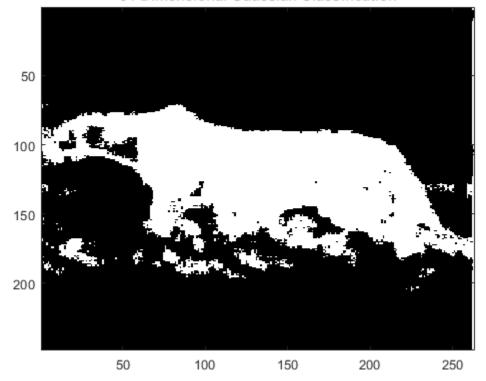
-0.05

0.05





64-Dimensional Gaussian Classification



8-Dimensional Gaussian Classification

